STATS 235: Modern Data Analysis Classification Models—LDA, QDA & NB

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Introduction

- Logistic regression is a discriminative model with linear boundaries
- In this lecture, we discuss several generative models, where we model P(x|y)
- We start with linear discriminant analysis (LDA), which also provide linear boundaries
- Next, we extend LDA to allow for nonlinear boundaries
- Finally, we discuss naive Bayes classifiers

 When the set of p predictors, x, are continuos random variables, we can assume that their joint distribution is multivariate normal for each class,

$$f_k(x) = (2\pi)^{-p/2} |\Sigma|^{-1/2} \exp[-\frac{1}{2}(x-\mu_k)^T \Sigma^{-1}(x-\mu_k)]$$

- Note that in this setting, only the mean of the distributions, μ_k , changes from one class to another. The covariance matrix Σ remains the same for all classes.
- This assumption is of course not realistic and is made only for simplicity. We will relax it later.

Using Bayes theorem, we have

$$P(y = k|x) = \frac{\pi_k f_k(x)}{\sum_{k'=1}^K \pi_{k'} f_{k'}(x)}$$

where $\pi_k = P(y = k)$.

• For a given value of x, the denominator remains the same for all classes. Therefore, we can define the discriminant function based on the numerator, $\pi_k f_k(x)$, or more commonly based on its log,

$$\delta_k(x) = \log \pi_k + \log[f_k(x)]$$

=
$$\log \pi_k - \frac{1}{2}\log(|\Sigma|) - \frac{1}{2}(x - \mu_k)^T \Sigma^{-1}(x - \mu_k)$$

 With further simplification (and removing the constant parts), we have

$$\delta_k(\mathbf{x}) = \log \pi_k - \frac{1}{2} \mu_k^T \Sigma^{-1} \mu_k + \mathbf{x}^T \Sigma^{-1} \mu_k$$

- Note that the above functions are linear in x.
- Therefore, we refer to them as *linear discriminant functions*.
- Classifying cases according to these functions is called *linear* discriminant analysis (LDA).

• We can estimate π_k and μ_k for $k=1,\ldots,K$, and Σ as follows:

$$\hat{\pi}_k = \frac{n_k}{n}$$

$$\hat{\mu}_k = \frac{1}{n_k} \sum_{i:y_i=k}^{n_k} x_i$$

$$\hat{\Sigma} = \frac{1}{n-k} \sum_{k=1}^K \sum_{i:y_i=k}^{n_k} (x_i - \hat{\mu}_k)(x_i - \hat{\mu}_k)^T$$

where n_k is the number of observed cases (training cases) that belong to class k.

- After estimating the model parameters, we assign each case, i, to the class whose value of the discriminant function, $\delta_k(x_i)$, is the highest.
- Cases for which $\delta_k(x) = \delta_I(x)$ fall on the decision boundary between the two classes k and I.
- For these cases, $\delta_k(x) \delta_l(x) = 0$, which means

$$\log \frac{\pi_k}{\pi_l} - \frac{1}{2} (\mu_k - \mu_l)^T \Sigma^{-1} (\mu_k - \mu_l) + x^T \Sigma^{-1} (\mu_k - \mu_l) = 0$$

• Note that the above equation, which specifies the decision boundary, is linear in x. As the result, the decision boundaries are *hyperplanes* in the *p*-dimensional space. (The decision boundary is straight line if we have two predictors only.)

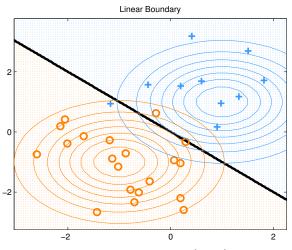


Figure 4.5a in Murphy (2012)

Quadratic discriminant analysis

- As mentioned above, the equal-covariance assumption is restrictive and is only made for convenience.
- By relaxing this assumption, the discriminant function becomes

$$\delta_k(x) = \log \pi_k - \frac{1}{2} \log(|\Sigma_k|) - \frac{1}{2} (x - \mu_k)^T \Sigma_k^{-1} (x - \mu_k)$$

which are quadratic functions of x; hence, they are called *quadratic* discriminant functions.

- Classifying cases according to these functions is called quadratic discriminant analysis (QDA).
- The decision boundaries for this approach are not linear any more.

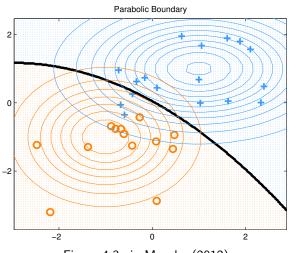


Figure 4.3a in Murphy (2012)

Naive Bayes models

- This is an alternative classification model, which is especially attractive when the dimension p is large.
- In this approach, we again use Bayes theorem to obtain the probability of each class given the observed values of predictors,

$$P(y = k | x_1, ..., x_p) = \frac{P(y = k)P(x_1, ..., x_p | y = k)}{\sum_{k'=1}^{K} P(y = k')P(x_1, ..., x_p | y = k')}$$

• This time, however, we make an assumption that is naive and possibly wrong, but it simplifies the model: we assume that given a class y=k, the predictors are independent,

$$P(x_1,...,x_p|y=k) = \prod_{j=1}^p P(x_j|y=k)$$

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Naive Bayes models

As a result of the above naive assumption, the model simplifies to

$$P(y = k | x_1, ..., x_p) = \frac{P(y = k) \prod_{j=1}^p P(x_j | y = k)}{\sum_{k'=1}^K P(y = k') \prod_{j=1}^p P(x_j | y = k')}$$

- As before, we assign each case, i, to the class with the highest conditional probability given x_{i1}, \ldots, x_{ip} .
- It is more common to distinguish between two classes using the following logit function

$$\log \frac{P(y = k | x_1, \dots, x_p)}{P(y = l | x_1, \dots, x_p)} = \log \frac{P(y = k) \prod_{j=1}^p P(x_j | y = k)}{P(y = l) \prod_{j=1}^p P(x_j | y = l)}$$

$$= \log \frac{\pi_k}{\pi_l} + \sum_{j=1}^p \log \frac{P(x_j | y = k)}{P(x_j | y = l)}$$

Naive Bayes models

- In practice, we estimate π_k using the proportion of observed cases that belong to class k.
- To estimate $P(x_j|k)$, we first need to assume a probability distribution model for x_i given k.
- If x_j is categorical, we can estimate $P(x_j|k)$ using the observed proportion of each category of x_j for cases with y = k.
- If x_j is continuous, we can assume $x_j|k$ has a Gaussian distribution and estimate its mean and variance using the cases with y = k.