# STATS 230: Computational Statistics Some Preliminary Concepts

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## Inference in the frequentist framework

- We typically start statistical inference by defining the underlying mechanism that generates data, y, using a probability model,  $P(y|\theta)$ , which depends on the unknown parameter of interest,  $\theta$ .
- The likelihood function is defined by plugging-in the observed data in the probability distribution and expressing it as a function of model parameters:  $f(\theta; y)$ .
- To estimate model parameters, we can find their values such that the probability of the observed data is maximum.
- For this, we maximize the likelihood function with respect to model parameters.
- Of course, it is easier to maximize the log of likelihood function, i.e.,  $L(\theta) = log(f(\theta))$ .

#### Score function and information

For single parameter exponential family,

$$L(\theta) = g(\theta)s(y) - c(\theta)$$

• The first derivative of log-likelihood function,  $L(\theta)$ , is called the *score function* 

$$u(\theta) = \frac{\partial L(\theta)}{\partial \theta}$$

For single parameter exponential family,

$$u(\theta) = s(y) \frac{\partial g(\theta)}{\partial \theta} - \frac{\partial c(\theta)}{\partial \theta}$$

To find MLE, we set

$$u(\theta) = 0$$



### Maximum likelihood estimation

- Under weak regularity conditions, the MLE demonstrates attractive properties as  $n \to \infty$ : the asymptotic distribution of MLE is normal, MLE is asymptotically consistent and efficient.
- Under some regularity conditions (Rao, 1973), the asymptotic covariance matrix for MLE,  $Cov(\hat{\theta})$ , is the inverse of Fisher information matrix,  $i(\theta)$ , where the (j,k) element of  $i(\theta)$  is

$$Cov[\frac{\partial L(\theta)}{\partial \theta_j}, \frac{\partial L(\theta)}{\partial \theta_k}]$$

which is equal to the following (assuming that we can take differentiate twice inside integral)

$$E\Big(-\frac{\partial^2 L(\theta)}{\partial \theta_i \partial \theta_k}\Big)$$

## Bayesian inference

- In Bayesian statistics, besides specifying a model  $P(y|\theta)$  for the observed data, we specify our prior  $P(\theta)$  for the model parameters.
- Then, we make probabilistic conclusions regarding the unobserved quantity  $\theta$  conditional on the observed data y.
- That is, we are interested in  $P(\theta|y)$ , which is called *posterior distribution*.
- Bayes' theorem provides a mathematical formula for obtaining  $P(\theta|y)$  based on  $P(\theta)$  and  $P(y|\theta)$ :

$$P(\theta|y) = \frac{P(\theta)P(y|\theta)}{P(y)}$$

$$\propto P(\theta)P(y|\theta)$$

# Bayesian inference

- Inference in the Bayesian framework is based on  $P(\theta|y)$ .
- For example, we can predict future observations,  $\tilde{y}$ , given the observed data y:

$$P(\tilde{y}|y) = \int_{\theta} P(\tilde{y}|\theta)P(\theta|y)d\theta$$

ullet This is a simple concept; however, finding  $P(\theta|y)$  in practice is challenging.

# Conjugate priors

- In some cases, we can limit our choice of prior to a specific class of distributions such that the posterior distribution has a closed form.
- This is called "conjugacy" and the prior is called a "conjugate" prior.
- Conjugacy is informally defined as a situation where the prior distribution  $P(\theta)$  and the corresponding posterior distribution,  $P(\theta|y)$  belong to the same distributional family.
- Using conjugate priors makes Bayesian inference easier.

# Conjugate priors

Recall that the exponential family has the following form:

$$P(y|\theta) \propto \exp\{g(\theta)s(y) - nc(\theta)\}$$

Now if we define the prior as follows:

$$P(\theta) \propto \exp\{g(\theta)\nu - \eta c(\theta)\}$$

• Then the posterior would have a similar form:

$$P(\theta|y) \propto \exp\{g(\theta)(\nu + s(y)) - (n+\eta)c(\theta)\}$$

### Poisson model

- Poisson model is another member of exponential family and is commonly used for count data.
- Assume we have observed  $y = (y_1, y_2, ..., y_n)$ :

$$P(y|\theta) \propto \exp(\log(\theta) \sum y_i - n\theta)$$

• The conjugate prior would have the following form:

$$P(\theta) \propto \exp(\log(\theta)\nu - \eta\theta)$$
  
  $\propto \exp(-\eta\theta)\theta^{\nu}$ 

• Using  $P(\theta) \propto \exp(-\beta \theta) \theta^{\alpha-1}$ , which is a Gamma $(\alpha, \beta)$  distribution,

$$\theta|y \sim \operatorname{Gamma}(\alpha + \sum_{i=1}^{n} y_i, \beta + n)$$

## Computation in statistics

- In general, finding MLE and posterior distribution analytically is difficult.
- Therefore, we almost always rely on computational methods.
- In this course, we will discuss a variety of computational techniques for numerical optimization and integration
- Optimization methods are mainly discussed within the frequentist framework.
- Numerical integration methods are mainly discussed with respect to their application in Bayesian inference.
- We will also discuss a variety of other computational methods (e.g., numerical linear algebra, bootstrap) that are commonly used in modern statistics.

### What's next?

- Please read Chapter II.1 from "Handbook of Computational Statistics," by Gentle et al. to learn some basic concepts about computer arithmetic and algorithms.
- Also, read Chapter 1 from "Computational Statistics," by Givens and Hoeting for a review of notation and background materials in statistics and probability.
- We will start our lectures by numerical linear algebra.
- We then spend several lectures on optimization methods
- Next, we will discuss a variety of methods for numerical integration and approximation.
- The last several lectures are devoted to more advanced topics including bootstrap, EM, and advanced sampling algorithms.