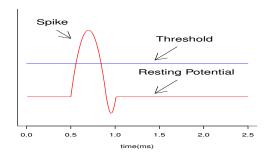
# A Dynamic Bayesian Model for Detecting Neuronal Communities

Babak Shahbaba<sup>1</sup>

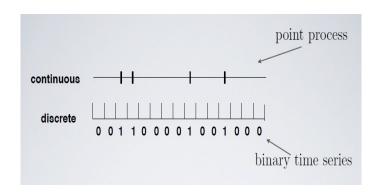
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September, 2014

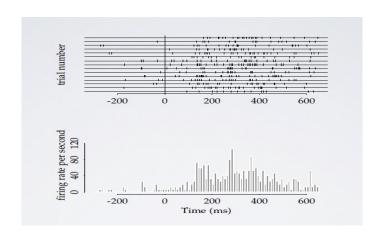
## Spike Train



## Spike Train

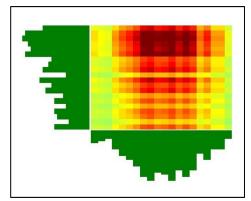


## Spike Train and PSTH



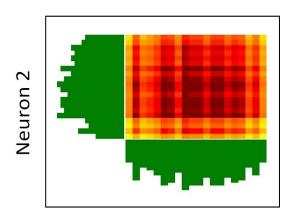
## JPSTH- Independent Neurons





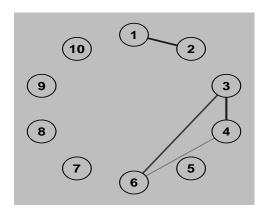
Neuron 1

## JPSTH– Synchronous Neurons

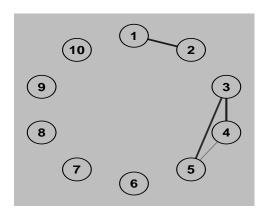


Neuron 1

#### **Neuronal Communities**



## **Dynamic Neuronal Communities**



#### Outline

- Modeling firing rates
- A stationary model for detecting synchrony
- A dynamic model for detecting synchrony
- A stationary model for detecting neuronal communities
- A dynamic model for detecting neuronal communities
- Simulation studies
- Experimental results



## Modeling Firing Rates

• In our first attempt, we assumed that the firing rate for each neuron depends on an underlying latent variable, u(t), which has a Gaussian process prior.

$$u(t) \sim \mathsf{GP}(0, C)$$

$$C_{ij} = \mathsf{Cov}[u(t_i), u(t_j)]$$

$$= \kappa^2 \exp[-\lambda(t_i - t_j)^2] + \delta_{ij}\xi^2$$

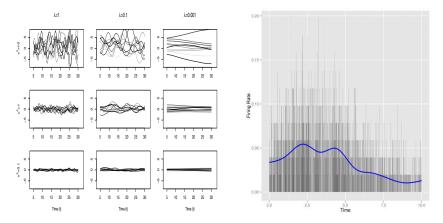
• We specify the spike probability,  $p_t$ , within time interval t in terms of u(t) through the following transformation:

$$\rho_t = \frac{1}{1 + \exp[-u(t)]}$$

As u(t) increases, so does  $p_t$ .

## Modeling Firing Rates

Our model can capture time-varying firing rates



 However, its extension to multiple neurons was not easy; therefore, we decided to use a slightly different model.

## Stationary Model for Detecting Synchrony

• For multiple neurons, we model the joint firing probability of spike trains at time t,  $P_r(Y_{1t} = y_{1t}, ..., Y_{nt} = y_{nt})$ , subject to the following simplex constraint:

$$\sum_{(y_{1t},...,y_{nt})\in(0,1)^n} \mathsf{P}_r\big(Y_{1t}=y_{1t},...,Y_{nt}=y_{nt}\big) = 1, \quad t=1,2,...,T$$

ullet We use a continuous latent variable  $u_{it}$  and a threshold  $au_{ij}$ 

$$Y_{ij} = \mathbb{1}_{(-\infty, au_{ij}]}(u_{ij}) = egin{cases} 1, & ext{if } u_{ij} \leq au_{ij} \ 0, & ext{otherwise.} \end{cases}$$
 $(u_{1t}, ..., u_{nt})^T \sim N(0, \Sigma)$ 

• The support of the joint distribution is the Cartesian cross of the real lines partitioned into  $2^n$  quadrants.

#### Covariance Matrix

We specify the the covariance matrix,

$$\Sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1n} \\ \sigma_{12} & \sigma_{22} & \cdots & \sigma_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1n} & \sigma_{2n} & \cdots & \sigma_{nn} \end{bmatrix}_{,}$$

by decomposing it as follows:

• We use  $\rho_{ij}$  for inference regarding the connection between neurons i and j.

#### Gaussian Process Prior on the Thresholds

 For each neuron, we assume the following Gaussian process prior for the threshold parameters:

$$(\tau_{i1}, ..., \tau_{iT}) \sim GP(0, C_i)$$

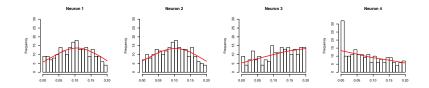
$$C_i|_{j,k} = Cov(\tau_{ij}, \tau_{ik})$$

$$= \kappa_i^2 \exp[-\lambda_i (t_i - t_j)^2] + \delta_{jk} \xi_i^2$$

 Alternatively, a Brownian motion prior can be used to improve computational efficiency:

$$C_i|_{j,k} = \mathsf{Cov}(\tau_{ij}, \tau_{ik}) = \theta_i \, \mathsf{min}(j,k)$$

## Illustration



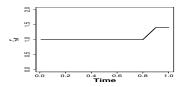
Parameter	Posterior Estimate
$ ho_{12}$	0.75 (0.66,0.84)
$ ho_{13}$	0.02 (-0.12,0.15)
$ ho_{14}$	0.12 (-0.01,0.25)
$ ho_{23}$	-0.05 (-0.19,0.12)
$ ho_{24}$	0.03 (-0.13,0.17)
$ ho_{34}$	-0.46 (-0.61,-0.32)

#### Limitations

- The above method has several shortcomings:
  - It is static (stationary) so it cannot capture the dynamics of neural networks.
  - Also, the method does not identify neuronal communities.

## Illustrating Limitations of Static Models

• Consider the following example, where the probability of co-firing is the product of marginal probabilities times  $\zeta$ , representing excessive firing rate beyond random:



- Using our method, the 95% probability interval for correlation is [-0.039, 0.066].
- The method of Kass and Kelly (2011) and Shahbaba et al. (2014) also report non-significant results.

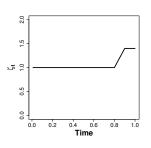
#### A non-stationary model

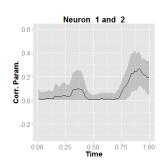
 We can modify the correlation matrix to make it non-stationary, while preserving its positive-definiteness:

$$\begin{split} \varSigma_t & = \begin{bmatrix} \sigma_{11} & \sigma_{12}l_1^t l_2^t & \cdots & \sigma_{1n}l_1^t l_n^t \\ \sigma_{12}l_2^t l_1^t & \sigma_{22} & \cdots & \sigma_{2n}l_2^t l_n^t \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1n}l_n^t l_1^t & \sigma_{2n}l_n^t l_2^t & \cdots & \sigma_{nn} \end{bmatrix} \\ & = \begin{bmatrix} l_1^t & 0 & \cdots & 0 \\ 0 & l_2^t & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & l_n^t \end{bmatrix} \begin{bmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1n} \\ \sigma_{12} & \sigma_{22} & \cdots & \sigma_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1n} & \sigma_{2n} & \cdots & \sigma_{nn} \end{bmatrix} \begin{bmatrix} l_1^t & 0 & \cdots & 0 \\ 0 & l_2^t & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & l_n^t \end{bmatrix} \\ & + \begin{bmatrix} \sigma_{11}(1-l_1^t) & 0 & \cdots & 0 \\ 0 & \sigma_{22}(1-l_2^t) & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_{nn}(1-l_n^t) \end{bmatrix}_{\vdots} \end{split}$$

## A non-stationary model

 The resulting model can capture the dynamics of the cross-neuronal interactions





However, it still cannot detect neuronal communities.

#### Chinese Restaurant Process

- In order to detect subsets (communities) of correlated neurons, we use Ewens sampling formula to allocate neurons into K partitions without pre-specifying K
- Given the previous j-1 assignments, we assign the  $j^{th}$  neuron either to an existing subset, M, with probability

$$\frac{|M|}{\alpha+j-1}$$

or to an empty subset (i.e., the neuron starts a new partition) with probability

$$\frac{\alpha}{\alpha + j - 1}$$



#### Chinese Restaurant Process

- This defines a prior distribution on a partition,  $\{z_1, z_2, \dots, z_n\}$ , where  $z_i$  assigns the  $i^{th}$  neuron to one of the K partitions.
- Given the partition, we rewrite the correlation matrix, R, as follows:

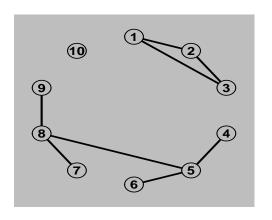
$$R = \begin{bmatrix} 1 & \rho_{12} \mathbb{1}_{\{z_1 = z_2\}} & \cdots & \rho_{1n} \mathbb{1}_{\{z_1 = z_n\}} \\ \rho_{12} \mathbb{1}_{\{z_1 = z_2\}} & 1 & \cdots & \rho_{2n} \mathbb{1}_{\{z_2 = z_n\}} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{1n} \mathbb{1}_{\{z_1 = z_n\}} & \rho_{2n} \mathbb{1}_{\{z_2 = z_n\}} & \cdots & 1 \end{bmatrix}$$

## Non-stationary Model for Detecting Synchrony

 We generalize the above model by allowing the partitions change over time,

$$R_{t} = \begin{bmatrix} 1 & \rho_{12} \mathbb{1}_{\{z_{1t} = z_{2t}\}} & \cdots & \rho_{1n} \mathbb{1}_{\{z_{1t} = z_{nt}\}} \\ \rho_{12} \mathbb{1}_{\{z_{1t} = z_{2t}\}} & 1 & \cdots & \rho_{2n} \mathbb{1}_{\{z_{2t} = z_{nt}\}} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{1n} \mathbb{1}_{\{z_{1t} = z_{nt}\}} & \rho_{2n} \mathbb{1}_{\{z_{2t} = z_{nt}\}} & \cdots & 1 \end{bmatrix}$$

## Simulation 1– Stationary Model



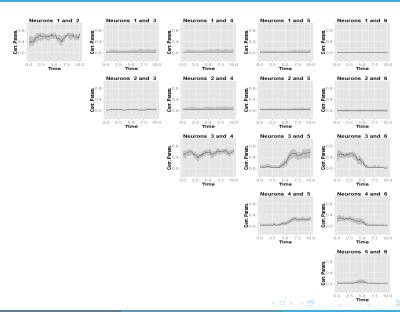
## Simulation 1- Stationary Model

1	0.45(0.31,0.59)	0.52(0.33,0.69)	0.02(-0.16,0.19)	-0.01(-0.17,0.14)	0.00(-0.13,0.14)	0.04(-0.10,0.21)	0.00(-0.11,0.12)	0.01(-0.12,0.15)	0.00(-0.10,0.11)
0.45(0.31,0.59)	1	0.47(0.31,0.64)	0.03(-0.12,0.16)	0.00(-0.12,0.11)	0.00(-0.13,0.12)	-0.02(-0.17,0.13)	0.01(-0.15,0.16)	0.02(-0.12,0.17)	0.00(-0.12,0.11)
0.52(0.33,0.69)	0.47(0.31,0.64)	1	0.00(-0.13,0.14)	0.01(-0.11,0.15)	0.00(-0.15,0.14)	0.02(-0.11,0.16)	0.01(-0.10,0.15)	0.03(-0.11,0.18)	0.01(-0.11,0.16)
0.02(-0.16,0.19)	0.03(-0.12,0.16)	0.00(-0.13,0.14)	1	0.42(0.27,0.55)	0.05(-0.0.10,0.22)	-0.03(-0.18,0.11)	0.01(-0.15,0.17)	-0.04(-0.21,0.12)	-0.02(-0.17,0.12)
-0.01(-0.17,0.14)	0.00(-0.12,0.11)	0.01(-0.11,0.15)	0.42(0.27,0.55)	1	0.44(0.30,0.59)	0.03(-0.12,0.20)	0.51(0.35,0.66)	-0.03(-0.18,0.11)	0.00(-0.14,0.15)
0.00(-0.13,0.14)	0.00(-0.13,0.12)	0.00(-0.15,0.14)	0.05(-0.0.10,0.22)	0.44(0.30,0.59)	1	0.03(-0.11,0.18)	0.01(-0.14,0.16)	0.04(-0.11,0.20)	0.01(-0.14,0.17)
0.04(-0.10,0.21)	-0.02(-0.17,0.13)	0.02(-0.11,0.16)	-0.03(-0.18,0.11)	0.03(-0.12,0.20)	0.03(-0.11,0.18)	1	0.46(0.29,0.61)	0.05(-0.08,0.21)	0.02(-0.13,0.17)
0.00(-0.11,0.12)	0.01(-0.15,0.16)	0.01(-0.10,0.15)	0.01(-0.15,0.17)	0.51(0.35,0.66)	0.01(-0.14,0.16)	0.46(0.29,0.61)	1	0.44(0.28,0.60)	0.00(-0.12,0.13)
0.01(-0.12,0.15)	0.02(-0.12,0.17)	0.03(-0.11,0.18)	-0.04(-0.21,0.12)	-0.03(-0.18,0.11)	0.04(-0.11,0.20)	0.05(-0.08,0.21)	0.44(0.28,0.60)	1	0.00(-0.13,0.13)
0.00(-0.10,0.11)	0.00(-0.12,0.11)	0.01(-0.11,0.16)	-0.02(-0.17,0.12)	0.00(-0.14,0.15)	0.01(-0.14,0.17)	0.02(-0.13,0.17)	0.00(-0.12,0.13)	0.00(-0.13,0.13)	1

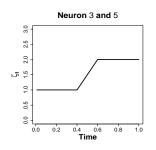
## Simulation 2- Dynamic Model

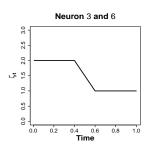
- We first generate time-varying marginal firing probabilities for each neuron; the joint probabilities of the two neurons is the product of marginal firing probabilities times an extra term,  $\zeta$
- For the first community, there are two neurons (indexed by 1 and 2) with constant correlation structure ( $\zeta=2$ )
- For the second community, there are 4 neurons (indexed by 3, 4, 5 and 6 ), where neuron 3 and 4 have constant correlation ( $\zeta=2$ )
- The correlations between neuron 3 and neurons 5 and 6 change over
- ullet Neurons 7 to 10 are not involved in the network  $(\zeta=1)$

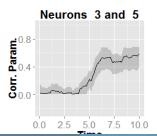
## Simulation 2- Dynamic Model

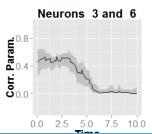


## Simulation 2– Dynamic Model

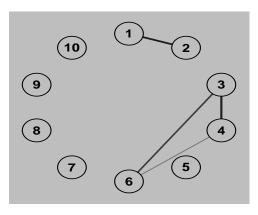






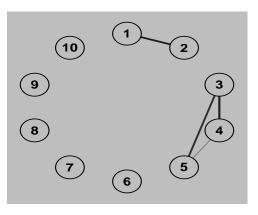


## Simulation 2– Dynamic Model



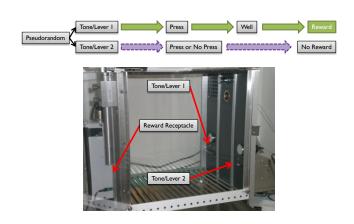
First Half

## Simulation 2– Dynamic Model

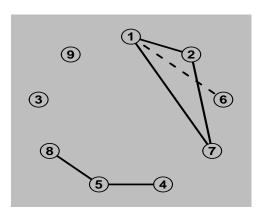


Second Half

## **Experimental Data**

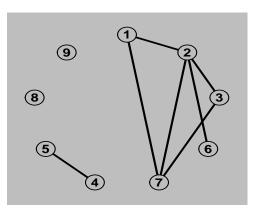


## Experimental Data



Rewarded

## Experimental Data



Non-rewarded

#### Discussion

- Our method has a number of advantages:
  - ▶ It captures the time-varying dependencies among neurons
  - It is useful for testing differences in cross-neuronal correlations in activity between different experimental conditions
  - It can be applied to a moderate to large number of neurons, and the computational complexity increases with the number of interacting neurons only
  - ▶ It can be applied to different data from a broad spectrum including continuous-valued time series that have some latent structure

#### Discussion

- To improve our method, we need to
  - properly and adaptively adjust bin-widths
  - allow for possible changes in the direction of relationships (from positive to negative and vice versa)
  - reduce computational cost

## Acknowledgement

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  - Hernando Ombao (UCI)
  - David Moorman (UMass Amherst)
  - Bo Zhou (UCI)
  - Shiwei Lan (UCI)
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  - ▶ NSF: IIS-1216045
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## Thank You!