### 1. Introduction

- course goals and topics
- mathematical optimization
- rough plan

# Course goals and topics

# Prerequisites

### Requirements: One of the following courses

- CPSC 302 (Numerical Computation for Algebraic Problems)
- CPSC 303 (Numerical Approximation and Discretization)
- MATH 307 (Applied Linear Algebra)

### In practice

- (very) comfortable with linear algebra
- multivariate calculus
- comfortable programming eg, Julia (recommended), Python, or Matlab (nor recommended)

### Book (some reading and homework assignments)

• Introduction to Nonlinear Optimization: Theory, Algorithms, and Applications with Matlab, by Amir Beck

# Course goals and topics

#### Goals

- recognize and formulate the main optimization problem classes
- understand the strengths and weaknesses of standard algorithms
- hands-on experience with useful software

### **Emphasis**

- formulating problems
- algorithms
- case studies
- mathematical software

# Grades and homework policy

#### **Grades**

• 6 homework assignments	30%
• 1 midterm exam	30%
• final exam	40%

### Homework policy

- welcome to work together (indicate collaborators)
- hand in your own assignments
- typeset assignments only (no handwritten submissions accepted)
- 3 late days total yours to budget (weekend  $\equiv 1$  weekday)

### Resources

#### Website

- Main site: https://friedlander.io/19T2-406
- Piazza: for discussions and solutions piazza.com/ubc.ca/winterterm22020/cpsc406/home

#### Office Hours

• TBD. Keep an eye on the webpage.

# Mathematical optimization

# Mathematical optimization

$$\label{eq:subject_to} \underset{x}{\text{minimize}} \quad f(x) \quad \text{subject to} \quad x \in \mathcal{C} \subseteq \mathbb{R}^n,$$

- $x = (x_1, \dots, x_n)$  is vector of optimization variables
- $f: \mathbf{R}^n \to \mathbf{R}$  is the objective (or cost) function
- C is a constraint (feasible) set, eg,

$$\mathcal{C} = \{ x \in \mathbf{R}^n \mid c_i(x) \le b_i, \ i = 1, \dots, m \}$$

where  $c_i \in \mathbf{R}^n \to \mathbf{R}$  are constraint functions

**Optimal solution**  $x^*$  has the **smallest** value of f among all vectors  $x \in \mathcal{C}$ , eg,

$$f(x^*) \le f(x)$$
 for all  $x$  such that  $c_i(x) \le b_i$ 

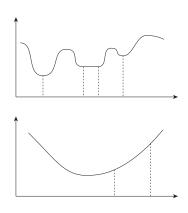
Problems don't necessarily appear this way. We may need to apply a transformation to reduce them to a standard form.

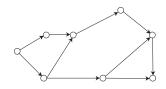
### Illustrative examples

$$\underset{x}{\operatorname{minimize}} \quad f(x)$$

minimize cost of flow subject to network capacity

flow conservation





# Varieties of optimization problems

- continuous vs discrete
- unconstrained vs constrained
- global vs local
- stochastic vs deterministic

Our domain is in blue.

# Solving optimization problems

### General optimization problems (no structure)

- difficult to solve
- most methods involve some compromise, eg, long computation time vs finding exact/correct solution
- not usually clear which methods work best

### **Ideally** recognize the type/class of problem – some are "easy"

- least-squares
- linear programs
- convex problems

#### Structure is often hidden

- network flows
- dynamic programs

## Linear least squares

$$\mathop{\rm minimize}_x \ \|Ax-b\|_2 \qquad \text{with} \qquad A \ \text{and} \ m\text{-by-}n \ \text{matrix}$$

#### **Formulation**

Data: 
$$A = [a_1 \ a_2 \ \cdots a_n], \ a_i \in \mathbb{R}^m$$
  
 $b = (b_1 \ b_2 \ \cdots b_m), \ b \in \mathbb{R}^m$ 

Model 1: 
$$b \approx a_1x_1 + a_2x_2 + \cdots + a_nx_n$$

Model 2:  $b \approx Ax + \epsilon$ , where  $\epsilon$  is "noise"

#### Solution

•  $x^* = (A^T A)^{-1} A^T b$ 

rarely this easy!

- reliable and efficient algorithms and software direct and indirect solvers
- standard techniques to increase flexibility eg, incorporate prior information
- · easy to recognize

# Different fitting criteria

$$\underset{x}{\mathsf{minimize}} \ \|Ax - b\|$$

### least-squares approximation:

$$||r||_2^2 = r_1^2 + \dots + r_m^2$$

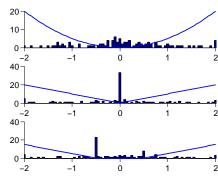
closed form solution  $x^*$  solves  $A^T\!Ax = A^T\!b$ 

### one-norm approximation:

$$||r||_1 = |r_1| + \cdots + |r_m|$$

### deadzone approximation:

$$||r|| = \sum_{i=1}^{m} \max\{|r_i| - \alpha, 0\}$$



# Linear Programming (LP)

#### **Formulation**

- equality and inequality constraints
- both objective and constraint functions are linear

### Solving LPs

- generally no analytic solution exists
- robust and efficient algorithms and software (eg, simplex method)

### Using LPs

- arises in unexpected places
- many problems can be turned into LPs

# **Example: Scheduling**

Objective: schedule weekly night-shifts for nurse staff at minimum cost

#### Constraint:

- 1. every nurse must work 5 straight nights
- 2. on night  $j = 1, \dots, 7$ ,  $d_j$  nurses are required

### Variables: not obvious! First attempt:

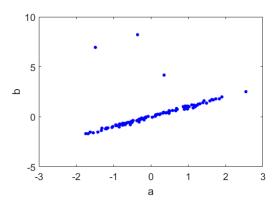
- $y_j$  nurses work on night j
- minimize  $\sum_{j} y_{j}$  subject to  $y_{j} \geq d_{j}, \ j = 1, \ldots, 7$

**Second attempt:** Let  $x_j$  be no. of nurses **starting** their 5 day shift on day j:

minimize 
$$x_1 + x_2 + x_3 + x_4 + x_5 + x_6 + x_7$$
 subject to 
$$x_1 + x_4 + x_5 + x_6 + x_7 \ge d_1$$
 
$$x_1 + x_2 + x_5 + x_6 + x_7 \ge d_2$$
 
$$x_1 + x_2 + x_3 + x_6 + x_7 \ge d_3$$
 
$$x_1 + x_2 + x_3 + x_4 + x_7 \ge d_4$$
 
$$x_1 + x_2 + x_3 + x_4 + x_5 + x_6 \ge d_5$$
 
$$x_2 + x_3 + x_4 + x_5 + x_6 \ge d_6$$
 
$$x_3 + x_4 + x_5 + x_6 + x_7 \ge d_7$$
 
$$x_1, \dots, x_7 \ge 0$$

- note the constraint structure. This is almost always true of practical LPs
- ullet we may want to restrict  $x_j$  to be integer. This is a much harder problem!

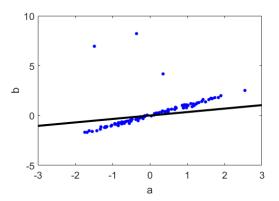
Almost linear data with a few outliers



Idea 1: Solve least squares

$$\underset{x}{\mathsf{minimize}} \quad \sum_{i=1}^{n} (a_i x - b_i)^2$$

Plot f(a) = ax (black line)

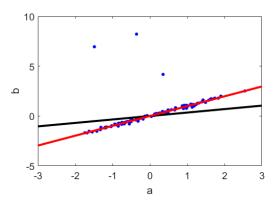


Terrible!

Idea 2: Solve with different error term

$$\underset{x}{\mathsf{minimize}} \quad \sum_{i=1}^{n} |a_i x - b_i|$$

Plot f(a) = ax (red line)



So much better!

In higher dimensions,

$$\underset{x}{\operatorname{minimize}} \quad \|Ax - b\|_1 = \sum_{i=1}^m |a_i^T x - b_i|$$

#### LP reformulation.

$$\begin{array}{ll} \underset{x,v}{\text{minimize}} & \sum_{i=1}^m v_i \\ \text{subject to} & -v_i \leq a_i^T x - b_i \leq v_i, \ i = 1, \dots, m \end{array}$$

# Rough plan

# The (rough) plan

- (~ 3 weeks) Advanced linear algebra, simple optimization problems
- (~ 3 weeks) Convex optimization, important methods

Midterm (good luck!)

- (~ 3 weeks) Applications, extensions
- (~ 3 weeks) Linear programming, duality

Final (good luck!)

Any questions?