Agricultural Marketing and Price Analysis Lecture 4

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Agricultural Marketing and Price Analysis Lecture 4

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Background

A Two-period model

programming

- single homogeneous product (commodity)
- single location
- Sold at different points in time (intertemporal analysis)
- No centralized market

Sale at different points in time implies storage which implies dynamic analysis

Incentive to store a commodity

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A Two-period model

Non-linear programming

Dynamics

Expected discounted future sales price - Current price (Marginal Benefits) > Marginal physical costs of storage



Non-linear programmin

- Speculative storage implies: Expected discounted future sales price - Current price (Marginal Benefits) = Marginal physical costs of storage (cf. Hotelling's rule in resource economics)
- ▶ If traders hold no speculative stocks, then Expected discounted future sales price - Current price (Marginal Benefits) < Marginal physical costs of storage (stock-out property)

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Adjacent time periods should be characterized by rising (current prices) prices (until Δ marginal price = marginal cost of storage. Followed by stockout (after the new harvest) and price collapse. resulting in price cycles and a saw -tooth pattern.

- Rarely observed in reality due to trade (e.g. spatial effects)

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- pipeline stocks
- speculative stocks (storage in excess of pipeline requirements)
- investment in storage responds to price differential
- Government may store commodities for other purposes

- ▶ Production h_1 and h_2 , (harvest in periods 1 and period 2)
- ▶ Inverse market demand P(X) and P'(X) < 0.
- S units of production will be stored in period 1 and sold in period 2
- ▶ Equilibrium prices in each period are $P(h_1 S)$ and $P(h_2 + S)$
- ▶ C(S) is the cost of storing S units for one period. C'(S) > 0 and $C''(S) \ge 0$

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Dynamics

$$\int_{0}^{h_{1}-S} P(x)dx - P(h_{1}-S)(h_{1}-S) \text{period } 1$$

$$\int_{0}^{h_{2}+S} P(x)dx - P(h_{2}+S)(h_{2}+S) \text{period } 2$$

Producer surplus is just the revenue, production costs can be ignored because they do not impact the optimal storage rule (due to fixed marginal costs)

 ${\sf Background}$

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Dynamics

$$V(S) = \int_0^{h_1 - S} P(x) dx + \delta \int_0^{h_2 + S} P(x) dx - C(S)$$

storage is paid for "up-front".

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$$L(S, \lambda) = V(S) + \lambda S$$

Karrush-Kuhn-Tucker conditions:

$$\frac{\partial L}{\partial S} = V'(S) + \lambda \le 0$$

 $\lambda S = 0$ complementary slackness

$$\frac{\partial}{\partial z} \int_{a(z)}^{b(z)} f(x, z) dx = \int_{a(z)}^{b(z)} \frac{\partial f}{\partial z} dx + f(b(z), x) b'(z) - f(a(z), x) a'(z)$$

//mathworld.wolfram.com/LeibnizIntegralRule.html

Applying this rule to V(S):

$$V^{'}(S) = P(h_1 - S)(-1) + \delta P(h_2 + S)(+1) - C^{'}(S)$$
 please verify

So KKT implies

$$-(P(h_1 - S) + C'(S)) + \delta P(h_2 + S) + \lambda \le 0$$
$$\lambda S = 0$$

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Jynamics



Non-linear programming

Dynamics

$$-(P(h_1) + C'(0)) + \delta P(h_2) + \lambda \le 0$$
$$\lambda S = 0$$

This implies

$$P(h_1 - S) + C'(S)) > \delta P(h_2)$$

and that no storage would take place

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ynamics

$$-(P(h_1 - S^*) + C'(S^*)) + \delta P(h_2 + S^*) \le 0$$
$$\lambda S^* = 0$$

This implies

$$P(h_1 - S^*) + C'(S^*) = \delta P(h_2 + S^*)$$

This is just our LOP storage rule from the introduction.

Non-linear programming

- Note P'(x) < 0 and the optimal storage rule imply $h_1 > h_2$
- ▶ Intuition: Why store goods if you "know" there will be a good harvest.
- Optimal storage rule can be interpreted as arbitrage conditions within a market.
- tow work out how much to store we would need to know details of the inverse demand function and the cost function

programming

- 2-period models are not always sufficient
- What about a T-period storage model?
- In this case optimal storage period t depends on the equilibrium price in the t+1 period (Why?).
- ► This problem is dynamic because decisions in different periods are coupled together and not separable

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- ▶ Assume production *h* is fixed and exogenous
- Assume market demand is linear
- Assume marginal physical cost of storage is a constant
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The LOP equilibrium

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Dynamics

Choose the level of storage to maximize the sum of consumer and producer revenue minus the cost of storage over a T-period time horizon

- Construct an expression for the net present value of net aggregate welfare
- Assume production/harvesting occurs at the beginning of each period and and consumption immediately after harvest.
- ▶ S_{t-1} is the amount of stock carried over from period t-1 to period t.
- ▶ Period t consumption is $x_t = S_{t-1} S_t$
- Stocks available for consumption in period t are $q_t = h + S_{t-1}$
- ▶ Consumption is $x_t = q_t S_t$
- $ightharpoonup q_t$ is called the state variable

programming

- ▶ The price of the commodity in period t depends on the consumption $q_t S_t$
- $P_t = a b(q_t S_t)$
- Sum of producer and consumer surplus (aggregate welfare) is
- $a(q_t S_t) 0.5b(q_t S_t)^2$
- ▶ Equation of motion $q_{t+1} = q_t x_t$

programming

Dynamics

$$\max_{S_t} \sum_{t=0}^{T-1} \delta^t \left\{ ax_t - 0.5bx_t^2 - m(q_t - x_t) \right\} + V_T(S_T)$$

subject to

$$q_{t+1} = q_t - x_t$$

and
$$x_t = q_t - S_t$$
 and $S_T = 0$

Non-linear programming

Dynamics

The Bellman equation:

$$V_t(q) = max_S \left\{ a(q-S) - 0.5b(q-S)^2 - mS + \delta V_{t+1}(h+S) \right\}$$

To solve this, start at t=T with $S_T = 0$ then

$$V_{T}(q) = max_{S_{T}} \left\{ a(q_{T} - S_{T}) - 0.5b(q_{T} - S_{T})^{2} - mS_{T} \right\}$$

$$= \left\{ a(q_{T}) - 0.5b(q_{T})^{2} \right\}$$

$$V_{T}(h + S_{T-1}) = \left\{ a(h + S_{T-1}) - 0.5b(h + S_{T-1})^{2} \right\}$$

Now substitute this back into the Bellman equation and evaluate it (B.E.) at t = T - 1.

Dynamics

 $V_{T-1}(q) = \max_{S_{T-1}} \left\{ a(q_{T-1} - S_{T-1}) - 0.5b(q_{T-1} - S_{T-1})^2 - \right.$ $mS_{T-1} + \delta \left\{ a(h + S_{T-1}) - 0.5b(h + S_{T-1})^2 \right\} \right\}$

Dfferentiating the RHS gives

$$-a + b(q_{T-1} - S_{T-1}) - m + \delta a - \delta b(h + S_{T-1}) = 0$$
$$\frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)} = S_{T-1}$$

The textbook additionally defines $A_{T-1} = \delta a$ and $B_{T-1} = \delta b$, these will lead to an additional system of difference (recursive) equations that can be solved.

Non-linear programming Dynamics

Substitute storage S_{T-1} into V_{T-1} and replace q_{T-1} with $h + S_{T-2}$ (we will do this in steps):

$$V_{T-1}(q) = \max_{S_{T-1}} \left\{ a(q_{T-1} - \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)}) - \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)} \right\} - \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)} + \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)} + \frac{\delta \left\{ a(h + \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)}) - \frac{-a + bq_{T-1} - m + \delta a - \delta bh}{b(1 + \delta)} \right\} \right\}$$

Non-linear programming

Dynamics

$$V_{T-1}^{*}(q) = \left\{ a(h + S_{T-2} - \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)} \right) - \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)}$$

$$0.5b(h + S_{T-2} - \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)})^{2} - \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)} + \frac{\delta}{b(1 + \delta)}$$

$$\delta \left\{ a(h + \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)}) - \frac{\delta}{b(1 + \delta)} \right\}$$

$$0.5b(h + \frac{-a + b(h + S_{T-2}) - m + \delta a - \delta bh}{b(1 + \delta)})^{2} \right\}$$

All terms should now be in terms of T-2 (Check this!!) This is the continuation value for period T-2. This can be simplified a little by substituting A_{T-1} , B_{T-1}

Background

A Two-period model

Non-linear

We now return to the Bellman equation:

$$V_{T-2}(q_{T-2}) = extit{max}_{S_{T-2}} \left\{ extit{a} (q_{T-2} - S_{T-2}) - 0.5 extit{b} (q_{T-2} - S_{T-2})^2 - extit{m} S_{T-2} + \delta V_T^*
ight.$$

substitute in the continuation value and repeat the process until all periods are exhausted