Machine Learning Lecture 2: Linear Models

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Outline

- 1. Linear models overview
- 2. Linear Regression under the hood
- 3. Gauss-Markov theorem
- 4. Regularization in Linear regression
- 5. Model validation and evaluation



Previous lecture recap



- Dataset, observation, feature, design matrix, target
- i.i.d. property
- Model, prediction, loss/quality function
- Parameter, Hyperparameter

Supervised learning problem statement



Training set $\mathcal{L} = \{\mathbf{x_i}, y_i\}_{i=1}^n$, with **n** objects each having **p** features, where

- $\mathbf{x_i} \in \mathbb{R}^p, y_i \in \mathbb{R}$ for regression
- $\mathbf{x_i} \in \mathbb{R}^p, y_i \in \{-1, +1\}$ for binary classification

Model $\,\hat{y}=f(\mathbf{x})\,$ predicts some value \hat{y} for every object

Loss function $Q(\mathbf{x},y,\hat{y},f)$ that should be minimized

Unsupervised learning problem statement



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where $\mathbf{x_i} \in \mathbb{R}^p$

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Loss function $Q(\mathbf{x},\hat{y},f)$ that should be minimized

Evaluating the quality (simple)





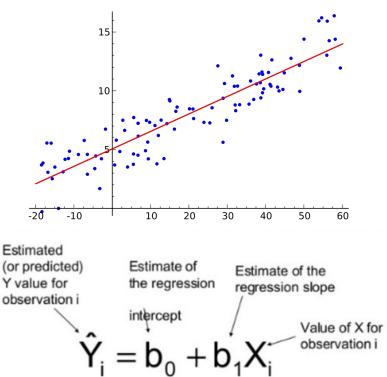
Quality != loss function

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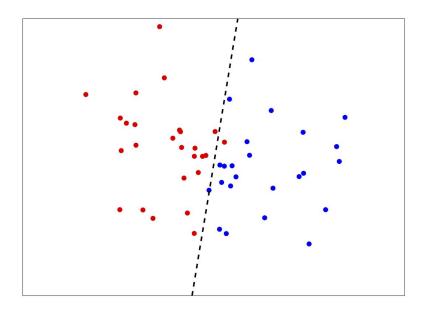


Regression models



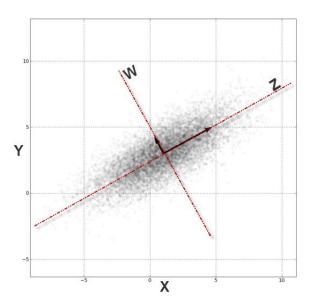


- Regression models
- Classification models





- Regression models
- Classification models
- Unsupervised models (e.g. PCA analysis):





- Regression models
- Classification models
- Unsupervised models (e.g. PCA analysis):
- Building block of other models (ensembles, NNs, etc.):

girafe ai





Linear regression problem statement:

ullet Dataset $\mathcal{L} = \{\mathbf{x}_i, y_i\}_{i=1}^N$, where $\mathbf{x}_i \in \mathbb{R}^n, \quad y_i \in \mathbb{R}$.



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- The model is linear:

$$\hat{y} = w_0 + \sum_{k=1}^{p} x_k \cdot w_k = //\mathbf{x} = [1, x_1, x_2, \dots, x_p]// = \mathbf{x}^T \mathbf{w}$$



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where $\mathbf{w} = (w_0, w_1, \dots, w_n)$, w_0 is bias term.



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 where $\mathbf{w}=\left(w_0,w_1,\ldots,w_n\right)/w_0$ is bias term.

we added an additional column of 1's to the design matrix to simplify the formulas



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where $\mathbf{w} = (w_0, w_1, \dots, w_n)$, w_0 is bias term.

• Least squares method (MSE minimization) provides a solution:

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \|Y - \hat{Y}\|_{2}^{2} = \arg\min_{\mathbf{w}} \|Y - X\mathbf{w}\|_{2}^{2}$$

Analytical solution



Denote quadratic loss function:

$$Q(\mathbf{w})=(Y-X\mathbf{w})^T(Y-X\mathbf{w})=\|Y-X\mathbf{w}\|_2^2$$
 , where $X=[\mathbf{x}_1,\ldots,\mathbf{x}_n], \quad \mathbf{x}_i\in\mathbb{R}^p\,Y=[y_1,\ldots,y_n], \quad y_i\in\mathbb{R}$.

$$\nabla_{\mathbf{w}} Q(\mathbf{w}) = \nabla_{\mathbf{w}} [Y^T Y - Y^T X \mathbf{w} - \mathbf{w}^T X^T Y + \mathbf{w}^T X^T X \mathbf{w}] =$$

$$= 0 - X^T Y - X^T Y + (X^T X + X^T X) \mathbf{w} = 0$$

$$\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$$

what if this matrix is singular?

Analytical solution



$$\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$$

what if this matrix is singular?

Unstable solution



In case of multicollinear features the matrix X^TX is almost singular .

It leads to unstable solution:

```
w_true
array([ 2.68647887, -0.52184084, -1.12776533])

w_star = np.linalg.inv(X.T.dot(X)).dot(X.T).dot(Y)
w_star
array([ 2.68027723, -186.0552577, 184.41701118])
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corresponding features are almost collinear

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the coefficients are huge and sum up to almost 0

Regularization



To make the matrix nonsingular, we can add a diagonal matrix:

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$$I=\mathrm{diag}[1_1,\ldots,1_p]$$
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Regularization



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 .

Actually, it's a solution for the following loss function:

$$Q(\mathbf{w}) = ||Y - X\mathbf{w}||_2^2 + \lambda^2 ||\mathbf{w}||_2^2$$

exercise: derive it by yourself

Gauss-Markov theorem

girafe ai



Gauss-Markov theorem



Suppose target values are expressed in following form:

$$Y=X\mathbf{w}+oldsymbol{arepsilon}$$
 , where $oldsymbol{arepsilon}=[arepsilon_1,\dots,arepsilon_N]$ are random variables

Gauss-Markov assumptions:

- $\mathbb{E}(\varepsilon_i) = 0 \quad \forall i$
- $Var(\varepsilon_i) = \sigma^2 < \inf \forall i$
- $Cov(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i \neq j$

Gauss-Markov theorem



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$$\mathbf{\hat{w}} = (X^T X)^{-1} X^T Y$$

delivers **B**est **L**inear **U**nbiased **E**stimator

Different norms



Once more: loss functions:

$$MSE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_2^2$$

$$ullet$$
 L2 $\|\mathbf{w}\|_2^2$

only works for Gauss-Markov theorem

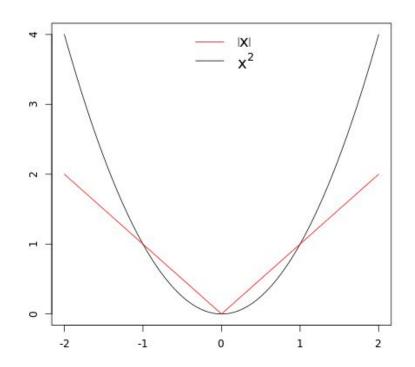
$$MAE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_1$$

$$ullet$$
 Li $\|\mathbf{w}\|_1$

What's the difference?



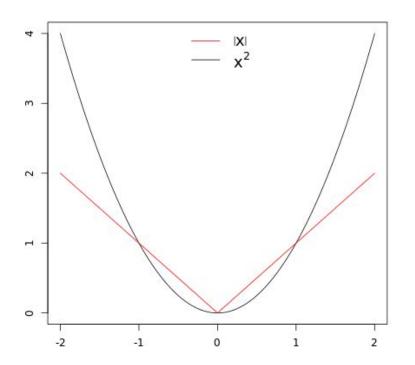
- MSE (L₂)
 - delivers BLUE according to Gauss-Markov theorem
 - o differentiable
 - o sensitive to noise
- MAE (L1)
 - o non-differentiable
 - not a problem
 - o much more prone to noise



What's the difference?



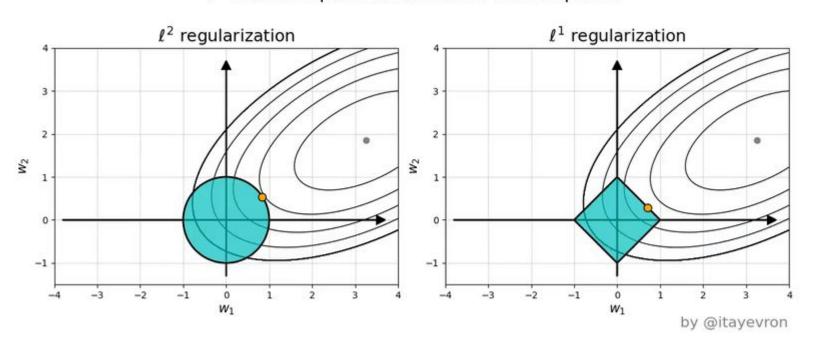
- L2 regularization
 - constraints weights
 - o delivers more stable solution
 - o differentiable
- L₁ regularization
 - o non-differentiable
 - o not a problem
 - o selects features



What's the difference?



 ℓ^1 induces sparse solutions for least squares



Loss functions in regression



Other functions to measure the quality in regression:

- R2 score
- MAPE
- SMAPE
- .

Model validation and evaluation

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Supervised learning problem statement



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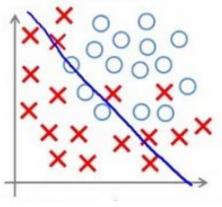
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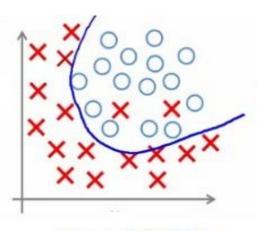
Overfitting vs. underfitting



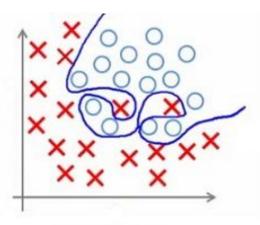


Under-fitting

(too simple to explain the variance)



Appropriate-fitting

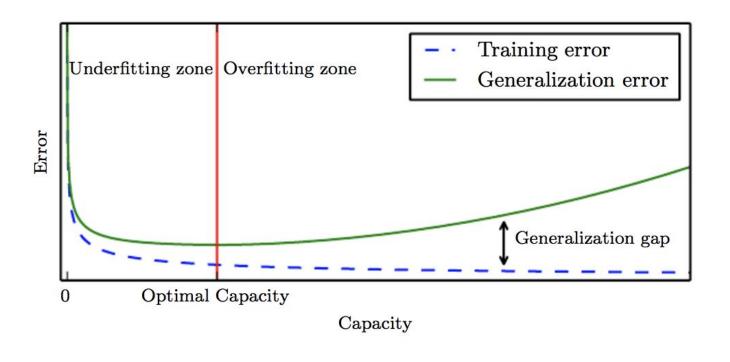


Over-fitting

(forcefitting -- too good to be true)

Overfitting vs. underfitting





Overfitting vs. underfitting



- We can control overfitting / underfitting by altering model's capacity (ability to fit a wide variety of functions):
- select appropriate hypothesis space
- learning algorithm's effective capacity may be less than the representational capacity of the model family



Dataset

Training

Testing

Holdout Method

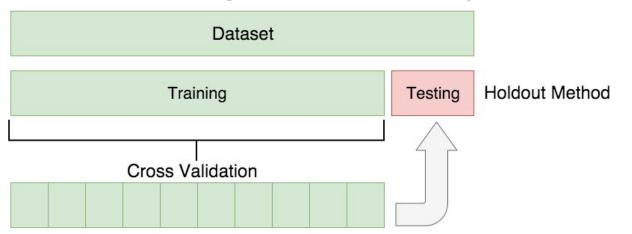


Dataset

Training Testing Holdout Method

Is it good enough?







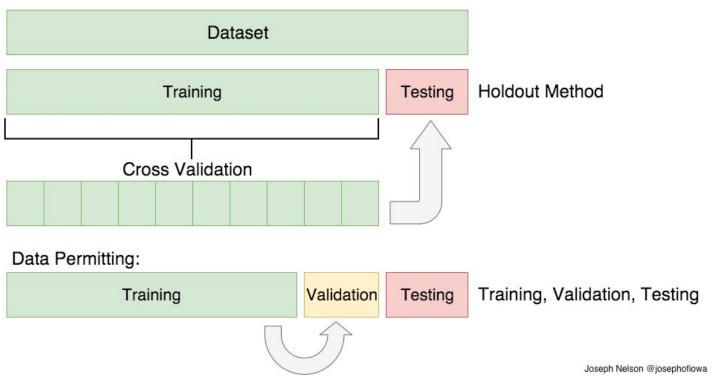
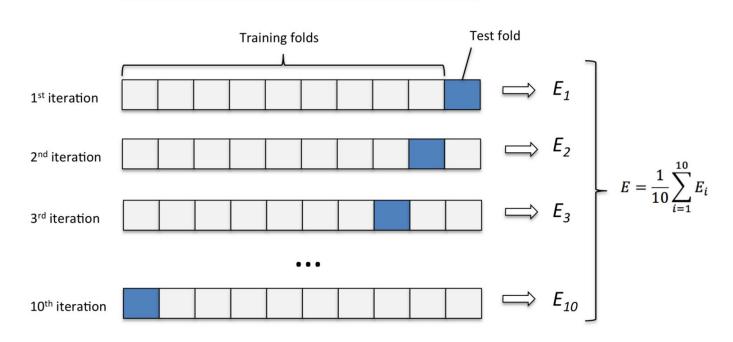


Image credit: Joseph Nelson @josephofiowa

Cross-validation







Outro



- Linear models are simple yet quite effective models
- Regularization incorporates some prior assumptions/additional constraints
- Trust your validation

Revise



- 2. Linear Regression under the hood
- 3. Gauss-Markov theorem
- 4. Regularization in Linear regression
- 5. Model validation and evaluation



Thanks for attention!

Questions?



