

# Title

- Text

## Exercise 2: LSQ & Newton's Method

MAD

[bacdavid@student.ethz.ch](mailto:bacdavid@student.ethz.ch)

# Outline

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# Information

## General

- Lecture material & problem sets available [here](#)
- Tutorial material available [here](#)

# Goals

## Goals of Today

- Know about SVD
- Understand the meaning of the condition number
- Know how to compute pseudo-inverse
- Know how to use Newton's Method

# Theory / Recap



# SVD

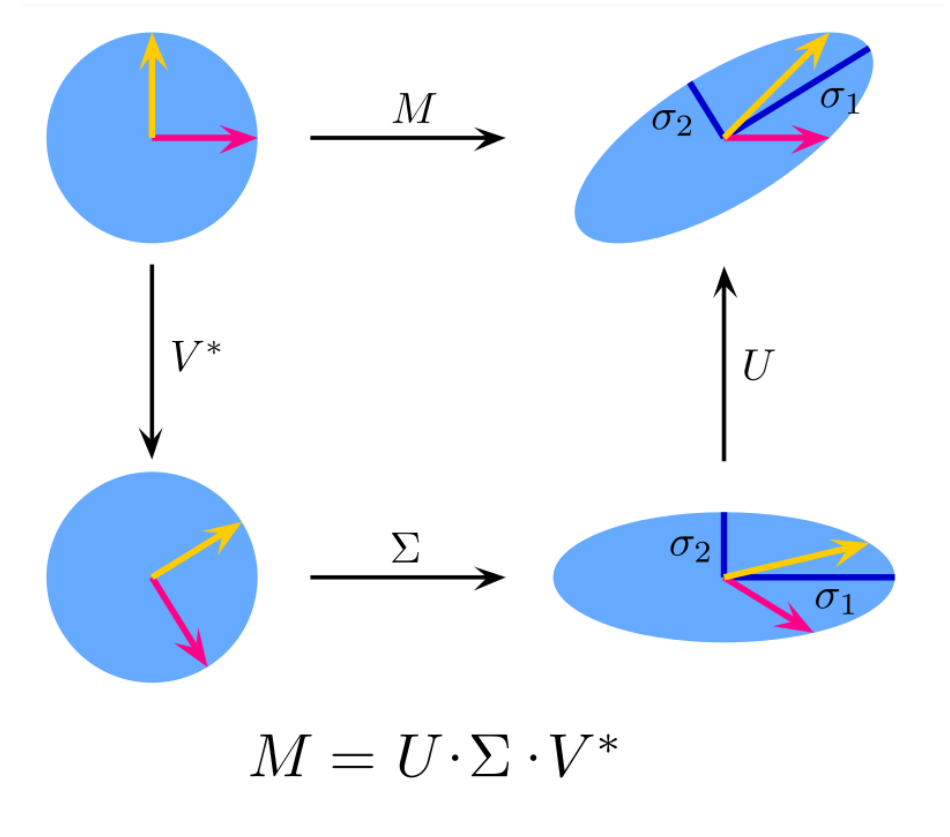
- $U, V$ : Orthogonal matrices
- $\Sigma$ : non-squared diagonal Matrix
- Decomposition:

$$M = U \Sigma V^T$$

- Inverse:

$$M^{-1} = V \Sigma^{-1} U^T$$

- Note:  $\text{diag}^{-1}(\sigma_i) = \text{diag}\left(\frac{1}{\sigma_i}\right)$



## Conditional Number

- Assume a system  $Ax = b$ , condition number:

$$\kappa(A) = \|A\| \cdot \|A^{-1}\| = \frac{\sigma_{\max}(A)}{\sigma_{\min}(A)}$$

- Describes impact of numerical error:

$$\|x_{\text{true}} - x_{\text{num}}\| \sim \kappa \cdot \|b_{\text{true}} - Ax_{\text{num}}\|$$

- Problem is well conditioned if  $\kappa$  is not too large

## Example 1: Compute Conditional Number

- x-data:  $\mathcal{X} = \left\{ [1, 0, 0], [0, 2, 0], \left[0, 0, \frac{1}{2}\right] \right\}$
- Assume LSQ problem
- Compute the conditional number
- Is the problem well conditioned?

# Pseudo Inverse

- Remember SVD:  

$$M^{-1} = V\Sigma^{-1}U^T$$
- If  $\sigma_i = 0 \Leftrightarrow M$  is singular
- If  $M$  is non-square the inv. doesn't exist
- Define the pseudo inverse:
  - Transpose  $\Sigma$
  - Reciprocal of non-zero singular values
  - Zeros remain in  $\Sigma$
  - $M^+ = V\Sigma^+U^T$

$$\Sigma^+ = \begin{bmatrix} \frac{1}{\sigma_1} & & & & & \\ & \ddots & & & & \\ & & \frac{1}{\sigma_r} & & & \\ & & & 0 & & \\ & & & & \ddots & \\ & & & & & 0 \end{bmatrix}$$

## Example 2: Compute the pseudo-inverse

- x-data:  $\mathcal{X} = \left\{ [1, 0, 0], \left[0, \frac{1}{2}, 0\right] \right\}$
- Assume LSQ problem
- Compute the rank – is a pseudo-inverse required?
- Decompose the matrix as  $\bar{X} = U\Sigma V^T$  (Tipp: U and V are identities – what dimensions?)
- Write down the pseudo inverse

## Intervention: What have we done so far?

- We have some **data**  $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$
- We want to fit a **function with linear parameters** to the data, ie.: (\*)
  - $y = w_0 \cdot x_1 + w_1 \cdot x_2$
  - $y = w_0 + w_1 \cdot x_1^2 + w_2 \cdot x_2^3$
- We decide on a **squared penalty**  $\|\bar{X}w - \bar{y}\|_2^2$
- Now we can optimize for  $w$  to **minimize the penalty**
- One way to do this is by **normal form**, if the **condition number** is large this is difficult since it has a “squared effect”
- Constructing the **pseudo-invers via SVD** weakens the effect of the large condition number

(\*) Please note  $x_1^{(1)} = x_1$  etc.

## Now something different: Newton's Method

- Newton's Method takes advantage of slope: Assume *somewhat* strict monotonic increase/ decrease towards root
- Derivation:
  - Approximate:  $f(x + \Delta x) \approx f(x) + f'(x)\Delta x$  (Taylor)
  - Discretize:  $f(x^{(k)}) = f(x^{(k-1)}) + f'(x^{(k-1)})(x^{(k)} - x^{(k-1)})$
  - Set  $f(x^{(k)}) = 0$ : 
$$x^{(k)} = x^{(k-1)} - \frac{f(x^{(k-1)})}{f'(x^{(k-1)})}$$
 (update rule)
- Iterate until  $|x^{(k)} - x^{(k-1)}| < \epsilon$
- Link

## Example 3: Using Newton's method

- Cube of volume  $10 \text{ m}^3$  - What's the side length?
- Write down the function you are trying to find a root of
- Make an initial guess
- Iterate once using newton's method
- Use  $x^0 = 0$  as an initial guess – what happens? Why?



# Exercises

## Q1

- Compute the condition number and find out what insights it reveals about a numerical problem
- Compute the pseudo inverse using SVD

## Q2

- Pseudo-code of a recursive task
- Use newton's method to compute the sqrt. (similar to example 3)
- Implement newton's method

# Questions?

