

4 Neural Networks

④

P6

$$f(\sum \omega_i x_i) = f(\vec{x}^T \vec{\omega}) \quad \text{with } \vec{x} = \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{pmatrix} \\ \vec{\omega} = \begin{pmatrix} \omega_0 \\ \omega_1 \\ \vdots \\ \omega_n \end{pmatrix}$$

P8

$$o_1 = f(\vec{x}_1^T \vec{\omega}_1)$$

↓ belongs to neuron 1

⋮

$$o_k = f(\vec{x}^T \vec{\omega}_k)$$

define: $W = \begin{bmatrix} - & \vec{\omega}_1 & - \\ & \vdots & \\ - & \vec{\omega}_k & - \end{bmatrix}$

elements in the vector
↓

$$\& \vec{F} = \begin{bmatrix} f(v_1) \\ \vdots \\ f(v_k) \end{bmatrix}$$

then:

$$\underline{\underline{\vec{O} = \vec{F}(W\vec{x})}}$$

... p 14

⑤

compute an update

1) forward pass: we need to know "y"

$$y = w_3 \cdot \max(0, w_1 x_1 + w_2 x_2)$$

$$y = \underline{4}$$

$$\frac{de}{dy} \Big|_{y=4} = -2(2-4) = \underline{4}$$

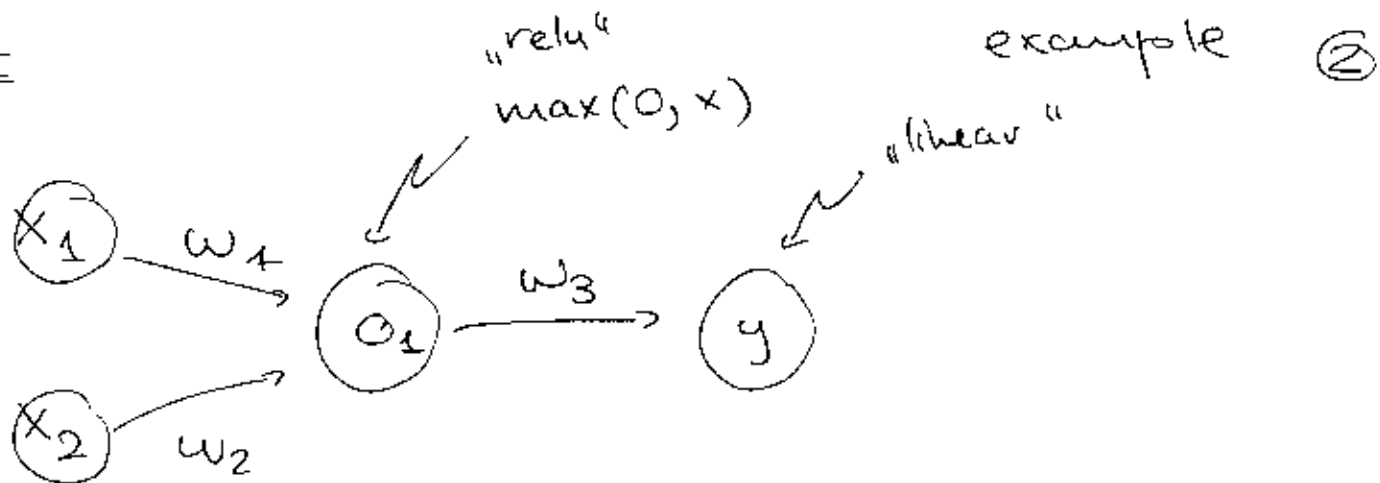
$$\frac{dy}{dw_1} \Big|_{w_3=1} = 1$$

$$\frac{dy}{dw_1} \Big|_{w_1, w_2, x_1, x_2} = 1 \cdot 2 = \underline{2}$$

$$\frac{de}{dw_1} = 4 \cdot 1 \cdot 2 = \underline{8}$$

$$w_1 \leftarrow w_1 - 1 \cdot \frac{de}{dw_1} = 1 - 0.8 = \underline{\underline{0.2}}$$

P 114



$$o_1 = \max(0, w_1 x_1 + w_2 x_2)$$

$$y = w_3 o_1$$

$$e = (y_{\text{target}} - y)^2$$

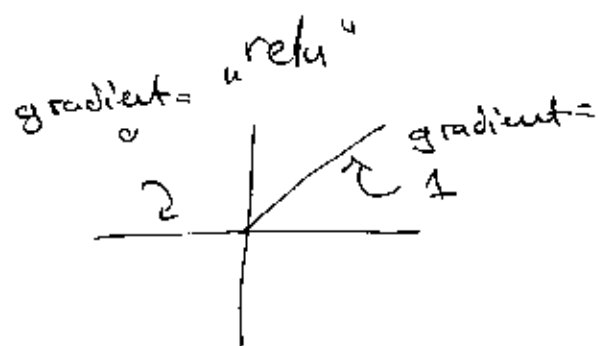
$$\frac{de}{dw_1} = \frac{de}{dy} \cdot \frac{dy}{do_1} \cdot \frac{do_1}{dw_1}$$

“back propagation”

$$\frac{de}{dy} = -2(y_{\text{target}} - y)$$

$$\frac{dy}{do_1} = w_3$$

$$\frac{do_1}{dw_1} = \begin{cases} 1 \cdot x_1 & \text{if } w_1 x_1 + w_2 x_2 > 0 \\ 0 & \text{else} \end{cases}$$



P13

④

- Prediction
- Backpropagation - for optimization
- Yes, for the error computation

P14

- No, functions aren't convex
- Slope: We move along the steepest slope until we reach the lowest point of the valley!
- Gradient $\nabla f = \begin{bmatrix} \frac{df}{dx_1} \\ \vdots \end{bmatrix}$

P15

$$\bullet \quad o_1 = f(\vec{w}_1^T \vec{x}) ; \quad y = \vec{w}_2^T \vec{o}$$

$$\vec{w}_1 = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}, \quad \vec{w}_2 = \begin{bmatrix} w_3 \\ w_4 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \vec{o} = \begin{bmatrix} x_3 \\ o_1 \end{bmatrix}$$

$$o_1 = f(w_1 x_1 + w_2 x_2)$$

$$y = w_3 x_3 + w_4 o_1$$

$$e = (\hat{y}_{target} - y)^2$$

$$\frac{de}{dw_1} = \frac{de}{dy} \cdot \frac{dy}{do_1} \cdot \frac{do_1}{dw_1}$$

... P15

$$\frac{de}{dy} = -2(\bar{y} - y)$$

$$\frac{dy}{do_1} = w_1$$

$$\frac{do_1}{dw_1} = \begin{cases} x_1 & \text{if } w_1 x_1 + w_2 x_2 > 0 \\ 0 & \text{else} \end{cases}$$

update:

$$y = 1 \cdot 1 + 1 \cdot f(1 \cdot 1 + 1 \cdot 1) = \underline{3}$$

$$\frac{de}{dw_1} = 2 \cdot 1 \cdot 1 = \underline{2}$$

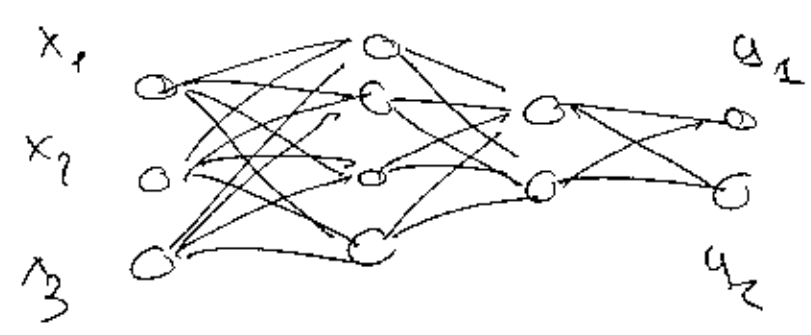
$$\nabla e = \begin{pmatrix} \frac{de}{dw_1} \\ \frac{de}{dw_2} \\ \frac{de}{dw_3} \\ \frac{de}{dw_4} \end{pmatrix} \begin{array}{l} \leftarrow \text{already done} \\ \leftarrow \text{only changes } \frac{do_1}{dw_2} \\ \leftarrow \frac{de}{dy} \cdot \frac{dy}{dw_3} \\ \leftarrow \frac{de}{dy} \cdot \frac{dy}{dw_4} \end{array}$$

$$\frac{do_1}{dw_2} = \begin{cases} x_2 & \text{if } w_1 x_1 + w_2 x_2 > 0 \\ 0 & \text{else} \end{cases}$$

$$\frac{dy}{dw_3} = x_3$$

$$\frac{dy}{dw_4} = 0_1$$

all missing terms



Connecting neuron 1 to neuron 1

Connecting neuron 2 to neuron 1 etc.

$$\vec{O}_1 = \vec{f}(w_1 \vec{X})$$

$$w_1 = \begin{bmatrix} w_{11} & w_{21} & w_{31} \\ \vdots & & \\ w_{14} & \dots & w_{34} \end{bmatrix}_1$$

$$\vec{O}_2 = \vec{f}(w_2 \vec{O}_1)$$

$$w_2 = \begin{bmatrix} w_{11} & w_{21} & w_{31} & w_{41} \\ w_{12} & w_{22} & w_{32} & w_{42} \end{bmatrix}_2$$

$$\vec{y} = \vec{f}(w_3 \vec{O}_2)$$

$$w_3 = \begin{bmatrix} w_{11} & w_{21} \\ w_{12} & w_{22} \end{bmatrix}_3$$

$$\nabla e = \begin{bmatrix} \frac{de}{dw_{11}} \\ \frac{de}{dw_{21}} \\ \vdots \\ \frac{de}{dw_{22}} \end{bmatrix}$$

denotes the layer

\Rightarrow simply all weights in w_1, w_2, w_3

→ nothing new; do as in prev. examples

⇒ one thing to note: We are using the logistic function as activation not the ReLU:

$$g'(x) = g(x) (1 - g(x))$$

(also has an easy gradient)