27

exump le

$$||\vec{x}\omega - \hat{g}||_{2}^{2} = (\vec{x}\omega - \hat{g})^{T}(\vec{x}\omega - \hat{g})$$

$$= \omega^{2} \times T \hat{x} - 2\omega \hat{x}^{T} \hat{g} + \hat{g}^{T} \hat{g}^{T}$$

$$= \partial_{\text{eriuntine}} \partial_{\omega}() = 2\omega \hat{x}^{T} \hat{x}^{2} - 2x^{2} + \hat{g}^{T} \hat{g}^{T}$$

$$- \lambda \omega^{T} = \frac{x^{T} \hat{g}}{x^{T} \hat{x}}$$

78 — example

$$\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \omega = \begin{bmatrix} 0 \\ 1.5 \\ 2.2 \end{bmatrix}$$

 $\frac{d}{d\omega} \left[ (\omega - 1.5)^2 + (2\omega - 2.2)^2 \right] = 0$   $\omega^* = 4.18$ 

thus:

9 = 1.18.10 - 11.8

example

 $\langle \mathcal{Z} \rangle$ 

$$X = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 3 & 9 \end{bmatrix} \quad \hat{y} - \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$$

$$J = \left[ 1 \quad 5 \quad 25 \right] \left[ \begin{array}{c} -1 \\ 2 \\ 0 \end{array} \right] = \frac{9}{4}$$

## 0 16

$$x = \begin{cases} 1 & 1 & 1 \\ 1 & 1 & 4 \\ 1 & 2 & 16 \end{cases} \quad \hat{y} = \begin{bmatrix} 1 & 1 \\ 3 & 5 \end{bmatrix}$$

$$\vec{\omega}^* = \begin{bmatrix} 6.83 \\ -6.0 \\ 0.66 \end{bmatrix}$$

$$y = [1 \ 10 \ 2007 \left[ \frac{6.33}{0.66} \right] = \frac{13}{0.66}$$

$$g = \omega_{\perp} \exp(\omega_{2}x + \omega_{8}x^{2})$$
 |  $l_{No}$   
 $l_{No} g = l_{N}(\omega_{L}) + l_{N} \exp(\omega_{2}x + \omega_{3}x^{2})$   
 $l_{No} g = l_{N}(\omega_{L}) + \omega_{2}x + \omega_{3}x^{2}$   
 $l_{No} g = l_{N}(\omega_{L}) + \omega_{2}x + \omega_{3}x^{2}$   
 $l_{No} g = l_{N}(\omega_{L}) + \omega_{2}x + \omega_{3}x^{2}$ 

## P 18

$$X = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix}$$

=> if we can compute the eigenvalues

they are the same as the eigenvalues

$$Z_1 = 0.5$$
,  $Z_2 = 1$ ,  $Z_3 = 2$ 

$$K = \frac{L}{6.5} = 4$$
 well confund



$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

$$= \vec{q}^{T}\vec{q} - \vec{q}^{T} \times \vec{\omega} - \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{x}^{T}$$

$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

$$= \vec{q}^{T}\vec{q} - \vec{q}^{T} \times \vec{\omega} - \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{x}^{T}$$

$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

$$= \vec{q}^{T}\vec{q} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times \vec{\omega} - \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{x}^{T}$$

$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

$$= \vec{q}^{T}\vec{q} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times \vec{\omega} - \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{x}^{T} \times \vec{\omega}$$

$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

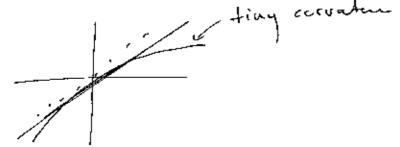
$$= \vec{q}^{T}\vec{q} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times \vec{\omega} - \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{x}^{T} \times \vec{\omega}$$

$$|| X\vec{\omega} - \vec{q} ||_{Q^{2}} = (X\vec{\omega} - \vec{q})^{T} (X\vec{\omega} - \vec{q})$$

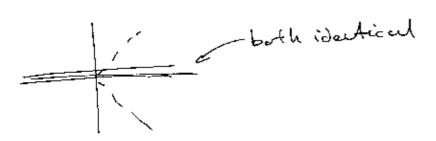
$$= \vec{q}^{T}\vec{q} + \vec{\omega}^{T} \times^{T} \vec{q} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times^{T} \vec{q}^{T} \times^{T} \vec{q}^{T} + \vec{\omega}^{T} \times$$

$$-x \omega^{x} = (x^{T}x)^{-1} \times \vec{y}$$

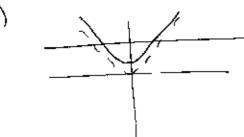




p)



c)



$$\omega_{t}^{T} = \operatorname{argmin} \sum_{i \neq j} (\omega_{t} - \omega_{t})^{2}$$

$$+ (x_{t} + \omega_{t} - x_{j} - \omega_{t} - \varepsilon_{j})^{2}$$

$$= (\lambda - 1)(\omega_{t} - \omega_{t}) + 2(\omega_{t} - \omega_{t} - \varepsilon_{j})^{-1} = 0$$

$$= (\lambda - 1)(\omega_{t} - \omega_{t}) + \omega_{t} - \omega_{t}^{T} - \varepsilon_{j} = 0$$

$$= (\lambda - 1)(\omega_{t} - \omega_{t}) + \omega_{t}^{T} - \omega_{t}^{T} = 0$$

$$\times \vec{\omega} = \vec{q} \Rightarrow \vec{\omega}^* - x^{-1}\vec{g} = \begin{bmatrix} 2 \\ 10 \\ 0 \end{bmatrix}$$