

PIC16F882/883/884/886/887

Data Sheet

28/40/44-Pin, Enhanced Flash-Based 8-Bit
CMOS Microcontrollers with
nanoWatt Technology

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights.

Trademarks

The Microchip name and logo, the Microchip logo, Accuron, dsPIC, KEELOQ, KEELOQ logo, MPLAB, PIC, PICmicro, PICSTART, PRO MATE, rfPIC and SmartShunt are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

AmpLab, FilterLab, Linear Active Thermistor, MXDEV, MXLAB, SEEVAL, SmartSensor and The Embedded Control Solutions Company are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Analog-for-the-Digital Age, Application Maestro, CodeGuard, dsPICDEM, dsPICDEM.net, dsPICworks, dsSPEAK, ECAN, ECONOMONITOR, FanSense, In-Circuit Serial Programming, ICSP, ICEPIC, Mindi, MiWi, MPASM, MPLAB Certified logo, MPLIB, MPLINK, mTouch, PICkit, PICDEM, PICDEM.net, PICtail, PowerCal, PowerInfo, PowerMate, PowerTool, REAL ICE, rfLAB, Select Mode, Total Endurance, UNI/O, WiperLock and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

SQTP is a service mark of Microchip Technology Incorporated in the U.S.A.

All other trademarks mentioned herein are property of their respective companies.

© 2008, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

 Printed on recycled paper.

**QUALITY MANAGEMENT SYSTEM
CERTIFIED BY DNV
= ISO/TS 16949:2002 =**

Microchip received ISO/TS-16949:2002 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company's quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELOQ® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip's quality system for the design and manufacture of development systems is ISO 9001:2000 certified.



MICROCHIP

PIC16F882/883/884/886/887

28/40/44-Pin Flash-Based, 8-Bit CMOS Microcontrollers with nanoWatt Technology

High-Performance RISC CPU:

- Only 35 Instructions to Learn:
 - All single-cycle instructions except branches
- Operating Speed:
 - DC – 20 MHz oscillator/clock input
 - DC – 200 ns instruction cycle
- Interrupt Capability
- 8-Level Deep Hardware Stack
- Direct, Indirect and Relative Addressing modes

Special Microcontroller Features:

- Precision Internal Oscillator:
 - Factory calibrated to $\pm 1\%$
 - Software selectable frequency range of 8 MHz to 31 kHz
 - Software tunable
 - Two-Speed Start-up mode
 - Crystal fail detect for critical applications
 - Clock mode switching during operation for power savings
- Power-Saving Sleep mode
- Wide Operating Voltage Range (2.0V-5.5V)
- Industrial and Extended Temperature Range
- Power-on Reset (POR)
- Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Brown-out Reset (BOR) with Software Control Option
- Enhanced Low-Current Watchdog Timer (WDT) with On-Chip Oscillator (software selectable nominal 268 seconds with full prescaler) with software enable
- Multiplexed Master Clear with Pull-up/Input Pin
- Programmable Code Protection
- High Endurance Flash/EEPROM Cell:
 - 100,000 write Flash endurance
 - 1,000,000 write EEPROM endurance
 - Flash/Data EEPROM retention: > 40 years
- Program Memory Read/Write during run time
- In-Circuit Debugger (on board)

Low-Power Features:

- Standby Current:
 - 50 nA @ 2.0V, typical
- Operating Current:
 - 11 μ A @ 32 kHz, 2.0V, typical
 - 220 μ A @ 4 MHz, 2.0V, typical
- Watchdog Timer Current:
 - 1 μ A @ 2.0V, typical

Peripheral Features:

- 24/35 I/O Pins with Individual Direction Control:
 - High current source/sink for direct LED drive
 - Interrupt-on-Change pin
 - Individually programmable weak pull-ups
 - Ultra Low-Power Wake-up (ULPWU)
- Analog Comparator Module with:
 - Two analog comparators
 - Programmable on-chip voltage reference (CVREF) module (% of VDD)
 - Fixed voltage reference (0.6V)
 - Comparator inputs and outputs externally accessible
 - SR Latch mode
 - External Timer1 Gate (count enable)
- A/D Converter:
 - 10-bit resolution and 11/14 channels
- Timer0: 8-bit Timer/Counter with 8-bit Programmable Prescaler
- Enhanced Timer1:
 - 16-bit timer/counter with prescaler
 - External Gate Input mode
 - Dedicated low-power 32 kHz oscillator
- Timer2: 8-bit Timer/Counter with 8-bit Period Register, Prescaler and Postscaler
- Enhanced Capture, Compare, PWM+ Module:
 - 16-bit Capture, max. resolution 12.5 ns
 - Compare, max. resolution 200 ns
 - 10-bit PWM with 1, 2 or 4 output channels, programmable “dead time”, max. frequency 20 kHz
 - PWM output steering control
- Capture, Compare, PWM Module:
 - 16-bit Capture, max. resolution 12.5 ns
 - 16-bit Compare, max. resolution 200 ns
 - 10-bit PWM, max. frequency 20 kHz
- Enhanced USART Module:
 - Supports RS-485, RS-232, and LIN 2.0
 - Auto-Baud Detect
 - Auto-Wake-Up on Start bit
- In-Circuit Serial Programming™ (ICSP™) via Two Pins
- Master Synchronous Serial Port (MSSP) Module supporting 3-wire SPI (all 4 modes) and I²C™ Master and Slave Modes with I²C Address Mask

PIC16F882/883/884/886/887

Device	Program Memory	Data Memory		I/O	10-bit A/D (ch)	ECCP/ CCP	EUSART	MSSP	Comparators	Timers 8/16-bit
	Flash (words)	SRAM (bytes)	EEPROM (bytes)							
PIC16F882	2048	128	128	24	11	1/1	1	1	2	2/1
PIC16F883	4096	256	256	24	11	1/1	1	1	2	2/1
PIC16F884	4096	256	256	35	14	1/1	1	1	2	2/1
PIC16F886	8192	368	256	24	11	1/1	1	1	2	2/1
PIC16F887	8192	368	256	35	14	1/1	1	1	2	2/1

PIC16F882/883/884/886/887

Pin Diagrams – PIC16F882/883/886, 28-Pin PDIP, SOIC, SSOP

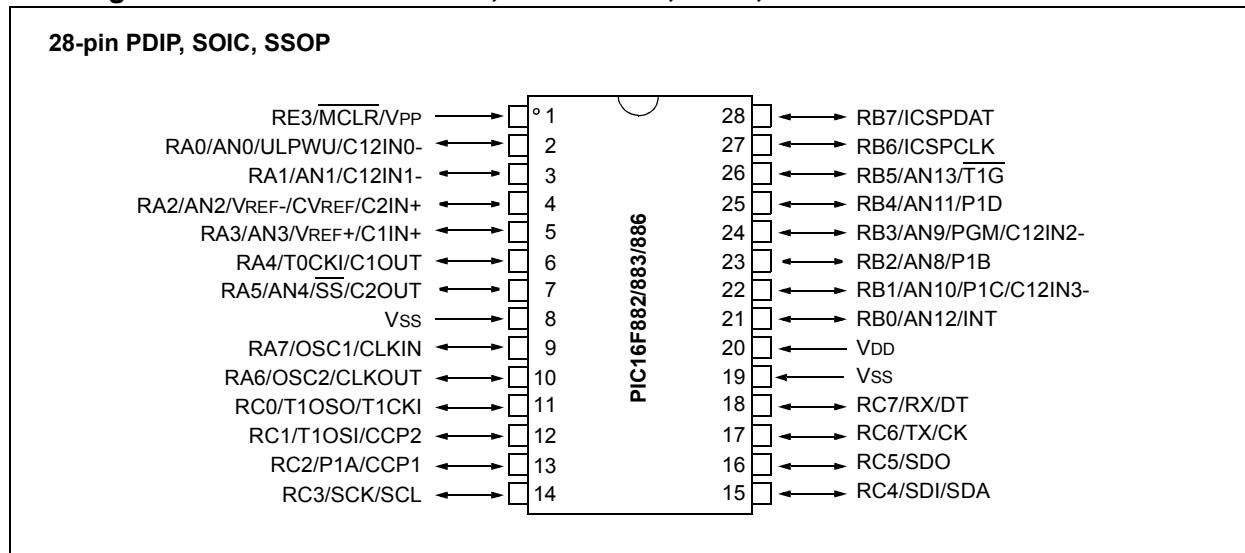


TABLE 1: PIC16F882/883/886 28-PIN SUMMARY (PDIP, SOIC, SSOP)

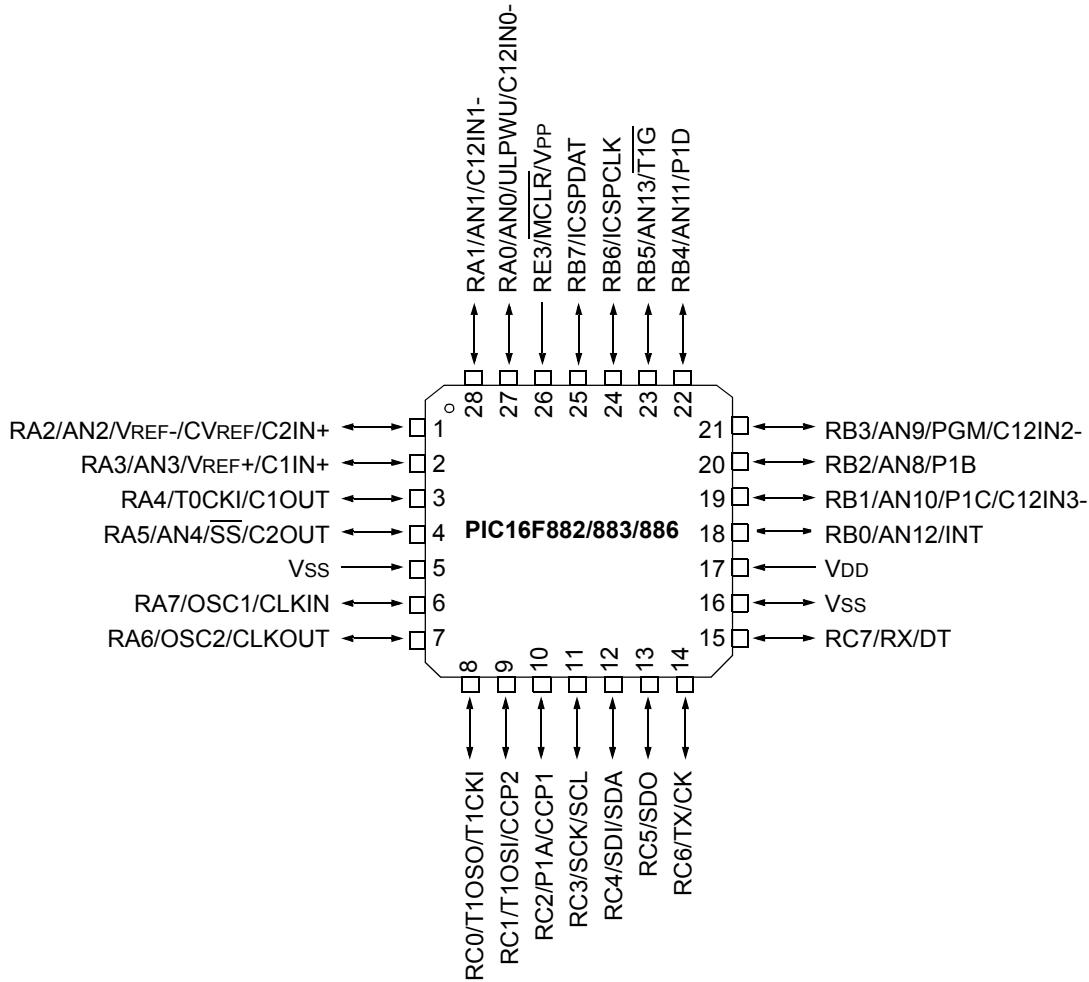
I/O	Pin	Analog	Comparators	Timers	ECCP	EUSART	MSSP	Interrupt	Pull-up	Basic
RA0	2	AN0/ULPWU	C12IN0-	—	—	—	—	—	—	—
RA1	3	AN1	C12IN1-	—	—	—	—	—	—	—
RA2	4	AN2	C2IN+	—	—	—	—	—	—	VREF-/CVREF
RA3	5	AN3	C1IN+	—	—	—	—	—	—	VREF+
RA4	6	—	C1OUT	T0CKI	—	—	—	—	—	—
RA5	7	AN4	C2OUT	—	—	—	SS	—	—	—
RA6	10	—	—	—	—	—	—	—	—	OSC2/CLKOUT
RA7	9	—	—	—	—	—	—	—	—	OSC1/CLKIN
RB0	21	AN12	—	—	—	—	—	IOC/INT	Y	—
RB1	22	AN10	C12IN3-	—	P1C	—	—	IOC	Y	—
RB2	23	AN8	—	—	P1B	—	—	IOC	Y	—
RB3	24	AN9	C12IN2-	—	—	—	—	IOC	Y	PGM
RB4	25	AN11	—	—	P1D	—	—	IOC	Y	—
RB5	26	AN13	—	T1G	—	—	—	IOC	Y	—
RB6	27	—	—	—	—	—	—	IOC	Y	ICSPCLK
RB7	28	—	—	—	—	—	—	IOC	Y	ICSPDAT
RC0	11	—	—	T1OSO/T1CKI	—	—	—	—	—	—
RC1	12	—	—	T1OSI	CCP2	—	—	—	—	—
RC2	13	—	—	—	CCP1/P1A	—	—	—	—	—
RC3	14	—	—	—	—	—	SCK/SCL	—	—	—
RC4	15	—	—	—	—	—	SDI/SDA	—	—	—
RC5	16	—	—	—	—	—	SDO	—	—	—
RC6	17	—	—	—	—	TX/CK	—	—	—	—
RC7	18	—	—	—	—	RX/DT	—	—	—	—
RE3	1	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/VPP
—	20	—	—	—	—	—	—	—	—	VDD
—	8	—	—	—	—	—	—	—	—	Vss
—	19	—	—	—	—	—	—	—	—	Vss

Note 1: Pull-up activated only with external MCLR configuration.

PIC16F882/883/884/886/887

Pin Diagrams – PIC16F882/883/886, 28-Pin QFN

28-pin QFN



PIC16F882/883/884/886/887

TABLE 2: PIC16F882/883/886 28-PIN SUMMARY (QFN)

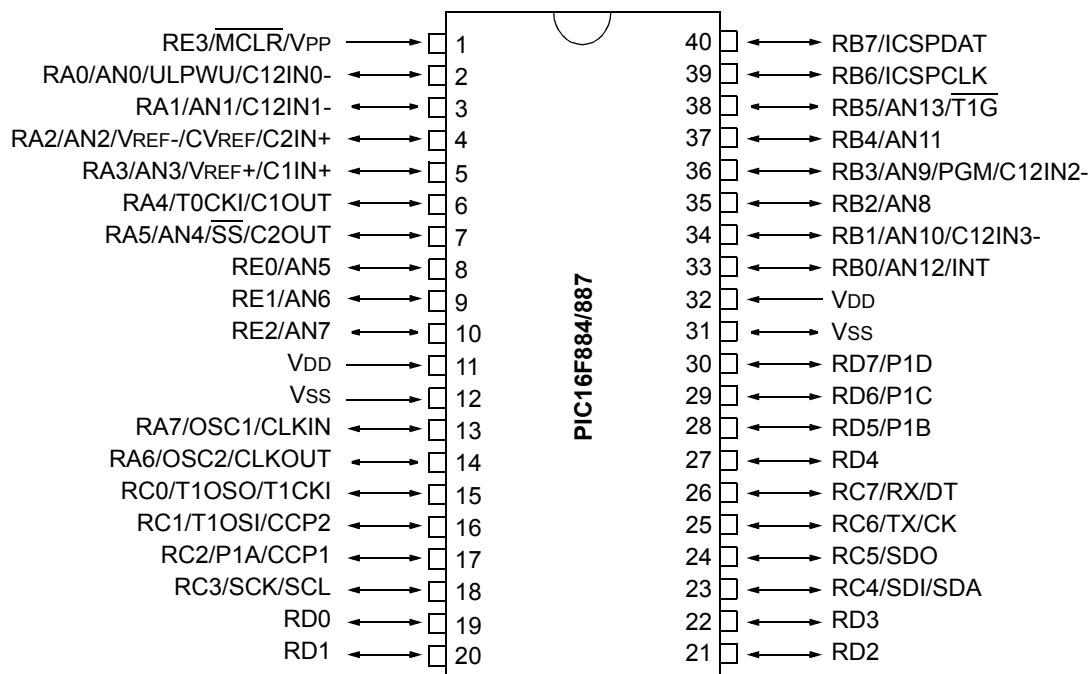
I/O	Pin	Analog	Comparators	Timers	ECCP	EUSART	MSSP	Interrupt	Pull-up	Basic
RA0	27	AN0/ULPWU	C12IN0-	—	—	—	—	—	—	—
RA1	28	AN1	C12IN1-	—	—	—	—	—	—	—
RA2	1	AN2	C2IN+	—	—	—	—	—	—	VREF-/CVREF
RA3	2	AN3	C1IN+	—	—	—	—	—	—	VREF+
RA4	3	—	C1OUT	T0CKI	—	—	—	—	—	—
RA5	4	AN4	C2OUT	—	—	—	SS	—	—	—
RA6	7	—	—	—	—	—	—	—	—	OSC2/CLKOUT
RA7	6	—	—	—	—	—	—	—	—	OSC1/CLKIN
RB0	18	AN12	—	—	—	—	—	IOC/INT	Y	—
RB1	19	AN10	C12IN3-	—	P1C	—	—	IOC	Y	—
RB2	20	AN8	—	—	P1B	—	—	IOC	Y	—
RB3	21	AN9	C12IN2-	—	—	—	—	IOC	Y	PGM
RB4	22	AN11	—	—	P1D	—	—	IOC	Y	—
RB5	23	AN13	—	—	—	—	—	IOC	Y	—
RB6	24	—	—	—	—	—	—	IOC	Y	ICSPCLK
RB7	25	—	—	—	—	—	—	IOC	Y	ICSPDAT
RC0	8	—	—	T1OSO/T1CKI	—	—	—	—	—	—
RC1	9	—	—	T1OSI	CCP2	—	—	—	—	—
RC2	10	—	—	—	CCP1/P1A	—	—	—	—	—
RC3	11	—	—	—	—	—	SCK/SCL	—	—	—
RC4	12	—	—	—	—	—	SDI/SDA	—	—	—
RC5	13	—	—	—	—	—	SDO	—	—	—
RC6	14	—	—	—	—	TX/CK	—	—	—	—
RC7	15	—	—	—	—	RX/DT	—	—	—	—
RE3	26	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/VPP
—	17	—	—	—	—	—	—	—	—	VDD
—	5	—	—	—	—	—	—	—	—	VSS
—	16	—	—	—	—	—	—	—	—	VSS

Note 1: Pull-up activated only with external MCLR configuration.

PIC16F882/883/884/886/887

Pin Diagrams – PIC16F884/887, 40-Pin PDIP

40-pin PDIP



PIC16F882/883/884/886/887

TABLE 3: PIC16F884/887 40-PIN SUMMARY (PDIP)

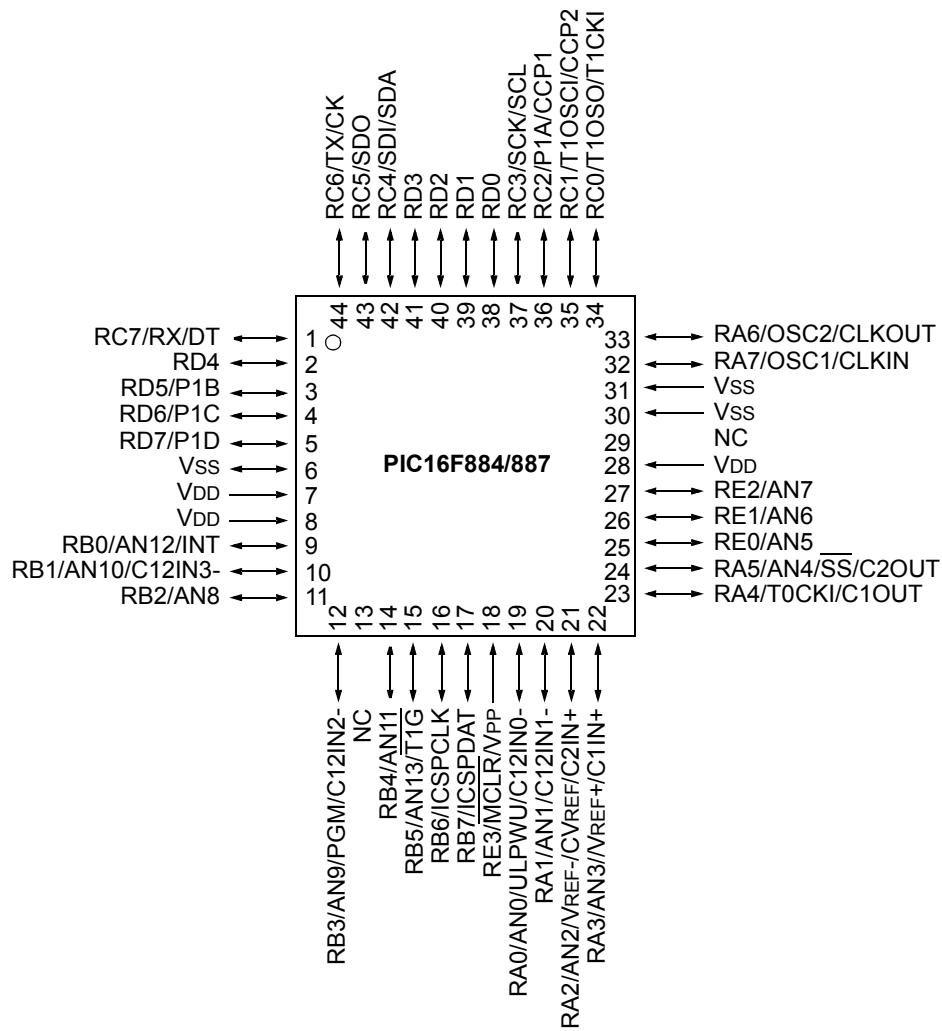
I/O	Pin	Analog	Comparators	Timers	ECCP	EUSART	MSSP	Interrupt	Pull-up	Basic
RA0	2	AN0/ULPWU	C12IN0-	—	—	—	—	—	—	—
RA1	3	AN1	C12IN1-	—	—	—	—	—	—	—
RA2	4	AN2	C2IN+	—	—	—	—	—	—	VREF-/CVREF
RA3	5	AN3	C1IN+	—	—	—	—	—	—	VREF+
RA4	6	—	C1OUT	T0CKI	—	—	—	—	—	—
RA5	7	AN4	C2OUT	—	—	—	SS	—	—	—
RA6	14	—	—	—	—	—	—	—	—	OSC2/CLKOUT
RA7	13	—	—	—	—	—	—	—	—	OSC1/CLKIN
RB0	33	AN12	—	—	—	—	—	IOC/INT	Y	—
RB1	34	AN10	C12IN3-	—	—	—	—	IOC	Y	—
RB2	35	AN8	—	—	—	—	—	IOC	Y	—
RB3	36	AN9	C12IN2-	—	—	—	—	IOC	Y	PGM
RB4	37	AN11	—	—	—	—	—	IOC	Y	—
RB5	38	AN13	—	T1G	—	—	—	IOC	Y	—
RB6	39	—	—	—	—	—	—	IOC	Y	ICSPCLK
RB7	40	—	—	—	—	—	—	IOC	Y	ICSPDAT
RC0	15	—	—	T1OSO/T1CKI	—	—	—	—	—	—
RC1	16	—	—	T1OSI	CCP2	—	—	—	—	—
RC2	17	—	—	—	CCP1/P1A	—	—	—	—	—
RC3	18	—	—	—	—	—	SCK/SCL	—	—	—
RC4	23	—	—	—	—	—	SDI/SDA	—	—	—
RC5	24	—	—	—	—	—	SDO	—	—	—
RC6	25	—	—	—	—	TX/CK	—	—	—	—
RC7	26	—	—	—	—	RX/DT	—	—	—	—
RD0	19	—	—	—	—	—	—	—	—	—
RD1	20	—	—	—	—	—	—	—	—	—
RD2	21	—	—	—	—	—	—	—	—	—
RD3	22	—	—	—	—	—	—	—	—	—
RD4	27	—	—	—	—	—	—	—	—	—
RD5	28	—	—	—	P1B	—	—	—	—	—
RD6	29	—	—	—	P1C	—	—	—	—	—
RD7	30	—	—	—	P1D	—	—	—	—	—
RE0	8	AN5	—	—	—	—	—	—	—	—
RE1	9	AN6	—	—	—	—	—	—	—	—
RE2	10	AN7	—	—	—	—	—	—	—	—
RE3	1	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/VPP
—	11	—	—	—	—	—	—	—	—	VDD
—	32	—	—	—	—	—	—	—	—	VDD
—	12	—	—	—	—	—	—	—	—	Vss
—	31	—	—	—	—	—	—	—	—	Vss

Note 1: Pull-up activated only with external MCLR configuration.

PIC16F882/883/884/886/887

Pin Diagrams – PIC16F884/887, 44-Pin QFN

44-pin QFN



PIC16F882/883/884/886/887

TABLE 4: PIC16F884/887 44-PIN SUMMARY (QFN)

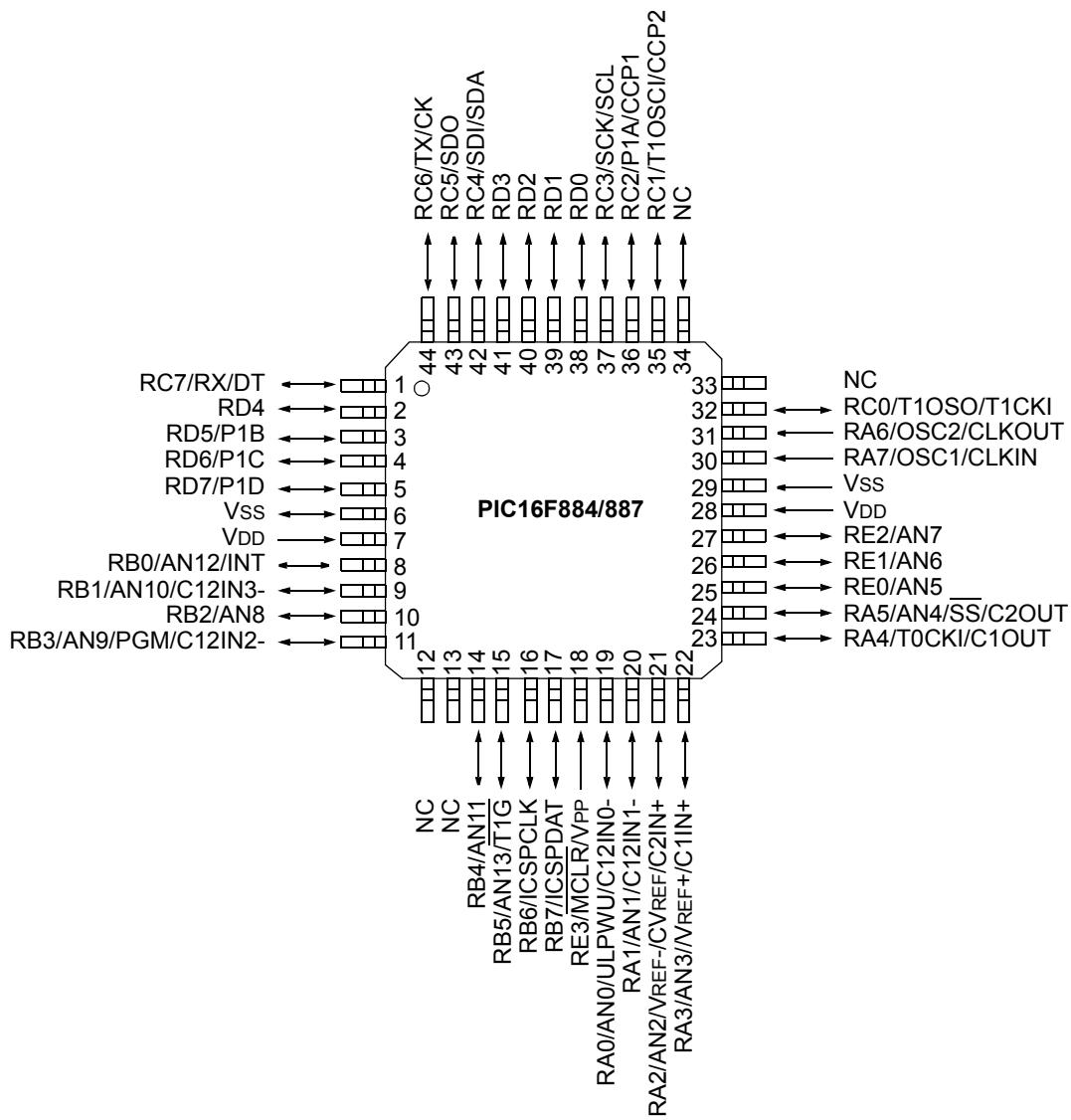
I/O	Pin	Analog	Comparators	Timers	ECCP	EUSART	MSSP	Interrupt	Pull-up	Basic
RA0	19	AN0/ULPWU	C12IN0-	—	—	—	—	—	—	—
RA1	20	AN1	C12IN1-	—	—	—	—	—	—	—
RA2	21	AN2	C2IN+	—	—	—	—	—	—	VREF-/CVREF
RA3	22	AN3	C1IN+	—	—	—	—	—	—	VREF+
RA4	23	—	C1OUT	T0CKI	—	—	—	—	—	—
RA5	24	AN4	C2OUT	—	—	—	SS	—	—	—
RA6	33	—	—	—	—	—	—	—	—	OSC2/CLKOUT
RA7	32	—	—	—	—	—	—	—	—	OSC1/CLKIN
RB0	9	AN12	—	—	—	—	—	IOC/INT	Y	—
RB1	10	AN10	C12IN3-	—	—	—	—	IOC	Y	—
RB2	11	AN8	—	—	—	—	—	IOC	Y	—
RB3	12	AN9	C12IN2-	—	—	—	—	IOC	Y	PGM
RB4	14	AN11	—	—	—	—	—	IOC	Y	—
RB5	15	AN13	—	T1G	—	—	—	IOC	Y	—
RB6	16	—	—	—	—	—	—	IOC	Y	ICSPCLK
RB7	17	—	—	—	—	—	—	IOC	Y	ICSPDAT
RC0	34	—	—	T1OSO/T1CKI	—	—	—	—	—	—
RC1	35	—	—	T1OSI	CCP2	—	—	—	—	—
RC2	36	—	—	—	CCP1/P1A	—	—	—	—	—
RC3	37	—	—	—	—	—	SCK/SCL	—	—	—
RC4	42	—	—	—	—	—	SDI/SDA	—	—	—
RC5	43	—	—	—	—	—	SDO	—	—	—
RC6	44	—	—	—	—	TX/CK	—	—	—	—
RC7	1	—	—	—	—	RX/DT	—	—	—	—
RD0	38	—	—	—	—	—	—	—	—	—
RD1	39	—	—	—	—	—	—	—	—	—
RD2	40	—	—	—	—	—	—	—	—	—
RD3	41	—	—	—	—	—	—	—	—	—
RD4	2	—	—	—	—	—	—	—	—	—
RD5	3	—	—	—	P1B	—	—	—	—	—
RD6	4	—	—	—	P1C	—	—	—	—	—
RD7	5	—	—	—	P1D	—	—	—	—	—
RE0	25	AN5	—	—	—	—	—	—	—	—
RE1	26	AN6	—	—	—	—	—	—	—	—
RE2	27	AN7	—	—	—	—	—	—	—	—
RE3	18	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/VPP
—	7	—	—	—	—	—	—	—	—	VDD
—	8	—	—	—	—	—	—	—	—	VDD
—	28	—	—	—	—	—	—	—	—	VDD
—	6	—	—	—	—	—	—	—	—	VSS
—	30	—	—	—	—	—	—	—	—	VSS
—	31	—	—	—	—	—	—	—	—	VSS
—	13	—	—	—	—	—	—	—	—	NC (no connect)
—	29	—	—	—	—	—	—	—	—	NC (no connect)

Note 1: Pull-up activated only with external MCLR configuration.

PIC16F882/883/884/886/887

Pin Diagrams – PIC16F884/887, 44-Pin TQFP

44-pin TQFP



PIC16F882/883/884/886/887

TABLE 5: PIC16F884/887 44-PIN SUMMARY (TQFP)

I/O	Pin	Analog	Comparators	Timers	ECCP	EUSART	MSSP	Interrupt	Pull-up	Basic
RA0	19	AN0/ULPWU	C12IN0-	—	—	—	—	—	—	—
RA1	20	AN1	C12IN1-	—	—	—	—	—	—	—
RA2	21	AN2	C2IN+	—	—	—	—	—	—	VREF-/CVREF
RA3	22	AN3	C1IN+	—	—	—	—	—	—	VREF+
RA4	23	—	C1OUT	T0CKI	—	—	—	—	—	—
RA5	24	AN4	C2OUT	—	—	—	SS	—	—	—
RA6	31	—	—	—	—	—	—	—	—	OSC2/CLKOUT
RA7	30	—	—	—	—	—	—	—	—	OSC1/CLKIN
RB0	8	AN12	—	—	—	—	—	IOC/INT	Y	—
RB1	9	AN10	C12IN3-	—	—	—	—	IOC	Y	—
RB2	10	AN8	—	—	—	—	—	IOC	Y	—
RB3	11	AN9	C12IN2-	—	—	—	—	IOC	Y	PGM
RB4	14	AN11	—	—	—	—	—	IOC	Y	—
RB5	15	AN13	—	T1G	—	—	—	IOC	Y	—
RB6	16	—	—	—	—	—	—	IOC	Y	ICSPCLK
RB7	17	—	—	—	—	—	—	IOC	Y	ICSPDAT
RC0	32	—	—	T1OSO/T1CKI	—	—	—	—	—	—
RC1	35	—	—	T1OSI	CCP2	—	—	—	—	—
RC2	36	—	—	—	CCP1/P1A	—	—	—	—	—
RC3	37	—	—	—	—	—	SCK/SCL	—	—	—
RC4	42	—	—	—	—	—	SDI/SDA	—	—	—
RC5	43	—	—	—	—	—	SDO	—	—	—
RC6	44	—	—	—	—	TX/CK	—	—	—	—
RC7	1	—	—	—	—	RX/DT	—	—	—	—
RD0	38	—	—	—	—	—	—	—	—	—
RD1	39	—	—	—	—	—	—	—	—	—
RD2	40	—	—	—	—	—	—	—	—	—
RD3	41	—	—	—	—	—	—	—	—	—
RD4	2	—	—	—	—	—	—	—	—	—
RD5	3	—	—	—	P1B	—	—	—	—	—
RD6	4	—	—	—	P1C	—	—	—	—	—
RD7	5	—	—	—	P1D	—	—	—	—	—
RE0	25	AN5	—	—	—	—	—	—	—	—
RE1	26	AN6	—	—	—	—	—	—	—	—
RE2	27	AN7	—	—	—	—	—	—	—	—
RE3	18	—	—	—	—	—	—	—	Y ⁽¹⁾	MCLR/VPP
—	7	—	—	—	—	—	—	—	—	VDD
—	28	—	—	—	—	—	—	—	—	VDD
—	6	—	—	—	—	—	—	—	—	Vss
—	13	—	—	—	—	—	—	—	—	NC (no connect)
—	29	—	—	—	—	—	—	—	—	Vss
—	34	—	—	—	—	—	—	—	—	NC (no connect)
—	33	—	—	—	—	—	—	—	—	NC (no connect)
—	12	—	—	—	—	—	—	—	—	NC (no connect)

Note 1: Pull-up activated only with external MCLR configuration.

PIC16F882/883/884/886/887

Table of Contents

1.0	Device Overview	13
2.0	Memory Organization	21
3.0	I/O Ports	39
4.0	Oscillator Module (With Fail-Safe Clock Monitor).....	61
5.0	Timer0 Module	73
6.0	Timer1 Module with Gate Control.....	76
7.0	Timer2 Module	81
8.0	Comparator Module.....	83
9.0	Analog-to-Digital Converter (ADC) Module	99
10.0	Data EEPROM and Flash Program Memory Control	111
11.0	Enhanced Capture/Compare/PWM Module	123
12.0	Enhanced Universal Synchronous Asynchronous Receiver Transmitter (EUSART).....	151
13.0	Master Synchronous Serial Port (MSSP) Module	179
14.0	Special Features of the CPU	209
15.0	Instruction Set Summary	231
16.0	Development Support.....	241
17.0	Electrical Specifications.....	245
18.0	DC and AC Characteristics Graphs and Tables	273
19.0	Packaging Information.....	301
Appendix A: Data Sheet Revision History		313
Appendix B: Migrating from other PIC® Devices		313
Index		315
The Microchip Web Site		323
Customer Change Notification Service		323
Customer Support		323
Reader Response		324
Product Identification System.....		325

TO OUR VALUED CUSTOMERS

It is our intention to provide our valued customers with the best documentation possible to ensure successful use of your Microchip products. To this end, we will continue to improve our publications to better suit your needs. Our publications will be refined and enhanced as new volumes and updates are introduced.

If you have any questions or comments regarding this publication, please contact the Marketing Communications Department via E-mail at docerrors@microchip.com or fax the **Reader Response Form** in the back of this data sheet to (480) 792-4150. We welcome your feedback.

Most Current Data Sheet

To obtain the most up-to-date version of this data sheet, please register at our Worldwide Web site at:

<http://www.microchip.com>

You can determine the version of a data sheet by examining its literature number found on the bottom outside corner of any page. The last character of the literature number is the version number, (e.g., DS30000A is version A of document DS30000).

Errata

An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

To determine if an errata sheet exists for a particular device, please check with one of the following:

- Microchip's Worldwide Web site; <http://www.microchip.com>
- Your local Microchip sales office (see last page)

When contacting a sales office, please specify which device, revision of silicon and data sheet (include literature number) you are using.

Customer Notification System

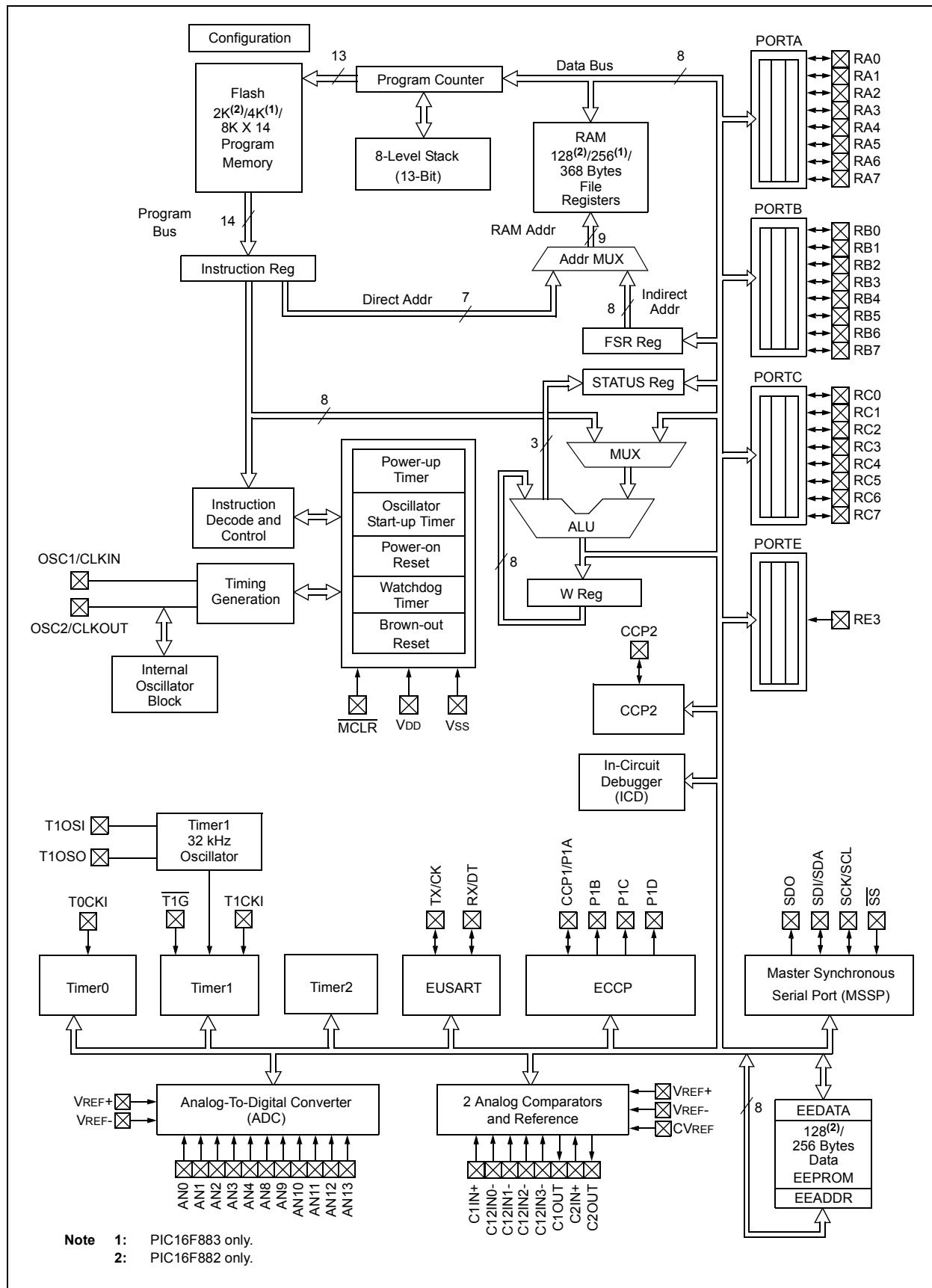
Register on our web site at www.microchip.com to receive the most current information on all of our products.

1.0 DEVICE OVERVIEW

The PIC16F882/883/884/886/887 is covered by this data sheet. The PIC16F882/883/886 is available in 28-pin PDIP, SOIC, SSOP and QFN packages. The PIC16F884/887 is available in a 40-pin PDIP and 44-pin QFN and TQFP packages. Figure 1-1 shows the block diagram of PIC16F882/883/886 and Figure 1-2 shows a block diagram of the PIC16F884/887 device. Table 1-1 and Table 1-2 show the corresponding pinout descriptions.

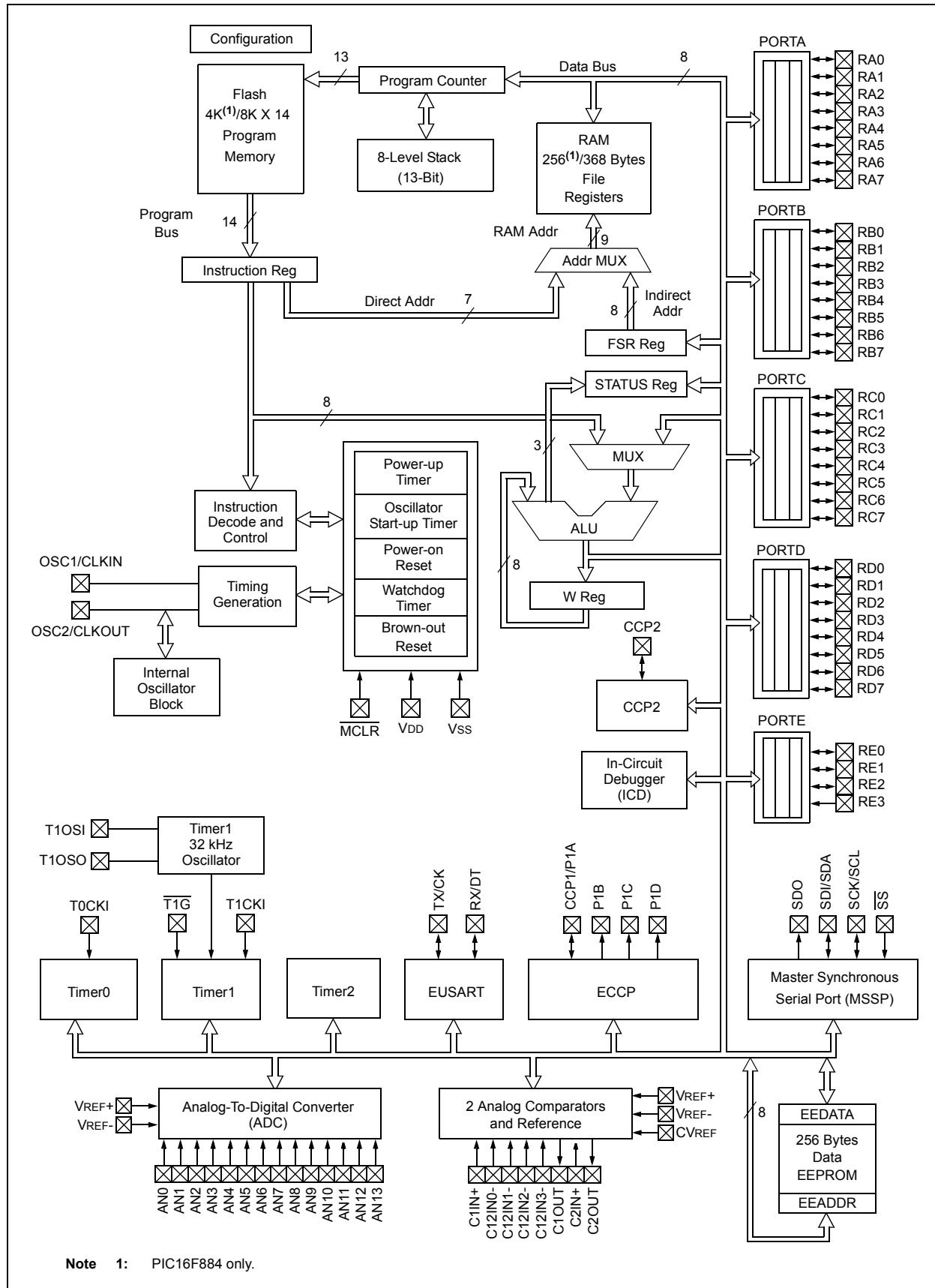
PIC16F882/883/884/886/887

FIGURE 1-1: PIC16F882/883/884/886 BLOCK DIAGRAM



PIC16F882/883/884/886/887

FIGURE 1-2: PIC16F884/PIC16F887 BLOCK DIAGRAM



PIC16F882/883/884/886/887

TABLE 1-1: PIC16F882/883/886 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/AN0/ULPWU/C12IN0-	RA0	TTL	CMOS	General purpose I/O.
	AN0	AN	—	A/D Channel 0 input.
	ULPWU	AN	—	Ultra Low-Power Wake-up input.
	C12IN0-	AN	—	Comparator C1 or C2 negative input.
RA1/AN1/C12IN1-	RA1	TTL	CMOS	General purpose I/O.
	AN1	AN	—	A/D Channel 1 input.
	C12IN1-	AN	—	Comparator C1 or C2 negative input.
RA2/AN2/VREF-/CVREF/C2IN+	RA2	TTL	CMOS	General purpose I/O.
	AN2	AN	—	A/D Channel 2.
	VREF-	AN	—	A/D Negative Voltage Reference input.
	CVREF	—	AN	Comparator Voltage Reference output.
	C2IN+	AN	—	Comparator C2 positive input.
RA3/AN3/VREF+/C1IN+	RA3	TTL	—	General purpose I/O.
	AN3	AN	—	A/D Channel 3.
	VREF+	AN	—	Programming voltage.
	C1IN+	AN	—	Comparator C1 positive input.
RA4/T0CKI/C1OUT	RA4	TTL	CMOS	General purpose I/O.
	T0CKI	ST	—	Timer0 clock input.
	C1OUT	—	CMOS	Comparator C1 output.
RA5/AN4/SS/C2OUT	RA5	TTL	CMOS	General purpose I/O.
	AN4	AN	—	A/D Channel 4.
	SS	ST	—	Slave Select input.
	C2OUT	—	CMOS	Comparator C2 output.
RA6/OSC2/CLKOUT	RA6	TTL	CMOS	General purpose I/O.
	OSC2	—	XTAL	Master Clear with internal pull-up.
	CLKOUT	—	CMOS	Fosc/4 output.
RA7/OSC1/CLKIN	RA7	TTL	CMOS	General purpose I/O.
	OSC1	XTAL	—	Crystal/Resonator.
	CLKIN	ST	—	External clock input/RC oscillator connection.
RB0/AN12/INT	RB0	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN12	AN	—	A/D Channel 12.
	INT	ST	—	External interrupt.
RB1/AN10/P1C/C12IN3-	RB1	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN10	AN	—	A/D Channel 10.
	P1C	—	CMOS	PWM output.
	C12IN3-	AN	—	Comparator C1 or C2 negative input.
RB2/AN8/P1B	RB2	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN8	AN	—	A/D Channel 8.
	P1B	—	CMOS	PWM output.

Legend: AN = Analog input or output
 TTL = TTL compatible input
 HV = High Voltage

CMOS = CMOS compatible input or output
 ST = Schmitt Trigger input with CMOS levels
 XTAL = Crystal

PIC16F882/883/884/886/887

TABLE 1-1: PIC16F882/883/886 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RB3/AN9/PGM/C12IN2-	RB3	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN9	AN	—	A/D Channel 9.
	PGM	ST	—	Low-voltage ICSP™ Programming enable pin.
	C12IN2-	AN	—	Comparator C1 or C2 negative input.
RB4/AN11/P1D	RB4	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN11	AN	—	A/D Channel 11.
	P1D	—	CMOS	PWM output.
RB5/AN13/T1G	RB5	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN13	AN	—	A/D Channel 13.
	T1G	ST	—	Timer1 Gate input.
RB6/ICSPCLK	RB6	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPCLK	ST	—	Serial Programming Clock.
RB7/ICSPDAT	RB7	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPDAT	ST	CMOS	ICSP™ Data I/O.
RC0/T1OSO/T1CKI	RC0	ST	CMOS	General purpose I/O.
	T1OSO	—	CMOS	Timer1 oscillator output.
	T1CKI	ST	—	Timer1 clock input.
RC1/T1OSI/CCP2	RC1	ST	CMOS	General purpose I/O.
	T1OSI	ST	—	Timer1 oscillator input.
	CCP2	ST	CMOS	Capture/Compare/PWM2.
RC2/P1A/CCP1	RC2	ST	CMOS	General purpose I/O.
	P1A	—	CMOS	PWM output.
	CCP1	ST	CMOS	Capture/Compare/PWM1.
RC3/SCK/SCL	RC3	ST	CMOS	General purpose I/O.
	SCK	ST	CMOS	SPI clock.
	SCL	ST	OD	I ² C™ clock.
RC4/SDI/SDA	RC4	ST	CMOS	General purpose I/O.
	SDI	ST	—	SPI data input.
	SDA	ST	OD	I ² C data input/output.
RC5/SDO	RC5	ST	CMOS	General purpose I/O.
	SDO	—	CMOS	SPI data output.
RC6/TX/CK	RC6	ST	CMOS	General purpose I/O.
	TX	—	CMOS	EUSART asynchronous transmit.
	CK	ST	CMOS	EUSART synchronous clock.
RC7/RX/DT	RC7	ST	CMOS	General purpose I/O.
	RX	ST	—	EUSART asynchronous input.
	DT	ST	CMOS	EUSART synchronous data.
RE3/MCLR/VPP	RE3	TTL	—	General purpose input.
	MCLR	ST	—	Master Clear with internal pull-up.
	VPP	HV	—	Programming voltage.
Vss	Vss	Power	—	Ground reference.
VDD	VDD	Power	—	Positive supply.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain
 TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels
 HV = High Voltage XTAL = Crystal

PIC16F882/883/884/886/887

TABLE 1-2: PIC16F884/887 PINOUT DESCRIPTION

Name	Function	Input Type	Output Type	Description
RA0/AN0/ULPWU/C12IN0-	RA0	TTL	CMOS	General purpose I/O.
	AN0	AN	—	A/D Channel 0 input.
	ULPWU	AN	—	Ultra Low-Power Wake-up input.
	C12IN0-	AN	—	Comparator C1 or C2 negative input.
RA1/AN1/C12IN1-	RA1	TTL	CMOS	General purpose I/O.
	AN1	AN	—	A/D Channel 1 input.
	C12IN1-	AN	—	Comparator C1 or C2 negative input.
RA2/AN2/VREF-/CVREF/C2IN+	RA2	TTL	CMOS	General purpose I/O.
	AN2	AN	—	A/D Channel 2.
	VREF-	AN	—	A/D Negative Voltage Reference input.
	CVREF	—	AN	Comparator Voltage Reference output.
	C2IN+	AN	—	Comparator C2 positive input.
RA3/AN3/VREF+/C1IN+	RA3	TTL	CMOS	General purpose I/O.
	AN3	AN	—	A/D Channel 3.
	VREF+	AN	—	A/D Positive Voltage Reference input.
	C1IN+	AN	—	Comparator C1 positive input.
RA4/T0CKI/C1OUT	RA4	TTL	CMOS	General purpose I/O.
	T0CKI	ST	—	Timer0 clock input.
	C1OUT	—	CMOS	Comparator C1 output.
RA5/AN4/SS/C2OUT	RA5	TTL	CMOS	General purpose I/O.
	AN4	AN	—	A/D Channel 4.
	SS	ST	—	Slave Select input.
	C2OUT	—	CMOS	Comparator C2 output.
RA6/OSC2/CLKOUT	RA6	TTL	CMOS	General purpose I/O.
	OSC2	—	XTAL	Crystal/Resonator.
	CLKOUT	—	CMOS	Fosc/4 output.
RA7/OSC1/CLKIN	RA7	TTL	CMOS	General purpose I/O.
	OSC1	XTAL	—	Crystal/Resonator.
	CLKIN	ST	—	External clock input/RC oscillator connection.
RB0/AN12/INT	RB0	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN12	AN	—	A/D Channel 12.
	INT	ST	—	External interrupt.
RB1/AN10/C12IN3-	RB1	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN10	AN	—	A/D Channel 10.
	C12IN3-	AN	—	Comparator C1 or C2 negative input.
RB2/AN8	RB2	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN8	AN	—	A/D Channel 8.
RB3/AN9/PGM/C12IN2-	RB3	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN9	AN	—	A/D Channel 9.
	PGM	ST	—	Low-voltage ICSP™ Programming enable pin.
	C12IN2-	AN	—	Comparator C1 or C2 negative input.

Legend: AN = Analog input or output
 TTL = TTL compatible input
 HV = High Voltage

CMOS = CMOS compatible input or output
 OD = Open Drain
 ST = Schmitt Trigger input with CMOS levels
 XTAL = Crystal

PIC16F882/883/884/886/887

TABLE 1-2: PIC16F884/887 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RB4/AN11	RB4	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN11	AN	—	A/D Channel 11.
RB5/AN13/T1G	RB5	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	AN13	AN	—	A/D Channel 13.
	T1G	ST	—	Timer1 Gate input.
RB6/ICSPCLK	RB6	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPCLK	ST	—	Serial Programming Clock.
RB7/ICSPDAT	RB7	TTL	CMOS	General purpose I/O. Individually controlled interrupt-on-change. Individually enabled pull-up.
	ICSPDAT	ST	TTL	ICSP™ Data I/O.
RC0/T1OSO/T1CKI	RC0	ST	CMOS	General purpose I/O.
	T1OSO	—	XTAL	Timer1 oscillator output.
	T1CKI	ST	—	Timer1 clock input.
RC1/T1OSI/CCP2	RC1	ST	CMOS	General purpose I/O.
	T1OSI	XTAL	—	Timer1 oscillator input.
	CCP2	ST	CMOS	Capture/Compare/PWM2.
RC2/P1A/CCP1	RC2	ST	CMOS	General purpose I/O.
	P1A	ST	CMOS	PWM output.
	CCP1	—	CMOS	Capture/Compare/PWM1.
RC3/SCK/SCL	RC3	ST	CMOS	General purpose I/O.
	SCK	ST	CMOS	SPI clock.
	SCL	ST	OD	I ² C™ clock.
RC4/SDI/SDA	RC4	ST	CMOS	General purpose I/O.
	SDI	ST	—	SPI data input.
	SDA	ST	OD	I ² C data input/output.
RC5/SDO	RC5	ST	CMOS	General purpose I/O.
	SDO	—	CMOS	SPI data output.
RC6/TX/CK	RC6	ST	CMOS	General purpose I/O.
	TX	—	CMOS	EUSART asynchronous transmit.
	CK	ST	CMOS	EUSART synchronous clock.
RC7/RX/DT	RC7	ST	CMOS	General purpose I/O.
	RX	ST	—	EUSART asynchronous input.
	DT	ST	CMOS	EUSART synchronous data.
RD0	RD0	TTL	CMOS	General purpose I/O.
RD1	RD1	TTL	CMOS	General purpose I/O.
RD2	RD2	TTL	CMOS	General purpose I/O.
RD3	RD3	TTL	CMOS	General purpose I/O.
RD4	RD4	TTL	CMOS	General purpose I/O.
RD5/P1B	RD5	TTL	CMOS	General purpose I/O.
	P1B	—	CMOS	PWM output.
RD6/P1C	RD6	TTL	CMOS	General purpose I/O.
	P1C	—	CMOS	PWM output.

Legend: AN = Analog input or output
 TTL = TTL compatible input
 HV = High Voltage

CMOS = CMOS compatible input or output
 ST = Schmitt Trigger input with CMOS levels
 XTAL = Crystal
 OD = Open Drain

PIC16F882/883/884/886/887

TABLE 1-2: PIC16F884/887 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RD7/P1D	RD7	TTL	CMOS	General purpose I/O.
	P1D	AN	—	PWM output.
RE0/AN5	RE0	TTL	CMOS	General purpose I/O.
	AN5	AN	—	A/D Channel 5.
RE1/AN6	RE1	TTL	CMOS	General purpose I/O.
	AN6	AN	—	A/D Channel 6.
RE2/AN7	RE2	TTL	CMOS	General purpose I/O.
	AN7	AN	—	A/D Channel 7.
RE3/MCLR/VPP	RE3	TTL	—	General purpose input.
	MCLR	ST	—	Master Clear with internal pull-up.
	VPP	HV	—	Programming voltage.
VSS	VSS	Power	—	Ground reference.
VDD	VDD	Power	—	Positive supply.

Legend: AN = Analog input or output
 TTL = TTL compatible input
 HV = High Voltage

CMOS = CMOS compatible input or output
 ST = Schmitt Trigger input with CMOS levels
 XTAL = Crystal

2.0 MEMORY ORGANIZATION

2.1 Program Memory Organization

The PIC16F882/883/884/886/887 has a 13-bit program counter capable of addressing a $2K \times 14$ (0000h-07FFh) for the PIC16F882, $4K \times 14$ (0000h-0FFFh) for the PIC16F883/PIC16F884, and $8K \times 14$ (0000h-1FFFh) for the PIC16F886/PIC16F887 program memory space. Accessing a location above these boundaries will cause a wrap-around within the first $8K \times 14$ space. The Reset vector is at 0000h and the interrupt vector is at 0004h (see Figures 2-2 and 2-3).

FIGURE 2-1: PROGRAM MEMORY MAP AND STACK FOR THE PIC16F882

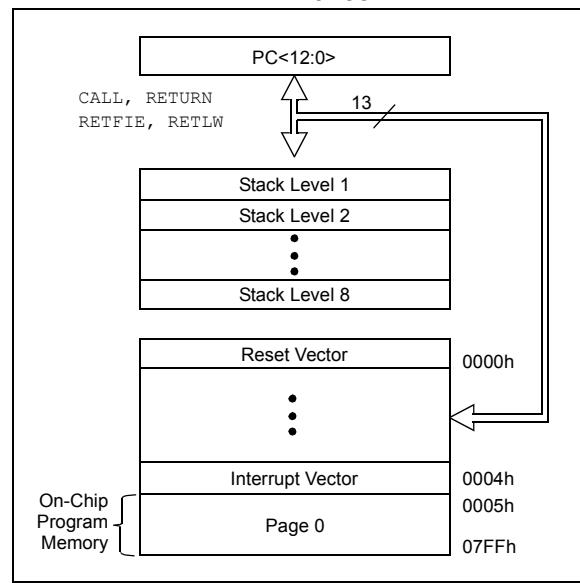


FIGURE 2-2: PROGRAM MEMORY MAP AND STACK FOR THE PIC16F883/PIC16F884

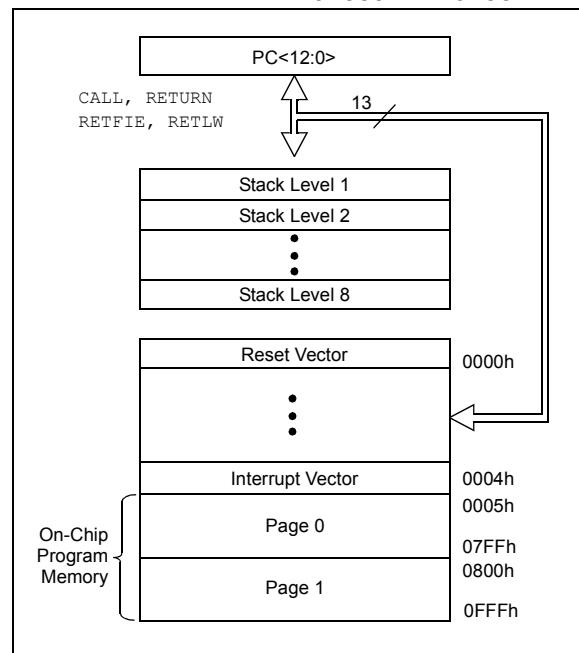
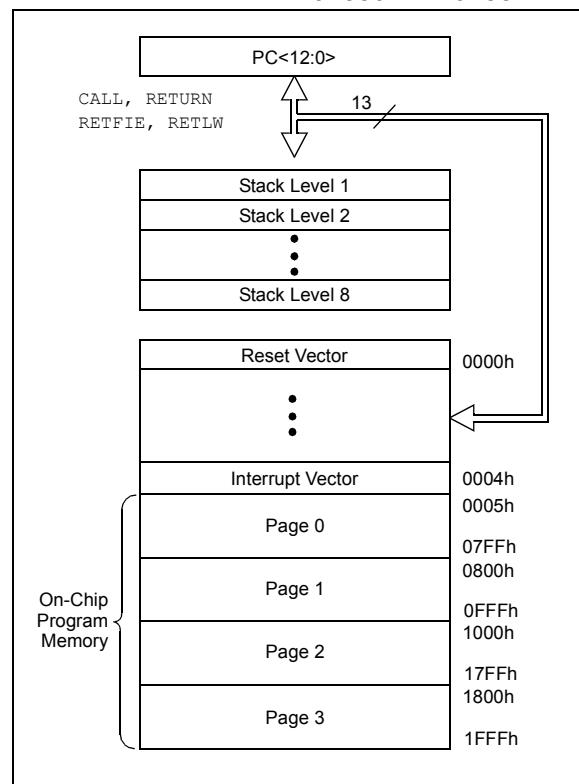


FIGURE 2-3: PROGRAM MEMORY MAP AND STACK FOR THE PIC16F886/PIC16F887



PIC16F882/883/884/886/887

2.2 Data Memory Organization

The data memory (see Figures 2-2 and 2-3) is partitioned into four banks which contain the General Purpose Registers (GPR) and the Special Function Registers (SFR). The Special Function Registers are located in the first 32 locations of each bank. The General Purpose Registers, implemented as static RAM, are located in the last 96 locations of each Bank. Register locations F0h-FFh in Bank 1, 170h-17Fh in Bank 2 and 1F0h-1FFh in Bank 3, point to addresses 70h-7Fh in Bank 0. The actual number of General Purpose Registers (GPR) implemented in each Bank depends on the device. Details are shown in Figures 2-5 and 2-6. All other RAM is unimplemented and returns '0' when read. RP<1:0> of the STATUS register are the bank select bits:

RP1 RP0

0	0	→Bank 0 is selected
0	1	→Bank 1 is selected
1	0	→Bank 2 is selected
1	1	→Bank 3 is selected

2.2.1 GENERAL PURPOSE REGISTER FILE

The register file is organized as 128 x 8 in the PIC16F882, 256 x 8 in the PIC16F883/PIC16F884, and 368 x 8 in the PIC16F886/PIC16F887. Each register is accessed, either directly or indirectly, through the File Select Register (FSR) (see **Section 2.4 “Indirect Addressing, INDF and FSR Registers”**).

2.2.2 SPECIAL FUNCTION REGISTERS

The Special Function Registers are registers used by the CPU and peripheral functions for controlling the desired operation of the device (see Table 2-1). These registers are static RAM.

The special registers can be classified into two sets: core and peripheral. The Special Function Registers associated with the “core” are described in this section. Those related to the operation of the peripheral features are described in the section of that peripheral feature.

PIC16F882/883/884/886/887

FIGURE 2-4: PIC16F882 SPECIAL FUNCTION REGISTERS

File	File	File	File
Address	Address	Address	Address
Indirect addr. (1)	Indirect addr. (1)	Indirect addr. (1)	Indirect addr. (1)
TMRO	OPTION_REG	TMRO	OPTION_REG
PCL	PCL	PCL	PCL
STATUS	STATUS	STATUS	STATUS
FSR	FSR	FSR	FSR
PORTA	TRISA	WDTCON	SRCON
PORTB	TRISB	PORTB	TRISB
PORTC	TRISC	CM1CON0	BAUDCTL
PORTE	TRISE	CM2CON0	ANSEL
PCLATH	PCLATH	CM2CON1	ANSELH
INTCON	INTCON	PCLATH	PCLATH
PIR1	PIE1	INTCON	INTCON
PIR2	PIE2	EEDAT	EECON1
TMR1L	PCON	EEADR	EECON2 ⁽¹⁾
TMR1H	OSCCON	EEDATH	Reserved
T1CON	OSCTUNE	EEADRH	Reserved
TMR2	SSPCON2		
T2CON	PR2		
SSPBUF	SSPADD		
SSPCON	SSPSTAT		
CCPR1L	WPUB		
CCPR1H	IOCB		
CCP1CON	VRCON		
RCSTA	TXSTA		
TXREG	SPBRG		
RCREG	SPBRGH		
CCPR2L	PWM1CON		
CCPR2H	ECCPAS		
CCP2CON	PSTRCON		
ADRESH	ADRESL		
ADCON0	ADCON1		
General Purpose Registers 96 Bytes	General Purpose Registers 32 Bytes	A0h	
		BFh	
Bank 0	Bank 1	C0h	
		EFh	
7Fh	accesses 70h-7Fh	F0h	accesses 70h-7Fh
		FFh	
Bank 2			16Fh
			170h
Bank 3			17Fh
			1EFh
			1F0h
			1FFh

■ Unimplemented data memory locations, read as '0'.

Note 1: Not a physical register.

PIC16F882/883/884/886/887

FIGURE 2-5: PIC16F883/PIC16F884 SPECIAL FUNCTION REGISTERS

File	File	File	File
Address	Address	Address	Address
Indirect addr. (1)	Indirect addr. (1)	Indirect addr. (1)	Indirect addr. (1)
00h	OPTION_REG	80h	TMR0
01h	PCL	81h	PCL
02h	STATUS	82h	STATUS
03h	FSR	83h	FSR
04h	PORTA	84h	WDTCON
05h	PORTB	85h	PORTB
06h	PORTC	86h	CM1CON0
07h	PORTD(2)	87h	CM2CON0
08h	PORTE	88h	CM2CON1
09h	PCLATH	89h	PCLATH
0Ah	INTCON	8Ah	INTCON
0Bh	PIR1	8Bh	EEDAT
0Ch	PIR2	8Ch	EEADR
0Dh	TMR1L	8Dh	EEDATH
0Eh	TMR1H	8Eh	EEADRH
0Fh	T1CON	8Fh	
10h	OSCTUNE	90h	
11h	SSPCON2	91h	
12h	T2CON	92h	
13h	SSPBUF	93h	
14h	SSPCON	94h	
15h	CCPR1L	95h	
16h	CCPR1H	96h	
17h	CCP1CON	97h	
18h	RCSTA	98h	
19h	TXREG	99h	
1Ah	SPBRG	9Ah	
1Bh	RCREG	SPBRGH	
1Ch	CCPR2L	PWM1CON	
1Dh	CCPR2H	ECCPAS	
1Eh	CCP2CON	PSTRCON	
1Fh	ADRESH	ADRESL	
	ADC0N0	ADCON1	
General Purpose Registers 96 Bytes	20h	General Purpose Registers 80 Bytes	A0h
		EFh	General Purpose Registers 80 Bytes
Bank 0	7Fh	accesses 70h-7Fh	EFh
		FFh	F0h
Bank 1	7Fh	accesses 70h-7Fh	F0h
		FFh	FFh
Bank 2	7Fh	accesses 70h-7Fh	16Fh
		FFh	17Fh
Bank 3	7Fh	accesses 70h-7Fh	17Fh
		FFh	1FFh

■ Unimplemented data memory locations, read as '0'.

Note 1: Not a physical register.

2: PIC16F884 only.

PIC16F882/883/884/886/887

FIGURE 2-6: PIC16F886/PIC16F887 SPECIAL FUNCTION REGISTERS

File Address	File Address	File Address	File Address	File Address
Indirect addr. (1) 00h	Indirect addr. (1) 00h	Indirect addr. (1) 80h	Indirect addr. (1) 100h	Indirect addr. (1) 180h
TMR0 01h	OPTION_REG 01h	TMR0 81h	TMR0 101h	OPTION_REG 181h
PCL 02h	PCL 02h	PCL 82h	PCL 102h	PCL 182h
STATUS 03h	STATUS 03h	STATUS 83h	STATUS 103h	STATUS 183h
FSR 04h	FSR 04h	FSR 84h	FSR 104h	FSR 184h
PORTA 05h	TRISA 05h	WDTCON 85h	SRCON 105h	SRCON 185h
PORTB 06h	TRISB 06h	PORTB 86h	TRISB 106h	TRISB 186h
PORTC 07h	TRISC 07h	CM1CON0 87h	BAUDCTL 107h	BAUDCTL 187h
PORTD(2) 08h	TRISD(2) 08h	CM2CON0 88h	ANSEL 108h	ANSEL 188h
PORTE 09h	TRISE 09h	CM2CON1 89h	ANSELH 109h	ANSELH 189h
PCLATH 0Ah	PCLATH 0Ah	PCLATH 8Ah	PCLATH 10Ah	PCLATH 18Ah
INTCON 0Bh	INTCON 0Bh	INTCON 8Bh	INTCON 10Bh	INTCON 18Bh
PIR1 0Ch	PIE1 0Ch	EEDAT 8Ch	EECON1 10Ch	EECON1 18Ch
PIR2 0Dh	PIE2 0Dh	EEADR 8Dh	EECON2(1) 10Dh	EECON2(1) 18Dh
TMR1L 0Eh	PCON 0Eh	EEDATH 8Eh	Reserved 10Eh	Reserved 18Eh
TMR1H 0Fh	OSCCON 0Fh	EEADRH 8Fh	Reserved 10Fh	Reserved 18Fh
T1CON 10h	OSCTUNE 10h			190h
TMR2 11h	SSPCON2 11h			191h
T2CON 12h	PR2 12h			192h
SSPBUF 13h	SSPADD 13h			193h
SSPCON 14h	SSPSTAT 14h			194h
CCPR1L 15h	WPUB 15h			195h
CCPR1H 16h	IOCB 16h			196h
CCP1CON 17h	VRCON 17h			197h
RCSTA 18h	TXSTA 18h			198h
TXREG 19h	SPBRG 19h			199h
RCREG 1Ah	SPBRGH 1Ah			19Ah
CCPR2L 1Bh	PWM1CON 1Bh			19Bh
CCPR2H 1Ch	ECCPAS 1Ch			19Ch
CCP2CON 1Dh	PSTRCON 1Dh			19Dh
ADRESH 1Eh	ADRESL 1Eh			19Eh
ADCON0 1Fh	ADCON1 1Fh			19Fh
General Purpose Registers 96 Bytes	General Purpose Registers 80 Bytes	General Purpose Registers 80 Bytes	General Purpose Registers 80 Bytes	General Purpose Registers 80 Bytes
Bank 0	Bank 1	Bank 2	Bank 3	
[Unimplemented data memory locations, read as '0'.				
Note 1: Not a physical register.				
2: PIC16F887 only.				

PIC16F882/883/884/886/887

TABLE 2-1: PIC16F882/883/884/886/887 SPECIAL FUNCTION REGISTERS SUMMARY BANK 0

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
Bank 0											
00h	INDF	Addressing this location uses contents of FSR to address data memory (not a physical register)								xxxx xxxx	37,217
01h	TMR0	Timer0 Module Register								xxxx xxxx	73,217
02h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	37,217
03h	STATUS	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	29,217
04h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	37,217
05h	PORTA ⁽³⁾	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx xxxx	39,217
06h	PORTB ⁽³⁾	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	48,217
07h	PORTC ⁽³⁾	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	53,217
08h	PORTD ^(3,4)	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0	xxxx xxxx	57,217
09h	PORTE ⁽³⁾	—	—	—	—	RE3	RE2 ⁽⁴⁾	RE1 ⁽⁴⁾	RE0 ⁽⁴⁾	---- xxxx	59,217
0Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of Program Counter					--0 0000	37,217
0Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF ⁽¹⁾	0000 000x	31,217
0Ch	PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	34,217
0Dh	PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	35,217
0Eh	TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	76,217
0Fh	TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	76,217
10h	T1CON	T1GINV	T1M1GE	T1CKPS1	T1CKPS0	T1OSCEN	TO1SYNC	TMR1CS	TMR1ON	0000 0000	79,217
11h	TMR2	Timer2 Module Register								0000 0000	81,217
12h	T2CON	—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	82,217
13h	SSPBUF	Synchronous Serial Port Receive Buffer/Transmit Register								xxxx xxxx	183,217
14h	SSPCON ⁽²⁾	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	181,217
15h	CCPR1L	Capture/Compare/PWM Register 1 Low Byte (LSB)								xxxx xxxx	126,217
16h	CCPR1H	Capture/Compare/PWM Register 1 High Byte (MSB)								xxxx xxxx	126,217
17h	CCP1CON	P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	0000 0000	124,217
18h	RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	161,217
19h	TXREG	EUSART Transmit Data Register								0000 0000	153,217
1Ah	RCREG	EUSART Receive Data Register								0000 0000	158,217
1Bh	CCPR2L	Capture/Compare/PWM Register 2 Low Byte (LSB)								xxxx xxxx	126,217
1Ch	CCPR2H	Capture/Compare/PWM Register 2 High Byte (MSB)								xxxx xxxx	126,218
1Dh	CCP2CON	—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	--00 0000	125,218
1Eh	ADRESH	A/D Result Register High Byte								xxxx xxxx	99,218
1Fh	ADCON0	ADCS1	ADCS0	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON	0000 0000	104,218

Legend: — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: MCLR and WDT Reset do not affect the previous value data latch. The RBIF bit will be cleared upon Reset but will set again if the mismatch exists.

2: When SSPCON register bits SSPM<3:0> = 1001, any reads or writes to the SSPADD SFR address are accessed through the SSPMSK register. See Registers • and 13-4 for more detail.

3: Port pins with analog functions controlled by the ANSEL and ANSELH registers will read '0' immediately after a Reset even though the data latches are either undefined (POR) or unchanged (other Resets).

4: PIC16F884/PIC16F887 only.

PIC16F882/883/884/886/887

TABLE 2-2: PIC16F882/883/884/886/887 SPECIAL FUNCTION REGISTERS SUMMARY BANK 1

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
Bank 1											
80h	INDF									xxxx xxxx	37,217
81h	OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	30,218
82h	PCL	Program Counter's (PC) Least Significant Byte								0000 0000	37,217
83h	STATUS	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	29,217
84h	FSR	Indirect Data Memory Address Pointer								xxxx xxxx	37,217
85h	TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	39,218
86h	TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	48,218
87h	TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISCO	1111 1111	53,218
88h	TRISD ⁽³⁾	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	1111 1111	57,218
89h	TRISE	—	—	—	—	TRISE3	TRISE2 ⁽³⁾	TRISE1 ⁽³⁾	TRISE0 ⁽³⁾	---- 1111	59,218
8Ah	PCLATH	—	—	—	Write Buffer for the upper 5 bits of the Program Counter						---0 0000
8Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF ⁽¹⁾	0000 000x	31,217
8Ch	PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	32,218
8Dh	PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	33,218
8Eh	PCON	—	—	ULPWUE	SBOREN	—	—	POR	BOR	--01 --qq	36,218
8Fh	OSCCON	—	IRCF2	IRCF1	IRCF0	OSTS	HTS	LTS	SCS	-110 q000	62,218
90h	OSCTUNE	—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0	---0 0000	66,218
91h	SSPCON2	GCEN	ACKSTAT	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	0000 0000	181,218
92h	PR2	Timer2 Period Register								1111 1111	81,218
93h	SSPADD ⁽²⁾	Synchronous Serial Port (I ² C mode) Address Register								0000 0000	189,218
93h	SSPMASK ⁽²⁾	MSK7	MSK6	MSK5	MSK4	MSK3	MSK2	MSK1	MSK0	1111 1111	189,218
94h	SSPSTAT	SMP	CKE	D/A	P	S	R/W	UA	BF	0000 0000	189,218
95h	WPUB	WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0	1111 1111	49,218
96h	IOCB	IOCB7	IOCB6	IOCB5	IOCB4	IOCB3	IOCB2	IOCB1	IOCB0	0000 0000	49,218
97h	VRCON	VREN	VROE	VRR	VRSS	VR3	VR2	VR1	VR0	0000 0000	97,218
98h	TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	160,218
99h	SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	163,218
9Ah	SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	163,218
9Bh	PWM1CON	PRSEN	PDC6	PDC5	PDC4	PDC3	PDC2	PDC1	PDC0	0000 0000	145,218
9Ch	ECCPAS	ECCPASE	ECCPAS2	ECCPAS1	ECCPAS0	PSSAC1	PSSAC0	PSSBD1	PSSBD0	0000 0000	142,218
9Dh	PSTRCON	—	—	—	STRSYNC	STRD	STRC	STRB	STRA	---0 0001	146,218
9Eh	ADRESL	A/D Result Register Low Byte								xxxx xxxx	99,218
9Fh	ADC0N1	ADFM	—	VCFG1	VCFG0	—	—	—	—	0-00 ----	105,218

Legend: — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: MCLR and WDT Reset do not affect the previous value data latch. The RBIF bit will be cleared upon Reset but will set again if the mismatch exists.

2: Accessible only when SSPCON register bits SSPM<3:0> = 1001.

3: PIC16F884/PIC16F887 only.

PIC16F882/883/884/886/887

TABLE 2-3: PIC16F882/883/884/886/887 SPECIAL FUNCTION REGISTERS SUMMARY BANK 2

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
Bank 2											
100h	INDF									xxxx xxxx	37,217
101h	TMR0									xxxx xxxx	73,217
102h	PCL									0000 0000	37,217
103h	STATUS	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	29,217
104h	FSR									xxxx xxxx	37,217
105h	WDTCON	—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	SWDTEN	---0 1000	225,218
106h	PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	48,217
107h	CM1CON0	C1ON	C1OUT	C1OE	C1POL	—	C1R	C1CH1	C1CH0	0000 -000	88,218
108h	CM2CON0	C2ON	C2OUT	C2OE	C2POL	—	C2R	C2CH1	C2CH0	0000 -000	89,218
109h	CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	91,219
10Ah	PCLATH	—	—	—						---0 0000	37,217
10Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF ⁽¹⁾	0000 000x	31,217
10Ch	EEDAT	EEDAT7	EEDAT6	EEDAT5	EEDAT4	EEDAT3	EEDAT2	EEDAT1	EEDAT0	0000 0000	112,219
10Dh	EEADR	EEADR7	EEADR6	EEADR5	EEADR4	EEADR3	EEADR2	EEADR1	EEADR0	0000 0000	112,219
10Eh	EEDATH	—	—	EEDATH5	EEDATH4	EEDATH3	EEDATH2	EEDATH1	EEDATH0	--00 0000	112,219
10Fh	EEADRH	—	—	—	EEADRH4 ⁽²⁾	EEADRH3	EEADRH2	EEADRH1	EEADRH0	---- 0000	112,219

Legend: — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: MCLR and WDT Reset does not affect the previous value data latch. The RBIF bit will be cleared upon Reset but will set again if the mismatch exists.

2: PIC16F886/PIC16F887 only.

TABLE 2-4: PIC16F882/883/884/886/887 SPECIAL FUNCTION REGISTERS SUMMARY BANK 3

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page
Bank 3											
180h	INDF									xxxx xxxx	37,217
181h	OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	30,218
182h	PCL									0000 0000	37,217
183h	STATUS	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	29,217
184h	FSR									xxxx xxxx	37,217
185h	SRCON	SR1	SR0	C1SEN	C2REN	PULSS	PULSR	—	FVREN	0000 00-0	93,219
186h	TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	48,218
187h	BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	162,219
188h	ANSEL	ANS7 ⁽²⁾	ANS6 ⁽²⁾	ANS5 ⁽²⁾	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	40,219
189h	ANSELH	—	—	ANS13	ANS12	ANS11	ANS10	ANS9	ANS8	--11 1111	99,219
18Ah	PCLATH	—	—	—						---0 0000	37,217
18Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF ⁽¹⁾	0000 000x	31,217
18Ch	EECON1	EEPGD	—	—	—	WRERR	WREN	WR	RD	x--- x000	113,219
18Dh	EECON2									---- ----	111,219

Legend: — = Unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: MCLR and WDT Reset does not affect the previous value data latch. The RBIF bit will be cleared upon Reset but will set again if the mismatch exists.

2: PIC16F884/PIC16F887 only.

2.2.2.1 STATUS Register

The STATUS register, shown in Register 2-1, contains:

- the arithmetic status of the ALU
- the Reset status
- the bank select bits for data memory (GPR and SFR)

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the TO and PD bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS`, will clear the upper three bits and set the Z bit. This leaves the STATUS register as '000u uuu' (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits, see **Section 15.0 "Instruction Set Summary"**

Note 1: The C and DC bits operate as a Borrow and Digit Borrow out bit, respectively, in subtraction.

REGISTER 2-1: STATUS: STATUS REGISTER

R/W-0	R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
IRP	RP1	RP0	<u>TO</u>	<u>PD</u>	Z	DC ⁽¹⁾	C ⁽¹⁾
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	IRP: Register Bank Select bit (used for indirect addressing) 1 = Bank 2, 3 (100h-1FFh) 0 = Bank 0, 1 (00h-FFh)
bit 6-5	RP<1:0>: Register Bank Select bits (used for direct addressing) 00 = Bank 0 (00h-7Fh) 01 = Bank 1 (80h-FFh) 10 = Bank 2 (100h-17Fh) 11 = Bank 3 (180h-1FFh)
bit 4	TO: Time-out bit 1 = After power-up, <code>CLRWD</code> T instruction or <code>SLEEP</code> instruction 0 = A WDT time-out occurred
bit 3	PD: Power-down bit 1 = After power-up or by the <code>CLRWD</code> T instruction 0 = By execution of the <code>SLEEP</code> instruction
bit 2	Z: Zero bit 1 = The result of an arithmetic or logic operation is zero 0 = The result of an arithmetic or logic operation is not zero
bit 1	DC: Digit Carry/Borrow bit (<code>ADDWF</code> , <code>ADDLW</code> , <code>SUBLW</code> , <code>SUBWF</code> instructions) ⁽¹⁾ 1 = A carry-out from the 4th low-order bit of the result occurred 0 = No carry-out from the 4th low-order bit of the result
bit 0	C: Carry/Borrow bit (<code>ADDWF</code> , <code>ADDLW</code> , <code>SUBLW</code> , <code>SUBWF</code> instructions) ⁽¹⁾ 1 = A carry-out from the Most Significant bit of the result occurred 0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For Borrow, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

PIC16F882/883/884/886/887

2.2.2.2 OPTION Register

The OPTION register, shown in Register 2-2, is a readable and writable register, which contains various control bits to configure:

- Timer0/WDT prescaler
- External INT interrupt
- Timer0
- Weak pull-ups on PORTB

Note: To achieve a 1:1 prescaler assignment for Timer0, assign the prescaler to the WDT by setting PSA bit of the OPTION register to '1'. See **Section 6.3 "Timer1 Prescaler"**.

REGISTER 2-2: OPTION_REG: OPTION REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
bit 7							

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7

RBPU: PORTB Pull-up Enable bit

1 = PORTB pull-ups are disabled

0 = PORTB pull-ups are enabled by individual PORT latch values

bit 6

INTEDG: Interrupt Edge Select bit

1 = Interrupt on rising edge of INT pin

0 = Interrupt on falling edge of INT pin

bit 5

T0CS: Timer0 Clock Source Select bit

1 = Transition on T0CKI pin

0 = Internal instruction cycle clock (Fosc/4)

bit 4

T0SE: Timer0 Source Edge Select bit

1 = Increment on high-to-low transition on T0CKI pin

0 = Increment on low-to-high transition on T0CKI pin

bit 3

PSA: Prescaler Assignment bit

1 = Prescaler is assigned to the WDT

0 = Prescaler is assigned to the Timer0 module

bit 2-0

PS<2:0>: Prescaler Rate Select bits

Bit Value	Timer0 Rate	WDT Rate
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

2.2.2.3 INTCON Register

The INTCON register, shown in Register 2-3, is a readable and writable register, which contains the various enable and flag bits for TMR0 register overflow, PORTB change and external INT pin interrupts.

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 2-3: INTCON: INTERRUPT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
GIE	PEIE	T0IE	INTE	RBIE ⁽¹⁾	T0IF ⁽²⁾	INTF	RBIF
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	GIE: Global Interrupt Enable bit 1 = Enables all unmasked interrupts 0 = Disables all interrupts
bit 6	PEIE: Peripheral Interrupt Enable bit 1 = Enables all unmasked peripheral interrupts 0 = Disables all peripheral interrupts
bit 5	T0IE: Timer0 Overflow Interrupt Enable bit 1 = Enables the Timer0 interrupt 0 = Disables the Timer0 interrupt
bit 4	INTE: INT External Interrupt Enable bit 1 = Enables the INT external interrupt 0 = Disables the INT external interrupt
bit 3	RBIE: PORTB Change Interrupt Enable bit ⁽¹⁾ 1 = Enables the PORTB change interrupt 0 = Disables the PORTB change interrupt
bit 2	T0IF: Timer0 Overflow Interrupt Flag bit ⁽²⁾ 1 = TMR0 register has overflowed (must be cleared in software) 0 = TMR0 register did not overflow
bit 1	INTF: INT External Interrupt Flag bit 1 = The INT external interrupt occurred (must be cleared in software) 0 = The INT external interrupt did not occur
bit 0	RBIF: PORTB Change Interrupt Flag bit 1 = When at least one of the PORTB general purpose I/O pins changed state (must be cleared in software) 0 = None of the PORTB general purpose I/O pins have changed state

Note 1: IOCB register must also be enabled.

2: T0IF bit is set when Timer0 rolls over. Timer0 is unchanged on Reset and should be initialized before clearing T0IF bit.

PIC16F882/883/884/886/887

2.2.2.4 PIE1 Register

The PIE1 register contains the interrupt enable bits, as shown in Register 2-4.

Note: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

REGISTER 2-4: PIE1: PERIPHERAL INTERRUPT ENABLE REGISTER 1

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE
bit 7							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Read as '0'

bit 6 **ADIE:** A/D Converter (ADC) Interrupt Enable bit

1 = Enables the ADC interrupt

0 = Disables the ADC interrupt

bit 5 **RCIE:** EUSART Receive Interrupt Enable bit

1 = Enables the EUSART receive interrupt

0 = Disables the EUSART receive interrupt

bit 4 **TXIE:** EUSART Transmit Interrupt Enable bit

1 = Enables the EUSART transmit interrupt

0 = Disables the EUSART transmit interrupt

bit 3 **SSPIE:** Master Synchronous Serial Port (MSSP) Interrupt Enable bit

1 = Enables the MSSP interrupt

0 = Disables the MSSP interrupt

bit 2 **CCP1IE:** CCP1 Interrupt Enable bit

1 = Enables the CCP1 interrupt

0 = Disables the CCP1 interrupt

bit 1 **TMR2IE:** Timer2 to PR2 Match Interrupt Enable bit

1 = Enables the Timer2 to PR2 match interrupt

0 = Disables the Timer2 to PR2 match interrupt

bit 0 **TMR1IE:** Timer1 Overflow Interrupt Enable bit

1 = Enables the Timer1 overflow interrupt

0 = Disables the Timer1 overflow interrupt

2.2.2.5 PIE2 Register

The PIE2 register contains the interrupt enable bits, as shown in Register 2-5.

Note: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

REGISTER 2-5: PIE2: PERIPHERAL INTERRUPT ENABLE REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	OSFIE: Oscillator Fail Interrupt Enable bit 1 = Enables oscillator fail interrupt 0 = Disables oscillator fail interrupt
bit 6	C2IE: Comparator C2 Interrupt Enable bit 1 = Enables Comparator C2 interrupt 0 = Disables Comparator C2 interrupt
bit 5	C1IE: Comparator C1 Interrupt Enable bit 1 = Enables Comparator C1 interrupt 0 = Disables Comparator C1 interrupt
bit 4	EEIE: EEPROM Write Operation Interrupt Enable bit 1 = Enables EEPROM write operation interrupt 0 = Disables EEPROM write operation interrupt
bit 3	BCLIE: Bus Collision Interrupt Enable bit 1 = Enables Bus Collision interrupt 0 = Disables Bus Collision interrupt
bit 2	ULPWUIE: Ultra Low-Power Wake-up Interrupt Enable bit 1 = Enables Ultra Low-Power Wake-up interrupt 0 = Disables Ultra Low-Power Wake-up interrupt
bit 1	Unimplemented: Read as '0'
bit 0	CCP2IE: CCP2 Interrupt Enable bit 1 = Enables CCP2 interrupt 0 = Disables CCP2 interrupt

PIC16F882/883/884/886/887

2.2.2.6 PIR1 Register

The PIR1 register contains the interrupt flag bits, as shown in Register 2-6.

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 2-6: PIR1: PERIPHERAL INTERRUPT REQUEST REGISTER 1

U-0	R/W-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7 **Unimplemented:** Read as '0'
- bit 6 **ADIF:** A/D Converter Interrupt Flag bit
1 = A/D conversion complete (must be cleared in software)
0 = A/D conversion has not completed or has not been started
- bit 5 **RCIF:** EUSART Receive Interrupt Flag bit
1 = The EUSART receive buffer is full (cleared by reading RCREG)
0 = The EUSART receive buffer is not full
- bit 4 **TXIF:** EUSART Transmit Interrupt Flag bit
1 = The EUSART transmit buffer is empty (cleared by writing to TXREG)
0 = The EUSART transmit buffer is full
- bit 3 **SSPIF:** Master Synchronous Serial Port (MSSP) Interrupt Flag bit
1 = The MSSP interrupt condition has occurred, and must be cleared in software before returning from the Interrupt Service Routine. The conditions that will set this bit are:
SPI
A transmission/reception has taken place
I²C Slave/Master
A transmission/reception has taken place
I²C Master
The initiated Start condition was completed by the MSSP module
The initiated Stop condition was completed by the MSSP module
The initiated restart condition was completed by the MSSP module
The initiated Acknowledge condition was completed by the MSSP module
A Start condition occurred while the MSSP module was idle (Multi-master system)
A Stop condition occurred while the MSSP module was idle (Multi-master system)
0 = No MSSP interrupt condition has occurred
- bit 2 **CCP1IF:** CCP1 Interrupt Flag bit
Capture mode:
1 = A TMR1 register capture occurred (must be cleared in software)
0 = No TMR1 register capture occurred
Compare mode:
1 = A TMR1 register compare match occurred (must be cleared in software)
0 = No TMR1 register compare match occurred
PWM mode:
Unused in this mode
- bit 1 **TMR2IF:** Timer2 to PR2 Interrupt Flag bit
1 = A Timer2 to PR2 match occurred (must be cleared in software)
0 = No Timer2 to PR2 match occurred
- bit 0 **TMR1IF:** Timer1 Overflow Interrupt Flag bit
1 = The TMR1 register overflowed (must be cleared in software)
0 = The TMR1 register did not overflow

2.2.2.7 PIR2 Register

The PIR2 register contains the interrupt flag bits, as shown in Register 2-7.

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 2-7: PIR2: PERIPHERAL INTERRUPT REQUEST REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- | | |
|-------|---|
| bit 7 | OSFIF: Oscillator Fail Interrupt Flag bit
1 = System oscillator failed, clock input has changed to INTOSC (must be cleared in software)
0 = System clock operating |
| bit 6 | C2IF: Comparator C2 Interrupt Flag bit
1 = Comparator output (C2OUT bit) has changed (must be cleared in software)
0 = Comparator output (C2OUT bit) has not changed |
| bit 5 | C1IF: Comparator C1 Interrupt Flag bit
1 = Comparator output (C1OUT bit) has changed (must be cleared in software)
0 = Comparator output (C1OUT bit) has not changed |
| bit 4 | EEIF: EE Write Operation Interrupt Flag bit
1 = Write operation completed (must be cleared in software)
0 = Write operation has not completed or has not started |
| bit 3 | BCLIF: Bus Collision Interrupt Flag bit
1 = A bus collision has occurred in the MSSP when configured for I ² C Master mode
0 = No bus collision has occurred |
| bit 2 | ULPWUIF: Ultra Low-Power Wake-up Interrupt Flag bit
1 = Wake-up condition has occurred (must be cleared in software)
0 = No Wake-up condition has occurred |
| bit 1 | Unimplemented: Read as '0' |
| bit 0 | CCP2IF: CCP2 Interrupt Flag bit
<u>Capture mode:</u>
1 = A TMR1 register capture occurred (must be cleared in software)
0 = No TMR1 register capture occurred
<u>Compare mode:</u>
1 = A TMR1 register compare match occurred (must be cleared in software)
0 = No TMR1 register compare match occurred
<u>PWM mode:</u>
Unused in this mode |

PIC16F882/883/884/886/887

2.2.2.8 PCON Register

The Power Control (PCON) register (see Register 2-8) contains flag bits to differentiate between a:

- Power-on Reset (POR)
- Brown-out Reset (BOR)
- Watchdog Timer Reset (WDT)
- External MCLR Reset

The PCON register also controls the Ultra Low-Power Wake-up and software enable of the BOR.

REGISTER 2-8: PCON: POWER CONTROL REGISTER

U-0	U-0	R/W-0	R/W-1	U-0	U-0	R/W-0	R/W-x
—	—	ULPWUE	SBOREN ⁽¹⁾	—	—	<u><u>POR</u></u>	<u><u>BOR</u></u>
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **ULPWUE:** Ultra Low-Power Wake-up Enable bit

 1 = Ultra Low-Power Wake-up enabled

 0 = Ultra Low-Power Wake-up disabled

bit 4 **SBOREN:** Software BOR Enable bit⁽¹⁾

 1 = BOR enabled

 0 = BOR disabled

bit 3-2 **Unimplemented:** Read as '0'

bit 1 **POR:** Power-on Reset Status bit

 1 = No Power-on Reset occurred

 0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

bit 0 **BOR:** Brown-out Reset Status bit

 1 = No Brown-out Reset occurred

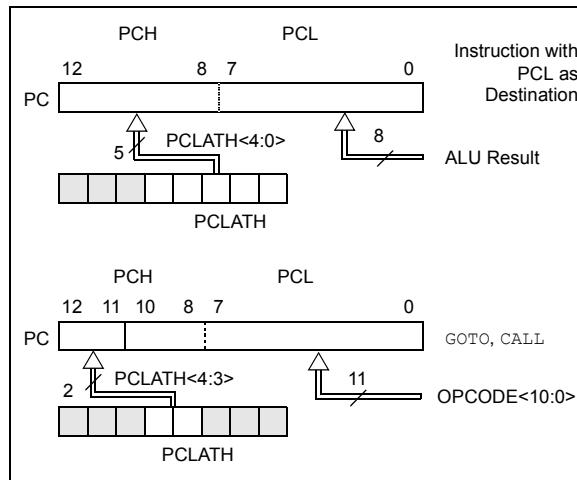
 0 = A Brown-out Reset occurred (must be set in software after a Brown-out Reset occurs)

Note 1: BOREN<1:0> = 01 in the Configuration Word Register 1 for this bit to control the BOR.

2.3 PCL and PCLATH

The Program Counter (PC) is 13 bits wide. The low byte comes from the PCL register, which is a readable and writable register. The high byte (PC<12:8>) is not directly readable or writable and comes from PCLATH. On any Reset, the PC is cleared. Figure 2-7 shows the two situations for the loading of the PC. The upper example in Figure 2-7 shows how the PC is loaded on a write to PCL (PCLATH<4:0> → PCH). The lower example in Figure 2-7 shows how the PC is loaded during a CALL or GOTO instruction (PCLATH<4:3> → PCH).

FIGURE 2-7: LOADING OF PC IN DIFFERENT SITUATIONS



2.3.1 MODIFYING PCL

Executing any instruction with the PCL register as the destination simultaneously causes the Program Counter PC<12:8> bits (PCH) to be replaced by the contents of the PCLATH register. This allows the entire contents of the program counter to be changed by writing the desired upper 5 bits to the PCLATH register. When the lower 8 bits are written to the PCL register, all 13 bits of the program counter will change to the values contained in the PCLATH register and those being written to the PCL register.

A computed GOTO is accomplished by adding an offset to the program counter (ADDDWF PCL). Care should be exercised when jumping into a look-up table or program branch table (computed GOTO) by modifying the PCL register. Assuming that PCLATH is set to the table start address, if the table length is greater than 255 instructions or if the lower 8 bits of the memory address rolls over from 0xFF to 0x00 in the middle of the table, then PCLATH must be incremented for each address rollover that occurs between the table beginning and the target location within the table.

For more information refer to Application Note AN556, "Implementing a Table Read" (DS00556).

2.3.2 STACK

The PIC16F882/883/884/886/887 devices have an 8-level x 13-bit wide hardware stack (see Figures 2-2 and 2-3). The stack space is not part of either program or data space and the Stack Pointer is not readable or writable. The PC is PUSHed onto the stack when a CALL instruction is executed or an interrupt causes a branch. The stack is POPped in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not affected by a PUSH or POP operation.

The stack operates as a circular buffer. This means that after the stack has been PUSHed eight times, the ninth push overwrites the value that was stored from the first push. The tenth push overwrites the second push (and so on).

- Note 1:** There are no Status bits to indicate stack overflow or stack underflow conditions.
- 2:** There are no instructions/mnemonics called PUSH or POP. These are actions that occur from the execution of the CALL, RETURN, RETLW and RETFIE instructions or the vectoring to an interrupt address.

2.4 Indirect Addressing, INDF and FSR Registers

The INDF register is not a physical register. Addressing the INDF register will cause indirect addressing.

Indirect addressing is possible by using the INDF register. Any instruction using the INDF register actually accesses data pointed to by the File Select Register (FSR). Reading INDF itself indirectly will produce 00h. Writing to the INDF register indirectly results in a no operation (although Status bits may be affected). An effective 9-bit address is obtained by concatenating the 8-bit FSR and the IRP bit of the STATUS register, as shown in Figure 2-8.

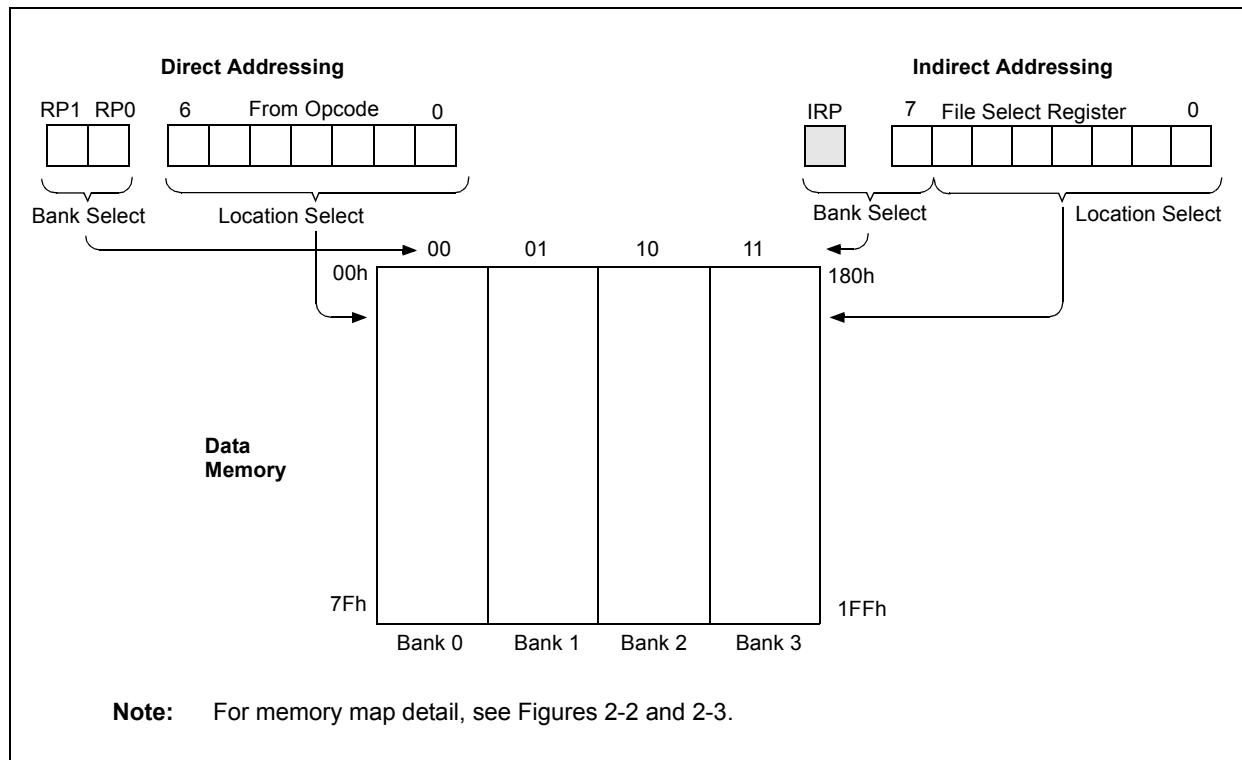
A simple program to clear RAM location 20h-2Fh using indirect addressing is shown in Example 2-1.

EXAMPLE 2-1: INDIRECT ADDRESSING

MOVWF	FSR	;to RAM	
NEXT	CLRF	INDF	;clear INDF register
	INCF	FSR	;inc pointer
	BTFS	FSR, 4	;all done?
	GOTO	NEXT	;no clear next
CONTINUE			;yes continue

PIC16F882/883/884/886/887

FIGURE 2-8: DIRECT/INDIRECT ADDRESSING PIC16F882/883/884/886/887



3.0 I/O PORTS

There are as many as thirty-five general purpose I/O pins available. Depending on which peripherals are enabled, some or all of the pins may not be available as general purpose I/O. In general, when a peripheral is enabled, the associated pin may not be used as a general purpose I/O pin.

3.1 PORTA and the TRISA Registers

PORTA is a 8-bit wide, bidirectional port. The corresponding data direction register is TRISA (Register 3-2). Setting a TRISA bit (= 1) will make the corresponding PORTA pin an input (i.e., disable the output driver). Clearing a TRISA bit (= 0) will make the corresponding PORTA pin an output (i.e., enables output driver and puts the contents of the output latch on the selected pin). Example 3-1 shows how to initialize PORTA.

Reading the PORTA register (Register 3-1) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write

operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch.

The TRISA register (Register 3-2) controls the PORTA pin output drivers, even when they are being used as analog inputs. The user should ensure the bits in the TRISA register are maintained set when using them as analog inputs. I/O pins configured as analog input always read '0'.

Note: The ANSEL register must be initialized to configure an analog channel as a digital input. Pins configured as analog inputs will read '0'.

EXAMPLE 3-1: INITIALIZING PORTA

```
BANKSEL PORTA      ;  
CLRF  PORTA       ;Init PORTA  
BANKSEL ANSEL     ;  
CLRF  ANSEL       ;digital I/O  
BANKSEL TRISA     ;  
MOVLW  0Ch          ;Set RA<3:2> as inputs  
MOVWF  TRISA        ;and set RA<5:4,1:0>  
                      ;as outputs
```

REGISTER 3-1: PORTA: PORTA REGISTER

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| RA7 | RA6 | RA5 | RA4 | RA3 | RA2 | RA1 | RA0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

RA<7:0>: PORTA I/O Pin bit

1 = Port pin is > VIH

0 = Port pin is < VIL

REGISTER 3-2: TRISA: PORTA TRI-STATE REGISTER

R/W-1 ⁽¹⁾	R/W-1 ⁽¹⁾	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

TRISA<7:0>: PORTA Tri-State Control bit

1 = PORTA pin configured as an input (tri-stated)

0 = PORTA pin configured as an output

Note 1: TRISA<7:6> always reads '1' in XT, HS and LP Oscillator modes.

PIC16F882/883/884/886/887

3.2 Additional Pin Functions

RA0 also has an Ultra Low-Power Wake-up option. The next three sections describe these functions.

3.2.1 ANSEL REGISTER

The ANSEL register (Register 3-3) is used to configure the Input mode of an I/O pin to analog. Setting the appropriate ANSEL bit high will cause all digital reads on the pin to be read as '0' and allow analog functions on the pin to operate correctly.

The state of the ANSEL bits has no affect on digital output functions. A pin with TRIS clear and ANSEL set will still operate as a digital output, but the Input mode will be analog. This can cause unexpected behavior when executing read-modify-write instructions on the affected port.

REGISTER 3-3: ANSEL: ANALOG SELECT REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
ANS7 ⁽²⁾	ANS6 ⁽²⁾	ANS5 ⁽²⁾	ANS4	ANS3	ANS2	ANS1	ANS0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

ANS<7:0>: Analog Select bits

Analog select between analog or digital function on pins AN<7:0>, respectively.

1 = Analog input. Pin is assigned as analog input⁽¹⁾.

0 = Digital I/O. Pin is assigned to port or special function.

Note 1: Setting a pin to an analog input automatically disables the digital input circuitry, weak pull-ups, and interrupt-on-change if available. The corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

2: Not implemented on PIC16F883/886.

3.2.2 ULTRA LOW-POWER WAKE-UP

The Ultra Low-Power Wake-up (ULPWU) on RA0 allows a slow falling voltage to generate an interrupt-on-change on RA0 without excess current consumption. The mode is selected by setting the ULPWUE bit of the PCON register. This enables a small current sink, which can be used to discharge a capacitor on RA0.

Follow these steps to use this feature:

- a) Charge the capacitor on RA0 by configuring the RA0 pin to output (= 1).
- b) Configure RA0 as an input.
- c) Set the ULPWUIE bit of the PIE2 register to enable interrupt.
- d) Set the ULPWUE bit of the PCON register to begin the capacitor discharge.
- e) Execute a SLEEP instruction.

When the voltage on RA0 drops below VIL, an interrupt will be generated which will cause the device to wake-up and execute the next instruction. If the GIE bit of the INTCON register is set, the device will then call the interrupt vector (0004h).

This feature provides a low-power technique for periodically waking up the device from Sleep. The time-out is dependent on the discharge time of the RC circuit on RA0. See Example 3-2 for initializing the Ultra Low-Power Wake-up module.

A series resistor between RA0 and the external capacitor provides overcurrent protection for the RA0/AN0/ULPWU/C12IN0- pin and can allow for software calibration of the time-out (see Figure 3-1). A timer can be used to measure the charge time and discharge time of the capacitor. The charge time can then be adjusted to provide the desired interrupt delay. This technique will compensate for the affects of temperature, voltage and component accuracy. The Ultra Low-Power Wake-up peripheral can also be configured as a simple Programmable Low Voltage Detect or temperature sensor.

Note: For more information, refer to AN879, "Using the Microchip Ultra Low-Power Wake-up Module" Application Note (DS00879).

EXAMPLE 3-2: ULTRA LOW-POWER WAKE-UP INITIALIZATION

```
BANKSEL PORTA          ;  
BSF     PORTA,0        ;Set RA0 data latch  
BANKSEL ANSEL          ;  
BCF     ANSEL,0        ;RA0 to digital I/O  
BANKSEL TRISA          ;  
BCF     TRISA,0        ;Output high to  
CALL    CapDelay      ;charge capacitor  
BANKSEL PIR2          ;  
BCF     PIR2,ULPWUIF   ;Clear flag  
BANKSEL PCON          ;  
BSF     PCON,ULPWUE    ;Enable ULP Wake-up  
BSF     TRISA,0        ;RA0 to input  
BSF     PIE2, ULPWUIE   ;Enable interrupt  
MOVLW  B'11000000'     ;Enable peripheral  
MOVWF   INTCON         ;interrupt  
SLEEP                ;Wait for IOC  
NOP                  ;
```

PIC16F882/883/884/886/887

3.2.3 PIN DESCRIPTIONS AND DIAGRAMS

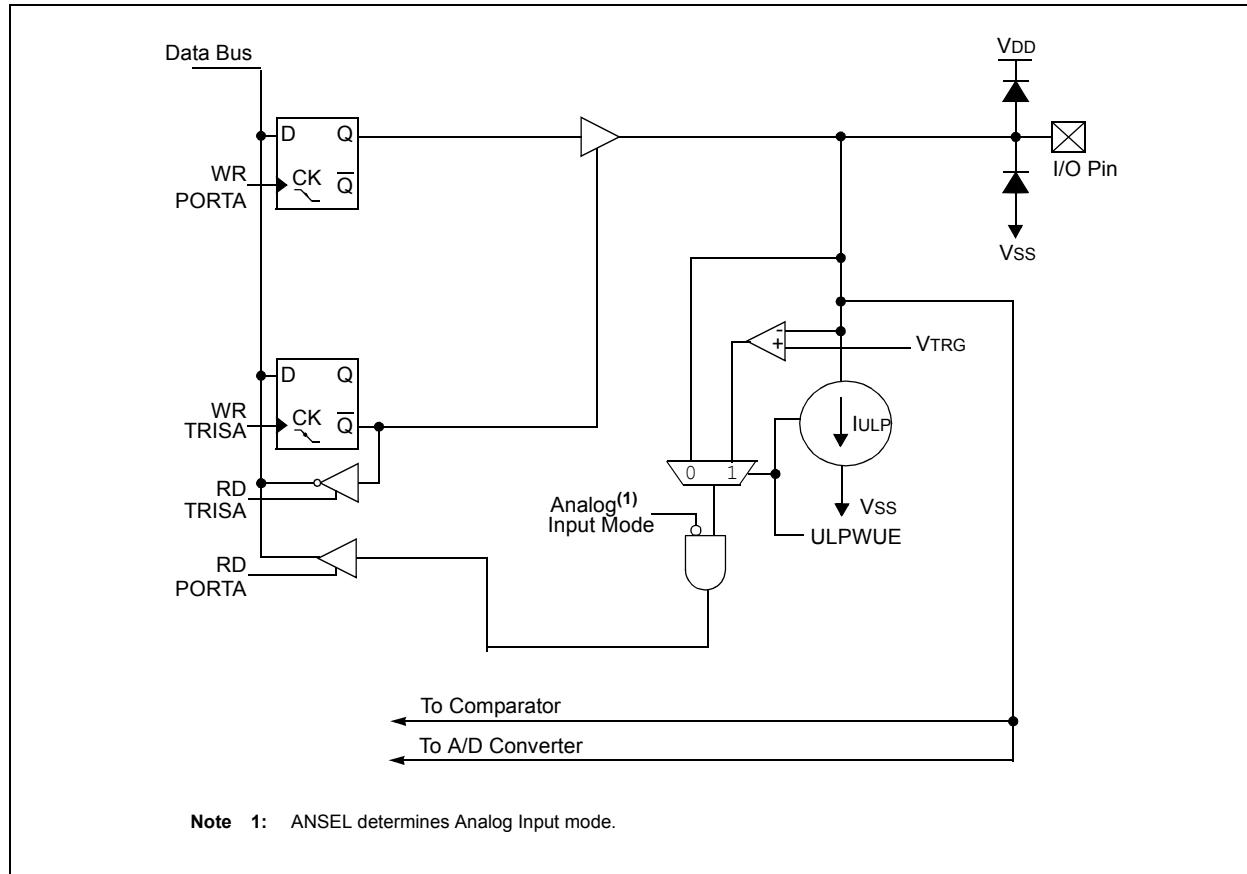
Each PORTA pin is multiplexed with other functions. The pins and their combined functions are briefly described here. For specific information about individual functions such as the comparator or the A/D Converter (ADC), refer to the appropriate section in this data sheet.

3.2.3.1 RA0/AN0/ULPWU/C12IN0-

Figure 3-1 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a negative analog input to Comparator C1 or C2
- an analog input for the Ultra Low-Power Wake-up

FIGURE 3-1: BLOCK DIAGRAM OF RA0

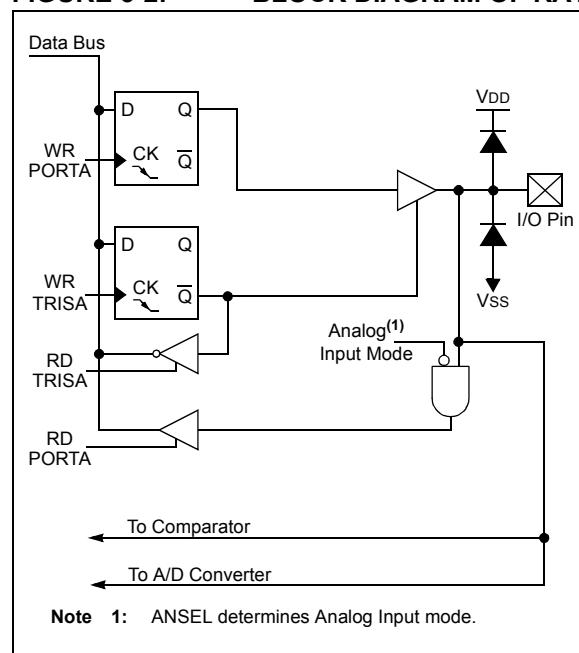


3.2.3.2 RA1/AN1/C12IN1-

Figure 3-2 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a negative analog input to Comparator C1 or C2

FIGURE 3-2: BLOCK DIAGRAM OF RA1



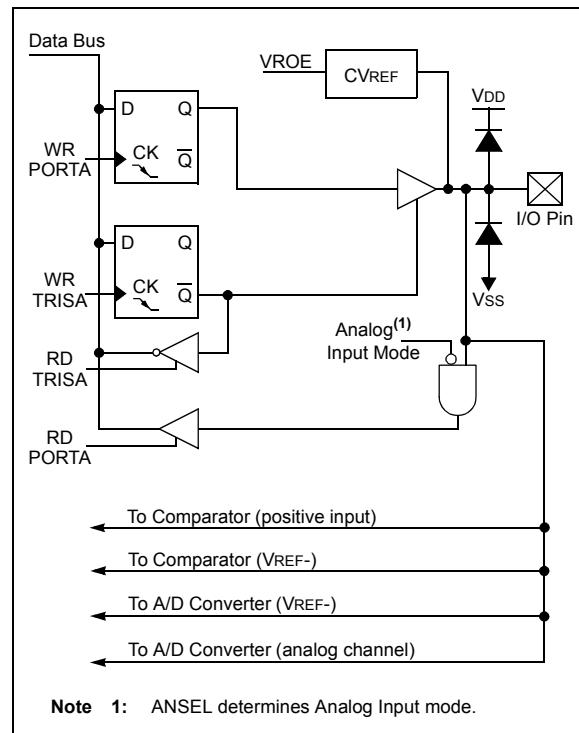
Note 1: ANSEL determines Analog Input mode.

3.2.3.3 RA2/AN2/VREF-/CVREF/C2IN+

Figure 3-3 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a negative voltage reference input for the ADC and CVREF
- a comparator voltage reference output
- a positive analog input to Comparator C2

FIGURE 3-3: BLOCK DIAGRAM OF RA2



Note 1: ANSEL determines Analog Input mode.

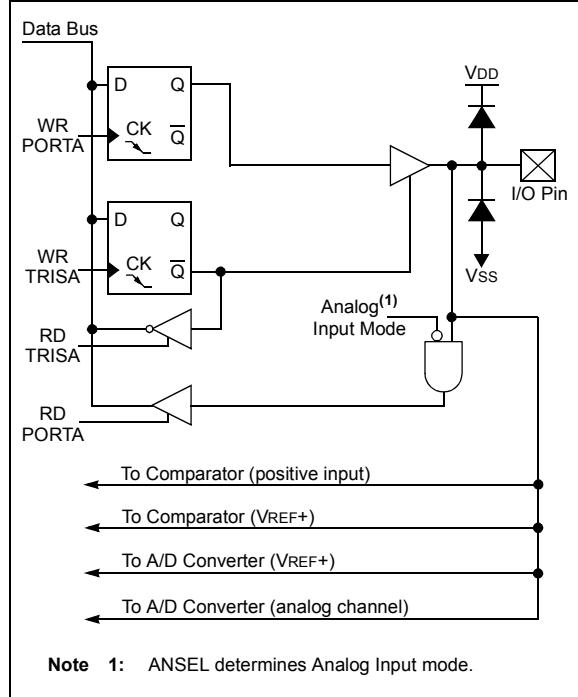
PIC16F882/883/884/886/887

3.2.3.4 RA3/AN3/VREF+/C1IN+

Figure 3-4 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose input
- an analog input for the ADC
- a positive voltage reference input for the ADC and CVREF
- a positive analog input to Comparator C1

FIGURE 3-4: BLOCK DIAGRAM OF RA3

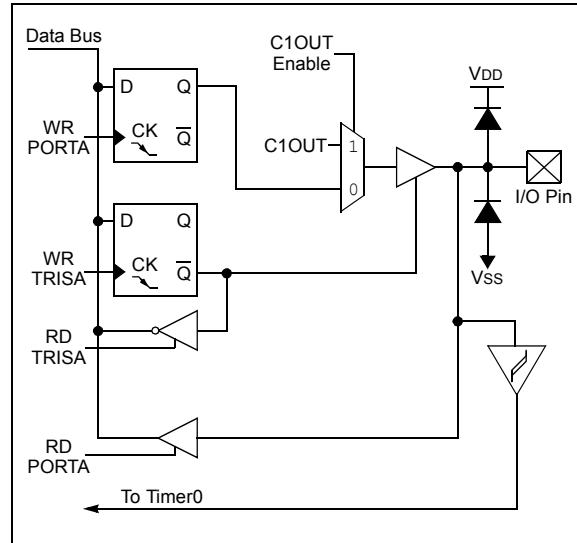


3.2.3.5 RA4/T0CKI/C1OUT

Figure 3-5 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a clock input for Timer0
- a digital output from Comparator C1

FIGURE 3-5: BLOCK DIAGRAM OF RA4

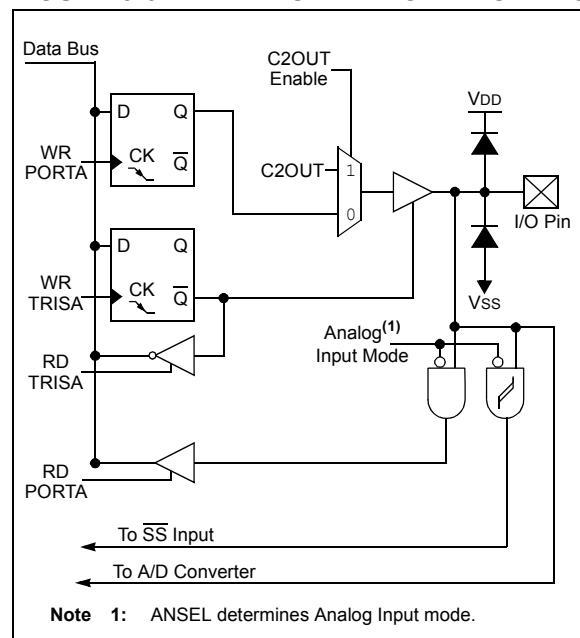


3.2.3.6 RA5/AN4/SS/C2OUT

Figure 3-6 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a slave select input
- a digital output from Comparator C2

FIGURE 3-6: BLOCK DIAGRAM OF RA5

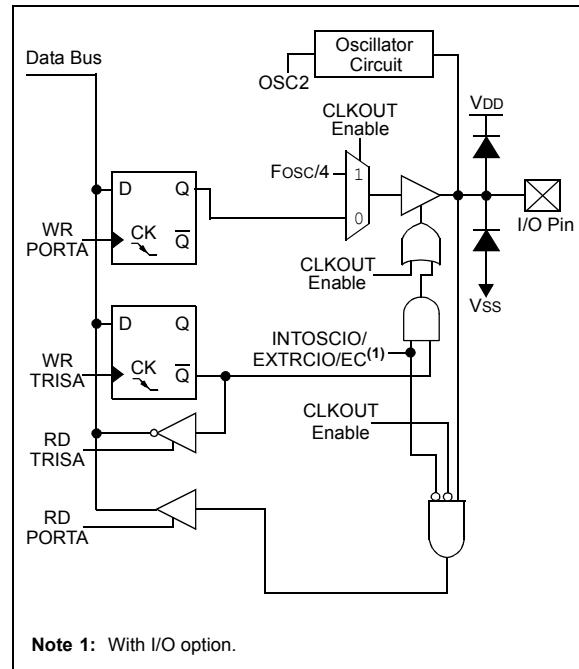


3.2.3.7 RA6/OSC2/CLKOUT

Figure 3-7 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a crystal/resonator connection
- a clock output

FIGURE 3-7: BLOCK DIAGRAM OF RA6



PIC16F882/883/884/886/887

3.2.3.8 RA7/OSC1/CLKIN

Figure 3-8 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a crystal/resonator connection
- a clock input

FIGURE 3-8: BLOCK DIAGRAM OF RA7

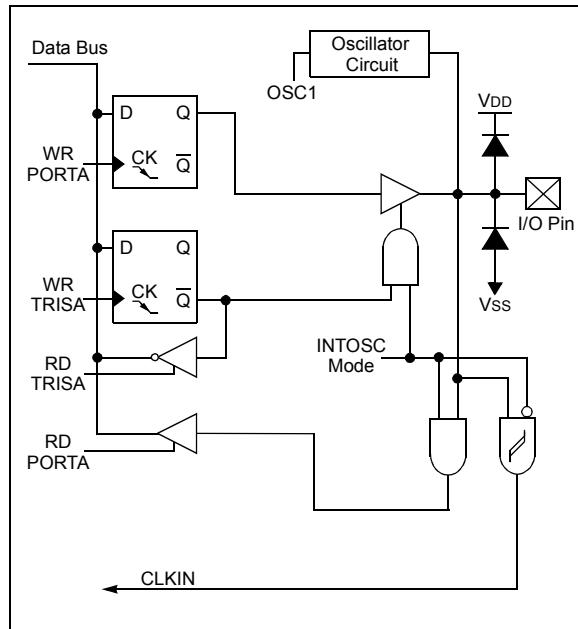


TABLE 3-1: SUMMARY OF REGISTERS ASSOCIATED WITH PORTA

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ADCON0	ADCS1	ADCS0	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON	0000 0000	0000 0000
ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	1111 1111
CM1CON0	C1ON	C1OUT	C1OE	C1POL	—	C1R	C1CH1	C1CH0	0000 -000	0000 -000
CM2CON0	C2ON	C2OUT	C2OE	C2POL	—	C2R	C2CH1	C2CH0	0000 -000	0000 -000
CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	0000 --10
PCON	—	—	ULPWUE	SBOREN	—	—	<u>POR</u>	<u>BOR</u>	--01 --qq	--0u --uu
OPTION_REG	<u>RBU</u>	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx xxxx	uuuu uuuu
SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, - = unimplemented locations read as '0'. Shaded cells are not used by PORTA.

3.3 PORTB and TRISB Registers

PORTB is an 8-bit wide, bidirectional port. The corresponding data direction register is TRISB (Register 3-6). Setting a TRISB bit (= 1) will make the corresponding PORTB pin an input (i.e., put the corresponding output driver in a High-Impedance mode). Clearing a TRISB bit (= 0) will make the corresponding PORTB pin an output (i.e., enable the output driver and put the contents of the output latch on the selected pin). Example 3-3 shows how to initialize PORTB.

Reading the PORTB register (Register 3-5) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch.

The TRISB register (Register 3-6) controls the PORTB pin output drivers, even when they are being used as analog inputs. The user should ensure the bits in the TRISB register are maintained set when using them as analog inputs. I/O pins configured as analog input always read '0'. Example 3-3 shows how to initialize PORTB.

EXAMPLE 3-3: INITIALIZING PORTB

```
BANKSEL PORTB      ;  
CLRF  PORTB       ;Init PORTB  
BANKSEL TRISB     ;  
MOVLW B'11110000' ;Set RB<7:4> as inputs  
                  ;and RB<3:0> as outputs  
MOVWF TRISB       ;
```

Note: The ANSELH register must be initialized to configure an analog channel as a digital input. Pins configured as analog inputs will read '0'.

3.4 Additional PORTB Pin Functions

PORTB pins RB<7:0> on the device family device have an interrupt-on-change option and a weak pull-up option. The following three sections describe these PORTB pin functions.

Every PORTB pin on this device family has an interrupt-on-change option and a weak pull-up option.

3.4.1 ANSELH REGISTER

The ANSELH register (Register 3-4) is used to configure the Input mode of an I/O pin to analog. Setting the appropriate ANSELH bit high will cause all digital reads on the pin to be read as '0' and allow analog functions on the pin to operate correctly.

The state of the ANSELH bits has no affect on digital output functions. A pin with TRIS clear and ANSELH set will still operate as a digital output, but the Input mode will be analog. This can cause unexpected behavior when executing read-modify-write instructions on the affected port.

3.4.2 WEAK PULL-UPS

Each of the PORTB pins has an individually configurable internal weak pull-up. Control bits WPUB<7:0> enable or disable each pull-up (see Register 3-7). Each weak pull-up is automatically turned off when the port pin is configured as an output. All pull-ups are disabled on a Power-on Reset by the RBPU bit of the OPTION register.

3.4.3 INTERRUPT-ON-CHANGE

All of the PORTB pins are individually configurable as an interrupt-on-change pin. Control bits IOCB<7:0> enable or disable the interrupt function for each pin. Refer to Register 3-8. The interrupt-on-change feature is disabled on a Power-on Reset.

For enabled interrupt-on-change pins, the present value is compared with the old value latched on the last read of PORTB to determine which bits have changed or mismatched the old value. The 'mismatch' outputs of the last read are OR'd together to set the PORTB Change Interrupt flag bit (RBIF) in the INTCON register.

This interrupt can wake the device from Sleep. The user, in the Interrupt Service Routine, clears the interrupt by:

- Any read or write of PORTB. This will end the mismatch condition.
- Clear the flag bit RBIF.

A mismatch condition will continue to set flag bit RBIF. Reading or writing PORTB will end the mismatch condition and allow flag bit RBIF to be cleared. The latch holding the last read value is not affected by a MCLR nor Brown-out Reset. After these Resets, the RBIF flag will continue to be set if a mismatch is present.

Note: If a change on the I/O pin should occur when the read operation is being executed (start of the Q2 cycle), then the RBIF interrupt flag may not get set. Furthermore, since a read or write on a port affects all bits of that port, care must be taken when using multiple pins in Interrupt-on-Change mode. Changes on one pin may not be seen while servicing changes on another pin.

PIC16F882/883/884/886/887

REGISTER 3-4: ANSELH: ANALOG SELECT HIGH REGISTER

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	ANS13	ANS12	ANS11	ANS10	ANS9	ANS8
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **ANS<13:8>:** Analog Select bits

Analog select between analog or digital function on pins AN<13:8>, respectively.

1 = Analog input. Pin is assigned as analog input⁽¹⁾.

0 = Digital I/O. Pin is assigned to port or special function.

Note 1: Setting a pin to an analog input automatically disables the digital input circuitry, weak pull-ups, and interrupt-on-change if available. The corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

REGISTER 3-5: PORTB: PORTB REGISTER

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **RB<7:0>:** PORTB I/O Pin bit

1 = Port pin is > VIH

0 = Port pin is < VIL

REGISTER 3-6: TRISB: PORTB TRI-STATE REGISTER

| R/W-1 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **TRISB<7:0>:** PORTB Tri-State Control bit

1 = PORTB pin configured as an input (tri-stated)

0 = PORTB pin configured as an output

REGISTER 3-7: WPUB: WEAK PULL-UP PORTB REGISTER

| R/W-1 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| WPUB7 | WPUB6 | WPUB5 | WPUB4 | WPUB3 | WPUB2 | WPUB1 | WPUB0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **WPUB<7:0>**: Weak Pull-up Register bit

1 = Pull-up enabled

0 = Pull-up disabled

Note 1: Global \overline{RBPU} bit of the OPTION register must be cleared for individual pull-ups to be enabled.

2: The weak pull-up device is automatically disabled if the pin is in configured as an output.

REGISTER 3-8: IOCB: INTERRUPT-ON-CHANGE PORTB REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| IOCB7 | IOCB6 | IOCB5 | IOCB4 | IOCB3 | IOCB2 | IOCB1 | IOCB0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **IOCB<7:0>**: Interrupt-on-Change PORTB Control bit

1 = Interrupt-on-change enabled

0 = Interrupt-on-change disabled

PIC16F882/883/884/886/887

3.4.4 PIN DESCRIPTIONS AND DIAGRAMS

Each PORTB pin is multiplexed with other functions. The pins and their combined functions are briefly described here. For specific information about individual functions such as the SSP, I²C or interrupts, refer to the appropriate section in this data sheet.

3.4.4.1 RB0/AN12/INT

Figure 3-9 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- an external edge triggered interrupt

3.4.4.2 RB1/AN10/P1C⁽¹⁾/C12IN3-

Figure 3-9 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a PWM output⁽¹⁾
- an analog input to Comparator C1 or C2

Note 1: P1C is available on PIC16F882/883/886 only.

3.4.4.3 RB2/AN8/P1B⁽¹⁾

Figure 3-9 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a PWM output⁽¹⁾

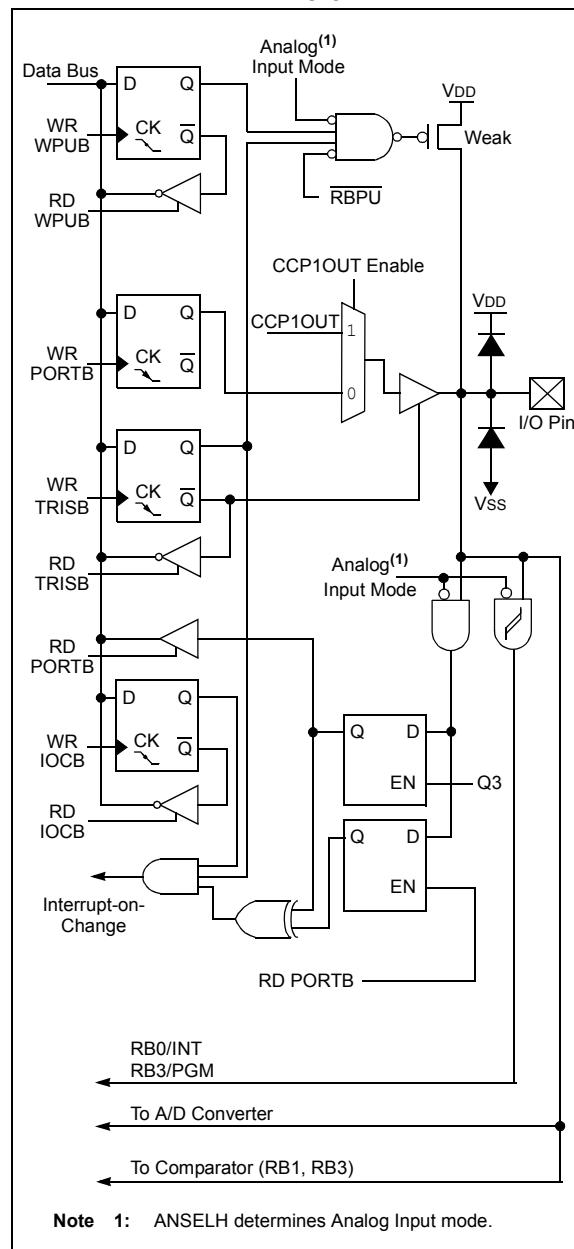
Note 1: P1B is available on PIC16F882/883/886 only.

3.4.4.4 RB3/AN9/PGM/C12IN2-

Figure 3-9 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- Low-voltage In-Circuit Serial Programming enable pin
- an analog input to Comparator C1 or C2

FIGURE 3-9: BLOCK DIAGRAM OF RB<3:0>



3.4.4.5 RB4/AN11/P1D⁽¹⁾

Figure 3-10 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a PWM output⁽¹⁾

Note 1: P1D is available on PIC16F882/883/886 only.

3.4.4.6 RB5/AN13/T1G

Figure 3-10 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC
- a Timer1 gate input

3.4.4.7 RB6/ICSPCLK

Figure 3-10 shows the diagram for this pin. This pin is configurable to function as one of the following:

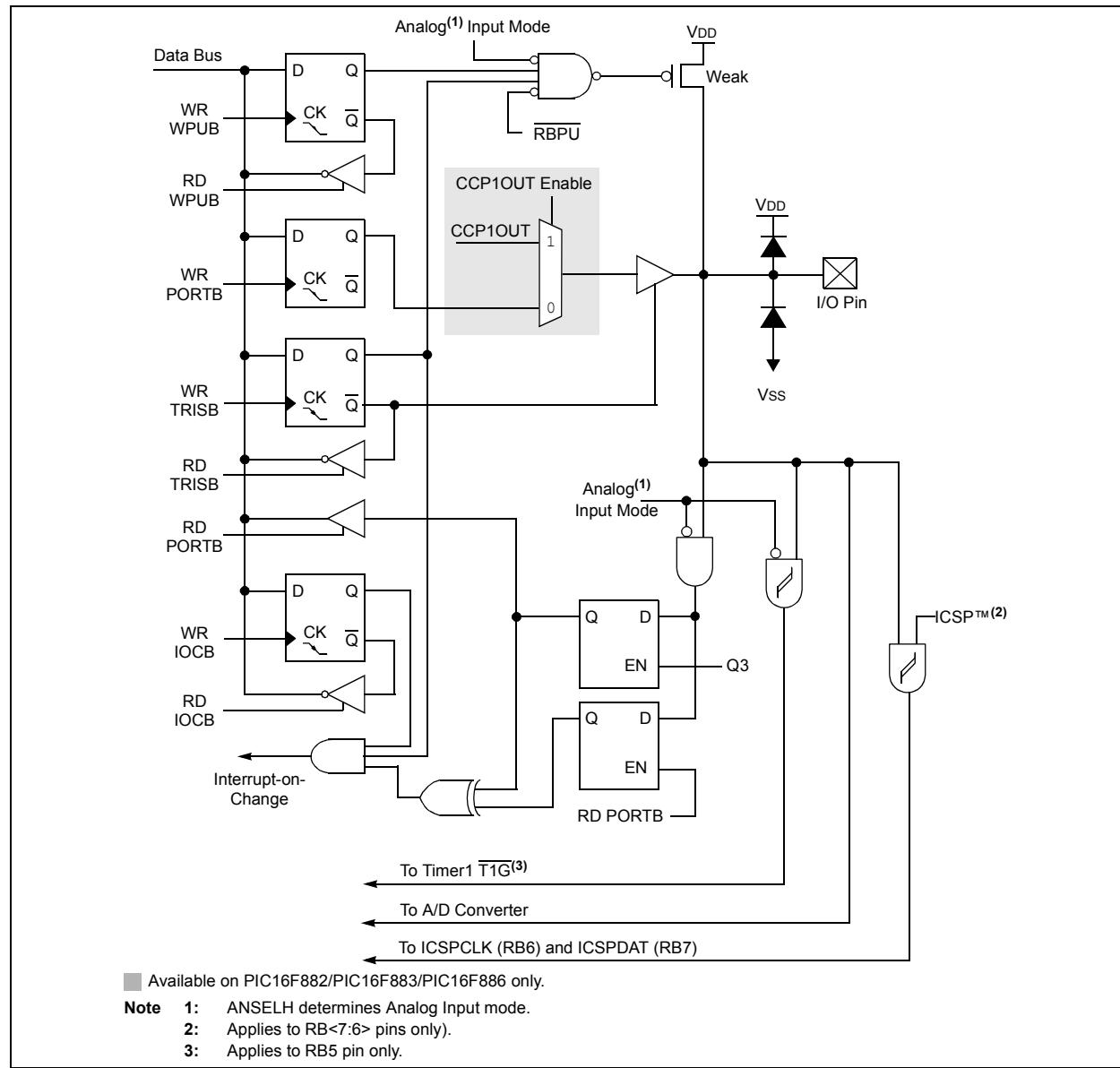
- a general purpose I/O
- In-Circuit Serial Programming clock

3.4.4.8 RB7/ICSPDAT

Figure 3-10 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- In-Circuit Serial Programming data

FIGURE 3-10: BLOCK DIAGRAM OF RB<7:4>



PIC16F882/883/884/886/887

TABLE 3-2: SUMMARY OF REGISTERS ASSOCIATED WITH PORTB

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSELH	—	—	ANS13	ANS12	ANS11	ANS10	ANS9	ANS8	--11 1111	--11 1111
CCP1CON	P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	0000 0000	0000 0000
CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	0000 --10
IOCB	IOCB7	IOCB6	IOCB5	IOCB4	IOCB3	IOCB2	IOCB1	IOCB0	0000 0000	0000 0000
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
OPTION_REG	<u>RBPU</u>	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	uuuu uuuu
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	1111 1111
WPUB	WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, — = unimplemented read as '0'. Shaded cells are not used by PORTB.

3.5 PORTC and TRISC Registers

PORTC is a 8-bit wide, bidirectional port. The corresponding data direction register is TRISC (Register 3-10). Setting a TRISC bit (= 1) will make the corresponding PORTC pin an input (i.e., put the corresponding output driver in a High-Impedance mode). Clearing a TRISC bit (= 0) will make the corresponding PORTC pin an output (i.e., enable the output driver and put the contents of the output latch on the selected pin). Example 3-4 shows how to initialize PORTC.

Reading the PORTC register (Register 3-9) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch.

REGISTER 3-9: PORTC: PORTC REGISTER

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| RC7 | RC6 | RC5 | RC4 | RC3 | RC2 | RC1 | RC0 |
| bit 7 | | | | bit 0 | | | |

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared

bit 7-0 **RC<7:0>**: PORTC General Purpose I/O Pin bit
 1 = Port pin is > VIH
 0 = Port pin is < VIL

REGISTER 3-10: TRISC: PORTC TRI-STATE REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1 ⁽¹⁾	R/W-1 ⁽¹⁾
TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared

bit 7-0 **TRISC<7:0>**: PORTC Tri-State Control bit
 1 = PORTC pin configured as an input (tri-stated)
 0 = PORTC pin configured as an output

Note 1: TRISC<1:0> always reads '1' in LP Oscillator mode.

The TRISC register (Register 3-10) controls the PORTC pin output drivers, even when they are being used as analog inputs. The user should ensure the bits in the TRISC register are maintained set when using them as analog inputs. I/O pins configured as analog input always read '0'.

EXAMPLE 3-4: INITIALIZING PORTC

```
BANKSEL PORTC          ;  
CLRF    PORTC          ;Init PORTC  
BANKSEL TRISC          ;  
MOVLW   B'000001100'    ;Set RC<3:2> as inputs  
MOVWF   TRISC          ;and set RC<7:4,1:0>  
                      ;as outputs
```

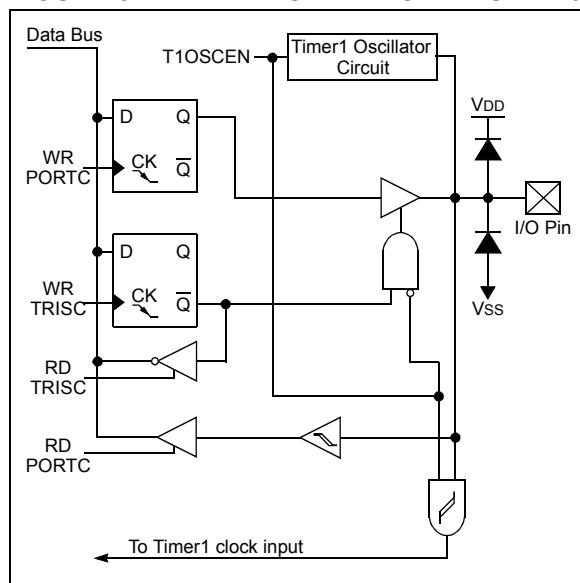
PIC16F882/883/884/886/887

3.5.1 RC0/T1OSO/T1CKI

Figure 3-11 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a Timer1 oscillator output
- a Timer1 clock input

FIGURE 3-11: BLOCK DIAGRAM OF RC0

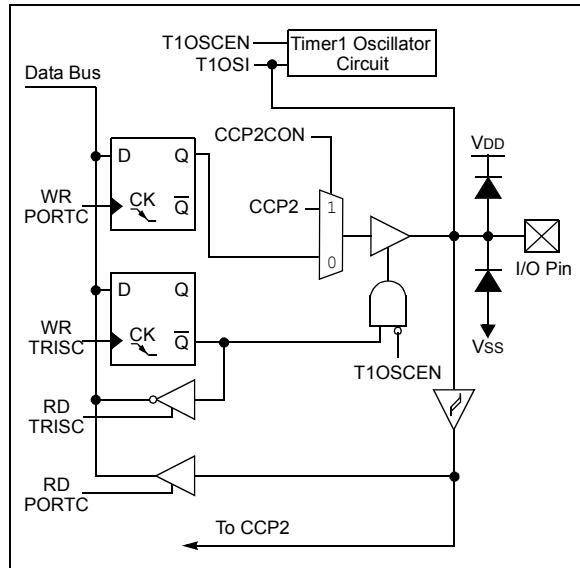


3.5.2 RC1/T1OSI/CCP2

Figure 3-12 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a Timer1 oscillator input
- a Capture input and Compare/PWM output for Comparator C2

FIGURE 3-12: BLOCK DIAGRAM OF RC1

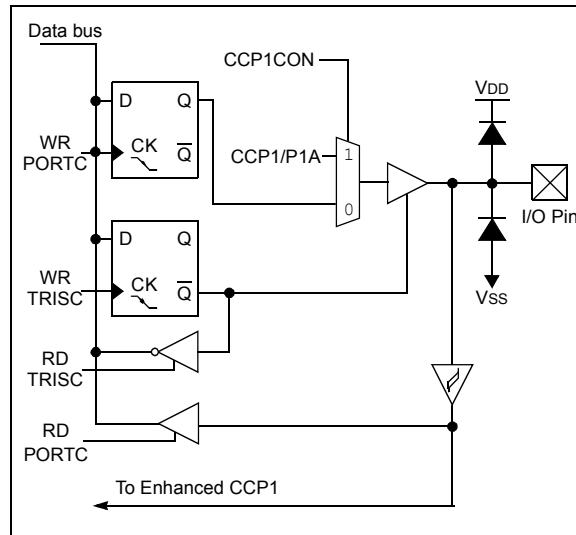


3.5.3 RC2/P1A/CCP1

Figure 3-13 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a PWM output
- a Capture input and Compare output for Comparator C1

FIGURE 3-13: BLOCK DIAGRAM OF RC2

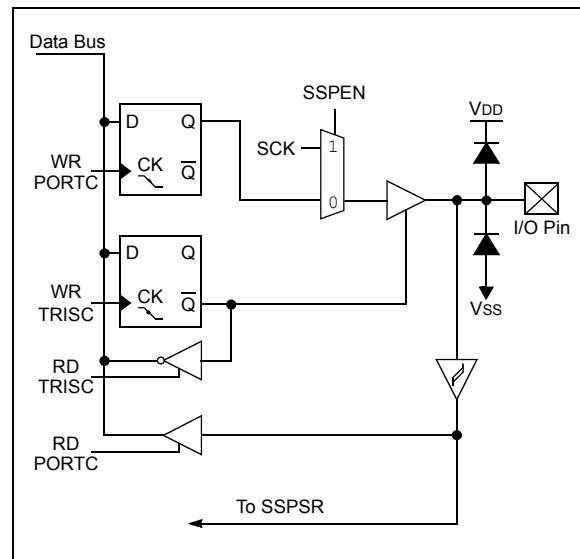


3.5.4 RC3/SCK/SCL

Figure 3-14 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a SPI clock
- an I²C™ clock

FIGURE 3-14: BLOCK DIAGRAM OF RC3

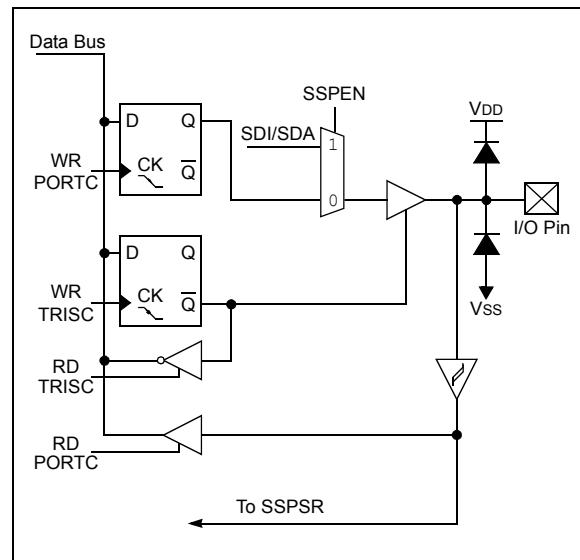


3.5.5 RC4/SDI/SDA

Figure 3-15 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a SPI data I/O
- an I²C data I/O

FIGURE 3-15: BLOCK DIAGRAM OF RC4

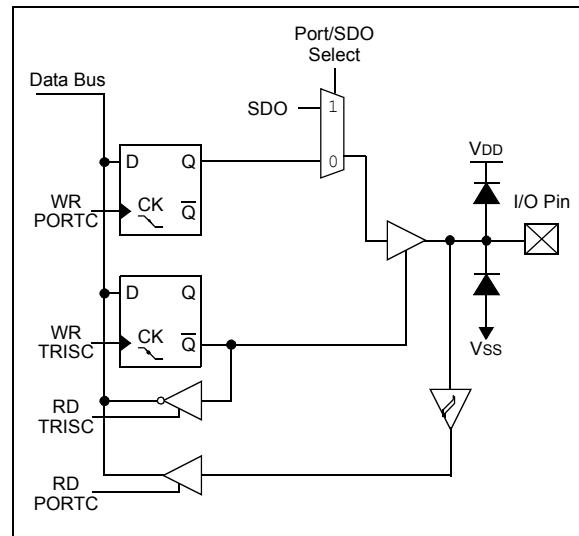


3.5.6 RC5/SDO

Figure 3-16 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a serial data output

FIGURE 3-16: BLOCK DIAGRAM OF RC5



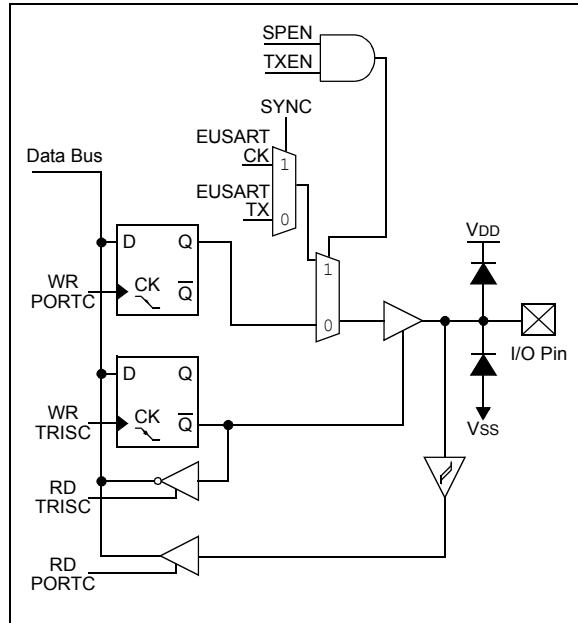
PIC16F882/883/884/886/887

3.5.7 RC6/TX/CK

Figure 3-17 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an asynchronous serial output
- a synchronous clock I/O

FIGURE 3-17: BLOCK DIAGRAM OF RC6



3.5.8 RC7/RX/DT

Figure 3-18 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- an asynchronous serial input
- a synchronous serial data I/O

FIGURE 3-18: BLOCK DIAGRAM OF RC7

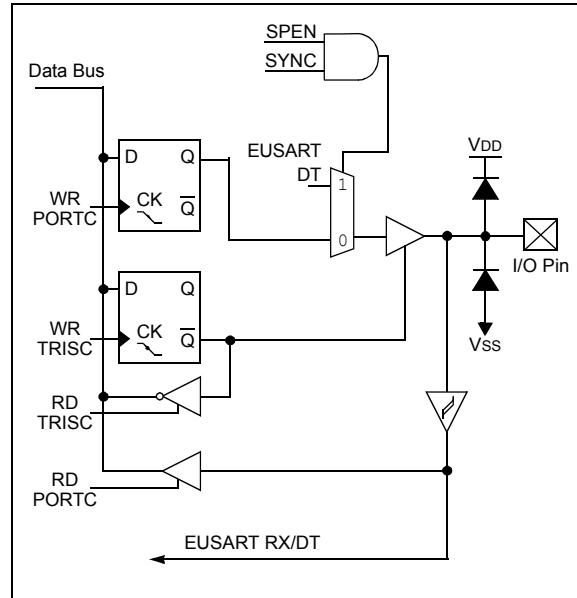


TABLE 3-3: SUMMARY OF REGISTERS ASSOCIATED WITH PORTC

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
CCP1CON	P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	0000 0000	0000 0000
CCP2CON	—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	--00 0000	--00 0000
PORTC	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx xxxx	uuuu uuuu
PSTRCON	—	—	—	STRSYNC	STRD	STRC	STRB	STRA	---0 0001	---0 0001
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
T1CON	T1GINV	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISCO	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by PORTC.

3.6 PORTD and TRISD Registers

PORTD⁽¹⁾ is a 8-bit wide, bidirectional port. The corresponding data direction register is TRISD (Register 3-12). Setting a TRISD bit (= 1) will make the corresponding PORTD pin an input (i.e., put the corresponding output driver in a High-Impedance mode). Clearing a TRISD bit (= 0) will make the corresponding PORTD pin an output (i.e., enable the output driver and put the contents of the output latch on the selected pin). Example 3-5 shows how to initialize PORTD.

Reading the PORTD register (Register 3-11) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch.

Note 1: PORTD is available on PIC16F884/887 only.

REGISTER 3-11: PORTD: PORTD REGISTER

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| RD7 | RD6 | RD5 | RD4 | RD3 | RD2 | RD1 | RD0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **RD<7:0>**: PORTD General Purpose I/O Pin bit
 1 = Port pin is > VIH
 0 = Port pin is < VIL

REGISTER 3-12: TRISD: PORTD TRI-STATE REGISTER

| R/W-1 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| TRISD7 | TRISD6 | TRISD5 | TRISD4 | TRISD3 | TRISD2 | TRISD1 | TRISD0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **TRISD<7:0>**: PORTD Tri-State Control bit
 1 = PORTD pin configured as an input (tri-stated)
 0 = PORTD pin configured as an output

The TRISD register (Register 3-12) controls the PORTD pin output drivers, even when they are being used as analog inputs. The user should ensure the bits in the TRISD register are maintained set when using them as analog inputs. I/O pins configured as analog input always read '0'.

EXAMPLE 3-5: INITIALIZING PORTD

```
BANKSEL PORTD      ;  

CLRF   PORTD       ;Init PORTD  

BANKSEL TRISD      ;  

MOVlw  B'00001100'  ;Set RD<3:2> as inputs  

MOVwf  TRISD       ;and set RD<7:4,1:0>  

                   ;as outputs
```

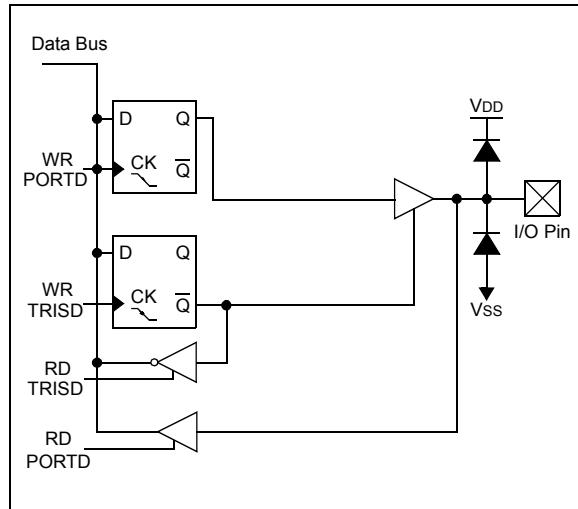
PIC16F882/883/884/886/887

3.6.1 RD<4:0>

Figure 3-19 shows the diagram for these pins. These pins are configured to function as general purpose I/O's.

Note: RD<4:0> is available on PIC16F884/887 only.

FIGURE 3-19: BLOCK DIAGRAM OF RD<4:0>



3.6.2 RD5/P1B⁽¹⁾

Figure 3-20 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a PWM output

Note 1: RD5/P1B is available on PIC16F884/887 only. See RB2/AN8/P1B for this function on PIC16F882/883/886.

3.6.3 RD6/P1C⁽¹⁾

Figure 3-20 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a PWM output

Note 1: RD6/P1C is available on PIC16F884/887 only. See RB1/AN10/P1C/C12IN3- for this function on PIC16F882/883/886.

3.6.4 RD7/P1D⁽¹⁾

Figure 3-20 shows the diagram for this pin. This pin is configurable to function as one of the following:

- a general purpose I/O
- a PWM output

Note 1: RD7/P1D is available on PIC16F884/887 only. See RB4/AN11/P1D for this function on PIC16F882/883/886.

FIGURE 3-20: BLOCK DIAGRAM OF RD<7:5>

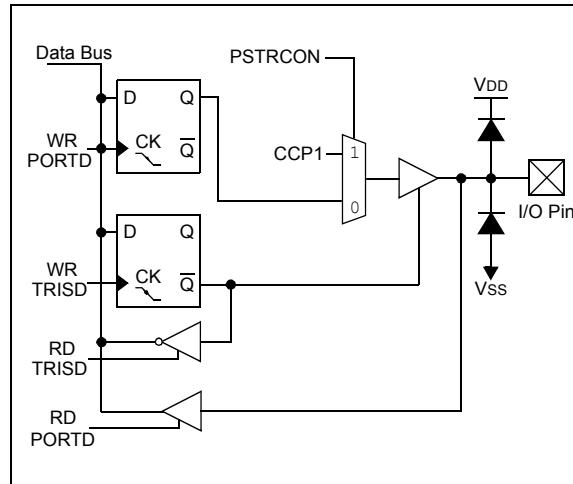


TABLE 3-4: SUMMARY OF REGISTERS ASSOCIATED WITH PORTD

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
PORTD	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0	xxxx xxxx	uuuu uuuu
PSTRCON	—	—	—	STRSYNC	STRD	STRC	STRB	STRA	---0 0001	---0 0001
TRISD	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by PORTD.

3.7 PORTE and TRISE Registers

PORTE⁽¹⁾ is a 4-bit wide, bidirectional port. The corresponding data direction register is TRISE. Setting a TRISE bit (= 1) will make the corresponding PORTE pin an input (i.e., put the corresponding output driver in a High-Impedance mode). Clearing a TRISE bit (= 0) will make the corresponding PORTE pin an output (i.e., enable the output driver and put the contents of the output latch on the selected pin). The exception is RE3, which is input only and its TRIS bit will always read as '1'. Example 3-6 shows how to initialize PORTE.

Reading the PORTE register (Register 3-13) reads the status of the pins, whereas writing to it will write to the PORT latch. All write operations are read-modify-write operations. Therefore, a write to a port implies that the port pins are read, this value is modified and then written to the PORT data latch. RE3 reads '0' when MCLRE = 1.

Note 1: RE<2:0> pins are available on PIC16F884/887 only.

The TRISE register (Register 3-14) controls the PORTE pin output drivers, even when they are being used as analog inputs. The user should ensure the bits in the TRISE register are maintained set when using them as analog inputs. I/O pins configured as analog input always read '0'.

Note: The ANSEL register must be initialized to configure an analog channel as a digital input. Pins configured as analog inputs will read '0'.

EXAMPLE 3-6: INITIALIZING PORTE

```
BANKSEL PORTE      ;  
CLRF  PORTE       ;Init PORTE  
BANKSEL ANSEL      ;  
CLRF  ANSEL       ;digital I/O  
BCF   STATUS,RP1   ;Bank 1  
BANKSEL TRISE      ;  
MOVLW B'00001100'  ;Set RE<3:2> as inputs  
MOVWF  TRISE       ;and set RE<1:0>  
                  ;as outputs
```

REGISTER 3-13: PORTE: PORTE REGISTER

U-0	U-0	U-0	U-0	R-x	R/W-x	R/W-x	R/W-x
—	—	—	—	RE3	RE2	RE1	RE0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **Unimplemented:** Read as '0'

bit 3-0 **RD<3:0>:** PORTE General Purpose I/O Pin bit

1 = Port pin is > VIH

0 = Port pin is < VIL

REGISTER 3-14: TRISE: PORTE TRI-STATE REGISTER

U-0	U-0	U-0	U-0	R-1 ⁽¹⁾	R/W-1	R/W-1	R/W-1
—	—	—	—	TRISE3	TRISE2	TRISE1	TRISE0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **Unimplemented:** Read as '0'

bit 3-0 **TRISE<3:0>:** PORTE Tri-State Control bit

1 = PORTE pin configured as an input (tri-stated)

0 = PORTE pin configured as an output

Note 1: TRISE<3> always reads '1'.

PIC16F882/883/884/886/887

3.7.1 RE0/AN5⁽¹⁾

This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC

Note 1: RE0/AN5 is available on PIC16F884/887 only.

3.7.2 RE1/AN6⁽¹⁾

This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC

Note 1: RE1/AN6 is available on PIC16F884/887 only.

3.7.3 RE2/AN7⁽¹⁾

This pin is configurable to function as one of the following:

- a general purpose I/O
- an analog input for the ADC

Note 1: RE2/AN7 is available on PIC16F884/887 only.

FIGURE 3-21: BLOCK DIAGRAM OF RE<2:0>

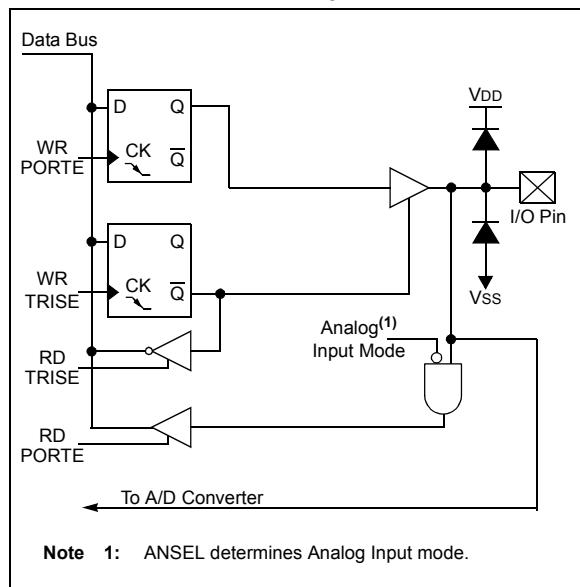


TABLE 3-5: SUMMARY OF REGISTERS ASSOCIATED WITH PORTE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	1111 1111
PORTE	—	—	—	—	RE3	RE2	RE1	RE0	---- xxxx	---- uuuu
TRISE	—	—	—	—	TRISE3	TRISE2	TRISE1	TRISE0	---- 1111	---- 1111

Legend: x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by PORTE

4.0 OSCILLATOR MODULE (WITH FAIL-SAFE CLOCK MONITOR)

4.1 Overview

The oscillator module has a wide variety of clock sources and selection features that allow it to be used in a wide range of applications while maximizing performance and minimizing power consumption. Figure 4-1 illustrates a block diagram of the oscillator module.

Clock sources can be configured from external oscillators, quartz crystal resonators, ceramic resonators and Resistor-Capacitor (RC) circuits. In addition, the system clock source can be configured from one of two internal oscillators, with a choice of speeds selectable via software. Additional clock features include:

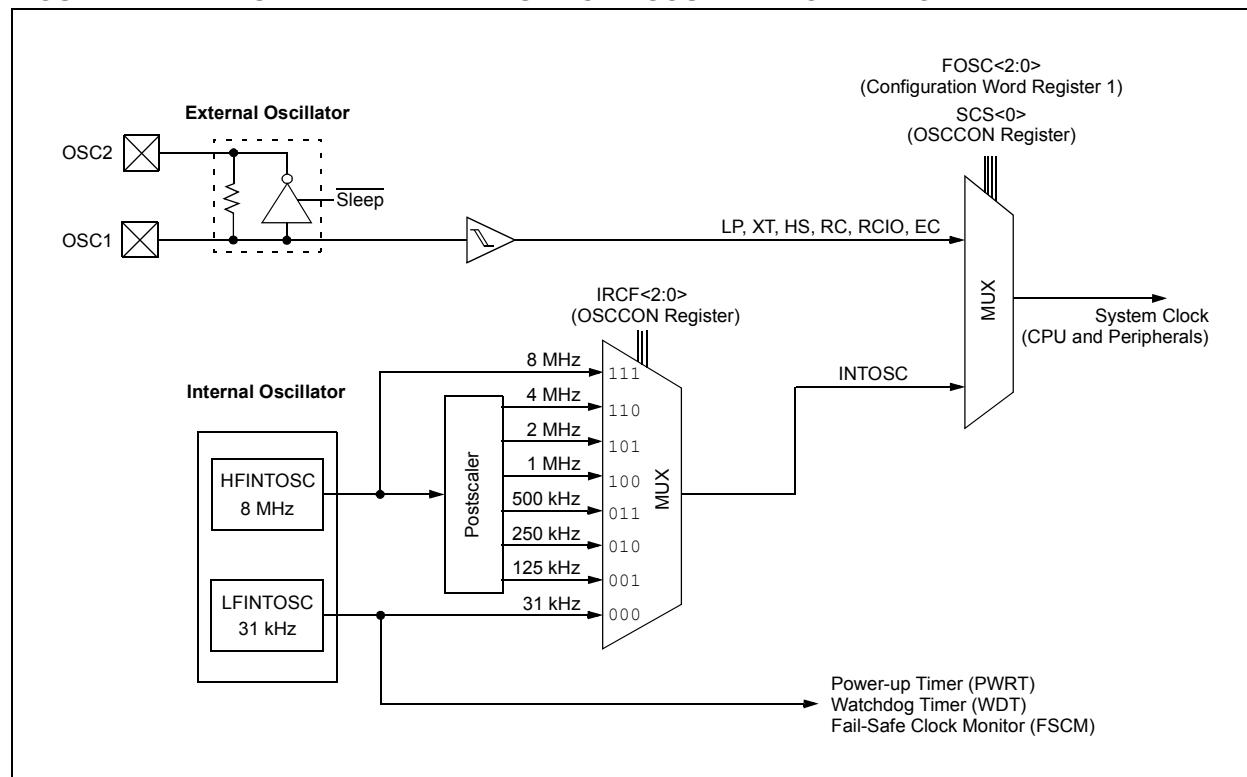
- Selectable system clock source between external or internal via software.
- Two-Speed Start-up mode, which minimizes latency between external oscillator start-up and code execution.
- Fail-Safe Clock Monitor (FSCM) designed to detect a failure of the external clock source (LP, XT, HS, EC or RC modes) and switch automatically to the internal oscillator.

The oscillator module can be configured in one of eight clock modes.

1. EC – External clock with I/O on OSC2/CLKOUT.
2. LP – 32 kHz Low-Power Crystal mode.
3. XT – Medium Gain Crystal or Ceramic Resonator Oscillator mode.
4. HS – High Gain Crystal or Ceramic Resonator mode.
5. RC – External Resistor-Capacitor (RC) with Fosc/4 output on OSC2/CLKOUT.
6. RCIO – External Resistor-Capacitor (RC) with I/O on OSC2/CLKOUT.
7. INTOSC – Internal oscillator with Fosc/4 output on OSC2 and I/O on OSC1/CLKIN.
8. INTSCIO – Internal oscillator with I/O on OSC1/CLKIN and OSC2/CLKOUT.

Clock Source modes are configured by the FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1). The internal clock can be generated from two internal oscillators. The HFINTOSC is a calibrated high-frequency oscillator. The LFINTOSC is an uncalibrated low-frequency oscillator.

FIGURE 4-1: SIMPLIFIED PIC® MCU CLOCK SOURCE BLOCK DIAGRAM



PIC16F882/883/884/886/887

4.2 Oscillator Control

The Oscillator Control (OSCCON) register (Figure 4-1) controls the system clock and frequency selection options. The OSCCON register contains the following bits:

- Frequency selection bits (IRCF)
- Frequency Status bits (HTS, LTS)
- System clock control bits (OSTS, SCS)

REGISTER 4-1: OSCCON: OSCILLATOR CONTROL REGISTER

U-0	R/W-1	R/W-1	R/W-0	R-1	R-0	R-0	R/W-0
—	IRCF2	IRCF1	IRCF0	OSTS ⁽¹⁾	HTS	LTS	SCS
bit 7					bit 0		

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IRCF<2:0>:** Internal Oscillator Frequency Select bits

111 = 8 MHz

110 = 4 MHz (default)

101 = 2 MHz

100 = 1 MHz

011 = 500 kHz

010 = 250 kHz

001 = 125 kHz

000 = 31 kHz (LFINTOSC)

bit 3 **OSTS:** Oscillator Start-up Time-out Status bit⁽¹⁾

1 = Device is running from the clock defined by FOSC<2:0> of the CONFIG1 register

0 = Device is running from the internal oscillator (HFINTOSC or LFINTOSC)

bit 2 **HTS:** HFINTOSC Status bit (High Frequency – 8 MHz to 125 kHz)

1 = HFINTOSC is stable

0 = HFINTOSC is not stable

bit 1 **LTS:** LFINTOSC Stable bit (Low Frequency – 31 kHz)

1 = LFINTOSC is stable

0 = LFINTOSC is not stable

bit 0 **SCS:** System Clock Select bit

1 = Internal oscillator is used for system clock

0 = Clock source defined by FOSC<2:0> of the CONFIG1 register

Note 1: Bit resets to '0' with Two-Speed Start-up and LP, XT or HS selected as the Oscillator mode or Fail-Safe mode is enabled.

4.3 Clock Source Modes

Clock Source modes can be classified as external or internal.

- External Clock modes rely on external circuitry for the clock source. Examples are: oscillator modules (EC mode), quartz crystal resonators or ceramic resonators (LP, XT and HS modes) and Resistor-Capacitor (RC) mode circuits.
- Internal clock sources are contained internally within the oscillator module. The oscillator module has two internal oscillators: the 8 MHz High-Frequency Internal Oscillator (HFINTOSC) and the 31 kHz Low-Frequency Internal Oscillator (LFINTOSC).

The system clock can be selected between external or internal clock sources via the System Clock Select (SCS) bit of the OSCCON register. See **Section 4.6 “Clock Switching”** for additional information.

4.4 External Clock Modes

4.4.1 OSCILLATOR START-UP TIMER (OST)

If the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) counts 1024 oscillations from OSC1. This occurs following a Power-on Reset (POR) and when the Power-up Timer (PWRT) has expired (if configured), or a wake-up from Sleep. During this time, the program counter does not increment and program execution is suspended. The OST ensures that the oscillator circuit, using a quartz crystal resonator or ceramic resonator, has started and is providing a stable system clock to the oscillator module. When switching between clock sources, a delay is required to allow the new clock to stabilize. These oscillator delays are shown in Table 4-1.

In order to minimize latency between external oscillator start-up and code execution, the Two-Speed Clock Start-up mode can be selected (see **Section 4.7 “Two-Speed Clock Start-up Mode”**).

TABLE 4-1: OSCILLATOR DELAY EXAMPLES

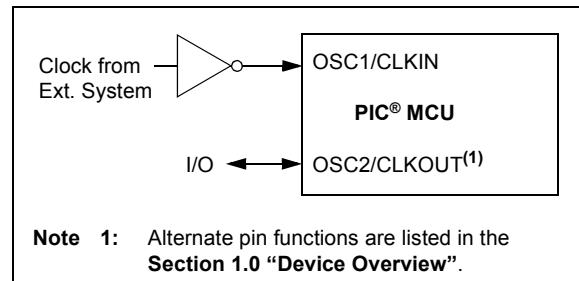
Switch From	Switch To	Frequency	Oscillator Delay
Sleep/POR	LFINTOSC HFINTOSC	31 kHz 125 kHz to 8 MHz	Oscillator Warm-up Delay (TWARM)
Sleep/POR	EC, RC	DC – 20 MHz	2 cycles
LFINTOSC (31 kHz)	EC, RC	DC – 20 MHz	1 cycle of each
Sleep/POR	LP, XT, HS	32 kHz to 20 MHz	1024 Clock Cycles (OST)
LFINTOSC (31 kHz)	HFINTOSC	125 kHz to 8 MHz	1 μ s (approx.)

4.4.2 EC MODE

The External Clock (EC) mode allows an externally generated logic level as the system clock source. When operating in this mode, an external clock source is connected to the OSC1 input and the OSC2 is available for general purpose I/O. Figure 4-2 shows the pin connections for EC mode.

The Oscillator Start-up Timer (OST) is disabled when EC mode is selected. Therefore, there is no delay in operation after a Power-on Reset (POR) or wake-up from Sleep. Because the PIC® MCU design is fully static, stopping the external clock input will have the effect of halting the device while leaving all data intact. Upon restarting the external clock, the device will resume operation as if no time had elapsed.

FIGURE 4-2: EXTERNAL CLOCK (EC) MODE OPERATION



PIC16F882/883/884/886/887

4.4.3 LP, XT, HS MODES

The LP, XT and HS modes support the use of quartz crystal resonators or ceramic resonators connected to OSC1 and OSC2 (Figure 4-3). The mode selects a low, medium or high gain setting of the internal inverter-amplifier to support various resonator types and speed.

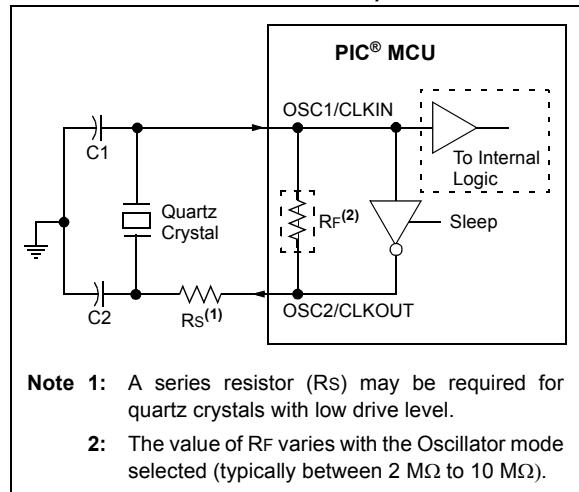
LP Oscillator mode selects the lowest gain setting of the internal inverter-amplifier. LP mode current consumption is the least of the three modes. This mode is designed to drive only 32.768 kHz tuning-fork type crystals (watch crystals).

XT Oscillator mode selects the intermediate gain setting of the internal inverter-amplifier. XT mode current consumption is the medium of the three modes. This mode is best suited to drive resonators with a medium drive level specification.

HS Oscillator mode selects the highest gain setting of the internal inverter-amplifier. HS mode current consumption is the highest of the three modes. This mode is best suited for resonators that require a high drive setting.

Figure 4-3 and Figure 4-4 show typical circuits for quartz crystal and ceramic resonators, respectively.

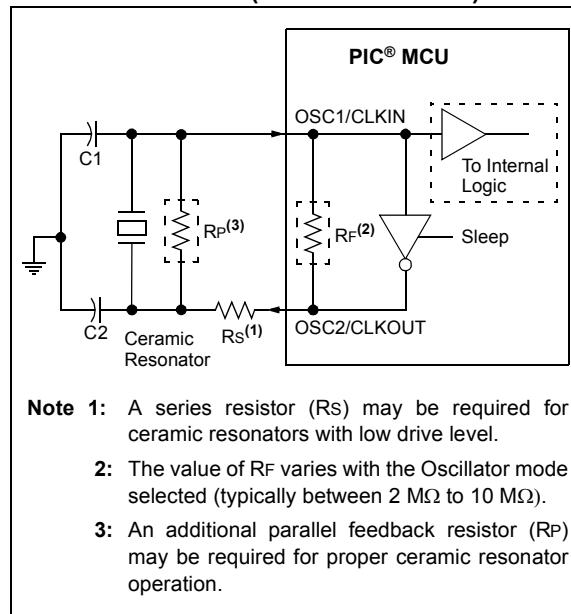
FIGURE 4-3: QUARTZ CRYSTAL OPERATION (LP, XT OR HS MODE)



Note 1: Quartz crystal characteristics vary according to type, package and manufacturer. The user should consult the manufacturer data sheets for specifications and recommended application.

- 2:** Always verify oscillator performance over the VDD and temperature range that is expected for the application.
- 3:** For oscillator design assistance, reference the following Microchip Applications Notes:
 - AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC® and PIC® Devices" (DS00826)
 - AN849, "Basic PIC® Oscillator Design" (DS00849)
 - AN943, "Practical PIC® Oscillator Analysis and Design" (DS00943)
 - AN949, "Making Your Oscillator Work" (DS00949)

FIGURE 4-4: CERAMIC RESONATOR OPERATION (XT OR HS MODE)

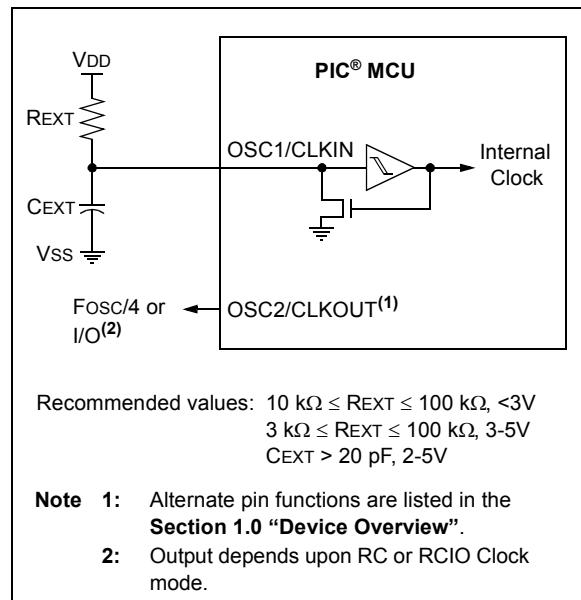


4.4.4 EXTERNAL RC MODES

The external Resistor-Capacitor (RC) modes support the use of an external RC circuit. This allows the designer maximum flexibility in frequency choice while keeping costs to a minimum when clock accuracy is not required. There are two modes: RC and RCIO.

In RC mode, the RC circuit connects to OSC1. OSC2/CLKOUT outputs the RC oscillator frequency divided by 4. This signal may be used to provide a clock for external circuitry, synchronization, calibration, test or other application requirements. Figure 4-5 shows the external RC mode connections.

FIGURE 4-5: EXTERNAL RC MODES



In RCIO mode, the RC circuit is connected to OSC1. OSC2 becomes an additional general purpose I/O pin.

The RC oscillator frequency is a function of the supply voltage, the resistor (REXT) and capacitor (CEXT) values and the operating temperature. Other factors affecting the oscillator frequency are:

- threshold voltage variation
- component tolerances
- packaging variations in capacitance

The user also needs to take into account variation due to tolerance of external RC components used.

4.5 Internal Clock Modes

The oscillator module has two independent, internal oscillators that can be configured or selected as the system clock source.

1. The **HFINTOSC** (High-Frequency Internal Oscillator) is factory calibrated and operates at 8 MHz. The frequency of the HFINTOSC can be user-adjusted via software using the OSCTUNE register (Register 4-2).
2. The **LFINTOSC** (Low-Frequency Internal Oscillator) is uncalibrated and operates at 31 kHz.

The system clock speed can be selected via software using the Internal Oscillator Frequency Select bits IRCF<2:0> of the OSCCON register.

The system clock can be selected between external or internal clock sources via the System Clock Selection (SCS) bit of the OSCCON register. See **Section 4.6 "Clock Switching"** for more information.

4.5.1 INTOSC AND INTOSCI MODES

The INTOSC and INTOSCI modes configure the internal oscillators as the system clock source when the device is programmed using the oscillator selection or the FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1).

In **INTOSC** mode, OSC1/CLKIN is available for general purpose I/O. OSC2/CLKOUT outputs the selected internal oscillator frequency divided by 4. The CLKOUT signal may be used to provide a clock for external circuitry, synchronization, calibration, test or other application requirements.

In **INTOSCI** mode, OSC1/CLKIN and OSC2/CLKOUT are available for general purpose I/O.

4.5.2 HFINTOSC

The High-Frequency Internal Oscillator (HFINTOSC) is a factory calibrated 8 MHz internal clock source. The frequency of the HFINTOSC can be altered via software using the OSCTUNE register (Register 4-2).

The output of the HFINTOSC connects to a postscaler and multiplexer (see Figure 4-1). One of seven frequencies can be selected via software using the IRCF<2:0> bits of the OSCCON register. See **Section 4.5.4 "Frequency Select Bits (IRCF)"** for more information.

The HFINTOSC is enabled by selecting any frequency between 8 MHz and 125 kHz by setting the IRCF<2:0> bits of the OSCCON register $\neq 000$. Then, set the System Clock Source (SCS) bit of the OSCCON register to '1' or enable Two-Speed Start-up by setting the IESO bit in the Configuration Word Register 1 (CONFIG1) to '1'.

The HF Internal Oscillator (HTS) bit of the OSCCON register indicates whether the HFINTOSC is stable or not.

PIC16F882/883/884/886/887

4.5.2.1 OSCTUNE Register

The HFINTOSC is factory calibrated but can be adjusted in software by writing to the OSCTUNE register (Register 4-2).

The default value of the OSCTUNE register is '0'. The value is a 5-bit two's complement number.

When the OSCTUNE register is modified, the HFINTOSC frequency will begin shifting to the new frequency. Code execution continues during this shift. There is no indication that the shift has occurred.

OSCTUNE does not affect the LFINTOSC frequency. Operation of features that depend on the LFINTOSC clock source frequency, such as the Power-up Timer (PWRT), Watchdog Timer (WDT), Fail-Safe Clock Monitor (FSCM) and peripherals, are *not* affected by the change in frequency.

REGISTER 4-2: OSCTUNE: OSCILLATOR TUNING REGISTER

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5

Unimplemented: Read as '0'

bit 4-0

TUN<4:0>: Frequency Tuning bits

01111 = Maximum frequency

01110 =

•

•

•

00001 =

00000 = Oscillator module is running at the factory-calibrated frequency.

11111 =

•

•

•

10000 = Minimum frequency

4.5.3 LFINTOSC

The Low-Frequency Internal Oscillator (LFINTOSC) is an uncalibrated 31 kHz internal clock source.

The output of the LFINTOSC connects to a postscaler and multiplexer (see Figure 4-1). Select 31 kHz, via software, using the **IRCF<2:0>** bits of the OSCCON register. See **Section 4.5.4 “Frequency Select Bits (IRCF)**” for more information. The LFINTOSC is also the frequency for the Power-up Timer (PWRT), Watchdog Timer (WDT) and Fail-Safe Clock Monitor (FSCM).

The LFINTOSC is enabled by selecting 31 kHz (**IRCF<2:0>** bits of the OSCCON register = 000) as the system clock source (SCS bit of the OSCCON register = 1), or when any of the following are enabled:

- Two-Speed Start-up IESO bit of the Configuration Word Register 1 = 1 and **IRCF<2:0>** bits of the OSCCON register = 000
- Power-up Timer (PWRT)
- Watchdog Timer (WDT)
- Fail-Safe Clock Monitor (FSCM)

The LF Internal Oscillator (LTS) bit of the OSCCON register indicates whether the LFINTOSC is stable or not.

4.5.4 FREQUENCY SELECT BITS (IRCF)

The output of the 8 MHz HFINTOSC and 31 kHz LFINTOSC connects to a postscaler and multiplexer (see Figure 4-1). The Internal Oscillator Frequency Select bits **IRCF<2:0>** of the OSCCON register select the frequency output of the internal oscillators. One of eight frequencies can be selected via software:

- 8 MHz
- 4 MHz (Default after Reset)
- 2 MHz
- 1 MHz
- 500 kHz
- 250 kHz
- 125 kHz
- 31 kHz (LFINTOSC)

Note: Following any Reset, the **IRCF<2:0>** bits of the OSCCON register are set to '110' and the frequency selection is set to 4 MHz. The user can modify the IRCF bits to select a different frequency.

4.5.5 HFINTOSC AND LFINTOSC CLOCK SWITCH TIMING

When switching between the LFINTOSC and the HFINTOSC, the new oscillator may already be shut down to save power (see Figure 4-6). If this is the case, there is a delay after the **IRCF<2:0>** bits of the OSCCON register are modified before the frequency selection takes place. The LTS and HTS bits of the OSCCON register will reflect the current active status of the LFINTOSC and HFINTOSC oscillators. The timing of a frequency selection is as follows:

1. **IRCF<2:0>** bits of the OSCCON register are modified.
2. If the new clock is shut down, a clock start-up delay is started.
3. Clock switch circuitry waits for a falling edge of the current clock.
4. CLKOUT is held low and the clock switch circuitry waits for a rising edge in the new clock.
5. CLKOUT is now connected with the new clock. LTS and HTS bits of the OSCCON register are updated as required.
6. Clock switch is complete.

See Figure 4-1 for more details.

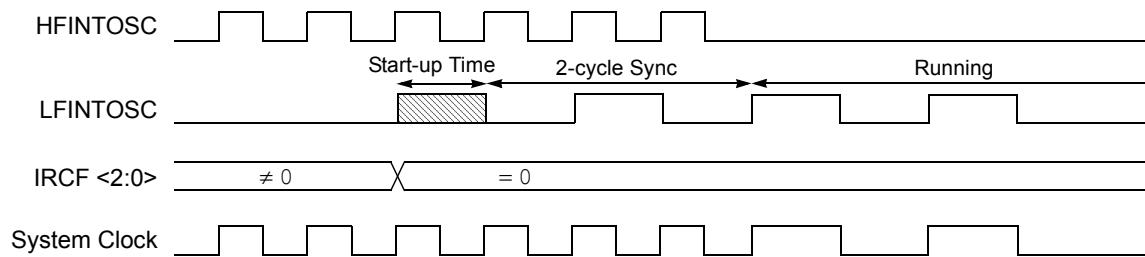
If the internal oscillator speed selected is between 8 MHz and 125 kHz, there is no start-up delay before the new frequency is selected. This is because the old and new frequencies are derived from the HFINTOSC via the postscaler and multiplexer.

Start-up delay specifications are located in the oscillator tables of **Section 17.0 “Electrical Specifications”**.

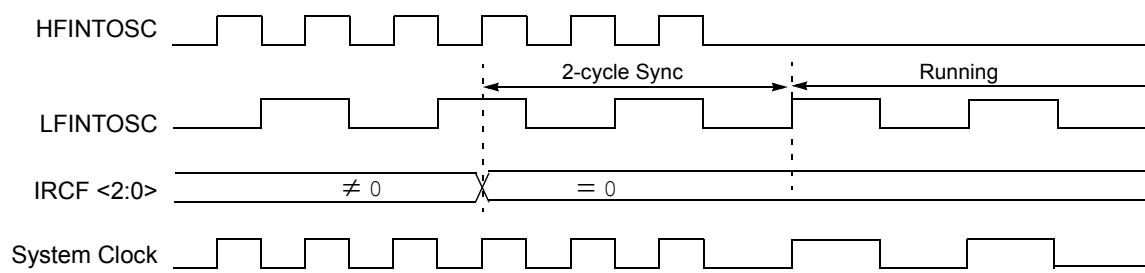
PIC16F882/883/884/886/887

FIGURE 4-6: INTERNAL OSCILLATOR SWITCH TIMING

HFINTOSC → LFINTOSC (FSCM and WDT disabled)

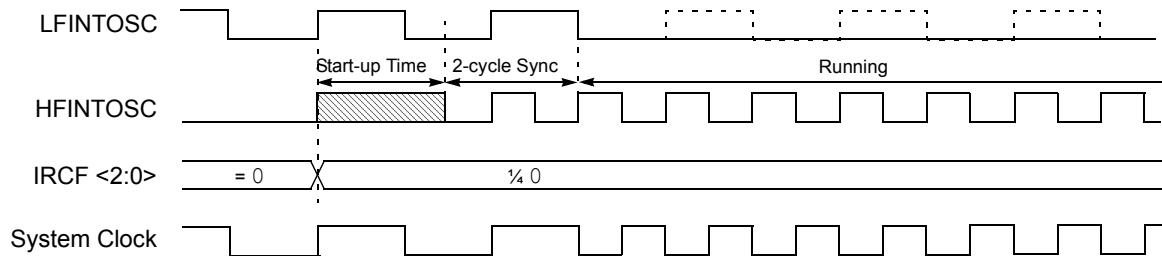


HFINTOSC → LFINTOSC (Either FSCM or WDT enabled)



LFINTOSC → HFINTOSC

LFINTOSC turns off unless WDT or FSCM is enabled



4.6 Clock Switching

The system clock source can be switched between external and internal clock sources via software using the System Clock Select (SCS) bit of the OSCCON register.

4.6.1 SYSTEM CLOCK SELECT (SCS) BIT

The System Clock Select (SCS) bit of the OSCCON register selects the system clock source that is used for the CPU and peripherals.

- When the SCS bit of the OSCCON register = 0, the system clock source is determined by configuration of the FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1).
- When the SCS bit of the OSCCON register = 1, the system clock source is chosen by the internal oscillator frequency selected by the IRCF<2:0> bits of the OSCCON register. After a Reset, the SCS bit of the OSCCON register is always cleared.

Note: Any automatic clock switch, which may occur from Two-Speed Start-up or Fail-Safe Clock Monitor, does not update the SCS bit of the OSCCON register. The user can monitor the OSTS bit of the OSCCON register to determine the current system clock source.

4.6.2 OSCILLATOR START-UP TIME-OUT STATUS (OSTS) BIT

The Oscillator Start-up Time-out Status (OSTS) bit of the OSCCON register indicates whether the system clock is running from the external clock source, as defined by the FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1), or from the internal clock source. In particular, OSTS indicates that the Oscillator Start-up Timer (OST) has timed out for LP, XT or HS modes.

4.7 Two-Speed Clock Start-up Mode

Two-Speed Start-up mode provides additional power savings by minimizing the latency between external oscillator start-up and code execution. In applications that make heavy use of the Sleep mode, Two-Speed Start-up will remove the external oscillator start-up time from the time spent awake and can reduce the overall power consumption of the device.

This mode allows the application to wake-up from Sleep, perform a few instructions using the INTOSC as the clock source and go back to Sleep without waiting for the primary oscillator to become stable.

Note: Executing a SLEEP instruction will abort the oscillator start-up time and will cause the OSTS bit of the OSCCON register to remain clear.

When the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) is enabled (see **Section 4.4.1 “Oscillator Start-up Timer (OST)”**). The OST will suspend program execution until 1024 oscillations are counted. Two-Speed Start-up mode minimizes the delay in code execution by operating from the internal oscillator as the OST is counting. When the OST count reaches 1024 and the OSTS bit of the OSCCON register is set, program execution switches to the external oscillator.

4.7.1 TWO-SPEED START-UP MODE CONFIGURATION

Two-Speed Start-up mode is configured by the following settings:

- IESO (of the Configuration Word Register 1) = 1; Internal/External Switchover bit (Two-Speed Start-up mode enabled).
- SCS (of the OSCCON register) = 0.
- FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1) configured for LP, XT or HS mode.

Two-Speed Start-up mode is entered after:

- Power-on Reset (POR) and, if enabled, after Power-up Timer (PWRT) has expired, or
- Wake-up from Sleep.

If the external clock oscillator is configured to be anything other than LP, XT or HS mode, then Two-speed Start-up is disabled. This is because the external clock oscillator does not require any stabilization time after POR or an exit from Sleep.

4.7.2 TWO-SPEED START-UP SEQUENCE

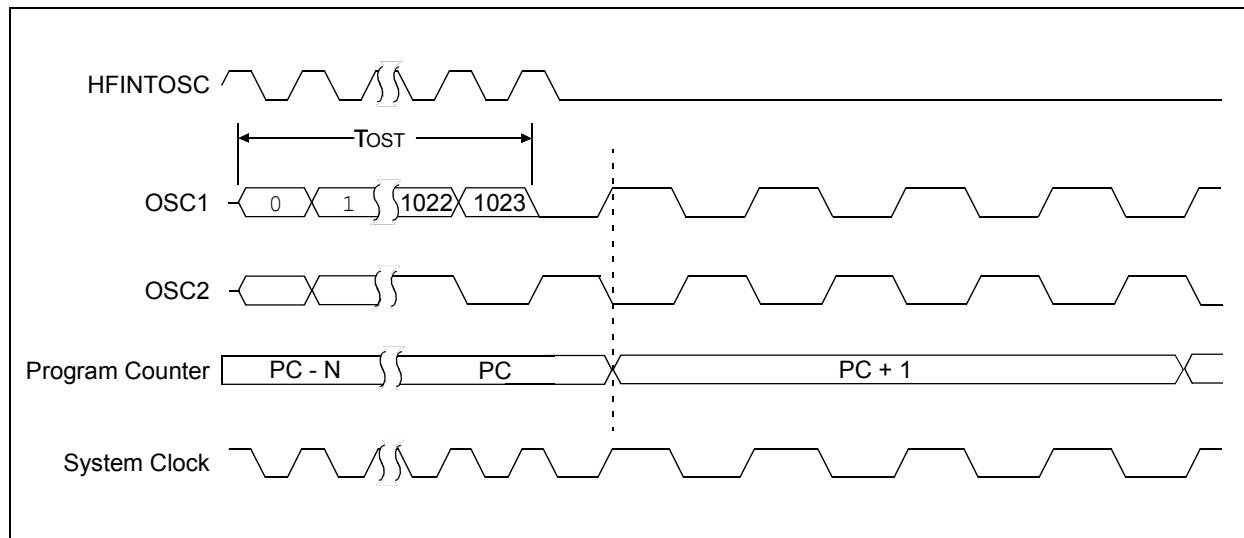
1. Wake-up from Power-on Reset or Sleep.
2. Instructions begin execution by the internal oscillator at the frequency set in the IRCF<2:0> bits of the OSCCON register.
3. OST enabled to count 1024 clock cycles.
4. OST timed out, wait for falling edge of the internal oscillator.
5. OSTS is set.
6. System clock held low until the next falling edge of new clock (LP, XT or HS mode).
7. System clock is switched to external clock source.

PIC16F882/883/884/886/887

4.7.3 CHECKING TWO-SPEED CLOCK STATUS

Checking the state of the OSTS bit of the OSCCON register will confirm if the microcontroller is running from the external clock source, as defined by the FOSC<2:0> bits in the Configuration Word Register 1 (CONFIG1), or the internal oscillator.

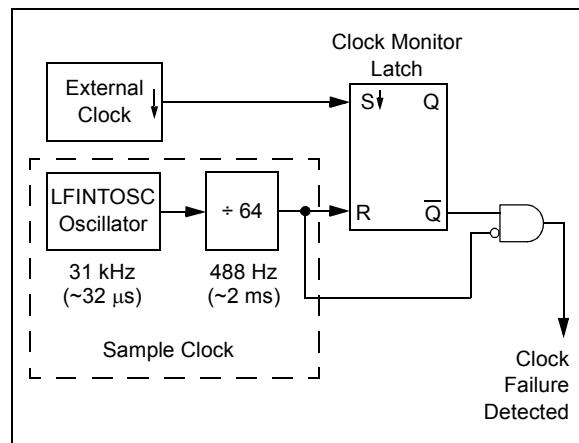
FIGURE 4-7: TWO-SPEED START-UP



4.8 Fail-Safe Clock Monitor

The Fail-Safe Clock Monitor (FSCM) allows the device to continue operating should the external oscillator fail. The FSCM can detect oscillator failure any time after the Oscillator Start-up Timer (OST) has expired. The FSCM is enabled by setting the FCMEN bit in the Configuration Word Register 1 (CONFIG1). The FSCM is applicable to all external Oscillator modes (LP, XT, HS, EC, RC and RCIO).

FIGURE 4-8: FSCM BLOCK DIAGRAM



4.8.1 FAIL-SAFE DETECTION

The FSCM module detects a failed oscillator by comparing the external oscillator to the FSCM sample clock. The sample clock is generated by dividing the LFINTOSC by 64. See Figure 4-8. Inside the fail detector block is a latch. The external clock sets the latch on each falling edge of the external clock. The sample clock clears the latch on each rising edge of the sample clock. A failure is detected when an entire half-cycle of the sample clock elapses before the primary clock goes low.

4.8.2 FAIL-SAFE OPERATION

When the external clock fails, the FSCM switches the device clock to an internal clock source and sets the bit flag OSFIF of the PIR2 register. Setting this flag will generate an interrupt if the OSFIE bit of the PIE2 register is also set. The device firmware can then take steps to mitigate the problems that may arise from a failed clock. The system clock will continue to be sourced from the internal clock source until the device firmware successfully restarts the external oscillator and switches back to external operation.

The internal clock source chosen by the FSCM is determined by the IRCF<2:0> bits of the OSCCON register. This allows the internal oscillator to be configured before a failure occurs.

4.8.3 FAIL-SAFE CONDITION CLEARING

The Fail-Safe condition is cleared after a Reset, executing a SLEEP instruction or toggling the SCS bit of the OSCCON register. When the SCS bit is toggled, the OST is restarted. While the OST is running, the device continues to operate from the INTOSC selected in OSCCON. When the OST times out, the Fail-Safe condition is cleared and the device will be operating from the external clock source. The Fail-Safe condition must be cleared before the OSFIF flag can be cleared.

4.8.4 RESET OR WAKE-UP FROM SLEEP

The FSCM is designed to detect an oscillator failure after the Oscillator Start-up Timer (OST) has expired. The OST is used after waking up from Sleep and after any type of Reset. The OST is not used with the EC or RC Clock modes so that the FSCM will be active as soon as the Reset or wake-up has completed. When the FSCM is enabled, the Two-Speed Start-up is also enabled. Therefore, the device will always be executing code while the OST is operating.

Note: Due to the wide range of oscillator start-up times, the Fail-Safe circuit is not active during oscillator start-up (i.e., after exiting Reset or Sleep). After an appropriate amount of time, the user should check the OSTS bit of the OSCCON register to verify the oscillator start-up and that the system clock switchover has successfully completed.

PIC16F882/883/884/886/887

FIGURE 4-9: FSCM TIMING DIAGRAM

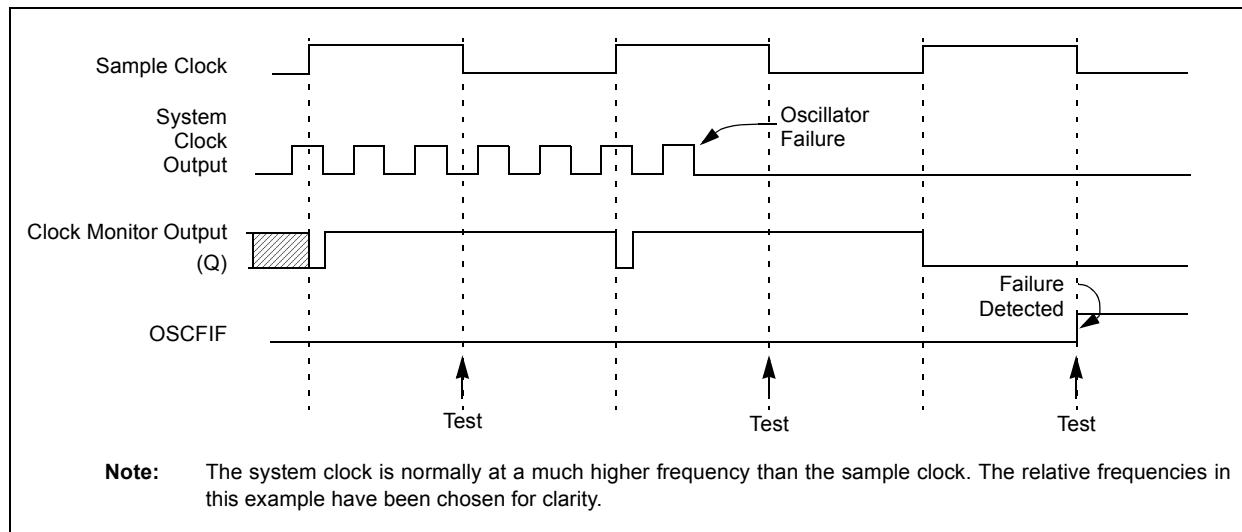


TABLE 4-2: SUMMARY OF REGISTERS ASSOCIATED WITH CLOCK SOURCES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets ⁽¹⁾
CONFIG1 ⁽²⁾	$\overline{\text{CPD}}$	$\overline{\text{CP}}$	MCLRE	$\overline{\text{PWRTE}}$	WDTE	FOSC2	FOSC1	FOSC0	—	—
OSCCON	—	IRCF2	IRCF1	IRCF0	OSTS	HTS	LTS	SCS	-110 x000	-110 x000
OSCTUNE	—	—	—	TUN4	TUN3	TUN2	TUN1	TUN0	---0 0000	---u uuuu
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	0000 00-0
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	0000 00-0

Legend: x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by oscillators.

Note 1: Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

2: See Configuration Word Register 1 (Register 14-1) for operation of all register bits.

5.0 TIMER0 MODULE

The Timer0 module is an 8-bit timer/counter with the following features:

- 8-bit timer/counter register (TMR0)
- 8-bit prescaler (shared with Watchdog Timer)
- Programmable internal or external clock source
- Programmable external clock edge selection
- Interrupt on overflow

Figure 5-1 is a block diagram of the Timer0 module.

5.1 Timer0 Operation

When used as a timer, the Timer0 module can be used as either an 8-bit timer or an 8-bit counter.

5.1.1 8-BIT TIMER MODE

When used as a timer, the Timer0 module will increment every instruction cycle (without prescaler). Timer mode is selected by clearing the T0CS bit of the OPTION register to '0'.

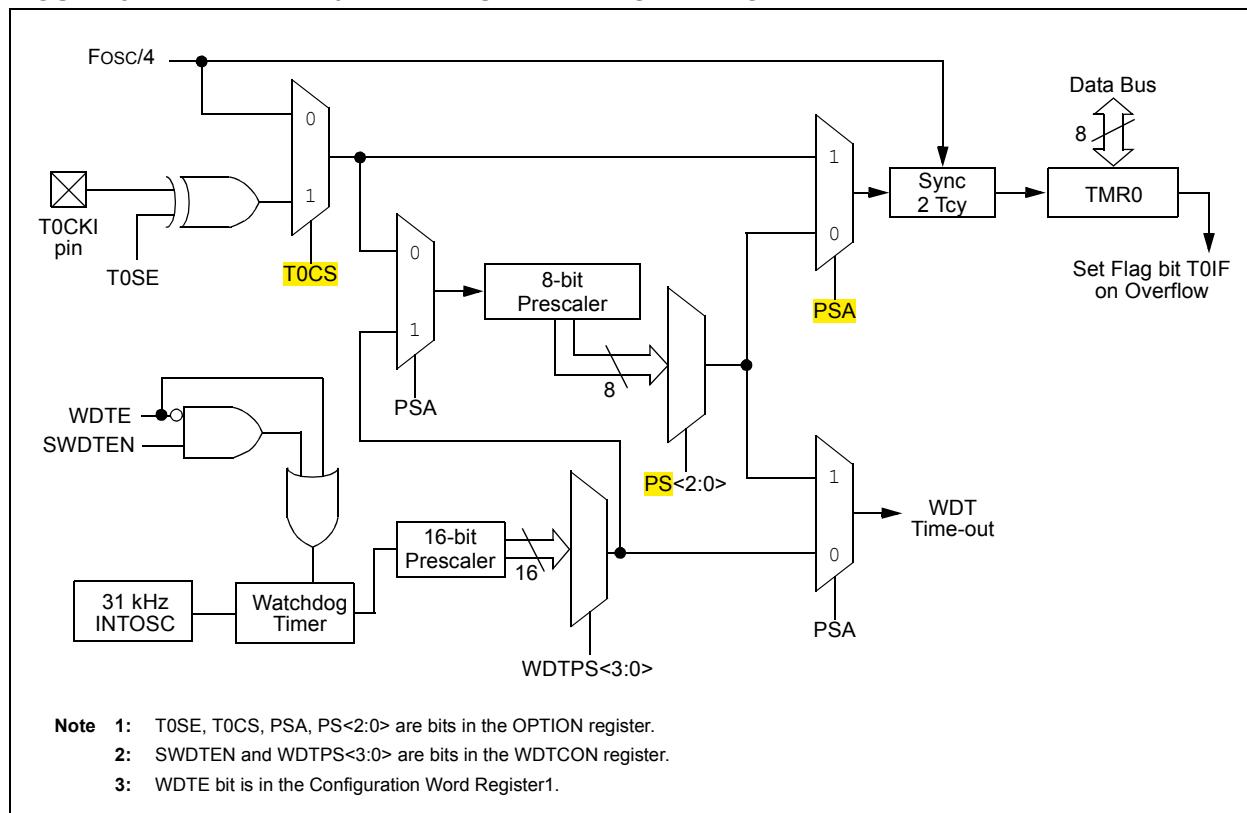
When TMR0 is written, the increment is inhibited for two instruction cycles immediately following the write.

Note: The value written to the TMR0 register can be adjusted, in order to account for the two instruction cycle delay when TMR0 is written.

5.1.2 8-BIT COUNTER MODE

When used as a counter, the Timer0 module will increment on every rising or falling edge of the T0CKI pin. The incrementing edge is determined by the T0SE bit of the OPTION register. Counter mode is selected by setting the T0CS bit of the OPTION register to '1'.

FIGURE 5-1: TIMER0/WDT PRESCALER BLOCK DIAGRAM



PIC16F882/883/884/886/887

5.1.3 SOFTWARE PROGRAMMABLE PRESCALER

A single software programmable prescaler is available for use with either Timer0 or the Watchdog Timer (WDT), but not both simultaneously. The prescaler assignment is controlled by the PSA bit of the OPTION register. To assign the prescaler to Timer0, the PSA bit must be cleared to a '0'.

There are 8 prescaler options for the Timer0 module ranging from 1:2 to 1:256. The prescale values are selectable via the PS<2:0> bits of the OPTION register. In order to have a 1:1 prescaler value for the Timer0 module, the prescaler must be assigned to the WDT module.

The prescaler is not readable or writable. When assigned to the Timer0 module, all instructions writing to the TMR0 register will clear the prescaler.

When the prescaler is assigned to WDT, a CLRWD_T instruction will clear the prescaler along with the WDT.

5.1.3.1 Switching Prescaler Between Timer0 and WDT Modules

As a result of having the prescaler assigned to either Timer0 or the WDT, it is possible to generate an unintended device Reset when switching prescaler values. When changing the prescaler assignment from Timer0 to the WDT module, the instruction sequence shown in Example 5-1, must be executed.

EXAMPLE 5-1: CHANGING PRESCALER (TIMER0 → WDT)

```
BANKSEL TMR0          ;  
CLRWDT           ;Clear WDT  
CLRF  TMR0          ;Clear TMR0 and  
                   ;prescaler  
BANKSEL OPTION_REG   ;  
BSF    OPTION_REG, PSA ;Select WDT  
CLRWDT           ;  
                   ;  
MOVLW  b'11111000'   ;Mask prescaler  
ANDWF  OPTION_REG,W  ;bits  
IORLW  b'00000101'   ;Set WDT prescaler  
MOVWF  OPTION_REG     ;to 1:32
```

When changing the prescaler assignment from the WDT to the Timer0 module, the following instruction sequence must be executed (see Example 5-2).

EXAMPLE 5-2: CHANGING PRESCALER (WDT → TIMER0)

```
CLRWDT           ;Clear WDT and  
                   ;prescaler  
BANKSEL OPTION_REG   ;  
MOVLW  b'11110000'   ;Mask TMRO select and  
ANDWF  OPTION_REG,W  ;prescaler bits  
IORLW  b'00000011'   ;Set prescale to 1:16  
MOVWF  OPTION_REG     ;
```

5.1.4 TIMER0 INTERRUPT

Timer0 will generate an interrupt when the TMRO register overflows from FFh to 00h. The T0IF interrupt flag bit of the INTCON register is set every time the TMRO register overflows, regardless of whether or not the Timer0 interrupt is enabled. The T0IE bit must be cleared in software. The Timer0 interrupt enable is the T0IE bit of the INTCON register.

Note: The Timer0 interrupt cannot wake the processor from Sleep since the timer is frozen during Sleep.

5.1.5 USING TIMER0 WITH AN EXTERNAL CLOCK

When Timer0 is in Counter mode, the synchronization of the T0CKI input and the Timer0 register is accomplished by sampling the prescaler output on the Q2 and Q4 cycles of the internal phase clocks. Therefore, the high and low periods of the external clock source must meet the timing requirements as shown in the **Section 17.0 “Electrical Specifications”**.

PIC16F882/883/884/886/887

REGISTER 5-1: OPTION_REG: OPTION REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	RBPU: PORTB Pull-up Enable bit 1 = PORTB pull-ups are disabled 0 = PORTB pull-ups are enabled by individual PORT latch values
bit 6	INTEDG: Interrupt Edge Select bit 1 = Interrupt on rising edge of INT pin 0 = Interrupt on falling edge of INT pin
bit 5	T0CS: TMR0 Clock Source Select bit 1 = Transition on T0CKI pin 0 = Internal instruction cycle clock (Fosc/4)
bit 4	T0SE: TMR0 Source Edge Select bit 1 = Increment on high-to-low transition on T0CKI pin 0 = Increment on low-to-high transition on T0CKI pin
bit 3	PSA: Prescaler Assignment bit 1 = Prescaler is assigned to the WDT 0 = Prescaler is assigned to the Timer0 module
bit 2-0	PS<2:0>: Prescaler Rate Select bits

BIT VALUE	TMR0 RATE	WDT RATE
000	1 : 2	1 : 1
001	1 : 4	1 : 2
010	1 : 8	1 : 4
011	1 : 16	1 : 8
100	1 : 32	1 : 16
101	1 : 64	1 : 32
110	1 : 128	1 : 64
111	1 : 256	1 : 128

Note 1: A dedicated 16-bit WDT postscaler is available. See **Section 14.5 “Watchdog Timer (WDT)”** for more information.

TABLE 5-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER0

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
TMR0	Timer0 Module Register							xxxx xxxx	uuuu uuuu	
INTCON	GIE	PEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	0000 000x	0000 000x
OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111

Legend: - = Unimplemented locations, read as '0', u = unchanged, x = unknown. Shaded cells are not used by the Timer0 module.

PIC16F882/883/884/886/887

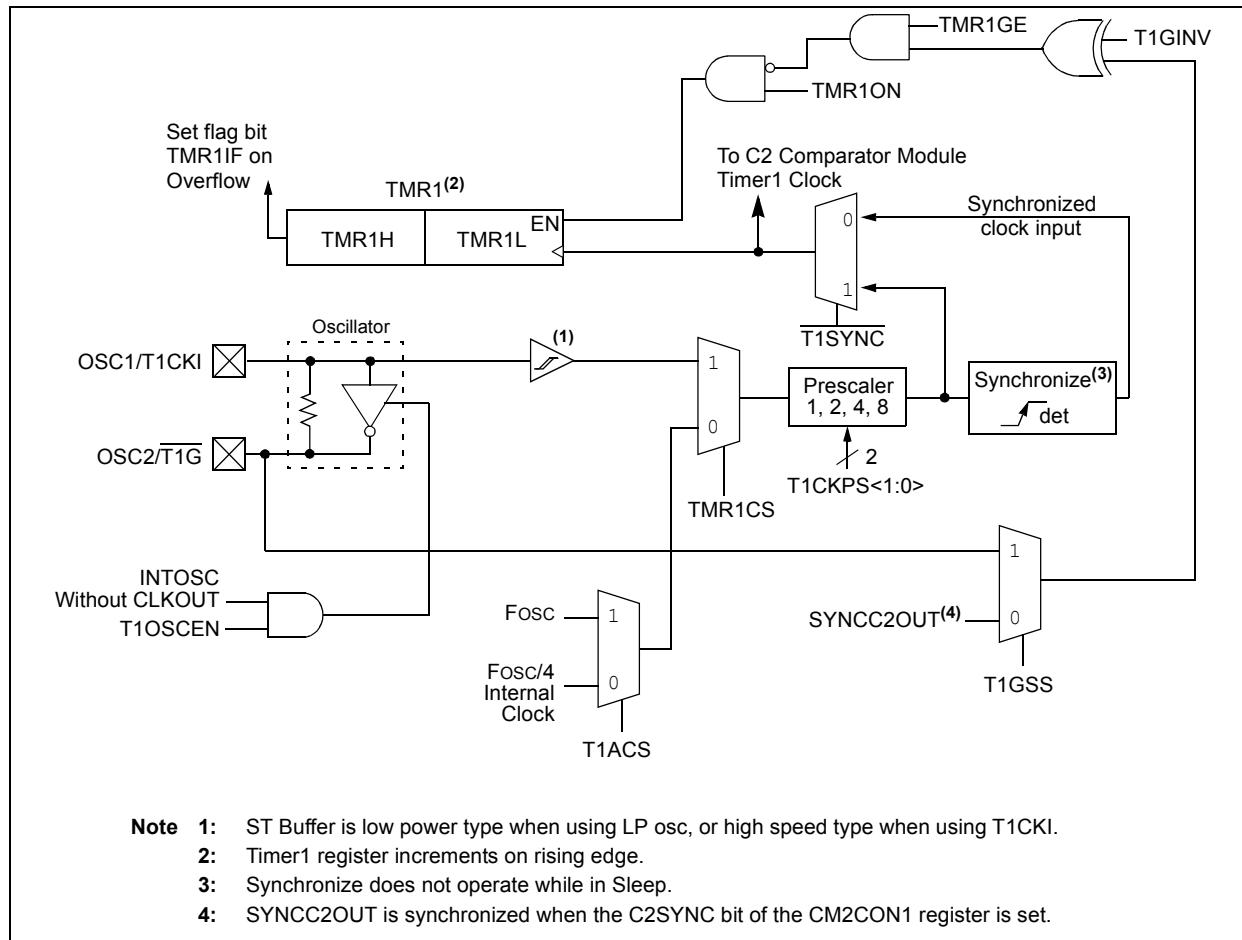
6.0 TIMER1 MODULE WITH GATE CONTROL

The Timer1 module is a 16-bit timer/counter with the following features:

- 16-bit timer/counter register pair (TMR1H:TMR1L)
- Programmable internal or external clock source
- 3-bit prescaler
- Optional LP oscillator
- Synchronous or asynchronous operation
- Timer1 gate (count enable) via comparator or T1G pin
- Interrupt on overflow
- Wake-up on overflow (external clock, Asynchronous mode only)
- Time base for the Capture/Compare function
- Special Event Trigger (with ECCP)
- Comparator output synchronization to Timer1 clock

Figure 6-1 is a block diagram of the Timer1 module.

FIGURE 6-1: TIMER1 BLOCK DIAGRAM



6.2.1 INTERNAL CLOCK SOURCE

When the internal clock source is selected the TMR1H:TMR1L register pair will increment on multiples of Fosc as determined by the Timer1 prescaler.

6.2.2 EXTERNAL CLOCK SOURCE

When the external clock source is selected, the Timer1 module may work as a timer or a counter.

When counting, Timer1 is incremented on the rising edge of the external clock input T1CKI. In addition, the Counter mode clock can be synchronized to the microcontroller system clock or run asynchronously.

If an external clock oscillator is needed (and the microcontroller is using the INTOSC without CLKOUT), Timer1 can use the LP oscillator as a clock source.

In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge after one or more of the following conditions (see Figure 6-2):

- Timer1 is enabled after POR or BOR Reset
- A write to TMR1H or TMR1L
- T1CKI is high when Timer1 is disabled and when Timer1 is reenabled T1CKI is low.

6.3 Timer1 Prescaler

Timer1 has four prescaler options allowing 1, 2, 4 or 8 divisions of the clock input. The T1CKPS bits of the T1CON register control the prescale counter. The prescale counter is not directly readable or writable; however, the prescaler counter is cleared upon a write to TMR1H or TMR1L.

6.4 Timer1 Oscillator

A low-power 32.768 kHz oscillator is built-in between pins T1OSI (input) and T1OSO (amplifier output). The oscillator is enabled by setting the T1OSCEN control bit of the T1CON register. The oscillator will continue to run during Sleep.

The Timer1 oscillator is identical to the LP oscillator. The user must provide a software time delay to ensure proper oscillator start-up.

TRISC0 and TRISC1 bits are set when the Timer1 oscillator is enabled. RC0 and RC1 bits read as '0' and TRISC0 and TRISC1 bits read as '1'.

Note: The oscillator requires a start-up and stabilization time before use. Thus, T1OSCEN should be set and a suitable delay observed prior to enabling Timer1.

6.5 Timer1 Operation in Asynchronous Counter Mode

If control bit T1SYNC of the T1CON register is set, the external clock input is not synchronized. The timer continues to increment asynchronous to the internal phase clocks. The timer will continue to run during Sleep and can generate an interrupt on overflow, which will wake-up the processor. However, special precautions in software are needed to read/write the timer (see **Section 6.5.1 “Reading and Writing Timer1 in Asynchronous Counter Mode”**).

Note: When switching from synchronous to asynchronous operation, it is possible to skip an increment. When switching from asynchronous to synchronous operation, it is possible to produce a single spurious increment.

6.5.1 READING AND WRITING TIMER1 IN ASYNCHRONOUS COUNTER MODE

Reading TMR1H or TMR1L while the timer is running from an external asynchronous clock will ensure a valid read (taken care of in hardware). However, the user should keep in mind that reading the 16-bit timer in two 8-bit values itself, poses certain problems, since the timer may overflow between the reads.

For writes, it is recommended that the user simply stop the timer and write the desired values. A write contention may occur by writing to the timer registers, while the register is incrementing. This may produce an unpredictable value in the TMR1H:TTMR1L register pair.

6.6 Timer1 Gate

Timer1 gate source is software configurable to be the T1G pin or the output of Comparator C2. This allows the device to directly time external events using T1G or analog events using Comparator C2. See the CM2CON1 register (Register 8-3) for selecting the Timer1 gate source. This feature can simplify the software for a Delta-Sigma A/D converter and many other applications. For more information on Delta-Sigma A/D converters, see the Microchip web site (www.microchip.com).

Note: TMR1GE bit of the T1CON register must be set to use the Timer1 gate.

Timer1 gate can be inverted using the T1GINV bit of the T1CON register, whether it originates from the T1G pin or Comparator C2 output. This configures Timer1 to measure either the active-high or active-low time between events.

PIC16F882/883/884/886/887

6.7 Timer1 Interrupt

The Timer1 register pair (TMR1H:TMR1L) increments to FFFFh and rolls over to 0000h. When Timer1 rolls over, the Timer1 interrupt flag bit of the PIR1 register is set. To enable the interrupt on rollover, you must set these bits:

- Timer1 interrupt enable bit of the PIE1 register
- PEIE bit of the INTCON register
- GIE bit of the INTCON register

The interrupt is cleared by clearing the TMR1IF bit in the Interrupt Service Routine.

Note: The TMR1H:TTMR1L register pair and the TMR1IF bit should be cleared before enabling interrupts.

6.8 Timer1 Operation During Sleep

Timer1 can only operate during Sleep when setup in Asynchronous Counter mode. In this mode, an external crystal or clock source can be used to increment the counter. To set up the timer to wake the device:

- TMR1ON bit of the T1CON register must be set
- TMR1IE bit of the PIE1 register must be set
- PEIE bit of the INTCON register must be set

The device will wake-up on an overflow and execute the next instruction. If the GIE bit of the INTCON register is set, the device will call the Interrupt Service Routine (0004h).

6.9 ECCP Capture/Compare Time Base

The ECCP module uses the TMR1H:TMR1L register pair as the time base when operating in Capture or Compare mode.

In Capture mode, the value in the TMR1H:TMR1L register pair is copied into the CCPRxH:CCPRxL register pair on a configured event.

In Compare mode, an event is triggered when the value CCPRxH:CCPRxL register pair matches the value in the TMR1H:TMR1L register pair. This event can be a Special Event Trigger.

See **Section 11.0 “Capture/Compare/PWM Modules (CCP1 and CCP2)”** for more information.

6.10 ECCP Special Event Trigger

If an ECCP is configured to trigger a special event, the trigger will clear the TMR1H:TMR1L register pair. This special event does not cause a Timer1 interrupt. The ECCP module may still be configured to generate a ECCP interrupt.

In this mode of operation, the CCPRxH:CCPRxL register pair effectively becomes the period register for Timer1.

Timer1 should be synchronized to the Fosc to utilize the Special Event Trigger. Asynchronous operation of Timer1 can cause a Special Event Trigger to be missed.

In the event that a write to TMR1H or TMR1L coincides with a Special Event Trigger from the ECCP, the write will take precedence.

For more information, see **Section 11.0 “Capture/Compare/PWM Modules (CCP1 and CCP2)”**.

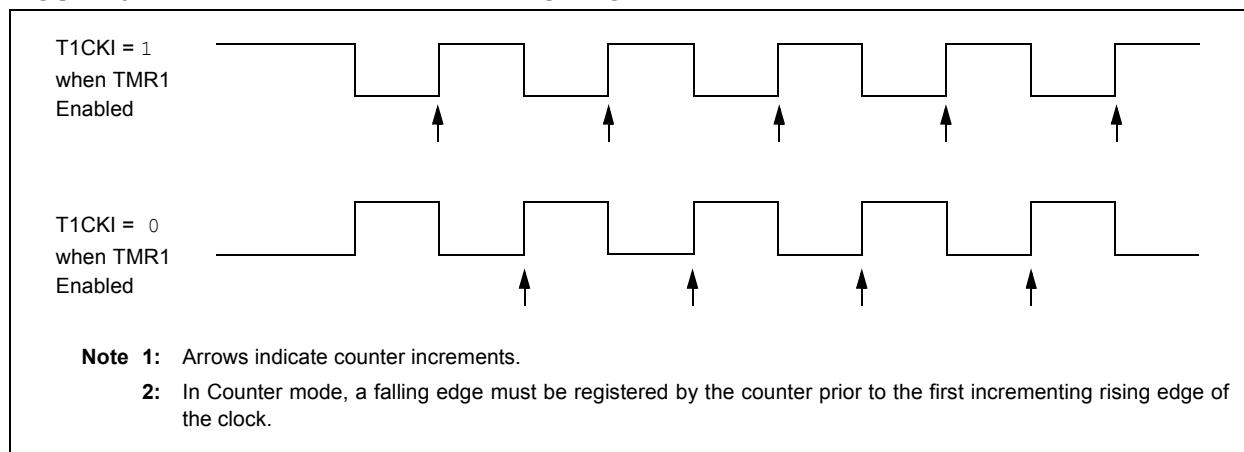
6.11 Comparator Synchronization

The same clock used to increment Timer1 can also be used to synchronize the comparator output. This feature is enabled in the Comparator module.

When using the comparator for Timer1 gate, the comparator output should be synchronized to Timer1. This ensures Timer1 does not miss an increment if the comparator changes.

For more information, see **Section 8.0 “Comparator Module”**.

FIGURE 6-2: TIMER1 INCREMENTING EDGE



6.12 Timer1 Control Register

The Timer1 Control register (T1CON), shown in Register 6-1, is used to control Timer1 and select the various features of the Timer1 module.

REGISTER 6-1: T1CON: TIMER1 CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
T1GINV ⁽¹⁾	TMR1GE ⁽²⁾	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7 **T1GINV:** Timer1 Gate Invert bit⁽¹⁾
 1 = Timer1 gate is active-high (Timer1 counts when gate is high)
 0 = Timer1 gate is active-low (Timer1 counts when gate is low)
- bit 6 **TMR1GE:** Timer1 Gate Enable bit⁽²⁾
If TMR1ON = 0:
 This bit is ignored
If TMR1ON = 1:
 1 = Timer1 counting is controlled by the Timer1 Gate function
 0 = Timer1 is always counting
- bit 5-4 **T1CKPS<1:0>:** Timer1 Input Clock Prescale Select bits
 11 = 1:8 Prescale Value
 10 = 1:4 Prescale Value
 01 = 1:2 Prescale Value
 00 = 1:1 Prescale Value
- bit 3 **T1OSCEN:** LP Oscillator Enable Control bit
 1 = LP oscillator is enabled for Timer1 clock
 0 = LP oscillator is off
- bit 2 **T1SYNC:** Timer1 External Clock Input Synchronization Control bit
TMR1CS = 1:
 1 = Do not synchronize external clock input
 0 = Synchronize external clock input
TMR1CS = 0:
 This bit is ignored. Timer1 uses the internal clock
- bit 1 **TMR1CS:** Timer1 Clock Source Select bit
 1 = External clock from T1CKI pin (on the rising edge)
 0 = Internal clock (Fosc/4)
- bit 0 **TMR1ON:** Timer1 On bit
 1 = Enables Timer1
 0 = Stops Timer1

Note 1: T1GINV bit inverts the Timer1 gate logic, regardless of source.

2: TMR1GE bit must be set to use either T1G pin or C2OUT, as selected by the T1GSS bit of the CM2CON1 register, as a Timer1 gate source.

PIC16F882/883/884/886/887

TABLE 6-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER1

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	0000 --10
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	uuuu uuuu
TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	uuuu uuuu
T1CON	T1GINV	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON	0000 0000	uuuu uuuu

Legend: x = unknown, u = unchanged, — = unimplemented, read as '0'. Shaded cells are not used by the Timer1 module.

7.0 TIMER2 MODULE

The Timer2 module is an eight-bit timer with the following features:

- 8-bit timer register (TMR2)
- 8-bit period register (PR2)
- Interrupt on TMR2 match with PR2
- Software programmable prescaler (1:1, 1:4, 1:16)
- Software programmable postscale (1:1 to 1:16)

See Figure 7-1 for a block diagram of Timer2.

7.1 Timer2 Operation

The clock input to the Timer2 module is the system instruction clock ($F_{osc}/4$). The clock is fed into the Timer2 prescaler, which has prescale options of 1:1, 1:4 or 1:16. The output of the prescaler is then used to increment the TMR2 register.

The values of TMR2 and PR2 are constantly compared to determine when they match. TMR2 will increment from 00h until it matches the value in PR2. When a match occurs, two things happen:

- TMR2 is reset to 00h on the next increment cycle
- The Timer2 postscaler is incremented

The match output of the Timer2/PR2 comparator is then fed into the Timer2 postscaler. The postscaler has postscale options of 1:1 to 1:16 inclusive. The output of the Timer2 postscaler is used to set the TMR2IF interrupt flag bit in the PIR1 register.

The TMR2 and PR2 registers are both fully readable and writable. On any Reset, the TMR2 register is set to 00h and the PR2 register is set to FFh.

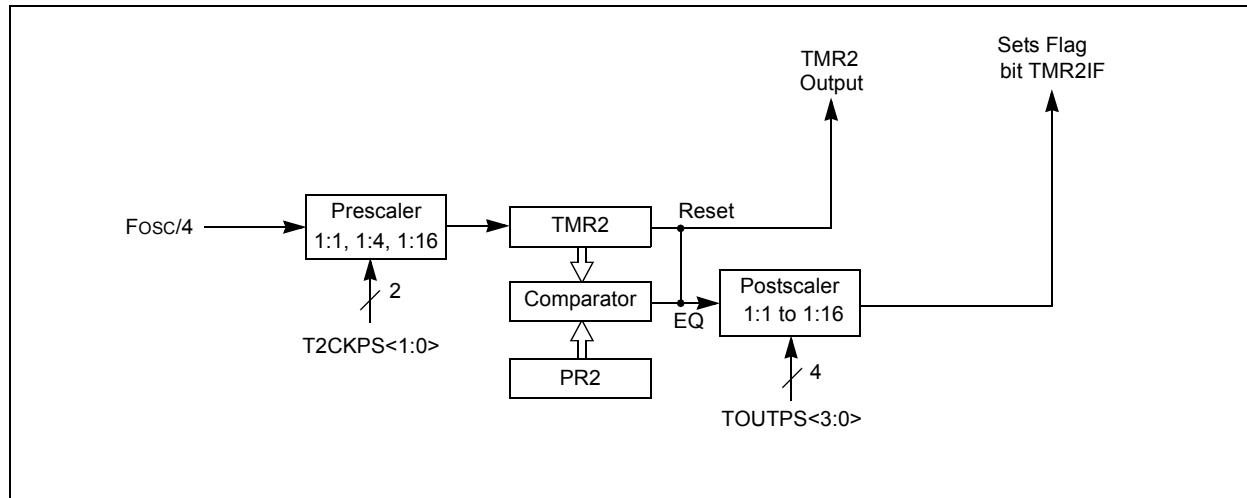
Timer2 is turned on by setting the TMR2ON bit in the T2CON register to a '1'. Timer2 is turned off by clearing the TMR2ON bit to a '0'.

The Timer2 prescaler is controlled by the T2CKPS bits in the T2CON register. The Timer2 postscaler is controlled by the TOUTPS bits in the T2CON register. The prescaler and postscaler counters are cleared when:

- A write to TMR2 occurs.
- A write to T2CON occurs.
- Any device Reset occurs (Power-on Reset, MCLR Reset, Watchdog Timer Reset, or Brown-out Reset).

Note: TMR2 is not cleared when T2CON is written.

FIGURE 7-1: TIMER2 BLOCK DIAGRAM



PIC16F882/883/884/886/887

REGISTER 7-1: T2CON: TIMER2 CONTROL REGISTER

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Read as '0'bit 6-3 **TOUTPS<3:0>:** Timer2 Output Postscaler Select bits

0000 = 1:1 Postscaler

0001 = 1:2 Postscaler

0010 = 1:3 Postscaler

0011 = 1:4 Postscaler

0100 = 1:5 Postscaler

0101 = 1:6 Postscaler

0110 = 1:7 Postscaler

0111 = 1:8 Postscaler

1000 = 1:9 Postscaler

1001 = 1:10 Postscaler

1010 = 1:11 Postscaler

1011 = 1:12 Postscaler

1100 = 1:13 Postscaler

1101 = 1:14 Postscaler

1110 = 1:15 Postscaler

1111 = 1:16 Postscaler

bit 2 **TMR2ON:** Timer2 On bit

1 = Timer2 is on

0 = Timer2 is off

bit 1-0 **T2CKPS<1:0>:** Timer2 Clock Prescale Select bits

00 = Prescaler is 1

01 = Prescaler is 4

1x = Prescaler is 16

TABLE 7-1: SUMMARY OF ASSOCIATED TIMER2 REGISTERS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
PR2	Timer2 Module Period Register							1111 1111	1111 1111	
TMR2	Holding Register for the 8-bit TMR2 Register							0000 0000	0000 0000	
T2CON	—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	-000 0000

Legend: x = unknown, u = unchanged, — = unimplemented read as '0'. Shaded cells are not used for Timer2 module.

8.0 COMPARATOR MODULE

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. The comparators are very useful mixed signal building blocks because they provide analog functionality independent of the program execution. The analog comparator module includes the following features:

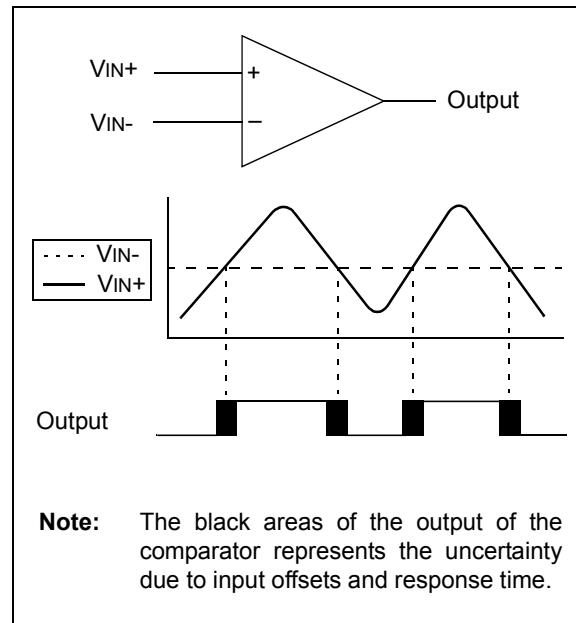
- Independent comparator control
- Programmable input selection
- Comparator output is available internally/externally
- Programmable output polarity
- Interrupt-on-change
- Wake-up from Sleep
- PWM shutdown
- Timer1 gate (count enable)
- Output synchronization to Timer1 clock input
- SR Latch
- Programmable and fixed voltage reference

Note: Only Comparator C2 can be linked to Timer1.

8.1 Comparator Overview

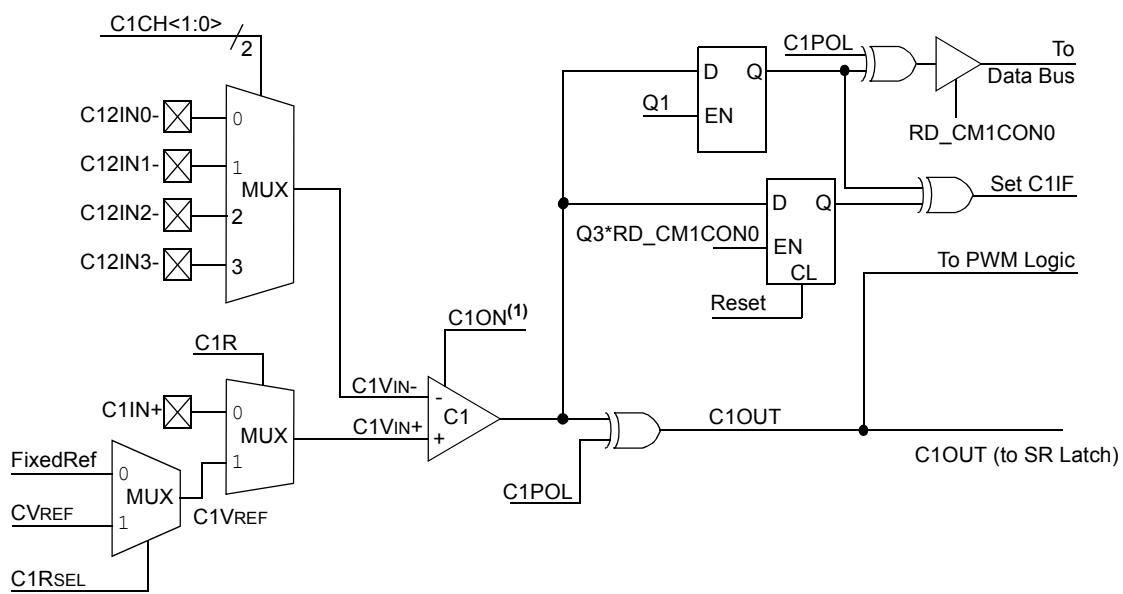
A single comparator is shown in Figure 8-1 along with the relationship between the analog input levels and the digital output. When the analog voltage at V_{IN+} is less than the analog voltage at V_{IN-} , the output of the comparator is a digital low level. When the analog voltage at V_{IN+} is greater than the analog voltage at V_{IN-} , the output of the comparator is a digital high level.

FIGURE 8-1: SINGLE COMPARATOR



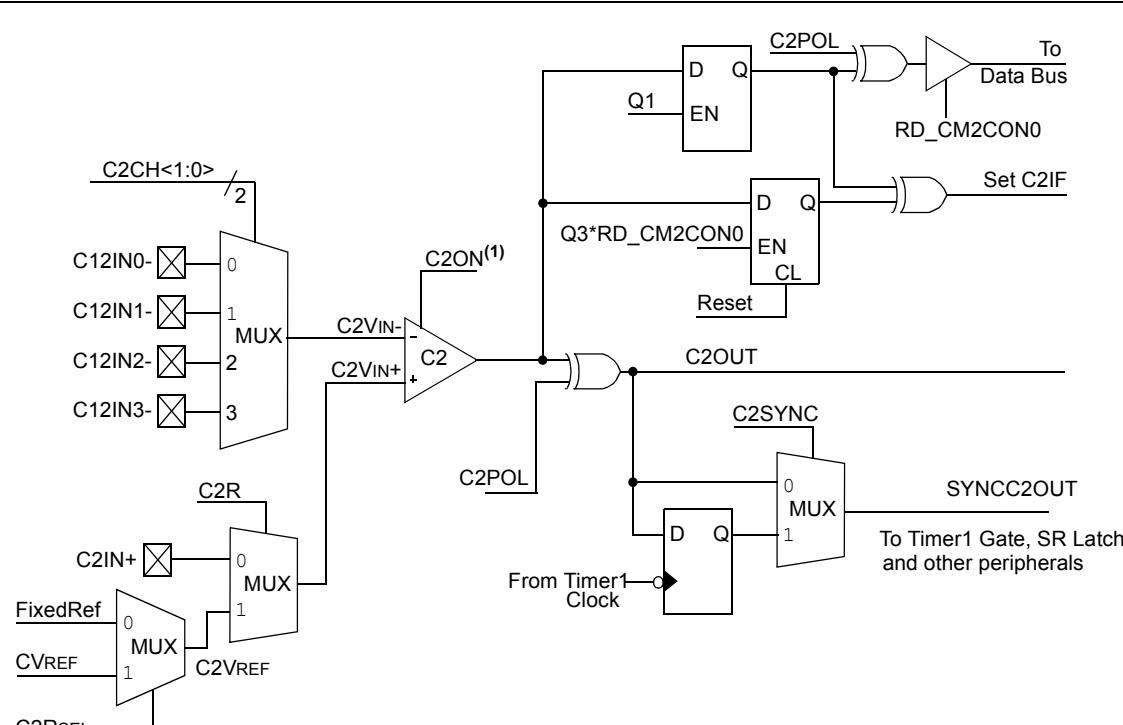
PIC16F882/883/884/886/887

FIGURE 8-2: COMPARATOR C1 SIMPLIFIED BLOCK DIAGRAM



- Note**
- 1: When C1ON = 0, the C1 comparator will produce a '0' output to the XOR Gate.
 - 2: Q1 and Q3 are phases of the four-phase system clock (Fosc).
 - 3: Q1 is held high during Sleep mode.

FIGURE 8-3: COMPARATOR C2 SIMPLIFIED BLOCK DIAGRAM



- Note**
- 1: When C2ON = 0, the C2 comparator will produce a '0' output to the XOR Gate.
 - 2: Q1 and Q3 are phases of the four-phase system clock (Fosc).
 - 3: Q1 is held high during Sleep mode.

8.2 Comparator Control

Each comparator has a separate control and Configuration register: CM1CON0 for Comparator C1 and CM2CON0 for Comparator C2. In addition, Comparator C2 has a second control register, CM2CON1, for controlling the interaction with Timer1 and simultaneous reading of both comparator outputs.

The CM1CON0 and CM2CON0 registers (see Registers 8-1 and 8-2, respectively) contain the control and Status bits for the following:

- Enable
- Input selection
- Reference selection
- Output selection
- Output polarity

8.2.1 COMPARATOR ENABLE

Setting the CxON bit of the CMxCON0 register enables the comparator for operation. Clearing the CxON bit disables the comparator resulting in minimum current consumption.

8.2.2 COMPARATOR INPUT SELECTION

The CxCH<1:0> bits of the CMxCON0 register direct one of four analog input pins to the comparator inverting input.

Note: To use **C_xIN+** and **C_xIN-** pins as analog inputs, the appropriate bits must be set in the ANSEL and ANSELH registers and the corresponding TRIS bits must also be set to disable the output drivers.

8.2.3 COMPARATOR REFERENCE SELECTION

Setting the CxR bit of the CMxCON0 register directs an internal voltage reference or an analog input pin to the non-inverting input of the comparator. See **Section 8.10 “Comparator Voltage Reference”** for more information on the internal voltage reference module.

8.2.4 COMPARATOR OUTPUT SELECTION

The output of the comparator can be monitored by reading either the CxOUT bit of the CMxCON0 register or the MCxOUT bit of the CM2CON1 register. In order to make the output available for an external connection, the following conditions must be true:

- CxOE bit of the CMxCON0 register must be set
- Corresponding TRIS bit must be cleared
- CxON bit of the CMxCON0 register must be set

Note 1: The CxOE bit overrides the PORT data latch. Setting the CxON has no impact on the port override.

2: The internal output of the comparator is latched with each instruction cycle. Unless otherwise specified, external outputs are not latched.

8.2.5 COMPARATOR OUTPUT POLARITY

Inverting the output of the comparator is functionally equivalent to swapping the comparator inputs. The polarity of the comparator output can be inverted by setting the CxPOL bit of the CMxCON0 register. Clearing the CxPOL bit results in a non-inverted output.

Table 8-1 shows the output state versus input conditions, including polarity control.

TABLE 8-1: COMPARATOR OUTPUT STATE VS. INPUT CONDITIONS

Input Condition	CxPOL	CxOUT
CxVIN- > CxVIN+	0	0
CxVIN- < CxVIN+	0	1
CxVIN- > CxVIN+	1	1
CxVIN- < CxVIN+	1	0

8.3 Comparator Response Time

The comparator output is indeterminate for a period of time after the change of an input source or the selection of a new reference voltage. This period is referred to as the response time. The response time of the comparator differs from the settling time of the voltage reference. Therefore, both of these times must be considered when determining the total response time to a comparator input change. See the Comparator and Voltage Reference specifications in **Section 17.0 “Electrical Specifications”** for more details.

PIC16F882/883/884/886/887

8.4 Comparator Interrupt Operation

The comparator interrupt flag can be set whenever there is a change in the output value of the comparator. Changes are recognized by means of a mismatch circuit which consists of two latches and an exclusive-or gate (see Figures 8-2 and 8-3). One latch is updated with the comparator output level when the CMxCON0 register is read. This latch retains the value until the next read of the CMxCON0 register or the occurrence of a Reset. The other latch of the mismatch circuit is updated on every Q1 system clock. A mismatch condition will occur when a comparator output change is clocked through the second latch on the Q1 clock cycle. At this point the two mismatch latches have opposite output levels which is detected by the exclusive-or gate and fed to the interrupt circuitry. The mismatch condition persists until either the CMxCON0 register is read or the comparator output returns to the previous state.

- Note 1:** A write operation to the CMxCON0 register will also clear the mismatch condition because all writes include a read operation at the beginning of the write cycle.
- 2:** Comparator interrupts will operate correctly regardless of the state of CxOE.

The comparator interrupt is set by the mismatch edge and not the mismatch level. This means that the interrupt flag can be reset without the additional step of reading or writing the CMxCON0 register to clear the mismatch registers. When the mismatch registers are cleared, an interrupt will occur upon the comparator's return to the previous state, otherwise no interrupt will be generated.

Software will need to maintain information about the status of the comparator output, as read from the CMxCON0 register, or CM2CON1 register, to determine the actual change that has occurred.

The CxIF bit of the PIR2 register is the comparator interrupt flag. This bit must be reset in software by clearing it to '0'. Since it is also possible to write a '1' to this register, an interrupt can be generated.

The CxIE bit of the PIE2 register and the PEIE and GIE bits of the INTCON register must all be set to enable comparator interrupts. If any of these bits are cleared, the interrupt is not enabled, although the CxIF bit of the PIR2 register will still be set if an interrupt condition occurs.

FIGURE 8-4: COMPARATOR INTERRUPT TIMING W/O CMxCON0 READ

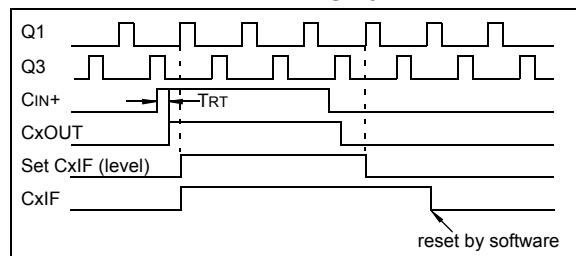
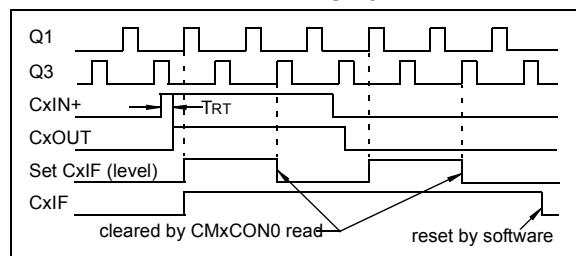


FIGURE 8-5: COMPARATOR INTERRUPT TIMING WITH CMxCON0 READ



Note 1: If a change in the CMxCON0 register (CxOUT) should occur when a read operation is being executed (start of the Q2 cycle), then the CxIF of the PIR2 register interrupt flag may not get set.

2: When either comparator is first enabled, bias circuitry in the comparator module may cause an invalid output from the comparator until the bias circuitry is stable. Allow about 1 μ s for bias settling then clear the mismatch condition and interrupt flags before enabling comparator interrupts.

8.5 Operation During Sleep

The comparator, if enabled before entering Sleep mode, remains active during Sleep. The additional current consumed by the comparator is shown separately in the **Section 17.0 “Electrical Specifications”**. If the comparator is not used to wake the device, power consumption can be minimized while in Sleep mode by turning off the comparator. Each comparator is turned off by clearing the CxON bit of the CMxCON0 register.

A change to the comparator output can wake-up the device from Sleep. To enable the comparator to wake the device from Sleep, the CxIE bit of the PIE2 register and the PEIE bit of the INTCON register must be set. The instruction following the Sleep instruction always executes following a wake from Sleep. If the GIE bit of the INTCON register is also set, the device will then execute the Interrupt Service Routine.

8.6 Effects of a Reset

A device Reset forces the CMxCON0 and CM2CON1 registers to their Reset states. This forces both comparators and the voltage references to their Off states.

PIC16F882/883/884/886/887

REGISTER 8-1: CM1CON0: COMPARATOR C1 CONTROL REGISTER 0

R/W-0	R-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
C1ON	C1OUT	C1OE	C1POL	—	C1R	C1CH1	C1CH0
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **C1ON:** Comparator C1 Enable bit

1 = Comparator C1 is enabled
0 = Comparator C1 is disabled

bit 6 **C1OUT:** Comparator C1 Output bit

If C1POL = 1 (inverted polarity):
C1OUT = 0 when C1VIN+ > C1VIN-
C1OUT = 1 when C1VIN+ < C1VIN-
If C1POL = 0 (non-inverted polarity):
C1OUT = 1 when C1VIN+ > C1VIN-
C1OUT = 0 when C1VIN+ < C1VIN-

bit 5 **C1OE:** Comparator C1 Output Enable bit

1 = C1OUT is present on the C1OUT pin⁽¹⁾
0 = C1OUT is internal only

bit 4 **C1POL:** Comparator C1 Output Polarity Select bit

1 = C1OUT logic is inverted
0 = C1OUT logic is not inverted

bit 3 **Unimplemented:** Read as '0'

bit 2 **C1R:** Comparator C1 Reference Select bit (non-inverting input)

1 = C1VIN+ connects to C1VREF output
0 = C1VIN+ connects to C1IN+ pin

bit 1-0 **C1CH<1:0>:** Comparator C1 Channel Select bit

00 = C12IN0- pin of C1 connects to C1VIN-
01 = C12IN1- pin of C1 connects to C1VIN-
10 = C12IN2- pin of C1 connects to C1VIN-
11 = C12IN3- pin of C1 connects to C1VIN-

Note 1: Comparator output requires the following three conditions: C1OE = 1, C1ON = 1 and corresponding port TRIS bit = 0.

REGISTER 8-2: CM2CON0: COMPARATOR C2 CONTROL REGISTER 0

R/W-0	R-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
C2ON	C2OUT	C2OE	C2POL	—	C2R	C2CH1	C2CH0
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	C2ON: Comparator C2 Enable bit 1 = Comparator C2 is enabled 0 = Comparator C2 is disabled
bit 6	C2OUT: Comparator C2 Output bit <u>If C2POL = 1 (inverted polarity):</u> C2OUT = 0 when C2VIN+ > C2VIN- C2OUT = 1 when C2VIN+ < C2VIN- <u>If C2POL = 0 (non-inverted polarity):</u> C2OUT = 1 when C2VIN+ > C2VIN- C2OUT = 0 when C2VIN+ < C2VIN-
bit 5	C2OE: Comparator C2 Output Enable bit 1 = C2OUT is present on C2OUT pin ⁽¹⁾ 0 = C2OUT is internal only
bit 4	C2POL: Comparator C2 Output Polarity Select bit 1 = C2OUT logic is inverted 0 = C2OUT logic is not inverted
bit 3	Unimplemented: Read as '0'
bit 2	C2R: Comparator C2 Reference Select bits (non-inverting input) 1 = C2VIN+ connects to C2VREF 0 = C2VIN+ connects to C2IN+ pin
bit 1-0	C2CH<1:0>: Comparator C2 Channel Select bits 00 = C12IN0- pin of C2 connects to C2VIN- 01 = C12IN1- pin of C2 connects to C2VIN- 10 = C12IN2- pin of C2 connects to C2VIN- 11 = C12IN3- pin of C2 connects to C2VIN-

Note 1: Comparator output requires the following three conditions: C2OE = 1, C2ON = 1 and corresponding port TRIS bit = 0.

8.7 Analog Input Connection Considerations

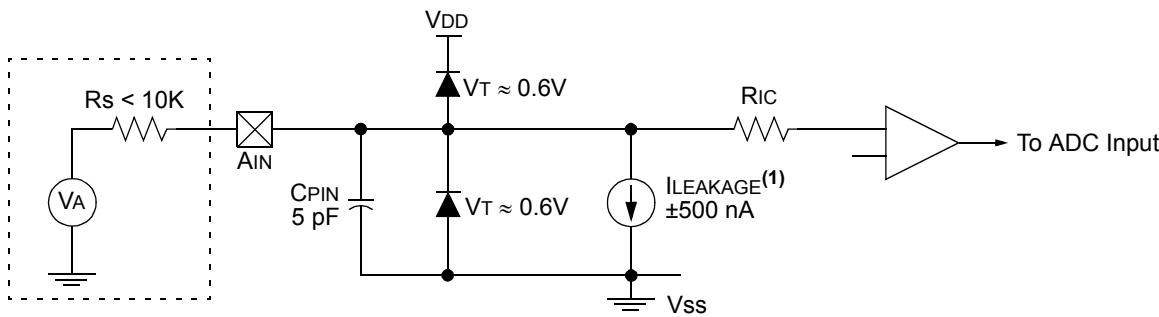
A simplified circuit for an analog input is shown in Figure 8-6. Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to VDD and Vss. The analog input, therefore, must be between Vss and VDD. If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of $10\text{ k}\Omega$ is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

Note 1: When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

2: Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

FIGURE 8-6: ANALOG INPUT MODEL



Legend:

- CPIN = Input Capacitance
- I_{LEAKAGE} = Leakage Current at the pin due to various junctions
- R_{IC} = Interconnect Resistance
- R_S = Source Impedance
- V_A = Analog Voltage
- V_T = Threshold Voltage

Note 1: See Section 17.0 "Electrical Specifications".

8.8 Additional Comparator Features

There are three additional comparator features:

- Timer1 count enable (gate)
- Synchronizing output with Timer1
- Simultaneous read of comparator outputs

8.8.1 COMPARATOR C2 GATING TIMER1

This feature can be used to time the duration or interval of analog events. Clearing the T1GSS bit of the CM2CON1 register will enable Timer1 to increment based on the output of Comparator C2. This requires that Timer1 is on and gating is enabled. See **Section 6.0 “Timer1 Module with Gate Control”** for details.

It is recommended to synchronize the comparator with Timer1 by setting the C2SYNC bit when the comparator is used as the Timer1 gate source. This ensures Timer1 does not miss an increment if the comparator changes during an increment.

8.8.2 SYNCHRONIZING COMPARATOR C2 OUTPUT TO TIMER1

The Comparator C2 output can be synchronized with Timer1 by setting the C2SYNC bit of the CM2CON1 register. When enabled, the C2 output is latched on the falling edge of the Timer1 clock source. If a prescaler is used with Timer1, the comparator output is latched after the prescaling function. To prevent a race condition, the comparator output is latched on the falling edge of the Timer1 clock source and Timer1 increments on the rising edge of its clock source. See the Comparator Block Diagram (Figures 8-2 and 8-3) and the Timer1 Block Diagram (Figure 6-1) for more information.

8.8.3 SIMULTANEOUS COMPARATOR OUTPUT READ

The MC1OUT and MC2OUT bits of the CM2CON1 register are mirror copies of both comparator outputs. The ability to read both outputs simultaneously from a single register eliminates the timing skew of reading separate registers.

Note 1: Obtaining the status of C1OUT or C2OUT by reading CM2CON1 does not affect the comparator interrupt mismatch registers.

REGISTER 8-3: CM2CON1: COMPARATOR C2 CONTROL REGISTER 1

R-0	R-0	R/W-0	R/W-0	U-0	U-0	R/W-1	R/W-0
MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as ‘0’

-n = Value at POR

‘1’ = Bit is set

‘0’ = Bit is cleared

x = Bit is unknown

bit 7	MC1OUT: Mirror Copy of C1OUT bit
bit 6	MC2OUT: Mirror Copy of C2OUT bit
bit 5	C1RSEL: Comparator C1 Reference Select bit 1 = CVREF routed to C1VREF input of Comparator C1 0 = Absolute voltage reference (0.6) routed to C1VREF input of Comparator C1 (or 1.2V precision reference on parts so equipped)
bit 4	C2RSEL: Comparator C2 Reference Select bit 1 = CVREF routed to C2VREF input of Comparator C2 0 = Absolute voltage reference (0.6) routed to C2VREF input of Comparator C2 (or 1.2V precision reference on parts so equipped)
bit 3-2	Unimplemented: Read as ‘0’
bit 1	T1GSS: Timer1 Gate Source Select bit 1 = Timer1 gate source is $\overline{T1G}$ 0 = Timer1 gate source is SYNCC2OUT.
bit 0	C2SYNC: Comparator C2 Output Synchronization bit 1 = Output is synchronous to falling edge of Timer1 clock 0 = Output is asynchronous

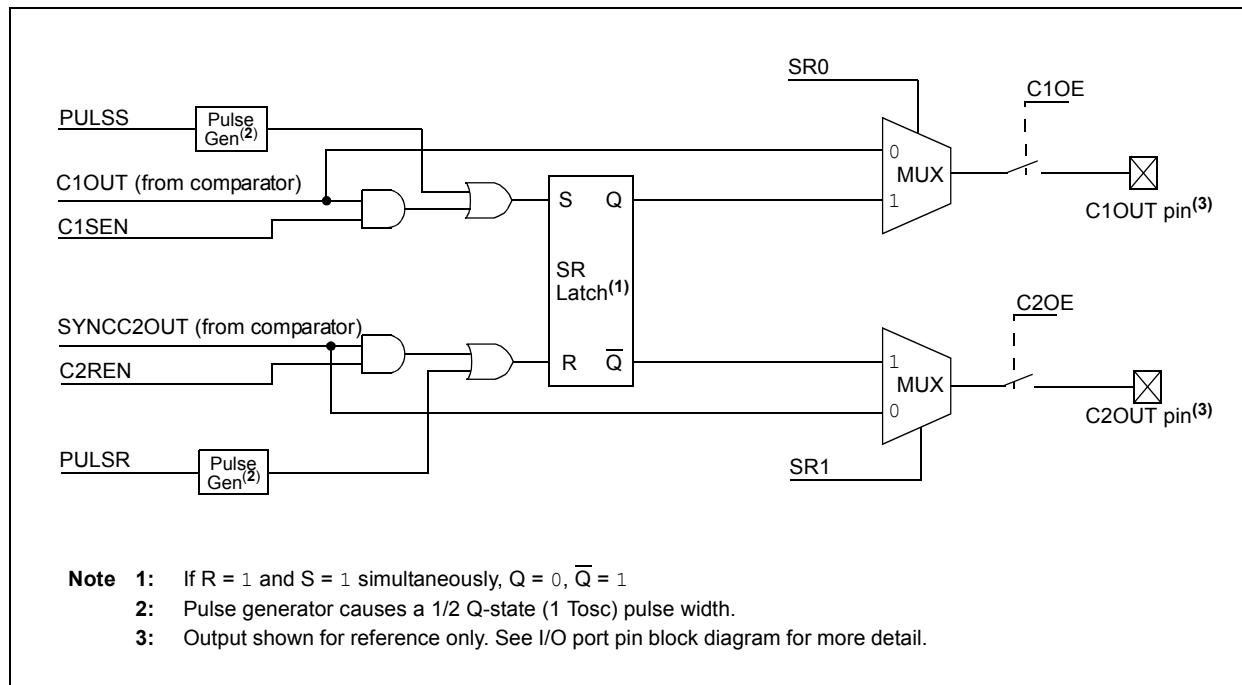
8.9 Comparator SR Latch

The SR latch module provides additional control of the comparator outputs. The module consists of a single SR latch and output multiplexers. The SR latch can be set, reset or toggled by the comparator outputs. The SR latch may also be set or reset, independent of comparator output, by control bits in the SRCON control register. The SR latch output multiplexers select whether the latch outputs or the comparator outputs are directed to the I/O port logic for eventual output to a pin.

8.9.1 LATCH OPERATION

The latch is a Set-Reset latch that does not depend on a clock source. Each of the Set and Reset inputs are active-high. Each latch input is connected to a comparator output and a software controlled pulse generator. The latch can be set by C1OUT or the PULSS bit of the SRCON register. The latch can be reset by C2OUT or the PULSR bit of the SRCON register. The latch is reset-dominant, therefore, if both Set and Reset inputs are high the latch will go to the Reset state. Both the PULSS and PULSR bits are self resetting which means that a single write to either of the bits is all that is necessary to complete a latch set or Reset operation.

FIGURE 8-7: SR LATCH SIMPLIFIED BLOCK DIAGRAM



REGISTER 8-4: SRCON: SR LATCH CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/S-0	R/S-0	U-0	R/W-0
SR1 ⁽²⁾	SR0 ⁽²⁾	C1SEN	C2REN	PULSS	PULSR	—	FVREN
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

S = Bit is set only -

-n = Value at POR

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7	SR1: SR Latch Configuration bit ⁽²⁾ 1 = C2OUT pin is the latch \bar{Q} output 0 = C2OUT pin is the C2 comparator output
bit 6	SR0: SR Latch Configuration bits ⁽²⁾ 1 = C1OUT pin is the latch Q output 0 = C1OUT pin is the C1 Comparator output
bit 5	C1SEN: C1 Set Enable bit 1 = C1 comparator output sets SR latch 0 = C1 comparator output has no effect on SR latch
bit 4	C2REN: C2 Reset Enable bit 1 = C2 comparator output resets SR latch 0 = C2 comparator output has no effect on SR latch
bit 3	PULSS: Pulse the SET Input of the SR Latch bit 1 = Triggers pulse generator to set SR latch. Bit is immediately reset by hardware. 0 = Does not trigger pulse generator
bit 2	PULSR: Pulse the Reset Input of the SR Latch bit 1 = Triggers pulse generator to reset SR latch. Bit is immediately reset by hardware. 0 = Does not trigger pulse generator
bit 1	Unimplemented: Read as '0'
bit 0	FVREN: Fixed Voltage Reference Enable bit 1 = 0.6V Reference FROM INTOSC LDO is enabled 0 = 0.6V Reference FROM INTOSC LDO is disabled

Note 1: The CxOUT bit in the CMxCON0 register will always reflect the actual comparator output (not the level on the pin), regardless of the SR latch operation.

2: To enable an SR Latch output to the pin, the appropriate CxOE and TRIS bits must be properly configured.

PIC16F882/883/884/886/887

8.10 Comparator Voltage Reference

The comparator voltage reference module provides an internally generated voltage reference for the comparators. The following features are available:

- Independent from Comparator operation
- Two 16-level voltage ranges
- Output clamped to Vss
- Ratiometric with VDD
- Fixed Reference (0.6V)

The VRCON register (Register 8-5) controls the voltage reference module shown in Figure 8-8.

The voltage source is selectable through both ends of the 16 connection resistor ladder network. Bit VRSS of the VRCON register selects either the internal or external voltage source.

The PIC16F882/883/884/886/887 allows the CVREF signal to be output to the RA2 pin of PORTA under certain configurations only. For more details, see Figure 8-9.

8.10.1 INDEPENDENT OPERATION

The comparator voltage reference is independent of the comparator configuration. Setting the VREN bit of the VRCON register will enable the voltage reference.

8.10.2 OUTPUT VOLTAGE SELECTION

The CVREF voltage reference has 2 ranges with 16 voltage levels in each range. Range selection is controlled by the VRR bit of the VRCON register. The 16 levels are set with the VR<3:0> bits of the VRCON register.

The CVREF output voltage is determined by the following equations:

EQUATION 8-1: CVREF OUTPUT VOLTAGE

$$V_{RR} = 1 \text{ (low range)}$$

$$CVREF = (VR<3:0>/24) \times VLADDER$$

$$V_{RR} = 0 \text{ (high range)}$$

$$CVREF = (VLADDER/4) + (VR<3:0> \times VLADDER/32)$$

$$VLADDER = VDD \text{ or } (VREF+ - VREF-) \text{ or } VREF+$$

The full range of Vss to VDD cannot be realized due to the construction of the module. See Figure 8-8.

8.10.3 OUTPUT CLAMPED TO Vss

The CVREF output voltage can be set to Vss with no power consumption by clearing the FVREN bit of the VRCON register.

This allows the comparator to detect a zero-crossing while not consuming additional CVREF module current.

8.10.4 OUTPUT RATIO METRIC TO VDD

The comparator voltage reference is VDD derived and therefore, the CVREF output changes with fluctuations in VDD. The tested absolute accuracy of the Comparator Voltage Reference can be found in **Section 17.0 "Electrical Specifications"**.

8.10.5 FIXED VOLTAGE REFERENCE

The fixed voltage reference is independent of VDD, with a nominal output voltage of 0.6V. This reference can be enabled by setting the FVREN bit of the SRCON register to '1'. This reference is always enabled when the HFINTOSC oscillator is active.

8.10.6 FIXED VOLTAGE REFERENCE STABILIZATION PERIOD

When the fixed voltage reference module is enabled, it will require some time for the reference and its amplifier circuits to stabilize. The user program must include a small delay routine to allow the module to settle. See **Section 17.0 "Electrical Specifications"** for the minimum delay requirement.

8.10.7 VOLTAGE REFERENCE SELECTION

Multiplexers on the output of the voltage reference module enable selection of either the CVREF or fixed voltage reference for use by the comparators.

Setting the C1VREN bit of the VRCON register enables current to flow in the CVREF voltage divider and selects the CVREF voltage for use by C1. Clearing the C1VREN bit selects the fixed voltage for use by C1.

Setting the C2VREN bit of the VRCON register enables current to flow in the CVREF voltage divider and selects the CVREF voltage for use by C2. Clearing the C2VREN bit selects the fixed voltage for use by C2.

When both the C1VREN and C2VREN bits are cleared, current flow in the CVREF voltage divider is disabled minimizing the power drain of the voltage reference peripheral.

PIC16F882/883/884/886/887

FIGURE 8-8: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM

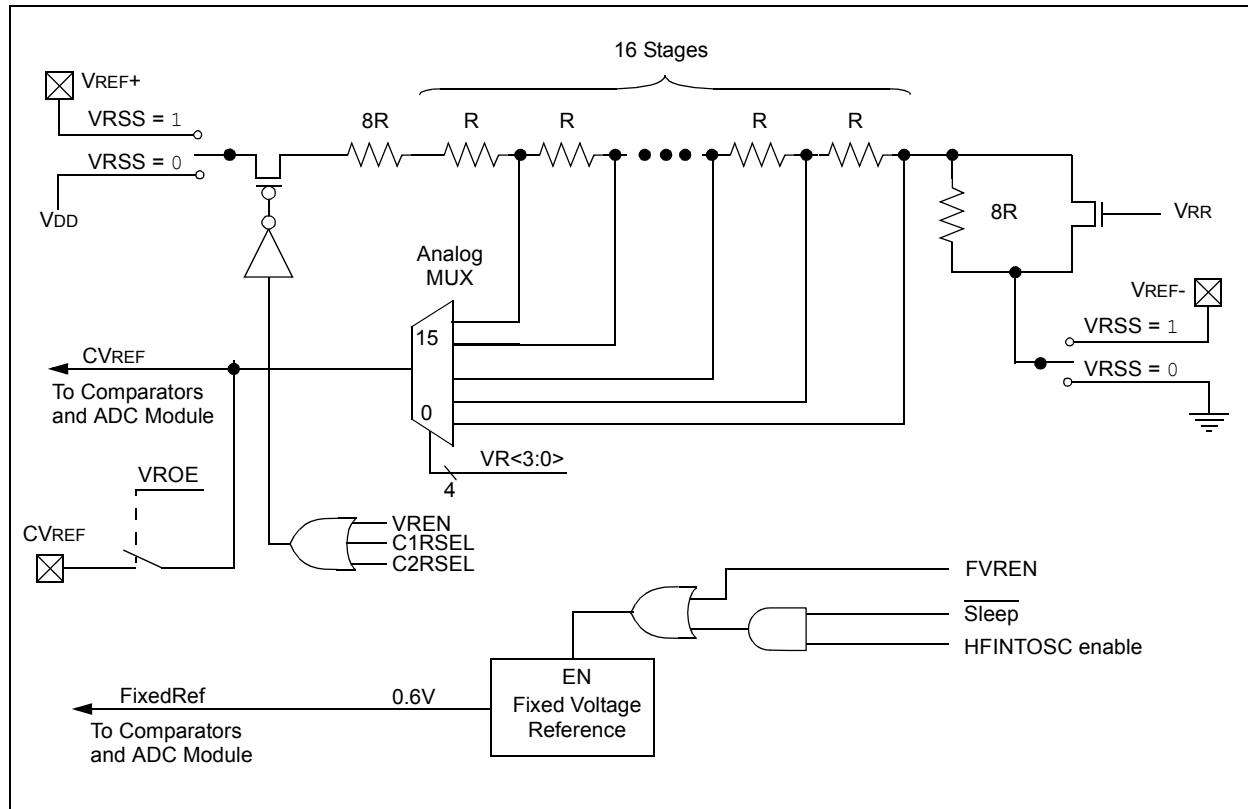
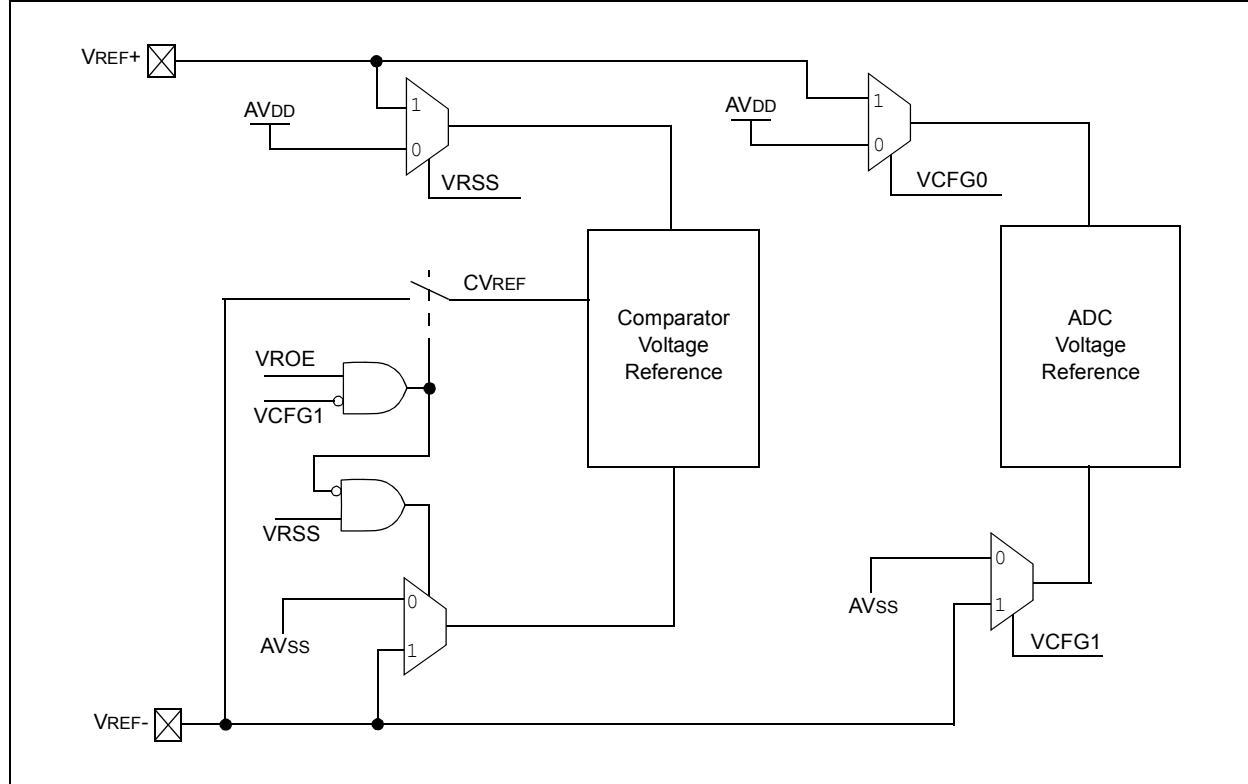


FIGURE 8-9: COMPARATOR AND ADC VOLTAGE REFERENCE BLOCK DIAGRAM



PIC16F882/883/884/886/887

TABLE 8-2: COMPARATOR AND ADC VOLTAGE REFERENCE PRIORITY

RA3	RA2	Comp. Reference (+)	Comp. Reference (-)	ADC Reference (+)	ADC Reference (-)	CFG1	CFG0	VRSS	VROE
I/O	I/O	AVDD	AVSS	AVDD	AVSS	0	0	0	0
I/O	CVREF	AVDD	AVSS	AVDD	AVSS	0	0	0	1
VREF+	VREF-	VREF+	VREF-	AVDD	AVSS	0	0	1	0
VREF+	CVREF	VREF+	AVSS	AVDD	AVSS	0	0	1	1
VREF+	I/O	AVDD	AVSS	VREF+	AVSS	0	1	0	0
VREF+	CVREF	AVDD	AVSS	VREF+	AVSS	0	1	0	1
VREF+	VREF-	VREF+	VREF-	VREF+	AVSS	0	1	1	0
VREF+	CVREF	VREF+	AVSS	VREF+	AVSS	0	1	1	1
I/O	VREF-	AVDD	AVSS	AVDD	VREF-	1	0	0	0
I/O	VREF-	AVDD	AVSS	AVDD	VREF-	1	0	0	1
VREF+	VREF-	VREF+	VREF-	AVDD	VREF-	1	0	1	0
VREF+	VREF-	VREF+	VREF-	AVDD	VREF-	1	0	1	1
VREF+	VREF-	AVDD	AVSS	VREF+	VREF-	1	1	0	0
VREF+	VREF-	AVDD	AVSS	VREF+	VREF-	1	1	0	1
VREF+	VREF-	VREF+	VREF-	VREF+	VREF-	1	1	1	0
VREF+	VREF-	VREF+	VREF-	VREF+	VREF-	1	1	1	1

REGISTER 8-5: VRCON: VOLTAGE REFERENCE CONTROL REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| VREN | VROE | VRR | VRSS | VR3 | VR2 | VR1 | VR0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	VREN: Comparator C1 Voltage Reference Enable bit 1 = CVREF circuit powered on 0 = CVREF circuit powered down
bit 6	VROE: Comparator C2 Voltage Reference Enable bit 1 = CVREF voltage level is also output on the RA2/AN2/VREF-/CVREF/C2IN+ pin 0 = CVREF voltage is disconnected from the RA2/AN2/VREF-/CVREF/C2IN+ pin
bit 5	VRR: CVREF Range Selection bit 1 = Low range 0 = High range
bit 4	VRSS: Comparator VREF Range Selection bit 1 = Comparator Reference Source, CVRSRC = (VREF+) - (VREF-) 0 = Comparator Reference Source, CVRSRC = VDD - VSS
bit 3-0	VR<3:0>: CVREF Value Selection $0 \leq VR<3:0> \leq 15$ <u>When VRR = 1:</u> CVREF = $(VR<3:0>/24) * VDD$ <u>When VRR = 0:</u> CVREF = $VDD/4 + (VR<3:0>/32) * VDD$

TABLE 8-3: SUMMARY OF REGISTERS ASSOCIATED WITH THE COMPARATOR AND VOLTAGE REFERENCE MODULES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	1111 1111
ANSELH	—	—	ANS13	ANS12	ANS11	ANS10	ANS9	ANS8	--11 1111	--11 1111
CM1CON0	C1ON	C1OUT	C1OE	C1POL	—	C1R	C1CH1	C1CH0	0000 -000	0000 -000
CM2CON0	C2ON	C2OUT	C2OE	C2POL	—	C2R	C2CH1	C2CH0	0000 -000	0000 -000
CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	0000 --10
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	0000 00-0
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	0000 00-0
PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx xxxx	uuuu uuuu
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	uuuu uuuu
SRCON	SR1	SR0	C1SEN	C2SEN	PULSS	PULSR	—	FVREN	0000 00-0	0000 00-0
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	1111 1111
VRCON	VREN	VROE	VRR	VRSS	VR3	VR2	VR1	VR0	0000 0000	0000 0000

Legend: x = unknown, u = unchanged, — = unimplemented, read as '0'. Shaded cells are not used for comparator.

PIC16F882/883/884/886/887

NOTES:

9.0 ANALOG-TO-DIGITAL CONVERTER (ADC) MODULE

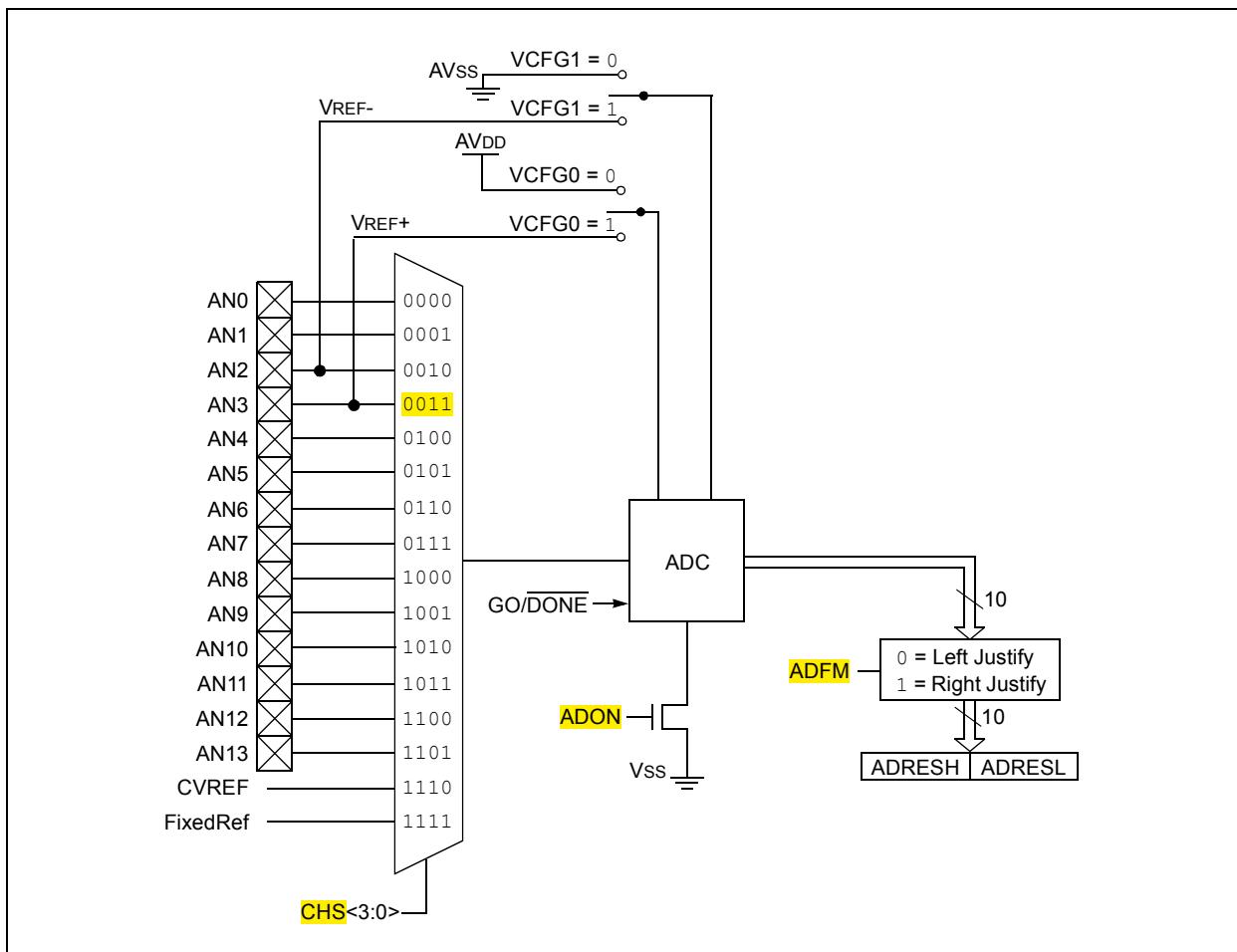
The Analog-to-Digital Converter (ADC) allows conversion of an analog input signal to a 10-bit binary representation of that signal. This device uses analog inputs, which are multiplexed into a single sample and hold circuit. The output of the sample and hold is connected to the input of the converter. The converter generates a 10-bit binary result via successive approximation and stores the conversion result into the ADC result registers (ADRESL and ADRESH).

The ADC voltage reference is software selectable to be either internally generated or externally supplied.

The ADC can generate an interrupt upon completion of a conversion. This interrupt can be used to wake-up the device from Sleep.

Figure 9-1 shows the block diagram of the ADC.

FIGURE 9-1: ADC BLOCK DIAGRAM



9.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- Port configuration
- Channel selection
- ADC voltage reference selection
- ADC conversion clock source
- Interrupt control
- Results formatting

9.1.1 PORT CONFIGURATION

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin should be configured for analog by setting the associated TRIS and ANSEL bits. See the corresponding Port section for more information.

Note: Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

9.1.2 CHANNEL SELECTION

The CHS bits of the ADCON0 register determine which channel is connected to the sample and hold circuit.

When changing channels, a delay is required before starting the next conversion. Refer to **Section 9.2 “ADC Operation”** for more information.

9.1.3 ADC VOLTAGE REFERENCE

The VCFG bits of the ADCON0 register provide independent control of the positive and negative voltage references. The positive voltage reference can be either VDD or an external voltage source. Likewise, the negative voltage reference can be either Vss or an external voltage source.

9.1.4 CONVERSION CLOCK

The source of the conversion clock is software selectable via the ADCS bits of the ADCON0 register. There are four possible clock options:

- Fosc/2
- Fosc/8
- Fosc/32
- FRC (dedicated internal oscillator)

The time to complete one bit conversion is defined as TAD. One full 10-bit conversion requires 11 TAD periods as shown in Figure 9-2.

For correct conversion, the appropriate TAD specification must be met. See A/D conversion requirements in **Section 17.0 “Electrical Specifications”** for more information. Table 9-1 gives examples of appropriate ADC clock selections.

Note: Unless using the FRC, any changes in the system clock frequency will change the ADC clock frequency, which may adversely affect the ADC result.

TABLE 9-1: ADC CLOCK PERIOD (TAD) Vs. DEVICE OPERATING FREQUENCIES (VDD \geq 3.0V)

ADC Clock Period (TAD)		Device Frequency (Fosc)			
ADC Clock Source	ADCS<1:0>	20 MHz	8 MHz	4 MHz	1 MHz
Fosc/2	00	100 ns ⁽²⁾	250 ns ⁽²⁾	500 ns ⁽²⁾	2.0 μ s
Fosc/8	01	400 ns ⁽²⁾	1.0 μ s ⁽²⁾	2.0 μ s	8.0 μ s ⁽³⁾
Fosc/32	10	1.6 μ s	4.0 μ s	8.0 μ s ⁽³⁾	32.0 μ s ⁽³⁾
FRC	11	2-6 μ s ^(1,4)			

Legend: Shaded cells are outside of recommended range.

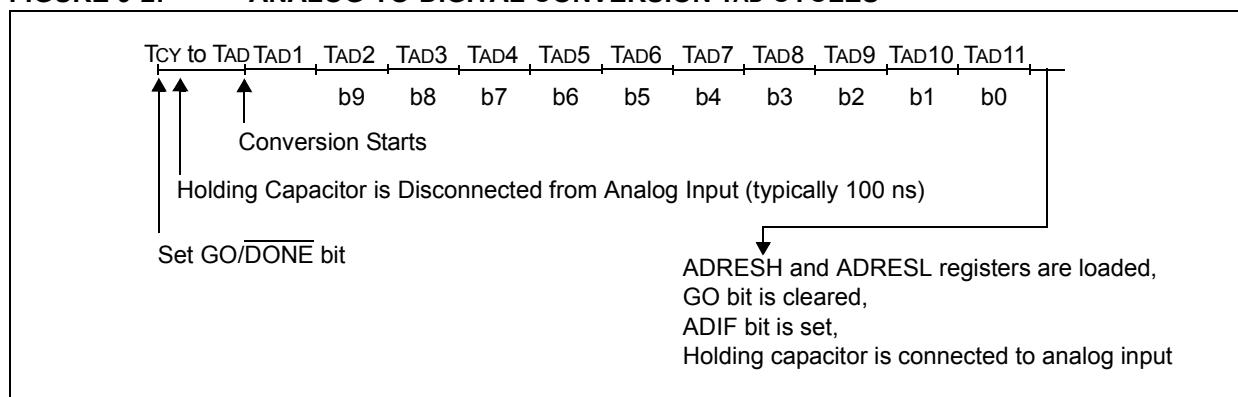
Note 1: The FRC source has a typical TAD time of 4 μ s for VDD > 3.0V.

2: These values violate the minimum required TAD time.

3: For faster conversion times, the selection of another clock source is recommended.

4: When the device frequency is greater than 1 MHz, the FRC clock source is only recommended if the conversion will be performed during Sleep.

FIGURE 9-2: ANALOG-TO-DIGITAL CONVERSION TAD CYCLES



9.1.5 INTERRUPTS

The ADC module allows for the ability to generate an interrupt upon completion of an Analog-to-Digital conversion. The ADC interrupt flag is the ADIF bit in the PIR1 register. The ADC interrupt enable is the ADIE bit in the PIE1 register. The ADIF bit must be cleared in software.

Note: The ADIF bit is set at the completion of every conversion, regardless of whether or not the ADC interrupt is enabled.

This interrupt can be generated while the device is operating or while in Sleep. If the device is in Sleep, the interrupt will wake-up the device. Upon waking from Sleep, the next instruction following the SLEEP instruction is always executed. If the user is attempting to wake-up from Sleep and resume in-line code execution, the global interrupt must be disabled. If the global interrupt is enabled, execution will switch to the Interrupt Service Routine.

Please see **Section 14.3 “Interrupts”** for more information.

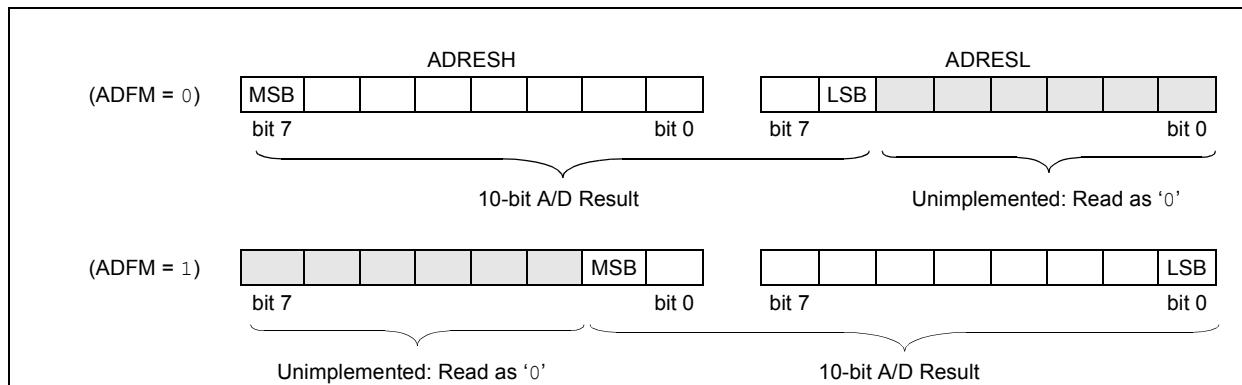
PIC16F882/883/884/886/887

9.1.6 RESULT FORMATTING

The 10-bit A/D conversion result can be supplied in two formats, left justified or right justified. The ADFM bit of the ADCON0 register controls the output format.

Figure 9-3 shows the two output formats.

FIGURE 9-3: 10-BIT A/D CONVERSION RESULT FORMAT



9.2 ADC Operation

9.2.1 STARTING A CONVERSION

To enable the ADC module, the ADON bit of the ADCON0 register must be set to a '1'. Setting the GO/DONE bit of the ADCON0 register to a '1' will start the Analog-to-Digital conversion.

Note: The GO/DONE bit should not be set in the same instruction that turns on the ADC. Refer to **Section 9.2.6 "A/D Conversion Procedure"**.

9.2.2 COMPLETION OF A CONVERSION

When the conversion is complete, the ADC module will:

- Clear the GO/DONE bit
- Set the ADIF flag bit
- Update the ADRESH:ADRESL registers with new conversion result

9.2.3 TERMINATING A CONVERSION

If a conversion must be terminated before completion, the GO/DONE bit can be cleared in software. The ADRESH:ADRESL registers will not be updated with the partially complete Analog-to-Digital conversion sample. Instead, the ADRESH:ADRESL register pair will retain the value of the previous conversion. Additionally, a 2 TAD delay is required before another acquisition can be initiated. Following this delay, an input acquisition is automatically started on the selected channel.

Note: A device Reset forces all registers to their Reset state. Thus, the ADC module is turned off and any pending conversion is terminated.

9.2.4 ADC OPERATION DURING SLEEP

The ADC module can operate during Sleep. This requires the ADC clock source to be set to the FRC option. When the FRC clock source is selected, the ADC waits one additional instruction before starting the conversion. This allows the SLEEP instruction to be executed, which can reduce system noise during the conversion. If the ADC interrupt is enabled, the device will wake-up from Sleep when the conversion completes. If the ADC interrupt is disabled, the ADC module is turned off after the conversion completes, although the ADON bit remains set.

When the ADC clock source is something other than FRC, a SLEEP instruction causes the present conversion to be aborted and the ADC module is turned off, although the ADON bit remains set.

9.2.5 SPECIAL EVENT TRIGGER

The CCP Special Event Trigger allows periodic ADC measurements without software intervention. When this trigger occurs, the GO/DONE bit is set by hardware and the Timer1 counter resets to zero.

Using the Special Event Trigger does not assure proper ADC timing. It is the user's responsibility to ensure that the ADC timing requirements are met.

See **Section 11.0 "Capture/Compare/PWM Modules (CCP1 and CCP2)"** for more information.

9.2.6 A/D CONVERSION PROCEDURE

This is an example procedure for using the ADC to perform an Analog-to-Digital conversion:

1. Configure Port:
 - Disable pin output driver (See TRIS register)
 - Configure pin as analog
2. Configure the ADC module:
 - Select ADC conversion clock
 - Configure voltage reference
 - Select ADC input channel
 - Select result format
 - Turn on ADC module
3. Configure ADC interrupt (optional):
 - Clear ADC interrupt flag
 - Enable ADC interrupt
 - Enable peripheral interrupt
 - Enable global interrupt⁽¹⁾
4. Wait the required acquisition time⁽²⁾.
5. Start conversion by setting the GO/DONE bit.
6. Wait for ADC conversion to complete by one of the following:
 - Polling the GO/DONE bit
 - Waiting for the ADC interrupt (interrupts enabled)
7. Read ADC Result
8. Clear the ADC interrupt flag (required if interrupt is enabled).

Note 1: The global interrupt can be disabled if the user is attempting to wake-up from Sleep and resume in-line code execution.

2: See **Section 9.3 “A/D Acquisition Requirements”**.

EXAMPLE 9-1: A/D CONVERSION

```
;This code block configures the ADC  
;for polling, Vdd and Vss as reference, Frc  
clock and AN0 input.  
;  
;Conversion start & polling for completion  
;are included.  
;  
BANKSEL    ADCON1      ;  
MOVlw     B'10000000'  ;right justify  
MOVwf     ADCON1      ;Vdd and Vss as Vref  
BANKSEL    TRISA       ;  
BSF       TRISA,0     ;Set RA0 to input  
BANKSEL    ANSEL       ;  
BSF       ANSEL,0     ;Set RA0 to analog  
BANKSEL    ADCON0      ;  
MOVlw     B'11000001'  ;ADC Frc clock,  
MOVwf     ADCON0      ;AN0, On  
CALL      SampleTime  ;Acquisition delay  
BSF       ADCON0,GO   ;Start conversion  
BTfsc    ADCON0,GO   ;Is conversion done?  
Goto     $-1          ;No, test again  
BANKSEL    ADRESH      ;  
Movf     ADRESH,W    ;Read upper 2 bits  
Movwf    RESULTHI    ;store in GPR space  
BANKSEL    ADRESL      ;  
Movf     ADRESL,W    ;Read lower 8 bits  
Movwf    RESULTLO    ;Store in GPR space
```

PIC16F882/883/884/886/887

9.2.7 ADC REGISTER DEFINITIONS

The following registers are used to control the operation of the ADC.

Note: For ANSEL and ANSELH registers, see Register 3-3 and Register 3-4, respectively.

REGISTER 9-1: ADCON0: A/D CONTROL REGISTER 0

R/W-0	R/W-0						
ADCS1	ADCS0	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON
bit 7							bit 0

Legend:

R = Readable bit
-n = Value at POR

W = Writable bit
'1' = Bit is set

U = Unimplemented bit, read as '0'
'0' = Bit is cleared
x = Bit is unknown

bit 7-6 **ADCS<1:0>**: A/D Conversion Clock Select bits
00 = Fosc/2
01 = Fosc/8
10 = Fosc/32
11 = FRC (clock derived from a dedicated internal oscillator = 500 kHz max)

bit 5-2 **CHS<3:0>**: Analog Channel Select bits

0000 = AN0
0001 = AN1
0010 = AN2
0011 = AN3
0100 = AN4
0101 = AN5
0110 = AN6
0111 = AN7
1000 = AN8
1001 = AN9
1010 = AN10
1011 = AN11
1100 = AN12
1101 = AN13
1110 = CVREF
1111 = Fixed Ref (0.6V fixed voltage reference)

bit 1 **GO/DONE**: A/D Conversion Status bit

1 = A/D conversion cycle in progress. Setting this bit starts an A/D conversion cycle.
This bit is automatically cleared by hardware when the A/D conversion has completed.
0 = A/D conversion completed/not in progress

bit 0 **ADON**: ADC Enable bit

1 = ADC is enabled
0 = ADC is disabled and consumes no operating current

REGISTER 9-2: ADCON1: A/D CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
ADFM	—	VCFG1	VCFG0	—	—	—	—
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **ADFM:** A/D Conversion Result Format Select bit1 = Right justified
0 = Left justifiedbit 6 **Unimplemented:** Read as '0'bit 5 **VCFG1:** Voltage Reference bit1 = VREF- pin
0 = VSSbit 4 **VCFG0:** Voltage Reference bit1 = VREF+ pin
0 = VDDbit 3-0 **Unimplemented:** Read as '0'

PIC16F882/883/884/886/887

REGISTER 9-3: ADRESH: ADC RESULT REGISTER HIGH (ADRESH) ADFM = 0

| R/W-x |
|--------|--------|--------|--------|--------|--------|--------|--------|
| ADRES9 | ADRES8 | ADRES7 | ADRES6 | ADRES5 | ADRES4 | ADRES3 | ADRES2 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **ADRES<9:2>**: ADC Result Register bits
Upper 8 bits of 10-bit conversion result

REGISTER 9-4: ADRESL: ADC RESULT REGISTER LOW (ADRESL) ADFM = 0

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
ADRES1	ADRES0	—	—	—	—	—	—
bit 7							bit 0

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **ADRES<1:0>**: ADC Result Register bits
Lower 2 bits of 10-bit conversion result

bit 5-0 **Reserved**: Do not use.

REGISTER 9-5: ADRESH: ADC RESULT REGISTER HIGH (ADRESH) ADFM = 1

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|--------|
| — | — | — | — | — | — | — | ADRES9 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-2 **Reserved**: Do not use.

bit 1-0 **ADRES<9:8>**: ADC Result Register bits
Upper 2 bits of 10-bit conversion result

REGISTER 9-6: ADRESL: ADC RESULT REGISTER LOW (ADRESL) ADFM = 1

| R/W-x |
|--------|--------|--------|--------|--------|--------|--------|--------|
| ADRES7 | ADRES6 | ADRES5 | ADRES4 | ADRES3 | ADRES2 | ADRES1 | ADRES0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **ADRES<7:0>**: ADC Result Register bits
Lower 8 bits of 10-bit conversion result

9.3 A/D Acquisition Requirements

For the ADC to meet its specified accuracy, the charge holding capacitor (CHOLD) must be allowed to fully charge to the input channel voltage level. The Analog Input model is shown in Figure 9-4. The source impedance (R_s) and the internal sampling switch (R_{ss}) impedance directly affect the time required to charge the capacitor CHOLD. The sampling switch (R_{ss}) impedance varies over the device voltage (V_{DD}), see Figure 9-4. **The maximum recommended impedance for analog sources is 10 k Ω .** As the source impedance is decreased, the acquisition time may be decreased. After the analog input channel is selected (or changed),

an A/D acquisition must be done before the conversion can be started. To calculate the minimum acquisition time, Equation 9-1 may be used. This equation assumes that 1/2 LSB error is used (1024 steps for the ADC). The 1/2 LSB error is the maximum error allowed for the ADC to meet its specified resolution.

EQUATION 9-1: ACQUISITION TIME EXAMPLE

Assumptions: Temperature = 50°C and external impedance of 10k Ω 5.0V VDD

$$\begin{aligned} T_{ACQ} &= \text{Amplifier Settling Time} + \text{Hold Capacitor Charging Time} + \text{Temperature Coefficient} \\ &= T_{AMP} + T_C + T_{COFF} \\ &= 2\mu s + T_C + [(Temperature - 25^\circ C)(0.05\mu s/\text{ }^\circ C)] \end{aligned}$$

The value for T_C can be approximated with the following equations:

$$\begin{aligned} V_{APPLIED} \left(I - \frac{1}{(2^{n+1}) - I} \right) &= V_{CHOLD} &&; [1] V_{CHOLD} \text{ charged to within 1/2 lsb} \\ V_{APPLIED} \left(I - e^{\frac{-T_C}{RC}} \right) &= V_{CHOLD} &&; [2] V_{CHOLD} \text{ charge response to } V_{APPLIED} \\ V_{APPLIED} \left(I - e^{\frac{-T_C}{RC}} \right) &= V_{APPLIED} \left(I - \frac{1}{(2^{n+1}) - I} \right) &&; \text{combining [1] and [2]} \end{aligned}$$

Solving for T_C :

$$\begin{aligned} T_C &= -C_{HOLD}(R_{IC} + R_{SS} + R_s) \ln(1/2047) \\ &= -10pF(1k\Omega + 7k\Omega + 10k\Omega) \ln(0.0004885) \\ &= 1.37\mu s \end{aligned}$$

Therefore:

$$\begin{aligned} T_{ACQ} &= 2\mu s + 1.37\mu s + [(50^\circ C - 25^\circ C)(0.05\mu s/\text{ }^\circ C)] \\ &= 4.67\mu s \end{aligned}$$

Note 1: The reference voltage (VREF) has no effect on the equation, since it cancels itself out.

- 2:** The charge holding capacitor (CHOLD) is not discharged after each conversion.
- 3:** The maximum recommended impedance for analog sources is 10 k Ω . This is required to meet the pin leakage specification.

PIC16F882/883/884/886/887

FIGURE 9-4: ANALOG INPUT MODEL

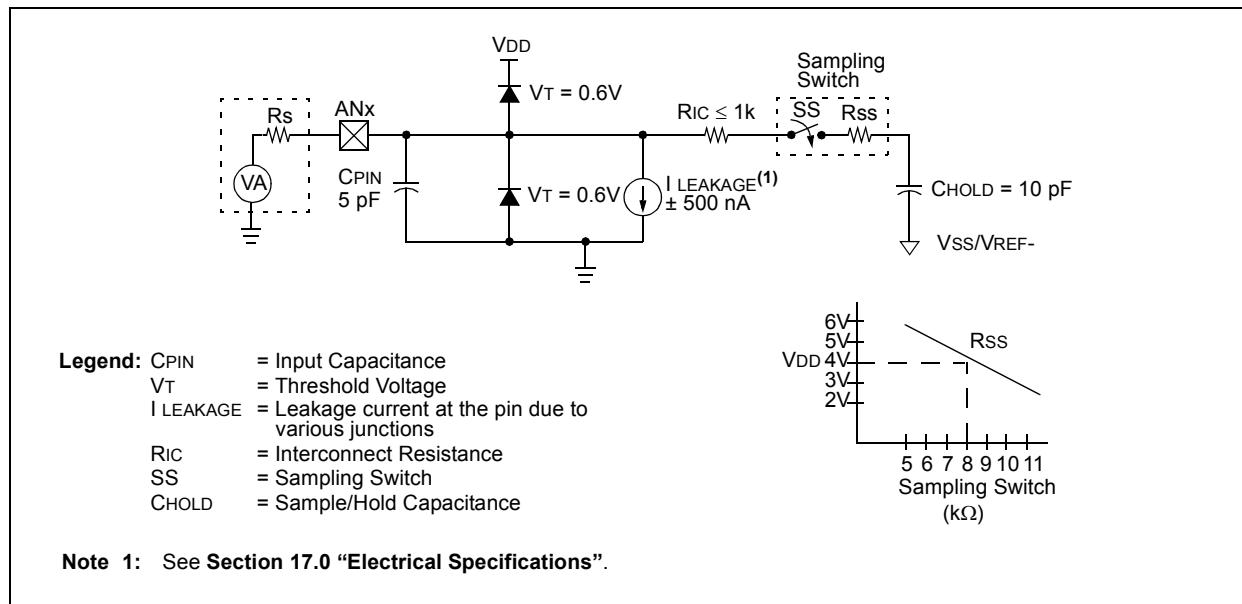
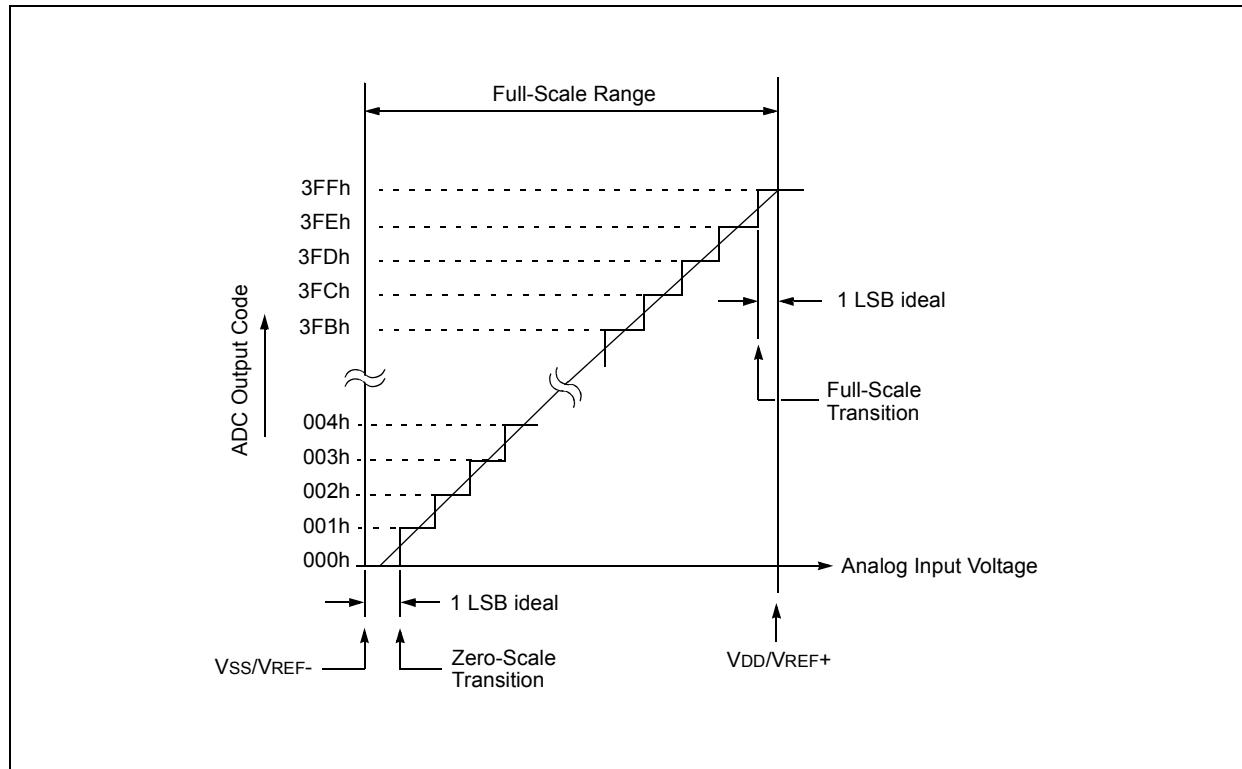


FIGURE 9-5: ADC TRANSFER FUNCTION



PIC16F882/883/884/886/887

TABLE 9-2: SUMMARY OF ASSOCIATED ADC REGISTERS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ADCON0	ADCS1	ADCS0	CHS3	CHS2	CHS1	CHS0	GO/DONE	ADON	0000 0000	0000 0000
ADCON1	ADFM	—	VCFG1	VCFG0	—	—	—	—	0-00 ----	-000 ----
ANSEL	ANS7	ANS6	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	1111 1111	1111 1111
ANSELH	—	—	ANS13	ANS12	ANS11	ANS10	ANS9	ANS8	--11 1111	--11 1111
ADRESH	A/D Result Register High Byte							xxxx xxxx	uuuu uuuu	
ADRESL	A/D Result Register Low Byte							xxxx xxxx	uuuu uuuu	
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx xxxx	uuuu uuuu
PORTB	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx xxxx	uuuu uuuu
PORTE	—	—	—	—	RE3	RE2	RE1	RE0	---- xxxx	---- uuuu
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	1111 111
TRISE	—	—	—	—	TRISE3	TRISE2	TRISE1	TRISE0	---- 1111	---- 111

Legend: x = unknown, u = unchanged, — = unimplemented read as '0'. Shaded cells are not used for ADC module.

PIC16F882/883/884/886/887

NOTES:

10.0 DATA EEPROM AND FLASH PROGRAM MEMORY CONTROL

The Data EEPROM and Flash program memory are readable and writable during normal operation (full V_{DD} range). These memories are not directly mapped in the register file space. Instead, they are indirectly addressed through the Special Function Registers (SFRs). There are six SFRs used to access these memories:

- EECON1
- EECON2
- EEDAT
- EEDATH
- EEADR
- EEADRH (bit 4 on PIC16F886/PIC16F887 only)

When interfacing the data memory block, EEDAT holds the 8-bit data for read/write, and EEADR holds the address of the EEDAT location being accessed. These devices have 256 bytes of data EEPROM with an address range from 0h to 0FFh.

When accessing the program memory block of the PIC16F886/PIC16F887 devices, the EEDAT and EEDATH registers form a 2-byte word that holds the 14-bit data for read/write, and the EEADR and EEADRH registers form a 2-byte word that holds the 12-bit address of the EEPROM location being read. The PIC16F882 devices have 2K words of program EEPROM with an address range from 0h to 07FFh. The PIC16F883/PIC16F884 devices have 4K words of program EEPROM with an address range from 0h to 0FFFh. The program memory allows one-word reads.

The EEPROM data memory allows byte read and write. A byte write automatically erases the location and writes the new data (erase before write).

The write time is controlled by an on-chip timer. The write/erase voltages are generated by an on-chip charge pump rated to operate over the voltage range of the device for byte or word operations.

Depending on the setting of the Flash Program Memory Self Write Enable bits WRT<1:0> of the Configuration Word Register 2, the device may or may not be able to write certain blocks of the program memory. However, reads from the program memory are allowed.

When the device is code-protected, the CPU may continue to read and write the data EEPROM memory and Flash program memory. When code-protected, the device programmer can no longer access data or program memory.

10.1 EEADR and EEADRH Registers

The EEADR and EEADRH registers can address up to a maximum of 256 bytes of data EEPROM or up to a maximum of 8K words of program EEPROM.

When selecting a program address value, the MSB of the address is written to the EEADRH register and the LSB is written to the EEADR register. When selecting a data address value, only the LSB of the address is written to the EEADR register.

10.1.1 EECON1 AND EECON2 REGISTERS

EECON1 is the control register for EE memory accesses.

Control bit EEPGD determines if the access will be a program or data memory access. When clear, as it is when reset, any subsequent operations will operate on the data memory. When set, any subsequent operations will operate on the program memory. Program memory can only be read.

Control bits RD and WR initiate read and write, respectively. These bits cannot be cleared, only set, in software. They are cleared in hardware at completion of the read or write operation. The inability to clear the WR bit in software prevents the accidental, premature termination of a write operation.

The WREN bit, when set, will allow a write operation to data EEPROM. On power-up, the WREN bit is clear. The WRERR bit is set when a write operation is interrupted by a MCLR or a WDT Time-out Reset during normal operation. In these situations, following Reset, the user can check the WRERR bit and rewrite the location.

Interrupt flag bit EEIF of the PIR2 register is set when write is complete. It must be cleared in the software.

EECON2 is not a physical register. Reading EECON2 will read all '0's. The EECON2 register is used exclusively in the data EEPROM write sequence.

PIC16F882/883/884/886/887

REGISTER 10-1: EEDAT: EEPROM DATA REGISTER

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| EEDAT7 | EEDAT6 | EEDAT5 | EEDAT4 | EEDAT3 | EEDAT2 | EEDAT1 | EEDAT0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **EEDAT<7:0>**: 8 Least Significant Address bits to Write to or Read from data EEPROM or Read from program memory

REGISTER 10-2: EEADR: EEPROM ADDRESS REGISTER

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| EEADR7 | EEADR6 | EEADR5 | EEADR4 | EEADR3 | EEADR2 | EEADR1 | EEADR0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **EEADR<7:0>**: 8 Least Significant Address bits for EEPROM Read/Write Operation⁽¹⁾ or Read from program memory

REGISTER 10-3: EEDATH: EEPROM DATA HIGH BYTE REGISTER

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	EEDATH5	EEDATH4	EEDATH3	EEDATH2	EEDATH1	EEDATH0
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **EEDATH<5:0>**: 6 Most Significant Data bits from program memory

REGISTER 10-4: EEADRH: EEPROM ADDRESS HIGH BYTE REGISTER

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	EEADRH4 ⁽¹⁾	EEADRH3	EEADRH2	EEADRH1	EEADRH0
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **EEADRH<4:0>**: Specifies the 4 Most Significant Address bits or high bits for program memory reads

Note 1: PIC16F886/PIC16F887 only.

REGISTER 10-5: EECON1: EEPROM CONTROL REGISTER

R/W-x	U-0	U-0	U-0	R/W-x	R/W-0	R/S-0	R/S-0
EEPGD	—	—	—	WRERR	WREN	WR	RD
bit 7	bit 0						

Legend:

S = Bit can only be set

R = Readable bit

-n = Value at POR

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

- | | |
|---------|--|
| bit 7 | EEPGD: Program/Data EEPROM Select bit
1 = Accesses program memory
0 = Accesses data memory |
| bit 6-4 | Unimplemented: Read as '0' |
| bit 3 | WRERR: EEPROM Error Flag bit
1 = A write operation is prematurely terminated (any <u>MCLR</u> Reset, any WDT Reset during normal operation or BOR Reset)
0 = The write operation completed |
| bit 2 | WREN: EEPROM Write Enable bit
1 = Allows write cycles
0 = Inhibits write to the data EEPROM |
| bit 1 | WR: Write Control bit
1 = Initiates a write cycle (The bit is cleared by hardware once write is complete. The WR bit can only be set, not cleared, in software.)
0 = Write cycle to the data EEPROM is complete |
| bit 0 | RD: Read Control bit
1 = Initiates a memory read (the RD is cleared in hardware and can only be set, not cleared, in software.)
0 = Does not initiate a memory read |

PIC16F882/883/884/886/887

10.1.2 READING THE DATA EEPROM MEMORY

To read a data memory location, the user must write the address to the EEADR register, clear the EEPGD control bit of the EECON1 register, and then set control bit RD. The data is available at the very next cycle, in the EEDAT register; therefore, it can be read in the next instruction. EEDAT will hold this value until another read or until it is written to by the user (during a write operation).

EXAMPLE 10-1: DATA EEPROM READ

```
BANKSEL EEADR      ;  
MOVLW  DATA_EE_ADDR ;  
MOVWF  EEADR      ;Data Memory  
                  ;Address to read  
BANKSEL EECON1     ;  
BCF    EECON1, EEPGD ;Point to DATA memory  
BSF    EECON1, RD   ;EE Read  
BANKSEL EEDAT      ;  
MOVF   EEDAT, W    ;W = EEDAT  
BCF    STATUS, RP1  ;Bank 0
```

10.1.3 WRITING TO THE DATA EEPROM MEMORY

To write an EEPROM data location, the user must first write the address to the EEADR register and the data to the EEDAT register. Then the user must follow a specific sequence to initiate the write for each byte.

The write will not initiate if the above sequence is not followed exactly (write 55h to EECON2, write AAh to EECON2, then set WR bit) for each byte. Interrupts should be disabled during this code segment.

Additionally, the WREN bit in EECON1 must be set to enable write. This mechanism prevents accidental writes to data EEPROM due to errant (unexpected) code execution (i.e., lost programs). The user should keep the WREN bit clear at all times, except when updating EEPROM. The WREN bit is not cleared by hardware.

After a write sequence has been initiated, clearing the WREN bit will not affect this write cycle. The WR bit will be inhibited from being set unless the WREN bit is set.

At the completion of the write cycle, the WR bit is cleared in hardware and the EE Write Complete Interrupt Flag bit (EEIF) is set. The user can either enable this interrupt or poll this bit. EEIF must be cleared by software.

EXAMPLE 10-2: DATA EEPROM WRITE

```
BANKSEL EEADR      ;  
MOVLW  DATA_EE_ADDR ;  
MOVWF  EEADR      ;Data Memory Address to write  
MOVLW  DATA_EE_DATA ;  
MOVWF  EEDAT      ;Data Memory Value to write  
BANKSEL EECON1     ;  
BCF    EECON1, EEPGD ;Point to DATA memory  
BSF    EECON1, WREN ;Enable writes  
  
BCF    INTCON, GIE  ;Disable INTs.  
BTFS  INTCON, GIE  ;SEE AN576  
GOTO  $-2  
MOVLW  55h          ;  
MOVWF  EECON2      ;Write 55h  
MOVLW  AAh          ;  
MOVWF  EECON2      ;Write AAh  
BSF    EECON1, WR   ;Set WR bit to begin write  
BSF    INTCON, GIE  ;Enable INTs.  
  
SLEEP             ;Wait for interrupt to signal write complete  
BCF    EECON1, WREN ;Disable writes  
BCF    STATUS, RP0  ;Bank 0  
BCF    STATUS, RP1  ;Bank 0
```

Required Sequence

10.1.4 READING THE FLASH PROGRAM MEMORY

To read a program memory location, the user must write the Least and Most Significant address bits to the EEADR and EEADRH registers, set the EEPGD control bit of the EECON1 register, and then set control bit RD. Once the read control bit is set, the program memory Flash controller will use the second instruction cycle to read the data. This causes the second instruction immediately following the “BSF EECON1, RD” instruction to be ignored. The data is available in the very next cycle, in the EEDAT and EEDATH registers; therefore, it can be read as two bytes in the following instructions.

EEDAT and EEDATH registers will hold this value until another read or until it is written to by the user.

Note 1: The two instructions following a program memory read are required to be NOPs. This prevents the user from executing a two-cycle instruction on the next instruction after the RD bit is set.

2: If the WR bit is set when EEPGD = 1, it will be immediately reset to ‘0’ and no operation will take place.

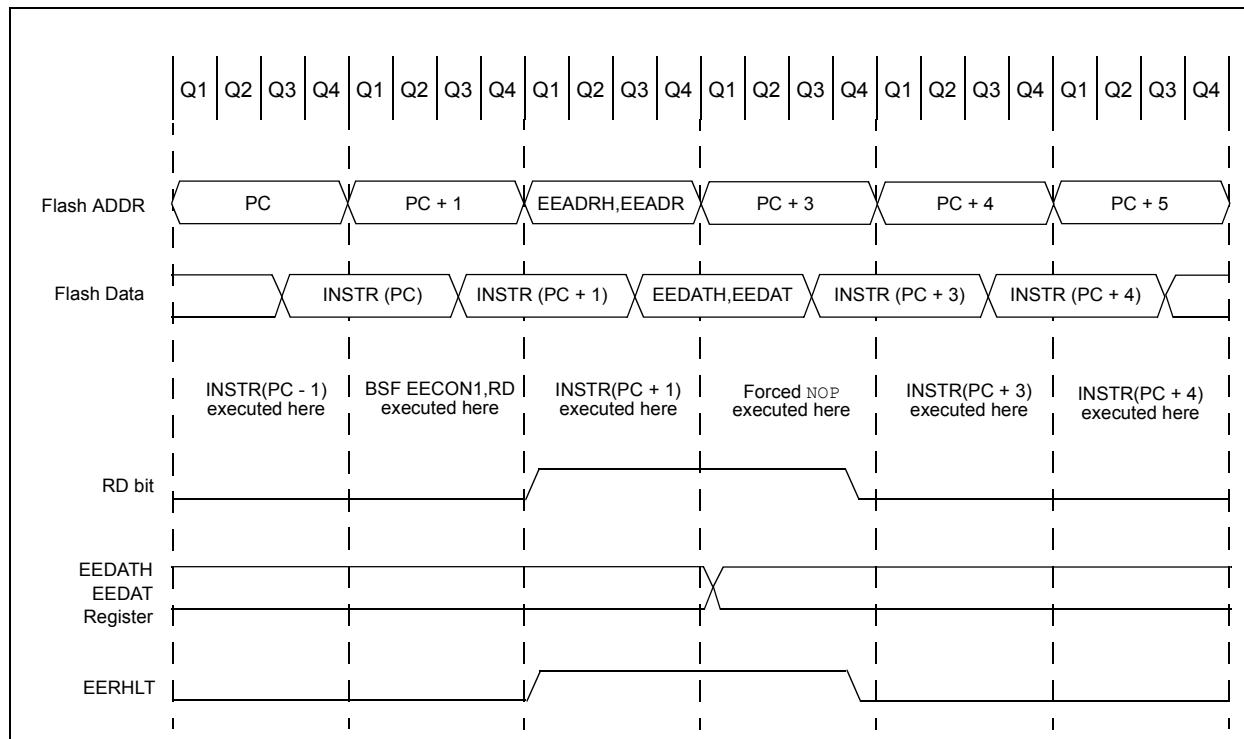
EXAMPLE 10-3: FLASH PROGRAM READ

```
BANKSEL EEADR ;  
MOVLW MS_PROG_EE_ADDR ;  
MOVWF EEADRH ;MS Byte of Program Address to read  
MOVLW LS_PROG_EE_ADDR ;  
MOVWF EEADR ;LS Byte of Program Address to read  
BANKSEL EECON1 ;  
BSF EECON1, EEPGD ;Point to PROGRAM memory  
BSF EECON1, RD ;EE Read  
;  
NOP ;First instruction after BSF EECON1, RD executes normally  
NOP ;Any instructions here are ignored as program  
;memory is read in second cycle after BSF EECON1, RD  
;  
BANKSEL EEDAT ;  
MOVF EEDAT, W ;W = LS Byte of Program Memory  
MOVWF LOWPMBYTE ;  
MOVF EEDATH, W ;W = MS Byte of Program EEDAT  
MOVWF HIGHPMBYTE ;  
BCF STATUS, RP1 ;Bank 0
```

Required Sequence

PIC16F882/883/884/886/887

FIGURE 10-1: FLASH PROGRAM MEMORY READ CYCLE EXECUTION



10.2 Writing to Flash Program Memory

Flash program memory may only be written to if the destination address is in a segment of memory that is not write-protected, as defined in bits WRT<1:0> of the Configuration Word Register 2. Flash program memory must be written in eight-word blocks (four-word blocks for 4K memory devices). See Figures 10-2 and 10-3 for more details. A block consists of eight words with sequential addresses, with a lower boundary defined by an address, where EEADR<2:0> = 000. All block writes to program memory are done as 16-word erase by eight-word write operations. The write operation is edge-aligned and cannot occur across boundaries.

To write program data, it must first be loaded into the buffer registers (see Figure 10-2). This is accomplished by first writing the destination address to EEADR and EEADRH and then writing the data to EEDATA and EEDATH. After the address and data have been set up, then the following sequence of events must be executed:

1. Set the EEPGD control bit of the EECON1 register.
2. Write 55h, then AAh, to EECON2 (Flash programming sequence).
3. Set the WR control bit of the EECON1 register.

All eight buffer register locations should be written to with correct data. If less than eight words are being written to in the block of eight words, then a read from the program memory location(s) not being written to must be performed. This takes the data from the program location(s) not being written and loads it into the EEDATA and EEDATH registers. Then the sequence of events to transfer data to the buffer registers must be executed.

To transfer data from the buffer registers to the program memory, the EEADR and EEADRH must point to the last location in the eight-word block (EEADR<2:0> = 111). Then the following sequence of events must be executed:

1. Set the EEPGD control bit of the EECON1 register.
2. Write 55h, then AAh, to EECON2 (Flash programming sequence).
3. Set control bit WR of the EECON1 register to begin the write operation.

The user must follow the same specific sequence to initiate the write for each word in the program block, writing each program word in sequence (000, 001, 010, 011, 100, 101, 110, 111). When the write is performed on the last word (EEADR<2:0> = 111), a block of sixteen words is automatically erased and the content of the eight word buffer registers are written into the program memory.

After the “BSF EECON1,WR” instruction, the processor requires two cycles to set up the erase/write operation. The user must place two NOP instructions after the WR bit is set. Since data is being written to buffer registers, the writing of the first seven words of the block appears to occur immediately. The processor will halt internal operations for the typical 4 ms, only during the cycle in which the erase takes place (i.e., the last word of the sixteen-word block erase). This is not Sleep mode as the clocks and peripherals will continue to run. After the eight-word write cycle, the processor will resume operation with the third instruction after the EECON1 write instruction. The above sequence must be repeated for the higher eight words.

PIC16F882/883/884/886/887

FIGURE 10-2: BLOCK WRITES TO 2K AND 4K FLASH PROGRAM MEMORY

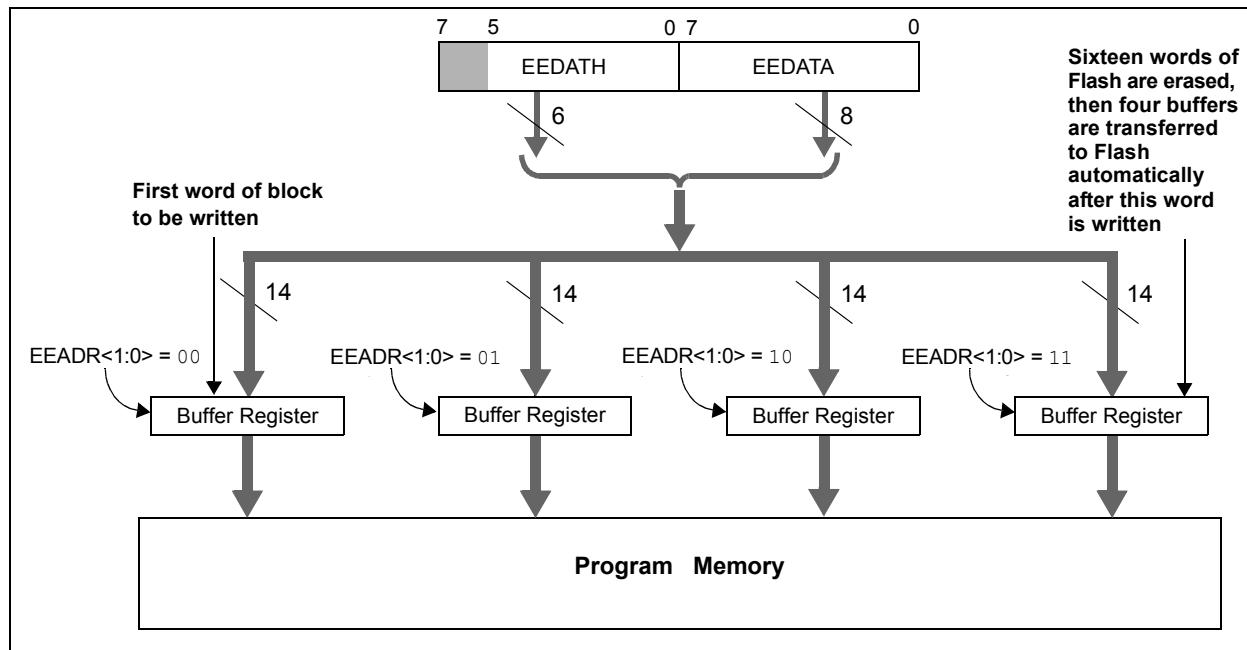
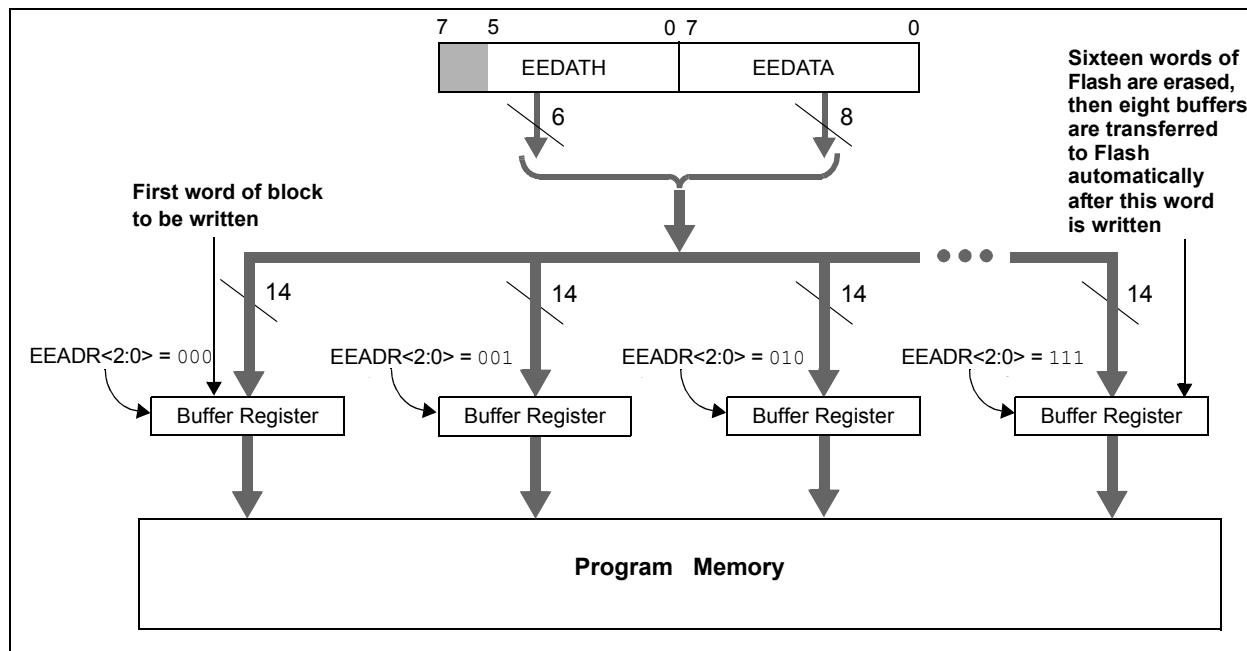


FIGURE 10-3: BLOCK WRITES TO 8K FLASH PROGRAM MEMORY



An example of the complete eight-word write sequence is shown in Example 10-4. The initial address is loaded into the EEADRH and EEADR register pair; the eight words of data are loaded using indirect addressing.

EXAMPLE 10-4: WRITING TO FLASH PROGRAM MEMORY

```
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;  
; This write routine assumes the following:  
; A valid starting address (the least significant bits = '000')  
; is loaded in ADDRH:ADDRL  
; ADDRH, ADDRL and DATAADDR are all located in data memory  
;  
BANKSEL EEADRH  
MOVF ADDRH,W ; Load initial address  
MOVWF EEADRH ;  
MOVF ADDRL,W ;  
MOVWF EEADR ;  
MOVF DATAADDR,W ; Load initial data address  
MOVWF FSR ;  
LOOP MOVF INDF,W ; Load first data byte into lower  
MOVWF EEDATA ;  
INCF FSR,F ; Next byte  
MOVF INDF,W ; Load second data byte into upper  
MOVWF EEDATH ;  
INCF FSR,F ;  
BANKSEL EECON1  
BSF EECON1,EEPGD ; Point to program memory  
BSF EECON1,WREN ; Enable writes  
BCF INTCON,GIE ; Disable interrupts (if using)  
BTFS C INTCON,GIE ; See AN576  
GOTO $-2  
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;  
; Required Sequence  
MOVWL 55h ; Start of required write sequence:  
MOVWF EECON2 ; Write 55h  
MOVWL 0AAh ;  
MOVWF EECON2 ; Write 0AAh  
BSF EECON1,WR ; Set WR bit to begin write  
NOP ; Required to transfer data to the buffer  
NOP ; registers  
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;  
BCF EECON1,WREN ; Disable writes  
BSF INTCON,GIE ; Enable interrupts (comment out if not using interrupts)  
BANKSEL EEADR  
MOVF EEADR, W  
INCF EEADR,F ; Increment address  
ANDLW 0x0F ; Indicates when sixteen words have been programmed  
SUBLW 0x0F ; 0x0F = 16 words  
; 0x0B = 12 words (PIC16F884/883/882 only)  
; 0x07 = 8 words  
; 0x03 = 4 words (PIC16F884/883/882 only)  
BTFS S STATUS,Z ; Exit on a match,  
GOTO LOOP ; Continue if more data needs to be written
```

PIC16F882/883/884/886/887

10.3 Write Verify

Depending on the application, good programming practice may dictate that the value written to the data EEPROM should be verified (see Example 10-5) to the desired value to be written.

EXAMPLE 10-5: WRITE VERIFY

```
BANKSEL EEDAT      ;  
MOVF   EEDAT, W    ;EEDAT not changed  
                  ;from previous write  
BANKSEL EECON1     ;  
BSF    EECON1, RD   ;YES, Read the  
                  ;value written  
BANKSEL EEDAT      ;  
XORWF  EEDAT, W    ;  
BTFS S STATUS, Z    ;Is data the same  
GOTO  WRITE_ERR     ;No, handle error  
:                 ;Yes, continue  
BCF    STATUS, RP1   ;Bank 0
```

When the data memory is code-protected, only the CPU is able to read and write data to the data EEPROM. It is recommended to code-protect the program memory when code-protecting data memory. This prevents anyone from programming zeroes over the existing code (which will execute as NOPs) to reach an added routine, programmed in unused program memory, which outputs the contents of data memory. Programming unused locations in program memory to '0' will also help prevent data memory code protection from becoming breached.

10.3.1 USING THE DATA EEPROM

The data EEPROM is a high-endurance, byte addressable array that has been optimized for the storage of frequently changing information (e.g., program variables or other data that are updated often). When variables in one section change frequently, while variables in another section do not change, it is possible to exceed the total number of write cycles to the EEPROM (specification D124) without exceeding the total number of write cycles to a single byte (specifications D120 and D120A). If this is the case, then a refresh of the array must be performed. For this reason, variables that change infrequently (such as constants, IDs, calibration, etc.) should be stored in Flash program memory.

10.4 Protection Against Spurious Write

There are conditions when the user may not want to write to the data EEPROM memory. To protect against spurious EEPROM writes, various mechanisms have been built in. On power-up, WREN is cleared. Also, the Power-up Timer (64 ms duration) prevents EEPROM write.

The write initiate sequence and the WREN bit together help prevent an accidental write during:

- Brown-out
- Power Glitch
- Software Malfunction

10.5 Data EEPROM Operation During Code-Protect

Data memory can be code-protected by programming the CPD bit in the Configuration Word Register 1 (Register 14-1) to '0'.

PIC16F882/883/884/886/887

TABLE 10-1: SUMMARY OF REGISTERS ASSOCIATED WITH DATA EEPROM

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
EECON1	EEPGD	—	—	—	WRERR	WREN	WR	RD	x--- x000	0--- q000
EECON2	EEPROM Control Register 2 (not a physical register)								-----	-----
EEADR	EEADR7	EEADR6	EEADR5	EEADR4	EEADR3	EEADR2	EEADR1	EEADR0	0000 0000	0000 0000
EEADRH	—	—	—	EEADRH4 ⁽¹⁾	EEADRH3	EEADRH2	EEADRH1	EEADRHO	---0 0000	---0 0000
EEDAT	EEDAT7	EEDAT6	EEDAT5	EEDAT4	EEDAT3	EEDAT2	EEDAT1	EEDAT0	0000 0000	0000 0000
EEDATH	—	—	EEDATH5	EEDATH4	EEDATH3	EEDATH2	EEDATH1	EEDATH0	--00 0000	--00 0000
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	0000 00-0
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	0000 00-0

Legend: x = unknown, u = unchanged, — = unimplemented read as '0', q = value depends upon condition.

Shaded cells are not used by data EEPROM module.

Note 1: PIC16F886/PIC16F887 only.

PIC16F882/883/884/886/887

NOTES:

11.0 CAPTURE/COMPARE/PWM MODULES (CCP1 AND CCP2)

This device contains one Enhanced Capture/Compare/PWM (CCP1) and Capture/Compare/PWM module (CCP2). The CCP1 and CCP2 modules are identical in operation, with the exception of the Enhanced PWM features available on CCP1 only. See **Section 11.6 “PWM (Enhanced Mode)”** for more information.

Note: CCPRx and CCPx throughout this document refer to CCPR1 or CCPR2 and CCP1 or CCP2, respectively.

PIC16F882/883/884/886/887

11.1 Enhanced Capture/Compare/PWM (CCP1)

The Enhanced Capture/Compare/PWM module is a peripheral which allows the user to time and control different events. In Capture mode, the peripheral allows the timing of the duration of an event. The Compare mode allows the user to trigger an external event when a predetermined amount of time has expired. The PWM mode can generate a Pulse-Width Modulated signal of varying frequency and duty cycle.

Table 11-1 shows the timer resources required by the ECCP module.

TABLE 11-1: ECCP MODE – TIMER RESOURCES REQUIRED

ECCP Mode	Timer Resource
Capture	Timer1
Compare	Timer1
PWM	Timer2

REGISTER 11-1: CCP1CON: ENHANCED CCP1 CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0
bit 7	bit 0						

Legend:

R = Readable bit
-n = Value at POR

W = Writable bit
'1' = Bit is set

U = Unimplemented bit, read as '0'
'0' = Bit is cleared
x = Bit is unknown

bit 7-6	P1M<1:0> : PWM Output Configuration bits <u>If CCP1M<3:2> = 00, 01, 10:</u> xx = P1A assigned as Capture/Compare input; P1B, P1C, P1D assigned as port pins <u>If CCP1M<3:2> = 11:</u> 00 = Single output; P1A modulated; P1B, P1C, P1D assigned as port pins 01 = Full-Bridge output forward; P1D modulated; P1A active; P1B, P1C inactive 10 = Half-Bridge output; P1A, P1B modulated with dead-band control; P1C, P1D assigned as port pins 11 = Full-Bridge output reverse; P1B modulated; P1C active; P1A, P1D inactive
bit 5-4	DC1B<1:0> : PWM Duty Cycle Least Significant bits <u>Capture mode:</u> Unused. <u>Compare mode:</u> Unused. <u>PWM mode:</u> These bits are the two LSbs of the PWM duty cycle. The eight MSbs are found in CCPR1L.
bit 3-0	CCP1M<3:0> : ECCP Mode Select bits 0000 = Capture/Compare/PWM off (resets ECCP module) 0001 = Unused (reserved) 0010 = Compare mode, toggle output on match (CCP1IF bit is set) 0011 = Unused (reserved) 0100 = Capture mode, every falling edge 0101 = Capture mode, every rising edge 0110 = Capture mode, every 4th rising edge 0111 = Capture mode, every 16th rising edge 1000 = Compare mode, set output on match (CCP1IF bit is set) 1001 = Compare mode, clear output on match (CCP1IF bit is set) 1010 = Compare mode, generate software interrupt on match (CCP1IF bit is set, CCP1 pin is unaffected) 1011 = Compare mode, trigger special event (CCP1IF bit is set; CCP1 resets TMR1 or TMR2) 1100 = PWM mode; P1A, P1C active-high; P1B, P1D active-high 1101 = PWM mode; P1A, P1C active-high; P1B, P1D active-low 1110 = PWM mode; P1A, P1C active-low; P1B, P1D active-high 1111 = PWM mode; P1A, P1C active-low; P1B, P1D active-low

11.2 Capture/Compare/PWM (CCP2)

The Capture/Compare/PWM module is a peripheral which allows the user to time and control different events. In Capture mode, the peripheral allows the timing of the duration of an event. The Compare mode allows the user to trigger an external event when a predetermined amount of time has expired. The PWM mode can generate a Pulse-Width Modulated signal of varying frequency and duty cycle.

The timer resources used by the module are shown in Table 11-2.

Additional information on CCP modules is available in the Application Note AN594, "Using the CCP Modules" (DS00594).

TABLE 11-2: CCP MODE – TIMER RESOURCES REQUIRED

CCP Mode	Timer Resource
Capture	Timer1
Compare	Timer1
PWM	Timer2

REGISTER 11-2: CCP2CON: CCP2 CONTROL REGISTER

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-4 **DC2B<1:0>:** PWM Duty Cycle Least Significant bits
Capture mode:
Unused.
Compare mode:
Unused.
PWM mode:
These bits are the two LSbs of the PWM duty cycle. The eight MSbs are found in CCPR2L.
- bit 3-0 **CCP2M<3:0>:** CCP2 Mode Select bits
0000 = Capture/Compare/PWM off (resets CCP2 module)
0001 = Unused (reserved)
0010 = Unused (reserved)
0011 = Unused (reserved)
0100 = Capture mode, every falling edge
0101 = Capture mode, every rising edge
0110 = Capture mode, every 4th rising edge
0111 = Capture mode, every 16th rising edge
1000 = Compare mode, set output on match (CCP2IF bit is set)
1001 = Compare mode, clear output on match (CCP2IF bit is set)
1010 = Compare mode, generate software interrupt on match (CCP2IF bit is set, CCP2 pin is unaffected)
1011 = Compare mode, trigger special event (CCP2IF bit is set, TMR1 is reset and A/D conversion is started if the ADC module is enabled. CCP2 pin is unaffected.)
11xx = PWM mode.

11.3 Capture Mode

In Capture mode, the CCPRxH, CCPRxL register pair captures the 16-bit value of the TMR1 register when an event occurs on pin CCPx. An event is defined as one of the following and is configured by the CCP1M<3:0> bits of the CCP1CON register:

- Every falling edge
- Every rising edge
- Every 4th rising edge
- Every 16th rising edge

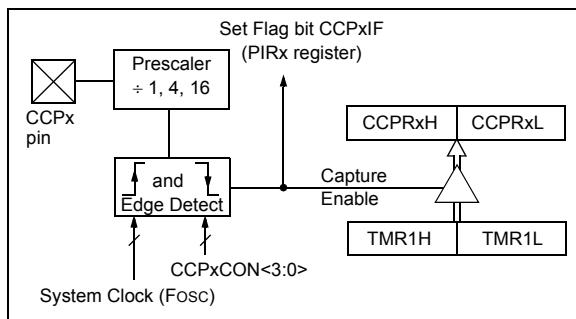
When a capture is made, the Interrupt Request Flag bit CCPxIF of the PIRx register is set. The interrupt flag must be cleared in software. If another capture occurs before the value in the CCPRxH, CCPRxL register pair is read, the old captured value is overwritten by the new captured value (see Figure 11-1).

11.3.1 CCP PIN CONFIGURATION

In Capture mode, the CCPx pin should be configured as an input by setting the associated TRIS control bit.

Note: If the CCPx pin is configured as an output, a write to the port can cause a capture condition.

FIGURE 11-1: CAPTURE MODE OPERATION BLOCK DIAGRAM



11.3.2 TIMER1 MODE SELECTION

Timer1 must be running in Timer mode or Synchronized Counter mode for the CCP module to use the capture feature. In Asynchronous Counter mode, the capture operation may not work.

11.3.3 SOFTWARE INTERRUPT

When the Capture mode is changed, a false capture interrupt may be generated. The user should keep the CCPxIE interrupt enable bit of the PIEx register clear to avoid false interrupts. Additionally, the user should clear the CCPxIF interrupt flag bit of the PIRx register following any change in Operating mode.

11.3.4 CCP PRESCALER

There are four prescaler settings specified by the CCPxM<3:0> bits of the CCPxCON register. Whenever the CCP module is turned off, or the CCP module is not in Capture mode, the prescaler counter is cleared. Any Reset will clear the prescaler counter.

Switching from one capture prescaler to another does not clear the prescaler and may generate a false interrupt. To avoid this unexpected operation, turn the module off by clearing the CCPxCON register before changing the prescaler (see Example 11-1).

EXAMPLE 11-1: CHANGING BETWEEN CAPTURE PRESCALERS

```

BANKSEL CCP1CON ; Set Bank bits to point
                  ; to CCP1CON
CLRF   CCP1CON ; Turn CCP module off
MOVLW NEW_CAPT_PS ; Load the W reg with
                   ; the new prescaler
                   ; move value and CCP ON
MOVWF CCP1CON ; Load CCP1CON with this
               ; value
    
```

11.4 Compare Mode

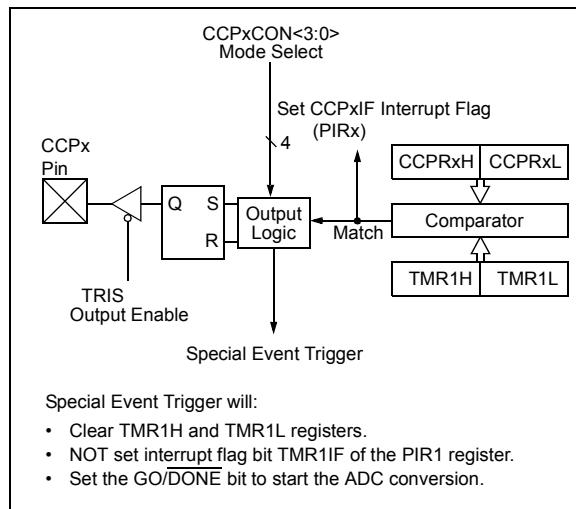
In Compare mode, the 16-bit CCPRx register value is constantly compared against the TMR1 register pair value. When a match occurs, the CCPx module may:

- Toggle the CCPx output
- Set the CCPx output
- Clear the CCPx output
- Generate a Special Event Trigger
- Generate a Software Interrupt

The action on the pin is based on the value of the CCPxM<3:0> control bits of the CCPx1CON register.

All Compare modes can generate an interrupt.

FIGURE 11-2: COMPARE MODE OPERATION BLOCK DIAGRAM



11.4.1 CCP PIN CONFIGURATION

The user must configure the CCPx pin as an output by clearing the associated TRIS bit.

Note: Clearing the CCP1CON register will force the CCPx compare output latch to the default low level. This is not the PORT I/O data latch.

11.4.2 TIMER1 MODE SELECTION

In Compare mode, Timer1 must be running in either Timer mode or Synchronized Counter mode. The compare operation may not work in Asynchronous Counter mode.

11.4.3 SOFTWARE INTERRUPT MODE

When Generate Software Interrupt mode is chosen (CCPxM<3:0> = 1010), the CCPx module does not assert control of the CCPx pin (see the CCP1CON register).

11.4.4 SPECIAL EVENT TRIGGER

When Special Event Trigger mode is chosen (CCPxM<3:0> = 1011), the CCPx module does the following:

- Resets Timer1
- Starts an ADC conversion if ADC is enabled

The CCPx module does not assert control of the CCPx pin in this mode (see the CCPxCON register).

The Special Event Trigger output of the CCP occurs immediately upon a match between the TMR1H, TMR1L register pair and the CCPRxH, CCPRxL register pair. The TMR1H, TMR1L register pair is not reset until the next rising edge of the Timer1 clock. This allows the CCPRxH, CCPRxL register pair to effectively provide a 16-bit programmable period register for Timer1.

Note 1: The Special Event Trigger from the CCP module does not set interrupt flag bit TMRxIF of the PIR1 register.

2: Removing the match condition by changing the contents of the CCPRxH and CCPRxL register pair, between the clock edge that generates the Special Event Trigger and the clock edge that generates the Timer1 Reset, will preclude the Reset from occurring.

PIC16F882/883/884/886/887

11.5 PWM Mode

The PWM mode generates a Pulse-Width Modulated signal on the CCPx pin. The duty cycle, period and resolution are determined by the following registers:

- PR2
- T2CON
- CCPRxL
- CCPxCON

In Pulse-Width Modulation (PWM) mode, the CCP module produces up to a 10-bit resolution PWM output on the CCPx pin. Since the CCPx pin is multiplexed with the PORT data latch, the TRIS for that pin must be cleared to enable the CCPx pin output driver.

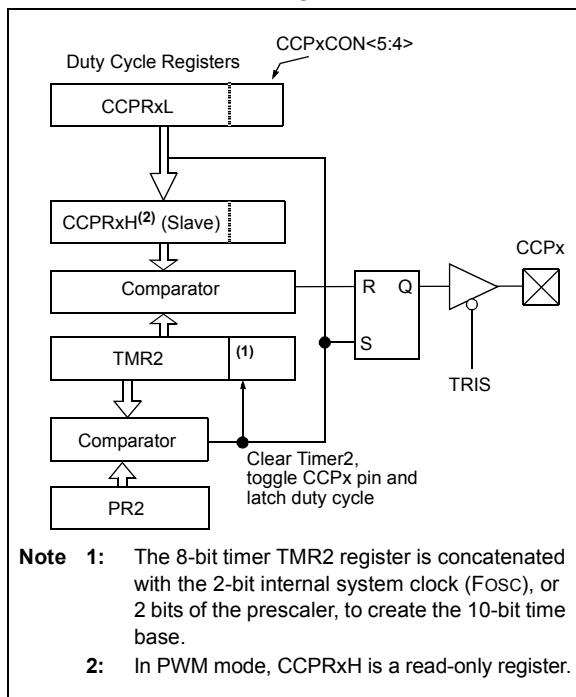
Note: Clearing the CCPxCON register will relinquish CCPx control of the CCPx pin.

Figure 11-3 shows a simplified block diagram of PWM operation.

Figure 11-4 shows a typical waveform of the PWM signal.

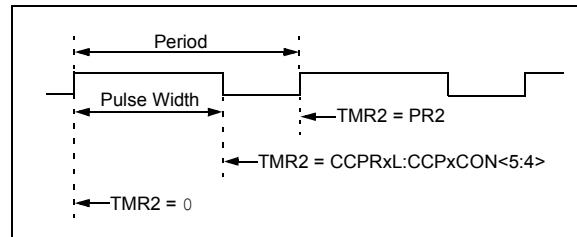
For a step-by-step procedure on how to set up the CCP module for PWM operation, see **Section 11.5.7 “Setup for PWM Operation”**.

FIGURE 11-3: SIMPLIFIED PWM BLOCK DIAGRAM



The PWM output (Figure 11-4) has a time base (period) and a time that the output stays high (duty cycle).

FIGURE 11-4: CCP PWM OUTPUT



11.5.1 PWM PERIOD

The PWM period is specified by the PR2 register of Timer2. The PWM period can be calculated using the formula of Equation 11-1.

EQUATION 11-1: PWM PERIOD

$$\text{PWM Period} = [(PR2) + 1] \cdot 4 \cdot TOSC \cdot (TMR2 \text{ Prescale Value})$$

Note: $TOSC = 1/Fosc$

When TMR2 is equal to PR2, the following three events occur on the next increment cycle:

- TMR2 is cleared
- The CCPx pin is set. (Exception: If the PWM duty cycle = 0%, the pin will not be set.)
- The PWM duty cycle is latched from CCPRxL into CCPRxH.

Note: The Timer2 postscaler (see **Section 7.1 “Timer2 Operation”**) is not used in the determination of the PWM frequency.

11.5.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing a 10-bit value to multiple registers: CCPRxL register and DCxB<1:0> bits of the CCPxCON register. The CCPRxL contains the eight MSbs and the DCxB<1:0> bits of the CCPxCON register contain the two LSbs. CCPRxL and DCxB<1:0> bits of the CCPxCON register can be written to at any time. The duty cycle value is not latched into CCPRxH until after the period completes (i.e., a match between PR2 and TMR2 registers occurs). While using the PWM, the CCPRxH register is read-only.

Equation 11-2 is used to calculate the PWM pulse width.

Equation 11-3 is used to calculate the PWM duty cycle ratio.

EQUATION 11-2: PULSE WIDTH

$$\text{Pulse Width} = (CCPRxL:CCPxCON<5:4>) \cdot TOSC \cdot (TMR2 \text{ Prescale Value})$$

EQUATION 11-3: DUTY CYCLE RATIO

$$\text{Duty Cycle Ratio} = \frac{(CCPRxL:CCPxCON<5:4>)}{4(PR2 + 1)}$$

The CCPRxH register and a 2-bit internal latch are used to double buffer the PWM duty cycle. This double buffering is essential for glitchless PWM operation.

The 8-bit timer TMR2 register is concatenated with either the 2-bit internal system clock (Fosc), or 2 bits of the prescaler, to create the 10-bit time base. The system clock is used if the Timer2 prescaler is set to 1:1.

When the 10-bit time base matches the CCPRxH and 2-bit latch, then the CCPx pin is cleared (see Figure 11-3).

PIC16F882/883/884/886/887

11.5.3 PWM RESOLUTION

The resolution determines the number of available duty cycles for a given period. For example, a 10-bit resolution will result in 1024 discrete duty cycles, whereas an 8-bit resolution will result in 256 discrete duty cycles.

The maximum PWM resolution is 10 bits when PR2 is 255. The resolution is a function of the PR2 register value as shown by Equation 11-4.

EQUATION 11-4: PWM RESOLUTION

$$\text{Resolution} = \frac{\log[4(PR2 + 1)]}{\log(2)} \text{ bits}$$

Note: If the pulse width value is greater than the period the assigned PWM pin(s) will remain unchanged.

TABLE 11-3: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (Fosc = 20 MHz)

PWM Frequency	1.22 kHz	4.88 kHz	19.53 kHz	78.12 kHz	156.3 kHz	208.3 kHz
Timer Prescale (1, 4, 16)	16	4	1	1	1	1
PR2 Value	0xFF	0xFF	0xFF	0x3F	0x1F	0x17
Maximum Resolution (bits)	10	10	10	8	7	6.6

TABLE 11-4: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (Fosc = 8 MHz)

PWM Frequency	1.22 kHz	4.90 kHz	19.61 kHz	76.92 kHz	153.85 kHz	200.0 kHz
Timer Prescale (1, 4, 16)	16	4	1	1	1	1
PR2 Value	0x65	0x65	0x65	0x19	0x0C	0x09
Maximum Resolution (bits)	8	8	8	6	5	5

11.5.4 OPERATION IN SLEEP MODE

In Sleep mode, the TMR2 register will not increment and the state of the module will not change. If the CCPx pin is driving a value, it will continue to drive that value. When the device wakes up, TMR2 will continue from its previous state.

11.5.5 CHANGES IN SYSTEM CLOCK FREQUENCY

The PWM frequency is derived from the system clock frequency. Any changes in the system clock frequency will result in changes to the PWM frequency. See **Section 4.0 “Oscillator Module (With Fail-Safe Clock Monitor)”** for additional details.

11.5.6 EFFECTS OF RESET

Any Reset will force all ports to Input mode and the CCP registers to their Reset states.

11.5.7 SETUP FOR PWM OPERATION

The following steps should be taken when configuring the CCP module for PWM operation:

1. Disable the PWM pin (CCPx) output drivers as an input by setting the associated TRIS bit.
2. Set the PWM period by loading the PR2 register.
3. Configure the CCP module for the PWM mode by loading the CCPxCON register with the appropriate values.
4. Set the PWM duty cycle by loading the CCPRxL register and DCxB<1:0> bits of the CCPxCON register.
5. Configure and start Timer2:
 - Clear the TMR2IF interrupt flag bit of the PIR1 register.
 - Set the Timer2 prescale value by loading the T2CKPS bits of the T2CON register.
 - Enable Timer2 by setting the TMR2ON bit of the T2CON register.
6. Enable PWM output after a new PWM cycle has started:
 - Wait until Timer2 overflows (TMR2IF bit of the PIR1 register is set).
 - Enable the CCPx pin output driver by clearing the associated TRIS bit.

PIC16F882/883/884/886/887

11.6 PWM (Enhanced Mode)

The Enhanced PWM Mode can generate a PWM signal on up to four different output pins with up to 10-bits of resolution. It can do this through four different PWM output modes:

- Single PWM
- Half-Bridge PWM
- Full-Bridge PWM, Forward mode
- Full-Bridge PWM, Reverse mode

To select an Enhanced PWM mode, the P1M bits of the CCP1CON register must be set appropriately.

Note: The PWM Enhanced mode is available on the Enhanced Capture/Compare/PWM module (CCP1) only.

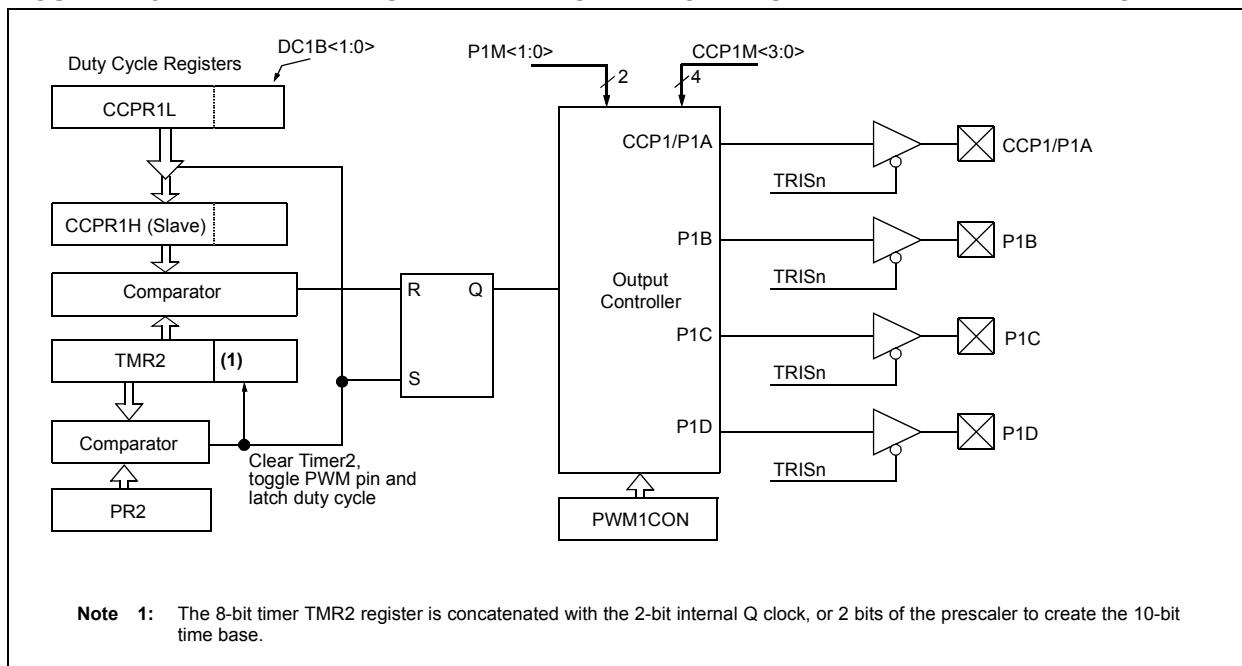
The PWM outputs are multiplexed with I/O pins and are designated P1A, P1B, P1C and P1D. The polarity of the PWM pins is configurable and is selected by setting the CCP1M bits in the CCP1CON register appropriately.

Table 11-5 shows the pin assignments for each Enhanced PWM mode.

Figure 11-5 shows an example of a simplified block diagram of the Enhanced PWM module.

Note: To prevent the generation of an incomplete waveform when the PWM is first enabled, the ECCP module waits until the start of a new PWM period before generating a PWM signal.

FIGURE 11-5: EXAMPLE SIMPLIFIED BLOCK DIAGRAM OF THE ENHANCED PWM MODE



- Note 1:** The TRIS register value for each PWM output must be configured appropriately.
2: Clearing the CCPxCON register will relinquish ECCP control of all PWM output pins.
3: Any pin not used by an Enhanced PWM mode is available for alternate pin functions.

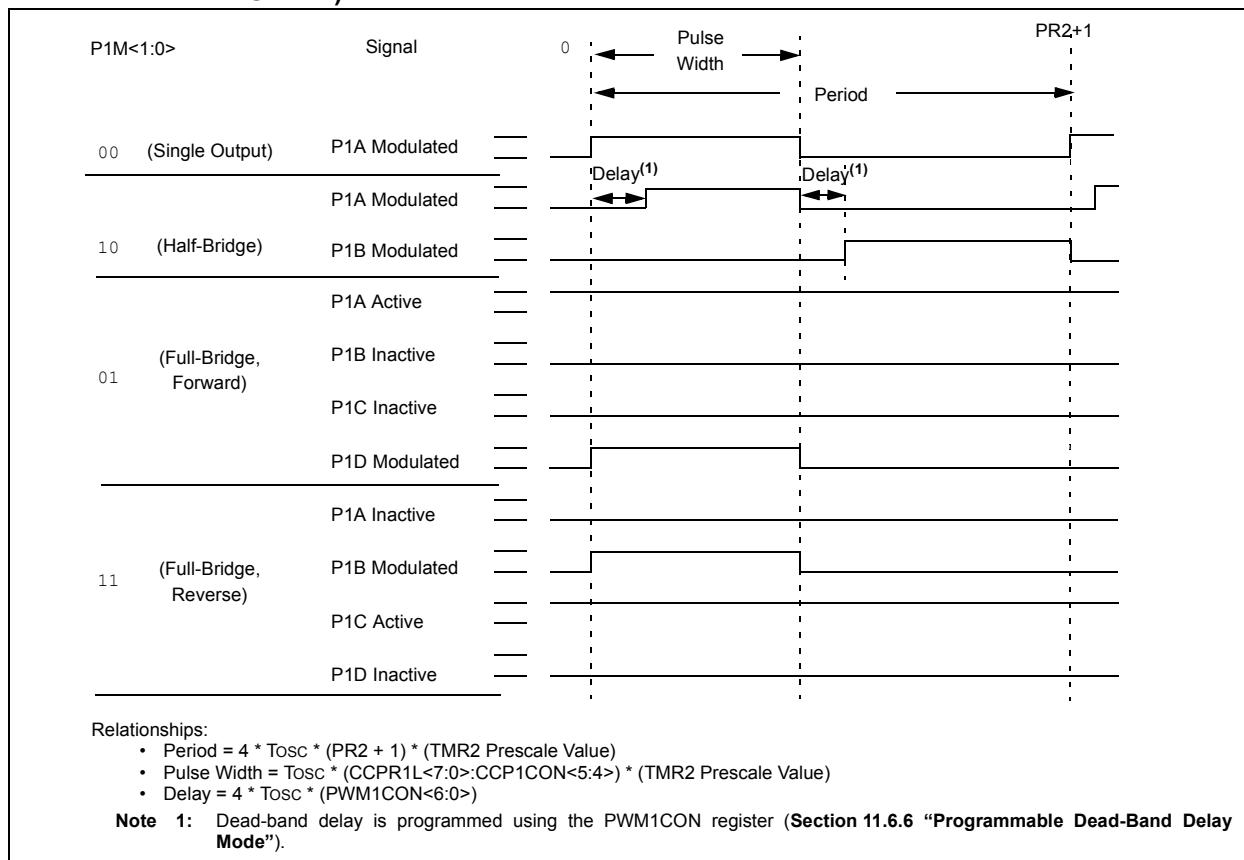
TABLE 11-5: EXAMPLE PIN ASSIGNMENTS FOR VARIOUS PWM ENHANCED MODES

ECCP Mode	P1M<1:0>	CCP1/P1A	P1B	P1C	P1D
Single	00	Yes ⁽¹⁾	Yes ⁽¹⁾	Yes ⁽¹⁾	Yes ⁽¹⁾
Half-Bridge	10	Yes	Yes	No	No
Full-Bridge, Forward	01	Yes	Yes	Yes	Yes
Full-Bridge, Reverse	11	Yes	Yes	Yes	Yes

Note 1: Pulse Steering enables outputs in Single mode.

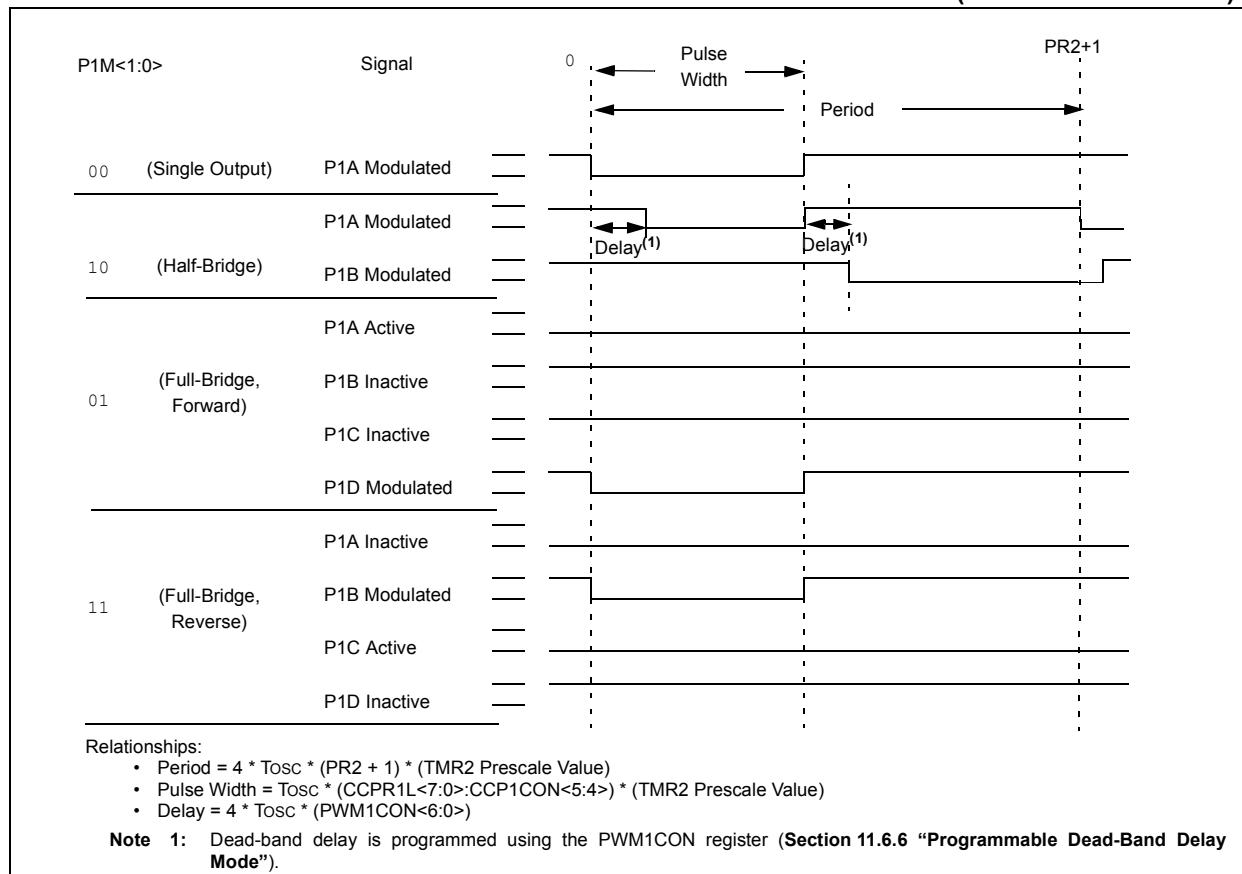
PIC16F882/883/884/886/887

FIGURE 11-6: EXAMPLE PWM (ENHANCED MODE) OUTPUT RELATIONSHIPS (ACTIVE-HIGH STATE)



PIC16F882/883/884/886/887

FIGURE 11-7: EXAMPLE ENHANCED PWM OUTPUT RELATIONSHIPS (ACTIVE-LOW STATE)



11.6.1 HALF-BRIDGE MODE

In Half-Bridge mode, two pins are used as outputs to drive push-pull loads. The PWM output signal is output on the CCPx/P1A pin, while the complementary PWM output signal is output on the P1B pin (see Figure 11-9). This mode can be used for Half-Bridge applications, as shown in Figure 11-9, or for Full-Bridge applications, where four power switches are being modulated with two PWM signals.

In Half-Bridge mode, the programmable dead-band delay can be used to prevent shoot-through current in Half-Bridge power devices. The value of the PDC<6:0> bits of the PWM1CON register sets the number of instruction cycles before the output is driven active. If the value is greater than the duty cycle, the corresponding output remains inactive during the entire cycle. See **Section 11.6.6 “Programmable Dead-Band Delay Mode”** for more details of the dead-band delay operations.

Since the P1A and P1B outputs are multiplexed with the PORT data latches, the associated TRIS bits must be cleared to configure P1A and P1B as outputs.

FIGURE 11-8: EXAMPLE OF HALF-BRIDGE PWM OUTPUT

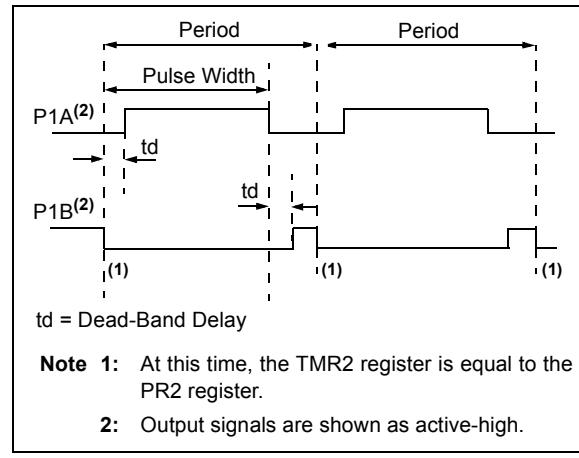
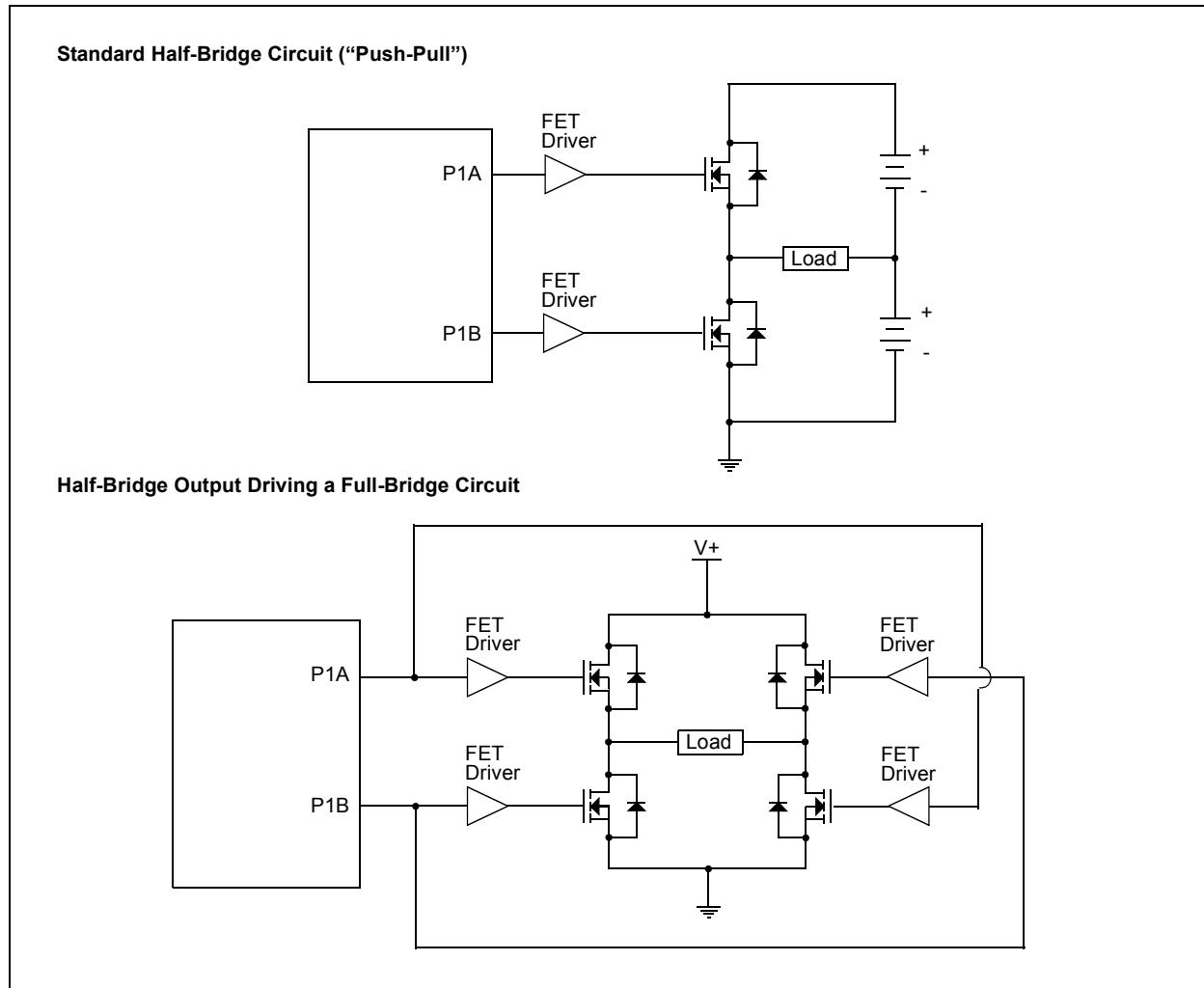


FIGURE 11-9: EXAMPLE OF HALF-BRIDGE APPLICATIONS



PIC16F882/883/884/886/887

11.6.2 FULL-BRIDGE MODE

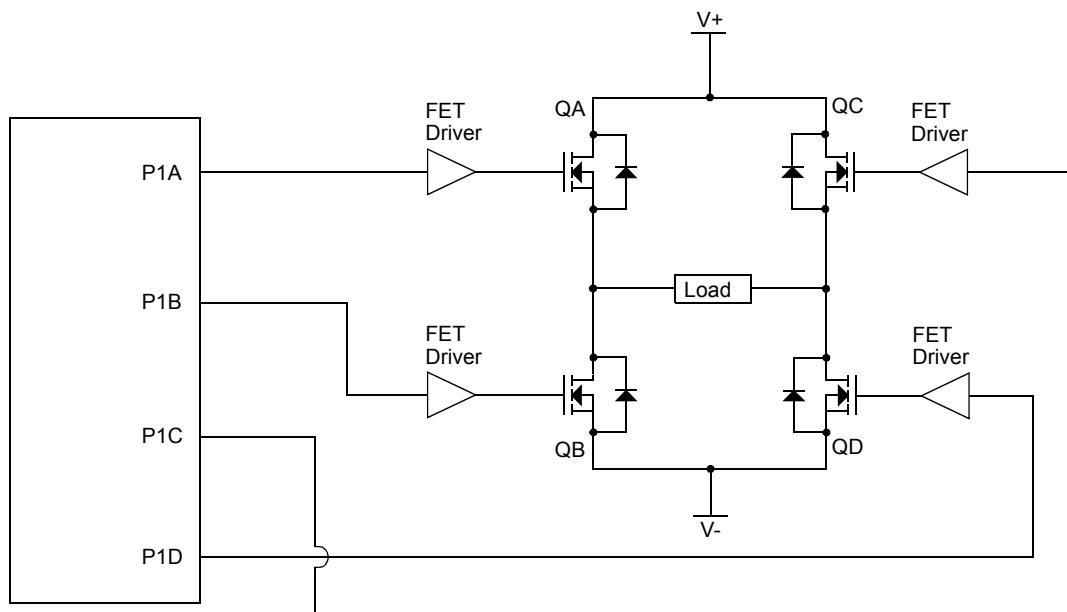
In Full-Bridge mode, all four pins are used as outputs. An example of Full-Bridge application is shown in Figure 11-10.

In the Forward mode, pin CCP1/P1A is driven to its active state, pin P1D is modulated, while P1B and P1C will be driven to their inactive state as shown in Figure 11-11.

In the Reverse mode, P1C is driven to its active state, pin P1B is modulated, while P1A and P1D will be driven to their inactive state as shown Figure 11-11.

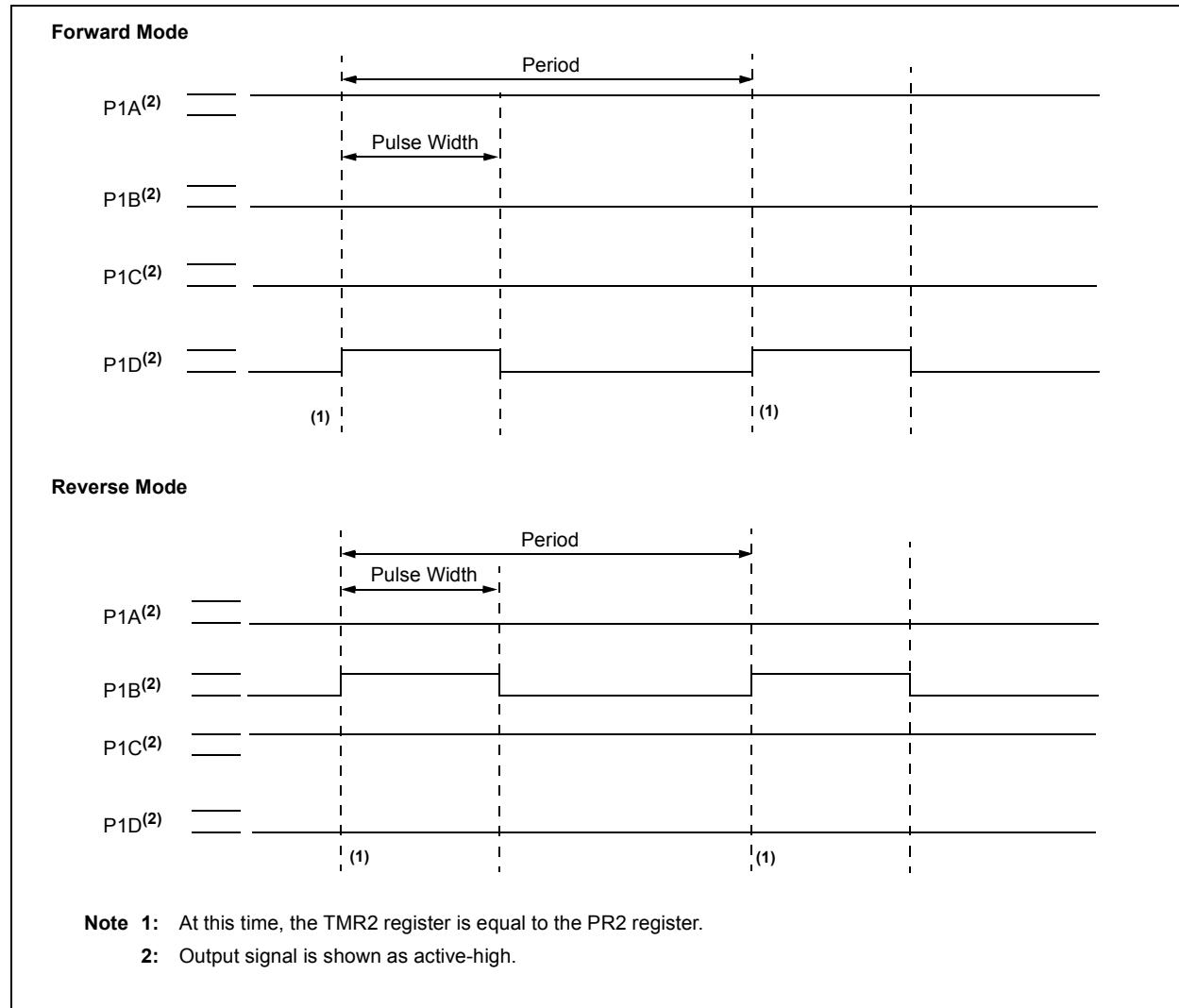
P1A, P1B, P1C and P1D outputs are multiplexed with the PORT data latches. The associated TRIS bits must be cleared to configure the P1A, P1B, P1C and P1D pins as outputs.

FIGURE 11-10: EXAMPLE OF FULL-BRIDGE APPLICATION



PIC16F882/883/884/886/887

FIGURE 11-11: EXAMPLE OF FULL-BRIDGE PWM OUTPUT



PIC16F882/883/884/886/887

11.6.2.1 Direction Change in Full-Bridge Mode

In the Full-Bridge mode, the P1M1 bit in the CCP1CON register allows users to control the forward/reverse direction. When the application firmware changes this direction control bit, the module will change to the new direction on the next PWM cycle.

A direction change is initiated in software by changing the P1M1 bit of the CCP1CON register. The following sequence occurs prior to the end of the current PWM period:

- The modulated outputs (P1B and P1D) are placed in their inactive state.
- The associated unmodulated outputs (P1A and P1C) are switched to drive in the opposite direction.
- PWM modulation resumes at the beginning of the next period.

See Figure 11-12 for an illustration of this sequence.

The Full-Bridge mode does not provide dead-band delay. As one output is modulated at a time, dead-band delay is generally not required. There is a situation where dead-band delay is required. This situation occurs when both of the following conditions are true:

1. The direction of the PWM output changes when the duty cycle of the output is at or near 100%.
2. The turn off time of the power switch, including the power device and driver circuit, is greater than the turn on time.

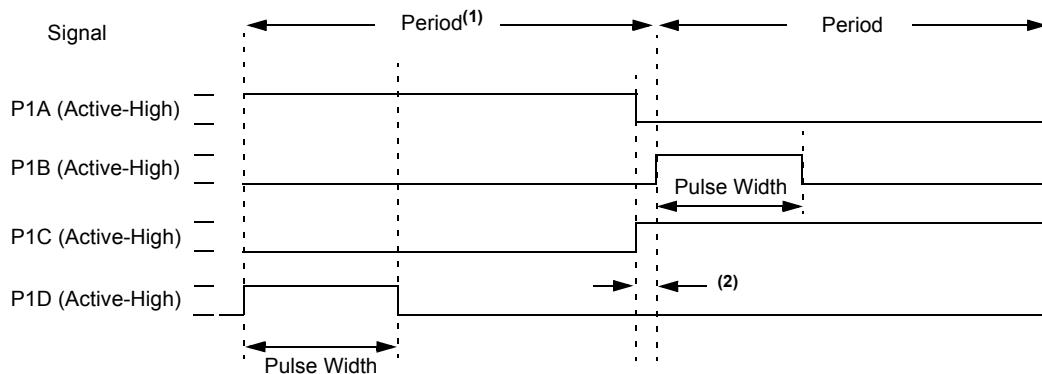
Figure 11-13 shows an example of the PWM direction changing from forward to reverse, at a near 100% duty cycle. In this example, at time t1, the output P1A and P1D become inactive, while output P1C becomes active. Since the turn off time of the power devices is longer than the turn on time, a shoot-through current will flow through power devices QC and QD (see Figure 11-10) for the duration of 't'. The same phenomenon will occur to power devices QA and QB for PWM direction change from reverse to forward.

If changing PWM direction at high duty cycle is required for an application, two possible solutions for eliminating the shoot-through current are:

1. Reduce PWM duty cycle for one PWM period before changing directions.
2. Use switch drivers that can drive the switches off faster than they can drive them on.

Other options to prevent shoot-through current may exist.

FIGURE 11-12: EXAMPLE OF PWM DIRECTION CHANGE

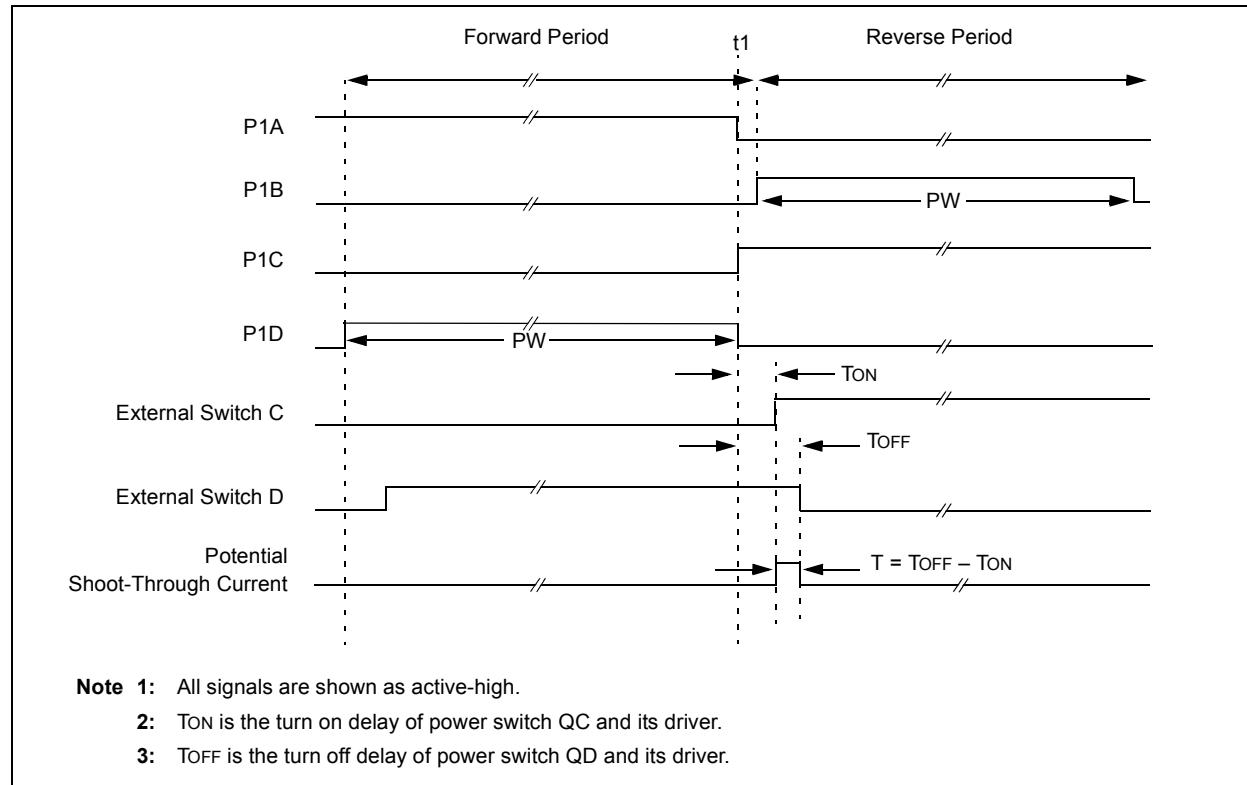


Note 1: The direction bit P1M1 of the CCP1CON register is written any time during the PWM cycle.

2: When changing directions, the P1A and P1C signals switch before the end of the current PWM cycle. The modulated P1B and P1D signals are inactive at this time. The length of this time is $(1/Fosc) \cdot TMR2$ prescale value.

PIC16F882/883/884/886/887

FIGURE 11-13: EXAMPLE OF PWM DIRECTION CHANGE AT NEAR 100% DUTY CYCLE



PIC16F882/883/884/886/887

11.6.3 START-UP CONSIDERATIONS

When any PWM mode is used, the application hardware must use the proper external pull-up and/or pull-down resistors on the PWM output pins.

Note: When the microcontroller is released from Reset, all of the I/O pins are in the high-impedance state. The external circuits must keep the power switch devices in the Off state until the microcontroller drives the I/O pins with the proper signal levels or activates the PWM output(s).

The CCP1M<1:0> bits of the CCP1CON register allow the user to choose whether the PWM output signals are active-high or active-low for each pair of PWM output pins (P1A/P1C and P1B/P1D). The PWM output polarities must be selected before the PWM pin output drivers are enabled. Changing the polarity configuration while the PWM pin output drivers are enable is not recommended since it may result in damage to the application circuits.

The P1A, P1B, P1C and P1D output latches may not be in the proper states when the PWM module is initialized. Enabling the PWM pin output drivers at the same time as the Enhanced PWM modes may cause damage to the application circuit. The Enhanced PWM modes must be enabled in the proper Output mode and complete a full PWM cycle before enabling the PWM pin output drivers. The completion of a full PWM cycle is indicated by the TMR2IF bit of the PIR1 register being set as the second PWM period begins.

11.6.4 ENHANCED PWM AUTO-SHUTDOWN MODE

The PWM mode supports an Auto-Shutdown mode that will disable the PWM outputs when an external shutdown event occurs. Auto-Shutdown mode places the PWM output pins into a predetermined state. This mode is used to help prevent the PWM from damaging the application.

The auto-shutdown sources are selected using the ECCPAS<2:0> bits of the ECCPAS register. A shutdown event may be generated by:

- A logic '0' on the INT pin
- Comparator C1
- Comparator C2
- Setting the ECCPASE bit in firmware

A shutdown condition is indicated by the ECCPASE (Auto-Shutdown Event Status) bit of the ECCPAS register. If the bit is a '0', the PWM pins are operating normally. If the bit is a '1', the PWM outputs are in the shutdown state.

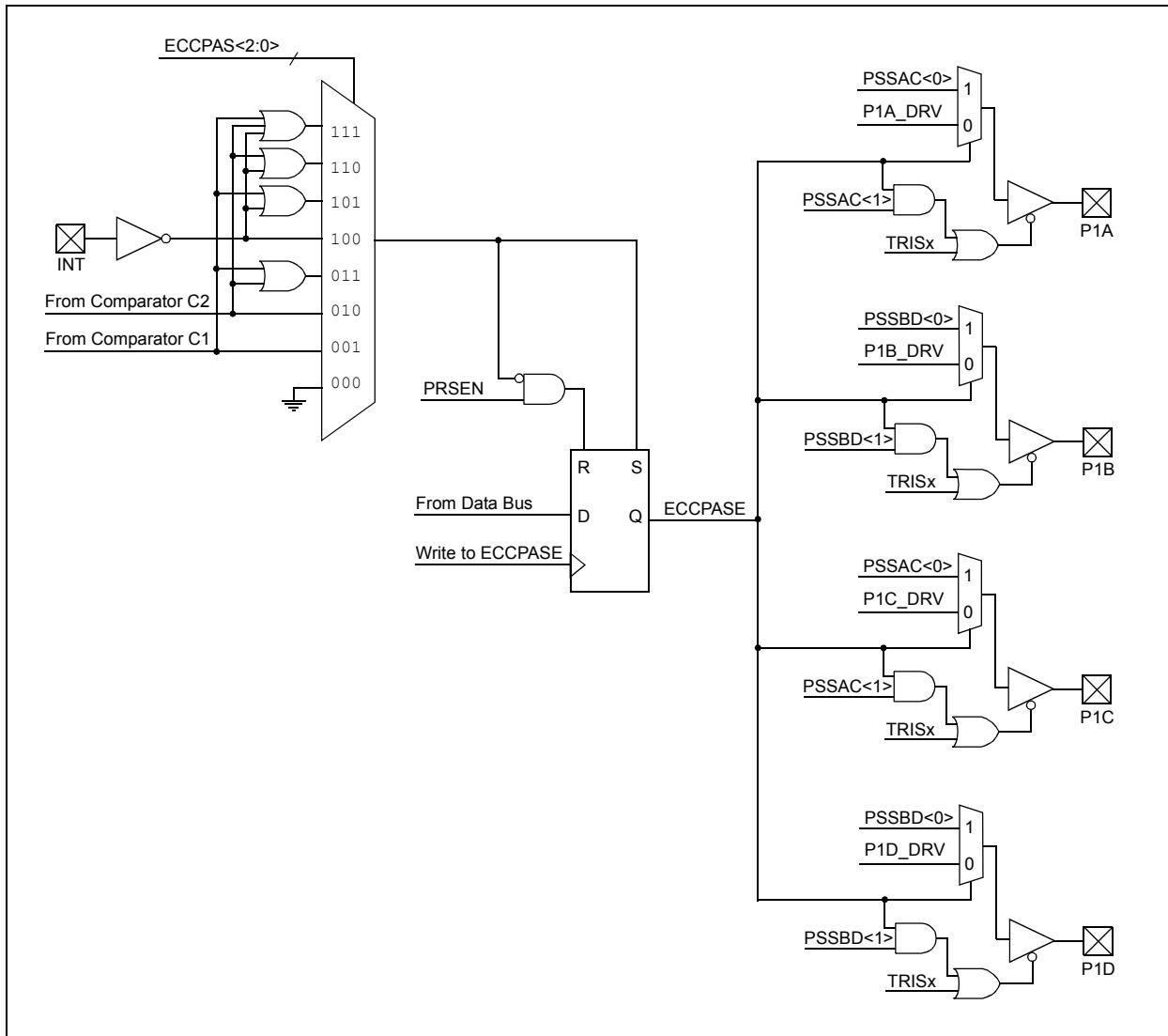
When a shutdown event occurs, two things happen:

The ECCPASE bit is set to '1'. The ECCPASE will remain set until cleared in firmware or an auto-restart occurs (see **Section 11.6.5 "Auto-Restart Mode"**).

The enabled PWM pins are asynchronously placed in their shutdown states. The PWM output pins are grouped into pairs [P1A/P1C] and [P1B/P1D]. The state of each pin pair is determined by the PSSAC and PSSBD bits of the ECCPAS register. Each pin pair may be placed into one of three states:

- Drive logic '1'
- Drive logic '0'
- Tri-state (high-impedance)

FIGURE 11-14: AUTO-SHUTDOWN BLOCK DIAGRAM



PIC16F882/883/884/886/887

REGISTER 11-3: ECCPAS: ENHANCED CAPTURE/COMPARE/PWM AUTO-SHUTDOWN CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ECCPASE	ECCPAS2	ECCPAS1	ECCPAS0	PSSAC1	PSSAC0	PSSBD1	PSSBD0	
bit 7								bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7

ECCPASE: ECCP Auto-Shutdown Event Status bit

- 1 = A shutdown event has occurred; ECCP outputs are in shutdown state
0 = ECCP outputs are operating

bit 6-4

ECCPAS<2:0>: ECCP Auto-shutdown Source Select bits

- 000 = Auto-Shutdown is disabled
001 = Comparator C1 output high
010 = Comparator C2 output high⁽¹⁾
011 = Either Comparators output is high
100 = VIL on INT pin
101 = VIL on INT pin or Comparator C1 output high
110 = VIL on INT pin or Comparator C2 output high
111 =VIL on INT pin or either Comparators output is high

bit 3-2

PSSACn: Pins P1A and P1C Shutdown State Control bits

- 00 = Drive pins P1A and P1C to '0'
01 = Drive pins P1A and P1C to '1'
1x = Pins P1A and P1C tri-state

bit 1-0

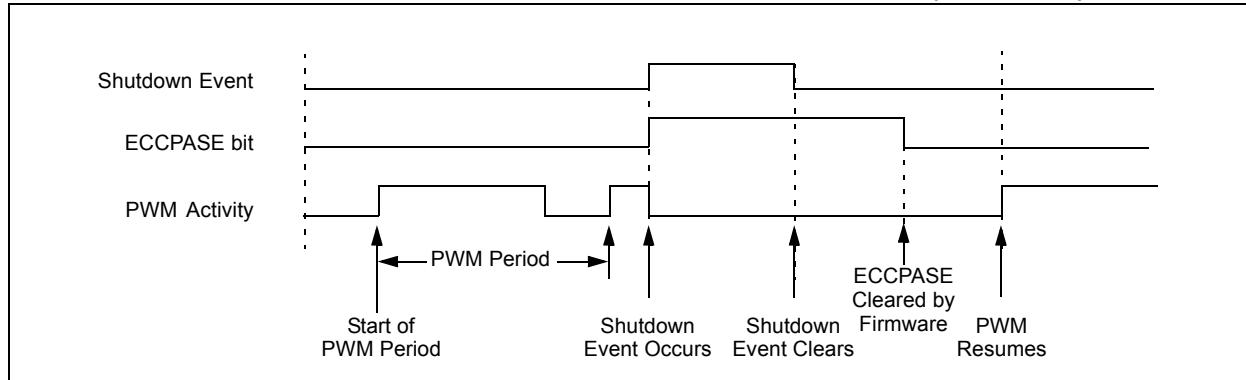
PSSBDn: Pins P1B and P1D Shutdown State Control bits

- 00 = Drive pins P1B and P1D to '0'
01 = Drive pins P1B and P1D to '1'
1x = Pins P1B and P1D tri-state

Note 1: If C2SYNC is enabled, the shutdown will be delayed by Timer1.

- Note 1:** The auto-shutdown condition is a level-based signal, not an edge-based signal. As long as the level is present, the auto-shutdown will persist.
- 2:** Writing to the ECCPASE bit is disabled while an auto-shutdown condition persists.
- 3:** Once the auto-shutdown condition has been removed and the PWM restarted (either through firmware or auto-restart) the PWM signal will always restart at the beginning of the next PWM period.

FIGURE 11-15: PWM AUTO-SHUTDOWN WITH FIRMWARE RESTART (PRSEN = 0)

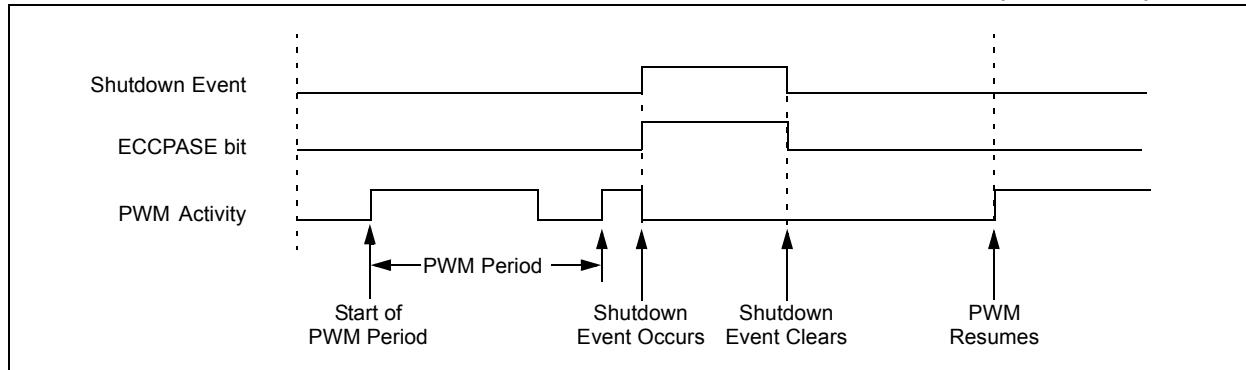


11.6.5 AUTO-RESTART MODE

The Enhanced PWM can be configured to automatically restart the PWM signal once the auto-shutdown condition has been removed. Auto-restart is enabled by setting the PRSEN bit in the PWM1CON register.

If auto-restart is enabled, the ECCPASE bit will remain set as long as the auto-shutdown condition is active. When the auto-shutdown condition is removed, the ECCPASE bit will be cleared via hardware and normal operation will resume.

FIGURE 11-16: PWM AUTO-SHUTDOWN WITH AUTO-RESTART ENABLED (PRSEN = 1)



PIC16F882/883/884/886/887

11.6.6 PROGRAMMABLE DEAD-BAND DELAY MODE

In Half-Bridge applications where all power switches are modulated at the PWM frequency, the power switches normally require more time to turn off than to turn on. If both the upper and lower power switches are switched at the same time (one turned on, and the other turned off), both switches may be on for a short period of time until one switch completely turns off. During this brief interval, a very high current (*shoot-through current*) will flow through both power switches, shorting the bridge supply. To avoid this potentially destructive shoot-through current from flowing during switching, turning on either of the power switches is normally delayed to allow the other switch to completely turn off.

In Half-Bridge mode, a digitally programmable dead-band delay is available to avoid shoot-through current from destroying the bridge power switches. The delay occurs at the signal transition from the non-active state to the active state. See Figure 11-17 for illustration. The lower seven bits of the associated PWM1CON register (Register 11-4) sets the delay period in terms of microcontroller instruction cycles (Tcy or 4 Tosc).

FIGURE 11-17: EXAMPLE OF HALF-BRIDGE PWM OUTPUT

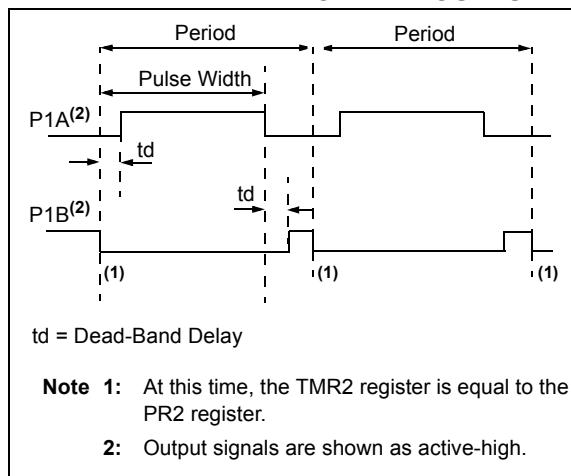
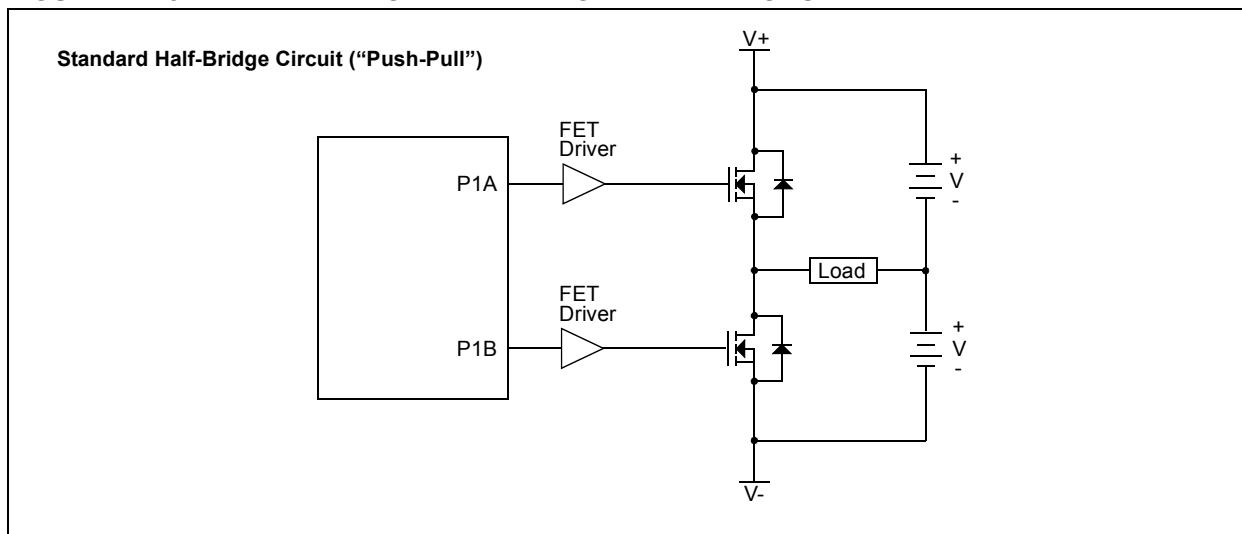


FIGURE 11-18: EXAMPLE OF HALF-BRIDGE APPLICATIONS



PIC16F882/883/884/886/887

REGISTER 11-4: PWM1CON: ENHANCED PWM CONTROL REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PRSEN | PDC6 | PDC5 | PDC4 | PDC3 | PDC2 | PDC1 | PDC0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **PRSEN:** PWM Restart Enable bit

1 = Upon auto-shutdown, the ECCPASE bit clears automatically once the shutdown event goes away; the PWM restarts automatically
0 = Upon auto-shutdown, ECCPASE must be cleared in software to restart the PWM

bit 6-0 **PDC<6:0>:** PWM Delay Count bits

PDCn = Number of Fosc/4 (4 * Tosc) cycles between the scheduled time when a PWM signal **should** transition active and the **actual** time it transitions active.

PIC16F882/883/884/886/887

11.6.7 PULSE STEERING MODE

In Single Output mode, pulse steering allows any of the PWM pins to be the modulated signal. Additionally, the same PWM signal can be simultaneously available on multiple pins.

Once the Single Output mode is selected ($\text{CCP1M}\langle 3:2 \rangle = 11$ and $\text{P1M}\langle 1:0 \rangle = 00$ of the CCP1CON register), the user firmware can bring out the same PWM signal to one, two, three or four output pins by setting the appropriate $\text{STR}\langle D:A \rangle$ bits of the PSTRCON register, as shown in Table 11-5.

Note: The associated TRIS bits must be set to output ('0') to enable the pin output driver in order to see the PWM signal on the pin.

While the PWM Steering mode is active, CCP1M<1:0> bits of the CCP1CON register select the PWM output polarity for the P1<D:A> pins.

The PWM auto-shutdown operation also applies to PWM Steering mode as described in **Section 11.6.4 “Enhanced PWM Auto-shutdown mode”**. An auto-shutdown event will only affect pins that have PWM outputs enabled.

REGISTER 11-5: PSTRCON: PULSE STEERING CONTROL REGISTER⁽¹⁾

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
—	—	—	STRSYNC	STRD	STRC	STRB	STRA
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **STRSYNC:** Steering Sync bit

1 = Output steering update occurs on next PWM period

0 = Output steering update occurs at the beginning of the instruction cycle boundary

bit 3 **STRD:** Steering Enable bit D

1 = P1D pin has the PWM waveform with polarity control from CCPxM<1:0>

0 = P1D pin is assigned to port pin

bit 2 **STRC:** Steering Enable bit C

1 = P1C pin has the PWM waveform with polarity control from CCPxM<1:0>

0 = P1C pin is assigned to port pin

bit 1 **STRB:** Steering Enable bit B

1 = P1B pin has the PWM waveform with polarity control from CCPxM<1:0>

0 = P1B pin is assigned to port pin

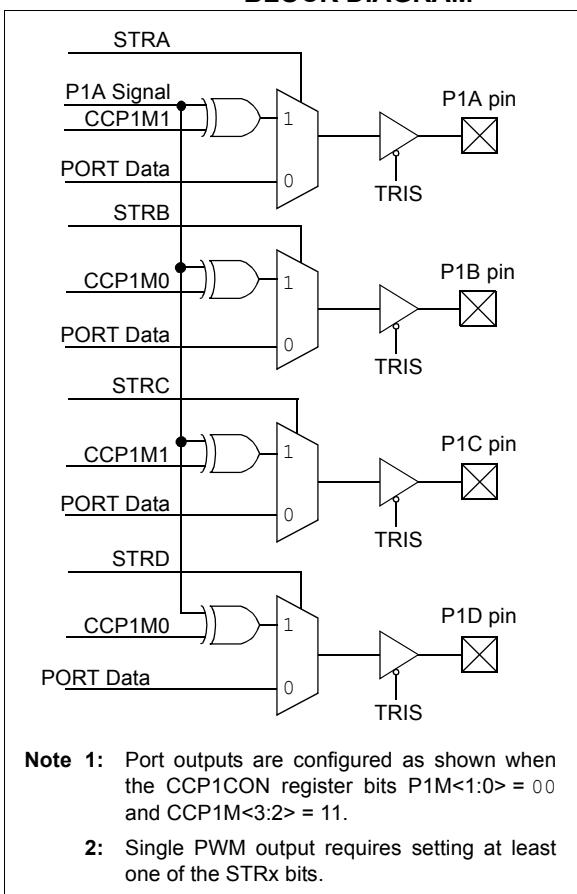
bit 0 **STRA:** Steering Enable bit A

1 = P1A pin has the PWM waveform with polarity control from CCPxM<1:0>

0 = P1A pin is assigned to port pin

Note 1: The PWM Steering mode is available only when the CCP1CON register bits CCP1M<3:2> = 11 and P1M<1:0> = 00.

FIGURE 11-19: SIMPLIFIED STEERING BLOCK DIAGRAM



PIC16F882/883/884/886/887

11.6.7.1 Steering Synchronization

The STRSYNC bit of the PSTRCON register gives the user two selections of when the steering event will happen. When the STRSYNC bit is '0', the steering event will happen at the end of the instruction that writes to the PSTRCON register. In this case, the output signal at the P1<D:A> pins may be an incomplete PWM waveform. This operation is useful when the user firmware needs to immediately remove a PWM signal from the pin.

When the STRSYNC bit is '1', the effective steering update will happen at the beginning of the next PWM period. In this case, steering on/off the PWM output will always produce a complete PWM waveform.

Figures 11-20 and 11-21 illustrate the timing diagrams of the PWM steering depending on the STRSYNC setting.

FIGURE 11-20: EXAMPLE OF STEERING EVENT AT END OF INSTRUCTION (STRSYNC = 0)

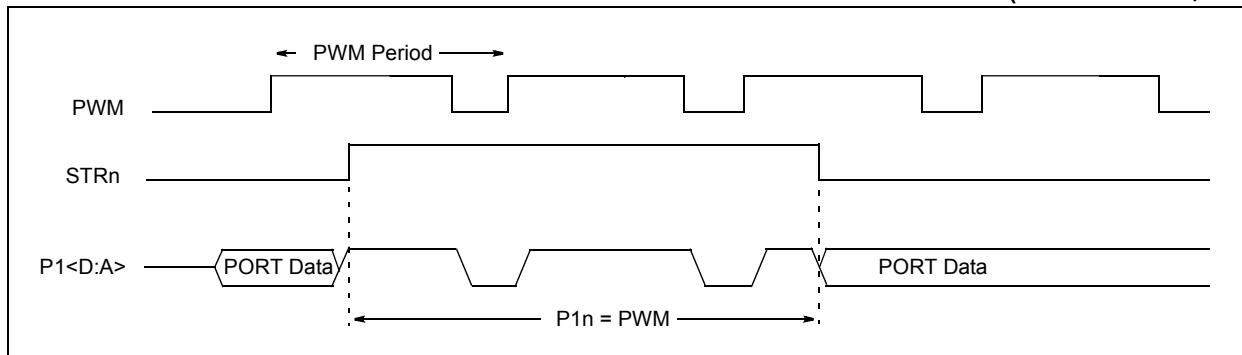
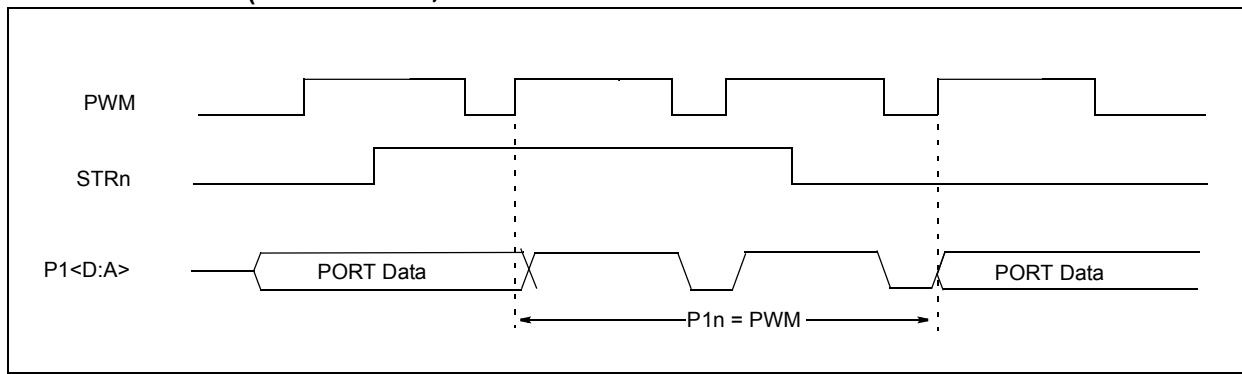


FIGURE 11-21: EXAMPLE OF STEERING EVENT AT BEGINNING OF INSTRUCTION (STRSYNC = 1)



PIC16F882/883/884/886/887

TABLE 11-6: REGISTERS ASSOCIATED WITH CAPTURE, COMPARE AND TIMER1

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
CCP1CON	P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	0000 0000	0000 0000
CCP2CON	—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	--00 0000	--00 0000
CCPR1L	Capture/Compare/PWM Register 1 Low Byte (LSB)								xxxx xxxx	xxxx xxxx
CCPR1H	Capture/Compare/PWM Register 1 High Byte (MSB)								xxxx xxxx	xxxx xxxx
CCPR2L	Capture/Compare/PWM Register 2 Low Byte (LSB)								xxxx xxxx	xxxx xxxx
CCPR2H	Capture/Compare/PWM Register 2 High Byte (MSB)								xxxx xxxx	xxxx xxxx
CM2CON1	MC1OUT	MC2OUT	C1RSEL	C2RSEL	—	—	T1GSS	C2SYNC	0000 --10	0000 --10
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	0000 00-0
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	0000 00-0
T1CON	T1GINV	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR1ON	0000 0000	0000 0000
TMR1L	Holding Register for the Least Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	xxxx xxxx
TMR1H	Holding Register for the Most Significant Byte of the 16-bit TMR1 Register								xxxx xxxx	xxxx xxxx
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111

Legend: — = Unimplemented locations, read as '0', u = unchanged, x = unknown. Shaded cells are not used by the Capture and Compare.

TABLE 11-7: REGISTERS ASSOCIATED WITH PWM AND TIMER2

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
CCP1CON	P1M1	P1M0	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	0000 0000	0000 0000
CCP2CON	—	—	DC2B1	DC2B0	CCP2M3	CCP2M2	CCP2M1	CCP2M0	--00 0000	--00 0000
ECCPAS	ECCPASE	ECCPAS2	ECCPAS1	ECCPAS0	PSSAC1	PSSAC0	PSSBD1	PSSBD0	0000 0000	0000 0000
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PR2	Timer2 Period Register								1111 1111	1111 1111
PSTRCON	—	—	—	STRSYNC	STRD	STRC	STRB	STRA	--0 0001	--0 0001
PWM1CON	PRSEN	PDC6	PDC5	PDC4	PDC3	PDC2	PDC1	PDC0	0000 0000	0000 0000
T2CON	—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0	-000 0000	-000 0000
TMR2	Timer2 Module Register								0000 0000	0000 0000
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	1111 1111	1111 1111
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TRISD	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	1111 1111	1111 1111

Legend: — = Unimplemented locations, read as '0', u = unchanged, x = unknown. Shaded cells are not used by the PWM.

PIC16F882/883/884/886/887

NOTES:

12.0 ENHANCED UNIVERSAL SYNCHRONOUS ASYNCHRONOUS RECEIVER TRANSMITTER (EUSART)

The Enhanced Universal Synchronous Asynchronous Receiver Transmitter (EUSART) module is a serial I/O communications peripheral. It contains all the clock generators, shift registers and data buffers necessary to perform an input or output serial data transfer independent of device program execution. The EUSART, also known as a Serial Communications Interface (SCI), can be configured as a full-duplex asynchronous system or half-duplex synchronous system. Full-Duplex mode is useful for communications with peripheral systems, such as CRT terminals and personal computers. Half-Duplex Synchronous mode is intended for communications with peripheral devices, such as A/D or D/A integrated circuits, serial EEPROMs or other microcontrollers. These devices typically do not have internal clocks for baud rate generation and require the external clock signal provided by a master synchronous device.

The EUSART module includes the following capabilities:

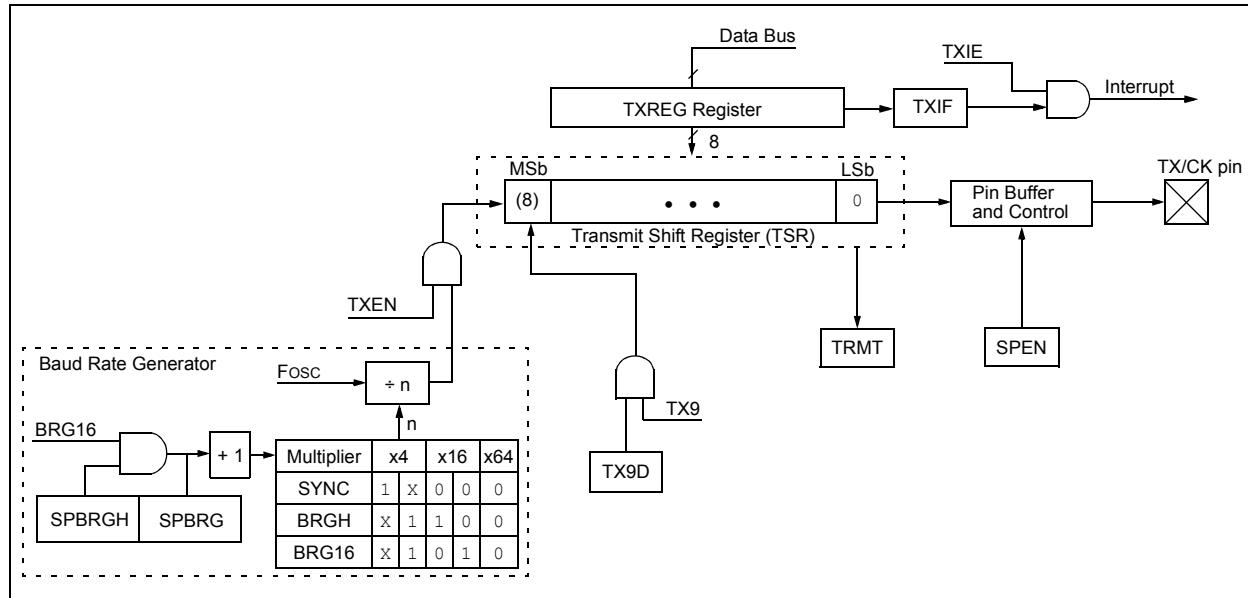
- Full-duplex asynchronous transmit and receive
- Two-character input buffer
- One-character output buffer
- Programmable 8-bit or 9-bit character length
- Address detection in 9-bit mode
- Input buffer overrun error detection
- Received character framing error detection
- Half-duplex synchronous master
- Half-duplex synchronous slave
- Programmable clock polarity in synchronous modes
- Sleep operation

The EUSART module implements the following additional features, making it ideally suited for use in Local Interconnect Network (LIN) bus systems:

- Automatic detection and calibration of the baud rate
- Wake-up on Break reception
- 13-bit Break character transmit

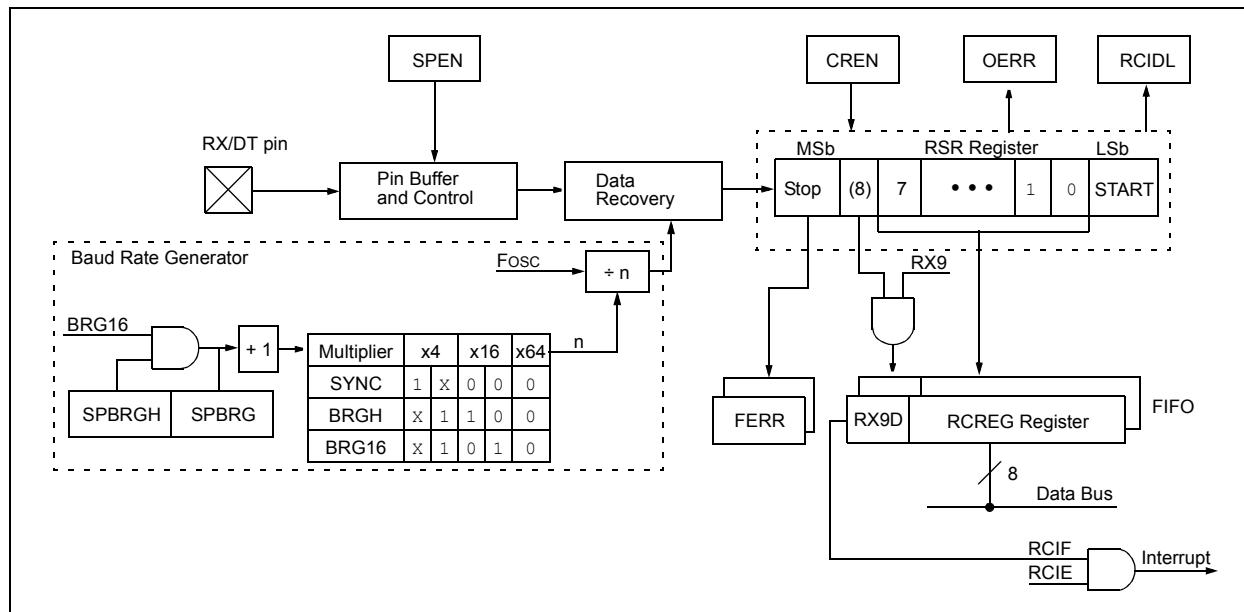
Block diagrams of the EUSART transmitter and receiver are shown in Figure 12-1 and Figure 12-2.

FIGURE 12-1: EUSART TRANSMIT BLOCK DIAGRAM



PIC16F882/883/884/886/887

FIGURE 12-2: EUSART RECEIVE BLOCK DIAGRAM



The operation of the EUSART module is controlled through three registers:

- Transmit Status and Control (TXSTA)
- Receive Status and Control (RCSTA)
- Baud Rate Control (BAUDCTL)

These registers are detailed in Register 12-1, Register 12-2 and Register 12-3, respectively.

12.1 EUSART Asynchronous Mode

The EUSART transmits and receives data using the standard non-return-to-zero (NRZ) format. NRZ is implemented with two levels: a VOH mark state which represents a '1' data bit, and a VOL space state which represents a '0' data bit. NRZ refers to the fact that consecutively transmitted data bits of the same value stay at the output level of that bit without returning to a neutral level between each bit transmission. An NRZ transmission port idles in the mark state. Each character transmission consists of one Start bit followed by eight or nine data bits and is always terminated by one or more Stop bits. The Start bit is always a space and the Stop bits are always marks. The most common data format is 8 bits. Each transmitted bit persists for a period of 1/(Baud Rate). An on-chip dedicated 8-bit/16-bit Baud Rate Generator is used to derive standard baud rate frequencies from the system oscillator. See Table 12-5 for examples of baud rate configurations.

The EUSART transmits and receives the LSb first. The EUSART's transmitter and receiver are functionally independent, but share the same data format and baud rate. Parity is not supported by the hardware, but can be implemented in software and stored as the ninth data bit.

12.1.1 EUSART ASYNCHRONOUS TRANSMITTER

The EUSART transmitter block diagram is shown in Figure 12-1. The heart of the transmitter is the serial Transmit Shift Register (TSR), which is not directly accessible by software. The TSR obtains its data from the transmit buffer, which is the TXREG register.

12.1.1.1 Enabling the Transmitter

The EUSART transmitter is enabled for asynchronous operations by configuring the following three control bits:

- TXEN = 1
- SYNC = 0
- SPEN = 1

All other EUSART control bits are assumed to be in their default state.

Setting the TXEN bit of the TXSTA register enables the transmitter circuitry of the EUSART. Clearing the SYNC bit of the TXSTA register configures the EUSART for asynchronous operation. Setting the SPEN bit of the RCSTA register enables the EUSART and automatically configures the TX/CK I/O pin as an output. If the TX/CK pin is shared with an analog peripheral the analog I/O function must be disabled by clearing the corresponding ANSEL bit.

Note 1: When the SPEN bit is set the RX/DT I/O pin is automatically configured as an input, regardless of the state of the corresponding TRIS bit and whether or not the EUSART receiver is enabled. The RX/DT pin data can be read via a normal PORT read but PORT latch data output is precluded.

2: The TXIF transmitter interrupt flag is set when the TXEN enable bit is set.

12.1.1.2 Transmitting Data

A transmission is initiated by writing a character to the TXREG register. If this is the first character, or the previous character has been completely flushed from the TSR, the data in the TXREG is immediately transferred to the TSR register. If the TSR still contains all or part of a previous character, the new character data is held in the TXREG until the Stop bit of the previous character has been transmitted. The pending character in the TXREG is then transferred to the TSR in one Tcy immediately following the Stop bit transmission. The transmission of the Start bit, data bits and Stop bit sequence commences immediately following the transfer of the data to the TSR from the TXREG.

12.1.1.3 Transmit Interrupt Flag

The TXIF interrupt flag bit of the PIR1 register is set whenever the EUSART transmitter is enabled and no character is being held for transmission in the TXREG. In other words, the TXIF bit is only clear when the TSR is busy with a character and a new character has been queued for transmission in the TXREG. The TXIF flag bit is not cleared immediately upon writing TXREG. TXIF becomes valid in the second instruction cycle following the write execution. Polling TXIF immediately following the TXREG write will return invalid results. The TXIF bit is read-only, it cannot be set or cleared by software.

The TXIF interrupt can be enabled by setting the TXIE interrupt enable bit of the PIE1 register. However, the TXIF flag bit will be set whenever the TXREG is empty, regardless of the state of TXIE enable bit.

To use interrupts when transmitting data, set the TXIE bit only when there is more data to send. Clear the TXIE interrupt enable bit upon writing the last character of the transmission to the TXREG.

PIC16F882/883/884/886/887

12.1.1.4 TSR Status

The TRMT bit of the TXSTA register indicates the status of the TSR register. This is a read-only bit. The TRMT bit is set when the TSR register is empty and is cleared when a character is transferred to the TSR register from the TXREG. The TRMT bit remains clear until all bits have been shifted out of the TSR register. No interrupt logic is tied to this bit, so the user has to poll this bit to determine the TSR status.

Note: The TSR register is not mapped in data memory, so it is not available to the user.

12.1.1.5 Transmitting 9-Bit Characters

The EUSART supports 9-bit character transmissions. When the TX9 bit of the TXSTA register is set the EUSART will shift 9 bits out for each character transmitted. The TX9D bit of the TXSTA register is the ninth, and Most Significant, data bit. When transmitting 9-bit data, the TX9D data bit must be written before writing the 8 Least Significant bits into the TXREG. All nine bits of data will be transferred to the TSR shift register immediately after the TXREG is written.

A special 9-bit Address mode is available for use with multiple receivers. See **Section 12.1.2.7 “Address Detection”** for more information on the Address mode.

12.1.1.6 Asynchronous Transmission Set-up:

1. Initialize the SPBRGH, SPBRG register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 12.3 “EUSART Baud Rate Generator (BRG)”**).
2. Enable the asynchronous serial port by clearing the SYNC bit and setting the SPEN bit.
3. If 9-bit transmission is desired, set the TX9 control bit. A set ninth data bit will indicate that the 8 Least Significant data bits are an address when the receiver is set for address detection.
4. Enable the transmission by setting the TXEN control bit. This will cause the TXIF interrupt bit to be set.
5. If interrupts are desired, set the TXIE interrupt enable bit of the PIE1 register. An interrupt will occur immediately provided that the GIE and PEIE bits of the INTCON register are also set.
6. If 9-bit transmission is selected, the ninth bit should be loaded into the TX9D data bit.
7. Load 8-bit data into the TXREG register. This will start the transmission.

FIGURE 12-3: ASYNCHRONOUS TRANSMISSION

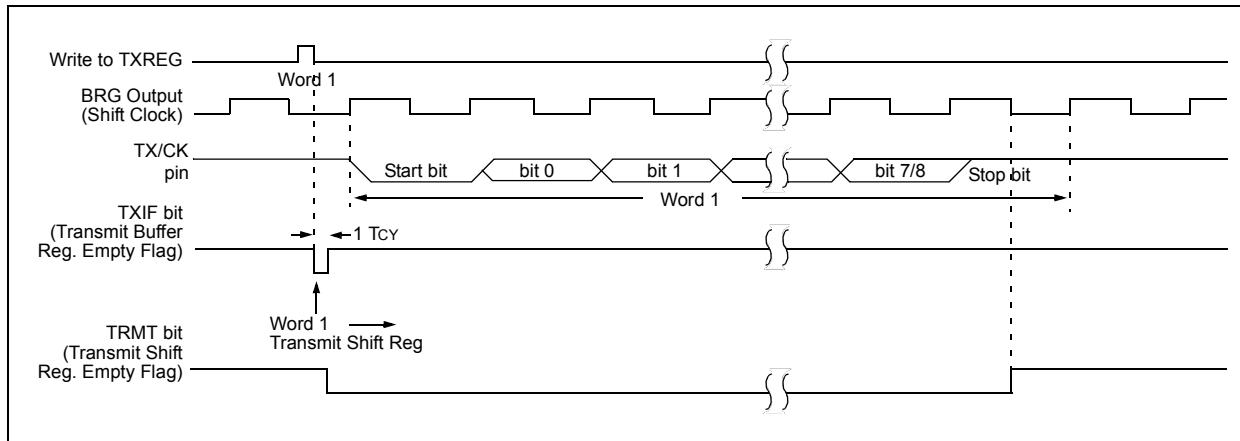
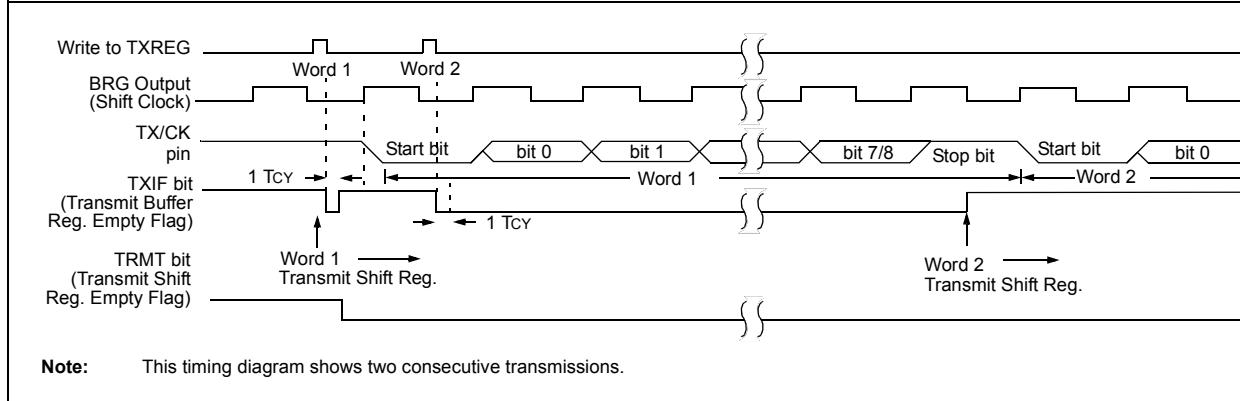


FIGURE 12-4: ASYNCHRONOUS TRANSMISSION (BACK TO BACK)



PIC16F882/883/884/886/887

TABLE 12-1: REGISTERS ASSOCIATED WITH ASYNCHRONOUS TRANSMISSION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register								0000 0000	0000 0000
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register								0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, – = unimplemented read as '0'. Shaded cells are not used for Asynchronous Transmission.

12.1.2 EUSART ASYNCHRONOUS RECEIVER

The Asynchronous mode is typically used in RS-232 systems. The receiver block diagram is shown in Figure 12-2. The data is received on the RX/DT pin and drives the data recovery block. The data recovery block is actually a high-speed shifter operating at 16 times the baud rate, whereas the serial Receive Shift Register (RSR) operates at the bit rate. When all 8 or 9 bits of the character have been shifted in, they are immediately transferred to a two character First-In-First-Out (FIFO) memory. The FIFO buffering allows reception of two complete characters and the start of a third character before software must start servicing the EUSART receiver. The FIFO and RSR registers are not directly accessible by software. Access to the received data is via the RCREG register.

12.1.2.1 Enabling the Receiver

The EUSART receiver is enabled for asynchronous operation by configuring the following three control bits:

- CREN = 1
- SYNC = 0
- SPEN = 1

All other EUSART control bits are assumed to be in their default state.

Setting the CREN bit of the RCSTA register enables the receiver circuitry of the EUSART. Clearing the SYNC bit of the TXSTA register configures the EUSART for asynchronous operation. Setting the SPEN bit of the RCSTA register enables the EUSART and automatically configures the RX/DT I/O pin as an input. If the RX/DT pin is shared with an analog peripheral the analog I/O function must be disabled by clearing the corresponding ANSEL bit.

Note: When the SPEN bit is set the TX/CK I/O pin is automatically configured as an output, regardless of the state of the corresponding TRIS bit and whether or not the EUSART transmitter is enabled. The PORT latch is disconnected from the output driver so it is not possible to use the TX/CK pin as a general purpose output.

12.1.2.2 Receiving Data

The receiver data recovery circuit initiates character reception on the falling edge of the first bit. The first bit, also known as the Start bit, is always a zero. The data recovery circuit counts one-half bit time to the center of the Start bit and verifies that the bit is still a zero. If it is not a zero then the data recovery circuit aborts character reception, without generating an error, and resumes looking for the falling edge of the Start bit. If the Start bit zero verification succeeds then the data recovery circuit counts a full bit time to the center of the next bit. The bit is then sampled by a majority detect circuit and the resulting '0' or '1' is shifted into the RSR. This repeats until all data bits have been sampled and shifted into the RSR. One final bit time is measured and the level sampled. This is the Stop bit, which is always a '1'. If the data recovery circuit samples a '0' in the Stop bit position then a framing error is set for this character, otherwise the framing error is cleared for this character. See **Section 12.1.2.4 “Receive Framing Error”** for more information on framing errors.

Immediately after all data bits and the Stop bit have been received, the character in the RSR is transferred to the EUSART receive FIFO and the RCIF interrupt flag bit of the PIR1 register is set. The top character in the FIFO is transferred out of the FIFO by reading the RCREG register.

Note: If the receive FIFO is overrun, no additional characters will be received until the overrun condition is cleared. See **Section 12.1.2.5 “Receive Overrun Error”** for more information on overrun errors.

12.1.2.3 Receive Interrupts

The RCIF interrupt flag bit of the PIR1 register is set whenever the EUSART receiver is enabled and there is an unread character in the receive FIFO. The RCIF interrupt flag bit is read-only, it cannot be set or cleared by software.

RCIF interrupts are enabled by setting all of the following bits:

- RCIE interrupt enable bit of the PIE1 register
- PEIE peripheral interrupt enable bit of the INTCON register
- GIE global interrupt enable bit of the INTCON register

The RCIF interrupt flag bit will be set when there is an unread character in the FIFO, regardless of the state of interrupt enable bits.

12.1.2.4 Receive Framing Error

Each character in the receive FIFO buffer has a corresponding framing error Status bit. A framing error indicates that a Stop bit was not seen at the expected time. The framing error status is accessed via the FERR bit of the RCSTA register. The FERR bit represents the status of the top unread character in the receive FIFO. Therefore, the FERR bit must be read before reading the RCREG.

The FERR bit is read-only and only applies to the top unread character in the receive FIFO. A framing error (FERR = 1) does not preclude reception of additional characters. It is not necessary to clear the FERR bit. Reading the next character from the FIFO buffer will advance the FIFO to the next character and the next corresponding framing error.

The FERR bit can be forced clear by clearing the SPEN bit of the RCSTA register which resets the EUSART. Clearing the CREN bit of the RCSTA register does not affect the FERR bit. A framing error by itself does not generate an interrupt.

Note: If all receive characters in the receive FIFO have framing errors, repeated reads of the RCREG will not clear the FERR bit.

12.1.2.5 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before the FIFO is accessed. When this happens the OERR bit of the RCSTA register is set. The characters already in the FIFO buffer can be read but no additional characters will be received until the error is cleared. The error must be cleared by either clearing the CREN bit of the RCSTA register or by resetting the EUSART by clearing the SPEN bit of the RCSTA register.

12.1.2.6 Receiving 9-bit Characters

The EUSART supports 9-bit character reception. When the RX9 bit of the RCSTA register is set the EUSART will shift 9 bits into the RSR for each character received. The RX9D bit of the RCSTA register is the ninth and Most Significant data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the 8 Least Significant bits from the RCREG.

12.1.2.7 Address Detection

A special Address Detection mode is available for use when multiple receivers share the same transmission line, such as in RS-485 systems. Address detection is enabled by setting the ADDEN bit of the RCSTA register.

Address detection requires 9-bit character reception. When address detection is enabled, only characters with the ninth data bit set will be transferred to the receive FIFO buffer, thereby setting the RCIF interrupt bit. All other characters will be ignored.

Upon receiving an address character, user software determines if the address matches its own. Upon address match, user software must disable address detection by clearing the ADDEN bit before the next Stop bit occurs. When user software detects the end of the message, determined by the message protocol used, software places the receiver back into the Address Detection mode by setting the ADDEN bit.

PIC16F882/883/884/886/887

12.1.2.8 Asynchronous Reception Set-up:

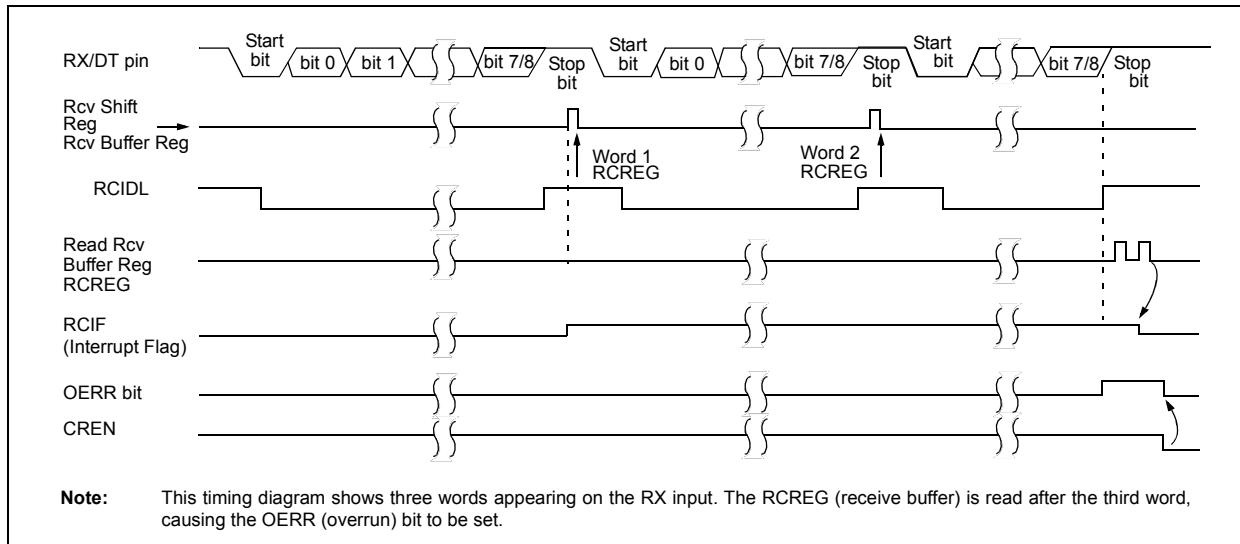
1. Initialize the SPBRGH, SPBRG register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 12.3 “EUSART Baud Rate Generator (BRG)”**).
2. Enable the serial port by setting the SPEN bit. The SYNC bit must be clear for asynchronous operation.
3. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
4. If 9-bit reception is desired, set the RX9 bit.
5. Enable reception by setting the CREN bit.
6. The RCIF interrupt flag bit will be set when a character is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCIE interrupt enable bit was also set.
7. Read the RCSTA register to get the error flags and, if 9-bit data reception is enabled, the ninth data bit.
8. Get the received 8 Least Significant data bits from the receive buffer by reading the RCREG register.
9. If an overrun occurred, clear the OERR flag by clearing the CREN receiver enable bit.

12.1.2.9 9-bit Address Detection Mode Set-up

This mode would typically be used in RS-485 systems. To set up an Asynchronous Reception with Address Detect Enable:

1. Initialize the SPBRGH, SPBRG register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 12.3 “EUSART Baud Rate Generator (BRG)”**).
2. Enable the serial port by setting the SPEN bit. The SYNC bit must be clear for asynchronous operation.
3. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
4. Enable 9-bit reception by setting the RX9 bit.
5. Enable address detection by setting the ADDEN bit.
6. Enable reception by setting the CREN bit.
7. The RCIF interrupt flag bit will be set when a character with the ninth bit set is transferred from the RSR to the receive buffer. An interrupt will be generated if the RCIE interrupt enable bit was also set.
8. Read the RCSTA register to get the error flags. The ninth data bit will always be set.
9. Get the received 8 Least Significant data bits from the receive buffer by reading the RCREG register. Software determines if this is the device's address.
10. If an overrun occurred, clear the OERR flag by clearing the CREN receiver enable bit.
11. If the device has been addressed, clear the ADDEN bit to allow all received data into the receive buffer and generate interrupts.

FIGURE 12-5: ASYNCHRONOUS RECEPTION



PIC16F882/883/884/886/887

TABLE 12-2: REGISTERS ASSOCIATED WITH ASYNCHRONOUS RECEPTION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register								0000 0000	0000 0000
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register								0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, – = unimplemented read as '0'. Shaded cells are not used for Asynchronous Reception.

PIC16F882/883/884/886/887

12.2 Clock Accuracy with Asynchronous Operation

The factory calibrates the Internal Oscillator block output (INTOSC). However, the INTOSC frequency may drift as VDD or temperature changes, and this directly affects the asynchronous baud rate. Two methods may be used to adjust the baud rate clock, but both require a reference clock source of some kind.

The first (preferred) method uses the OSCTUNE register to adjust the INTOSC output. Adjusting the value in the OSCTUNE register allows for fine resolution changes to the system clock source. See **Section 4.5 “Internal Clock Modes”** for more information.

The other method adjusts the value in the Baud Rate Generator. This can be done automatically with the Auto-Baud Detect feature (see **Section 12.3.1 “Auto-Baud Detect”**). There may not be fine enough resolution when adjusting the Baud Rate Generator to compensate for a gradual change in the peripheral clock frequency.

REGISTER 12-1: TXSTA: TRANSMIT STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-1	R/W-0
CSRC	TX9	TXEN ⁽¹⁾	SYNC	SEND B	BRGH	TRMT	TX9D
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as ‘0’

-n = Value at POR

‘1’ = Bit is set

‘0’ = Bit is cleared

x = Bit is unknown

- bit 7 **CSRC:** Clock Source Select bit
Asynchronous mode:
Don’t care
Synchronous mode:
1 = Master mode (clock generated internally from BRG)
0 = Slave mode (clock from external source)
- bit 6 **TX9:** 9-bit Transmit Enable bit
1 = Selects 9-bit transmission
0 = Selects 8-bit transmission
- bit 5 **TXEN:** Transmit Enable bit⁽¹⁾
1 = Transmit enabled
0 = Transmit disabled
- bit 4 **SYNC:** EUSART Mode Select bit
1 = Synchronous mode
0 = Asynchronous mode
- bit 3 **SEND B:** Send Break Character bit
Asynchronous mode:
1 = Send Sync Break on next transmission (cleared by hardware upon completion)
0 = Sync Break transmission completed
Synchronous mode:
Don’t care
- bit 2 **BRGH:** High Baud Rate Select bit
Asynchronous mode:
1 = High speed
0 = Low speed
Synchronous mode:
Unused in this mode
- bit 1 **TRMT:** Transmit Shift Register Status bit
1 = TSR empty
0 = TSR full
- bit 0 **TX9D:** Ninth bit of Transmit Data
Can be address/data bit or a parity bit.

Note 1: SREN/CREN overrides TXEN in Sync mode.

PIC16F882/883/884/886/887

REGISTER 12-2: RCSTA: RECEIVE STATUS AND CONTROL REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-x
SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	SPEN: Serial Port Enable bit 1 = Serial port enabled (configures RX/D _T and TX/C _K pins as serial port pins) 0 = Serial port disabled (held in Reset)
bit 6	RX9: 9-bit Receive Enable bit 1 = Selects 9-bit reception 0 = Selects 8-bit reception
bit 5	SREN: Single Receive Enable bit <u>Asynchronous mode:</u> Don't care <u>Synchronous mode – Master:</u> 1 = Enables single receive 0 = Disables single receive This bit is cleared after reception is complete. <u>Synchronous mode – Slave</u> Don't care
bit 4	CREN: Continuous Receive Enable bit <u>Asynchronous mode:</u> 1 = Enables receiver 0 = Disables receiver <u>Synchronous mode:</u> 1 = Enables continuous receive until enable bit CREN is cleared (CREN overrides SREN) 0 = Disables continuous receive
bit 3	ADDEN: Address Detect Enable bit <u>Asynchronous mode 9-bit (RX9 = 1):</u> 1 = Enables address detection, enable interrupt and load the receive buffer when RSR<8> is set 0 = Disables address detection, all bytes are received and ninth bit can be used as parity bit <u>Asynchronous mode 8-bit (RX9 = 0):</u> Don't care
bit 2	FERR: Framing Error bit 1 = Framing error (can be updated by reading RCREG register and receive next valid byte) 0 = No framing error
bit 1	OERR: Overrun Error bit 1 = Overrun error (can be cleared by clearing bit CREN) 0 = No overrun error
bit 0	RX9D: Ninth bit of Received Data This can be address/data bit or a parity bit and must be calculated by user firmware.

PIC16F882/883/884/886/887

REGISTER 12-3: BAUDCTL: BAUD RATE CONTROL REGISTER

R-0	R-1	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7

ABDOVF: Auto-Baud Detect Overflow bit

Asynchronous mode:

1 = Auto-baud timer overflowed

0 = Auto-baud timer did not overflow

Synchronous mode:

Don't care

bit 6

RCIDL: Receive Idle Flag bit

Asynchronous mode:

1 = Receiver is Idle

0 = Start bit has been received and the receiver is receiving

Synchronous mode:

Don't care

bit 5

Unimplemented: Read as '0'

bit 4

SCKP: Synchronous Clock Polarity Select bit

Asynchronous mode:

1 = Transmit inverted data to the RB7/TX/CK pin

0 = Transmit non-inverted data to the RB7/TX/CK pin

Synchronous mode:

1 = Data is clocked on rising edge of the clock

0 = Data is clocked on falling edge of the clock

bit 3

BRG16: 16-bit Baud Rate Generator bit

1 = 16-bit Baud Rate Generator is used

0 = 8-bit Baud Rate Generator is used

bit 2

Unimplemented: Read as '0'

bit 1

WUE: Wake-up Enable bit

Asynchronous mode:

1 = Receiver is waiting for a falling edge. No character will be received byte RCIF will be set. WUE will automatically clear after RCIF is set.

0 = Receiver is operating normally

Synchronous mode:

Don't care

bit 0

ABDEN: Auto-Baud Detect Enable bit

Asynchronous mode:

1 = Auto-Baud Detect mode is enabled (clears when auto-baud is complete)

0 = Auto-Baud Detect mode is disabled

Synchronous mode:

Don't care

12.3 EUSART Baud Rate Generator (BRG)

The Baud Rate Generator (BRG) is an 8-bit or 16-bit timer that is dedicated to the support of both the asynchronous and synchronous EUSART operation. By default, the BRG operates in 8-bit mode. Setting the BRG16 bit of the BAUDCTL register selects 16-bit mode.

The SPBRGH, SPBRG register pair determines the period of the free running baud rate timer. In Asynchronous mode the multiplier of the baud rate period is determined by both the BRGH bit of the TXSTA register and the BRG16 bit of the BAUDCTL register. In Synchronous mode, the BRGH bit is ignored.

Table 12-3 contains the formulas for determining the baud rate. Example 12-1 provides a sample calculation for determining the baud rate and baud rate error.

Typical baud rates and error values for various asynchronous modes have been computed for your convenience and are shown in Table 12-3. It may be advantageous to use the high baud rate (BRGH = 1), or the 16-bit BRG (BRG16 = 1) to reduce the baud rate error. The 16-bit BRG mode is used to achieve slow baud rates for fast oscillator frequencies.

Writing a new value to the SPBRGH, SPBRG register pair causes the BRG timer to be reset (or cleared). This ensures that the BRG does not wait for a timer overflow before outputting the new baud rate.

If the system clock is changed during an active receive operation, a receive error or data loss may result. To avoid this problem, check the status of the RCIDL bit to make sure that the receive operation is Idle before changing the system clock.

EXAMPLE 12-1: CALCULATING BAUD RATE ERROR

For a device with Fosc of 16 MHz, desired baud rate of 9600, Asynchronous mode, 8-bit BRG:

$$\text{Desired Baud Rate} = \frac{F_{OSC}}{64(\text{SPBRGH:SPBRG} + 1)}$$

Solving for SPBRGH:SPBRG:

$$\begin{aligned} X &= \frac{F_{OSC}}{64 \cdot \text{Desired Baud Rate}} - 1 \\ &= \frac{16000000}{64 \cdot 9600} - 1 \\ &= [25.042] = 25 \\ \text{Calculated Baud Rate} &= \frac{16000000}{64(25 + 1)} \\ &= 9615 \end{aligned}$$

$$\begin{aligned} \text{Error} &= \frac{\text{Calc. Baud Rate} - \text{Desired Baud Rate}}{\text{Desired Baud Rate}} \\ &= \frac{(9615 - 9600)}{9600} = 0.16\% \end{aligned}$$

TABLE 12-3: BAUD RATE FORMULAS

Configuration Bits			BRG/EUSART Mode			Baud Rate Formula			
SYNC	BRG16	BRGH							
0	0	0	8-bit/Asynchronous			Fosc/[64 (n+1)]			
0	0	1	8-bit/Asynchronous			Fosc/[16 (n+1)]			
0	1	0	16-bit/Asynchronous						
0	1	1	16-bit/Asynchronous			Fosc/[4 (n+1)]			
1	0	x	8-bit/Synchronous						
1	1	x	16-bit/Synchronous						

Legend: x = Don't care, n = value of SPBRGH, SPBRG register pair

TABLE 12-4: REGISTERS ASSOCIATED WITH THE BAUD RATE GENERATOR

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, — = unimplemented read as '0'. Shaded cells are not used for the Baud Rate Generator.

PIC16F882/883/884/886/887

TABLE 12-5: BAUD RATES FOR ASYNCHRONOUS MODES

BAUD RATE	SYNC = 0, BRGH = 0, BRG16 = 0											
	Fosc = 20.000 MHz			Fosc = 18.432 MHz			Fosc = 11.0592 MHz			Fosc = 8.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	—	—	—	—	—	—	—	—	—	—	—	—
1200	1221	1.73	255	1200	0.00	239	1200	0.00	143	1202	0.16	103
2400	2404	0.16	129	2400	0.00	119	2400	0.00	71	2404	0.16	51
9600	9470	-1.36	32	9600	0.00	29	9600	0.00	17	9615	0.16	12
10417	10417	0.00	29	10286	-1.26	27	10165	-2.42	16	10417	0.00	11
19.2k	19.53k	1.73	15	19.20k	0.00	14	19.20k	0.00	8	—	—	—
57.6k	—	—	—	57.60k	0.00	7	57.60k	0.00	2	—	—	—
115.2k	—	—	—	—	—	—	—	—	—	—	—	—

BAUD RATE	SYNC = 0, BRGH = 0, BRG16 = 0											
	Fosc = 4.000 MHz			Fosc = 3.6864 MHz			Fosc = 2.000 MHz			Fosc = 1.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	300	0.16	207	300	0.00	191	300	0.16	103	300	0.16	51
1200	1202	0.16	51	1200	0.00	47	1202	0.16	25	1202	0.16	12
2400	2404	0.16	25	2400	0.00	23	2404	0.16	12	—	—	—
9600	—	—	—	9600	0.00	5	—	—	—	—	—	—
10417	10417	0.00	5	—	—	—	10417	0.00	2	—	—	—
19.2k	—	—	—	19.20k	0.00	2	—	—	—	—	—	—
57.6k	—	—	—	57.60k	0.00	0	—	—	—	—	—	—
115.2k	—	—	—	—	—	—	—	—	—	—	—	—

BAUD RATE	SYNC = 0, BRGH = 1, BRG16 = 0											
	Fosc = 20.000 MHz			Fosc = 18.432 MHz			Fosc = 11.0592 MHz			Fosc = 8.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	—	—	—	—	—	—	—	—	—	—	—	—
1200	—	—	—	—	—	—	—	—	—	—	—	—
2400	—	—	—	—	—	—	—	—	—	2404	0.16	207
9600	9615	0.16	129	9600	0.00	119	9600	0.00	71	9615	0.16	51
10417	10417	0.00	119	10378	-0.37	110	10473	0.53	65	10417	0.00	47
19.2k	19.23k	0.16	64	19.20k	0.00	59	19.20k	0.00	35	19231	0.16	25
57.6k	56.82k	-1.36	21	57.60k	0.00	19	57.60k	0.00	11	55556	-3.55	8
115.2k	113.64k	-1.36	10	115.2k	0.00	9	115.2k	0.00	5	—	—	—

PIC16F882/883/884/886/887

TABLE 12-5: BAUD RATES FOR ASYNCHRONOUS MODES (CONTINUED)

BAUD RATE	SYNC = 0, BRGH = 1, BRG16 = 0											
	Fosc = 4.000 MHz			Fosc = 3.6864 MHz			Fosc = 2.000 MHz			Fosc = 1.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	—	—	—	—	—	—	—	—	—	300	0.16	207
1200	1202	0.16	207	1200	0.00	191	1202	0.16	103	1202	0.16	51
2400	2404	0.16	103	2400	0.00	95	2404	0.16	51	2404	0.16	25
9600	9615	0.16	25	9600	0.00	23	9615	0.16	12	—	—	—
10417	10417	0.00	23	10473	0.53	21	10417	0.00	11	10417	0.00	5
19.2k	19.23k	0.16	12	19.2k	0.00	11	—	—	—	—	—	—
57.6k	—	—	—	57.60k	0.00	3	—	—	—	—	—	—
115.2k	—	—	—	115.2k	0.00	1	—	—	—	—	—	—

BAUD RATE	SYNC = 0, BRGH = 0, BRG16 = 1											
	Fosc = 20.000 MHz			Fosc = 18.432 MHz			Fosc = 11.0592 MHz			Fosc = 8.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	300.0	-0.01	4166	300.0	0.00	3839	300.0	0.00	2303	299.9	-0.02	1666
1200	1200	-0.03	1041	1200	0.00	959	1200	0.00	575	1199	-0.08	416
2400	2399	-0.03	520	2400	0.00	479	2400	0.00	287	2404	0.16	207
9600	9615	0.16	129	9600	0.00	119	9600	0.00	71	9615	0.16	51
10417	10417	0.00	119	10378	-0.37	110	10473	0.53	65	10417	0.00	47
19.2k	19.23k	0.16	64	19.20k	0.00	59	19.20k	0.00	35	19.23k	0.16	25
57.6k	56.818	-1.36	21	57.60k	0.00	19	57.60k	0.00	11	55556	-3.55	8
115.2k	113.636	-1.36	10	115.2k	0.00	9	115.2k	0.00	5	—	—	—

BAUD RATE	SYNC = 0, BRGH = 0, BRG16 = 1											
	Fosc = 4.000 MHz			Fosc = 3.6864 MHz			Fosc = 2.000 MHz			Fosc = 1.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	300.1	0.04	832	300.0	0.00	767	299.8	-0.108	416	300.5	0.16	207
1200	1202	0.16	207	1200	0.00	191	1202	0.16	103	1202	0.16	51
2400	2404	0.16	103	2400	0.00	95	2404	0.16	51	2404	0.16	25
9600	9615	0.16	25	9600	0.00	23	9615	0.16	12	—	—	—
10417	10417	0.00	23	10473	0.53	21	10417	0.00	11	10417	0.00	5
19.2k	19.23k	0.16	12	19.20k	0.00	11	—	—	—	—	—	—
57.6k	—	—	—	57.60k	0.00	3	—	—	—	—	—	—
115.2k	—	—	—	115.2k	0.00	1	—	—	—	—	—	—

PIC16F882/883/884/886/887

TABLE 12-5: BAUD RATES FOR ASYNCHRONOUS MODES (CONTINUED)

BAUD RATE	SYNC = 0, BRGH = 1, BRG16 = 1 or SYNC = 1, BRG16 = 1											
	Fosc = 20.000 MHz			Fosc = 18.432 MHz			Fosc = 11.0592 MHz			Fosc = 8.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	300.0	0.00	16665	300.0	0.00	15359	300.0	0.00	9215	300.0	0.00	6666
1200	1200	-0.01	4166	1200	0.00	3839	1200	0.00	2303	1200	-0.02	1666
2400	2400	0.02	2082	2400	0.00	1919	2400	0.00	1151	2401	0.04	832
9600	9597	-0.03	520	9600	0.00	479	9600	0.00	287	9615	0.16	207
10417	10417	0.00	479	10425	0.08	441	10433	0.16	264	10417	0	191
19.2k	19.23k	0.16	259	19.20k	0.00	239	19.20k	0.00	143	19.23k	0.16	103
57.6k	57.47k	-0.22	86	57.60k	0.00	79	57.60k	0.00	47	57.14k	-0.79	34
115.2k	116.3k	0.94	42	115.2k	0.00	39	115.2k	0.00	23	117.6k	2.12	16

BAUD RATE	SYNC = 0, BRGH = 1, BRG16 = 1 or SYNC = 1, BRG16 = 1											
	Fosc = 4.000 MHz			Fosc = 3.6864 MHz			Fosc = 2.000 MHz			Fosc = 1.000 MHz		
	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)	Actual Rate	% Error	SPBRG value (decimal)
300	300.0	0.01	3332	300.0	0.00	3071	299.9	-0.02	1666	300.1	0.04	832
1200	1200	0.04	832	1200	0.00	767	1199	-0.08	416	1202	0.16	207
2400	2398	0.08	416	2400	0.00	383	2404	0.16	207	2404	0.16	103
9600	9615	0.16	103	9600	0.00	95	9615	0.16	51	9615	0.16	25
10417	10417	0.00	95	10473	0.53	87	10417	0.00	47	10417	0.00	23
19.2k	19.23k	0.16	51	19.20k	0.00	47	19.23k	0.16	25	19.23k	0.16	12
57.6k	58.82k	2.12	16	57.60k	0.00	15	55.56k	-3.55	8	—	—	—
115.2k	111.1k	-3.55	8	115.2k	0.00	7	—	—	—	—	—	—

12.3.1 AUTO-BAUD DETECT

The EUSART module supports automatic detection and calibration of the baud rate.

In the Auto-Baud Detect (ABD) mode, the clock to the BRG is reversed. Rather than the BRG clocking the incoming RX signal, the RX signal is timing the BRG. The Baud Rate Generator is used to time the period of a received 55h (ASCII "U") which is the Sync character for the LIN bus. The unique feature of this character is that it has five rising edges including the Stop bit edge.

Setting the ABDEN bit of the BAUDCTL register starts the auto-baud calibration sequence (Figure 12-6). While the ABD sequence takes place, the EUSART state machine is held in Idle. On the first rising edge of the receive line, after the Start bit, the SPBRG begins counting up using the BRG counter clock as shown in Table 12-6. The fifth rising edge will occur on the RX pin at the end of the eighth bit period. At that time, an accumulated value totaling the proper BRG period is left in the SPBRGH, SPBRG register pair, the ABDEN bit is automatically cleared and the RCIF interrupt flag is set. The value in the RCREG needs to be read to clear the RCIF interrupt. RCREG content should be discarded. When calibrating for modes that do not use the SPBRGH register the user can verify that the SPBRG register did not overflow by checking for 00h in the SPBRGH register.

The BRG auto-baud clock is determined by the BRG16 and BRGH bits as shown in Table 12-6. During ABD, both the SPBRGH and SPBRG registers are used as a 16-bit counter, independent of the BRG16 bit setting. While calibrating the baud rate period, the SPBRGH

and SPBRG registers are clocked at 1/8th the BRG base clock rate. The resulting byte measurement is the average bit time when clocked at full speed.

Note 1: If the WUE bit is set with the ABDEN bit, auto-baud detection will occur on the byte following the Break character (see Section 12.3.2 "Auto-Wake-up on Break").

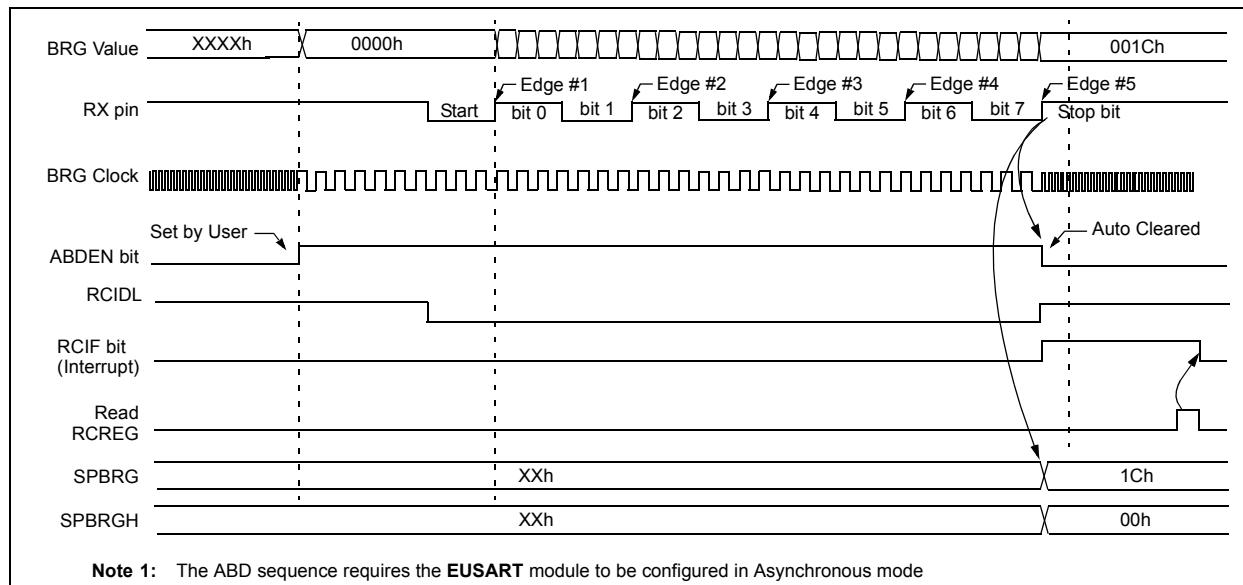
- 2: It is up to the user to determine that the incoming character baud rate is within the range of the selected BRG clock source. Some combinations of oscillator frequency and EUSART baud rates are not possible.
- 3: During the auto-baud process, the auto-baud counter starts counting at 1. Upon completion of the auto-baud sequence, to achieve maximum accuracy, subtract 1 from the SPBRGH:SPBRG register pair.

TABLE 12-6: BRG COUNTER CLOCK RATES

BRG16	BRGH	BRG Base Clock	BRG ABD Clock
0	0	Fosc/64	Fosc/512
0	1	Fosc/16	Fosc/128
1	0	Fosc/16	Fosc/128
1	1	Fosc/4	Fosc/32

Note: During the ABD sequence, SPBRG and SPBRGH registers are both used as a 16-bit counter, independent of BRG16 setting.

FIGURE 12-6: AUTOMATIC BAUD RATE CALIBRATION



PIC16F882/883/884/886/887

12.3.2 AUTO-WAKE-UP ON BREAK

During Sleep mode, all clocks to the EUSART are suspended. Because of this, the Baud Rate Generator is inactive and a proper character reception cannot be performed. The Auto-Wake-up feature allows the controller to wake-up due to activity on the RX/DT line. This feature is available only in Asynchronous mode.

The Auto-Wake-up feature is enabled by setting the WUE bit of the BAUDCTL register. Once set, the normal receive sequence on RX/DT is disabled, and the EUSART remains in an Idle state, monitoring for a wake-up event independent of the CPU mode. A wake-up event consists of a high-to-low transition on the RX/DT line. (This coincides with the start of a Sync Break or a wake-up signal character for the LIN protocol.)

The EUSART module generates an RCIF interrupt coincident with the wake-up event. The interrupt is generated synchronously to the Q clocks in normal CPU operating modes (Figure 12-7), and asynchronously if the device is in Sleep mode (Figure 12-8). The interrupt condition is cleared by reading the RCREG register.

The WUE bit is automatically cleared by the low-to-high transition on the RX line at the end of the Break. This signals to the user that the Break event is over. At this point, the EUSART module is in Idle mode waiting to receive the next character.

12.3.2.1 Special Considerations

Break Character

To avoid character errors or character fragments during a wake-up event, the wake-up character must be all zeros.

When the wake-up is enabled the function works independent of the low time on the data stream. If the WUE bit is set and a valid non-zero character is received, the low time from the Start bit to the first rising edge will be interpreted as the wake-up event. The remaining bits in the character will be received as a fragmented character and subsequent characters can result in framing or overrun errors.

Therefore, the initial character in the transmission must be all '0's. This must be 10 or more bit times, 13-bit times recommended for LIN bus, or any number of bit times for standard RS-232 devices.

Oscillator Startup Time

Oscillator start-up time must be considered, especially in applications using oscillators with longer start-up intervals (i.e., LP, XT or HS/PLL mode). The Sync Break (or wake-up signal) character must be of sufficient length, and be followed by a sufficient interval, to allow enough time for the selected oscillator to start and provide proper initialization of the EUSART.

WUE Bit

The wake-up event causes a receive interrupt by setting the RCIF bit. The WUE bit is cleared in hardware by a rising edge on RX/DT. The interrupt condition is then cleared in software by reading the RCREG register and discarding its contents.

To ensure that no actual data is lost, check the RCDL bit to verify that a receive operation is not in process before setting the WUE bit. If a receive operation is not occurring, the WUE bit may then be set just prior to entering the Sleep mode.

FIGURE 12-7: AUTO-WAKE-UP BIT (WUE) TIMING DURING NORMAL OPERATION

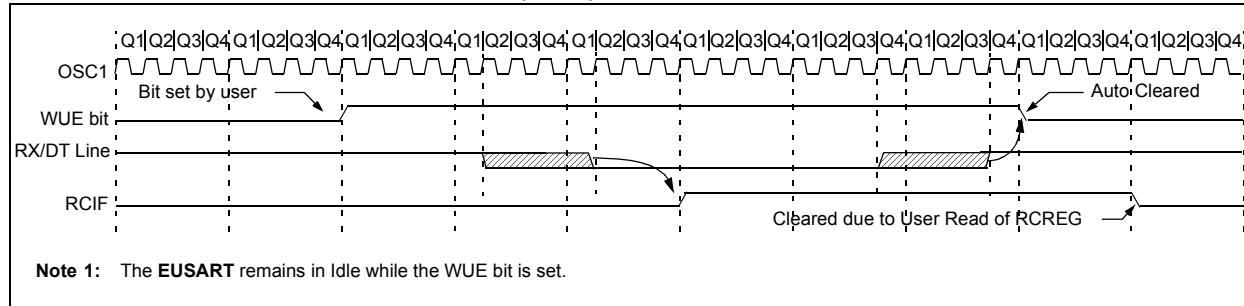
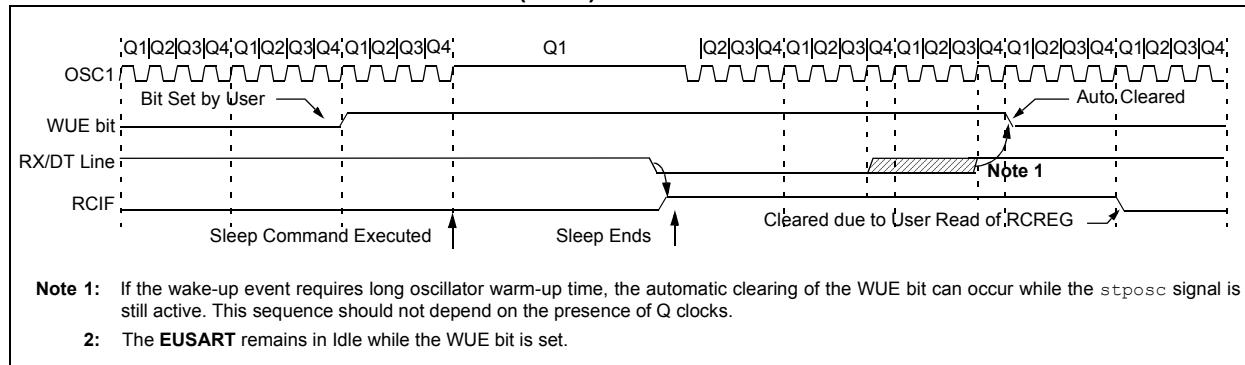


FIGURE 12-8: AUTO-WAKE-UP BIT (WUE) TIMINGS DURING SLEEP



12.3.3 BREAK CHARACTER SEQUENCE

The EUSART module has the capability of sending the special Break character sequences that are required by the LIN bus standard. A Break character consists of a Start bit, followed by 12 '0' bits and a Stop bit.

To send a Break character, set the SENDB and TXEN bits of the TXSTA register. The Break character transmission is then initiated by a write to the TXREG. The value of data written to TXREG will be ignored and all '0's will be transmitted.

The SENDB bit is automatically reset by hardware after the corresponding Stop bit is sent. This allows the user to preload the transmit FIFO with the next transmit byte following the Break character (typically, the Sync character in the LIN specification).

The TRMT bit of the TXSTA register indicates when the transmit operation is active or Idle, just as it does during normal transmission. See Figure 12-9 for the timing of the Break character sequence.

12.3.3.1 Break and Sync Transmit Sequence

The following sequence will start a message frame header made up of a Break, followed by an auto-baud Sync byte. This sequence is typical of a LIN bus master.

1. Configure the EUSART for the desired mode.
2. Set the TXEN and SENDB bits to enable the Break sequence.
3. Load the TXREG with a dummy character to initiate transmission (the value is ignored).
4. Write '55h' to TXREG to load the Sync character into the transmit FIFO buffer.
5. After the Break has been sent, the SENDB bit is reset by hardware and the Sync character is then transmitted.

When the TXREG becomes empty, as indicated by the TXIF, the next data byte can be written to TXREG.

12.3.4 RECEIVING A BREAK CHARACTER

The Enhanced EUSART module can receive a Break character in two ways.

The first method to detect a Break character uses the FERR bit of the RCSTA register and the Received data as indicated by RCREG. The Baud Rate Generator is assumed to have been initialized to the expected baud rate.

A Break character has been received when:

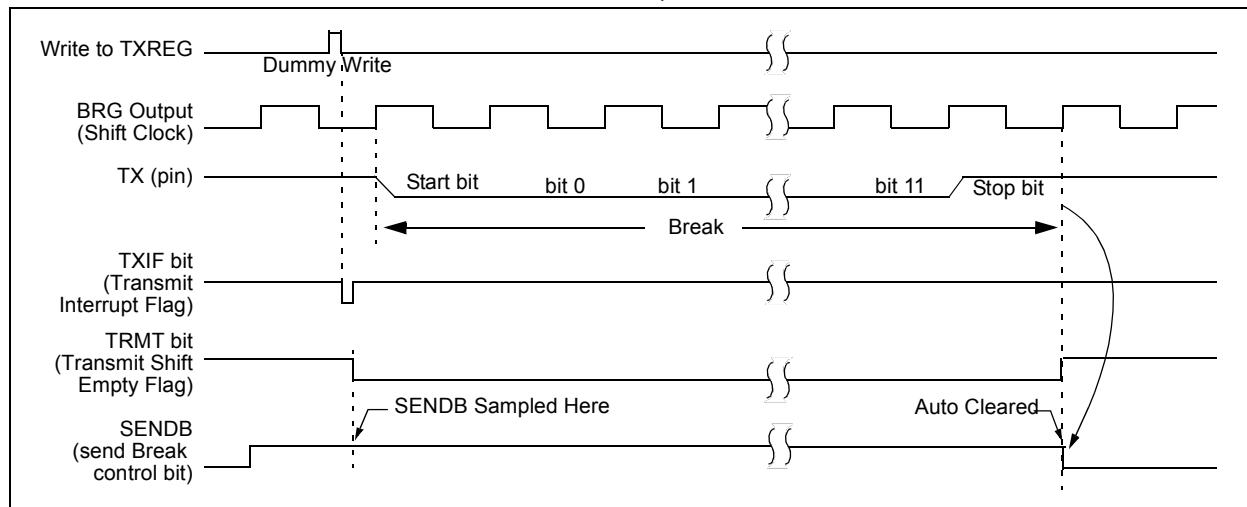
- RCIF bit is set
- FERR bit is set
- RCREG = 00h

The second method uses the Auto-Wake-up feature described in **Section 12.3.2 "Auto-Wake-up on Break"**. By enabling this feature, the EUSART will sample the next two transitions on RX/DT, cause an RCIF interrupt, and receive the next data byte followed by another interrupt.

Note that following a Break character, the user will typically want to enable the Auto-Baud Detect feature. For both methods, the user can set the ABDEN bit of the BAUDCTL register before placing the EUSART in Sleep mode.

PIC16F882/883/884/886/887

FIGURE 12-9: SEND BREAK CHARACTER SEQUENCE



12.4 EUSART Synchronous Mode

Synchronous serial communications are typically used in systems with a single master and one or more slaves. The master device contains the necessary circuitry for baud rate generation and supplies the clock for all devices in the system. Slave devices can take advantage of the master clock by eliminating the internal clock generation circuitry.

There are two signal lines in Synchronous mode: a bidirectional data line and a clock line. Slaves use the external clock supplied by the master to shift the serial data into and out of their respective receive and transmit shift registers. Since the data line is bidirectional, synchronous operation is half-duplex only. Half-duplex refers to the fact that master and slave devices can receive and transmit data but not both simultaneously. The EUSART can operate as either a master or slave device.

Start and Stop bits are not used in synchronous transmissions.

12.4.1 SYNCHRONOUS MASTER MODE

The following bits are used to configure the EUSART for Synchronous Master operation:

- SYNC = 1
- CSRC = 1
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TXSTA register configures the device for synchronous operation. Setting the CSRC bit of the TXSTA register configures the device as a master. Clearing the SREN and CREN bits of the RCSTA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RCSTA register enables the EUSART. If the RX/DT or TX/CK pins are shared with an analog peripheral the analog I/O functions must be disabled by clearing the corresponding ANSEL bits.

12.4.1.1 Master Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a master transmits the clock on the TX/CK line. The TX/CK pin output driver is automatically enabled when the EUSART is configured for synchronous transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One clock cycle is generated for each data bit. Only as many clock cycles are generated as there are data bits.

12.4.1.2 Clock Polarity

A clock polarity option is provided for Microwire compatibility. Clock polarity is selected with the SCKP bit of the BAUDCTL register. Setting the SCKP bit sets the clock Idle state as high. When the SCKP bit is set, the data changes on the falling edge of each clock. Clearing the SCKP bit sets the Idle state as low. When the SCKP bit is cleared, the data changes on the rising edge of each clock.

12.4.1.3 Synchronous Master Transmission

Data is transferred out of the device on the RX/DT pin. The RX/DT and TX/CK pin output drivers are automatically enabled when the EUSART is configured for synchronous master transmit operation.

A transmission is initiated by writing a character to the TXREG register. If the TSR still contains all or part of a previous character the new character data is held in the TXREG until the last bit of the previous character has been transmitted. If this is the first character, or the previous character has been completely flushed from the TSR, the data in the TXREG is immediately transferred to the TSR. The transmission of the character commences immediately following the transfer of the data to the TSR from the TXREG.

Each data bit changes on the leading edge of the master clock and remains valid until the subsequent leading clock edge.

Note: The TSR register is not mapped in data memory, so it is not available to the user.

12.4.1.4 Synchronous Master Transmission Set-up:

1. Initialize the SPBRGH, SPBRG register pair and the BRGH and BRG16 bits to achieve the desired baud rate (see **Section 12.3 “EUSART Baud Rate Generator (BRG)”**).
2. Enable the synchronous master serial port by setting bits SYNC, SPEN, and CSRC.
3. Disable Receive mode by clearing bits SREN and CREN.
4. Enable Transmit mode by setting the TXEN bit.
5. If 9-bit transmission is desired, set the TX9 bit.
6. If interrupts are desired, set the TXIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
7. If 9-bit transmission is selected, the ninth bit should be loaded in the TX9D bit.
8. Start transmission by loading data to the TXREG register.

PIC16F882/883/884/886/887

FIGURE 12-10: SYNCHRONOUS TRANSMISSION

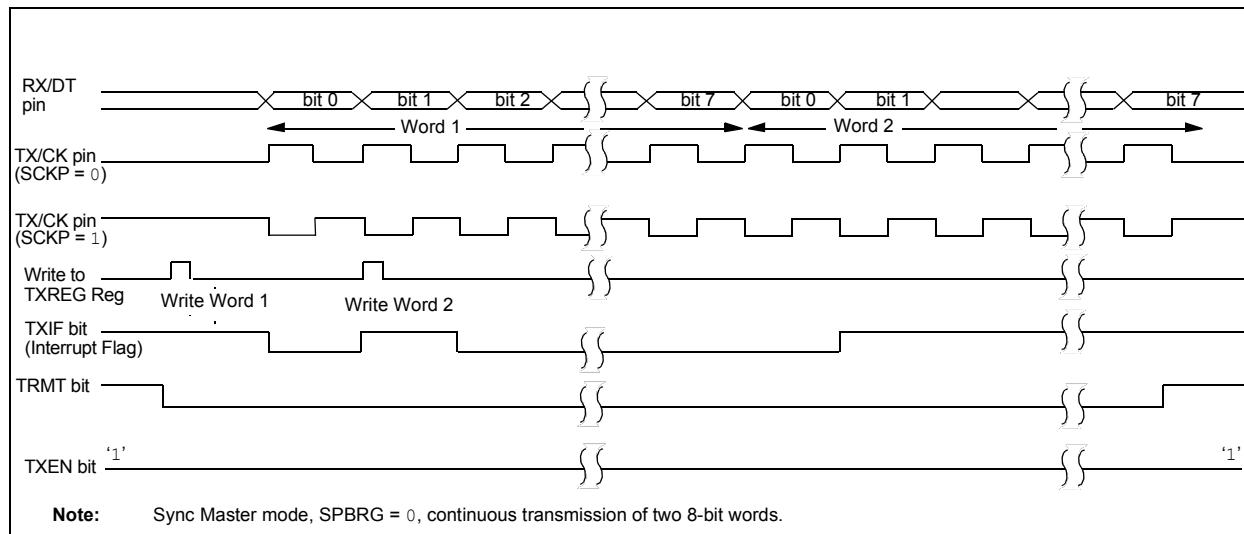


FIGURE 12-11: SYNCHRONOUS TRANSMISSION (THROUGH TXEN)

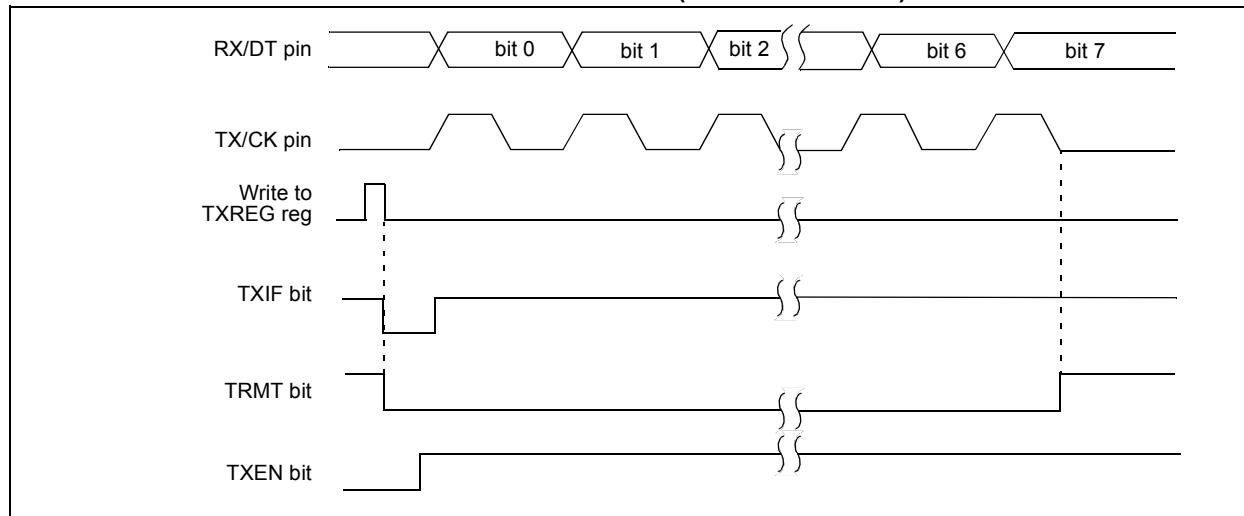


TABLE 12-7: REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER TRANSMISSION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register							0000 0000	0000 0000	0000 0000
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register							0000 0000	0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, — = unimplemented read as '0'. Shaded cells are not used for Synchronous Master Transmission.

12.4.1.5 Synchronous Master Reception

Data is received at the RX/DT pin. The RX/DT pin output driver is automatically disabled when the EUSART is configured for synchronous master receive operation.

In Synchronous mode, reception is enabled by setting either the Single Receive Enable bit (SREN of the RCSTA register) or the Continuous Receive Enable bit (CREN of the RCSTA register).

When SREN is set and CREN is clear, only as many clock cycles are generated as there are data bits in a single character. The SREN bit is automatically cleared at the completion of one character. When CREN is set, clocks are continuously generated until CREN is cleared. If CREN is cleared in the middle of a character the CK clock stops immediately and the partial character is discarded. If SREN and CREN are both set, then SREN is cleared at the completion of the first character and CREN takes precedence.

To initiate reception, set either SREN or CREN. Data is sampled at the RX/DT pin on the trailing edge of the TX/CK clock pin and is shifted into the Receive Shift Register (RSR). When a complete character is received into the RSR, the RCIF bit is set and the character is automatically transferred to the two character receive FIFO. The Least Significant eight bits of the top character in the receive FIFO are available in RCREG. The RCIF bit remains set as long as there are un-read characters in the receive FIFO.

12.4.1.6 Slave Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a slave receives the clock on the TX/CK line. The TX/CK pin output driver is automatically disabled when the device is configured for synchronous slave transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One data bit is transferred for each clock cycle. Only as many clock cycles should be received as there are data bits.

12.4.1.7 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before RCREG is read to access the FIFO. When this happens the OERR bit of the RCSTA register is set. Previous data in the FIFO will not be overwritten. The two characters in the FIFO buffer can be read, however, no additional characters will be received until the error is cleared. The OERR bit can only be cleared by clearing the overrun condition. If the overrun error occurred when the SREN bit is set and CREN is clear then the error is cleared by reading RCREG. If the overrun occurred when the CREN bit is

set then the error condition is cleared by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

12.4.1.8 Receiving 9-bit Characters

The EUSART supports 9-bit character reception. When the RX9 bit of the RCSTA register is set the EUSART will shift 9-bits into the RSR for each character received. The RX9D bit of the RCSTA register is the ninth, and Most Significant, data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the 8 Least Significant bits from the RCREG.

12.4.1.9 Synchronous Master Reception Set-up:

1. Initialize the SPBRGH, SPBRG register pair for the appropriate baud rate. Set or clear the BRGH and BRG16 bits, as required, to achieve the desired baud rate.
2. Enable the synchronous master serial port by setting bits SYNC, SPEN and CSRC.
3. Ensure bits CREN and SREN are clear.
4. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit reception is desired, set bit RX9.
6. Start reception by setting the SREN bit or for continuous reception, set the CREN bit.
7. Interrupt flag bit RCIF will be set when reception of a character is complete. An interrupt will be generated if the enable bit RCIE was set.
8. Read the RCSTA register to get the ninth bit (if enabled) and determine if any error occurred during reception.
9. Read the 8-bit received data by reading the RCREG register.
10. If an overrun error occurs, clear the error by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

PIC16F882/883/884/886/887

FIGURE 12-12: SYNCHRONOUS RECEPTION (MASTER MODE, SREN)

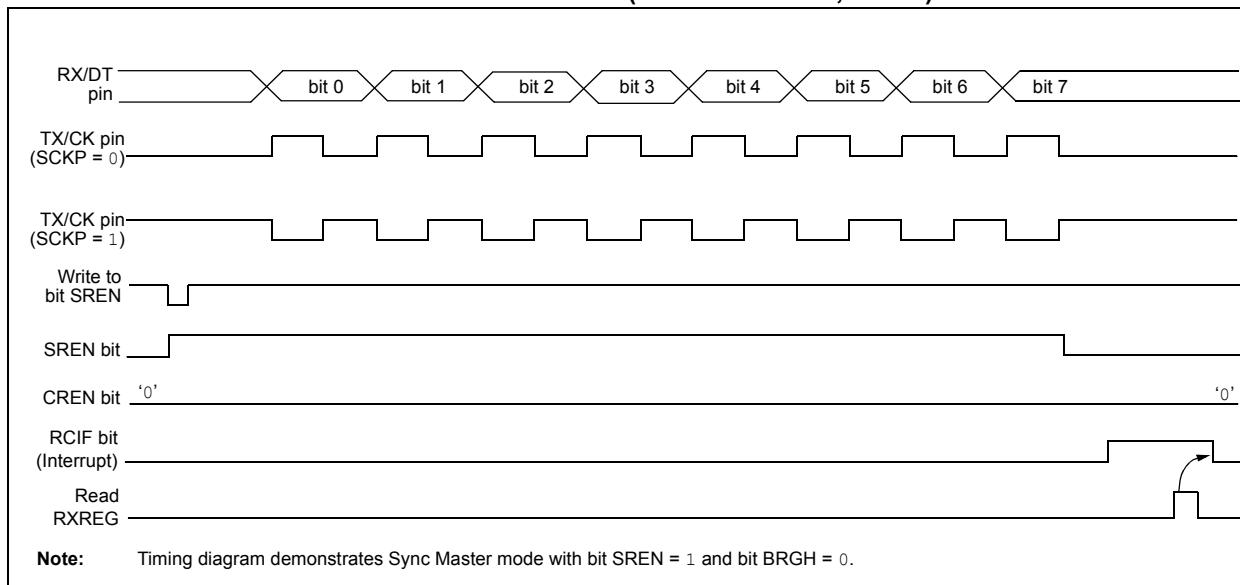


TABLE 12-8: REGISTERS ASSOCIATED WITH SYNCHRONOUS MASTER RECEPTION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register							0000 0000	0000 0000	
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register							0000 0000	0000 0000	
TXSTA	CSRC	TX9	TXEN	SYNC	SENDDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, — = unimplemented read as '0'. Shaded cells are not used for Synchronous Master Reception.

12.4.2 SYNCHRONOUS SLAVE MODE

The following bits are used to configure the EUSART for Synchronous slave operation:

- SYNC = 1
- CSRC = 0
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TXSTA register configures the device for synchronous operation. Clearing the CSRC bit of the TXSTA register configures the device as a slave. Clearing the SREN and CREN bits of the RCSTA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RCSTA register enables the EUSART. If the RX/DT or TX/CK pins are shared with an analog peripheral the analog I/O functions must be disabled by clearing the corresponding ANSEL bits.

12.4.2.1 EUSART Synchronous Slave Transmit

The operation of the Synchronous Master and Slave modes are identical (see **Section 12.4.1.3 "Synchronous Master Transmission"**), except in the case of the Sleep mode.

If two words are written to the TXREG and then the SLEEP instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in TXREG register.
3. The TXIF bit will not be set.
4. After the first character has been shifted out of TSR, the TXREG register will transfer the second character to the TSR and the TXIF bit will now be set.
5. If the PEIE and TXIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

12.4.2.2 Synchronous Slave Transmission Set-up:

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the CREN and SREN bits.
3. If interrupts are desired, set the TXIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
4. If 9-bit transmission is desired, set the TX9 bit.
5. Enable transmission by setting the TXEN bit.
6. If 9-bit transmission is selected, insert the Most Significant bit into the TX9D bit.
7. Start transmission by writing the Least Significant 8 bits to the TXREG register.

TABLE 12-9: REGISTERS ASSOCIATED WITH SYNCHRONOUS SLAVE TRANSMISSION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register								0000 0000	0000 0000
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register								0000 0000	0000 0000
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, – = unimplemented read as '0'. Shaded cells are not used for Synchronous Slave Transmission.

PIC16F882/883/884/886/887

12.4.2.3 EUSART Synchronous Slave Reception

The operation of the Synchronous Master and Slave modes is identical (**Section 12.4.1.5 “Synchronous Master Reception”**), with the following exceptions:

- Sleep
- CREN bit is always set, therefore the receiver is never Idle
- SREN bit, which is a “don’t care” in Slave mode

A character may be received while in Sleep mode by setting the CREN bit prior to entering Sleep. Once the word is received, the RSR register will transfer the data to the RCREG register. If the RCIE enable bit is set, the interrupt generated will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will branch to the interrupt vector.

12.4.2.4 Synchronous Slave Reception Set-up:

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
3. If 9-bit reception is desired, set the RX9 bit.
4. Set the CREN bit to enable reception.
5. The RCIF bit will be set when reception is complete. An interrupt will be generated if the RCIE bit was set.
6. If 9-bit mode is enabled, retrieve the Most Significant bit from the RX9D bit of the RCSTA register.
7. Retrieve the 8 Least Significant bits from the receive FIFO by reading the RCREG register.
8. If an overrun error occurs, clear the error by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

TABLE 12-10: REGISTERS ASSOCIATED WITH SYNCHRONOUS SLAVE RECEPTION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
BAUDCTL	ABDOVF	RCIDL	—	SCKP	BRG16	—	WUE	ABDEN	01-0 0-00	01-0 0-00
INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
RCREG	EUSART Receive Data Register							0000 0000	0000 0000	
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 000x	0000 000x
SPBRG	BRG7	BRG6	BRG5	BRG4	BRG3	BRG2	BRG1	BRG0	0000 0000	0000 0000
SPBRGH	BRG15	BRG14	BRG13	BRG12	BRG11	BRG10	BRG9	BRG8	0000 0000	0000 0000
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111
TXREG	EUSART Transmit Data Register							0000 0000	0000 0000	
TXSTA	CSRC	TX9	TXEN	SYNC	SENDB	BRGH	TRMT	TX9D	0000 0010	0000 0010

Legend: x = unknown, — = unimplemented read as ‘0’. Shaded cells are not used for Synchronous Slave Reception.

12.5 EUSART Operation During Sleep

The EUSART WILL remain active during Sleep only in the Synchronous Slave mode. All other modes require the system clock and therefore cannot generate the necessary signals to run the Transmit or Receive Shift registers during Sleep.

Synchronous Slave mode uses an externally generated clock to run the Transmit and Receive Shift registers.

12.5.1 SYNCHRONOUS RECEIVE DURING SLEEP

To receive during Sleep, all the following conditions must be met before entering Sleep mode:

- RCSTA and TXSTA Control registers must be configured for Synchronous Slave Reception (see **Section 12.4.2.4 “Synchronous Slave Reception Set-up:”**).
- If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
- The RCIF interrupt flag must be cleared by reading RCREG to unload any pending characters in the receive buffer.

Upon entering Sleep mode, the device will be ready to accept data and clocks on the RX/DT and TX/CK pins, respectively. When the data word has been completely clocked in by the external device, the RCIF interrupt flag bit of the PIR1 register will be set. Thereby, waking the processor from Sleep.

Upon waking from Sleep, the instruction following the **SLEEP** instruction will be executed. If the GIE global interrupt enable bit of the INTCON register is also set, then the Interrupt Service Routine at address 004h will be called.

12.5.2 SYNCHRONOUS TRANSMIT DURING SLEEP

To transmit during Sleep, all the following conditions must be met before entering Sleep mode:

- RCSTA and TXSTA Control registers must be configured for Synchronous Slave Transmission (see **Section 12.4.2.2 “Synchronous Slave Transmission Set-up:”**).
- The TXIF interrupt flag must be cleared by writing the output data to the TXREG, thereby filling the TSR and transmit buffer.
- 9. If interrupts are desired, set the TXIE bit of the PIE1 register and the PEIE bit of the INTCON register.
- Interrupt enable bits TXIE of the PIE1 register and PEIE of the INTCON register must set.

Upon entering Sleep mode, the device will be ready to accept clocks on TX/CK pin and transmit data on the RX/DT pin. When the data word in the TSR has been completely clocked out by the external device, the pending byte in the TXREG will transfer to the TSR and the TXIF flag will be set. Thereby, waking the processor from Sleep. At this point, the TXREG is available to accept another character for transmission, which will clear the TXIF flag.

Upon waking from Sleep, the instruction following the **SLEEP** instruction will be executed. If the GIE global interrupt enable bit is also set then the Interrupt Service Routine at address 0004h will be called.

PIC16F882/883/884/886/887

NOTES:

13.0 MASTER SYNCHRONOUS SERIAL PORT (MSSP) MODULE

13.1 Master SSP (MSSP) Module Overview

The Master Synchronous Serial Port (MSSP) module is a serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be Serial EEPROMs, shift registers, display drivers, A/D converters, etc. The MSSP module can operate in one of two modes:

- Serial Peripheral Interface (SPI)
- Inter-Integrated Circuit™ (I^2C ™)
 - Full Master mode
 - Slave mode (with general address call).

The I^2C interface supports the following modes in hardware:

- Master mode
- Multi-Master mode
- Slave mode.

13.2 Control Registers

The MSSP module has three associated registers. These include a STATUS register and two control registers.

Register 13-1 shows the MSSP STATUS register (SSPSTAT), Register 13-2 shows the MSSP Control Register 1 (SSPCON), and Register 13-3 shows the MSSP Control Register 2 (SSPCON2).

PIC16F882/883/884/886/887

REGISTER 13-1: SSPSTAT: SSP STATUS REGISTER

R/W-0	R/W-0	R-0	R-0	R-0	R-0	R-0	R-0
SMP	CKE	D/A	P	S	R/W	UA	BF
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7

SMP: Sample bit

SPI Master mode:

1 = Input data sampled at end of data output time

0 = Input data sampled at middle of data output time

SPI Slave mode:

SMP must be cleared when SPI is used in Slave mode

In I²C Master or Slave mode:

1 = Slew rate control disabled for standard speed mode (100 kHz and 1 MHz)

0 = Slew rate control enabled for high speed mode (400 kHz)

bit 6

CKE: SPI Clock Edge Select bit

CKP = 0:

1 = Data transmitted on rising edge of SCK

0 = Data transmitted on falling edge of SCK

CKP = 1:

1 = Data transmitted on falling edge of SCK

0 = Data transmitted on rising edge of SCK

bit 5

D/A: Data/Address bit (I²C mode only)

1 = Indicates that the last byte received or transmitted was data

0 = Indicates that the last byte received or transmitted was address

bit 4

P: Stop bit

(I²C mode only. This bit is cleared when the MSSP module is disabled, SSPEN is cleared.)

1 = Indicates that a Stop bit has been detected last (this bit is '0' on Reset)

0 = Stop bit was not detected last

bit 3

S: Start bit

(I²C mode only. This bit is cleared when the MSSP module is disabled, SSPEN is cleared.)

1 = Indicates that a Start bit has been detected last (this bit is '0' on Reset)

0 = Start bit was not detected last

bit 2

R/W: Read/Write bit information (I²C mode only)

This bit holds the R/W bit information following the last address match. This bit is only valid from the address match to the next Start bit, Stop bit, or not ACK bit.

In I²C Slave mode:

1 = Read

0 = Write

In I²C Master mode:

1 = Transmit is in progress

0 = Transmit is not in progress

OR-ing this bit with SEN, RSEN, PEN, RCEN, or ACKEN will indicate if the MSSP is in Idle mode.

bit 1

UA: Update Address bit (10-bit I²C mode only)

1 = Indicates that the user needs to update the address in the SSPADD register

0 = Address does not need to be updated

bit 0

BF: Buffer Full Status bit

Receive (SPI and I²C modes):

1 = Receive complete, SSPBUF is full

0 = Receive not complete, SSPBUF is empty

Transmit (I²C mode only):

1 = Data transmit in progress (does not include the ACK and Stop bits), SSPBUF is full

0 = Data transmit complete (does not include the ACK and Stop bits), SSPBUF is empty

PIC16F882/883/884/886/887

REGISTER 13-2: SSPCON: SSP CONTROL REGISTER 1

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| WCOL | SSPOV | SSPEN | CKP | SSPM3 | SSPM2 | SSPM1 | SSPM0 |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	WCOL: Write Collision Detect bit <u>Master mode:</u> 1 = A write to the SSPBUF register was attempted while the I ² C conditions were not valid for a transmission to be started 0 = No collision <u>Slave mode:</u> 1 = The SSPBUF register is written while it is still transmitting the previous word (must be cleared in software) 0 = No collision
bit 6	SSPOV: Receive Overflow Indicator bit <u>In SPI mode:</u> 1 = A new byte is received while the SSPBUF register is still holding the previous data. In case of overflow, the data in SSPSR is lost. Overflow can only occur in Slave mode. In Slave mode, the user must read the SSPBUF, even if only transmitting data, to avoid setting overflow. In Master mode, the overflow bit is not set since each new reception (and transmission) is initiated by writing to the SSPBUF register (must be cleared in software). 0 = No overflow <u>In I²C mode:</u> 1 = A byte is received while the SSPBUF register is still holding the previous byte. SSPOV is a "don't care" in Transmit mode (must be cleared in software). 0 = No overflow
bit 5	SSPEN: Synchronous Serial Port Enable bit In both modes, when enabled, these pins must be properly configured as input or output <u>In SPI mode:</u> 1 = Enables serial port and configures SCK, SDO, SDI and SS as the source of the serial port pins 0 = Disables serial port and configures these pins as I/O port pins <u>In I²C mode:</u> 1 = Enables the serial port and configures the SDA and SCL pins as the source of the serial port pins 0 = Disables serial port and configures these pins as I/O port pins
bit 4	CKP: Clock Polarity Select bit <u>In SPI mode:</u> 1 = Idle state for clock is a high level 0 = Idle state for clock is a low level <u>In I²C Slave mode:</u> SCK release control 1 = Enable clock 0 = Holds clock low (clock stretch). (Used to ensure data setup time.) <u>In I²C Master mode:</u> Unused in this mode
bit 3-0	SSPM<3:0>: Synchronous Serial Port Mode Select bits 0000 = SPI Master mode, clock = Fosc/4 0001 = SPI Master mode, clock = Fosc/16 0010 = SPI Master mode, clock = Fosc/64 0011 = SPI Master mode, clock = TMR2 output/2 0100 = SPI Slave mode, clock = SCK pin, SS pin control enabled 0101 = SPI Slave mode, clock = SCK pin, SS pin control disabled, SS can be used as I/O pin 0110 = I ² C Slave mode, 7-bit address 0111 = I ² C Slave mode, 10-bit address 1000 = I ² C Master mode, clock = Fosc / (4 * (SSPADD+1)) 1001 = Load Mask function 1010 = Reserved 1011 = I ² C firmware controlled Master mode (Slave idle) 1100 = Reserved 1101 = Reserved 1110 = I ² C Slave mode, 7-bit address with Start and Stop bit interrupts enabled 1111 = I ² C Slave mode, 10-bit address with Start and Stop bit interrupts enabled

PIC16F882/883/884/886/887

REGISTER 13-3: SSPCON2: SSP CONTROL REGISTER 2

R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
GCEN	ACKSTAT	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7	GCEN: General Call Enable bit (in I ² C Slave mode only) 1 = Enable interrupt when a general call address (0000h) is received in the SSPSR 0 = General call address disabled
bit 6	ACKSTAT: Acknowledge Status bit (in I ² C Master mode only) <u>In Master Transmit mode:</u> 1 = Acknowledge was not received from slave 0 = Acknowledge was received from slave
bit 5	ACKDT: Acknowledge Data bit (in I ² C Master mode only) <u>In Master Receive mode:</u> Value transmitted when the user initiates an Acknowledge sequence at the end of a receive 1 = Not Acknowledge 0 = Acknowledge
bit 4	ACKEN: Acknowledge Sequence Enable bit (in I ² C Master mode only) <u>In Master Receive mode:</u> 1 = Initiate Acknowledge sequence on SDA and SCL pins, and transmit ACKDT data bit. Automatically cleared by hardware. 0 = Acknowledge sequence idle
bit 3	RCEN: Receive Enable bit (in I ² C Master mode only) 1 = Enables Receive mode for I ² C 0 = Receive idle
bit 2	PEN: Stop Condition Enable bit (in I ² C Master mode only) <u>SCK Release Control:</u> 1 = Initiate Stop condition on SDA and SCL pins. Automatically cleared by hardware. 0 = Stop condition Idle
bit 1	RSEN: Repeated Start Condition Enabled bit (in I ² C Master mode only) 1 = Initiate Repeated Start condition on SDA and SCL pins. Automatically cleared by hardware. 0 = Repeated Start condition Idle
bit 0	SEN: Start Condition Enabled bit (in I ² C Master mode only) <u>In Master mode:</u> 1 = Initiate Start condition on SDA and SCL pins. Automatically cleared by hardware. 0 = Start condition Idle <u>In Slave mode:</u> 1 = Clock stretching is enabled for both slave transmit and slave receive (stretch enabled) 0 = Clock stretching is disabled

Note 1: For bits ACKEN, RCEN, PEN, RSEN, SEN: If the I²C module is not in the Idle mode, this bit may not be set (no spooling) and the SSPBUF may not be written (or writes to the SSPBUF are disabled).

13.3 SPI Mode

The SPI mode allows 8 bits of data to be synchronously transmitted and received, simultaneously. All four modes of SPI are supported. To accomplish communication, typically three pins are used:

- Serial Data Out (SDO) – RC5/SDO
- Serial Data In (SDI) – RC4/SDI/SDA
- Serial Clock (SCK) – RC3/SCK/SCL

Additionally, a fourth pin may be used when in any Slave mode of operation:

- Slave Select (\overline{SS}) – RA5/ \overline{SS} /AN4

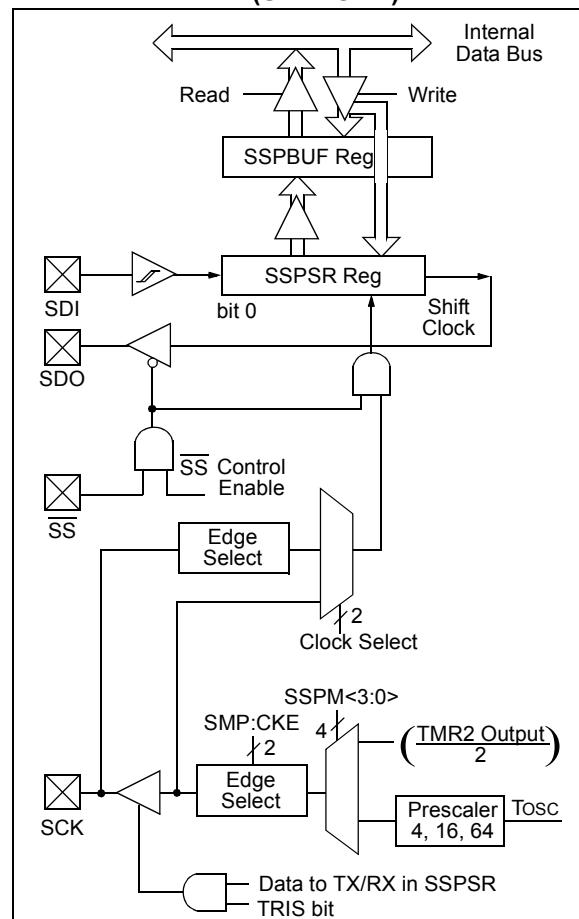
13.3.1 OPERATION

When initializing the SPI, several options need to be specified. This is done by programming the appropriate control bits $SSPCON<5:0>$ and $SSPSTAT<7:6>$. These control bits allow the following to be specified:

- Master mode (SCK is the clock output)
- Slave mode (SCK is the clock input)
- Clock polarity (Idle state of SCK)
- Data input sample phase (middle or end of data output time)
- Clock edge (output data on rising/falling edge of SCK)
- Clock rate (Master mode only)
- Slave Select mode (Slave mode only)

Figure 13-1 shows the block diagram of the MSSP module, when in SPI mode.

FIGURE 13-1: MSSP BLOCK DIAGRAM (SPI MODE)



Note: I/O pins have diode protection to VDD and Vss.

The MSSP consists of a transmit/receive shift register (SSPSR) and a buffer register (SSPBUF). The SSPSR shifts the data in and out of the device, MSb first. The SSPBUF holds the data that was written to the SSPSR, until the received data is ready. Once the 8 bits of data have been received, that byte is moved to the SSPBUF register. Then, the buffer full-detect bit BF of the SSPSTAT register and the interrupt flag bit SSPIF of the PIR1 register are set. This double buffering of the received data (SSPBUF) allows the next byte to start reception before reading the data that was just received. Any write to the SSPBUF register during transmission/reception of data will be ignored, and the write collision detect bit WCOL of the SSPCON register will be set. User software must clear the WCOL bit so that it can be determined if the following write(s) to the SSPBUF register completed successfully.

PIC16F882/883/884/886/887

When the application software is expecting to receive valid data, the SSPBUF should be read before the next byte of data to transfer is written to the SSPBUF. The buffer full bit BF of the SSPSTAT register indicates when SSPBUF has been loaded with the received data (transmission is complete). When the SSPBUF is read, the BF bit is cleared. This data may be irrelevant if the SPI is only a transmitter. Generally, the MSSP Interrupt is used to determine when the transmission/reception has completed. The SSPBUF must be read and/or written. If the interrupt method is not going to be used, then software polling can be done to ensure that a write collision does not occur. Example 13-1 shows the loading of the SSPBUF (SSPSR) for data transmission.

The SSPSR is not directly readable or writable, and can only be accessed by addressing the SSPBUF register. Additionally, the MSSP STATUS register (SSPSTAT register) indicates the various status conditions.

13.3.2 ENABLING SPI I/O

To enable the serial port, SSP Enable bit SSPEN of the SSPCON register must be set. To reset or reconfigure SPI mode, clear the SSPEN bit, re-initialize the SSPCON registers, and then set the SSPEN bit. This configures the SDI, SDO, SCK and SS pins as serial port pins. For the pins to behave as the serial port function, some must have their data direction bits (in the TRIS register) appropriately programmed. That is:

- SDI is automatically controlled by the SPI module
- SDO must have TRISC<5> bit cleared
- SCK (Master mode) must have TRISC<3> bit cleared
- SCK (Slave mode) must have TRISC<3> bit set
- SS must have TRISA<5> bit set

Any serial port function that is not desired may be overridden by programming the corresponding data direction (TRIS) register to the opposite value.

EXAMPLE 13-1: LOADING THE SSPBUF (SSPSR) REGISTER

```
LOOP BTFS  SSPSTAT, BF      ;Has data been received (transmit complete)?
    GOTO  LOOP                ;No
    MOVF  SSPBUF, W            ;WREG reg = contents of SSPBUF
    MOVWF RXDATA              ;Save in user RAM, if data is meaningful
    MOVF  TXDATA, W            ;W reg = contents of TXDATA
    MOVWF SSPBUF               ;New data to xmit
```

13.3.3 MASTER MODE

The master can initiate the data transfer at any time because it controls the SCK. The master determines when the slave is to broadcast data by the software protocol.

In Master mode, the data is transmitted/received as soon as the SSPBUF register is written to. If the SPI is only going to receive, the SDO output could be disabled (programmed as an input). The SSPSR register will continue to shift in the signal present on the SDI pin at the programmed clock rate. As each byte is received, it will be loaded into the SSPBUF register as a normal received byte (interrupts and Status bits appropriately set). This could be useful in receiver applications as a "Line Activity Monitor" mode.

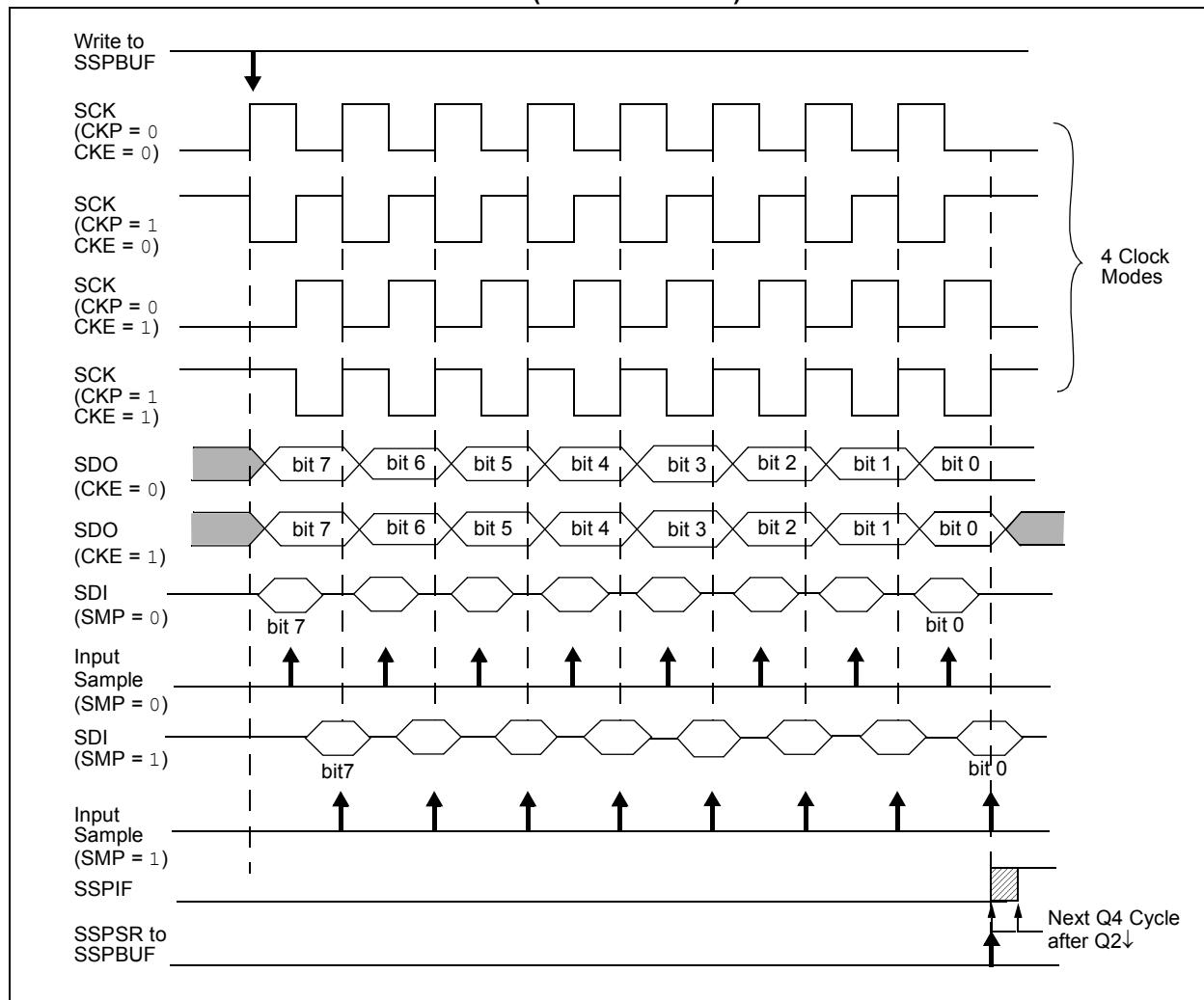
The clock polarity is selected by appropriately programming the CKP bit of the SSPCON register. This, then, would give waveforms for SPI communication as shown in Figure 13-2, Figure 13-4 and Figure 13-5, where the MSb is transmitted first. In Master mode, the SPI clock rate (bit rate) is user programmable to be one of the following:

- Fosc/4 (or T_{CY})
- Fosc/16 (or 4 • T_{CY})
- Fosc/64 (or 16 • T_{CY})
- Timer2 output/2

This allows a maximum data rate (at 40 MHz) of 10.00 Mbps.

Figure 13-2 shows the waveforms for Master mode. When the CKE bit of the SSPSTAT register is set, the SDO data is valid before there is a clock edge on SCK. The change of the input sample is shown based on the state of the SMP bit of the SSPSTAT register. The time when the SSPBUF is loaded with the received data is shown.

FIGURE 13-2: SPI MODE WAVEFORM (MASTER MODE)



PIC16F882/883/884/886/887

13.3.4 SLAVE MODE

In Slave mode, the data is transmitted and received as the external clock pulses appear on SCK. When the last bit is latched, the SSPIF interrupt flag bit of the PIR1 register is set.

While in Slave mode, the external clock is supplied by the external clock source on the SCK pin. This external clock must meet the minimum high and low times, as specified in the electrical specifications.

While in Sleep mode, the slave can transmit/receive data. When a byte is received, the device will wake-up from Sleep.

13.3.5 SLAVE SELECT SYNCHRONIZATION

The SS pin allows a Synchronous Slave mode. The SPI must be in Slave mode with SS pin control enabled (SSPCON<3:0> = 04h). The pin must not be driven low for the SS pin to function as an input. The Data Latch must be high. When the SS pin is low, transmission and reception are enabled and the SDO pin is driven. When the SS pin goes high,

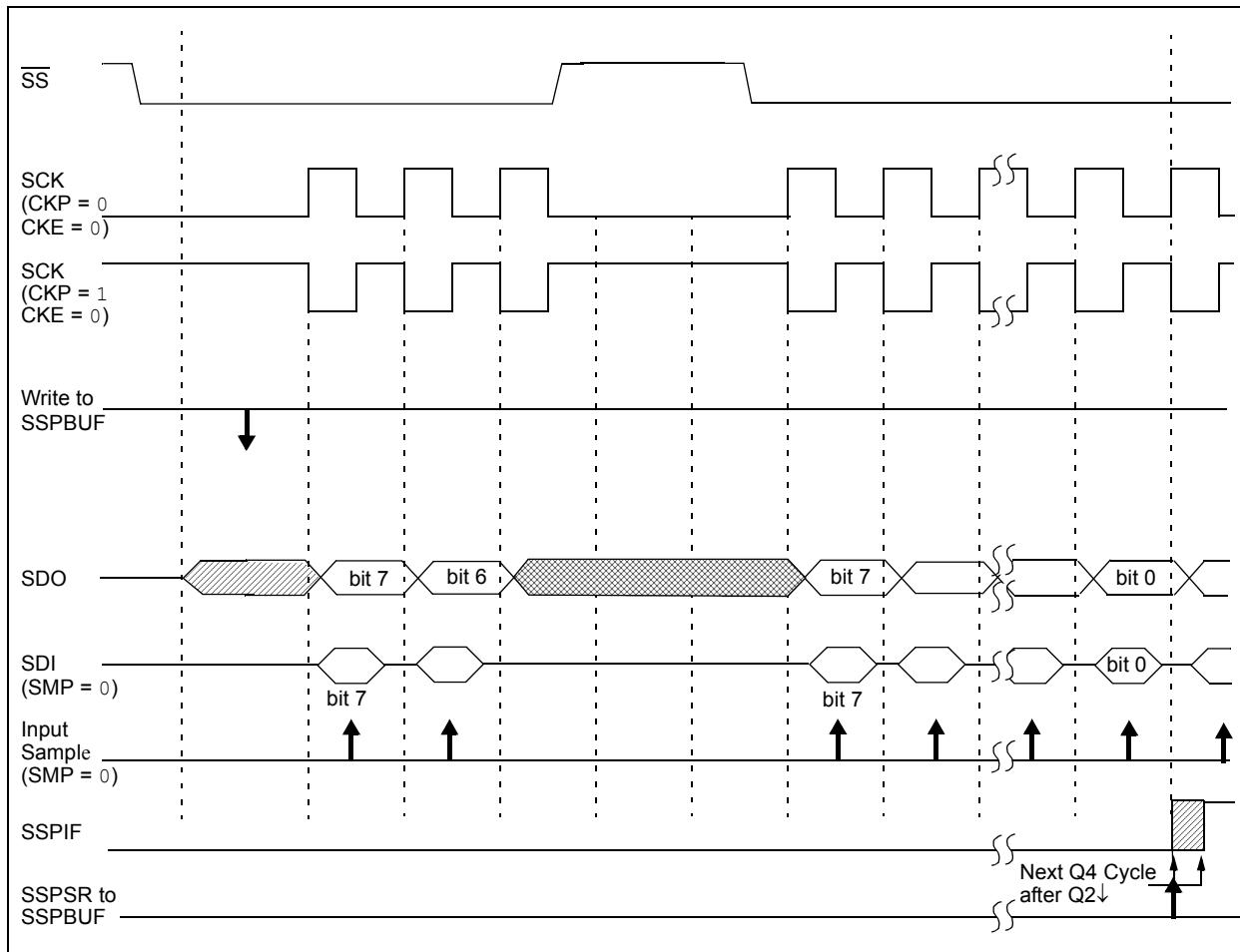
the SDO pin is no longer driven, even if in the middle of a transmitted byte, and becomes a floating output. External pull-up/pull-down resistors may be desirable, depending on the application.

- Note 1:** When the SPI is in Slave mode with SS pin control enabled (SSPCON<3:0> = 0100), the SPI module will reset if the SS pin is set to VDD.
- 2:** If the SPI is used in Slave mode with CKE set (SSPSTAT register), then the SS pin control must be enabled.

When the SPI module resets, the bit counter is forced to '0'. This can be done by either forcing the SS pin to a high level, or clearing the SSPEN bit.

To emulate two-wire communication, the SDO pin can be connected to the SDI pin. When the SPI needs to operate as a receiver, the SDO pin can be configured as an input. This disables transmissions from the SDO. The SDI can always be left as an input (SDI function), since it cannot create a bus conflict.

FIGURE 13-3: SLAVE SYNCHRONIZATION WAVEFORM



PIC16F882/883/884/886/887

FIGURE 13-4: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 0)

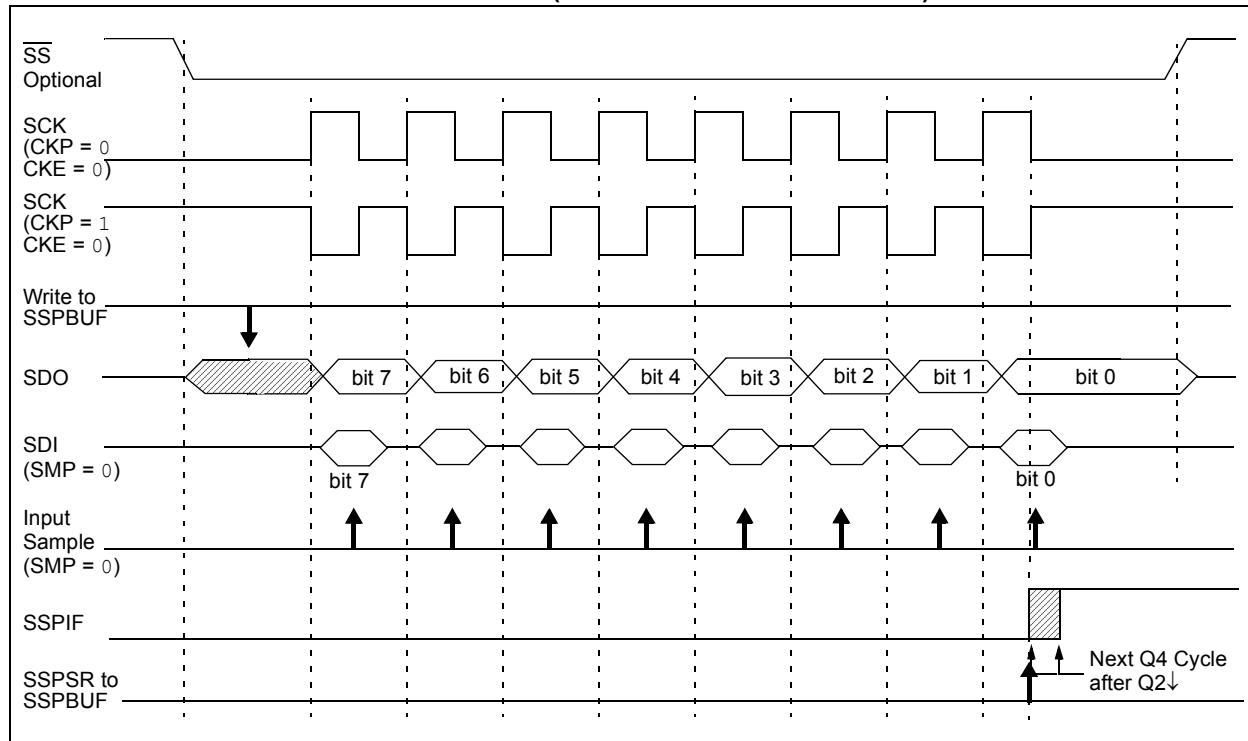
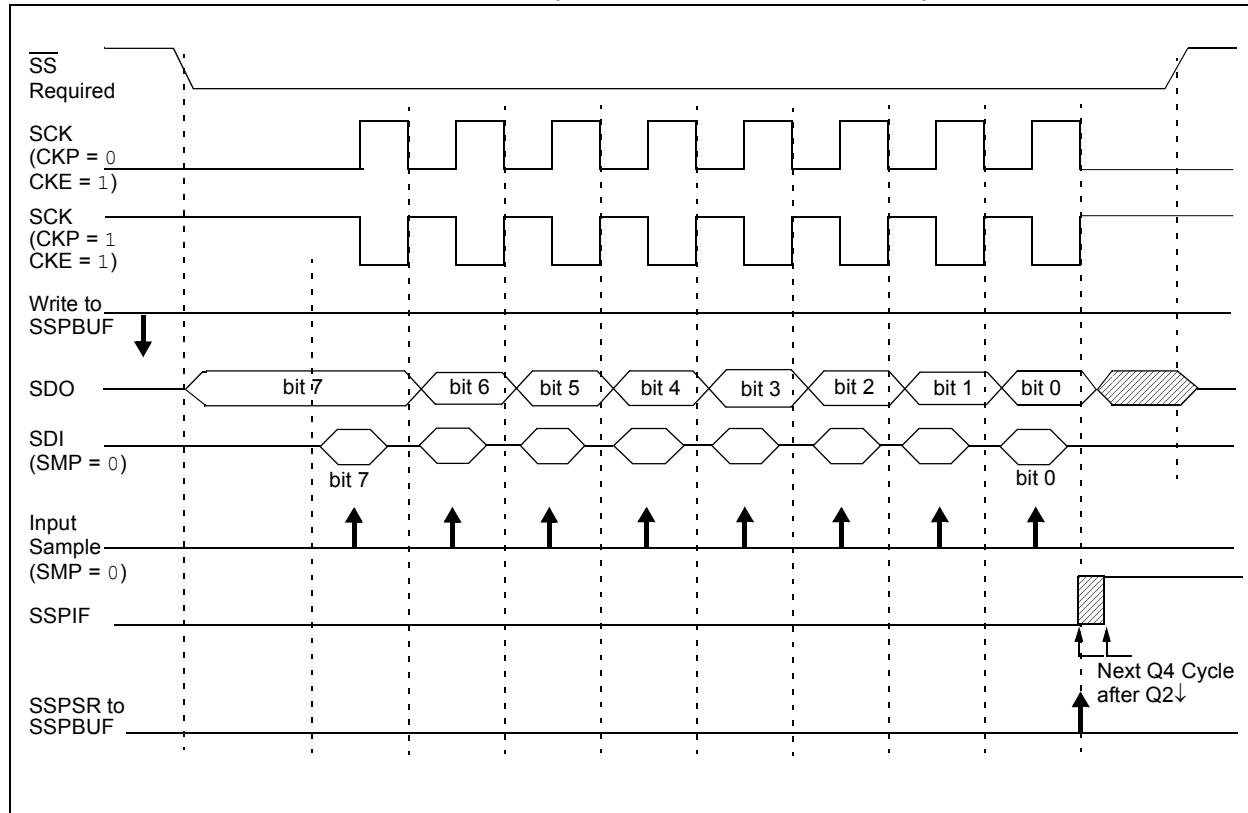


FIGURE 13-5: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 1)



PIC16F882/883/884/886/887

13.3.6 SLEEP OPERATION

In Master mode, all module clocks are halted, and the transmission/reception will remain in that state until the device wakes from Sleep. After the device returns to normal mode, the module will continue to transmit/receive data.

In Slave mode, the SPI transmit/receive shift register operates asynchronously to the device. This allows the device to be placed in Sleep mode and data to be shifted into the SPI transmit/receive shift register. When all eight bits have been received, the MSSP interrupt flag bit will be set and, if enabled, will wake the device from Sleep.

13.3.7 EFFECTS OF A RESET

A Reset disables the MSSP module and terminates the current transfer.

13.3.8 BUS MODE COMPATIBILITY

Table 13-1 shows the compatibility between the standard SPI modes and the states of the CKP and CKE control bits.

TABLE 13-1: SPI BUS MODES

Standard SPI Mode Terminology	Control Bits State	
	CKP	CKE
0, 0	0	1
0, 1	0	0
1, 0	1	1
1, 1	1	0

There is also a SMP bit that controls when the data will be sampled.

TABLE 13-2: REGISTERS ASSOCIATED WITH SPI OPERATION

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other RESETS
INTCON	GIE/GIEH	PEIE/GIEL	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000u
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	0000 0000
SSPBUF	Synchronous Serial Port Receive Buffer/Transmit Register								xxxx xxxx	uuuu uuuu
SSPCON	WCOL	SSPOV	SSPEN	CKP	SSPM3	SSPM2	SSPM1	SSPM0	0000 0000	0000 0000
SSPSTAT	SMP	CKE	D/A	P	S	R/W	UA	BF	0000 0000	0000 0000
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	1111 1111	1111 1111
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	1111 1111	1111 1111

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used by the MSSP in SPI mode.

Note 1: Bit 6 of PORTA, LATA and TRISA are enabled in ECIO and RCIO Oscillator modes only. In all other oscillator modes, they are disabled and read '0'.

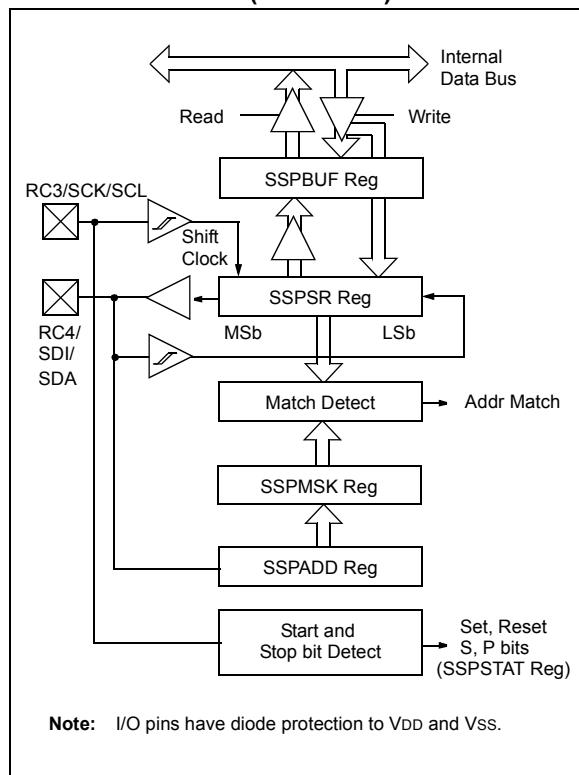
13.4 MSSP I²C Operation

The MSSP module in I²C mode, fully implements all master and slave functions (including general call support) and provides interrupts on Start and Stop bits in hardware, to determine a free bus (Multi-Master mode). The MSSP module implements the standard mode specifications, as well as 7-bit and 10-bit addressing.

Two pins are used for data transfer. These are the RC3/SCK/SCL pin, which is the clock (SCL), and the RC4/SDI/SDA pin, which is the data (SDA). The user must configure these pins as inputs or outputs through the TRISC<4:3> bits.

The MSSP module functions are enabled by setting MSSP Enable bit SSPEN of the SSPCON register.

FIGURE 13-6: MSSP BLOCK DIAGRAM (I²C MODE)



The MSSP module has these six registers for I²C operation:

- MSSP Control Register 1 (SSPCON)
- MSSP Control Register 2 (SSPCON2)
- MSSP STATUS register (SSPSTAT)
- Serial Receive/Transmit Buffer (SSPBUF)
- MSSP Shift Register (SSPSR) – Not directly accessible
- MSSP Address register (SSPADD)
- MSSP Mask register (SSPMSK)

The SSPCON register allows control of the I²C operation. The SSPM<3:0> mode selection bits (SSPCON register) allow one of the following I²C modes to be selected:

- I²C Master mode, clock = OSC/4 (SSPADD +1)
- I²C Slave mode (7-bit address)
- I²C Slave mode (10-bit address)
- I²C Slave mode (7-bit address), with Start and Stop bit interrupts enabled
- I²C Slave mode (10-bit address), with Start and Stop bit interrupts enabled
- I²C firmware controlled master operation, slave is idle

Selection of any I²C mode with the SSPEN bit set, forces the SCL and SDA pins to be open drain, provided these pins are programmed to be inputs by setting the appropriate TRISC bits.

13.4.1 SLAVE MODE

In Slave mode, the SCL and SDA pins must be configured as inputs (TRISC<4:3> set). The MSSP module will override the input state with the output data when required (slave-transmitter).

When an address is matched, or the data transfer after an address match is received, the hardware automatically will generate the Acknowledge (ACK) pulse and load the SSPBUF register with the received value currently in the SSPSR register.

If either or both of the following conditions are true, the MSSP module will not give this ACK pulse:

- The buffer full bit BF (SSPCON register) was set before the transfer was received.
- The overflow bit SSPOV (SSPCON register) was set before the transfer was received.

In this event, the SSPSR register value is not loaded into the SSPBUF, but bit SSPIF of the PIR1 register is set. The BF bit is cleared by reading the SSPBUF register, while bit SSPOV is cleared through software.

The SCL clock input must have a minimum high and low for proper operation. The high and low times of the I²C specification, as well as the requirement of the MSSP module, are shown in timing parameter #100 and parameter #101.

13.4.1.1 Addressing

Once the MSSP module has been enabled, it waits for a Start condition to occur. Following the Start condition, the eight bits are shifted into the SSPSR register. All incoming bits are sampled with the rising edge of the clock (SCL) line. The value of register SSPSR<7:1> is compared to the value of the SSPADD register. The address is compared on the falling edge of the eighth clock (SCL) pulse. If the addresses match, and the BF and SSPOV bits are clear, the following events occur:

- a) The SSPSR register value is loaded into the SSPBUF register.
- b) The buffer full bit BF is set.
- c) An ACK pulse is generated.
- d) MSSP interrupt flag bit, SSPIF of the PIR1 register, is set on the falling edge of the ninth SCL pulse (interrupt is generated, if enabled).

In 10-bit address mode, two address bytes need to be received by the slave. The five Most Significant bits (MSb) of the first address byte specify if this is a 10-bit address. The R/W bit (SSPSTAT register) must specify a write so the slave device will receive the second address byte. For a 10-bit address, the first byte would equal '1111 0 A9 A8 0', where A9 and A8 are the two MSb's of the address.

The sequence of events for 10-bit addressing is as follows, with steps 7-9 for slave-transmitter:

1. Receive first (high) byte of address (bit SSPIF of the PIR1 register and bits BF and UA of the SSPSTAT register are set).
2. Update the SSPADD register with second (low) byte of address (clears bit UA and releases the SCL line).
3. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.
4. Receive second (low) byte of address (bits SSPIF, BF, and UA are set).
5. Update the SSPADD register with the first (high) byte of address. If match releases SCL line, this will clear bit UA.
6. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.
7. Receive Repeated Start condition.
8. Receive first (high) byte of address (bits SSPIF and BF are set).
9. Read the SSPBUF register (clears bit BF) and clear flag bit SSPIF.

13.4.1.2 Reception

When the R/W bit of the address byte is clear and an address match occurs, the R/W bit of the SSPSTAT register is cleared. The received address is loaded into the SSPBUF register.

When the address byte overflow condition exists, then no Acknowledge (ACK) pulse is given. An overflow condition is defined as either bit BF (SSPSTAT register) is set, or bit SSPOV (SSPCON register) is set.

An MSSP interrupt is generated for each data transfer byte. Flag bit SSPIF of the PIR1 register must be cleared in software. The SSPSTAT register is used to determine the status of the byte.

13.4.1.3 Transmission

When the R/W bit of the incoming address byte is set and an address match occurs, the R/W bit of the SSPSTAT register is set. The received address is loaded into the SSPBUF register. The ACK pulse will be sent on the ninth bit and pin RC3/SCK/SCL is held low. The transmit data must be loaded into the SSPBUF register, which also loads the SSPSR register. Then pin RC3/SCK/SCL should be enabled by setting bit CKP (SSPCON register). The master must monitor the SCL pin prior to asserting another clock pulse. The slave devices may be holding off the master by stretching the clock. The eight data bits are shifted out on the falling edge of the SCL input. This ensures that the SDA signal is valid during the SCL high time (Figure 13-8).

An MSSP interrupt is generated for each data transfer byte. The SSPIF bit must be cleared in software and the SSPSTAT register is used to determine the status of the byte. The SSPIF bit is set on the falling edge of the ninth clock pulse.

As a slave-transmitter, the ACK pulse from the master-receiver is latched on the rising edge of the ninth SCL input pulse. If the SDA line is high (not ACK), then the data transfer is complete. When the ACK is latched by the slave, the slave logic is reset and the slave monitors for another occurrence of the Start bit. If the SDA line was low (ACK), the transmit data must be loaded into the SSPBUF register, which also loads the SSPSR register. Pin RC3/SCK/SCL should be enabled by setting bit CKP.

FIGURE 13-7: I²C™ SLAVE MODE WAVEFORMS FOR RECEPTION (7-BIT ADDRESS)

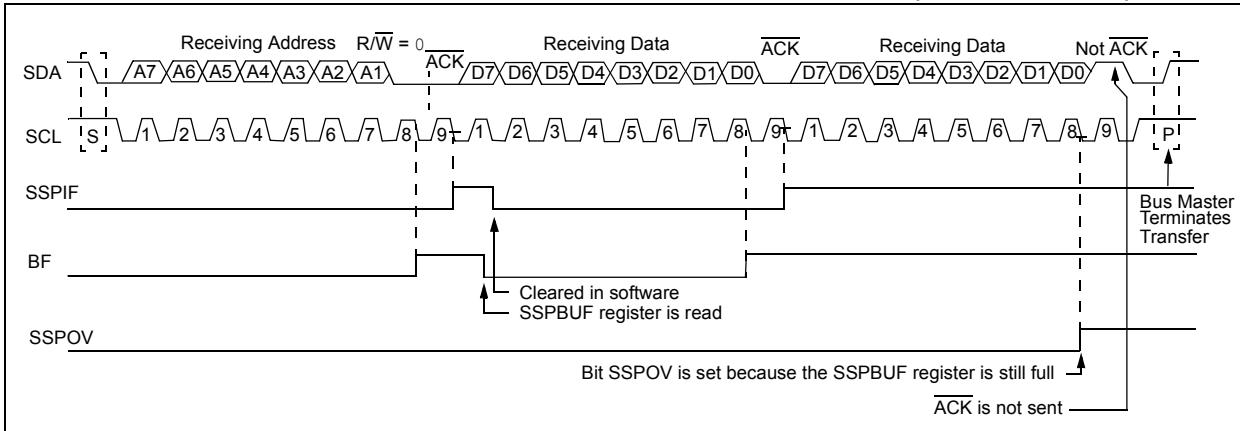
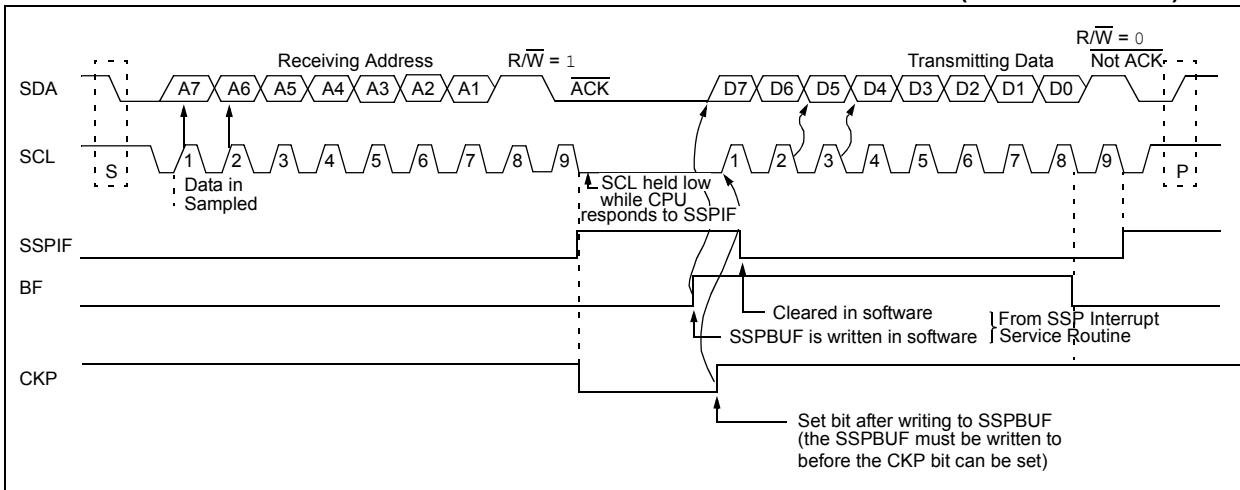


FIGURE 13-8: I²C™ SLAVE MODE WAVEFORMS FOR TRANSMISSION (7-BIT ADDRESS)



PIC16F882/883/884/886/887

13.4.2 GENERAL CALL ADDRESS SUPPORT

The addressing procedure for the I²C bus is such that, the first byte after the Start condition usually determines which device will be the slave addressed by the master. The exception is the general call address, which can address all devices. When this address is used, all devices should, in theory, respond with an Acknowledge.

The general call address is one of eight addresses reserved for specific purposes by the I²C protocol. It consists of all 0's with R/W = 0.

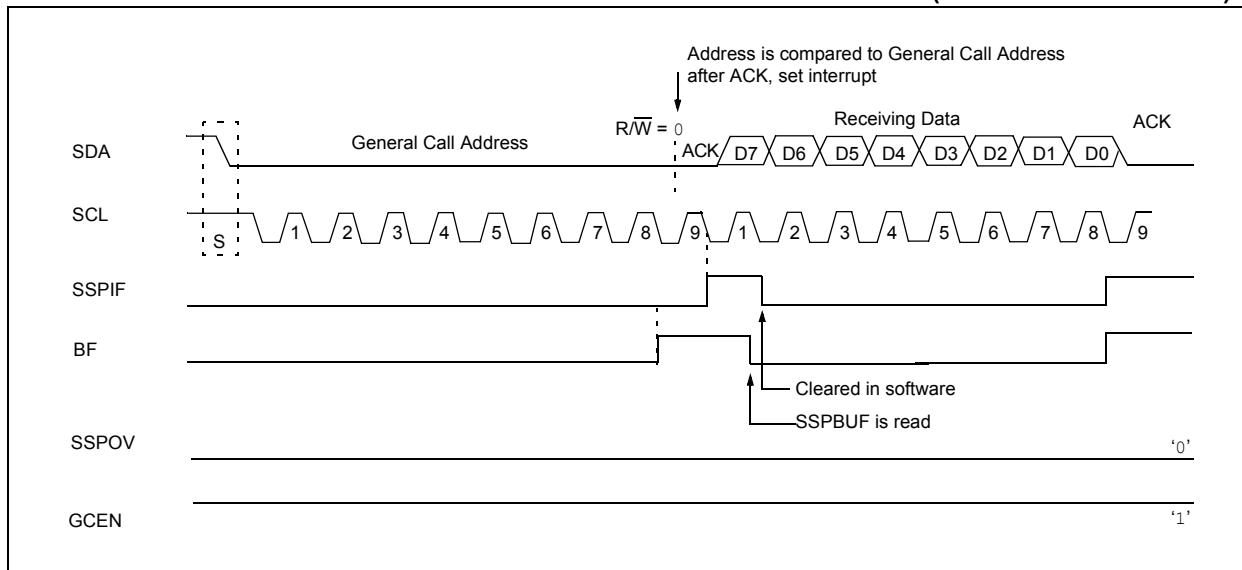
The general call address is recognized (enabled) when the General Call Enable (GCEN) bit is set (SSPCON2 register). Following a Start bit detect, eight bits are shifted into the SSPSR and the address is compared against the SSPADD. It is also compared to the general call address and fixed in hardware.

If the general call address matches, the SSPSR is transferred to the SSPBUF, the BF bit is set (eighth bit), and on the falling edge of the ninth bit (ACK bit), the SSPIF interrupt flag bit is set.

When the interrupt is serviced, the source for the interrupt can be checked by reading the contents of the SSPBUF. The value can be used to determine if the address was device specific or a general call address.

In 10-bit mode, the SSPADD is required to be updated for the second half of the address to match, and the UA bit is set (SSPSTAT register). If the general call address is sampled when the GCEN bit is set, and while the slave is configured in 10-bit address mode, then the second half of the address is not necessary. The UA bit will not be set, and the slave will begin receiving data after the Acknowledge (Figure 13-9).

FIGURE 13-9: SLAVE MODE GENERAL CALL ADDRESS SEQUENCE (7 OR 10-BIT ADDRESS)



13.4.3 MASTER MODE

Master mode of operation is supported by interrupt generation on the detection of the Start and Stop conditions. The Stop (P) and Start (S) bits are cleared from a Reset, or when the MSSP module is disabled. Control of the I²C bus may be taken when the P bit is set, or the bus is idle, with both the S and P bits clear.

In Master mode, the SCL and SDA lines are manipulated by the MSSP hardware.

The following events will cause SSP Interrupt Flag bit, SSPIF, to be set (SSP Interrupt if enabled):

- Start condition
- Stop condition
- Data transfer byte transmitted/received
- Acknowledge transmit
- Repeated Start condition

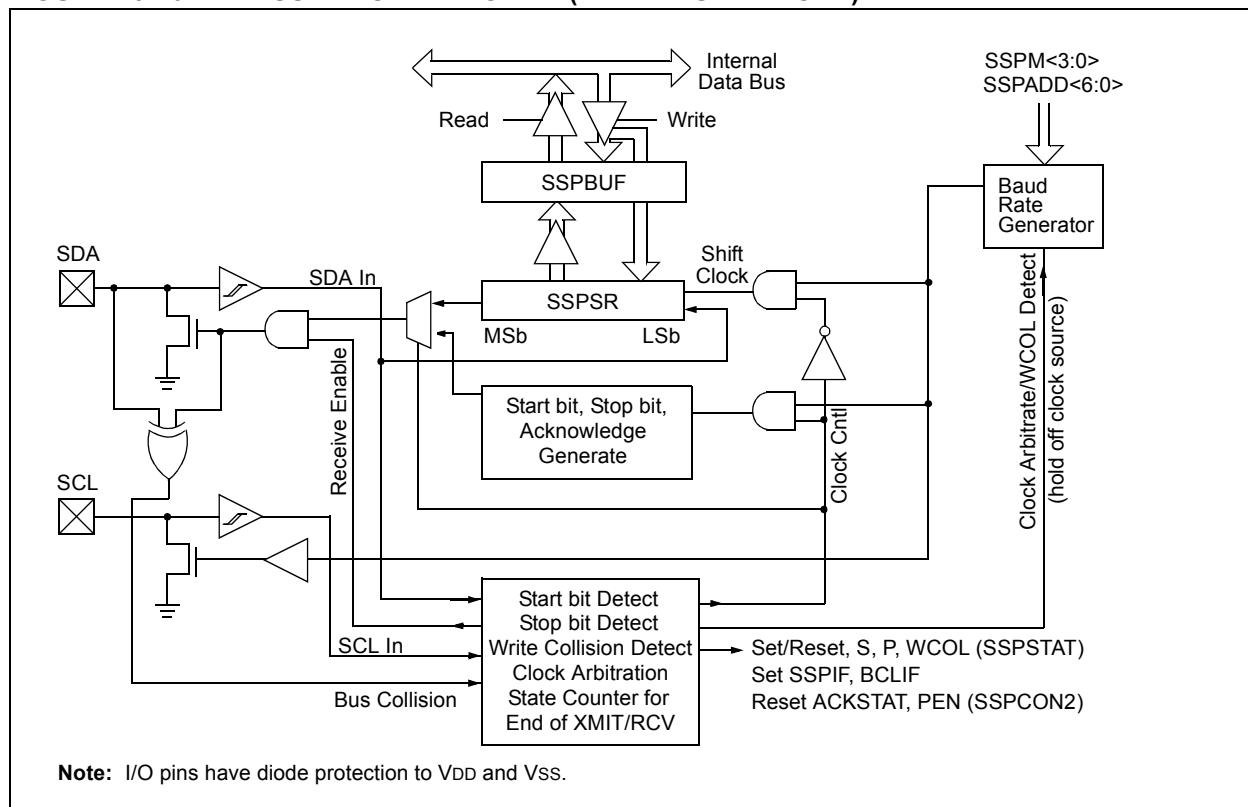
13.4.4 I²C™ MASTER MODE SUPPORT

Master mode is enabled by setting and clearing the appropriate SSPM bits in SSPCON and by setting the SSPEN bit. Once Master mode is enabled, the user has the following six options:

1. Assert a Start condition on SDA and SCL.
2. Assert a Repeated Start condition on SDA and SCL.
3. Write to the SSPBUF register initiating transmission of data/address.
4. Generate a Stop condition on SDA and SCL.
5. Configure the I²C port to receive data.
6. Generate an Acknowledge condition at the end of a received byte of data.

Note: The MSSP module, when configured in I²C Master mode, does not allow queueing of events. For instance, the user is not allowed to initiate a Start condition and immediately write the SSPBUF register to initiate transmission, before the Start condition is complete. In this case, the SSPBUF will not be written to and the WCOL bit will be set, indicating that a write to the SSPBUF did not occur.

FIGURE 13-10: MSSP BLOCK DIAGRAM (I²C™ MASTER MODE)



13.4.4.1 I²C™ Master Mode Operation

The master device generates all of the serial clock pulses and the Start and Stop conditions. A transfer is ended with a Stop condition or with a Repeated Start condition. Since the Repeated Start condition is also the beginning of the next serial transfer, the I²C bus will not be released.

In Master Transmitter mode, serial data is output through SDA, while SCL outputs the serial clock. The first byte transmitted contains the slave address of the receiving device (7 bits) and the Read/Write (R/W) bit. In this case, the R/W bit will be logic '0'. Serial data is transmitted eight bits at a time. After each byte is transmitted, an Acknowledge bit is received. Start and Stop conditions are output to indicate the beginning and the end of a serial transfer.

In Master Receive mode, the first byte transmitted contains the slave address of the transmitting device (7 bits) and the R/W bit. In this case, the R/W bit will be logic '1'. Thus, the first byte transmitted is a 7-bit slave address followed by a '1' to indicate receive bit. Serial data is received via SDA, while SCL outputs the serial clock. Serial data is received eight bits at a time. After each byte is received, an Acknowledge bit is transmitted. Start and Stop conditions indicate the beginning and end of transmission.

The Baud Rate Generator used for the SPI mode operation is now used to set the SCL clock frequency for either 100 kHz, 400 kHz, or 1 MHz I²C operation. The Baud Rate Generator reload value is contained in the lower 7 bits of the SSPADD register. The Baud Rate Generator will automatically begin counting on a write to the SSPBUF. Once the given operation is complete (i.e., transmission of the last data bit is followed by ACK), the internal clock will automatically stop counting and the SCL pin will remain in its last state.

A typical transmit sequence would go as follows:

- a) The user generates a Start condition by setting the Start Enable (SEN) bit (SSPCON2 register).
- b) SSPIF is set. The MSSP module will wait the required start time before any other operation takes place.
- c) The user loads the SSPBUF with the address to transmit.
- d) Address is shifted out the SDA pin until all eight bits are transmitted.
- e) The MSSP module shifts in the ACK bit from the slave device and writes its value into the ACKSTAT bit (SSPCON2 register).
- f) The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPIF bit.
- g) The user loads the SSPBUF with eight bits of data.
- h) Data is shifted out the SDA pin until all eight bits are transmitted.
- i) The MSSP module shifts in the ACK bit from the slave device and writes its value into the ACKSTAT bit (SSPCON2 register).
- j) The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPIF bit.
- k) The user generates a Stop condition by setting the Stop Enable bit PEN (SSPCON2 register).
- l) Interrupt is generated once the Stop condition is complete.

13.4.5 BAUD RATE GENERATOR

In I²C Master mode, the reload value for the BRG is located in the lower 7 bits of the SSPADD register (Figure 13-11). When the BRG is loaded with this value, the BRG counts down to 0 and stops until another reload has taken place. The BRG count is decremented twice per instruction cycle (TCY) on the Q2 and Q4 clocks. In I²C Master mode, the BRG is reloaded automatically. If clock arbitration is taking place, for instance, the BRG will be reloaded when the SCL pin is sampled high (Figure 13-12).

FIGURE 13-11: BAUD RATE GENERATOR BLOCK DIAGRAM

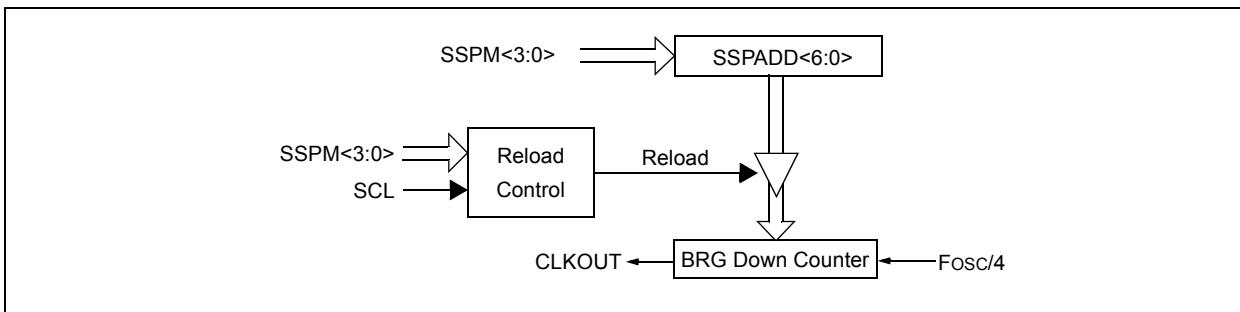
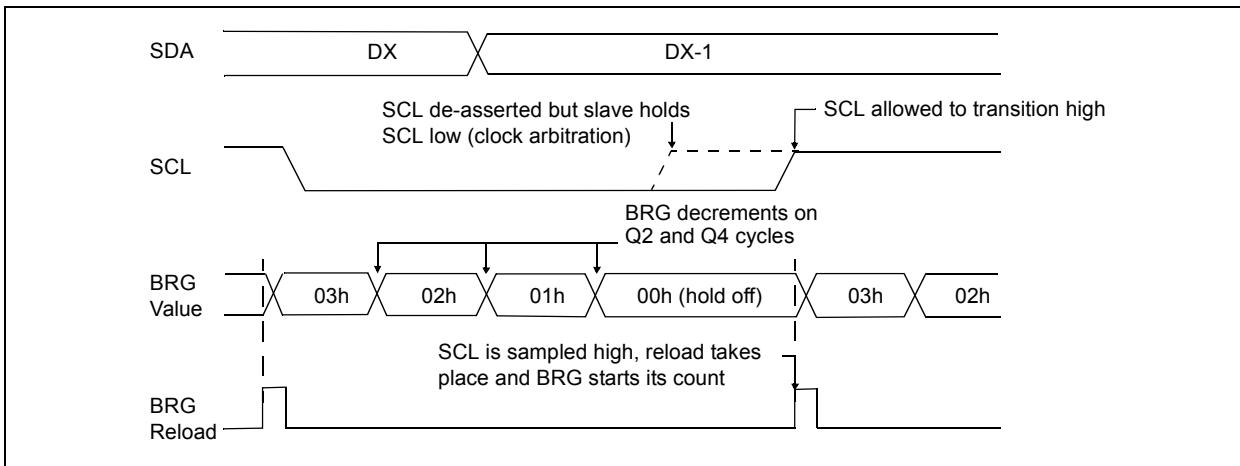


FIGURE 13-12: BAUD RATE GENERATOR TIMING WITH CLOCK ARBITRATION



PIC16F882/883/884/886/887

13.4.6 I²C™ MASTER MODE START CONDITION TIMING

To initiate a Start condition, the user sets the Start Condition Enable bit SEN of the SSPCON2 register. If the SDA and SCL pins are sampled high, the Baud Rate Generator is reloaded with the contents of SSPADD<6:0> and starts its count. If SCL and SDA are both sampled high when the Baud Rate Generator times out (TBRG), the SDA pin is driven low. The action of the SDA being driven low, while SCL is high, is the Start condition, and causes the S bit of the SSPSTAT register to be set. Following this, the Baud Rate Generator is reloaded with the contents of SSPADD<6:0> and resumes its count. When the Baud Rate Generator times out (TBRG), the SEN bit of the SSPCON2 register will be automatically cleared by hardware, the Baud Rate Generator is suspended leaving the SDA line held low and the Start condition is complete.

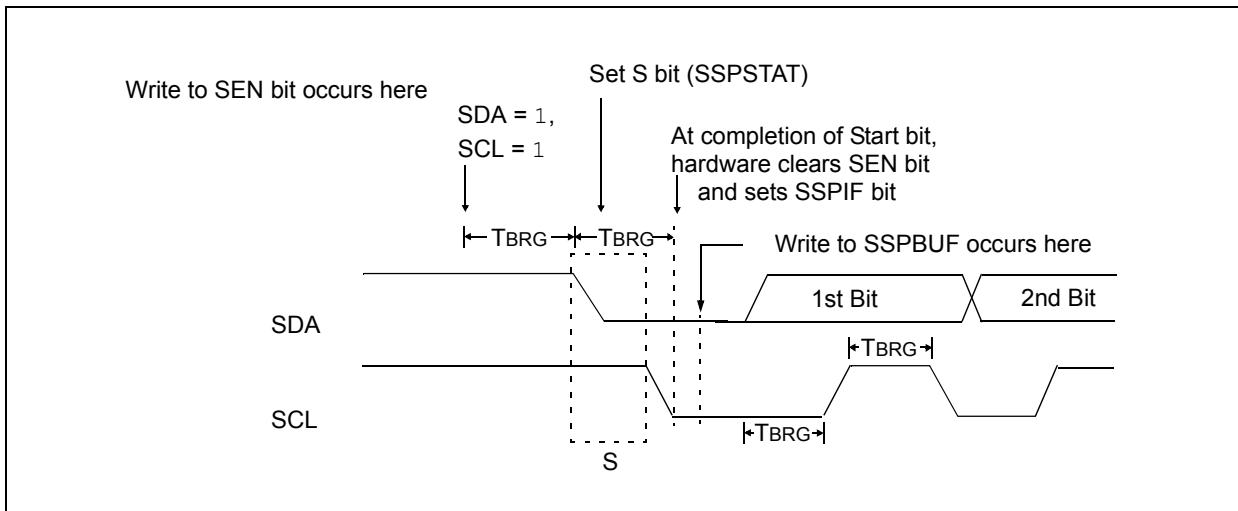
Note: If, at the beginning of the Start condition, the SDA and SCL pins are already sampled low, or if during the Start condition the SCL line is sampled low before the SDA line is driven low, a bus collision occurs, the Bus Collision Interrupt Flag, BCLIF, is set, the Start condition is aborted, and the I²C module is reset into its Idle state.

13.4.6.1 WCOL Status Flag

If the user writes the SSPBUF when a Start sequence is in progress, the WCOL is set and the contents of the buffer are unchanged (the write doesn't occur).

Note: Because queueing of events is not allowed, writing to the lower 5 bits of SSPCON2 is disabled until the Start condition is complete.

FIGURE 13-13: FIRST START BIT TIMING



13.4.7 I²C™ MASTER MODE REPEATED START CONDITION TIMING

A Repeated Start condition occurs when the RSEN bit (SSPCON2 register) is programmed high and the I²C logic module is in the Idle state. When the RSEN bit is set, the SCL pin is asserted low. When the SCL pin is sampled low, the Baud Rate Generator is loaded with the contents of SSPADD<5:0> and begins counting. The SDA pin is released (brought high) for one Baud Rate Generator count (TBRG). When the Baud Rate Generator times out, if SDA is sampled high, the SCL pin will be de-asserted (brought high). When SCL is sampled high, the Baud Rate Generator is reloaded with the contents of SSPADD<6:0> and begins counting. SDA and SCL must be sampled high for one TBRG. This action is then followed by assertion of the SDA pin (SDA = 0) for one TBRG, while SCL is high. Following this, the RSEN bit (SSPCON2 register) will be automatically cleared and the Baud Rate Generator will not be reloaded, leaving the SDA pin held low. As soon as a Start condition is detected on the SDA and SCL pins, the S bit (SSPSTAT register) will be set. The SSPIF bit will not be set until the Baud Rate Generator has timed out.

Note 1: If RSEN is programmed while any other event is in progress, it will not take effect.

2: A bus collision during the Repeated Start condition occurs if:

- SDA is sampled low when SCL goes from low-to-high.
- SCL goes low before SDA is asserted low. This may indicate that another master is attempting to transmit a data "1".

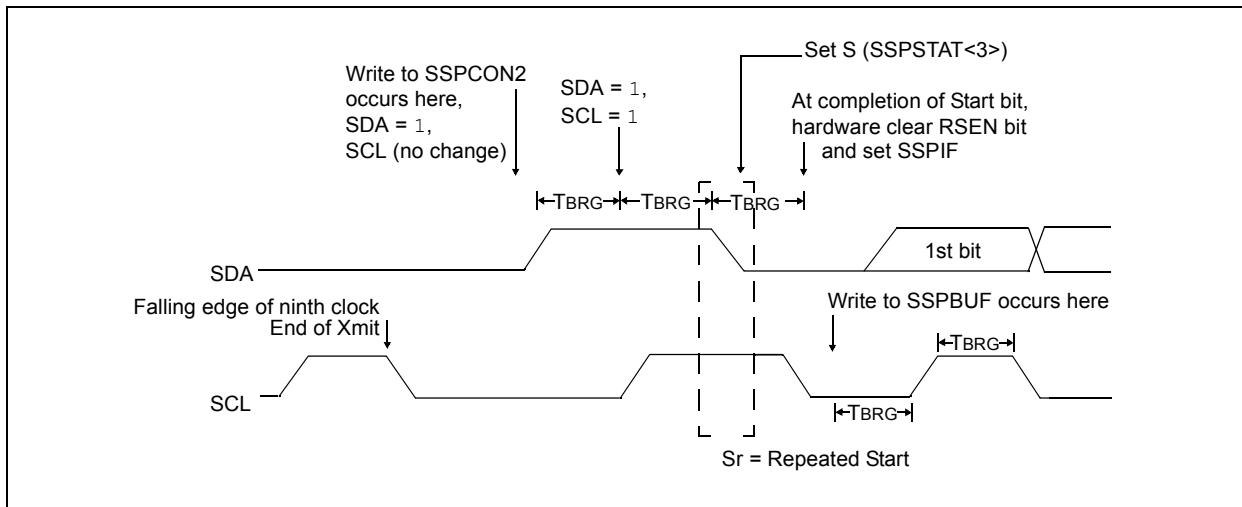
Immediately following the SSPIF bit getting set, the user may write the SSPBUF with the 7-bit address in 7-bit mode, or the default first address in 10-bit mode. After the first eight bits are transmitted and an ACK is received, the user may then transmit an additional eight bits of address (10-bit mode), or eight bits of data (7-bit mode).

13.4.7.1 WCOL Status Flag

If the user writes the SSPBUF when a Repeated Start sequence is in progress, the WCOL is set and the contents of the buffer are unchanged (the write doesn't occur).

Note: Because queueing of events is not allowed, writing of the lower 5 bits of SSPCON2 is disabled until the Repeated Start condition is complete.

FIGURE 13-14: REPEAT START CONDITION WAVEFORM



13.4.8 I²C™ MASTER MODE TRANSMISSION

Transmission of a data byte, a 7-bit address, or the other half of a 10-bit address, is accomplished by simply writing a value to the SSPBUF register. This action will set the Buffer Full bit, BF, and allow the Baud Rate Generator to begin counting and start the next transmission. Each bit of address/data will be shifted out onto the SDA pin after the falling edge of SCL is asserted (see data hold time specification, parameter 106). SCL is held low for one Baud Rate Generator roll-over count (TBRG). Data should be valid before SCL is released high (see data setup time specification, parameter 107). When the SCL pin is released high, it is held that way for TBRG. The data on the SDA pin must remain stable for that duration and some hold time after the next falling edge of SCL. After the eighth bit is shifted out (the falling edge of the eighth clock), the BF bit is cleared and the master releases SDA, allowing the slave device being addressed to respond with an ACK bit during the ninth bit time, if an address match occurs, or if data was received properly. The status of ACK is written into the ACKDT bit on the falling edge of the ninth clock. If the master receives an Acknowledge, the Acknowledge Status bit, ACKSTAT, is cleared. If not, the bit is set. After the ninth clock, the SSPIF bit is set and the master clock (Baud Rate Generator) is suspended until the next data byte is loaded into the SSPBUF, leaving SCL low and SDA unchanged (Figure 13-15).

After the write to the SSPBUF, each bit of the address will be shifted out on the falling edge of SCL, until all seven address bits and the R/W bit, are completed. On the falling edge of the eighth clock, the master will de-assert the SDA pin, allowing the slave to respond with an Acknowledge. On the falling edge of the ninth clock, the master will sample the SDA pin to see if the address was recognized by a slave. The status of the ACK bit is loaded into the ACKSTAT Status bit (SSPCON2 register). Following the falling edge of the ninth clock transmission of the address, the SSPIF is set, the BF bit is cleared and the Baud Rate Generator is turned off, until another write to the SSPBUF takes place, holding SCL low and allowing SDA to float.

13.4.8.1 BF Status Flag

In Transmit mode, the BF bit (SSPSTAT register) is set when the CPU writes to SSPBUF, and is cleared when all eight bits are shifted out.

13.4.8.2 WCOL Status Flag

If the user writes the SSPBUF when a transmit is already in progress (i.e., SSPSR is still shifting out a data byte), the WCOL is set and the contents of the buffer are unchanged (the write doesn't occur). WCOL must be cleared in software.

13.4.8.3 ACKSTAT Status Flag

In Transmit mode, the ACKSTAT bit (SSPCON2 register) is cleared when the slave has sent an Acknowledge (ACK = 0), and is set when the slave does not Acknowledge (ACK = 1). A slave sends an Acknowledge when it has recognized its address (including a general call), or when the slave has properly received its data.

13.4.9 I²C™ MASTER MODE RECEPTION

Master mode reception is enabled by programming the Receive Enable bit, RCEN (SSPCON2 register).

Note: The MSSP module must be in an Idle state before the RCEN bit is set, or the RCEN bit will be disregarded.

The Baud Rate Generator begins counting, and on each rollover, the state of the SCL pin changes (high-to-low/low-to-high) and data is shifted into the SSPSR. After the falling edge of the eighth clock, the RCEN bit is automatically cleared, the contents of the SSPSR are loaded into the SSPBUF, the BF bit is set, the SSPIF flag bit is set and the Baud Rate Generator is suspended from counting, holding SCL low. The MSSP is now in Idle state, awaiting the next command. When the buffer is read by the CPU, the BF bit is automatically cleared. The user can then send an Acknowledge bit at the end of reception, by setting the Acknowledge Sequence Enable bit ACKEN (SSPCON2 register).

13.4.9.1 BF Status Flag

In receive operation, the BF bit is set when an address or data byte is loaded into SSPBUF from SSPSR. It is cleared when the SSPBUF register is read.

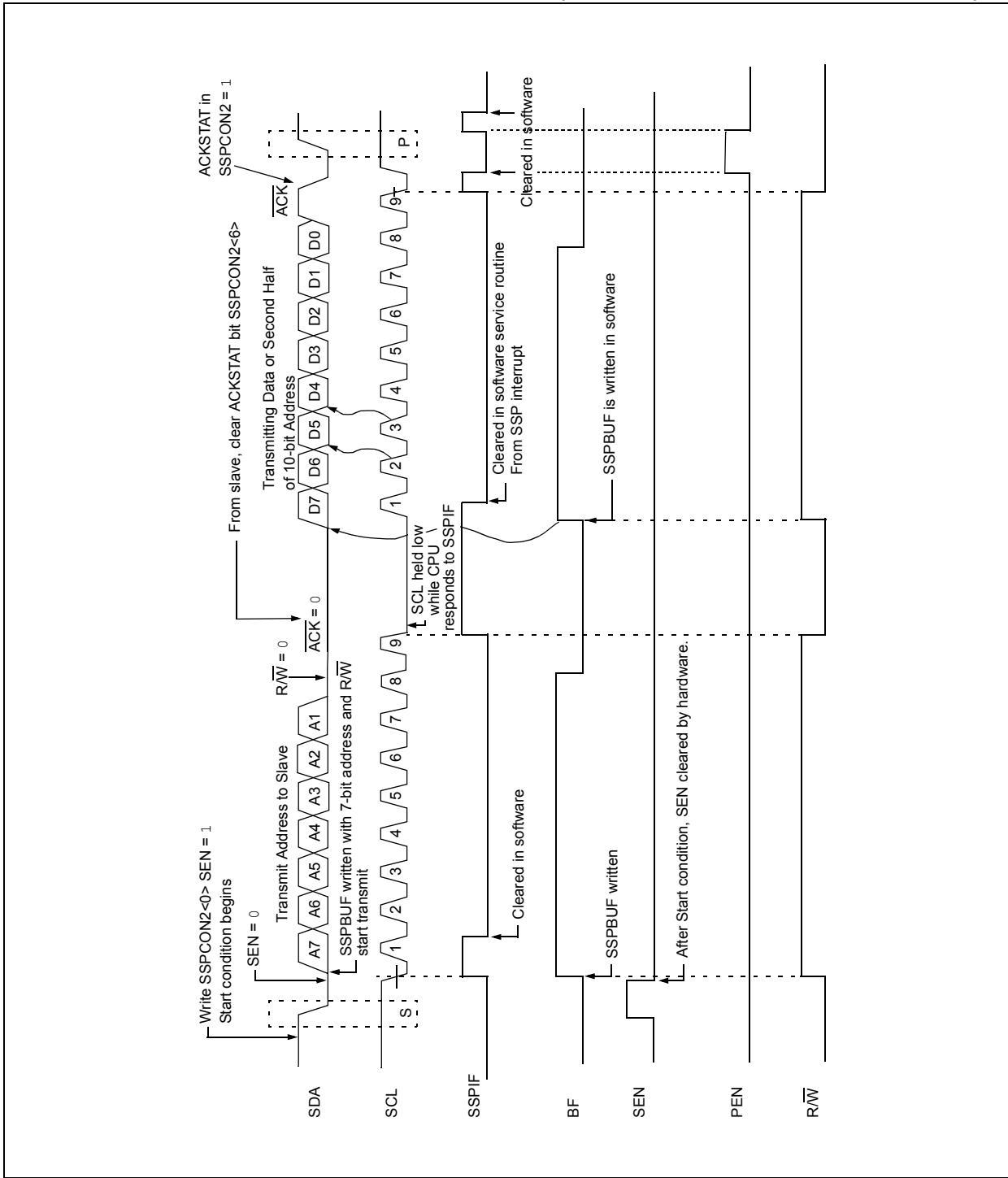
13.4.9.2 SSPOV Status Flag

In receive operation, the SSPOV bit is set when eight bits are received into the SSPSR and the BF bit is already set from a previous reception.

13.4.9.3 WCOL Status Flag

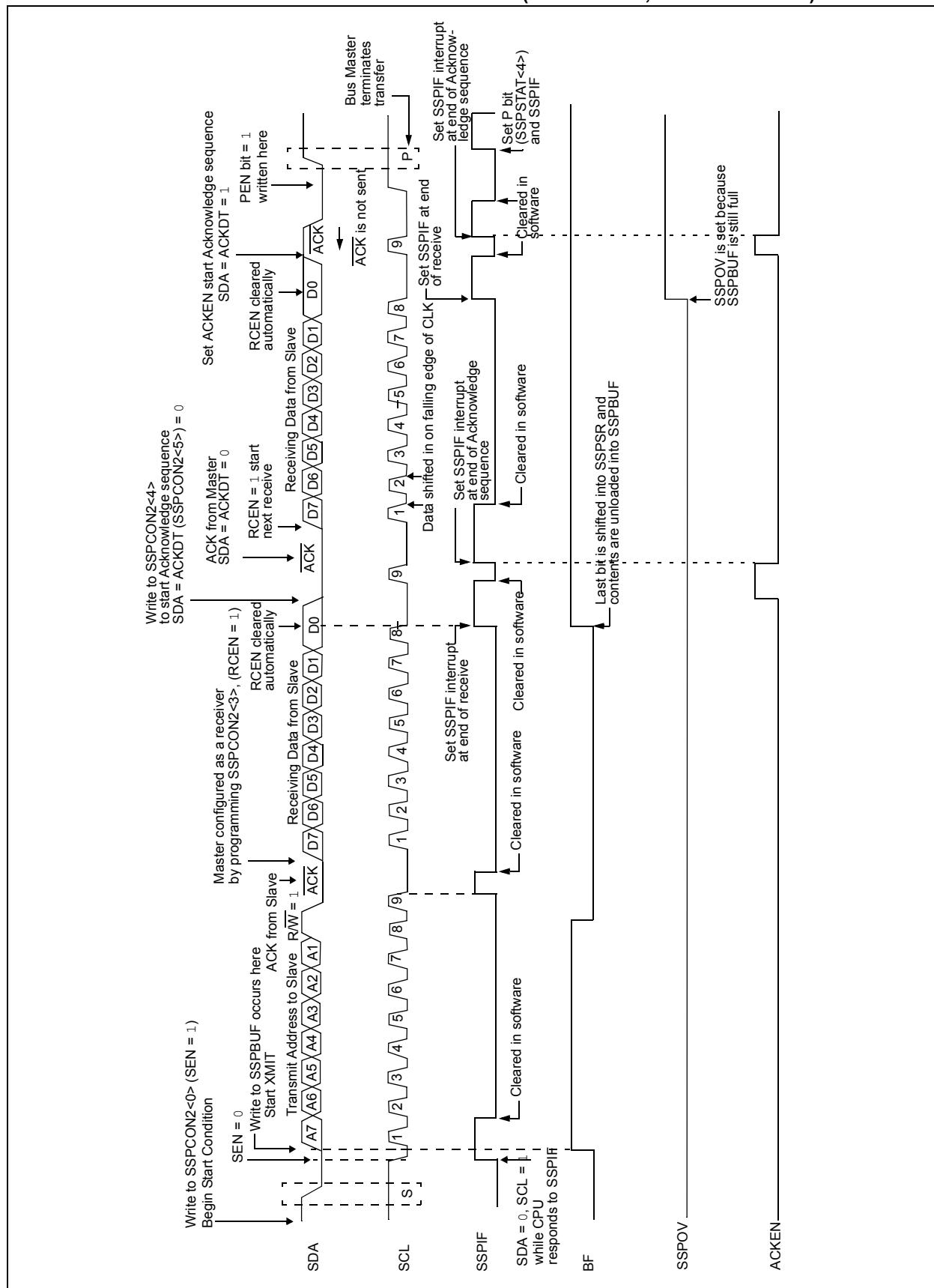
If the user writes the SSPBUF when a receive is already in progress (i.e., SSPSR is still shifting in a data byte), the WCOL bit is set and the contents of the buffer are unchanged (the write doesn't occur).

FIGURE 13-15: I²C™ MASTER MODE WAVEFORM (TRANSMISSION, 7 OR 10-BIT ADDRESS)



PIC16F882/883/884/886/887

FIGURE 13-16: I²C™ MASTER MODE WAVEFORM (RECEPTION, 7-BIT ADDRESS)



13.4.10 ACKNOWLEDGE SEQUENCE TIMING

An Acknowledge sequence is enabled by setting the Acknowledge Sequence Enable bit, ACKEN (SSPCON2 register). When this bit is set, the SCL pin is pulled low and the contents of the Acknowledge Data bit (ACKDT) is presented on the SDA pin. If the user wishes to generate an Acknowledge, then the ACKDT bit should be cleared. If not, the user should set the ACKDT bit before starting an Acknowledge sequence. The Baud Rate Generator then counts for one rollover period (TBRG) and the SCL pin is de-asserted (pulled high). When the SCL pin is sampled high (clock arbitration), the Baud Rate Generator counts for TBRG. The SCL pin is then pulled low. Following this, the ACKEN bit is automatically cleared, the Baud Rate Generator is turned off and the MSSP module then goes into Idle mode (Figure 13-17).

13.4.10.1 WCOL Status Flag

If the user writes the SSPBUF when an Acknowledge sequence is in progress, then WCOL is set and the contents of the buffer are unchanged (the write doesn't occur).

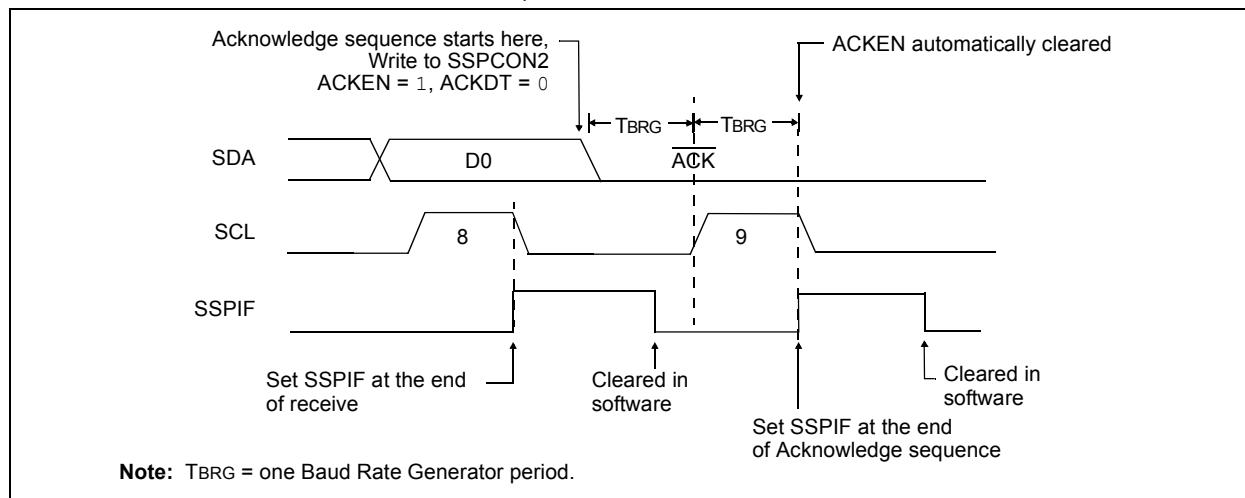
13.4.11 STOP CONDITION TIMING

A Stop bit is asserted on the SDA pin at the end of a receive/transmit by setting the Stop Sequence Enable bit, PEN (SSPCON2 register). At the end of a receive/transmit, the SCL line is held low after the falling edge of the ninth clock. When the PEN bit is set, the master will assert the SDA line low. When the SDA line is sampled low, the Baud Rate Generator is reloaded and counts down to 0. When the Baud Rate Generator times out, the SCL pin will be brought high, and one TBRG (Baud Rate Generator rollover count) later, the SDA pin will be de-asserted. When the SDA pin is sampled high while SCL is high, the P bit (SSPSTAT register) is set. A TBRG later, the PEN bit is cleared and the SSPIF bit is set (Figure 13-18).

13.4.11.1 WCOL Status Flag

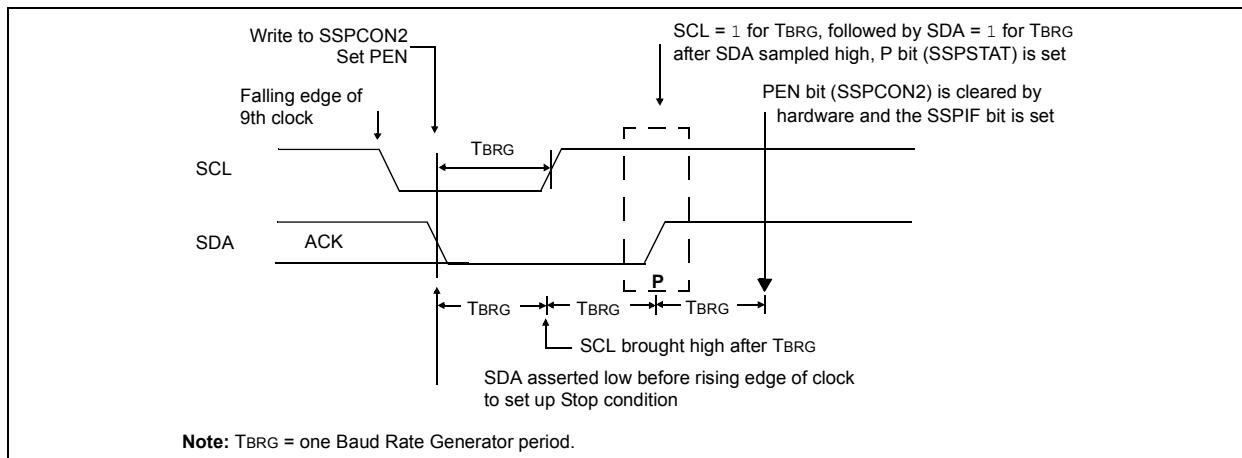
If the user writes the SSPBUF when a Stop sequence is in progress, then the WCOL bit is set and the contents of the buffer are unchanged (the write doesn't occur).

FIGURE 13-17: ACKNOWLEDGE SEQUENCE WAVEFORM



PIC16F882/883/884/886/887

FIGURE 13-18: STOP CONDITION RECEIVE OR TRANSMIT MODE



13.4.12 CLOCK ARBITRATION

Clock arbitration occurs when the master, during any receive, transmit or Repeated Start/Stop condition, de-asserts the SCL pin (SCL allowed to float high). When the SCL pin is allowed to float high, the Baud Rate Generator (BRG) is suspended from counting until the SCL pin is actually sampled high. When the SCL pin is sampled high, the Baud Rate Generator is reloaded with the contents of SSPADD<6:0> and begins counting. This ensures that the SCL high time will always be at least one BRG rollover count, in the event that the clock is held low by an external device (Figure 13-19).

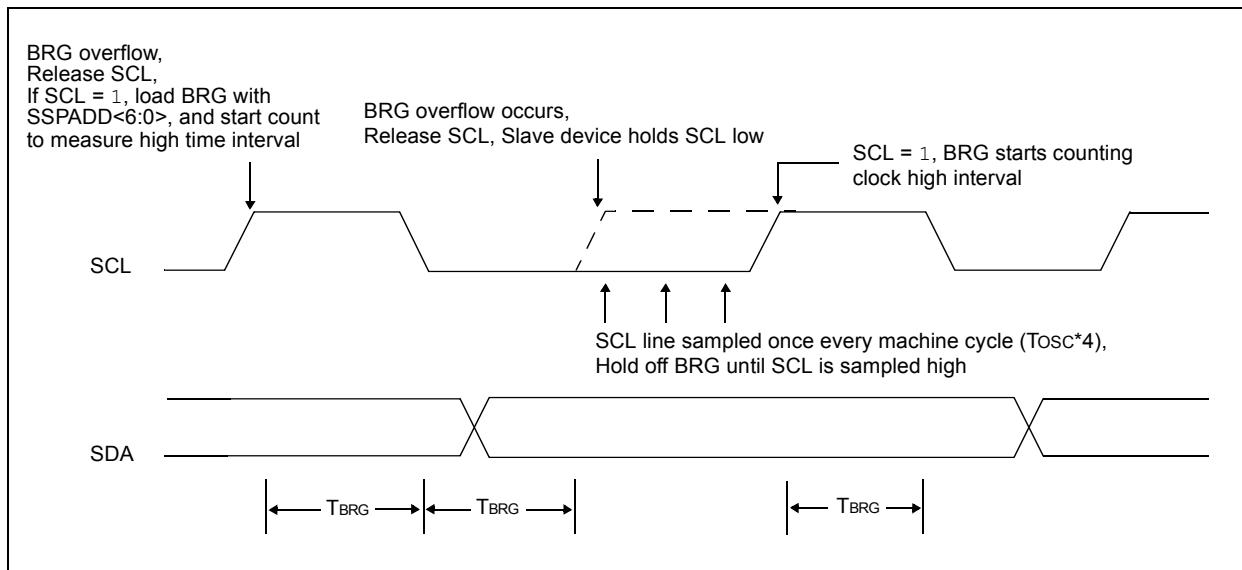
13.4.13 SLEEP OPERATION

While in Sleep mode, the I²C module can receive addresses or data, and when an address match or complete byte transfer occurs, wake the processor from Sleep (if the MSSP interrupt is enabled).

13.4.14 EFFECT OF A RESET

A Reset disables the MSSP module and terminates the current transfer.

FIGURE 13-19: CLOCK ARBITRATION TIMING IN MASTER TRANSMIT MODE



13.4.15 MULTI-MASTER MODE

In Multi-Master mode, the interrupt generation on the detection of the Start and Stop conditions allows the determination of when the bus is free. The Stop (P) and Start (S) bits are cleared from a Reset, or when the MSSP module is disabled. Control of the I²C bus may be taken when the P bit (SSPSTAT register) is set, or the bus is idle with both the S and P bits clear. When the bus is busy, enabling the SSP Interrupt will generate the interrupt when the Stop condition occurs.

In Multi-Master operation, the SDA line must be monitored for arbitration, to see if the signal level is the expected output level. This check is performed in hardware, with the result placed in the BCLIF bit.

Arbitration can be lost in the following states:

- Address transfer
- Data transfer
- A Start condition
- A Repeated Start condition
- An Acknowledge condition

13.4.16 MULTI -MASTER COMMUNICATION, BUS COLLISION, AND BUS ARBITRATION

Multi-Master mode support is achieved by bus arbitration. When the master outputs address/data bits onto the SDA pin, arbitration takes place when the master outputs a '1' on SDA, by letting SDA float high and another master asserts a '0'. When the SCL pin floats high, data should be stable. If the expected data on

SDA is a '1' and the data sampled on the SDA pin = 0, then a bus collision has taken place. The master will set the Bus Collision Interrupt Flag (BCLIF) and reset the I²C port to its Idle state (Figure 13-20).

If a transmit was in progress when the bus collision occurred, the transmission is halted, the BF bit is cleared, the SDA and SCL lines are de-asserted, and the SSPBUF can be written to. When the user services the bus collision interrupt service routine, and if the I²C bus is free, the user can resume communication by asserting a Start condition.

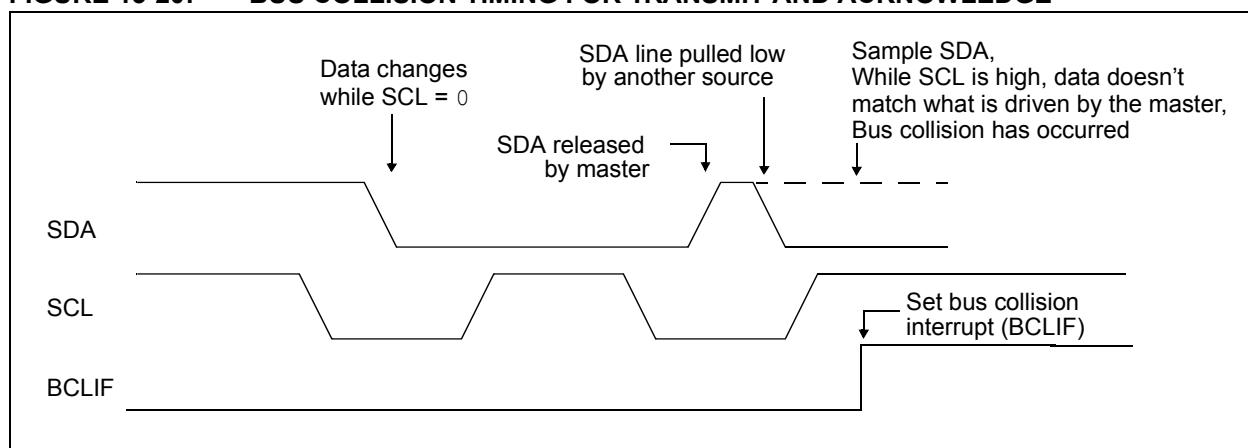
If a Start, Repeated Start, Stop, or Acknowledge condition was in progress when the bus collision occurred, the condition is aborted, the SDA and SCL lines are de-asserted, and the respective control bits in the SSPCON2 register are cleared. When the user services the bus collision interrupt service routine, and if the I²C bus is free, the user can resume communication by asserting a Start condition.

The master will continue to monitor the SDA and SCL pins. If a Stop condition occurs, the SSPIF bit will be set.

A write to the SSPBUF will start the transmission of data at the first data bit, regardless of where the transmitter left off when the bus collision occurred.

In Multi-Master mode, the interrupt generation on the detection of Start and Stop conditions allows the determination of when the bus is free. Control of the I²C bus can be taken when the P bit is set in the SSPSTAT register, or the bus is idle and the S and P bits are cleared.

FIGURE 13-20: BUS COLLISION TIMING FOR TRANSMIT AND ACKNOWLEDGE



PIC16F882/883/884/886/887

13.4.16.1 Bus Collision During a Start Condition

During a Start condition, a bus collision occurs if:

- SDA or SCL are sampled low at the beginning of the Start condition (Figure 13-21).
- SCL is sampled low before SDA is asserted low (Figure 13-22).

During a Start condition, both the SDA and the SCL pins are monitored, if:

the SDA pin is already low,
or the SCL pin is already low,

then:

the Start condition is aborted,
and the BCLIF flag is set,
and the MSSP module is reset to its Idle state
(Figure 13-21).

The Start condition begins with the SDA and SCL pins de-asserted. When the SDA pin is sampled high, the Baud Rate Generator is loaded from SSPADD<6:0> and counts down to 0. If the SCL pin is sampled low

while SDA is high, a bus collision occurs, because it is assumed that another master is attempting to drive a data '1' during the Start condition.

If the SDA pin is sampled low during this count, the BRG is reset and the SDA line is asserted early (Figure 13-23). If, however, a '1' is sampled on the SDA pin, the SDA pin is asserted low at the end of the BRG count. The Baud Rate Generator is then reloaded and counts down to 0, and during this time, if the SCL pin is sampled as '0', a bus collision does not occur. At the end of the BRG count, the SCL pin is asserted low.

Note: The reason that bus collision is not a factor during a Start condition, is that no two bus masters can assert a Start condition at the exact same time. Therefore, one master will always assert SDA before the other. This condition does not cause a bus collision, because the two masters must be allowed to arbitrate the first address following the Start condition. If the address is the same, arbitration must be allowed to continue into the data portion, Repeated Start or Stop conditions.

FIGURE 13-21: BUS COLLISION DURING START CONDITION (SDA ONLY)

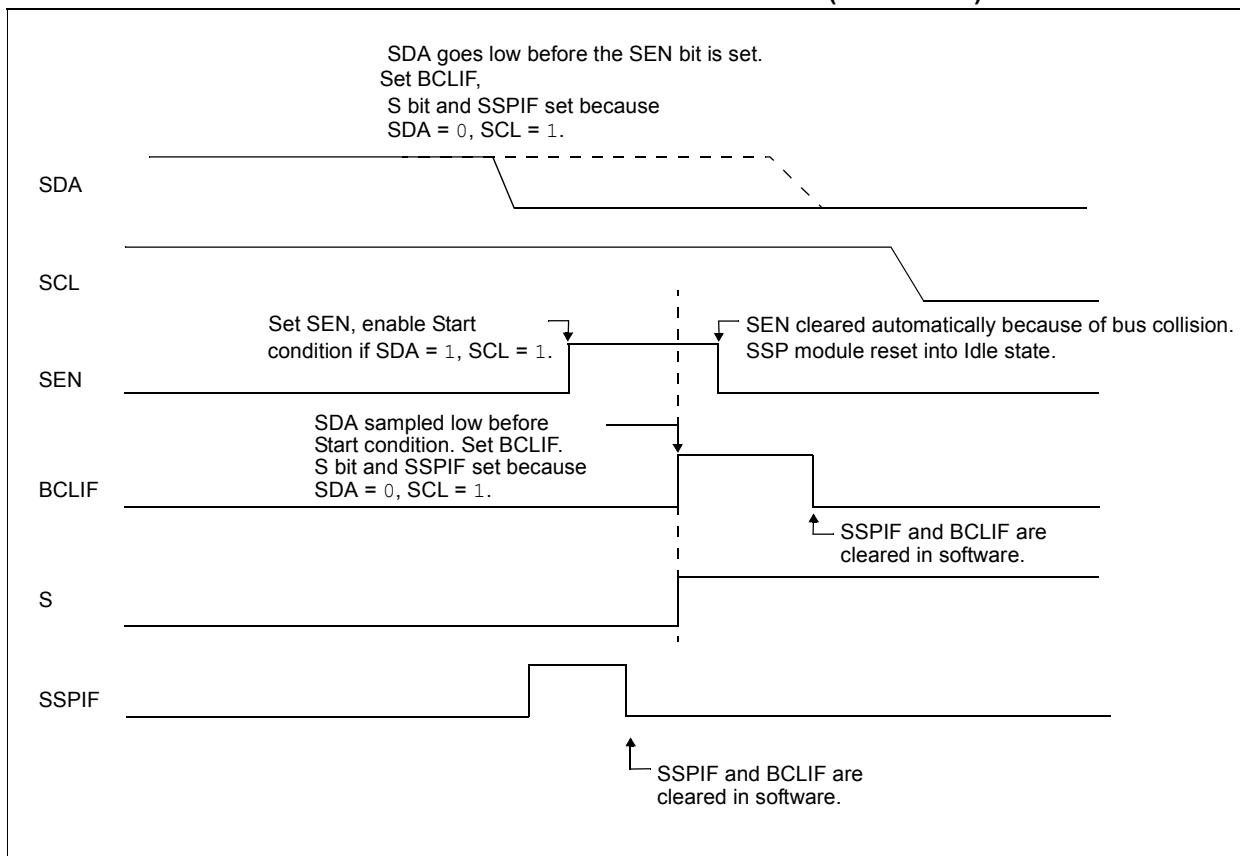


FIGURE 13-22: BUS COLLISION DURING START CONDITION (SCL = 0)

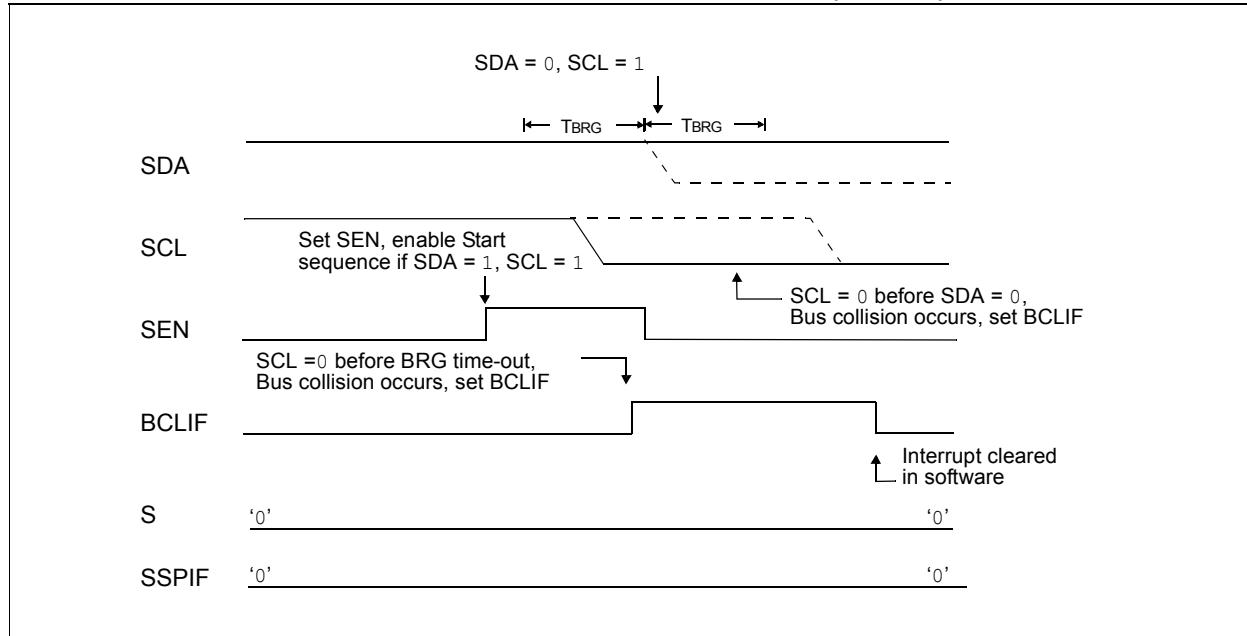
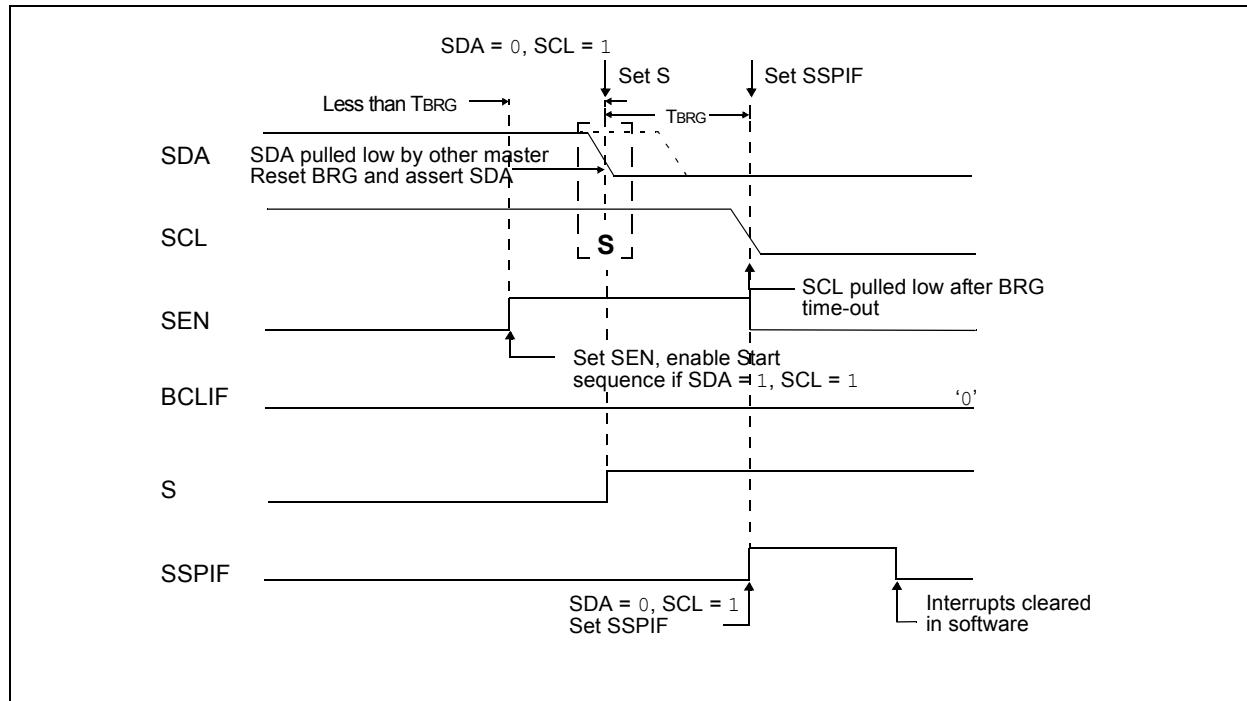


FIGURE 13-23: BRG RESET DUE TO SDA ARBITRATION DURING START CONDITION



PIC16F882/883/884/886/887

13.4.16.2 Bus Collision During a Repeated Start Condition

During a Repeated Start condition, a bus collision occurs if:

- A low level is sampled on SDA when SCL goes from low level to high level.
- SCL goes low before SDA is asserted low, indicating that another master is attempting to transmit a data '1'.

When the user de-asserts SDA and the pin is allowed to float high, the BRG is loaded with SSPADD<6:0> and counts down to 0. The SCL pin is then de-asserted, and when sampled high, the SDA pin is sampled.

If SDA is low, a bus collision has occurred (i.e. another master is attempting to transmit a data '0', see Figure 13-24). If SDA is sampled high, the BRG is reloaded and begins counting. If SDA goes from high-to-low before the BRG times out, no bus collision occurs because no two masters can assert SDA at exactly the same time.

If SCL goes from high-to-low before the BRG times out and SDA has not already been asserted, a bus collision occurs. In this case, another master is attempting to transmit a data '1' during the Repeated Start condition (Figure 13-25).

If at the end of the BRG time-out, both SCL and SDA are still high, the SDA pin is driven low and the BRG is reloaded and begins counting. At the end of the count, regardless of the status of the SCL pin, the SCL pin is driven low and the Repeated Start condition is complete.

FIGURE 13-24: BUS COLLISION DURING A REPEATED START CONDITION (CASE 1)

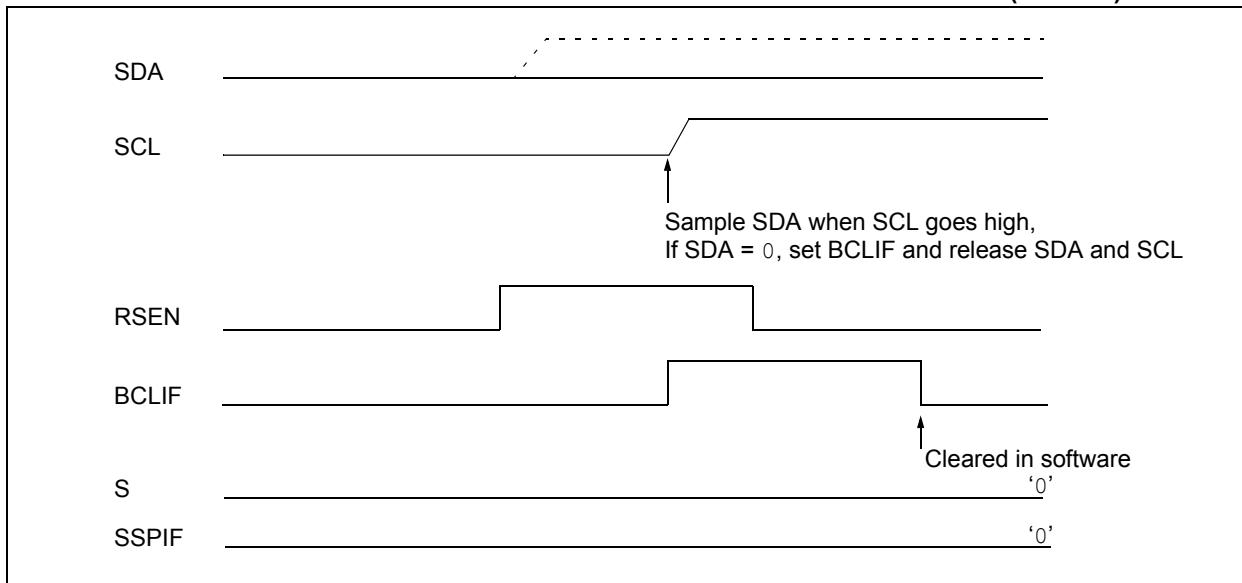
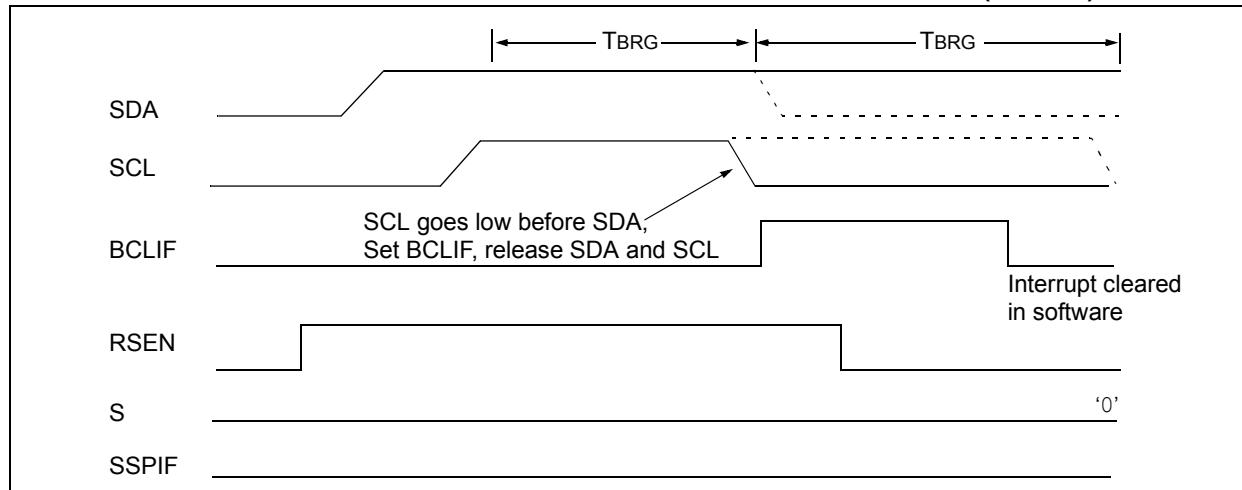


FIGURE 13-25: BUS COLLISION DURING REPEATED START CONDITION (CASE 2)



13.4.16.3 Bus Collision During a Stop Condition

Bus collision occurs during a Stop condition if:

- After the SDA pin has been de-asserted and allowed to float high, SDA is sampled low after the BRG has timed out.
- After the SCL pin is de-asserted, SCL is sampled low before SDA goes high.

The Stop condition begins with SDA asserted low. When SDA is sampled low, the SCL pin is allowed to float. When the pin is sampled high (clock arbitration), the Baud Rate Generator is loaded with SSPADD<6:0> and counts down to 0. After the BRG times out, SDA is sampled. If SDA is sampled low, a bus collision has occurred. This is due to another master attempting to drive a data '0' (Figure 13-26). If the SCL pin is sampled low before SDA is allowed to float high, a bus collision occurs. This is another case of another master attempting to drive a data '0' (Figure 13-27).

FIGURE 13-26: BUS COLLISION DURING A STOP CONDITION (CASE 1)

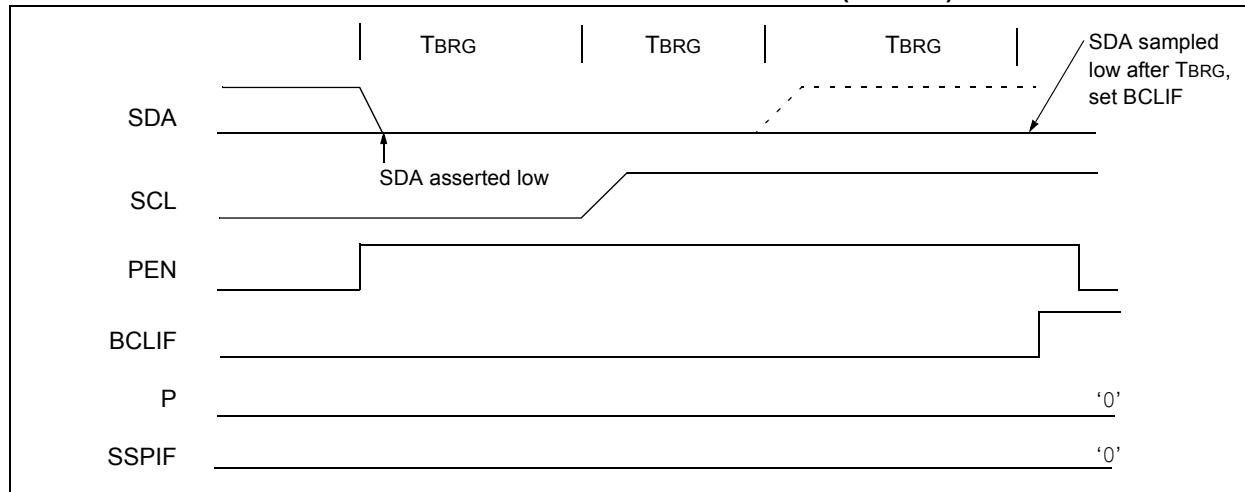
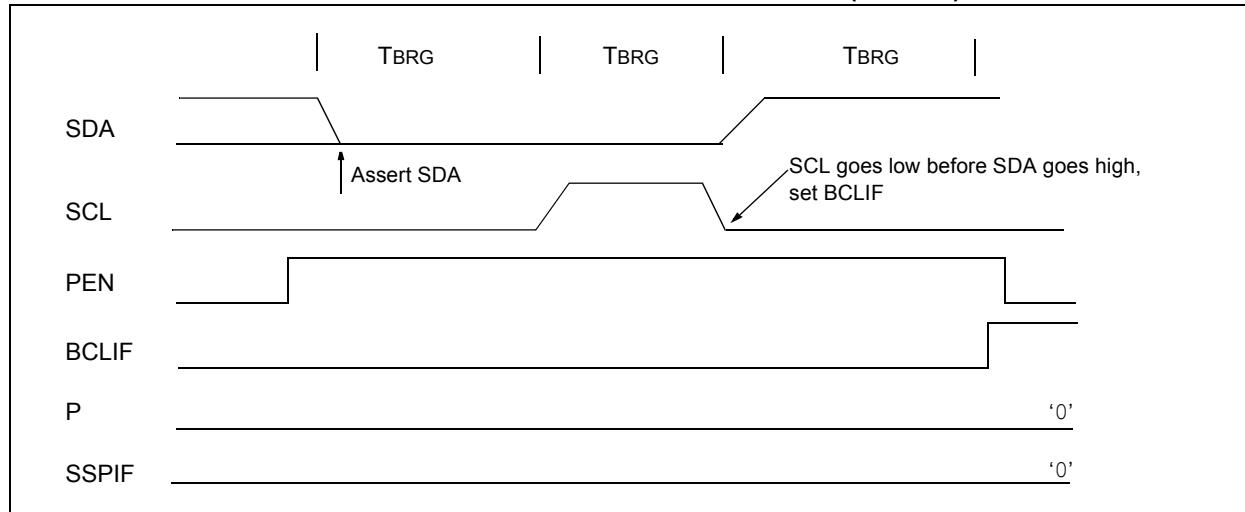


FIGURE 13-27: BUS COLLISION DURING A STOP CONDITION (CASE 2)



PIC16F882/883/884/886/887

13.4.17 SSP MASK REGISTER

An SSP Mask (SSPMSK) register is available in I²C Slave mode as a mask for the value held in the SSPSR register during an address comparison operation. A zero ('0') bit in the SSPMSK register has the effect of making the corresponding bit in the SSPSR register a "don't care".

This register is reset to all '1's upon any Reset condition and, therefore, has no effect on standard SSP operation until written with a mask value.

This register must be initiated prior to setting SSPM<3:0> bits to select the I²C Slave mode (7-bit or 10-bit address).

This register can only be accessed when the appropriate mode is selected by bits (SSPM<3:0> of SSPCON).

The SSP Mask register is active during:

- 7-bit Address mode: address compare of A<7:1>.
- 10-bit Address mode: address compare of A<7:0> only. The SSP mask has no effect during the reception of the first (high) byte of the address.

REGISTER 13-4: SSPMSK: SSP MASK REGISTER⁽¹⁾

| R/W-1 |
|-------|-------|-------|-------|-------|-------|-------|---------------------|
| MSK7 | MSK6 | MSK5 | MSK4 | MSK3 | MSK2 | MSK1 | MSK0 ⁽²⁾ |
| bit 7 | bit 0 | | | | | | |

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-1

MSK<7:1>: Mask bits

- 1 = The received address bit n is compared to SSPADD<n> to detect I²C address match
0 = The received address bit n is not used to detect I²C address match

bit 0

MSK<0>: Mask bit for I²C Slave mode, 10-bit Address⁽²⁾

I²C Slave mode, 10-bit Address (SSPM<3:0> = 0111):

- 1 = The received address bit 0 is compared to SSPADD<0> to detect I²C address match
0 = The received address bit 0 is not used to detect I²C address match

Note 1: When SSPCON bits SSPM<3:0> = 1001, any reads or writes to the SSPADD SFR address are accessed through the SSPMSK register.

2: In all other SSP modes, this bit has no effect.

14.0 SPECIAL FEATURES OF THE CPU

The PIC16F882/883/884/886/887 have a host of features intended to maximize system reliability, minimize cost through elimination of external components, provide power-saving features and offer code protection.

These features are:

- Reset
 - Power-on Reset (POR)
 - Power-up Timer (PWRT)
 - Oscillator Start-up Timer (OST)
 - Brown-out Reset (BOR)
- Interrupts
- Watchdog Timer (WDT)
- Oscillator selection
- Sleep
- Code protection
- ID Locations
- In-Circuit Serial Programming™
- Low-voltage In-Circuit Serial Programming™

The PIC16F882/883/884/886/887 have two timers that offer necessary delays on power-up. One is the Oscillator Start-up Timer (OST), intended to keep the chip in Reset until the crystal oscillator is stable. The other is the Power-up Timer (PWRT), which provides a fixed delay of 64 ms (nominal) on power-up only, designed to keep the part in Reset while the power supply stabilizes. There is also circuitry to reset the device if a brown-out occurs, which can use the Power-up Timer to provide at least a 64 ms Reset. With these three functions-on-chip, most applications need no external Reset circuitry.

The Sleep mode is designed to offer a very low-current Power-Down mode. The user can wake-up from Sleep through:

- External Reset
- Watchdog Timer Wake-up
- An interrupt

Several oscillator options are also made available to allow the part to fit the application. The INTOSC option saves system cost while the LP crystal option saves power. A set of Configuration bits are used to select various options (see Register 14-3).

PIC16F882/883/884/886/887

14.1 Configuration Bits

The Configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1') to select various device configurations as shown in Register 14-1. These bits are mapped in program memory location 2007h and 2008h, respectively.

Note: Address 2007h and 2008h are beyond the user program memory space. It belongs to the special configuration memory space (2000h-3FFFh), which can be accessed only during programming. See "PIC16F88X Memory Programming Specification" (DS41287) for more information.

REGISTER 14-1: CONFIG1: CONFIGURATION WORD REGISTER 1

—	—	DEBUG	LVP	FCMEN	IESO	BOREN1	BORENO
bit 15							bit 8

CPD	CP	MCLRE	PWRTE	WDTE	FOSC2	FOSC1	FOSC0
bit 7							bit 0

bit 15-14

Unimplemented: Read as '1'

bit 13

DEBUG: In-Circuit Debugger Mode bit

1 = In-Circuit Debugger disabled, RB6/ICSPCLK and RB7/ICSPDAT are general purpose I/O pins
0 = In-Circuit Debugger enabled, RB6/ICSPCLK and RB7/ICSPDAT are dedicated to the debugger

bit 12

LVP: Low Voltage Programming Enable bit

1 = RB3/PGM pin has PGM function, low voltage programming enabled
0 = RB3 pin is digital I/O, HV on MCLR must be used for programming

bit 11

FCMEN: Fail-Safe Clock Monitor Enabled bit

1 = Fail-Safe Clock Monitor is enabled
0 = Fail-Safe Clock Monitor is disabled

bit 10

IESO: Internal/External Switchover bit

1 = Internal/External Switchover mode is enabled
0 = Internal/External Switchover mode is disabled

bit 9-8

BOREN<1:0>: Brown-out Reset Selection bits⁽¹⁾

11 = BOR enabled
10 = BOR enabled during operation and disabled in Sleep
01 = BOR controlled by SBORN bit of the PCON register
00 = BOR disabled

bit 7

CPD: Data Code Protection bit⁽²⁾

1 = Data memory code protection is disabled
0 = Data memory code protection is enabled

bit 6

CP: Code Protection bit⁽³⁾

1 = Program memory code protection is disabled
0 = Program memory code protection is enabled

bit 5

MCLRE: RE3/MCLR pin function select bit⁽⁴⁾

1 = RE3/MCLR pin function is MCLR
0 = RE3/MCLR pin function is digital input, MCLR internally tied to VDD

bit 4

PWRTE: Power-up Timer Enable bit

1 = PWRT disabled
0 = PWRT enabled

bit 3

WDTE: Watchdog Timer Enable bit

1 = WDT enabled
0 = WDT disabled and can be enabled by SWDTEN bit of the WDTCON register

bit 2-0

FOSC<2:0>: Oscillator Selection bits

111 = RC oscillator: CLKOUT function on RA6/OSC2/CLKOUT pin, RC on RA7/OSC1/CLKIN
110 = RCIO oscillator: I/O function on RA6/OSC2/CLKOUT pin, RC on RA7/OSC1/CLKIN
101 = INTOSC oscillator: CLKOUT function on RA6/OSC2/CLKOUT pin, I/O function on RA7/OSC1/CLKIN
100 = INTOSCIO oscillator: I/O function on RA6/OSC2/CLKOUT pin, I/O function on RA7/OSC1/CLKIN
011 = EC: I/O function on RA6/OSC2/CLKOUT pin, CLKIN on RA7/OSC1/CLKIN
010 = HS oscillator: High-speed crystal/resonator on RA6/OSC2/CLKOUT and RA7/OSC1/CLKIN
001 = XT oscillator: Crystal/resonator on RA6/OSC2/CLKOUT and RA7/OSC1/CLKIN
000 = LP oscillator: Low-power crystal on RA6/OSC2/CLKOUT and RA7/OSC1/CLKIN

Note 1: Enabling Brown-out Reset does not automatically enable Power-up Timer.

Note 2: The entire data EEPROM will be erased when the code protection is turned off.

Note 3: The entire program memory will be erased when the code protection is turned off.

Note 4: When MCLR is asserted in INTOSC or RC mode, the internal clock oscillator is disabled.

PIC16F882/883/884/886/887

REGISTER 14-2: CONFIG2: CONFIGURATION WORD REGISTER 2

—	—	—	—	—	WRT1	WRT0	BOR4V
bit 15							bit 8

—	—	—	—	—	—	—	—
bit 7							bit 0

bit 15-11 **Unimplemented:** Read as '1'

bit 10-9 **WRT<1:0>:** Flash Program Memory Self Write Enable bits

PIC16F883/PIC16F884

00 = 0000h to 07FFh write protected, 0800h to 0FFFh may be modified by EECON control

01 = 0000h to 03FFh write protected, 0400h to 0FFFh may be modified by EECON control

10 = 0000h to 00FFh write protected, 0100h to 0FFFh may be modified by EECON control

11 = Write protection off

PIC16F886/PIC16F887

00 = 0000h to 0FFFh write protected, 1000h to 1FFFh may be modified by EECON control

01 = 0000h to 07FFh write protected, 0800h to 1FFFh may be modified by EECON control

10 = 0000h to 00FFh write protected, 0100h to 1FFFh may be modified by EECON control

11 = Write protection off

PIC16F882

00 = 0000h to 03FFh write protected, 0400h to 07FFh may be modified by EECON control

01 = 0000h to 00FFh write protected, 0100h to 07FFh may be modified by EECON control

11 = Write protection off

bit 8 **BOR4V:** Brown-out Reset Selection bit

0 = Brown-out Reset set to 2.1V

1 = Brown-out Reset set to 4.0V

bit 7-0 **Unimplemented:** Read as '1'

PIC16F882/883/884/886/887

14.2 Reset

The PIC16F882/883/884/886/887 differentiates between various kinds of Reset:

- Power-on Reset (POR)
- WDT Reset during normal operation
- WDT Reset during Sleep
- MCLR Reset during normal operation
- MCLR Reset during Sleep
- Brown-out Reset (BOR)

Some registers are not affected by any Reset condition; their status is unknown on POR and unchanged in any other Reset. Most other registers are reset to a "Reset state" on:

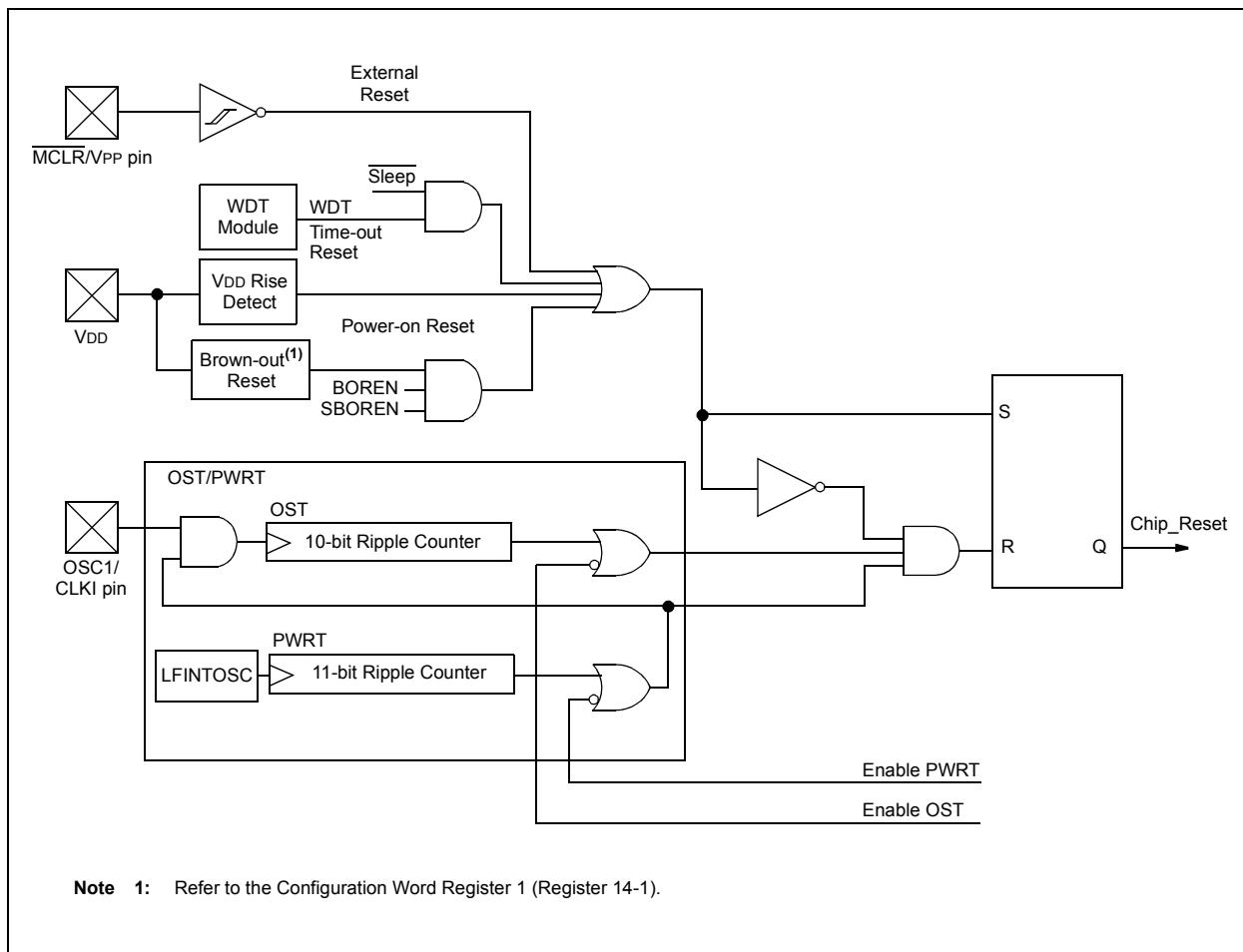
- Power-on Reset
- MCLR Reset
- MCLR Reset during Sleep
- WDT Reset
- Brown-out Reset (BOR)

They are not affected by a WDT Wake-up since this is viewed as the resumption of normal operation. $\overline{\text{TO}}$ and $\overline{\text{PD}}$ bits are set or cleared differently in different Reset situations, as indicated in Table 14-2. These bits are used in software to determine the nature of the Reset. See Table 14-5 for a full description of Reset states of all registers.

A simplified block diagram of the On-Chip Reset Circuit is shown in Figure 14-1.

The MCLR Reset path has a noise filter to detect and ignore small pulses. See **Section 17.0 "Electrical Specifications"** for pulse-width specifications.

FIGURE 14-1: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT



Note 1: Refer to the Configuration Word Register 1 (Register 14-1).

14.2.1 POWER-ON RESET (POR)

The on-chip POR circuit holds the chip in Reset until VDD has reached a high enough level for proper operation. A maximum rise time for VDD is required. See **Section 17.0 “Electrical Specifications”** for details. If the BOR is enabled, the maximum rise time specification does not apply. The BOR circuitry will keep the device in Reset until VDD reaches VBOR (see **Section 14.2.4 “Brown-out Reset (BOR)”**).

Note: The POR circuit does not produce an internal Reset when VDD declines. To re-enable the POR, VDD must reach Vss for a minimum of 100 μ s.

When the device starts normal operation (exits the Reset condition), device operating parameters (i.e., voltage, frequency, temperature, etc.) must be met to ensure operation. If these conditions are not met, the device must be held in Reset until the operating conditions are met.

For additional information, refer to Application Note AN607, “Power-up Trouble Shooting” (DS00607).

14.2.2 MCLR

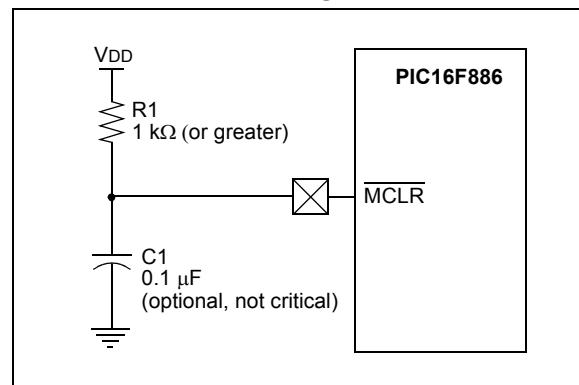
PIC16F882/883/884/886/887 has a noise filter in the MCLR Reset path. The filter will detect and ignore small pulses.

It should be noted that a WDT Reset does not drive MCLR pin low.

The behavior of the ESD protection on the MCLR pin has been altered from early devices of this family. Voltages applied to the pin that exceed its specification can result in both MCLR Resets and excessive current beyond the device specification during the ESD event. For this reason, Microchip recommends that the MCLR pin no longer be tied directly to VDD. The use of an RC network, as shown in Figure 14-2, is suggested.

An internal MCLR option is enabled by clearing the MCLRE bit in the Configuration Word Register 1. When MCLRE = 0, the Reset signal to the chip is generated internally. When the MCLRE = 1, the RA3/MCLR pin becomes an external Reset input. In this mode, the RA3/MCLR pin has a weak pull-up to VDD.

FIGURE 14-2: RECOMMENDED MCLR CIRCUIT



14.2.3 POWER-UP TIMER (PWRT)

The Power-up Timer provides a fixed 64 ms (nominal) time-out on power-up only, from POR or Brown-out Reset. The Power-up Timer operates from the 31 kHz LFINTOSC oscillator. For more information, see **Section 4.5 “Internal Clock Modes”**. The chip is kept in Reset as long as PWRT is active. The PWRT delay allows the VDD to rise to an acceptable level. A Configuration bit, PWRTE, can disable (if set) or enable (if cleared or programmed) the Power-up Timer. The Power-up Timer should be enabled when Brown-out Reset is enabled, although it is not required.

The Power-up Timer delay will vary from chip-to-chip and vary due to:

- VDD variation
- Temperature variation
- Process variation

See DC parameters for details (**Section 17.0 “Electrical Specifications”**).

PIC16F882/883/884/886/887

14.2.4 BROWN-OUT RESET (BOR)

The BOREN0 and BOREN1 bits in the Configuration Word Register 1 select one of four BOR modes. Two modes have been added to allow software or hardware control of the BOR enable. When BOREN<1:0> = 01, the SBOREN bit (PCON<4>) enables/disables the BOR allowing it to be controlled in software. By selecting BOREN<1:0>, the BOR is automatically disabled in Sleep to conserve power and enabled on wake-up. In this mode, the SBOREN bit is disabled. See Register 14-3 for the Configuration Word definition.

The BOR4V bit in the Configuration Word Register 2 selects one of two Brown-out Reset voltages. When BOR4B = 1, VBOR is set to 4V. When BOR4V = 0, VBOR is set to 2.1V.

If VDD falls below VBOR for greater than parameter (TBOR) (see **Section 17.0 “Electrical Specifications”**), the Brown-out situation will reset the device. This will

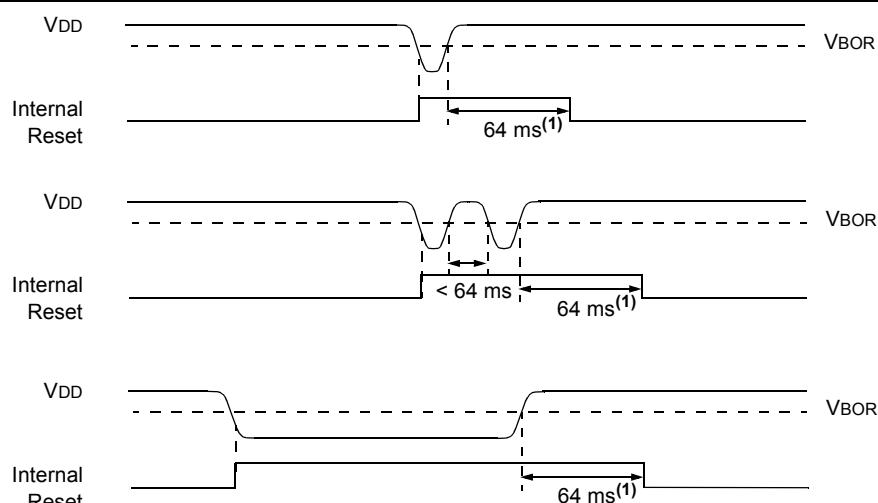
occur regardless of VDD slew rate. A Reset is not insured to occur if VDD falls below VBOR for less than parameter (TBOR).

On any Reset (Power-on, Brown-out Reset, Watchdog Timer, etc.), the chip will remain in Reset until VDD rises above VBOR (see Figure 14-3). The Power-up Timer will now be invoked, if enabled and will keep the chip in Reset an additional 64 ms.

Note: The Power-up Timer is enabled by the PWRTE bit in the Configuration Word Register 1.

If VDD drops below VBOR while the Power-up Timer is running, the chip will go back into a Brown-out Reset and the Power-up Timer will be re-initialized. Once VDD rises above VBOR, the Power-up Timer will execute a 64 ms Reset.

FIGURE 14-3: BROWN-OUT SITUATIONS



Note 1: 64 ms delay only if PWRTE bit is programmed to ‘0’.

14.2.5 TIME-OUT SEQUENCE

On power-up, the time-out sequence is as follows: first, PWRT time-out is invoked after POR has expired, then OST is activated after the PWRT time-out has expired. The total time-out will vary based on oscillator configuration and PWRTE bit status. For example, in EC mode with PWRTE bit erased (PWRT disabled), there will be no time-out at all. Figures 14-4, 14-5 and 14-6 depict time-out sequences. The device can execute code from the INTOSC while OST is active by enabling Two-Speed Start-up or Fail-Safe Monitor (see **Section 4.7.2 “Two-speed Start-up Sequence”** and **Section 4.8 “Fail-Safe Clock Monitor”**).

Since the time-outs occur from the POR pulse, if MCLR is kept low long enough, the time-outs will expire. Then, bringing MCLR high will begin execution immediately (see Figure 14-5). This is useful for testing purposes or to synchronize more than one PIC16F882/883/884/886/887 device operating in parallel.

Table 14-5 shows the Reset conditions for some special registers, while Table 14-4 shows the Reset conditions for all the registers.

TABLE 14-1: TIME-OUT IN VARIOUS SITUATIONS

Oscillator Configuration	Power-up		Brown-out Reset		Wake-up from Sleep
	PWRTE = 0	PWRTE = 1	PWRTE = 0	PWRTE = 1	
XT, HS, LP	TPWRT + 1024 • Tosc	1024 • Tosc	TPWRT + 1024 • Tosc	1024 • Tosc	1024 • Tosc
LP, T1OSCIN = 1	TPWRT	—	TPWRT	—	—
RC, EC, INTOSC	TPWRT	—	TPWRT	—	—

TABLE 14-2: STATUS/PCON BITS AND THEIR SIGNIFICANCE

POR	BOR	TO	PD	Condition
0	x	1	1	Power-on Reset
u	0	1	1	Brown-out Reset
u	u	0	u	WDT Reset
u	u	0	0	WDT Wake-up
u	u	u	u	MCLR Reset during normal operation
u	u	1	0	MCLR Reset during Sleep

Legend: u = unchanged, x = unknown

TABLE 14-3: SUMMARY OF REGISTERS ASSOCIATED WITH BROWN-OUT

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
PCON	—	—	ULPWUE	SBOREN	—	—	POR	BOR	--01 --qq	--0u --uu
STATUS	IRP	RP1	RPO	TO	PD	Z	DC	C	0001 1xxx	000q quuu

Legend: u = unchanged, x = unknown, - = unimplemented bit, reads as '0', q = value depends on condition. Shaded cells are not used by BOR.
Note 1: Other (non Power-up) Resets include MCLR Reset and Watchdog Timer Reset during normal operation.

PIC16F882/883/884/886/887

FIGURE 14-4: TIME-OUT SEQUENCE ON POWER-UP (DELAYED MCLR): CASE 1

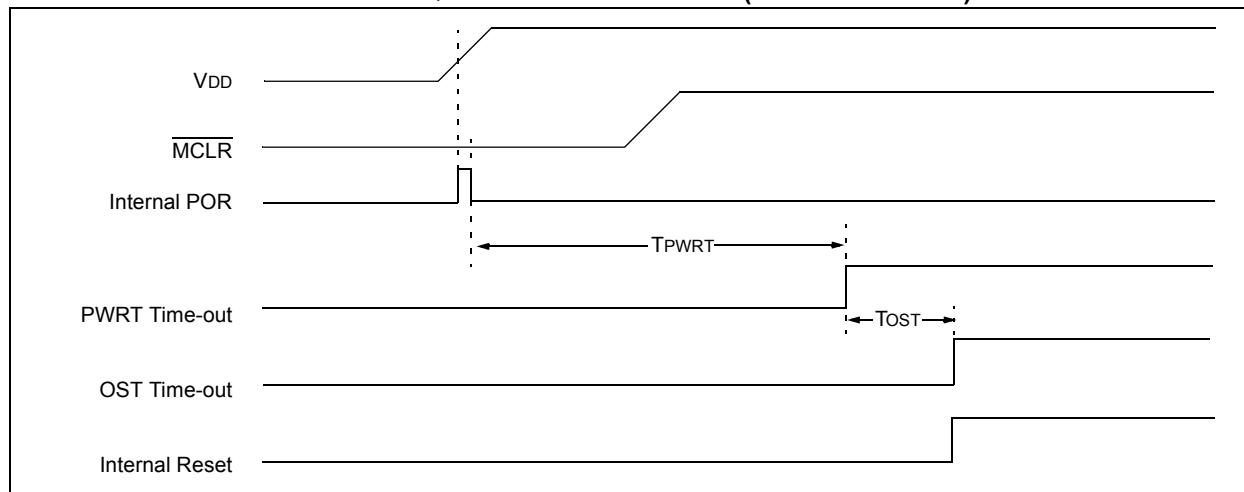


FIGURE 14-5: TIME-OUT SEQUENCE ON POWER-UP (DELAYED MCLR): CASE 2

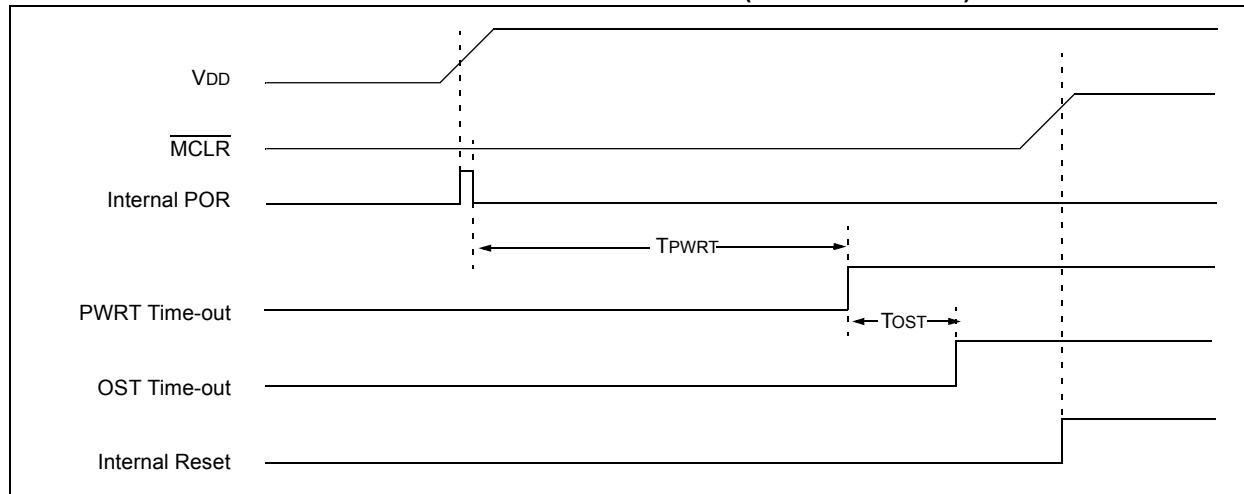


FIGURE 14-6: TIME-OUT SEQUENCE ON POWER-UP (MCLR WITH V_{DD})

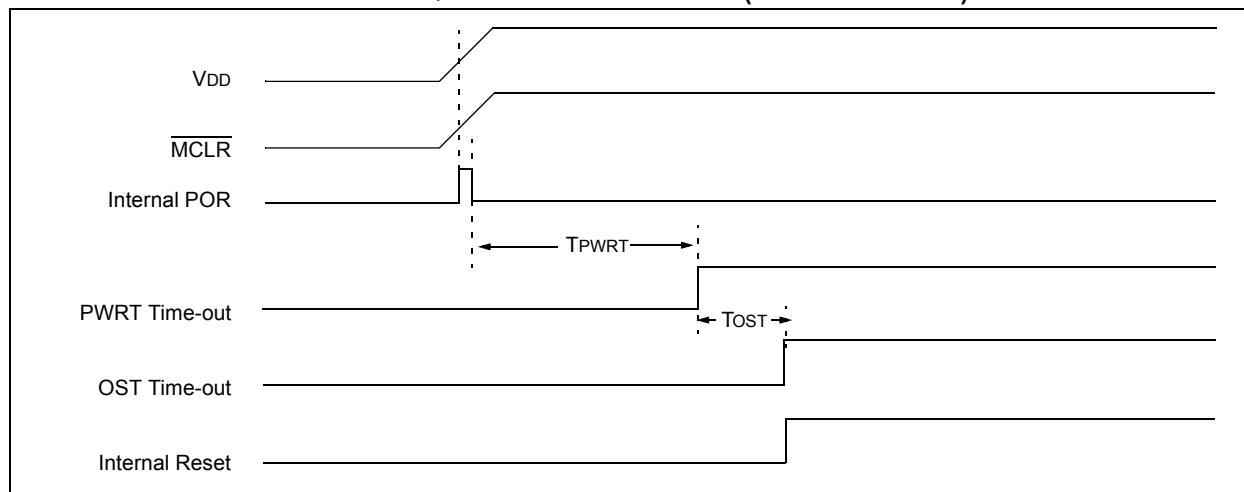


TABLE 14-4: INITIALIZATION CONDITION FOR REGISTER

Register	Address	Power-on Reset	MCLR Reset WDT Reset Brown-out Reset ⁽¹⁾	Wake-up from Sleep through Interrupt Wake-up from Sleep through WDT Time-out
W	—	xxxx xxxx	uuuu uuuu	uuuu uuuu
INDF	00h/80h/100h/180h	xxxx xxxx	xxxx xxxx	uuuu uuuu
TMR0	01h/101h	xxxx xxxx	uuuu uuuu	uuuu uuuu
PCL	02h/82h/102h/182h	0000 0000	0000 0000	PC + 1 ⁽³⁾
STATUS	03h/83h/103h/183h	0001 1xxx	000q quuu ⁽⁴⁾	uuuq quuu ⁽⁴⁾
FSR	04h/84h/104h/184h	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTA	05h	xxxx xxxx	0000 0000	uuuu uuuu
PORTB	06h/106h	xxxx xxxx	0000 0000	uuuu uuuu
PORTC	07h	xxxx xxxx	0000 0000	uuuu uuuu
PORTD	08h	xxxx xxxx	0000 0000	uuuu uuuu
PORTE	09h	---- xxxx	---- 0000	---- uuuu
PCLATH	0Ah/8Ah/10Ah/18Ah	--0 0000	--0 0000	--u uuuu
INTCON	0Bh/8Bh/10Bh/18Bh	0000 000x	0000 000u	uuuu uuuu ⁽²⁾
PIR1	0Ch	0000 0000	0000 0000	uuuu uuuu ⁽²⁾
PIR2	0Dh	0000 0000	0000 0000	uuuu uuuu ⁽²⁾
TMR1L	0Eh	xxxx xxxx	uuuu uuuu	uuuu uuuu
TMR1H	0Fh	xxxx xxxx	uuuu uuuu	uuuu uuuu
T1CON	10h	0000 0000	uuuu uuuu	-uuu uuuu
TMR2	11h	0000 0000	0000 0000	uuuu uuuu
T2CON	12h	-000 0000	-000 0000	-uuu uuuu
SSPBUF	13h	xxxx xxxx	uuuu uuuu	uuuu uuuu
SSPCON	14h	0000 0000	0000 0000	uuuu uuuu
CCPR1L	15h	xxxx xxxx	uuuu uuuu	uuuu uuuu
CCPR1H	16h	xxxx xxxx	uuuu uuuu	uuuu uuuu
CCP1CON	17h	0000 0000	0000 0000	uuuu uuuu
RCSTA	18h	0000 000x	0000 0000	uuuu uuuu
TXREG	19h	0000 0000	0000 0000	uuuu uuuu
RCREG	1Ah	0000 0000	0000 0000	uuuu uuuu
CCPR2L	1Bh	xxxx xxxx	uuuu uuuu	uuuu uuuu

Legend: u = unchanged, x = unknown, - = unimplemented bit, reads as '0', q = value depends on condition.

Note 1: If VDD goes too low, Power-on Reset will be activated and registers will be affected differently.

2: One or more bits in INTCON and/or PIR1 will be affected (to cause wake-up).

3: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

4: See Table 14-5 for Reset value for specific condition.

5: If Reset was due to brown-out, then bit 0 = 0. All other Resets will cause bit 0 = u.

6: Accessible only when SSPCON register bits SSPM<3:0> = 1001.

PIC16F882/883/884/886/887

TABLE 14-4: INITIALIZATION CONDITION FOR REGISTER (CONTINUED)

Register	Address	Power-on Reset	MCLR Reset WDT Reset (Continued) Brown-out Reset ⁽¹⁾	Wake-up from Sleep through Interrupt Wake-up from Sleep through WDT Time-out (Continued)
CCPR2H	1Ch	xxxx xxxx	uuuu uuuu	uuuu uuuu
CCP2CON	1Dh	--00 0000	--00 0000	--uu uuuu
ADRESH	1Eh	xxxx xxxx	uuuu uuuu	uuuu uuuu
ADCON0	1Fh	00-0 0000	00-0 0000	uu-u uuuu
OPTION_REG	81h/181h	1111 1111	1111 1111	uuuu uuuu
TRISA	85h	1111 1111	1111 1111	uuuu uuuu
TRISB	86h/186h	1111 1111	1111 1111	uuuu uuuu
TRISC	87h	1111 1111	1111 1111	uuuu uuuu
TRISD	88h	1111 1111	1111 1111	uuuu uuuu
TRISE	89h	---- 1111	---- 1111	---- uuuu
PIE1	8Ch	0000 0000	0000 0000	uuuu uuuu
PIE2	8Dh	0000 0000	0000 0000	uuuu uuuu
PCON	8Eh	--01 --0x	--0u --uu ^(1, 5)	--uu --uu
OSCCON	8Fh	-110 q000	-110 q000	-uuu uuuu
OSCTUNE	90h	---0 0000	---u uuuu	---u uuuu
SSPCON2	91h	0000 0000	0000 0000	uuuu uuuu
PR2	92h	1111 1111	1111 1111	1111 1111
SSPADD ⁽⁶⁾	93h	0000 0000	0000 0000	uuuu uuuu
SSPMASK ⁽⁶⁾	93h	1111 1111	1111 1111	1111 1111
SSPSTAT	94h	0000 0000	0000 0000	uuuu uuuu
WPUB	95h	1111 1111	1111 1111	uuuu uuuu
IOCB	96h	0000 0000	0000 0000	uuuu uuuu
VRCON	97h	0000 0000	0000 0000	uuuu uuuu
TXSTA	98h	0000 -010	0000 -010	uuuu -uuu
SPBRG	99h	0000 0000	0000 0000	uuuu uuuu
SPBRGH	9Ah	0000 0000	0000 0000	uuuu uuuu
PWM1CON	9Bh	0000 0000	0000 0000	uuuu uuuu
ECCPAS	9Ch	0000 0000	0000 0000	uuuu uuuu
PSTRCON	9Dh	---0 0001	---0 0001	---u uuuu
ADRESL	9Eh	xxxx xxxx	uuuu uuuu	uuuu uuuu
ADCON1	9Fh	0-00 ----	0-00 ----	u-uu ----
WDTCON	105h	---0 1000	---0 1000	---u uuuu
CM1CON0	107h	0000 0-00	0000 0-00	uuuu u-uu
CM2CON0	108h	0000 0-00	0000 0-00	uuuu u-uu

Legend: u = unchanged, x = unknown, - = unimplemented bit, reads as '0', q = value depends on condition.

Note 1: If VDD goes too low, Power-on Reset will be activated and registers will be affected differently.

2: One or more bits in INTCON and/or PIR1 will be affected (to cause wake-up).

3: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

4: See Table 14-5 for Reset value for specific condition.

5: If Reset was due to brown-out, then bit 0 = 0. All other Resets will cause bit 0 = u.

6: Accessible only when SSPCON register bits SSPM<3:0> = 1001.

TABLE 14-4: INITIALIZATION CONDITION FOR REGISTER (CONTINUED)

Register	Address	Power-on Reset	MCLR Reset WDT Reset (Continued) Brown-out Reset ⁽¹⁾	Wake-up from Sleep through Interrupt Wake-up from Sleep through WDT Time-out (Continued)
CM2CON1	109h	0000 0--0	0000 0--0	uuuu u--u
EEDAT	10Ch	0000 0000	0000 0000	uuuu uuuu
EEADR	10Dh	0000 0000	0000 0000	uuuu uuuu
EEDATH	10Eh	--00 0000	--00 0000	--uu uuuu
EEADRH	10Fh	--0 0000	--0 0000	--u uuuu
SRCON	185h	0000 00-0	0000 00-0	uuuu uu-u
BAUDCTL	187h	01-0 0-00	01-0 0-00	uu-u u-uu
ANSEL	188h	1111 1111	1111 1111	uuuu uuuu
ANSELH	189h	1111 1111	1111 1111	uuuu uuuu
EECON1	18Ch	---- x000	---- q000	---- uuuu
EECON2	18Dh	---- ----	---- ----	---- ----

Legend: u = unchanged, x = unknown, -- = unimplemented bit, reads as '0', q = value depends on condition.

Note 1: If VDD goes too low, Power-on Reset will be activated and registers will be affected differently.

- 2: One or more bits in INTCON and/or PIR1 will be affected (to cause wake-up).
- 3: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).
- 4: See Table 14-5 for Reset value for specific condition.
- 5: If Reset was due to brown-out, then bit 0 = 0. All other Resets will cause bit 0 = u.
- 6: Accessible only when SSPCON register bits SSPM<3:0> = 1001.

TABLE 14-5: INITIALIZATION CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	Status Register	PCON Register
Power-on Reset	000h	0001 1xxx	--01 --0x
MCLR Reset during normal operation	000h	000u uuuu	--0u --uu
MCLR Reset during Sleep	000h	0001 0uuu	--0u --uu
WDT Reset	000h	0000 uuuu	--0u --uu
WDT Wake-up	PC + 1	uuu0 0uuu	--uu --uu
Brown-out Reset	000h	0001 1uuu	--01 --u0
Interrupt Wake-up from Sleep	PC + 1 ⁽¹⁾	uuu1 0uuu	--uu --uu

Legend: u = unchanged, x = unknown, -- = unimplemented bit, reads as '0'.

Note 1: When the wake-up is due to an interrupt and Global Interrupt Enable bit, GIE, is set, the PC is loaded with the interrupt vector (0004h) after execution of PC + 1.

14.3 Interrupts

The PIC16F882/883/884/886/887 has multiple interrupt sources:

- External Interrupt RB0/INT
- Timer0 Overflow Interrupt
- PORTB Change Interrupts
- 2 Comparator Interrupts
- A/D Interrupt
- Timer1 Overflow Interrupt
- Timer2 Match Interrupt
- EEPROM Data Write Interrupt
- Fail-Safe Clock Monitor Interrupt
- Enhanced CCP Interrupt
- EUSART Receive and Transmit Interrupts
- Ultra Low-Power Wake-up Interrupt
- MSSP Interrupt

The Interrupt Control register (INTCON) and Peripheral Interrupt Request Register 1 (PIR1) record individual interrupt requests in flag bits. The INTCON register also has individual and global interrupt enable bits.

A Global Interrupt Enable bit, GIE (INTCON<7>), enables (if set) all unmasked interrupts, or disables (if cleared) all interrupts. Individual interrupts can be disabled through their corresponding enable bits in the INTCON, PIE1 and PIE2 registers, respectively. GIE is cleared on Reset.

The Return from Interrupt instruction, RETFIE, exits the interrupt routine, as well as sets the GIE bit, which re-enables unmasked interrupts.

The following interrupt flags are contained in the INTCON register:

- INT Pin Interrupt
- PORTB Change Interrupts
- Timer0 Overflow Interrupt

The peripheral interrupt flags are contained in the PIR1 and PIR2 registers. The corresponding interrupt enable bits are contained in PIE1 and PIE2 registers.

The following interrupt flags are contained in the PIR1 register:

- A/D Interrupt
- EUSART Receive and Transmit Interrupts
- Timer1 Overflow Interrupt
- Synchronous Serial Port (SSP) Interrupt
- Enhanced CCP1 Interrupt
- Timer1 Overflow Interrupt
- Timer2 Match Interrupt

The following interrupt flags are contained in the PIR2 register:

- Fail-Safe Clock Monitor Interrupt
- 2 Comparator Interrupts
- EEPROM Data Write Interrupt
- Ultra Low-Power Wake-up Interrupt
- CCP2 Interrupt

When an interrupt is serviced:

- The GIE is cleared to disable any further interrupt.
- The return address is pushed onto the stack.
- The PC is loaded with 0004h.

For external interrupt events, such as the INT pin, PORTB change interrupts, the interrupt latency will be three or four instruction cycles. The exact latency depends upon when the interrupt event occurs (see Figure 14-8). The latency is the same for one or two-cycle instructions. Once in the Interrupt Service Routine, the source(s) of the interrupt can be determined by polling the interrupt flag bits. The interrupt flag bit(s) must be cleared in software before re-enabling interrupts to avoid multiple interrupt requests.

Note 1: Individual interrupt flag bits are set, regardless of the status of their corresponding mask bit or the GIE bit.

2: When an instruction that clears the GIE bit is executed, any interrupts that were pending for execution in the next cycle are ignored. The interrupts, which were ignored, are still pending to be serviced when the GIE bit is set again.

For additional information on Timer1, Timer2, comparators, A/D, data EEPROM, EUSART, MSSP or Enhanced CCP modules, refer to the respective peripheral section.

14.3.1 RB0/INT INTERRUPT

External interrupt on RB0/INT pin is edge-triggered; either rising if the INTEDG bit (OPTION_REG<6>) is set, or falling, if the INTEDG bit is clear. When a valid edge appears on the RB0/INT pin, the INTF bit (INTCON<1>) is set. This interrupt can be disabled by clearing the INTE control bit (INTCON<4>). The INTF bit must be cleared in software in the Interrupt Service Routine before re-enabling this interrupt. The RB0/INT interrupt can wake-up the processor from Sleep, if the INTE bit was set prior to going into Sleep. The status of the GIE bit decides whether or not the processor branches to the interrupt vector following wake-up (0004h). See **Section 14.6 “Power-Down Mode (Sleep)”** for details on Sleep and Figure 14-10 for timing of wake-up from Sleep through RB0/INT interrupt.

14.3.2 TIMER0 INTERRUPT

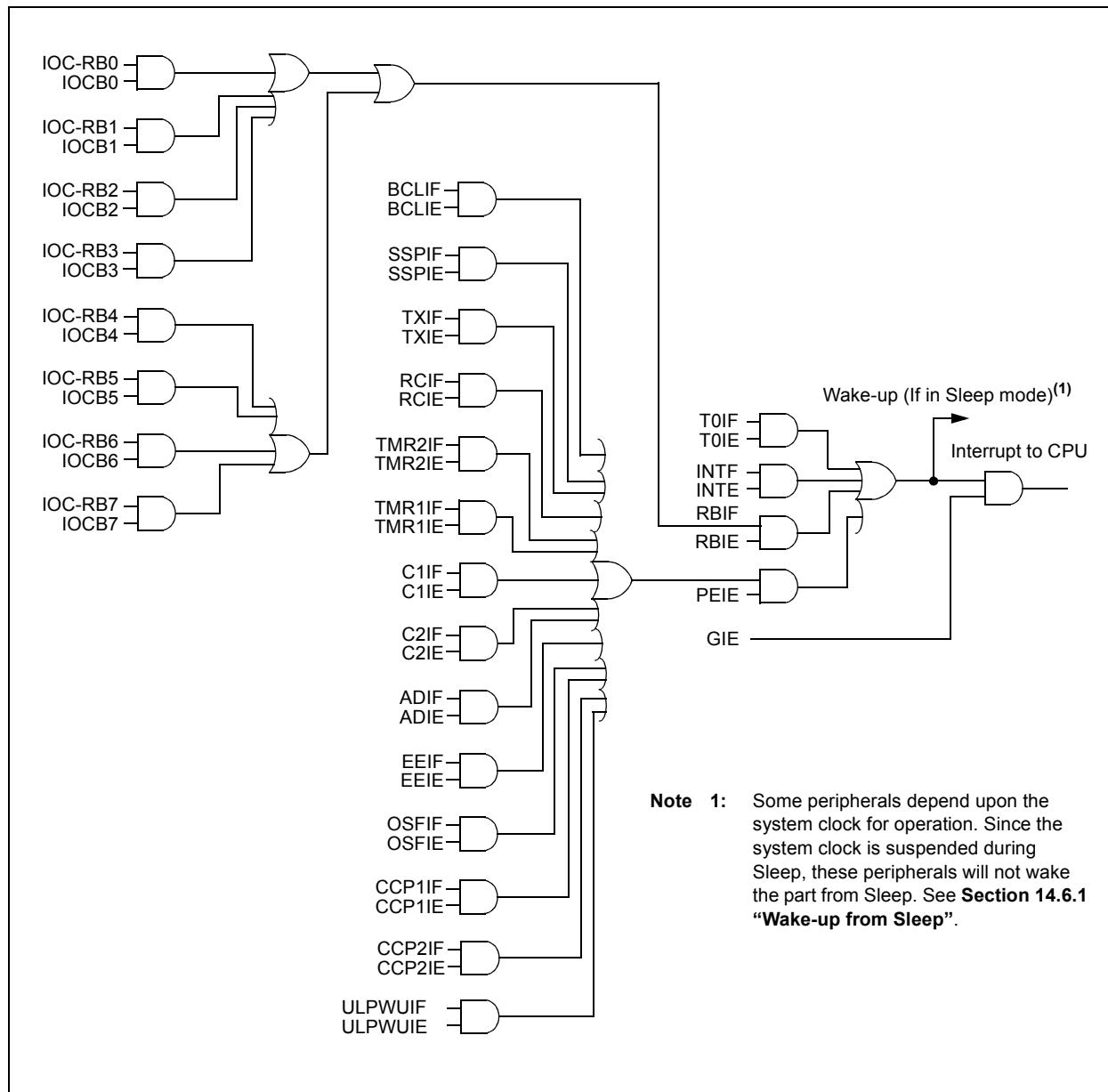
An overflow ($\text{FFh} \rightarrow 00\text{h}$) in the TMR0 register will set the T0IF (INTCON<2>) bit. The interrupt can be enabled/disabled by setting/clearing T0IE (INTCON<5>) bit. See **Section 5.0 “Timer0 Module”** for operation of the Timer0 module.

14.3.3 PORTB INTERRUPT

An input change on PORTB change sets the RBIF (INTCON<0>) bit. The interrupt can be enabled/disabled by setting/clearing the RBIE (INTCON<3>) bit. Plus, individual pins can be configured through the IOCB register.

Note: If a change on the I/O pin should occur when the read operation is being executed (start of the Q2 cycle), then the RBIF interrupt flag may not get set. See **Section 3.4.3 “Interrupt-on-Change”** for more information.

FIGURE 14-7: INTERRUPT LOGIC



PIC16F882/883/884/886/887

FIGURE 14-8: INT PIN INTERRUPT TIMING

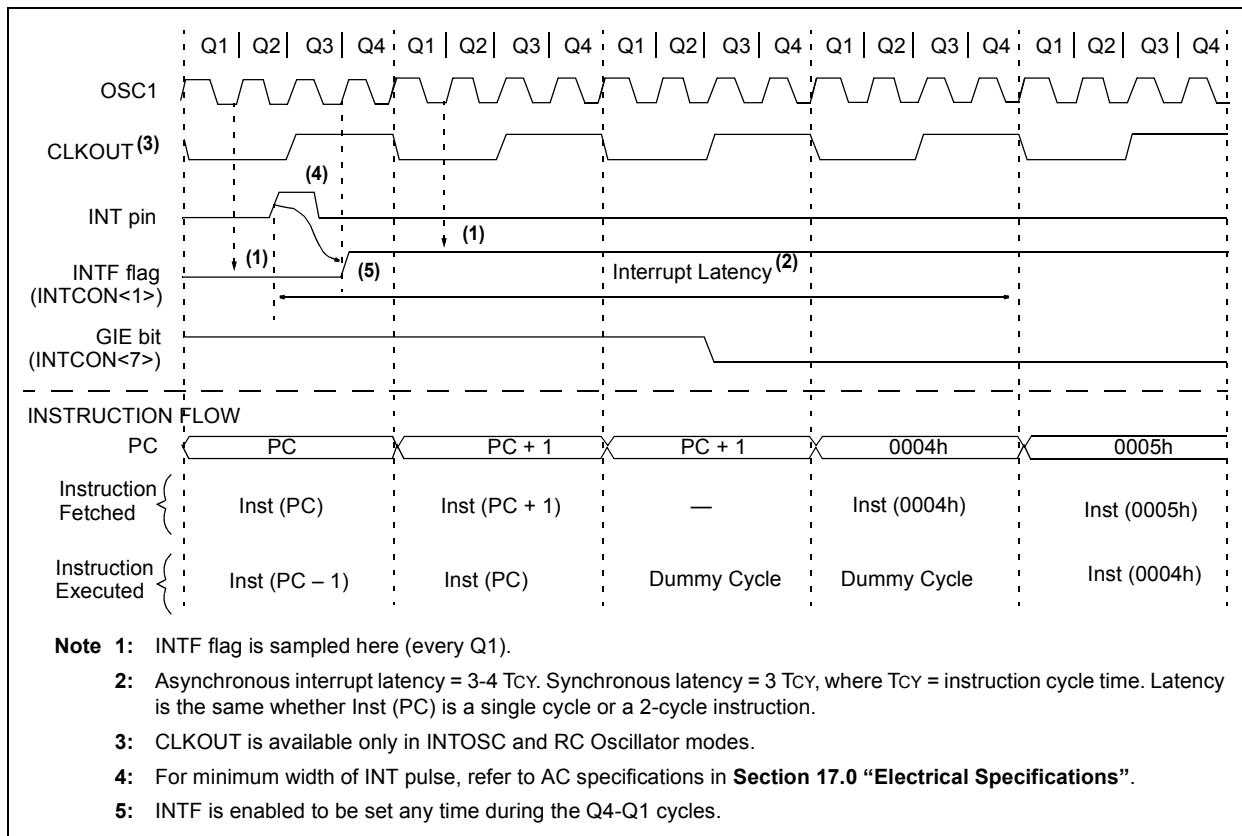


TABLE 14-6: SUMMARY OF INTERRUPT REGISTERS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
INTCON	GIE	PEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	0000 000x	0000 000x
PIE1	—	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	-000 0000	-000 0000
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	ULPWUIE	—	CCP2IE	0000 00-0	0000 00-0
PIR1	—	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	-000 0000	-000 0000
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	ULPWUIF	—	CCP2IF	0000 00-0	0000 00-0

Legend: x = unknown, u = unchanged, — = unimplemented read as ‘0’, q = value depends upon condition.
Shaded cells are not used by the Interrupt module.

14.4 Context Saving During Interrupts

During an interrupt, only the return PC value is saved on the stack. Typically, users may wish to save key registers during an interrupt (e.g., W and STATUS registers). This must be implemented in software.

Since the upper 16 bytes of all GPR banks are common in the PIC16F882/883/884/886/887 (see Figures 2-2 and 2-3), temporary holding registers, W_TEMP and STATUS_TEMP, should be placed in here. These 16 locations do not require banking and therefore, make it easier to context save and restore. The same code shown in Example 14-1 can be used to:

- Store the W register
- Store the STATUS register
- Execute the ISR code
- Restore the Status (and Bank Select Bit register)
- Restore the W register

Note: The PIC16F882/883/884/886/887 normally does not require saving the PCLATH. However, if computed GOTO's are used in the ISR and the main code, the PCLATH must be saved and restored in the ISR.

EXAMPLE 14-1: SAVING STATUS AND W REGISTERS IN RAM

```
MOVWF  W_TEMP           ;Copy W to TEMP register
SWAPF  STATUS,W          ;Swap status to be saved into W
                          ;Swaps are used because they do not affect the status bits
MOVWF  STATUS_TEMP        ;Save status to bank zero STATUS_TEMP register
:
:(ISR)                   ;Insert user code here
:
SWAPF  STATUS_TEMP,W     ;Swap STATUS_TEMP register into W
                          ;(sets bank to original state)
MOVWF  STATUS             ;Move W into STATUS register
SWAPF  W_TEMP,F           ;Swap W_TEMP
SWAPF  W_TEMP,W           ;Swap W_TEMP into W
```

PIC16F882/883/884/886/887

14.5 Watchdog Timer (WDT)

The WDT has the following features:

- Operates from the LFINTOSC (31 kHz)
- Contains a 16-bit prescaler
- Shares an 8-bit prescaler with Timer0
- Time-out period is from 1 ms to 268 seconds
- Configuration bit and software controlled

WDT is cleared under certain conditions described in Table 14-7.

14.5.1 WDT OSCILLATOR

The WDT derives its time base from the 31 kHz LFINTOSC. The LTS bit of the OSCCON register does not reflect that the LFINTOSC is enabled.

The value of WDTCON is '---0 1000' on all Resets. This gives a nominal time base of 17 ms.

Note: When the Oscillator Start-up Timer (OST) is invoked, the WDT is held in Reset, because the WDT Ripple Counter is used by the OST to perform the oscillator delay count. When the OST count has expired, the WDT will begin counting (if enabled).

14.5.2 WDT CONTROL

The WDTE bit is located in the Configuration Word Register 1. When set, the WDT runs continuously.

When the WDTE bit in the Configuration Word Register 1 is set, the SWDTEN bit of the WDTCON register has no effect. If WDTE is clear, then the SWDTEN bit can be used to enable and disable the WDT. Setting the bit will enable it and clearing the bit will disable it.

The PSA and PS<2:0> bits of the OPTION register have the same function as in previous versions of the PIC16F882/883/884/886/887 Family of microcontrollers. See **Section 5.0 “Timer0 Module”** for more information.

FIGURE 14-9: WATCHDOG TIMER BLOCK DIAGRAM

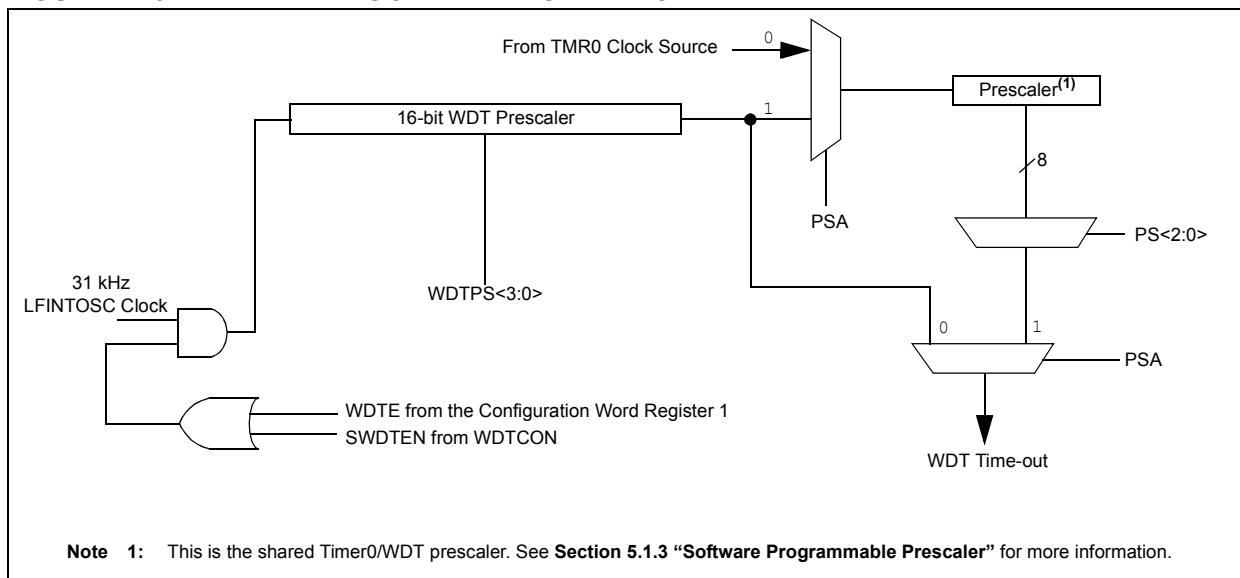


TABLE 14-7: WDT STATUS

Conditions	WDT
WDTE = 0	Cleared
CLRWDT Command	
Oscillator Fail Detected	
Exit Sleep + System Clock = T1OSC, EXTRC, INTOSC, EXTCLK	
Exit Sleep + System Clock = XT, HS, LP	Cleared until the end of OST

PIC16F882/883/884/886/887

REGISTER 14-3: WDTCON: WATCHDOG TIMER CONTROL REGISTER

U-0	U-0	U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	SWDTEN ⁽¹⁾
bit 7	bit 0						

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **Unimplemented:** Read as '0'

bit 4-1 **WDTPS<3:0>:** Watchdog Timer Period Select bits

Bit Value = Prescale Rate

0000 = 1:32

0001 = 1:64

0010 = 1:128

0011 = 1:256

0100 = 1:512 (Reset value)

0101 = 1:1024

0110 = 1:2048

0111 = 1:4096

1000 = 1:8192

1001 = 1:16384

1010 = 1:32768

1011 = 1:65536

1100 = reserved

1101 = reserved

1110 = reserved

1111 = reserved

bit 0 **SWDTEN:** Software Enable or Disable the Watchdog Timer⁽¹⁾

1 = WDT is turned on

0 = WDT is turned off (Reset value)

Note 1: If WDTE Configuration bit = 1, then WDT is always enabled, irrespective of this control bit. If WDTE Configuration bit = 0, then it is possible to turn WDT on/off with this control bit.

TABLE 14-8: SUMMARY OF WATCHDOG TIMER REGISTER

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
CONFIG1 ⁽¹⁾	CPD	CP	MCLRE	PWRTE	WDTE	FOSC2	FOSC1	FOSC0	—	—
OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
WDTCON	—	—	—	WDTPS3	WDTPS2	WSTPS1	WDTPS0	SWDTEN	---0 1000	---0 1000

Legend: Shaded cells are not used by the Watchdog Timer.

Note 1: See Register 14-1 for operation of all Configuration Word Register 1 bits.

14.6 Power-Down Mode (Sleep)

The Power-down mode is entered by executing a `SLEEP` instruction.

If the Watchdog Timer is enabled:

- WDT will be cleared but keeps running.
- `PD` bit in the STATUS register is cleared.
- `TO` bit is set.
- Oscillator driver is turned off.
- I/O ports maintain the status they had before `SLEEP` was executed (driving high, low or high-impedance).

For lowest current consumption in this mode, all I/O pins should be either at VDD or Vss, with no external circuitry drawing current from the I/O pin and the comparators and CVREF should be disabled. I/O pins that are high-impedance inputs should be pulled high or low externally to avoid switching currents caused by floating inputs. The T0CKI input should also be at VDD or Vss for lowest current consumption. The contribution from on-chip pull-ups on PORTA should be considered.

The `MCLR` pin must be at a logic high level.

Note: It should be noted that a Reset generated by a WDT time-out does not drive `MCLR` pin low.

14.6.1 WAKE-UP FROM SLEEP

The device can wake-up from Sleep through one of the following events:

1. External Reset input on `MCLR` pin.
2. Watchdog Timer Wake-up (if WDT was enabled).
3. Interrupt from RB0/INT pin, PORTB change or a peripheral interrupt.

The first event will cause a device Reset. The two latter events are considered a continuation of program execution. The `TO` and `PD` bits in the STATUS register can be used to determine the cause of device Reset. The `PD` bit, which is set on power-up, is cleared when Sleep is invoked. `TO` bit is cleared if WDT Wake-up occurred.

The following peripheral interrupts can wake the device from Sleep:

1. TMR1 interrupt. Timer1 must be operating as an asynchronous counter.
2. CCP Capture mode interrupt.
3. A/D conversion (when A/D clock source is FRC).
4. EEPROM write operation completion.
5. Comparator output changes state.
6. Interrupt-on-change.
7. External Interrupt from INT pin.
8. EUSART Break detect, I²C slave.

Other peripherals cannot generate interrupts since during Sleep, no on-chip clocks are present.

When the `SLEEP` instruction is being executed, the next instruction (`PC + 1`) is prefetched. For the device to wake-up through an interrupt event, the corresponding interrupt enable bit must be set (enabled). Wake-up occurs regardless of the state of the GIE bit. If the GIE bit is clear (disabled), the device continues execution at the instruction after the `SLEEP` instruction. If the GIE bit is set (enabled), the device executes the instruction after the `SLEEP` instruction, then branches to the interrupt address (0004h). In cases where the execution of the instruction following `SLEEP` is not desirable, the user should have a `NOP` after the `SLEEP` instruction.

Note: If the global interrupts are disabled (GIE is cleared), but any interrupt source has both its interrupt enable bit and the corresponding interrupt flag bits set, the device will immediately wake-up from Sleep. The `SLEEP` instruction is completely executed.

The WDT is cleared when the device wakes up from Sleep, regardless of the source of wake-up.

14.6.2 WAKE-UP USING INTERRUPTS

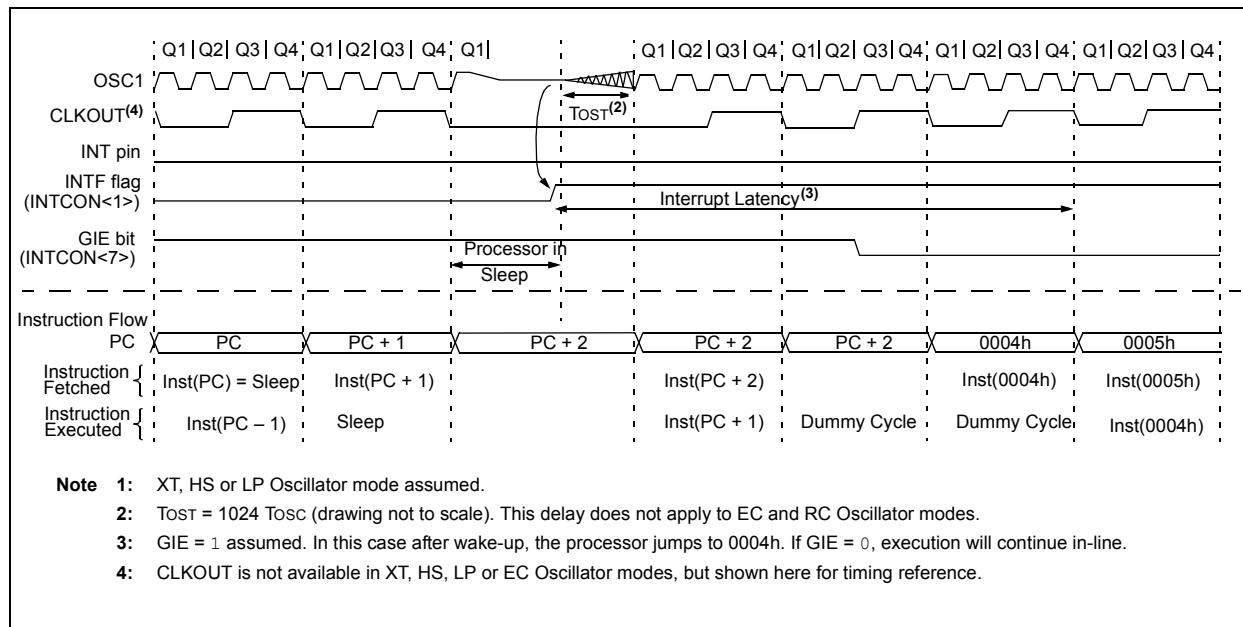
When global interrupts are disabled (GIE cleared) and any interrupt source has both its interrupt enable bit and interrupt flag bit set, one of the following will occur:

- If the interrupt occurs **before** the execution of a `SLEEP` instruction, the `SLEEP` instruction will complete as a `NOP`. Therefore, the WDT and WDT prescaler and postscaler (if enabled) will not be cleared, the `TO` bit will not be set and the `PD` bit will not be cleared.
- If the interrupt occurs **during or after** the execution of a `SLEEP` instruction, the device will immediately wake-up from Sleep. The `SLEEP` instruction will be completely executed before the wake-up. Therefore, the WDT and WDT prescaler and postscaler (if enabled) will be cleared, the `TO` bit will be set and the `PD` bit will be cleared.

Even if the flag bits were checked before executing a `SLEEP` instruction, it may be possible for flag bits to become set before the `SLEEP` instruction completes. To determine whether a `SLEEP` instruction executed, test the `PD` bit. If the `PD` bit is set, the `SLEEP` instruction was executed as a `NOP`.

To ensure that the WDT is cleared, a `CLRWDT` instruction should be executed before a `SLEEP` instruction.

FIGURE 14-10: WAKE-UP FROM SLEEP THROUGH INTERRUPT



14.7 Code Protection

If the code protection bit(s) have not been programmed, the on-chip program memory can be read out using ICSP™ for verification purposes.

Note: The entire data EEPROM and Flash program memory will be erased when the code protection is switched from on to off. See the “PIC16F88X Memory Programming Specification” (DS41287) for more information.

14.8 ID Locations

Four memory locations (2000h-2003h) are designated as ID locations where the user can store checksum or other code identification numbers. These locations are not accessible during normal execution but are readable and writable during Program/Verify mode. Only the Least Significant 7 bits of the ID locations are used.

14.9 In-Circuit Serial Programming™

The PIC16F882/883/884/886/887 microcontrollers can be serially programmed while in the end application circuit. This is simply done with two lines for clock and data and three other lines for:

- power
- ground
- programming voltage

This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

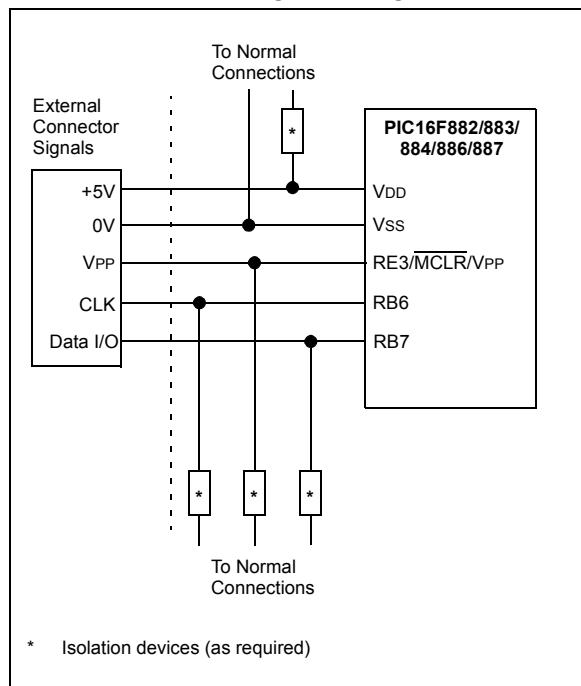
The device is placed into a Program/Verify mode by holding the RB6/ICSPCLK and RB7/ICSPDAT pins low, while raising the MCLR (VPP) pin from VIL to VIH. See the “PIC16F88X Memory Programming Specification” (DS41287) for more information. RB7 becomes the programming data and RB6 becomes the programming clock. Both RB7 and RB6 are Schmitt Trigger inputs in this mode.

After Reset, to place the device into Program/Verify mode, the Program Counter (PC) is at location 00h. A 6-bit command is then supplied to the device. Depending on the command, 14 bits of program data are then supplied to or from the device, depending on whether the command was a Load or a Read. For complete details of serial programming, please refer to the “PIC16F88X Memory Programming Specification” (DS41287).

A typical In-Circuit Serial Programming connection is shown in Figure 14-11.

PIC16F882/883/884/886/887

FIGURE 14-11: TYPICAL IN-CIRCUIT SERIAL PROGRAMMING™ CONNECTION



14.10 Low-Voltage (Single-Supply) ICSP Programming

The LVP bit of the Configuration Word enables low-voltage ICSP programming. This mode allows the microcontroller to be programmed via ICSP using a VDD source in the operating voltage range. This only means that VPP does not have to be brought to VI_H but can instead be left at the normal operating voltage. In this mode, the RB3/PGM pin is dedicated to the programming function and ceases to be a general purpose I/O pin. During programming, VDD is applied to the MCLR pin. To enter Programming mode, VDD must be applied to the RB3/PGM provided the LVP bit is set. The LVP bit defaults to on ('1') from the factory.

- Note 1:** The High-Voltage Programming mode is always available, regardless of the state of the LVP bit, by applying VI_H to the MCLR pin.
- 2: While in Low-Voltage ICSP mode, the RB3 pin can no longer be used as a general purpose I/O pin.
 - 3: When using Low-Voltage ICSP Programming (LVP) and the pull-ups on PORTB are enabled, bit 3 in the TRISB register must be cleared to disable the pull-up on RB3 and ensure the proper operation of the device.
 - 4: RB3 should not be allowed to float if LVP is enabled. An external pull-down device should be used to default the device to normal operating mode. If RB3 floats high, the PIC16F882/883/884/886/887 device will enter Programming mode.
 - 5: LVP mode is enabled by default on all devices shipped from Microchip. It can be disabled by clearing the LVP bit in the CONFIG register.

If Low-Voltage Programming mode is not used, the LVP bit can be programmed to a '0' and RB3/PGM becomes a digital I/O pin. However, the LVP bit may only be programmed when programming is entered with VI_H on MCLR. The LVP bit can only be charged when using high voltage on MCLR.

It should be noted, that once the LVP bit is programmed to '0', only the High-Voltage Programming mode is available and only High-Voltage Programming mode can be used to program the device.

When using low-voltage ICSP, the part must be supplied at 4.5V to 5.5V if a bulk erase will be executed. This includes reprogramming of the code-protect bits from an on state to an off state. For all other cases of low-voltage ICSP, the part may be programmed at the normal operating voltage. This means calibration values, unique user IDs or user code can be reprogrammed or added.

14.11 In-Circuit Debugger

The PIC16F882/883/884/886/887-ICD can be used in any of the package types. The device will be mounted on the target application board, which in turn has a 3 or 4 wire connection to the ICD tool.

When the debug bit in the Configuration Word (CONFIG<13>) is programmed to a '0', the In-Circuit Debugger functionality is enabled. This function allows simple debugging functions when used with MPLAB® ICD 2. When the microcontroller has this feature enabled, some of the resources are not available for general use. See Table 14-9 for more detail.

Note: The user's application must have the circuitry required to support ICD functionality. Once the ICD circuitry is enabled, normal device pin functions on RB6/ICSPCLK and RB7/ICSPDAT will not be usable. The ICD circuitry uses these pins for communication with the ICD2 external debugger.

For more information, see "Using *MPLAB® ICD 2*" (DS51265), available on Microchip's web site (www.microchip.com).

14.11.1 ICD PINOUT

The devices in the PIC16F88X family carry the circuitry for the In-Circuit Debugger on-chip and on existing device pins. This eliminates the need for a separate die or package for the ICD device. The pinout for the ICD device is the same as the devices (see **Section 1.0 "Device Overview"** for complete pinout and pin descriptions). Table 14-9 shows the location and function of the ICD related pins on the 28 and 40 pin devices.

TABLE 14-9: PIC16F883/884/886/887-ICD PIN DESCRIPTIONS

Pin (PDIP)		Name	Type	Pull-up	Description
PIC16F884/887	PIC16F882/883/ 886				
40	28	ICDDATA	TTL	—	In-Circuit Debugger Bidirectional data
39	27	ICDCLK	ST	—	In-Circuit Debugger Bidirectional clock
1	1	<u>MCLR/VPP</u>	HV	—	Programming voltage
11,32	20	VDD	P	—	
12,31	8,19	Vss	P	—	

Legend: TTL = TTL input buffer, ST = Schmitt Trigger input buffer, P = Power, HV = High Voltage

PIC16F882/883/884/886/887

NOTES:

15.0 INSTRUCTION SET SUMMARY

The PIC16F882/883/884/886/887 instruction set is highly orthogonal and is comprised of three basic categories:

- **Byte-oriented** operations
- **Bit-oriented** operations
- **Literal and control** operations

Each PIC16 instruction is a 14-bit word divided into an **opcode**, which specifies the instruction type and one or more **operands**, which further specify the operation of the instruction. The formats for each of the categories is presented in Figure 15-1, while the various opcode fields are summarized in Table 15-1.

Table 15-2 lists the instructions recognized by the MPASM™ assembler.

For **byte-oriented** instructions, 'f' represents a file register designator and 'd' represents a destination designator. The file register designator specifies which file register is to be used by the instruction.

The destination designator specifies where the result of the operation is to be placed. If 'd' is zero, the result is placed in the W register. If 'd' is one, the result is placed in the file register specified in the instruction.

For **bit-oriented** instructions, 'b' represents a bit field designator, which selects the bit affected by the operation, while 'f' represents the address of the file in which the bit is located.

For **literal and control** operations, 'k' represents an 8-bit or 11-bit constant, or literal value.

One instruction cycle consists of four oscillator periods; for an oscillator frequency of 4 MHz, this gives a normal instruction execution time of 1 μ s. All instructions are executed within a single instruction cycle, unless a conditional test is true, or the program counter is changed as a result of an instruction. When this occurs, the execution takes two instruction cycles, with the second cycle executed as a NOP.

All instruction examples use the format '0xhh' to represent a hexadecimal number, where 'h' signifies a hexadecimal digit.

15.1 Read-Modify-Write Operations

Any instruction that specifies a file register as part of the instruction performs a Read-Modify-Write (RMW) operation. The register is read, the data is modified, and the result is stored according to either the instruction, or the destination designator 'd'. A read operation is performed on a register even if the instruction writes to that register.

For example, a CLR PORTA instruction will read PORTA, clear all the data bits, then write the result back to PORTA. This example would have the unintended consequence of clearing the condition that set the RAIF flag.

TABLE 15-1: OPCODE FIELD DESCRIPTIONS

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f. Default is d = 1.
PC	Program Counter
TO	Time-out bit
C	Carry bit
DC	Digit carry bit
Z	Zero bit
PD	Power-down bit

FIGURE 15-1: GENERAL FORMAT FOR INSTRUCTIONS

Byte-oriented file register operations					
13	8	7	6 0		
OPCODE	d	f (FILE #)			
d = 0 for destination W					
d = 1 for destination f					
f = 7-bit file register address					
Bit-oriented file register operations					
13	10	9	7 6 0		
OPCODE	b (BIT #)	f (FILE #)			
b = 3-bit bit address					
f = 7-bit file register address					
Literal and control operations					
General					
13	8	7	0		
OPCODE	k (literal)				
k = 8-bit immediate value					
CALL and GOTO instructions only					
13	11	10	0		
OPCODE	k (literal)				
k = 11-bit immediate value					

PIC16F882/883/884/886/887

TABLE 15-2: PIC16F882/883/884/886/887 INSTRUCTION SET

Mnemonic, Operands	Description	Cycles	14-Bit Opcode				Status Affected	Notes
			MSb		Lsb			
BYTE-ORIENTED FILE REGISTER OPERATIONS								
ADDWF	f, d	Add W and f	1	00	0111	dfff	ffff	C, DC, Z 1, 2
ANDWF	f, d	AND W with f	1	00	0101	dfff	ffff	Z 1, 2
CLRF	f	Clear f	1	00	0001	1fff	ffff	Z 2
CLRW	-	Clear W	1	00	0001	0xxx	xxxx	Z
COMF	f, d	Complement f	1	00	1001	dfff	ffff	Z 1, 2
DECFSZ	f, d	Decrement f	1	00	0011	dfff	ffff	Z 1, 2
DECF	f, d	Decrement f, Skip if 0	1(2)	00	1011	dfff	ffff	1, 2, 3
INCF	f, d	Increment f	1	00	1010	dfff	ffff	Z 1, 2
INCFSZ	f, d	Increment f, Skip if 0	1(2)	00	1111	dfff	ffff	1, 2, 3
IORWF	f, d	Inclusive OR W with f	1	00	0100	dfff	ffff	Z 1, 2
MOVF	f, d	Move f	1	00	1000	dfff	ffff	Z 1, 2
MOVWF	f	Move W to f	1	00	0000	1fff	ffff	Z 1, 2
NOP	-	No Operation	1	00	0000	0xx0	0000	
RLF	f, d	Rotate Left f through Carry	1	00	1101	dfff	ffff	C 1, 2
RRF	f, d	Rotate Right f through Carry	1	00	1100	dfff	ffff	C 1, 2
SUBWF	f, d	Subtract W from f	1	00	0010	dfff	ffff	C, DC, Z 1, 2
SWAPF	f, d	Swap nibbles in f	1	00	1110	dfff	ffff	1, 2
XORWF	f, d	Exclusive OR W with f	1	00	0110	dfff	ffff	Z 1, 2
BIT-ORIENTED FILE REGISTER OPERATIONS								
BCF	f, b	Bit Clear f	1	01	00bb	bfff	ffff	1, 2
BSF	f, b	Bit Set f	1	01	01bb	bfff	ffff	1, 2
BTFSZ	f, b	Bit Test f, Skip if Clear	1(2)	01	10bb	bfff	ffff	3
BTFSS	f, b	Bit Test f, Skip if Set	1(2)	01	11bb	bfff	ffff	3
LITERAL AND CONTROL OPERATIONS								
ADDLW	k	Add literal and W	1	11	111x	kkkk	kkkk	C, DC, Z
ANDLW	k	AND literal with W	1	11	1001	kkkk	kkkk	Z
CALL	k	Call Subroutine	2	10	0kkk	kkkk	kkkk	
CLRWD	-	Clear Watchdog Timer	1	00	0000	0110	0100	TO, PD
GOTO	k	Go to address	2	10	1kkk	kkkk	kkkk	Z
IORLW	k	Inclusive OR literal with W	1	11	1000	kkkk	kkkk	
MOVlw	k	Move literal to W	1	11	00xx	kkkk	kkkk	
RETFIE	-	Return from interrupt	2	00	0000	0000	1001	
RETLW	k	Return with literal in W	2	11	01xx	kkkk	kkkk	
RETURN	-	Return from Subroutine	2	00	0000	0000	1000	
SLEEP	-	Go into Standby mode	1	00	0000	0110	0011	TO, PD
SUBLW	k	Subtract w from literal	1	11	110x	kkkk	kkkk	C, DC, Z
XORLW	k	Exclusive OR literal with W	1	11	1010	kkkk	kkkk	Z

- Note 1:** When an I/O register is modified as a function of itself (e.g., MOVF GPIO, 1), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.
- 2:** If this instruction is executed on the TMR0 register (and where applicable, d = 1), the prescaler will be cleared if assigned to the Timer0 module.
- 3:** If the Program Counter (PC) is modified, or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

15.2 Instruction Descriptions

ADDLW	Add literal and W	BCF	Bit Clear f
Syntax:	[<i>label</i>] ADDLW k	Syntax:	[<i>label</i>] BCF f,b
Operands:	0 ≤ k ≤ 255	Operands:	0 ≤ f ≤ 127 0 ≤ b ≤ 7
Operation:	(W) + k → (W)	Operation:	0 → (f)
Status Affected:	C, DC, Z	Status Affected:	None
Description:	The contents of the W register are added to the eight-bit literal 'k' and the result is placed in the W register.	Description:	Bit 'b' in register 'f' is cleared.
ADDWF	Add W and f	BSF	Bit Set f
Syntax:	[<i>label</i>] ADDWF f,d	Syntax:	[<i>label</i>] BSF f,b
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]	Operands:	0 ≤ f ≤ 127 0 ≤ b ≤ 7
Operation:	(W) + (f) → (destination)	Operation:	1 → (f)
Status Affected:	C, DC, Z	Status Affected:	None
Description:	Add the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.	Description:	Bit 'b' in register 'f' is set.
ANDLW	AND literal with W	BTFSC	Bit Test f, Skip if Clear
Syntax:	[<i>label</i>] ANDLW k	Syntax:	[<i>label</i>] BTFSC f,b
Operands:	0 ≤ k ≤ 255	Operands:	0 ≤ f ≤ 127 0 ≤ b ≤ 7
Operation:	(W) .AND. (k) → (W)	Operation:	skip if (f) = 0
Status Affected:	Z	Status Affected:	None
Description:	The contents of W register are AND'ed with the eight-bit literal 'k'. The result is placed in the W register.	Description:	If bit 'b' in register 'f' is '1', the next instruction is executed. If bit 'b' in register 'f' is '0', the next instruction is discarded, and a NOP is executed instead, making this a two-cycle instruction.
ANDWF	AND W with f		
Syntax:	[<i>label</i>] ANDWF f,d		
Operands:	0 ≤ f ≤ 127 d ∈ [0,1]		
Operation:	(W) .AND. (f) → (destination)		
Status Affected:	Z		
Description:	AND the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.		

PIC16F882/883/884/886/887

BTFSS	Bit Test f, Skip if Set
Syntax:	[<i>label</i>] BTFSS f,b
Operands:	$0 \leq f \leq 127$ $0 \leq b < 7$
Operation:	skip if $(f) = 1$
Status Affected:	None
Description:	If bit 'b' in register 'f' is '0', the next instruction is executed. If bit 'b' is '1', then the next instruction is discarded and a NOP is executed instead, making this a two-cycle instruction.

CLRWDT	Clear Watchdog Timer
Syntax:	[<i>label</i>] CLRWDT
Operands:	None
Operation:	$00h \rightarrow WDT$ $0 \rightarrow \underline{WDT}$ prescaler, $1 \rightarrow \underline{\overline{TO}}$ $1 \rightarrow \underline{\overline{PD}}$
Status Affected:	$\overline{TO}, \overline{PD}$
Description:	CLRWDT instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits \overline{TO} and \overline{PD} are set.

CALL	Call Subroutine
Syntax:	[<i>label</i>] CALL k
Operands:	$0 \leq k \leq 2047$
Operation:	$(PC)+1 \rightarrow TOS,$ $k \rightarrow PC<10:0>$, $(PCLATH<4:3>) \rightarrow PC<12:11>$
Status Affected:	None
Description:	Call Subroutine. First, return address ($PC + 1$) is pushed onto the stack. The eleven-bit immediate address is loaded into PC bits $<10:0>$. The upper bits of the PC are loaded from PCLATH. CALL is a two-cycle instruction.

COMF	Complement f
Syntax:	[<i>label</i>] COMF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) \rightarrow (destination)$
Status Affected:	Z
Description:	The contents of register 'f' are complemented. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f'.

CLRF	Clear f
Syntax:	[<i>label</i>] CLRF f
Operands:	$0 \leq f \leq 127$
Operation:	$00h \rightarrow (f)$ $1 \rightarrow Z$
Status Affected:	Z
Description:	The contents of register 'f' are cleared and the Z bit is set.

DECF	Decrement f
Syntax:	[<i>label</i>] DECF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) - 1 \rightarrow (destination)$
Status Affected:	Z
Description:	Decrement register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

CLRW	Clear W
Syntax:	[<i>label</i>] CLRW
Operands:	None
Operation:	$00h \rightarrow (W)$ $1 \rightarrow Z$
Status Affected:	Z
Description:	W register is cleared. Zero bit (Z) is set.

DECFSZ	Decrement f, Skip if 0
Syntax:	[<i>label</i>] DECFSZ f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) - 1 \rightarrow (\text{destination})$, skip if result = 0
Status Affected:	None
Description:	The contents of register 'f' are decremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'. If the result is '1', the next instruction is executed. If the result is '0', then a NOP is executed instead, making it a two-cycle instruction.

INCFSZ	Increment f, Skip if 0
Syntax:	[<i>label</i>] INCFSZ f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) + 1 \rightarrow (\text{destination})$, skip if result = 0
Status Affected:	None
Description:	The contents of register 'f' are incremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'. If the result is '1', the next instruction is executed. If the result is '0', a NOP is executed instead, making it a two-cycle instruction.

GOTO	Unconditional Branch
Syntax:	[<i>label</i>] GOTO k
Operands:	$0 \leq k \leq 2047$
Operation:	$k \rightarrow \text{PC} <10:0>$ $\text{PCLATH} <4:3> \rightarrow \text{PC} <12:11>$
Status Affected:	None
Description:	GOTO is an unconditional branch. The eleven-bit immediate value is loaded into PC bits <10:0>. The upper bits of PC are loaded from PCLATH<4:3>. GOTO is a two-cycle instruction.

IORLW	Inclusive OR literal with W
Syntax:	[<i>label</i>] IORLW k
Operands:	$0 \leq k \leq 255$
Operation:	$(W) .OR. k \rightarrow (W)$
Status Affected:	Z
Description:	The contents of the W register are OR'ed with the eight-bit literal 'k'. The result is placed in the W register.

INCF	Increment f
Syntax:	[<i>label</i>] INCF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) + 1 \rightarrow (\text{destination})$
Status Affected:	Z
Description:	The contents of register 'f' are incremented. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.

IORWF	Inclusive OR W with f
Syntax:	[<i>label</i>] IORWF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(W) .OR. (f) \rightarrow (\text{destination})$
Status Affected:	Z
Description:	Inclusive OR the W register with register 'f'. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'.

PIC16F882/883/884/886/887

MOVF	Move f
Syntax:	[<i>label</i>] MOVF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f) \rightarrow (\text{dest})$
Status Affected:	Z
Description:	The contents of register 'f' is moved to a destination dependent upon the status of 'd'. If $d = 0$, destination is W register. If $d = 1$, the destination is file register 'f' itself. $d = 1$ is useful to test a file register since status flag Z is affected.
Words:	1
Cycles:	1
<u>Example:</u>	MOVF FSR, 0
After Instruction	
W = value in FSR register	
Z = 1	

MOVWF	Move W to f
Syntax:	[<i>label</i>] MOVWF f
Operands:	$0 \leq f \leq 127$
Operation:	$(W) \rightarrow (f)$
Status Affected:	None
Description:	Move data from W register to register 'f'.
Words:	1
Cycles:	1
<u>Example:</u>	MOVW OPTION F
Before Instruction	
OPTION = 0xFF W = 0x4F	
After Instruction	
OPTION = 0x4F W = 0x4F	

MOVLW	Move literal to W
Syntax:	[<i>label</i>] MOVLW k
Operands:	$0 \leq k \leq 255$
Operation:	$k \rightarrow (W)$
Status Affected:	None
Description:	The eight-bit literal 'k' is loaded into W register. The "don't cares" will assemble as '0's.
Words:	1
Cycles:	1
<u>Example:</u>	MOVLW 0x5A
After Instruction	
W = 0x5A	

NOP	No Operation
Syntax:	[<i>label</i>] NOP
Operands:	None
Operation:	No operation
Status Affected:	None
Description:	No operation.
Words:	1
Cycles:	1
<u>Example:</u>	NOP

PIC16F882/883/884/886/887

RETFIE	Return from Interrupt
Syntax:	[<i>label</i>] RETFIE
Operands:	None
Operation:	TOS → PC, 1 → GIE
Status Affected:	None
Description:	Return from Interrupt. Stack is POPed and Top-of-Stack (TOS) is loaded in the PC. Interrupts are enabled by setting Global Interrupt Enable bit, GIE (INTCON<7>). This is a two-cycle instruction.
Words:	1
Cycles:	2
<u>Example:</u>	<pre>RETFIE After Interrupt PC = TOS GIE = 1</pre>

RETLW	Return with literal in W
Syntax:	[<i>label</i>] RETLW <i>k</i>
Operands:	0 ≤ <i>k</i> ≤ 255
Operation:	<i>k</i> → (W); TOS → PC
Status Affected:	None
Description:	The W register is loaded with the eight-bit literal ' <i>k</i> '. The program counter is loaded from the top of the stack (the return address). This is a two-cycle instruction.
Words:	1
Cycles:	2
<u>Example:</u>	<pre>CALL TABLE;W contains table ;offset value • ;W now has • ;table value • • ADDWF PC ;W = offset RETLW k1 ;Begin table RETLW k2 ; • • RETLW kn ;End of table</pre>

Before Instruction
 W = 0x07
 After Instruction
 W = value of *k*8

RETURN	Return from Subroutine
Syntax:	[<i>label</i>] RETURN
Operands:	None
Operation:	TOS → PC
Status Affected:	None
Description:	Return from subroutine. The stack is POPed and the top of the stack (TOS) is loaded into the program counter. This is a two-cycle instruction.

PIC16F882/883/884/886/887

RLF	Rotate Left f through Carry
Syntax:	[<i>label</i>] RLF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	See description below
Status Affected:	C
Description:	The contents of register 'f' are rotated one bit to the left through the Carry flag. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is stored back in register 'f'. 
Words:	1
Cycles:	1
<u>Example:</u>	RLF REG1,0

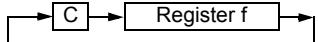
Before Instruction

```
REG1      = 1110 0110
C          = 0
```

After Instruction

```
REG1      = 1110 0110
W          = 1100 1100
C          = 1
```

SLEEP	Enter Sleep mode
Syntax:	[<i>label</i>] SLEEP
Operands:	None
Operation:	$00h \rightarrow \text{WDT}$, $0 \rightarrow \text{WDT prescaler}$, $1 \rightarrow \overline{\text{TO}}$, $0 \rightarrow \overline{\text{PD}}$
Status Affected:	$\overline{\text{TO}}, \overline{\text{PD}}$
Description:	The power-down Status bit, $\overline{\text{PD}}$ is cleared. Time-out Status bit, $\overline{\text{TO}}$ is set. Watchdog Timer and its prescaler are cleared. The processor is put into Sleep mode with the oscillator stopped.

RRF	Rotate Right f through Carry
Syntax:	[<i>label</i>] RRF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	See description below
Status Affected:	C
Description:	The contents of register 'f' are rotated one bit to the right through the Carry flag. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed back in register 'f'. 

SUBLW	Subtract W from literal
Syntax:	[<i>label</i>] SUBLW k
Operands:	$0 \leq k \leq 255$
Operation:	$k - (W) \rightarrow (W)$
Status Affected:	C, DC, Z
Description:	The W register is subtracted (2's complement method) from the eight-bit literal 'k'. The result is placed in the W register.

C = 0	W > k
C = 1	W ≤ k
DC = 0	W<3:0> > k<3:0>
DC = 1	W<3:0> ≤ k<3:0>

SUBWF	Subtract W from f								
Syntax:	[<i>label</i>] SUBWF f,d								
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$								
Operation:	$(f) - (W) \rightarrow (\text{destination})$								
Status Affected:	C, DC, Z								
Description:	Subtract (2's complement method) W register from register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.								
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="padding: 2px;">C = 0</td> <td style="padding: 2px;">W > f</td> </tr> <tr> <td style="padding: 2px;">C = 1</td> <td style="padding: 2px;">W ≤ f</td> </tr> <tr> <td style="padding: 2px;">DC = 0</td> <td style="padding: 2px;">W<3:0> > f<3:0></td> </tr> <tr> <td style="padding: 2px;">DC = 1</td> <td style="padding: 2px;">W<3:0> ≤ f<3:0></td> </tr> </table>		C = 0	W > f	C = 1	W ≤ f	DC = 0	W<3:0> > f<3:0>	DC = 1	W<3:0> ≤ f<3:0>
C = 0	W > f								
C = 1	W ≤ f								
DC = 0	W<3:0> > f<3:0>								
DC = 1	W<3:0> ≤ f<3:0>								

XORWF	Exclusive OR W with f
Syntax:	[<i>label</i>] XORWF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(W) .XOR. (f) \rightarrow (\text{destination})$
Status Affected:	Z
Description:	Exclusive OR the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

SWAPF	Swap Nibbles in f
Syntax:	[<i>label</i>] SWAPF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f<3:0>) \rightarrow (\text{destination}<7:4>),$ $(f<7:4>) \rightarrow (\text{destination}<3:0>)$
Status Affected:	None
Description:	The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed in register 'f'.

XORLW	Exclusive OR literal with W
Syntax:	[<i>label</i>] XORLW k
Operands:	$0 \leq k \leq 255$
Operation:	$(W) .XOR. k \rightarrow (W)$
Status Affected:	Z
Description:	The contents of the W register are XOR'ed with the eight-bit literal 'k'. The result is placed in the W register.

PIC16F882/883/884/886/887

NOTES:

16.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers are supported with a full range of hardware and software development tools:

- Integrated Development Environment
 - MPLAB® IDE Software
- Assemblers/Compilers/Linkers
 - MPASM™ Assembler
 - MPLAB C18 and MPLAB C30 C Compilers
 - MPLINK™ Object Linker/
MPLIB™ Object Librarian
 - MPLAB ASM30 Assembler/Linker/Library
- Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB ICE 2000 In-Circuit Emulator
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debugger
 - MPLAB ICD 2
- Device Programmers
 - PICSTART® Plus Development Programmer
 - MPLAB PM3 Device Programmer
 - PICkit™ 2 Development Programmer
- Low-Cost Demonstration and Development Boards and Evaluation Kits

16.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16-bit microcontroller market. The MPLAB IDE is a Windows® operating system-based application that contains:

- A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Visual device initializer for easy register initialization
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as HI-TECH Software C Compilers and IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either assembly or C)
- One touch assemble (or compile) and download to PIC MCU emulator and simulator tools (automatically updates all project information)
- Debug using:
 - Source files (assembly or C)
 - Mixed assembly and C
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

16.2 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for all PIC MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multi-purpose source files
- Directives that allow complete control over the assembly process

16.3 MPLAB C18 and MPLAB C30 C Compilers

The MPLAB C18 and MPLAB C30 Code Development Systems are complete ANSI C compilers for Microchip's PIC18 and PIC24 families of microcontrollers and the dsPIC30 and dsPIC33 family of digital signal controllers. These compilers provide powerful integration capabilities, superior code optimization and ease of use not found with other compilers.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

16.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler and the MPLAB C18 C Compiler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

16.5 MPLAB ASM30 Assembler, Linker and Librarian

MPLAB ASM30 Assembler produces relocatable machine code from symbolic assembly language for dsPIC30F devices. MPLAB C30 C Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire dsPIC30F instruction set
- Support for fixed-point and floating-point data
- Command line interface
- Rich directive set
- Flexible macro language
- MPLAB IDE compatibility

16.6 MPLAB SIM Software Simulator

The MPLAB SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC® DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB SIM Software Simulator fully supports symbolic debugging using the MPLAB C18 and MPLAB C30 C Compilers, and the MPASM and MPLAB ASM30 Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

16.7 MPLAB ICE 2000 High-Performance In-Circuit Emulator

The MPLAB ICE 2000 In-Circuit Emulator is intended to provide the product development engineer with a complete microcontroller design tool set for PIC microcontrollers. Software control of the MPLAB ICE 2000 In-Circuit Emulator is advanced by the MPLAB Integrated Development Environment, which allows editing, building, downloading and source debugging from a single environment.

The MPLAB ICE 2000 is a full-featured emulator system with enhanced trace, trigger and data monitoring features. Interchangeable processor modules allow the system to be easily reconfigured for emulation of different processors. The architecture of the MPLAB ICE 2000 In-Circuit Emulator allows expansion to support new PIC microcontrollers.

The MPLAB ICE 2000 In-Circuit Emulator system has been designed as a real-time emulation system with advanced features that are typically found on more expensive development tools. The PC platform and Microsoft® Windows® 32-bit operating system were chosen to best make these features available in a simple, unified application.

16.8 MPLAB REAL ICE In-Circuit Emulator System

MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC® and MCU devices. It debugs and programs PIC® and dsPIC® Flash microcontrollers with the easy-to-use, powerful graphical user interface of the MPLAB Integrated Development Environment (IDE), included with each kit.

The MPLAB REAL ICE probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with the popular MPLAB ICD 2 system (RJ11) or with the new high speed, noise tolerant, low-voltage differential signal (LVDS) interconnection (CAT5).

MPLAB REAL ICE is field upgradeable through future firmware downloads in MPLAB IDE. In upcoming releases of MPLAB IDE, new devices will be supported, and new features will be added, such as software breakpoints and assembly code trace. MPLAB REAL ICE offers significant advantages over competitive emulators including low-cost, full-speed emulation, real-time variable watches, trace analysis, complex breakpoints, a ruggedized probe interface and long (up to three meters) interconnection cables.

16.9 MPLAB ICD 2 In-Circuit Debugger

Microchip's In-Circuit Debugger, MPLAB ICD 2, is a powerful, low-cost, run-time development tool, connecting to the host PC via an RS-232 or high-speed USB interface. This tool is based on the Flash PIC MCUs and can be used to develop for these and other PIC MCUs and dsPIC DSCs. The MPLAB ICD 2 utilizes the in-circuit debugging capability built into the Flash devices. This feature, along with Microchip's In-Circuit Serial Programming™ (ICSP™) protocol, offers cost-effective, in-circuit Flash debugging from the graphical user interface of the MPLAB Integrated Development Environment. This enables a designer to develop and debug source code by setting breakpoints, single stepping and watching variables, and CPU status and peripheral registers. Running at full speed enables testing hardware and applications in real time. MPLAB ICD 2 also serves as a development programmer for selected PIC devices.

16.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an SD/MMC card for file storage and secure data applications.

PIC16F882/883/884/886/887

16.11 PICSTART Plus Development Programmer

The PICSTART Plus Development Programmer is an easy-to-use, low-cost, prototype programmer. It connects to the PC via a COM (RS-232) port. MPLAB Integrated Development Environment software makes using the programmer simple and efficient. The PICSTART Plus Development Programmer supports most PIC devices in DIP packages up to 40 pins. Larger pin count devices, such as the PIC16C92X and PIC17C76X, may be supported with an adapter socket. The PICSTART Plus Development Programmer is CE compliant.

16.12 PICkit 2 Development Programmer

The PICkit™ 2 Development Programmer is a low-cost programmer and selected Flash device debugger with an easy-to-use interface for programming many of Microchip's baseline, mid-range and PIC18F families of Flash memory microcontrollers. The PICkit 2 Starter Kit includes a prototyping development board, twelve sequential lessons, software and HI-TECH's PICC™ Lite C compiler, and is designed to help get up to speed quickly using PIC® microcontrollers. The kit provides everything needed to program, evaluate and develop applications using Microchip's powerful, mid-range Flash memory family of microcontrollers.

16.13 Demonstration, Development and Evaluation Boards

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart® battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Check the Microchip web page (www.microchip.com) and the latest "Product Selector Guide" (DS00148) for the complete list of demonstration, development and evaluation kits.

17.0 ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings^(†)

Ambient temperature under bias	-40° to +125°C
Storage temperature	-65°C to +150°C
Voltage on VDD with respect to Vss	-0.3V to +6.5V
Voltage on <u>MCLR</u> with respect to Vss	-0.3V to +13.5V
Voltage on all other pins with respect to Vss	-0.3V to (VDD + 0.3V)
Total power dissipation ⁽¹⁾	800 mW
Maximum current out of VSS pin	95 mA
Maximum current into VDD pin	95 mA
Input clamp current, I _{IK} (V _I < 0 or V _I > VDD).....	± 20 mA
Output clamp current, I _{OK} (V _O < 0 or V _O > VDD).....	± 20 mA
Maximum output current sunk by any I/O pin.....	25 mA
Maximum output current sourced by any I/O pin	25 mA
Maximum current sunk by all ports (combined) ⁽²⁾	90 mA
Maximum current sourced by all ports (combined) ⁽²⁾	90 mA

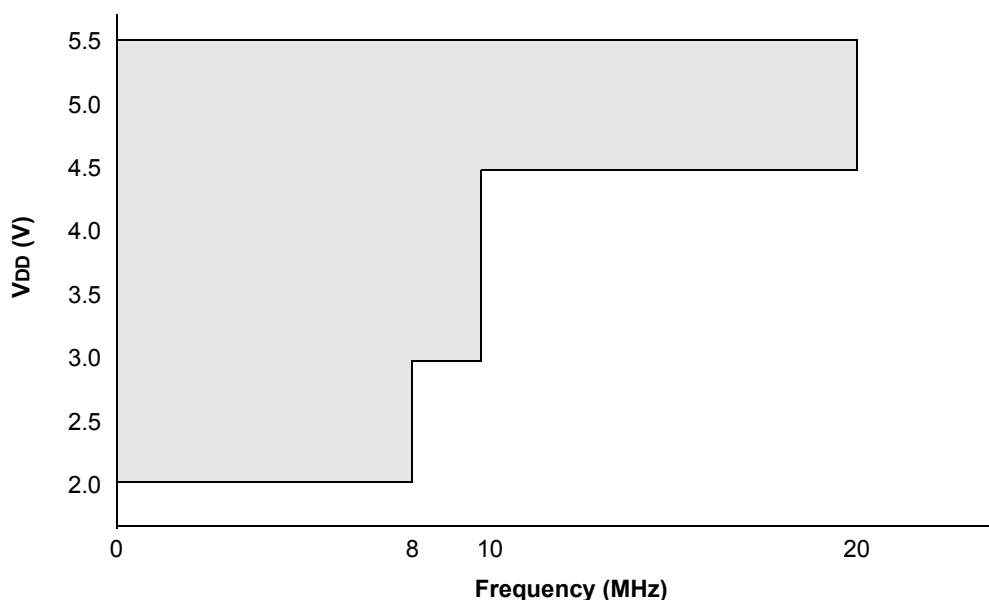
Note 1: Power dissipation is calculated as follows: PDIS = VDD x {I_{DD} - \sum I_{OH}} + \sum {(VDD - V_{OH}) x I_{OH}} + \sum {(V_{OL} x I_{OL})}

2: PORTD and PORTE are implemented on PIC16F886/PIC16F887 only.

† NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability.

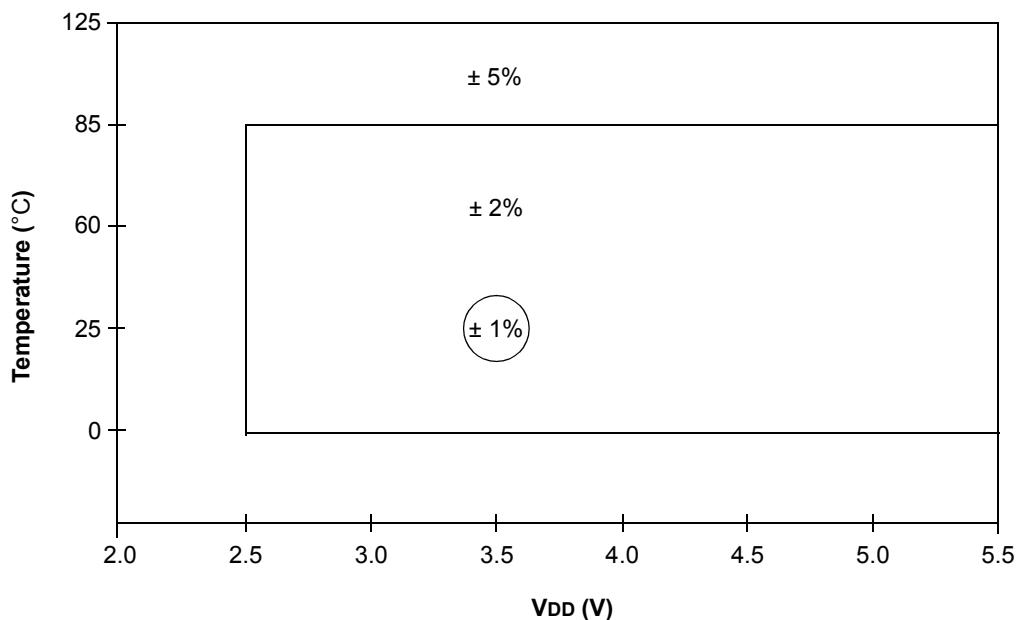
PIC16F882/883/884/886/887

FIGURE 17-1: PIC16F883/884/886/887 VOLTAGE-FREQUENCY GRAPH,
 $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

FIGURE 17-2: HFINTOSC FREQUENCY ACCURACY OVER DEVICE V_{DD} AND TEMPERATURE



PIC16F882/883/884/886/887

17.1 DC Characteristics: PIC16F883/884/886/887-I (Industrial) PIC16F883/884/886/887-E (Extended)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C}$ for industrial $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$ for extended				
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
D001	VDD	Supply Voltage	2.0	—	5.5	V	$\text{Fosc} \leq 8 \text{ MHz}$: HFINTOSC, EC
			2.0	—	5.5	V	$\text{Fosc} \leq 4 \text{ MHz}$
			3.0	—	5.5	V	$\text{Fosc} \leq 10 \text{ MHz}$
			4.5	—	5.5	V	$\text{Fosc} \leq 20 \text{ MHz}$
D002*	VDR	RAM Data Retention Voltage⁽¹⁾	1.5	—	—	V	Device in Sleep mode
D003	VPOR	VDD Start Voltage to ensure internal Power-on Reset signal	—	Vss	—	V	See Section 14.2.1 “Power-on Reset (POR)” for details.
D004*	SVDD	VDD Rise Rate to ensure internal Power-on Reset signal	0.05	—	—	V/ms	See Section 14.2.1 “Power-on Reset (POR)” for details.

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: This is the limit to which VDD can be lowered in Sleep mode without losing RAM data.

PIC16F882/883/884/886/887

17.2 DC Characteristics: PIC16F883/884/886/887-I (Industrial) PIC16F883/884/886/887-E (Extended)

DC CHARACTERISTICS		Standard Operating Conditions (unless otherwise stated)					
Param No.	Device Characteristics	Min.	Typ	Max.	Units	Conditions VDD	Note
		—	13	19	µA	2.0	
D010	Supply Current (IDD) ^(1, 2)	—	22	30	µA	3.0	Fosc = 32 kHz LP Oscillator mode
		—	33	60	µA	5.0	
		—	180	250	µA	2.0	
D011*		—	290	400	µA	3.0	Fosc = 1 MHz XT Oscillator mode
		—	490	650	µA	5.0	
		—	280	380	µA	2.0	
D012		—	480	670	µA	3.0	Fosc = 4 MHz XT Oscillator mode
		—	0.9	1.4	mA	5.0	
		—	170	295	µA	2.0	
D013*		—	280	480	µA	3.0	Fosc = 1 MHz EC Oscillator mode
		—	470	690	µA	5.0	
		—	290	450	µA	2.0	
D014		—	490	720	µA	3.0	Fosc = 4 MHz EC Oscillator mode
		—	0.85	1.3	mA	5.0	
		—	8	20	µA	2.0	
D015		—	16	40	µA	3.0	Fosc = 31 kHz LFINTOSC mode
		—	31	65	µA	5.0	
		—	416	520	µA	2.0	
D016*		—	640	840	µA	3.0	Fosc = 4 MHz HFINTOSC mode
		—	1.13	1.6	mA	5.0	
		—	0.65	0.9	mA	2.0	
D017		—	1.01	1.3	mA	3.0	Fosc = 8 MHz HFINTOSC mode
		—	1.86	2.3	mA	5.0	
		—	340	580	µA	2.0	
D018		—	550	900	µA	3.0	Fosc = 4 MHz EXT RC mode ⁽³⁾
		—	0.92	1.4	mA	5.0	
		—	3.8	4.7	mA	4.5	
D019		—	4.0	4.8	mA	5.0	Fosc = 20 MHz HS Oscillator mode

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** The test conditions for all IDD measurements in active operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD; MCLR = VDD; WDT disabled.
- 2:** The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.
- 3:** For RC oscillator configurations, current through REXT is not included. The current through the resistor can be extended by the formula $IR = VDD/2REXT$ (mA) with REXT in kΩ.

PIC16F882/883/884/886/887

17.3 DC Characteristics: PIC16F883/884/886/887-I (Industrial)

DC CHARACTERISTICS		Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C}$ for industrial					
Param No.	Device Characteristics	Min.	Typ†	Max.	Units	Conditions	
						VDD	
D020	Power-down Base Current(IPD)⁽²⁾	—	0.05	1.2	μA	2.0	WDT, BOR, Comparators, VREF and T1OSC disabled $-40^{\circ}\text{C} \leq \text{TA} \leq +25^{\circ}\text{C}$
		—	0.15	1.5	μA	3.0	
		—	0.35	1.8	μA	5.0	
		—	150	500	nA	3.0	
D021		—	1.0	2.2	μA	2.0	WDT Current ⁽¹⁾
		—	2.0	4.0	μA	3.0	
		—	3.0	7.0	μA	5.0	
D022		—	42	60	μA	3.0	BOR Current ⁽¹⁾
		—	85	122	μA	5.0	
D023		—	32	45	μA	2.0	Comparator Current ⁽¹⁾ , both comparators enabled
		—	60	78	μA	3.0	
		—	120	160	μA	5.0	
D024		—	30	36	μA	2.0	CVREF Current ⁽¹⁾ (high range)
		—	45	55	μA	3.0	
		—	75	95	μA	5.0	
D025*		—	39	47	μA	2.0	CVREF Current ⁽¹⁾ (low range)
		—	59	72	μA	3.0	
		—	98	124	μA	5.0	
D026		—	2.0	5.0	μA	2.0	T1OSC Current ⁽¹⁾ , 32.768 kHz
		—	2.5	5.5	μA	3.0	
		—	3.0	7.0	μA	5.0	
D027		—	0.30	1.6	μA	3.0	A/D Current ⁽¹⁾ , no conversion in progress
		—	0.36	1.9	μA	5.0	
D028		—	90	125	μA	3.0	VP6 Reference Current
		—	125	162	μA	5.0	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** The peripheral current is the sum of the base IDD or IPD and the additional current consumed when this peripheral is enabled. The peripheral Δ current can be determined by subtracting the base IDD or IPD current from this limit. Max values should be used when calculating total current consumption.
- 2:** The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to VDD.

PIC16F882/883/884/886/887

17.4 DC Characteristics: PIC16F883/884/886/887-E (Extended)

DC CHARACTERISTICS		Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$ for extended					
Param No.	Device Characteristics	Min.	Typ†	Max.	Units	Conditions	
						V _{DD}	Note
D020E	Power-down Base Current (IPD)⁽²⁾	—	0.05	9	μA	2.0	WDT, BOR, Comparators, V _{REF} and T1OSC disabled
		—	0.15	11	μA	3.0	
		—	0.35	15	μA	5.0	
D021E		—	1	28	μA	2.0	WDT Current ⁽¹⁾
		—	2	30	μA	3.0	
		—	3	35	μA	5.0	
D022E		—	42	65	μA	3.0	BOR Current ⁽¹⁾
		—	85	127	μA	5.0	
D023E		—	32	45	μA	2.0	Comparator Current ⁽¹⁾ , both comparators enabled
		—	60	78	μA	3.0	
		—	120	160	μA	5.0	
D024E		—	30	70	μA	2.0	CVREF Current ⁽¹⁾ (high range)
		—	45	90	μA	3.0	
		—	75	120	μA	5.0	
D025E*		—	39	91	μA	2.0	CVREF Current ⁽¹⁾ (low range)
		—	59	117	μA	3.0	
		—	98	156	μA	5.0	
D026E		—	3.5	18	μA	2.0	T1OSC Current ⁽¹⁾ , 32.768 kHz
		—	4.0	21	μA	3.0	
		—	5.0	24	μA	5.0	
D027E		—	0.30	12	μA	3.0	A/D Current ⁽¹⁾ , no conversion in progress
		—	0.36	16	μA	5.0	
D028E		—	90	130	μA	3.0	VP6 Reference Current
		—	125	170	μA	5.0	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: The peripheral current is the sum of the base IDD or IPD and the additional current consumed when this peripheral is enabled. The peripheral Δ current can be determined by subtracting the base IDD or IPD current from this limit. Max values should be used when calculating total current consumption.

2: The power-down current in Sleep mode does not depend on the oscillator type. Power-down current is measured with the part in Sleep mode, with all I/O pins in high-impedance state and tied to V_{DD}.

17.5 DC Characteristics: PIC16F883/884/886/887-I (Industrial) PIC16F883/884/886/887-E (Extended)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated)				
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
D030 D030A D031 D032 D033 D033A	VIL	Input Low Voltage I/O Port: with TTL buffer	Vss	—	0.8	V	4.5V ≤ VDD ≤ 5.5V
		with Schmitt Trigger buffer	Vss	—	0.15 VDD	V	2.0V ≤ VDD ≤ 4.5V
		MCLR, OSC1 (RC mode) ⁽¹⁾	Vss	—	0.2 VDD	V	2.0V ≤ VDD ≤ 5.5V
		OSC1 (XT and LP modes)	Vss	—	0.2 VDD	V	
		OSC1 (HS mode)	Vss	—	0.3	V	
		OSC1 (RC mode)	Vss	—	0.3 VDD	V	
D040 D040A D041 D042 D043 D043A D043B	VIH	Input High Voltage I/O ports: with TTL buffer	2.0	—	VDD	V	4.5V ≤ VDD ≤ 5.5V
		with Schmitt Trigger buffer	0.25 VDD + 0.8	—	VDD	V	2.0V ≤ VDD ≤ 4.5V
		MCLR	0.8 VDD	—	VDD	V	2.0V ≤ VDD ≤ 5.5V
		OSC1 (XT and LP modes)	0.8 VDD	—	VDD	V	
		OSC1 (HS mode)	1.6	—	VDD	V	
		OSC1 (RC mode)	0.7 VDD	—	VDD	V	
			0.9 VDD	—	VDD	V	(Note 1)
D060 D061 D063	IIL	Input Leakage Current⁽²⁾ I/O ports	—	± 0.1	± 1	µA	VSS ≤ VPIN ≤ VDD, Pin at high-impedance
		MCLR ⁽³⁾	—	± 0.1	± 5	µA	VSS ≤ VPIN ≤ VDD
		OSC1	—	± 0.1	± 5	µA	VSS ≤ VPIN ≤ VDD, XT, HS and LP oscillator configuration
D070*	IPUR	PORTE Weak Pull-up Current	50	250	400	µA	VDD = 5.0V, VPIN = VSS
D080	VOL	Output Low Voltage ⁽⁵⁾ I/O ports	—	—	0.6	V	IOL = 8.5 mA, VDD = 4.5V (Ind.)
D090	VOH	Output High Voltage ⁽⁵⁾ I/O ports	VDD – 0.7	—	—	V	IOH = -3.0 mA, VDD = 4.5V (Ind.)

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.
- 2:** Negative current is defined as current sourced by the pin.
- 3:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 4:** See **Section 10.3.1 “Using the Data EEPROM”** for additional information.
- 5:** Including OSC2 in CLKOUT mode.

PIC16F882/883/884/886/887

17.5 DC Characteristics: PIC16F883/884/886/887-I (Industrial) PIC16F883/884/886/887-E (Extended) (Continued)

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated)				
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
D100	IULP	Ultra Low-Power Wake-Up Current	—	200	—	nA	See Application Note AN879, "Using the Microchip Ultra Low-Power Wake-up Module" (DS00879)
D101*	COSC2	Capacitive Loading Specs on Output Pins OSC2 pin	—	—	15	pF	In XT, HS and LP modes when external clock is used to drive OSC1
D101A*	CIO	All I/O pins	—	—	50	pF	
Data EEPROM Memory							
D120	ED	Byte Endurance	100K	1M	—	E/W	-40°C ≤ TA ≤ +85°C
D120A	ED	Byte Endurance	10K	100K	—	E/W	+85°C ≤ TA ≤ +125°C
D121	VDRW	VDD for Read/Write	V _{MIN}	—	5.5	V	Using EECON1 to read/write V _{MIN} = Minimum operating voltage
D122	TDEW	Erase/Write Cycle Time	—	5	6	ms	
D123	TRETD	Characteristic Retention	40	—	—	Year	Provided no other specifications are violated
D124	TREF	Number of Total Erase/Write Cycles before Refresh ⁽⁴⁾	1M	10M	—	E/W	-40°C ≤ TA ≤ +85°C
Program Flash Memory							
D130	EP	Cell Endurance	10K	100K	—	E/W	-40°C ≤ TA ≤ +85°C
D130A	ED	Cell Endurance	1K	10K	—	E/W	+85°C ≤ TA ≤ +125°C
D131	VPR	VDD for Read	V _{MIN}	—	5.5	V	V _{MIN} = Minimum operating voltage
D132	VPEW	VDD for Row Erase/Write	V _{MIN}	—	5.5	V	
		VDD for Bulk Erase Operations	4.5	—	5.5	V	
D133	TPEW	Erase/Write cycle time	—	2	2.5	ms	
D134	TRETD	Characteristic Retention	40	—	—	Year	Provided no other specifications are violated

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.
- 2:** Negative current is defined as current sourced by the pin.
- 3:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 4:** See Section 10.3.1 "Using the Data EEPROM" for additional information.
- 5:** Including OSC2 in CLKOUT mode.

17.6 Thermal Considerations

Standard Operating Conditions (unless otherwise stated)					
Operating temperature -40°C ≤ TA ≤ +125°C					
Param No.	Sym.	Characteristic	Typ.	Units	Conditions
TH01	θJA	Thermal Resistance Junction to Ambient	47.2	C/W	40-pin PDIP package
			24.4	C/W	44-pin QFN package
			45.8	C/W	44-pin TQFP package
			60.2	C/W	28-pin PDIP package
			80.2	C/W	28-pin SOIC package
			89.4	C/W	28-pin SSOP package
			29	C/W	28-pin QFN package
TH02	θJC	Thermal Resistance Junction to Case	24.7	C/W	40-pin PDIP package
			20.0	C/W	44-pin QFN package
			14.5	C/W	44-pin TQFP package
			29	C/W	28-pin PDIP package
			23.8	C/W	28-pin SOIC package
			23.9	C/W	28-pin SSOP package
			20.0	C/W	28-pin QFN package
TH03	TJ	Junction Temperature	150	C	For derated power calculations
TH04	PD	Power Dissipation	—	W	$PD = PINTERNAL + PI/O$
TH05	PINTERNAL	Internal Power Dissipation	—	W	$PINTERNAL = IDD \times VDD$ (NOTE 1)
TH06	PI/O	I/O Power Dissipation	—	W	$PI/O = \sum (IOL * VOL) + \sum (IOH * (VDD - VOH))$
TH07	PDER	Derated Power	—	W	$PDER = (TJ - TA)/\theta JA$ (NOTE 2, 3)

Note 1: IDD is current to run the chip alone without driving any load on the output pins.

2: TA = Ambient Temperature.

3: Maximum allowable power dissipation is the lower value of either the absolute maximum total power dissipation or derated power (PDER).

PIC16F882/883/884/886/887

17.7 Timing Parameter Symbology

The timing parameter symbols have been created with one of the following formats:

1. TppS2ppS

2. TppS

T	
F	Frequency

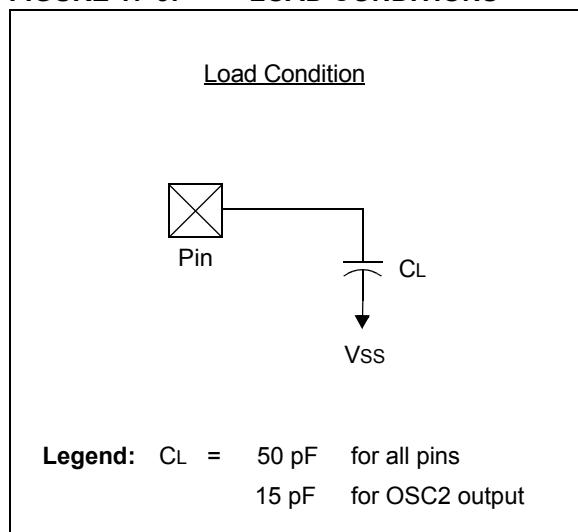
Lowercase letters (pp) and their meanings:

pp			
cc	CCP1	osc	OSC1
ck	CLKOUT	rd	<u>RD</u>
cs	<u>CS</u>	rw	<u>RD or WR</u>
di	SDI	sc	SCK
do	SDO	ss	<u>SS</u>
dt	Data in	t0	T0CKI
io	I/O PORT	t1	T1CKI
mc	<u>MCLR</u>	wr	<u>WR</u>

Uppercase letters and their meanings:

S		P	
F	Fall	P	Period
H	High	R	Rise
I	Invalid (High-impedance)	V	Valid
L	Low	Z	High-impedance

FIGURE 17-3: LOAD CONDITIONS



17.8 AC Characteristics: PIC16F883/884/886/887 (Industrial, Extended)

FIGURE 17-4: CLOCK TIMING

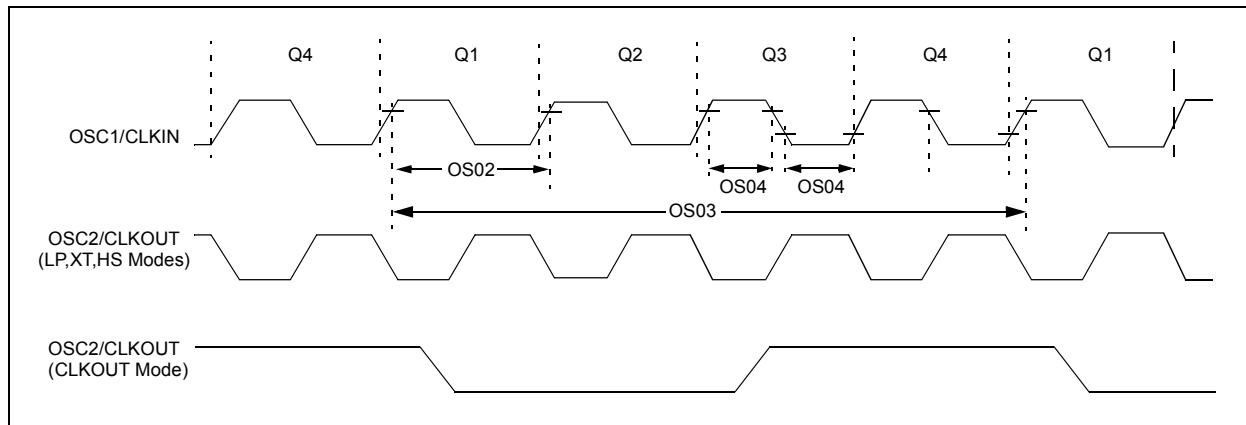


TABLE 17-1: CLOCK OSCILLATOR TIMING REQUIREMENTS

Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
OS01	FOSC	External CLKIN Frequency ⁽¹⁾	DC	—	37	kHz	LP Oscillator mode
			DC	—	4	MHz	XT Oscillator mode
			DC	—	20	MHz	HS Oscillator mode
			DC	—	20	MHz	EC Oscillator mode
		Oscillator Frequency ⁽¹⁾	—	32.768	—	kHz	LP Oscillator mode
			0.1	—	4	MHz	XT Oscillator mode
			1	—	20	MHz	HS Oscillator mode
			DC	—	4	MHz	RC Oscillator mode
OS02	TOSC	External CLKIN Period ⁽¹⁾	27	—	•	μs	LP Oscillator mode
			250	—	•	ns	XT Oscillator mode
			50	—	•	ns	HS Oscillator mode
			50	—	•	ns	EC Oscillator mode
		Oscillator Period ⁽¹⁾	—	30.5	—	μs	LP Oscillator mode
			250	—	10,000	ns	XT Oscillator mode
			50	—	1,000	ns	HS Oscillator mode
			250	—	—	ns	RC Oscillator mode
OS03	T _{CY}	Instruction Cycle Time ⁽¹⁾	200	T _{CY}	DC	ns	T _{CY} = 4/Fosc
OS04*	TosH, TosL	External CLKIN High, External CLKIN Low	2	—	—	μs	LP oscillator
			100	—	—	ns	XT oscillator
			20	—	—	ns	HS oscillator
OS05*	TosR, TosF	External CLKIN Rise, External CLKIN Fall	0	—	•	ns	LP oscillator
			0	—	•	ns	XT oscillator
			0	—	•	ns	HS oscillator

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Instruction cycle period (T_{CY}) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to OSC1 pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.

PIC16F882/883/884/886/887

TABLE 17-2: OSCILLATOR PARAMETERS

Standard Operating Conditions (unless otherwise stated)								
Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$								
Param No.	Sym.	Characteristic	Freq. Tolerance	Min.	Typ†	Max.	Units	Conditions
OS06	TWARM	Internal Oscillator Switch when running ⁽³⁾	—	—	—	2	Tosc	Slowest clock
OS07	Tsc	Fail-Safe Sample Clock Period ⁽¹⁾	—	—	21	—	ms	LFINTOSC/64
OS08	HFosc	Internal Calibrated HFINTOSC Frequency ⁽²⁾	$\pm 1\%$ $\pm 2\%$ $\pm 5\%$	7.92 7.84 7.60	8.0 8.0 8.0	8.08 8.16 8.40	MHz MHz MHz	$\text{VDD} = 3.5\text{V}, 25^{\circ}\text{C}$ $2.5\text{V} \leq \text{VDD} \leq 5.5\text{V}, 0^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C}$ $2.0\text{V} \leq \text{VDD} \leq 5.5\text{V}, -40^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C} (\text{Ind.}), -40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C} (\text{Ext.})$
OS09*	LFosc	Internal Uncalibrated LFINTOSC Frequency	—	15	31	45	kHz	
OS10*	Tiosc ST	HFINTOSC Oscillator Wake-up from Sleep Start-up Time	—	5.5	12	24	μs	$\text{VDD} = 2.0\text{V}, -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$
			—	3.5	7	14		$\text{VDD} = 3.0\text{V}, -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$
			—	3	6	11		$\text{VDD} = 5.0\text{V}, -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}$

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** Instruction cycle period (TCY) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to the OSC1 pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.
- 2:** To ensure these oscillator frequency tolerances, VDD and VSS must be capacitively decoupled as close to the device as possible. 0.1 μF and 0.01 μF values in parallel are recommended.
- 3:** By design.

FIGURE 17-5: CLKOUT AND I/O TIMING

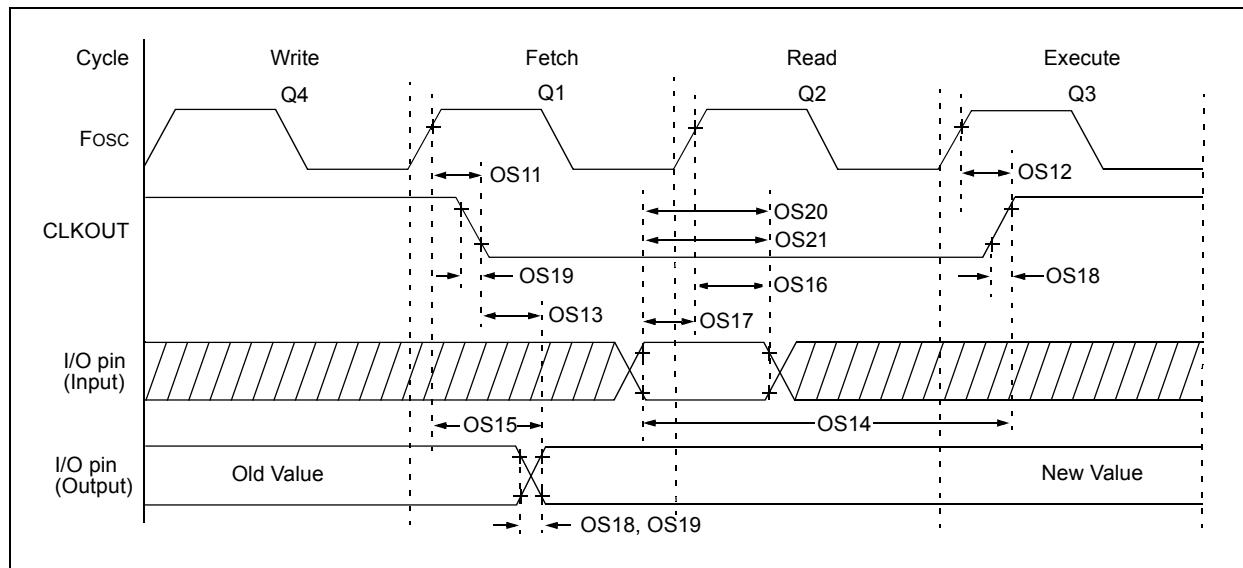


TABLE 17-3: CLKOUT AND I/O TIMING PARAMETERS

Standard Operating Conditions (unless otherwise stated)							
Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
OS11	TosH2ckL	Fosc \uparrow to CLKOUT \downarrow (1)	—	—	70	ns	VDD = 5.0V
OS12	TosH2ckH	Fosc \uparrow to CLKOUT \uparrow (1)	—	—	72	ns	VDD = 5.0V
OS13	TckL2ioV	CLKOUT \downarrow to Port out valid (1)	—	—	20	ns	
OS14	TioV2ckH	Port input valid before CLKOUT \uparrow (1)	Tosc + 200 ns	—	—	ns	
OS15*	TosH2ioV	Fosc \uparrow (Q1 cycle) to Port out valid	—	50	70	ns	VDD = 5.0V
OS16	TosH2iol	Fosc \uparrow (Q2 cycle) to Port input invalid (I/O in hold time)	50	—	—	ns	VDD = 5.0V
OS17	TioV2osh	Port input valid to Fosc \uparrow (Q2 cycle) (I/O in setup time)	20	—	—	ns	
OS18	TioR	Port output rise time (2)	—	15 40	72 32	ns	VDD = 2.0V VDD = 5.0V
OS19	TioF	Port output fall time (2)	—	28 15	55 30	ns	VDD = 2.0V VDD = 5.0V
OS20*	TinP	INT pin input high or low time	25	—	—	ns	
OS21*	TRAP	PORTA interrupt-on-change new input level time	TCY	—	—	ns	

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5.0V, 25°C unless otherwise stated.

Note 1: Measurements are taken in RC mode where CLKOUT output is 4 x Tosc.

2: Includes OSC2 in CLKOUT mode.

PIC16F882/883/884/886/887

FIGURE 17-6: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING

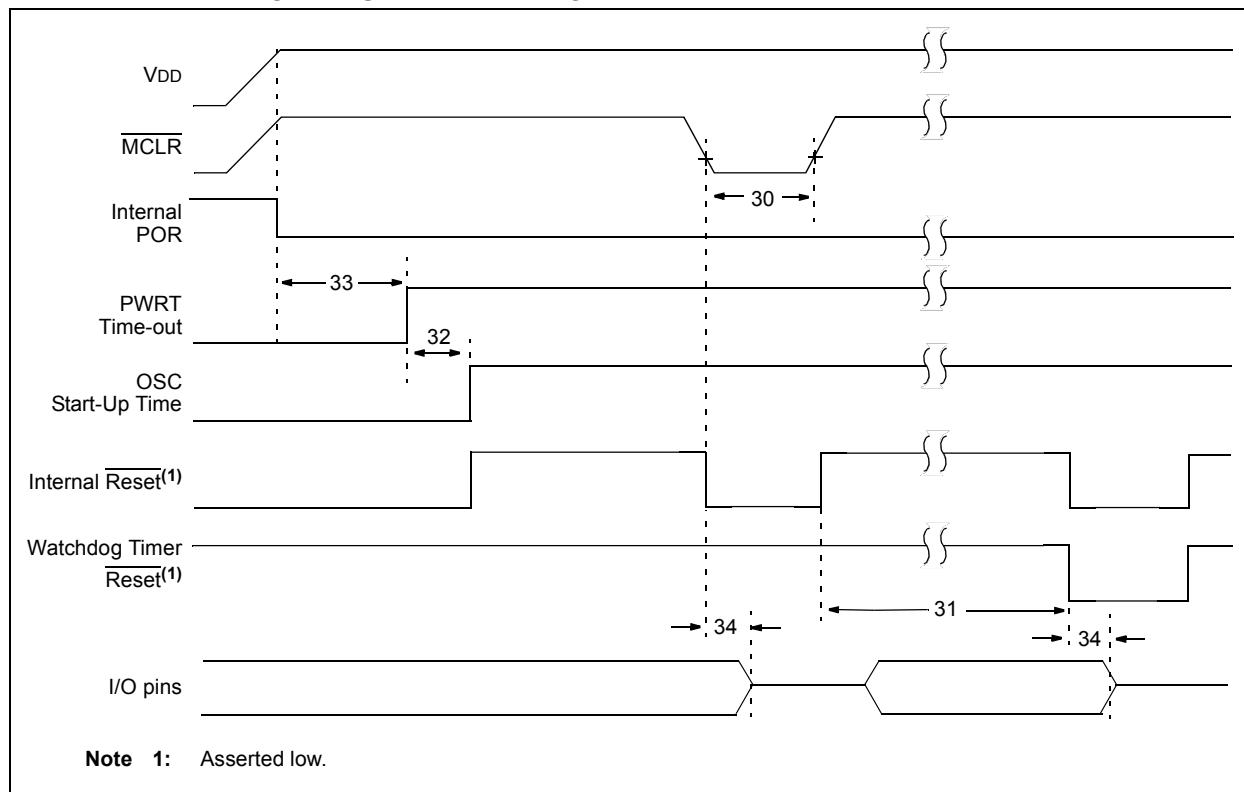
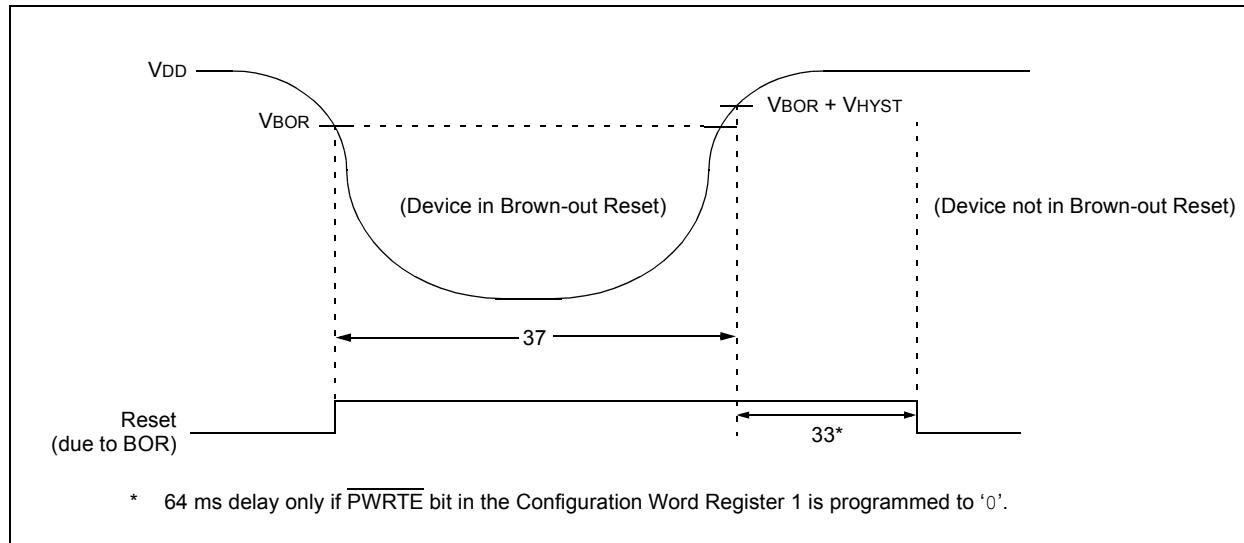


FIGURE 17-7: BROWN-OUT RESET TIMING AND CHARACTERISTICS



PIC16F882/883/884/886/887

TABLE 17-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER AND BROWN-OUT RESET PARAMETERS

Standard Operating Conditions (unless otherwise stated)							
Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typt	Max.	Units	Conditions
30	TMCL	MCLR Pulse Width (low)	2 5	— —	— —	μs μs	VDD = 5V, -40°C to $+85^{\circ}\text{C}$ VDD = 5V
31	TWDT	Watchdog Timer Time-out Period (No Prescaler)	10 10	16 16	29 31	ms ms	VDD = 5V, -40°C to $+85^{\circ}\text{C}$ VDD = 5V
32	TOST	Oscillation Start-up Timer Period ^(1, 2)	—	1024	—	TOSC	(NOTE 3)
33*	TPWRT	Power-up Timer Period	40	65	140	ms	
34*	TIOZ	I/O High-impedance from MCLR Low or Watchdog Timer Reset	—	—	2.0	μs	
35	VBOR	Brown-out Reset Voltage	2.0	—	2.2	V	BOR4V bit = 0 (NOTE 4)
			3.6	4.0	4.4	V	BOR4V bit = 1, -40°C to $+85^{\circ}\text{C}$ (NOTE 4)
			3.6	4.0	4.5	V	BOR4V bit = 1, -40°C to $+125^{\circ}\text{C}$ (NOTE 4)
36*	VHYST	Brown-out Reset Hysteresis	—	50	—	mV	
37*	TBOR	Brown-out Reset Minimum Detection Period	100	—	—	μs	VDD \leq VBOR

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Instruction cycle period (TCY) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at “min” values with an external clock applied to the OSC1 pin. When an external clock input is used, the “max” cycle time limit is “DC” (no clock) for all devices.

2: By design.

3: Period of the slower clock.

4: To ensure these voltage tolerances, VDD and Vss must be capacitively decoupled as close to the device as possible. 0.1 μF and 0.01 μF values in parallel are recommended.

PIC16F882/883/884/886/887

FIGURE 17-8: TIMER0 AND TIMER1 EXTERNAL CLOCK TIMINGS

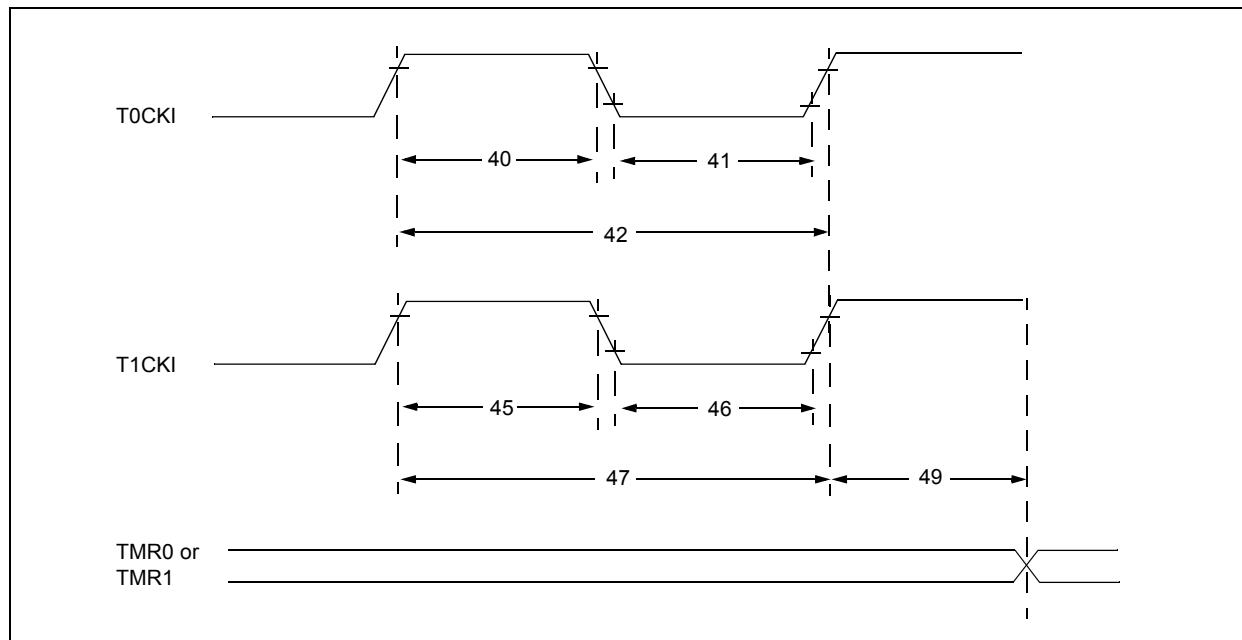


TABLE 17-5: TIMER0 AND TIMER1 EXTERNAL CLOCK REQUIREMENTS

Standard Operating Conditions (unless otherwise stated) Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$								
Param No.	Sym.	Characteristic		Min.	Typ†	Max.	Units	Conditions
40*	TT0H	T0CKI High Pulse Width	No Prescaler	0.5 TCY + 20	—	—	ns	
			With Prescaler	10	—	—	ns	
41*	TT0L	T0CKI Low Pulse Width	No Prescaler	0.5 TCY + 20	—	—	ns	
			With Prescaler	10	—	—	ns	
42*	TT0P	T0CKI Period		Greater of: 20 or $\frac{\text{TCY} + 40}{\text{N}}$	—	—	ns	N = prescale value (2, 4, ..., 256)
45*	TT1H	T1CKI High Time	Synchronous, No Prescaler	0.5 TCY + 20	—	—	ns	
			Synchronous, with Prescaler	15	—	—	ns	
			Asynchronous	30	—	—	ns	
46*	TT1L	T1CKI Low Time	Synchronous, No Prescaler	0.5 TCY + 20	—	—	ns	
			Synchronous, with Prescaler	15	—	—	ns	
			Asynchronous	30	—	—	ns	
47*	TT1P	T1CKI Input Period	Synchronous	Greater of: 30 or $\frac{\text{TCY} + 40}{\text{N}}$	—	—	ns	N = prescale value (1, 2, 4, 8)
			Asynchronous	60	—	—	ns	
48	FT1	Timer1 Oscillator Input Frequency Range (oscillator enabled by setting bit T1OSCEN)		—	32.768	—	kHz	
49*	TCKEZTMR1	Delay from External Clock Edge to Timer Increment		2 Tosc	—	7 Tosc	—	Timers in Sync mode

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 17-9: CAPTURE/COMPARE/PWM TIMINGS (ECCP)

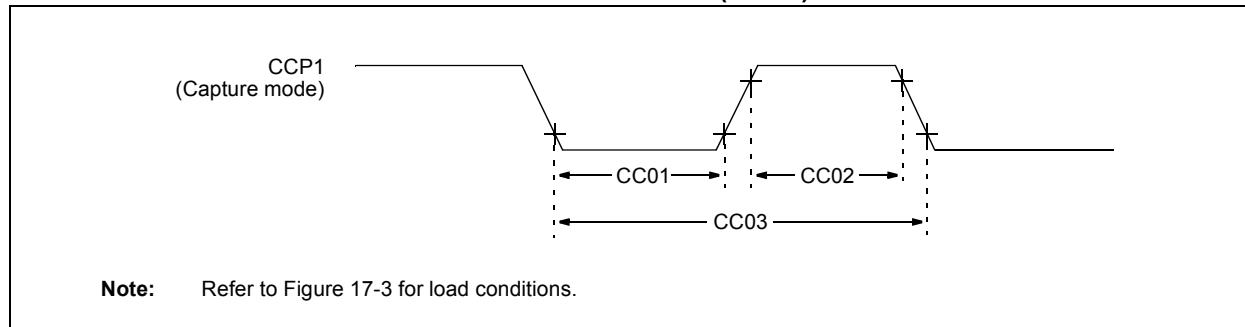


TABLE 17-6: CAPTURE/COMPARE/PWM REQUIREMENTS (ECCP)

Standard Operating Conditions (unless otherwise stated) Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$								
Param No.	Sym.	Characteristic		Min.	Typ†	Max.	Units	Conditions
CC01*	TccL	CCP1 Input Low Time	No Prescaler	$0.5\text{TCY} + 20$	—	—	ns	
			With Prescaler	20	—	—	ns	
CC02*	TccH	CCP1 Input High Time	No Prescaler	$0.5\text{TCY} + 20$	—	—	ns	
			With Prescaler	20	—	—	ns	
CC03*	TccP	CCP1 Input Period		$\frac{3\text{TCY} + 40}{N}$	—	—	ns	N = prescale value (1, 4 or 16)

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

PIC16F882/883/884/886/887

TABLE 17-7: COMPARATOR SPECIFICATIONS

Standard Operating Conditions (unless otherwise stated) Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$								
Param No.	Sym.	Characteristics		Min.	Typ†	Max.	Units	Comments
CM01	Vos	Input Offset Voltage		—	± 5.0	± 10	mV	(VDD - 1.5)/2
CM02	VCM	Input Common Mode Voltage		0	—	VDD - 1.5	V	
CM03*	CMRR	Common Mode Rejection Ratio		+55	—	—	dB	
CM04*	TRT	Response Time	Falling	—	150	600	ns	(NOTE 1)
			Rising	—	200	1000	ns	
CM05*	TMC2coV	Comparator Mode Change to Output Valid		—	—	10	μs	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Response time is measured with one comparator input at (VDD - 1.5)/2 - 100 mV to (VDD - 1.5)/2 + 20 mV.

TABLE 17-8: COMPARATOR VOLTAGE REFERENCE (CVREF) SPECIFICATIONS

Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristics	Min.	Typ†	Max.	Units	Comments
CV01*	CLSB	Step Size ⁽²⁾	— —	VDD/24 VDD/32	— —	V V	Low Range (VRR = 1) High Range (VRR = 0)
CV02*	CACC	Absolute Accuracy	— —	— —	$\pm 1/2$ $\pm 1/2$	LSb LSb	Low Range (VRR = 1) High Range (VRR = 0)
CV03*	CR	Unit Resistor Value (R)	—	2k	—	Ω	
CV04*	CST	Settling Time ⁽¹⁾	—	—	10	μs	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Settling time measured while VRR = 1 and VR<3:0> transitions from '0000' to '1111'.

2: See Section 8.10 "Comparator Voltage Reference" for more information.

TABLE 17-9: VOLTAGE (VR) REFERENCE SPECIFICATIONS

VR Voltage Reference Specifications			Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$				
Param No.	Symbol	Characteristics	Min.	Typ.	Max.	Units	Comments
VR01	VROUT	VR voltage output	0.5	0.6	0.7	V	
VR02*	TSTABLE	Settling Time	—	10	100*	μs	

* These parameters are characterized but not tested.

PIC16F882/883/884/886/887

TABLE 17-10: PIC16F883/884/886/887 A/D CONVERTER (ADC) CHARACTERISTICS

Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
AD01	NR	Resolution	—	—	10 bits	bit	
AD02	EIL	Integral Error	—	—	± 1	LSb	$\text{VREF} = 5.12\text{V}$
AD03	EDL	Differential Error	—	—	± 1	LSb	No missing codes to 10 bits $\text{VREF} = 5.12\text{V}$
AD04	Eoff	Offset Error	0	+1.5	+3.0	LSb	$\text{VREF} = 5.12\text{V}$
AD07	EGN	Gain Error	—	—	± 1	LSb	$\text{VREF} = 5.12\text{V}$
AD06	VREF	Reference Voltage ⁽³⁾	2.2	—	—	V	Absolute minimum to ensure 1 LSb accuracy
AD06A			2.7	—	VDD		
AD07	VAIN	Full-Scale Range	Vss	—	VREF	V	
AD08	ZAIN	Recommended Impedance of Analog Voltage Source	—	—	10	kΩ	
AD09*	IREF	VREF Input Current ⁽³⁾	10	—	1000	μA	During VAIN acquisition. Based on differential of VHOLD to VAIN.
			—	—	50	μA	During A/D conversion cycle.

* These parameters are characterized but not tested.

† Data in “Typ” column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Total Absolute Error includes integral, differential, offset and gain errors.

2: The A/D conversion result never decreases with an increase in the input voltage and has no missing codes.

3: ADC VREF is from external VREF or VDD pin, whichever is selected as reference input.

4: When ADC is off, it will not consume any current other than leakage current. The power-down current specification includes any such leakage from the ADC module.

PIC16F882/883/884/886/887

TABLE 17-11: PIC16F883/884/886/887 A/D CONVERSION REQUIREMENTS

Standard Operating Conditions (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
AD130*	TAD	A/D Clock Period	1.6	—	9.0	μs	Tosc-based, VREF $\geq 3.0\text{V}$
			3.0	—	9.0	μs	Tosc-based, VREF full range
AD130*		A/D Internal RC Oscillator Period	3.0	6.0	9.0	μs	ADCS<1:0> = 11 (ADRC mode)
			1.6	4.0	6.0	μs	At VDD = 2.5V
AD131	TCNV	Conversion Time (not including Acquisition Time) ⁽¹⁾	—	11	—	TAD	Set GO/DONE bit to new data in A/D Result register
AD132*	TACQ	Acquisition Time		11.5	—	μs	
AD133*	TAMP	Amplifier Settling Time	—	—	5	μs	
AD134	TGO	Q4 to A/D Clock Start	—	Tosc/2	—	—	If the A/D clock source is selected as RC, a time of TCY is added before the A/D clock starts. This allows the SLEEP instruction to be executed.
			—	Tosc/2 + TCY	—	—	

* These parameters are characterized but not tested.

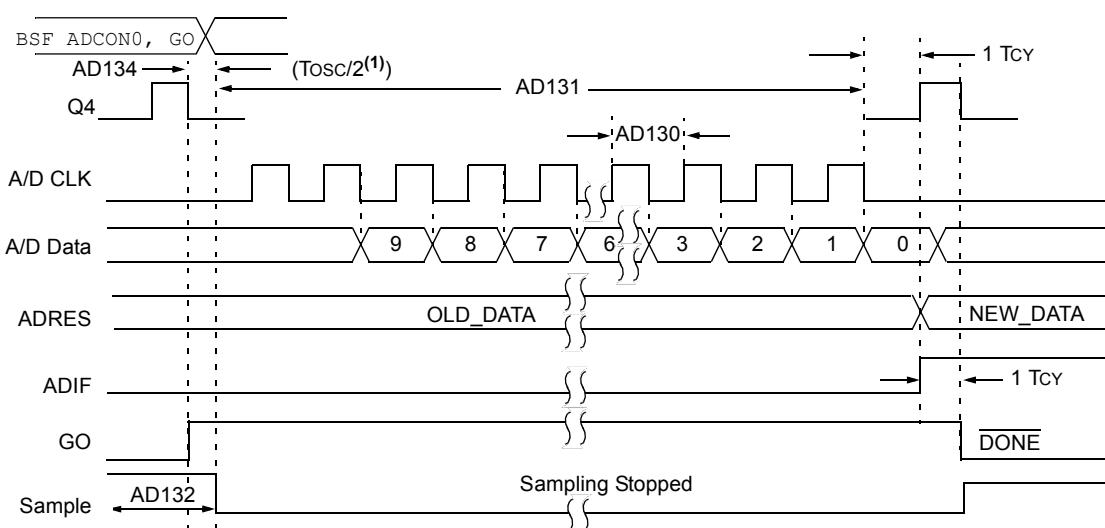
† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: ADRESH and ADRESL registers may be read on the following TCY cycle.

2: See **Section 9.3 “A/D Acquisition Requirements”** for minimum conditions.

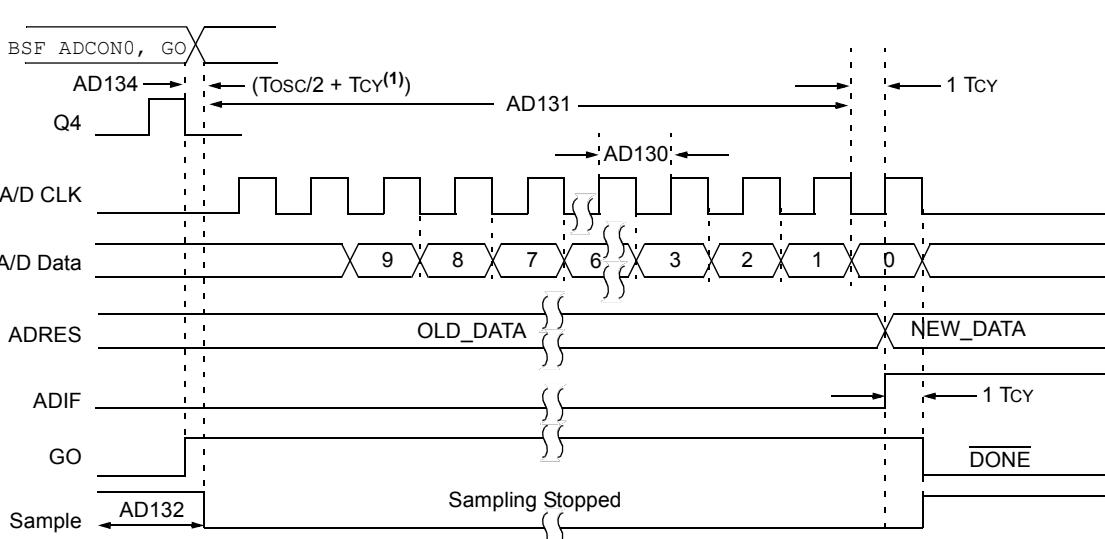
PIC16F882/883/884/886/887

FIGURE 17-10: PIC16F883/884/886/887 A/D CONVERSION TIMING (NORMAL MODE)



Note 1: If the A/D clock source is selected as RC, a time of TCY is added before the A/D clock starts. This allows the SLEEP instruction to be executed.

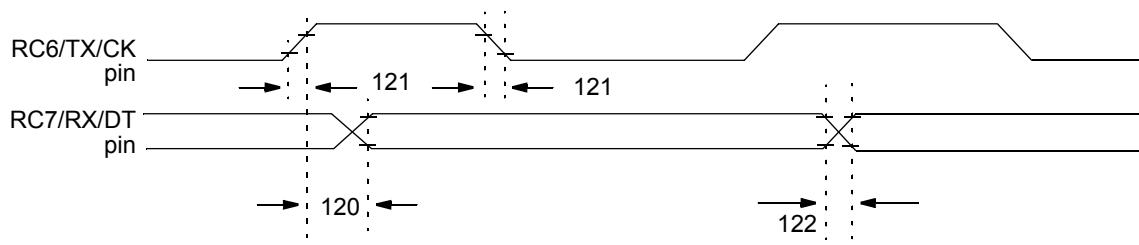
FIGURE 17-11: PIC16F883/884/886/887 A/D CONVERSION TIMING (SLEEP MODE)



Note 1: If the A/D clock source is selected as RC, a time of TCY is added before the A/D clock starts. This allows the SLEEP instruction to be executed.

PIC16F882/883/884/886/887

FIGURE 17-12: EUSART SYNCHRONOUS TRANSMISSION (MASTER/SLAVE) TIMING

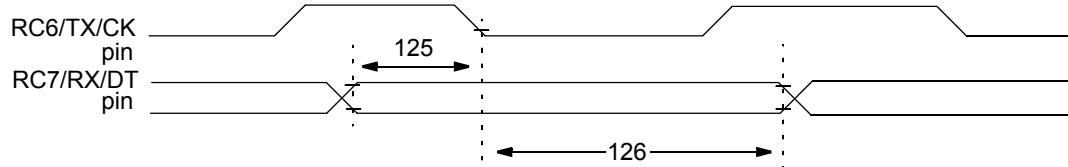


Note: Refer to Figure 17-3 for load conditions.

TABLE 17-12: EUSART SYNCHRONOUS TRANSMISSION REQUIREMENTS

Standard Operating Conditions (unless otherwise stated)						
Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$						
Param. No.	Symbol	Characteristic	Min.	Max.	Units	Conditions
120	TckH2DTV	SYNC XMIT (Master & Slave) Clock high to data-out valid	—	40	ns	
121	TCKRF	Clock out rise time and fall time (Master mode)	—	20	ns	
122	TDTRF	Data-out rise time and fall time	—	20	ns	

FIGURE 17-13: EUSART SYNCHRONOUS RECEIVE (MASTER/SLAVE) TIMING



Note: Refer to Figure 17-3 for load conditions.

TABLE 17-13: EUSART SYNCHRONOUS RECEIVE REQUIREMENTS

Standard Operating Conditions (unless otherwise stated)						
Operating Temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$						
Param. No.	Symbol	Characteristic	Min.	Max.	Units	Conditions
125	TDTV2CKL	SYNC RCV (Master & Slave) Data-hold before CK ↓ (DT hold time)	10	—	ns	
126	TckL2DTL	Data-hold after CK ↓ (DT hold time)	15	—	ns	

FIGURE 17-14: SPI MASTER MODE TIMING (CKE = 0, SMP = 0)

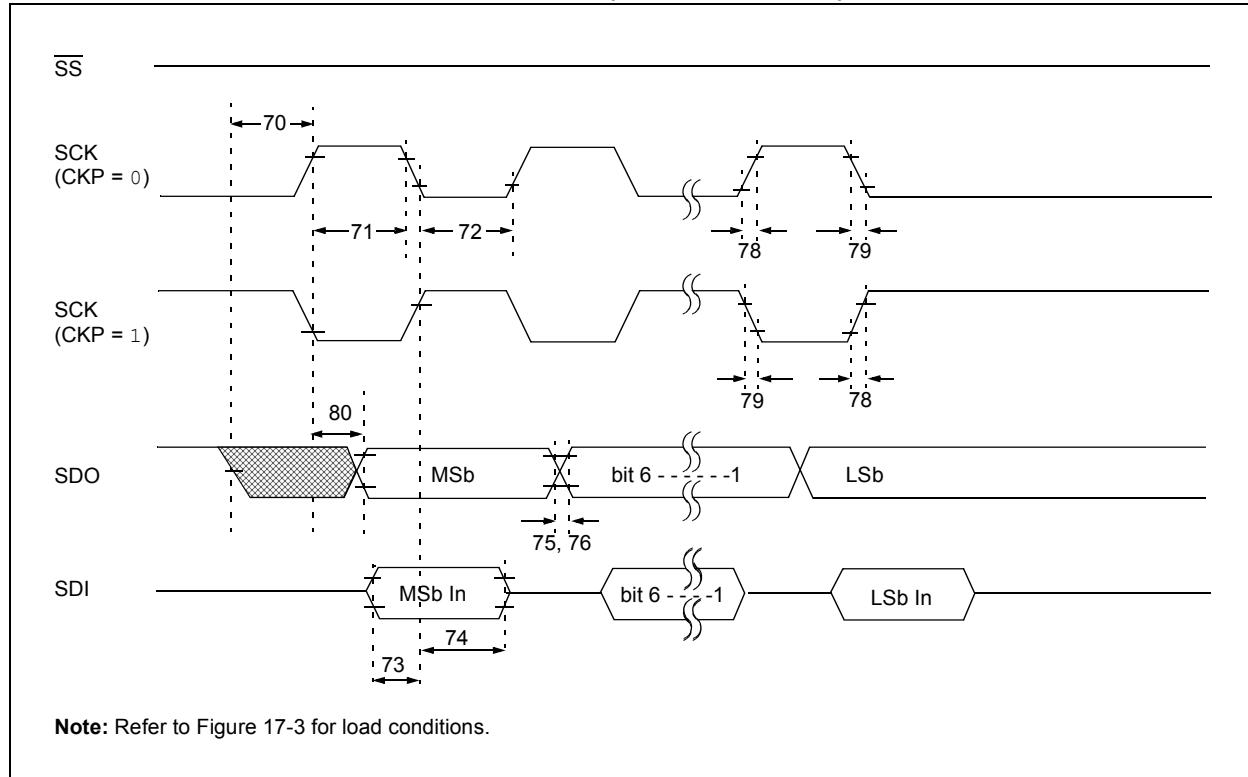
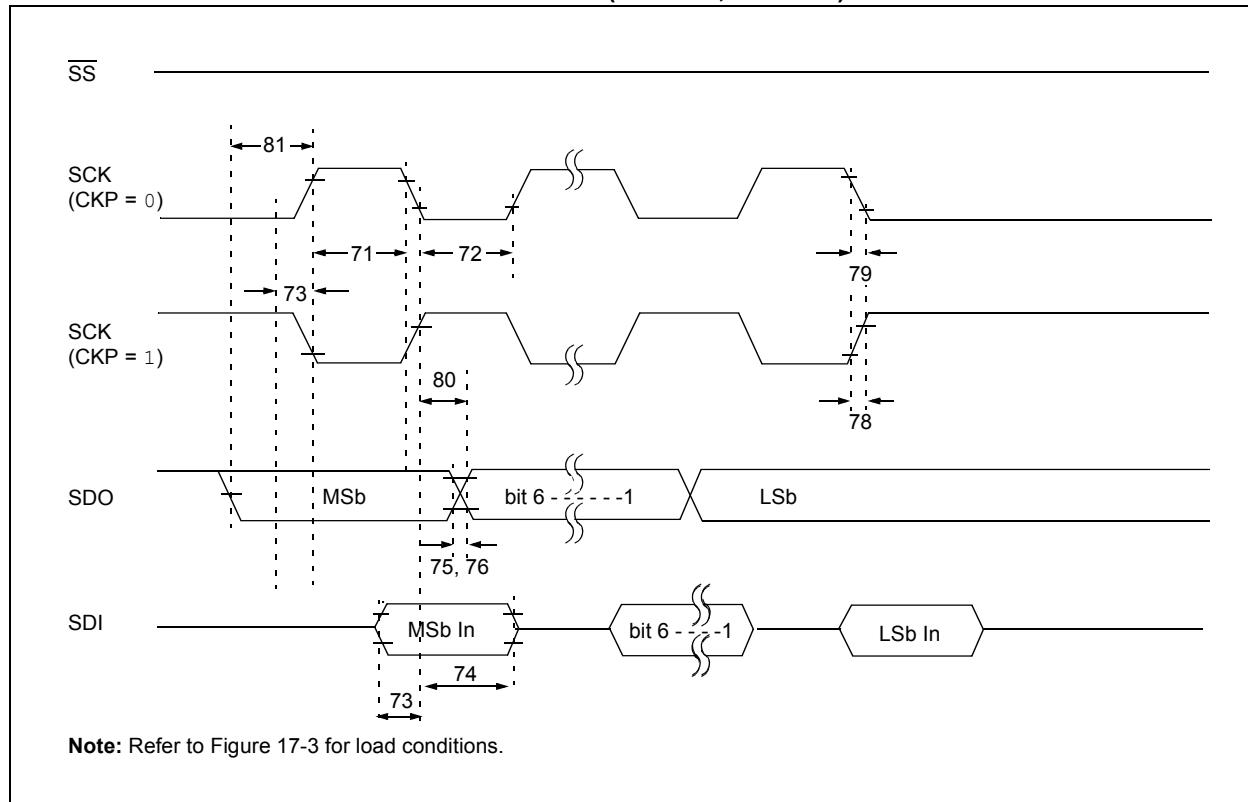


FIGURE 17-15: SPI MASTER MODE TIMING (CKE = 1, SMP = 1)



PIC16F882/883/884/886/887

FIGURE 17-16: SPI SLAVE MODE TIMING (CKE = 0)

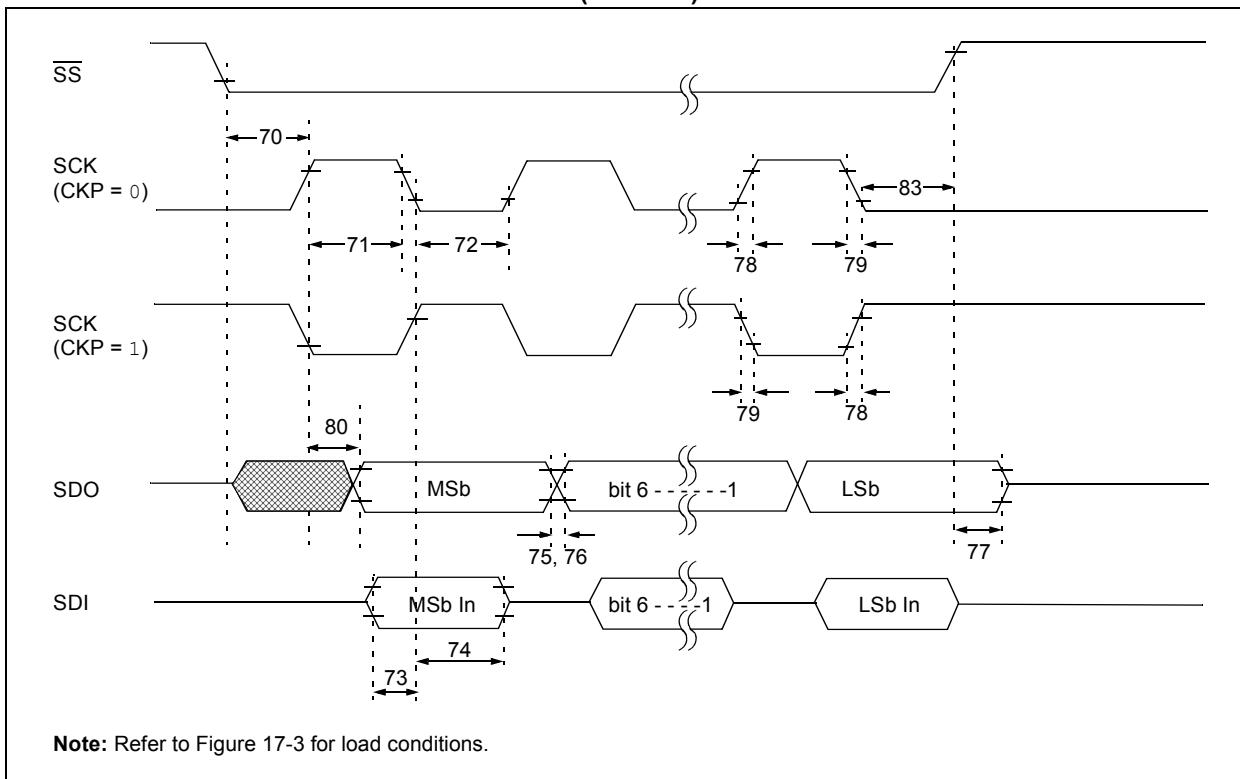


FIGURE 17-17: SPI SLAVE MODE TIMING (CKE = 1)

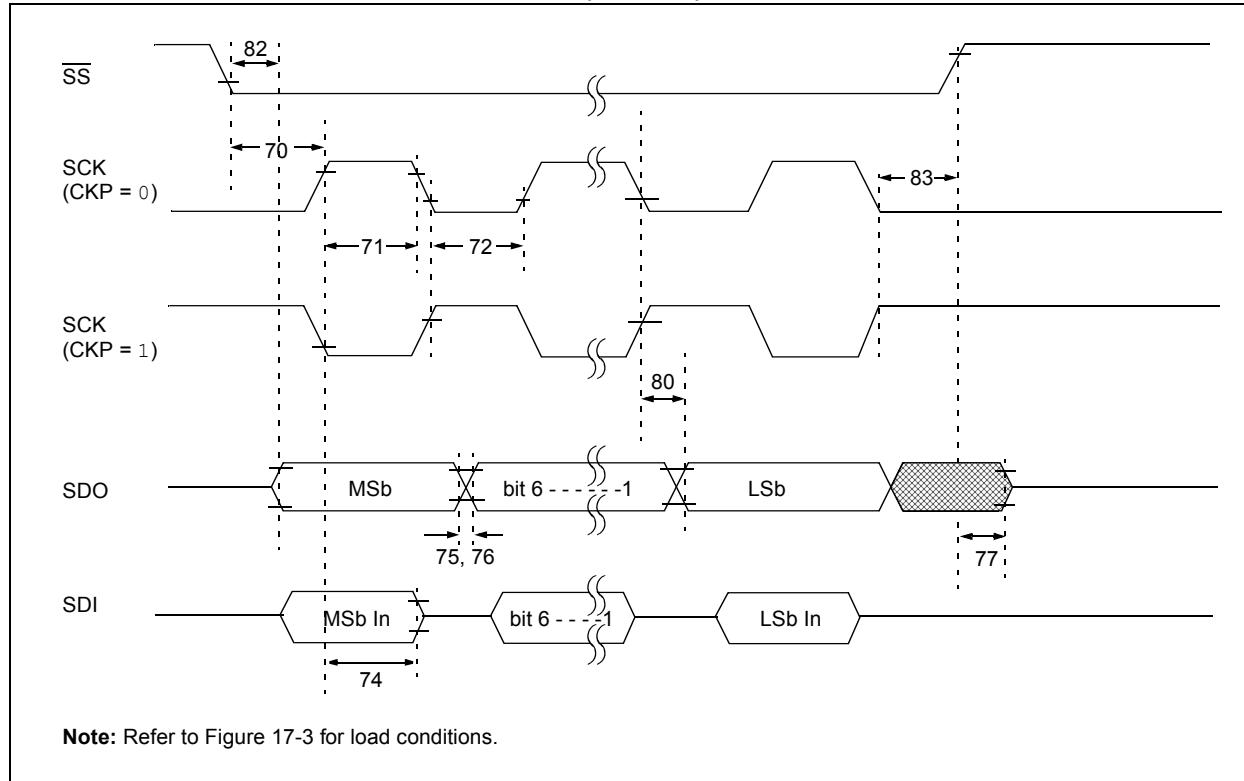


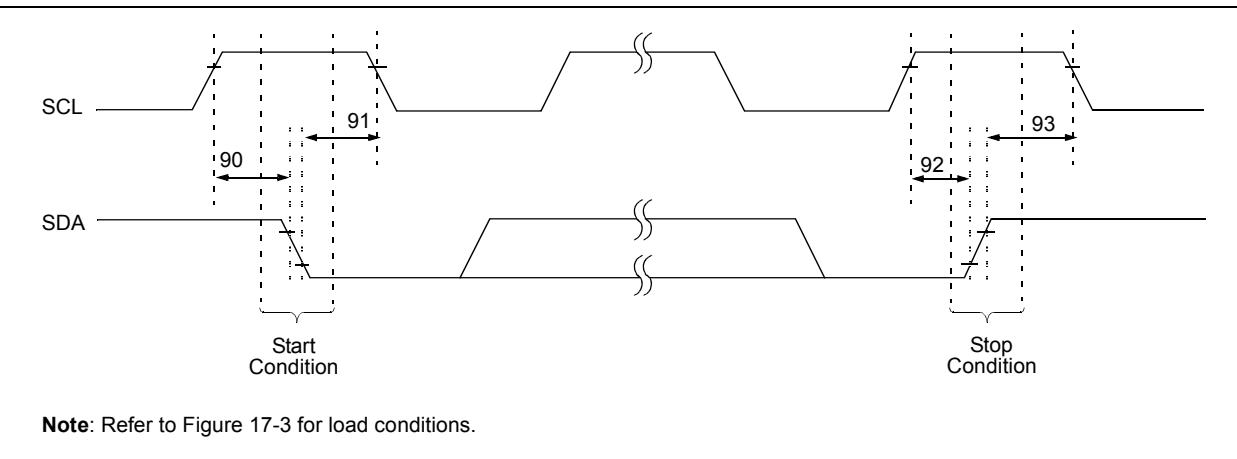
TABLE 17-14: SPI MODE REQUIREMENTS

Param No.	Symbol	Characteristic		Min.	Typ†	Max.	Units	Conditions
70*	TssL2sch, TssL2scl	\overline{SS} ↓ to SCK↓ or SCK↑ input		TCY	—	—	ns	
71*	TscH	SCK input high time (Slave mode)		TCY + 20	—	—	ns	
72*	TscL	SCK input low time (Slave mode)		TCY + 20	—	—	ns	
73*	TdIV2sch, TdIV2scl	Setup time of SDI data input to SCK edge		100	—	—	ns	
74*	Tsch2dil, Tscl2dil	Hold time of SDI data input to SCK edge		100	—	—	ns	
75*	TdoR	SDO data output rise time	3.0-5.5V	—	10	25	ns	
			2.0-5.5V	—	25	50	ns	
76*	TdoF	SDO data output fall time		—	10	25	ns	
77*	Tssh2doz	\overline{SS} ↑ to SDO output high-impedance		10	—	50	ns	
78*	TscR	SCK output rise time (Master mode)	3.0-5.5V	—	10	25	ns	
			2.0-5.5V	—	25	50	ns	
79*	TscF	SCK output fall time (Master mode)		—	10	25	ns	
80*	Tsch2dov, Tscl2dov	SDO data output valid after SCK edge	3.0-5.5V	—	—	50	ns	
			2.0-5.5V	—	—	145	ns	
81*	Tdov2sch, Tdov2scl	SDO data output setup to SCK edge		Tcy	—	—	ns	
82*	Tssl2dov	SDO data output valid after \overline{SS} ↓ edge		—	—	50	ns	
83*	Tsch2ssh, Tscl2ssh	\overline{SS} ↑ after SCK edge		1.5TCY + 40	—	—	ns	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

FIGURE 17-18: I²C™ BUS START/STOP BITS TIMING



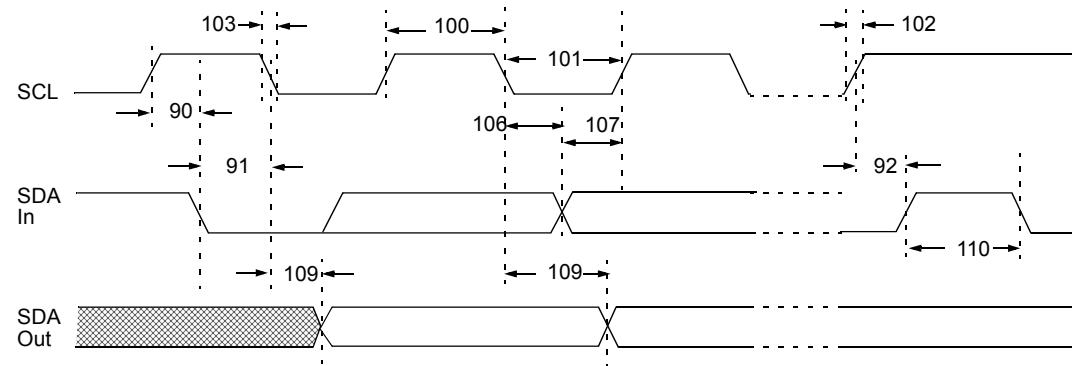
PIC16F882/883/884/886/887

TABLE 17-15: I²C™ BUS START/STOP BITS REQUIREMENTS

Param No.	Symbol	Characteristic		Min.	Typ.	Max.	Units	Conditions
90*	TsU:STA	Start condition	100 kHz mode	4700	—	—	ns	Only relevant for Repeated Start condition
		Setup time	400 kHz mode	600	—	—		
91*	THD:STA	Start condition	100 kHz mode	4000	—	—	ns	After this period, the first clock pulse is generated
		Hold time	400 kHz mode	600	—	—		
92*	TsU:STO	Stop condition	100 kHz mode	4700	—	—	ns	
		Setup time	400 kHz mode	600	—	—		
93	THD:STO	Stop condition	100 kHz mode	4000	—	—	ns	
		Hold time	400 kHz mode	600	—	—		

* These parameters are characterized but not tested.

FIGURE 17-19: I²C™ BUS DATA TIMING



Note: Refer to Figure 17-3 for load conditions.

TABLE 17-16: I²C™ BUS DATA REQUIREMENTS

Param. No.	Symbol	Characteristic		Min.	Max.	Units	Conditions
100*	THIGH	Clock high time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	—	μs	Device must operate at a minimum of 10 MHz
			SSP Module	1.5TCY	—		
101*	TLOW	Clock low time	100 kHz mode	4.7	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	1.3	—	μs	Device must operate at a minimum of 10 MHz
			SSP Module	1.5TCY	—		
102*	TR	SDA and SCL rise time	100 kHz mode	—	1000	ns	
			400 kHz mode	20 + 0.1CB	300	ns	CB is specified to be from 10-400 pF
103*	TF	SDA and SCL fall time	100 kHz mode	—	300	ns	
			400 kHz mode	20 + 0.1CB	300	ns	CB is specified to be from 10-400 pF
90*	TSU:STA	Start condition setup time	100 kHz mode	4.7	—	μs	Only relevant for Repeated Start condition
			400 kHz mode	0.6	—	μs	
91*	THD:STA	Start condition hold time	100 kHz mode	4.0	—	μs	After this period the first clock pulse is generated
			400 kHz mode	0.6	—	μs	
106*	THD:DAT	Data input hold time	100 kHz mode	0	—	ns	
			400 kHz mode	0	0.9	μs	
107*	TSU:DAT	Data input setup time	100 kHz mode	250	—	ns	(Note 2)
			400 kHz mode	100	—	ns	
92*	TSU:STO	Stop condition setup time	100 kHz mode	4.7	—	μs	
			400 kHz mode	0.6	—	μs	
109*	TAA	Output valid from clock	100 kHz mode	—	3500	ns	(Note 1)
			400 kHz mode	—	—	ns	
110*	TBUF	Bus free time	100 kHz mode	4.7	—	μs	Time the bus must be free before a new transmission can start
			400 kHz mode	1.3	—	μs	
	CB	Bus capacitive loading		—	400	pF	

* These parameters are characterized but not tested.

Note 1: As a transmitter, the device must provide this internal minimum delay time to bridge the undefined region (min. 300 ns) of the falling edge of SCL to avoid unintended generation of Start or Stop conditions.

2: A Fast mode (400 kHz) I²C bus device can be used in a Standard mode (100 kHz) I²C bus system, but the requirement $TSU:DAT \geq 250$ ns must then be met. This will automatically be the case if the device does not stretch the low period of the SCL signal. If such a device does stretch the low period of the SCL signal, it must output the next data bit to the SDA line TR max. + $TSU:DAT = 1000 + 250 = 1250$ ns (according to the Standard mode I²C bus specification), before the SCL line is released.

PIC16F882/883/884/886/887

NOTES:

18.0 DC AND AC CHARACTERISTICS GRAPHS AND TABLES

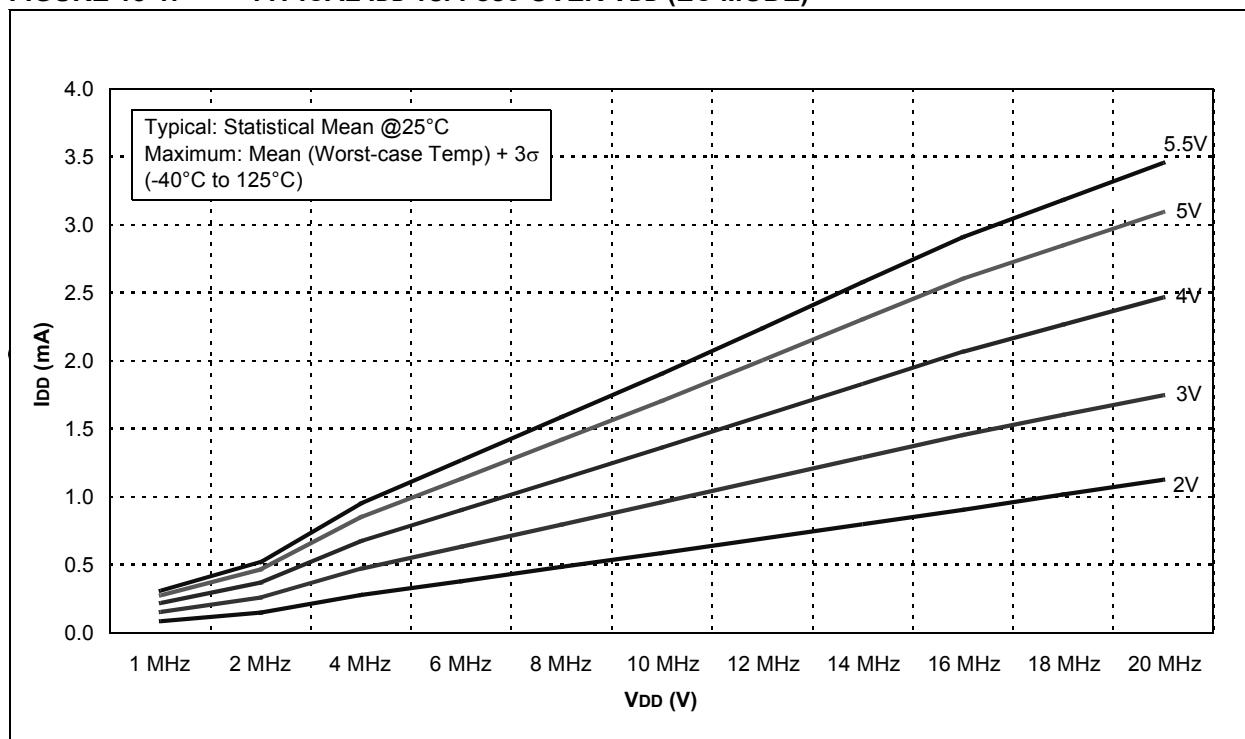
The graphs and tables provided in this section are for **design guidance** and are **not tested**.

In some graphs or tables, the data presented are **outside specified operating range** (i.e., outside specified V_{DD} range). This is for **information only** and devices are ensured to operate properly only within the specified range.

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore, outside the warranted range.

“Typical” represents the mean of the distribution at 25°C. “Maximum” or “minimum” represents (mean + 3 σ) or (mean - 3 σ) respectively, where σ is a standard deviation, over each temperature range.

FIGURE 18-1: TYPICAL I_{DD} vs. Fosc OVER V_{DD} (EC MODE)



PIC16F882/883/884/886/887

FIGURE 18-2: MAXIMUM IDD vs. FOSC OVER VDD (EC MODE)

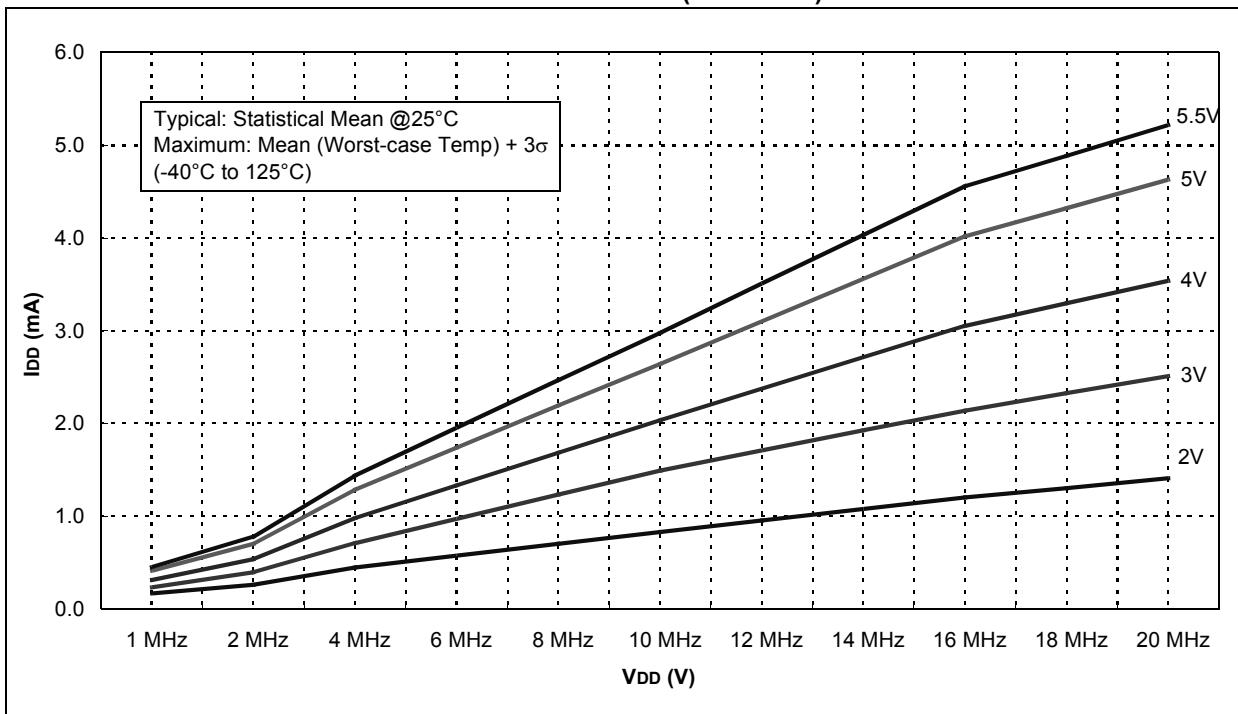
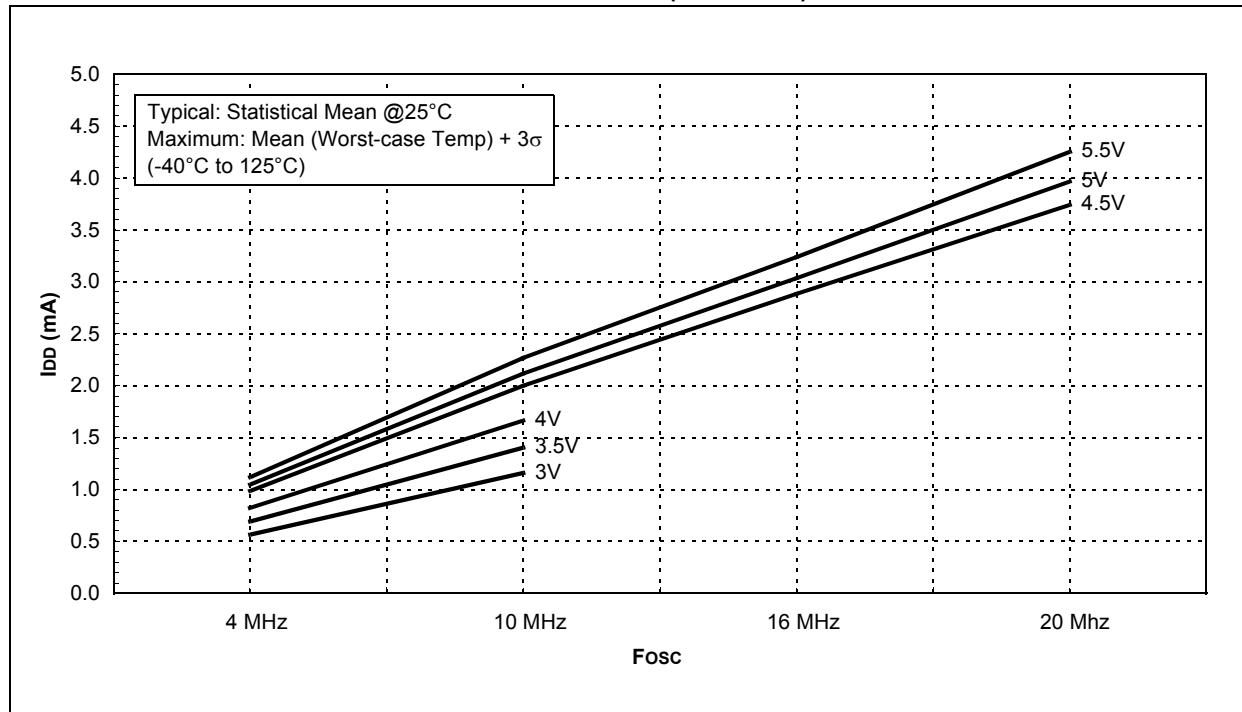


FIGURE 18-3: TYPICAL IDD vs. FOSC OVER VDD (HS MODE)



PIC16F882/883/884/886/887

FIGURE 18-4: MAXIMUM IDD vs. Fosc OVER VDD (HS MODE)

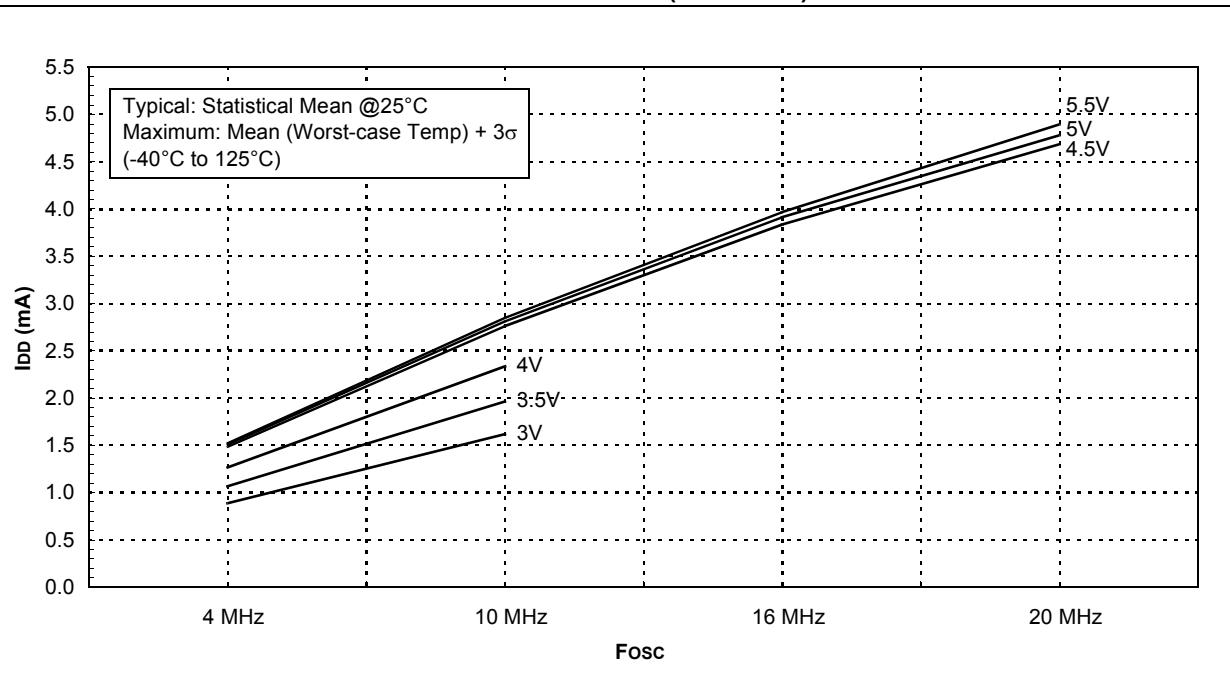
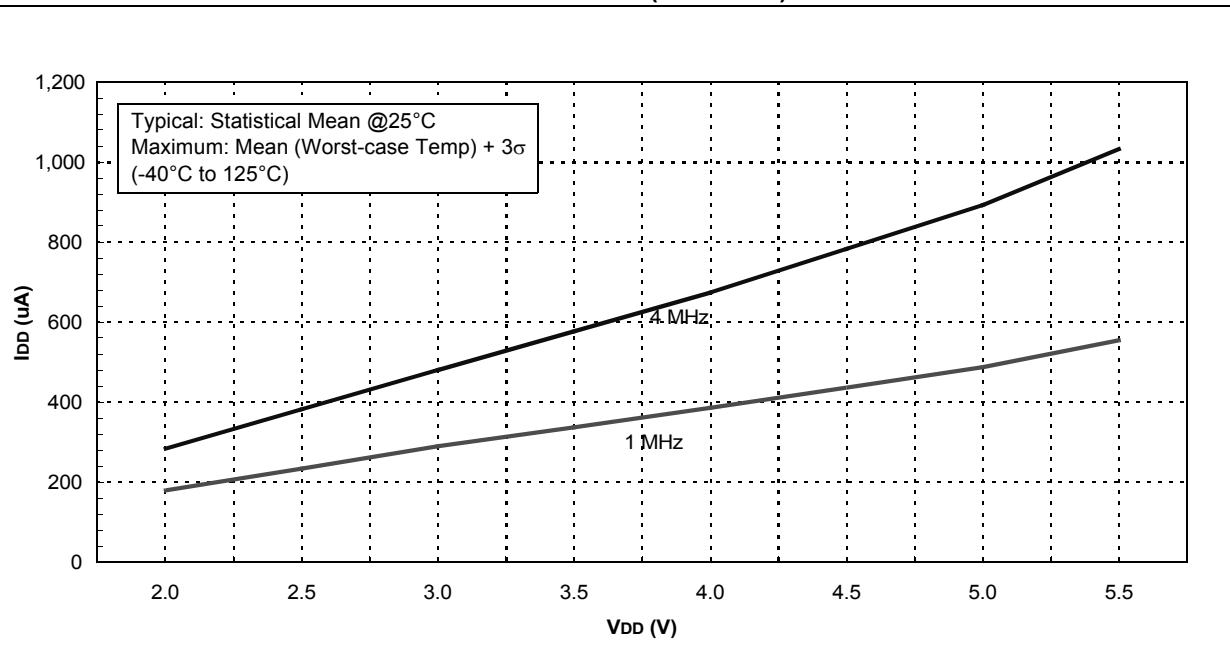


FIGURE 18-5: TYPICAL IDD vs. VDD OVER Fosc (XT MODE)



PIC16F882/883/884/886/887

FIGURE 18-6: MAXIMUM IDD VS. VDD OVER Fosc (XT MODE)

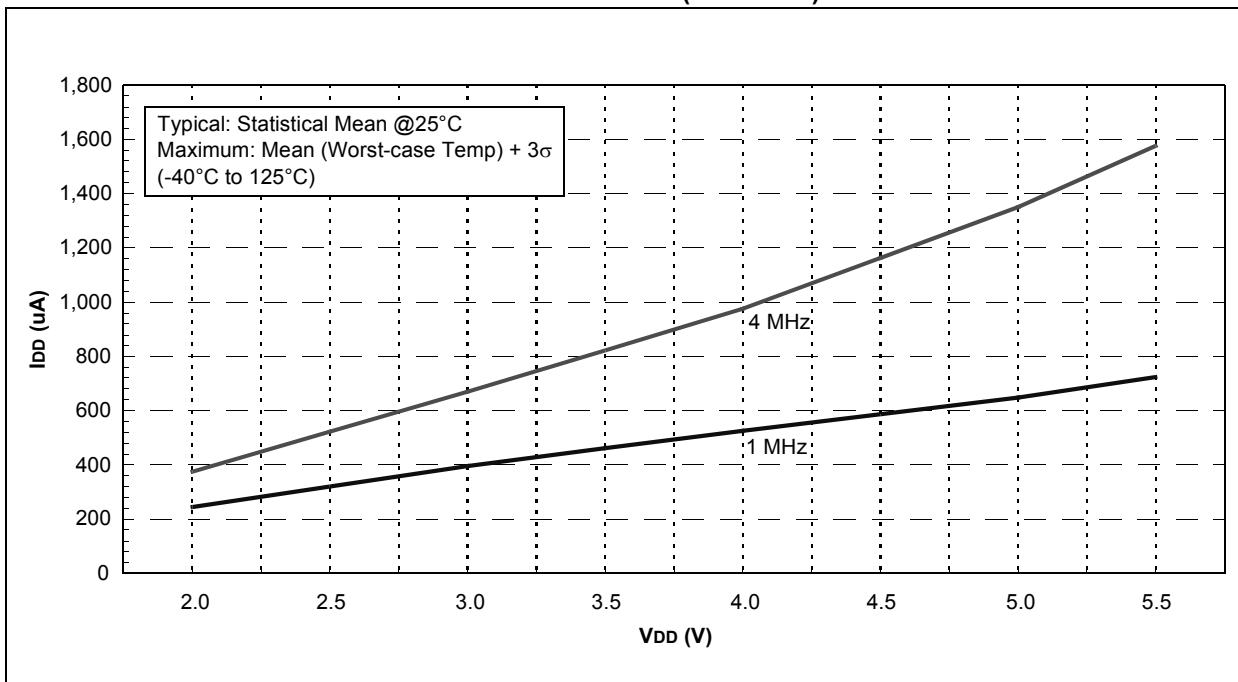


FIGURE 18-7: TYPICAL IDD VS. VDD OVER Fosc (EXTRC MODE)

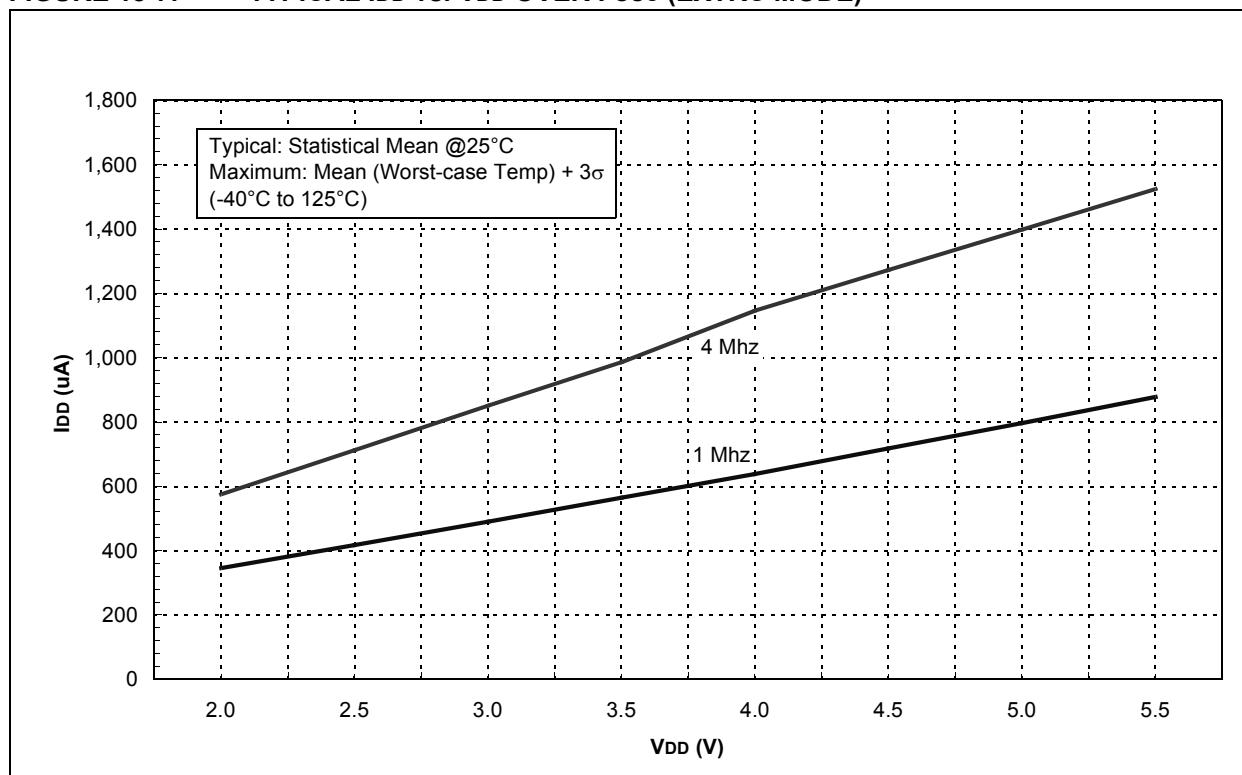


FIGURE 18-8: MAXIMUM IDD vs. VDD (EXTRC MODE)

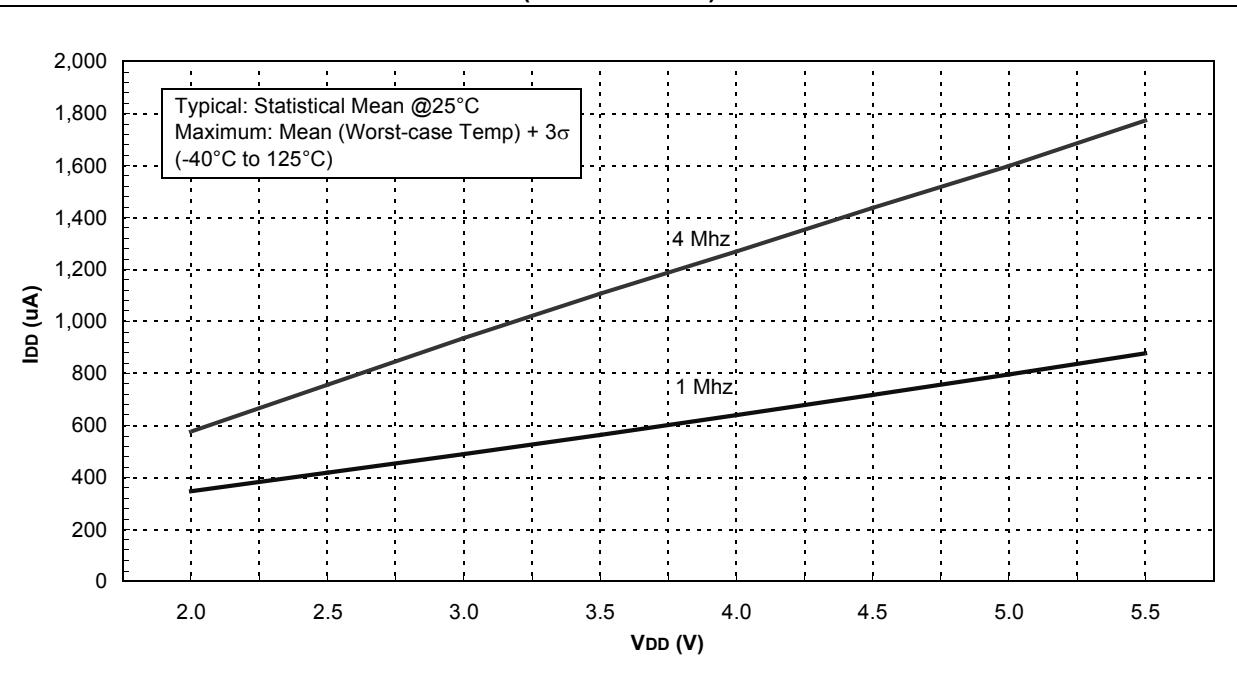
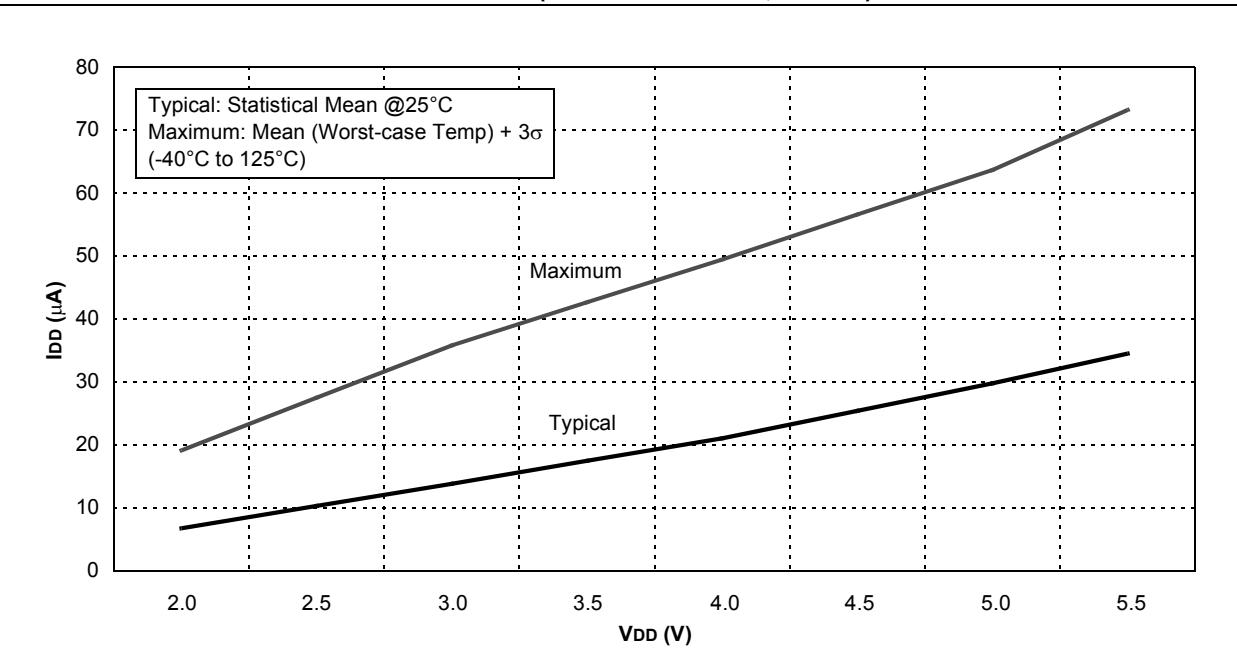


FIGURE 18-9: IDD vs. VDD OVER Fosc (LFINTOSC MODE, 31 kHz)



PIC16F882/883/884/886/887

FIGURE 18-10: IDD vs. VDD (LP MODE)

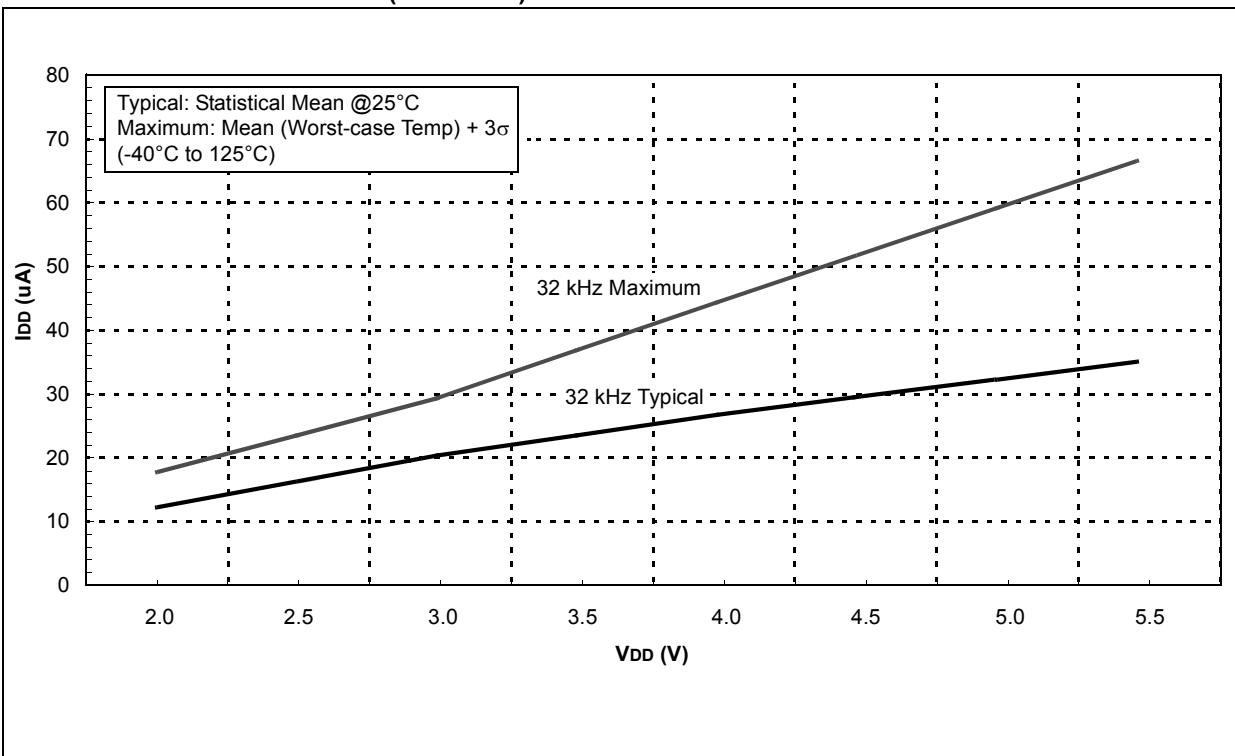
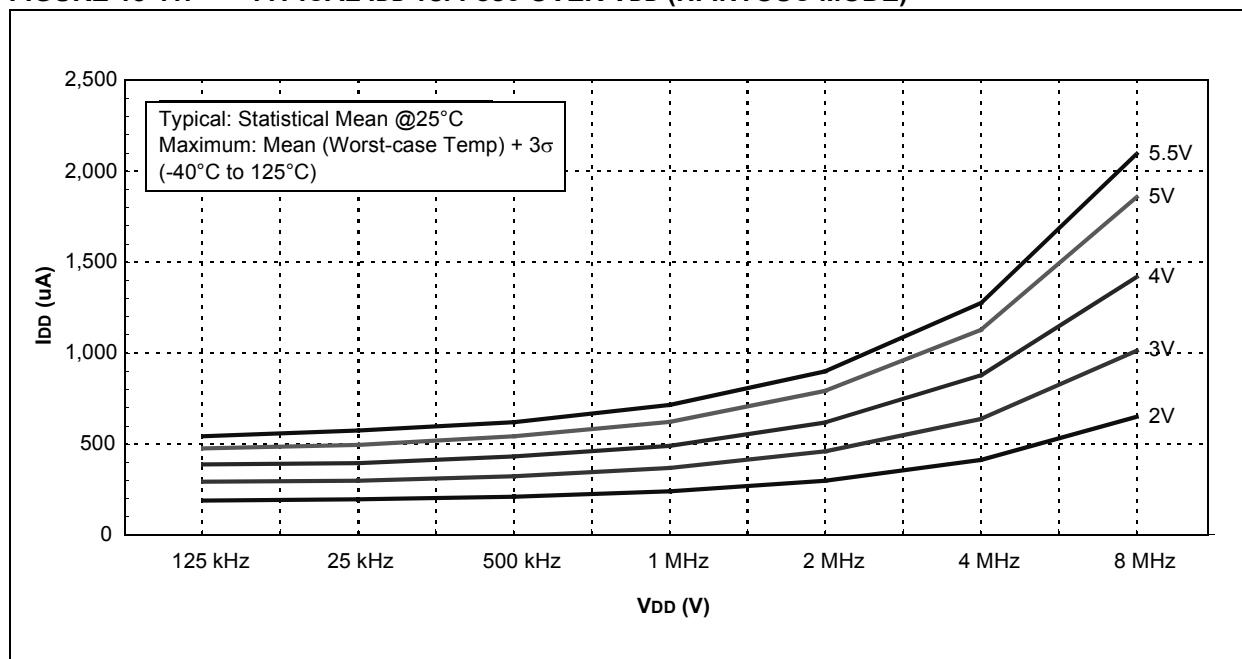


FIGURE 18-11: TYPICAL IDD vs. FOSC OVER VDD (HFINTOSC MODE)



PIC16F882/883/884/886/887

FIGURE 18-12: MAXIMUM IDD vs. Fosc OVER VDD (HFINTOSC MODE)

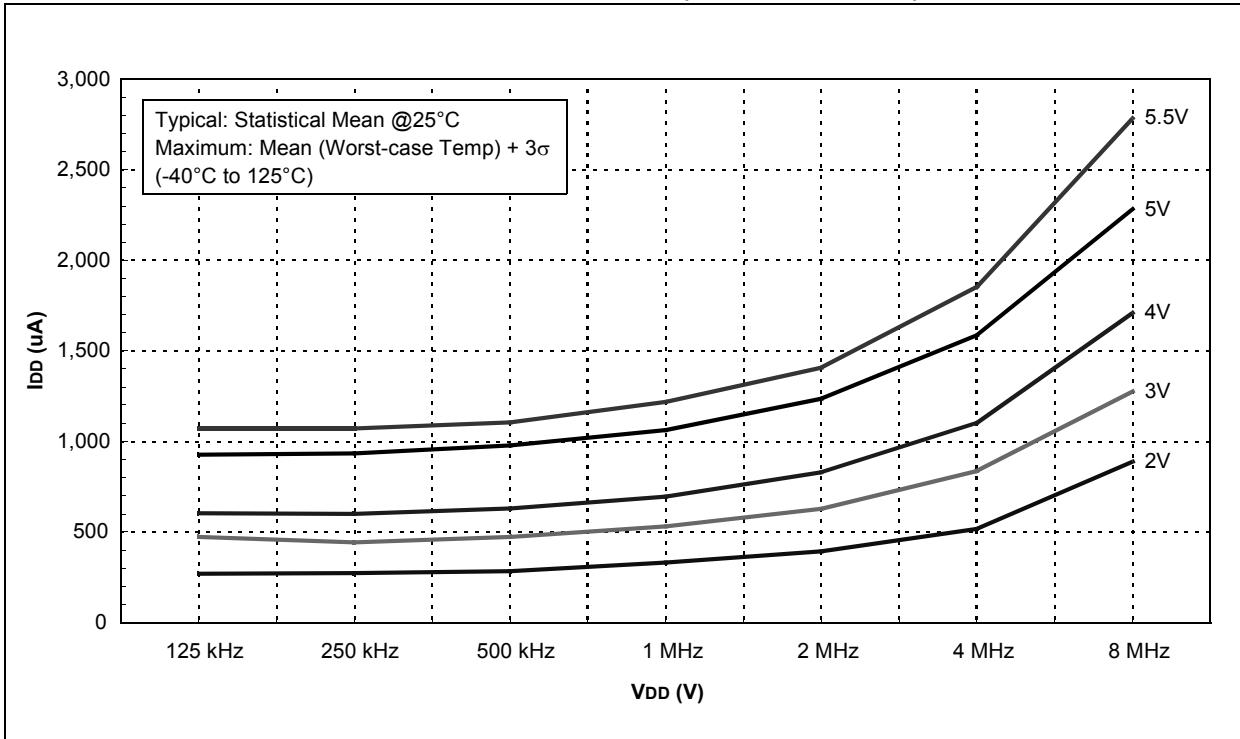
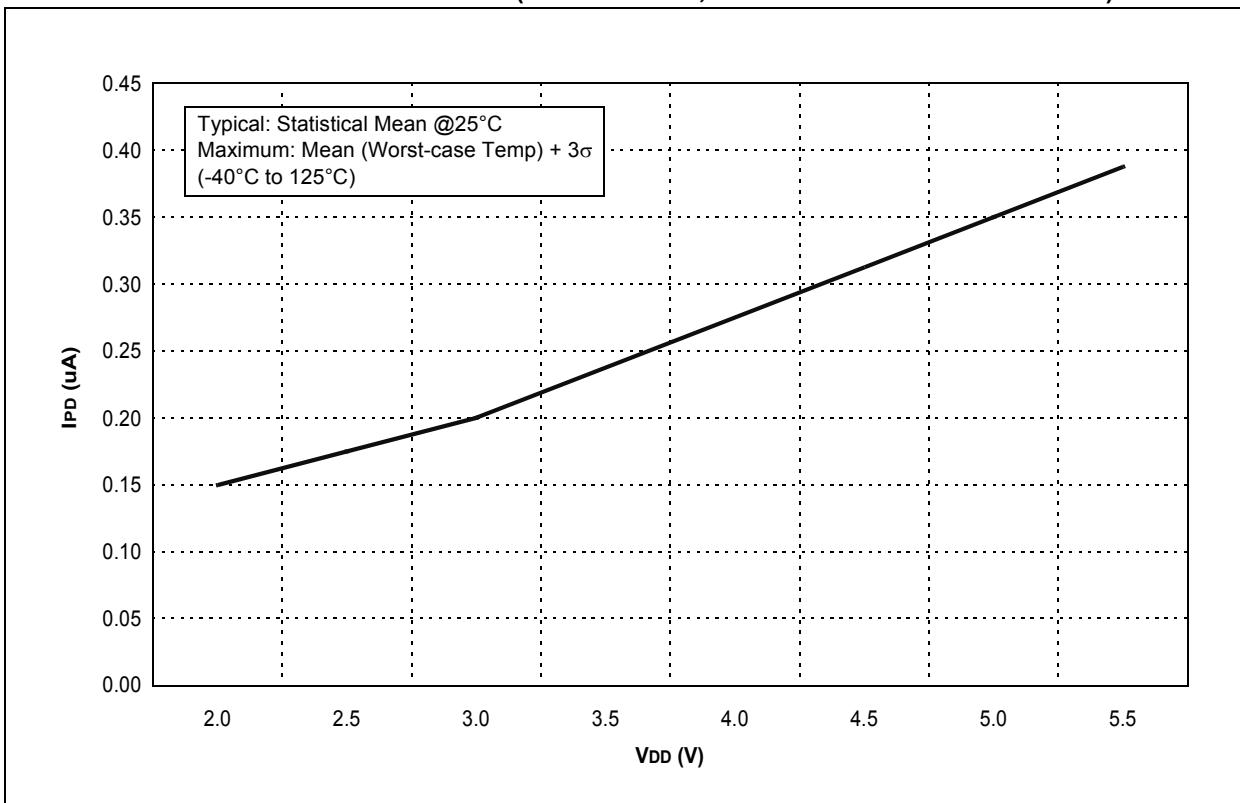


FIGURE 18-13: TYPICAL IPD vs. VDD (SLEEP MODE, ALL PERIPHERALS DISABLED)



PIC16F882/883/884/886/887

FIGURE 18-14: MAXIMUM IPD VS. VDD (SLEEP MODE, ALL PERIPHERALS DISABLED)

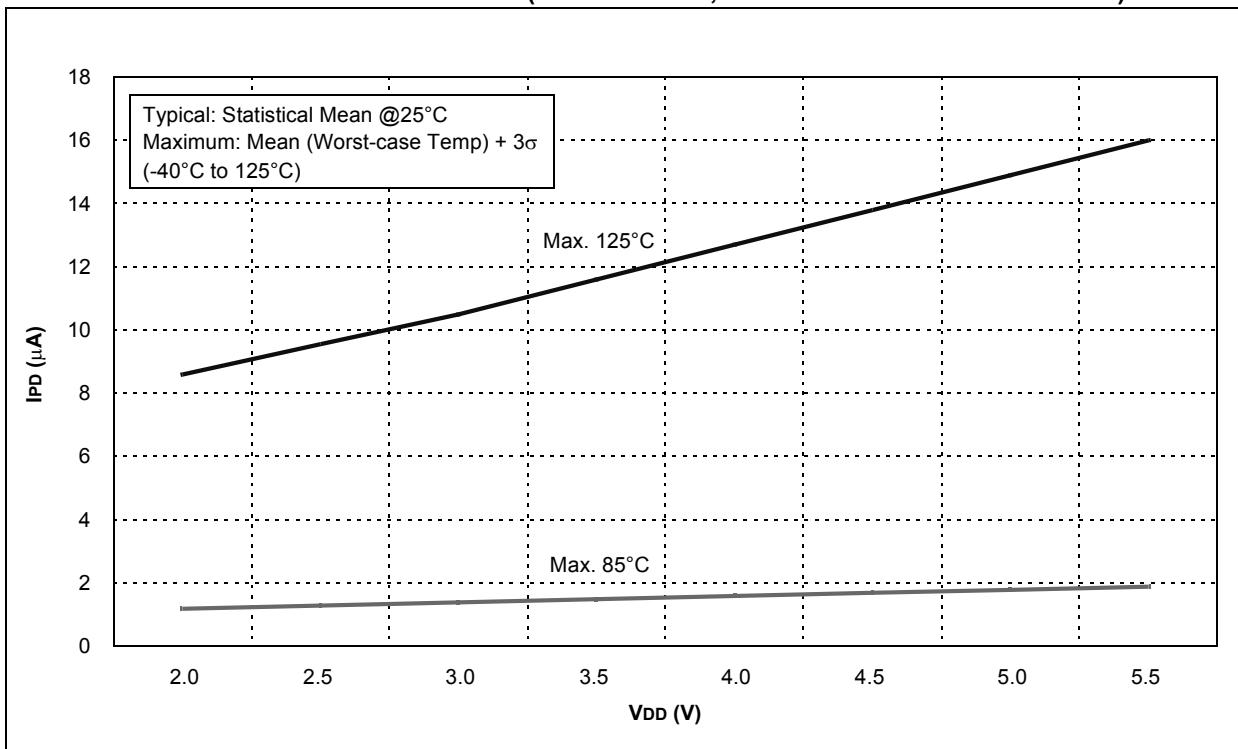


FIGURE 18-15: COMPARATOR IPD VS. VDD (BOTH COMPARATORS ENABLED)

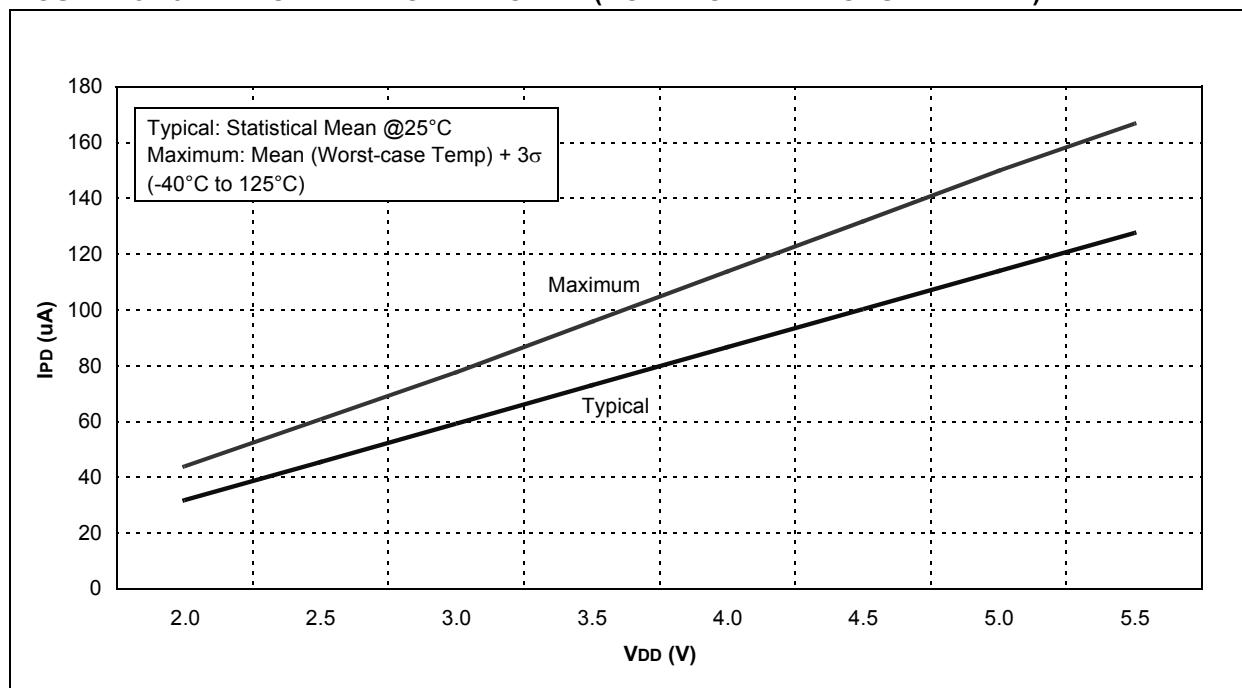


FIGURE 18-16: BOR IPD vs. VDD OVER TEMPERATURE

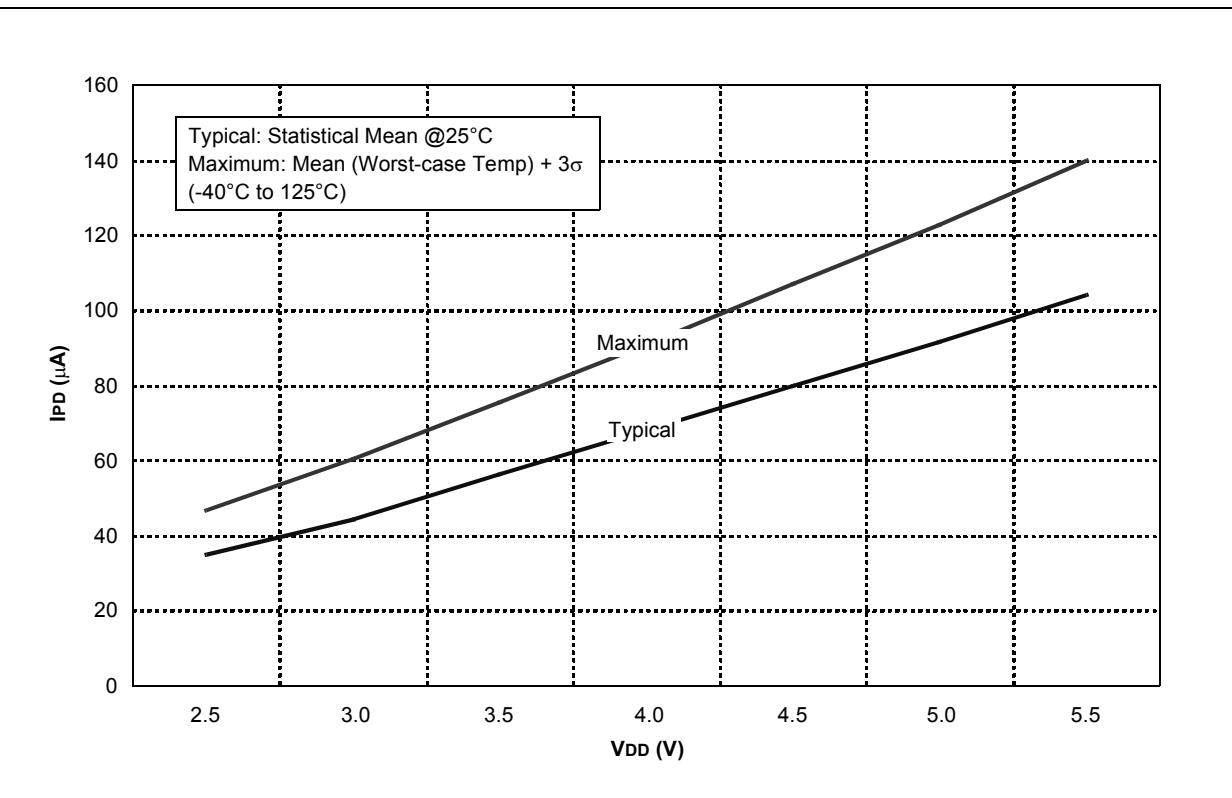
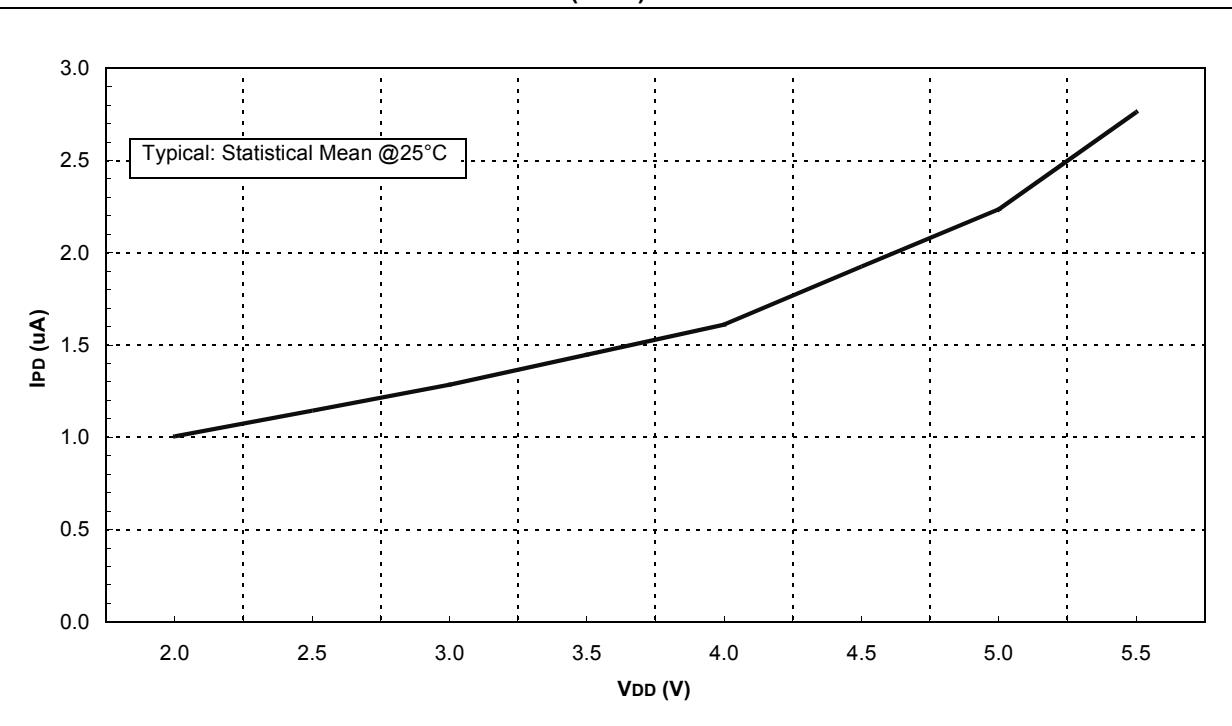


FIGURE 18-17: TYPICAL WDT IPD vs. VDD (25°C)



PIC16F882/883/884/886/887

FIGURE 18-18: MAXIMUM WDT IPD VS. VDD OVER TEMPERATURE

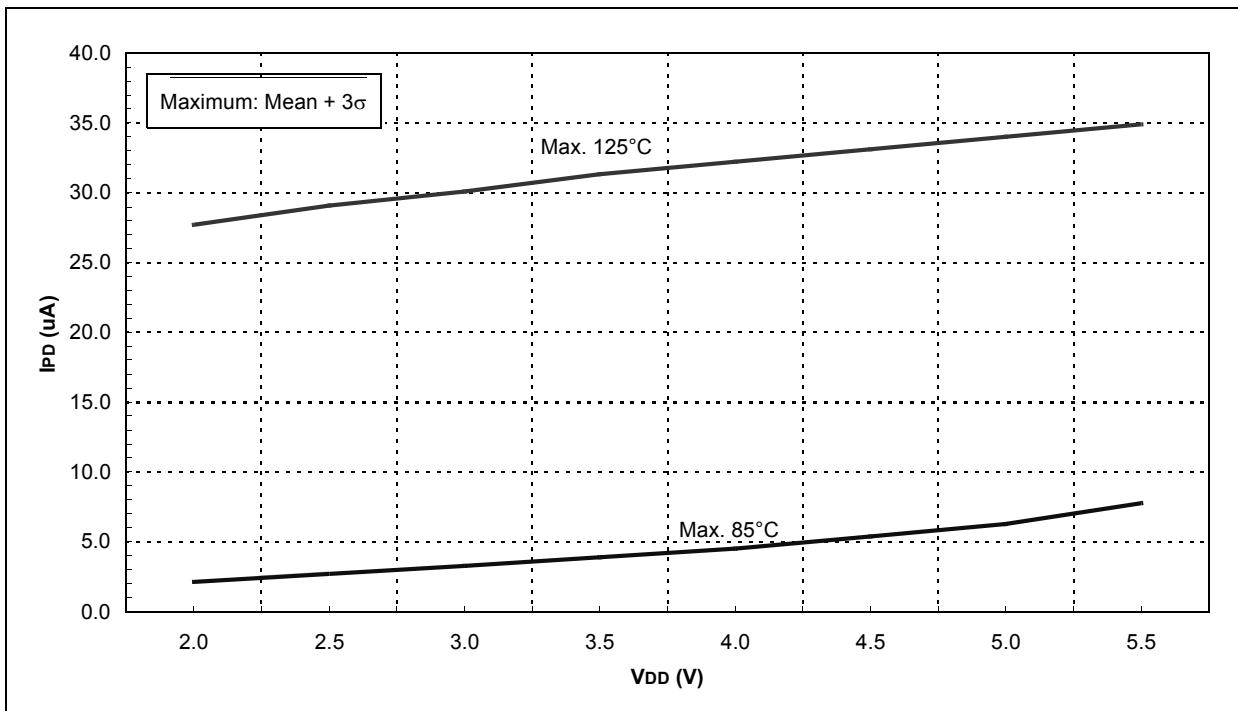


FIGURE 18-19: WDT PERIOD VS. VDD OVER TEMPERATURE

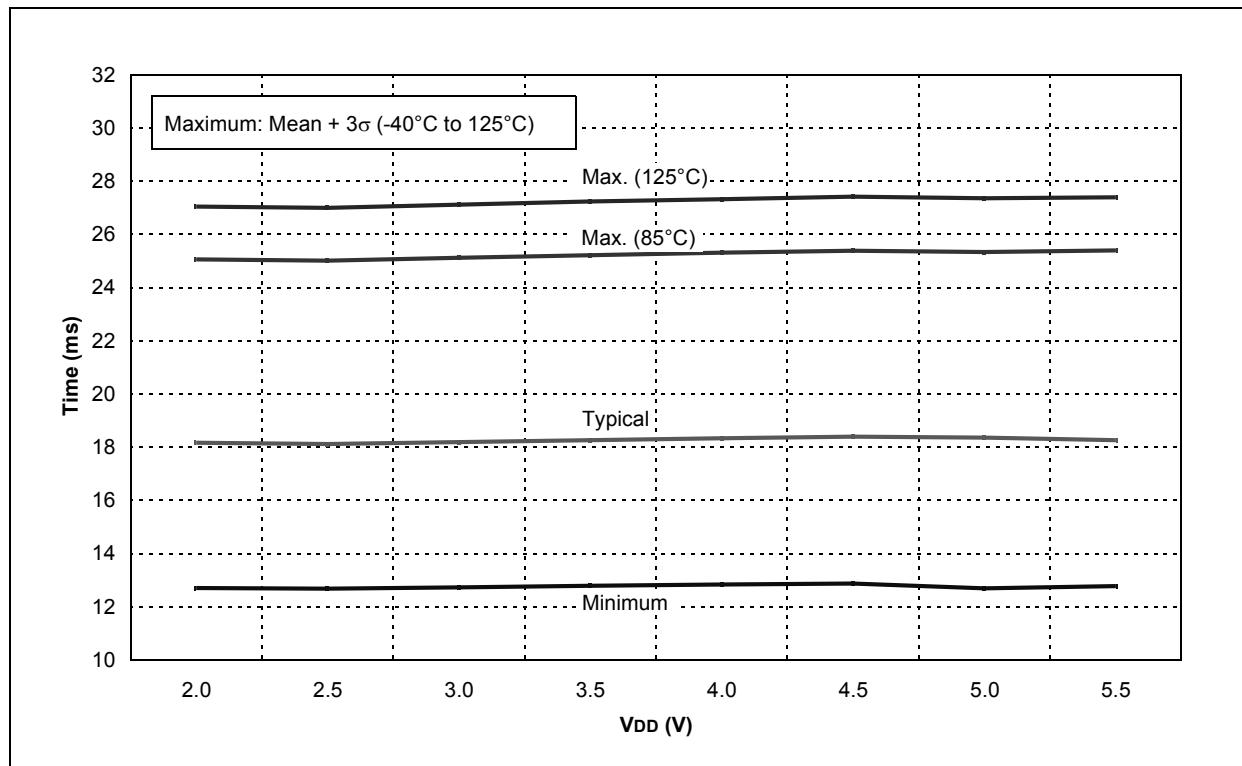


FIGURE 18-20: WDT PERIOD vs. TEMPERATURE (VDD = 5.0V)

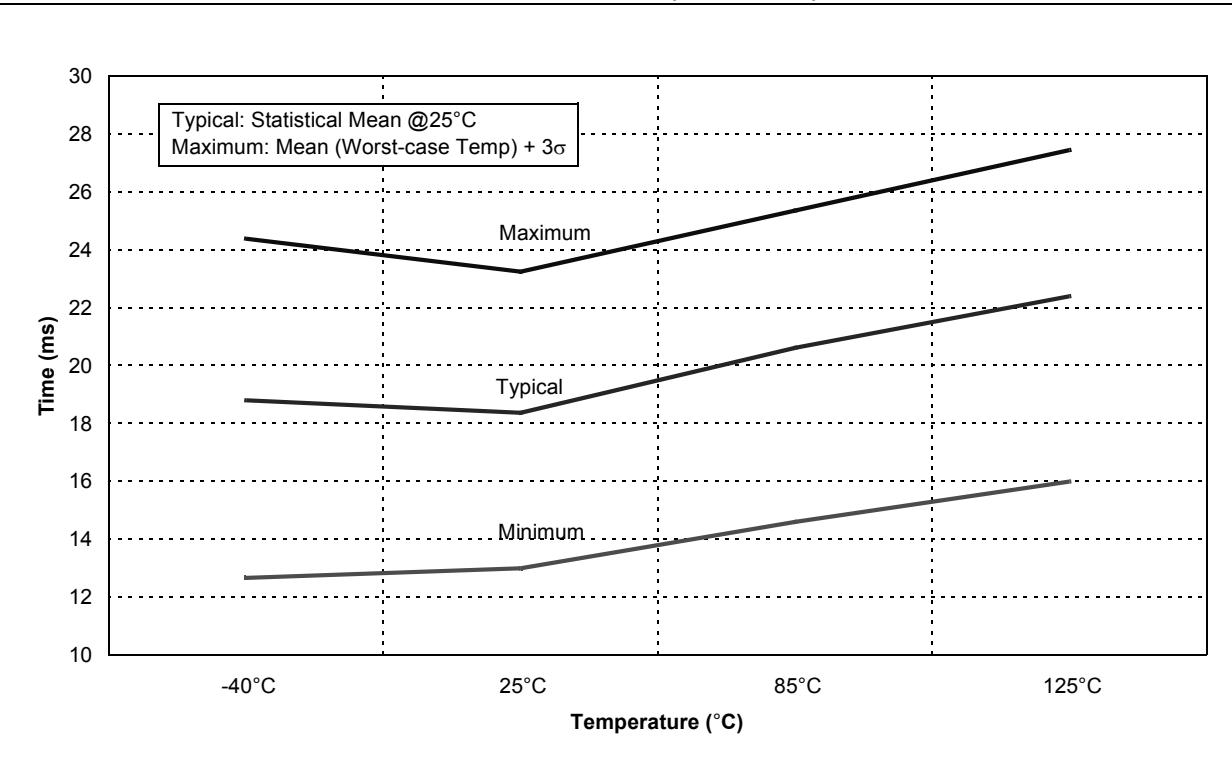
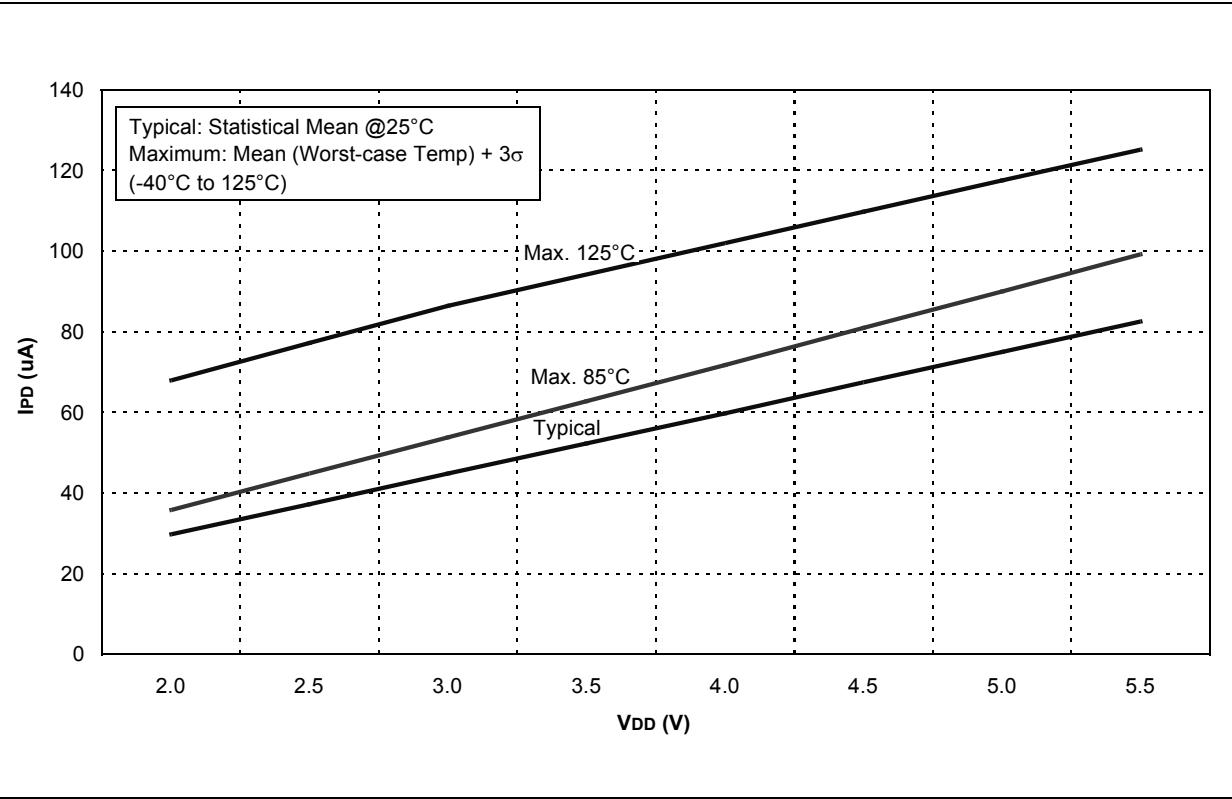


FIGURE 18-21: CVREF IPPD VS. VDD OVER TEMPERATURE (HIGH RANGE)



PIC16F882/883/884/886/887

FIGURE 18-22: CVREF IPD VS. VDD OVER TEMPERATURE (LOW RANGE)

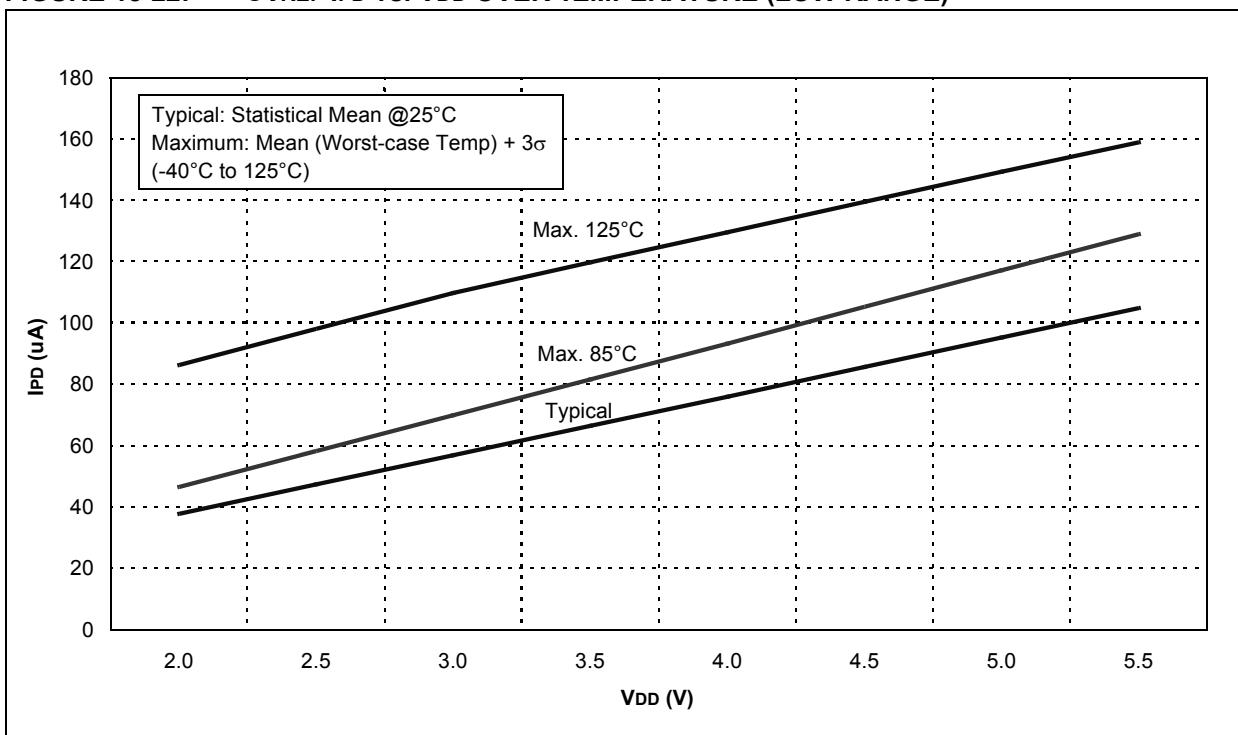
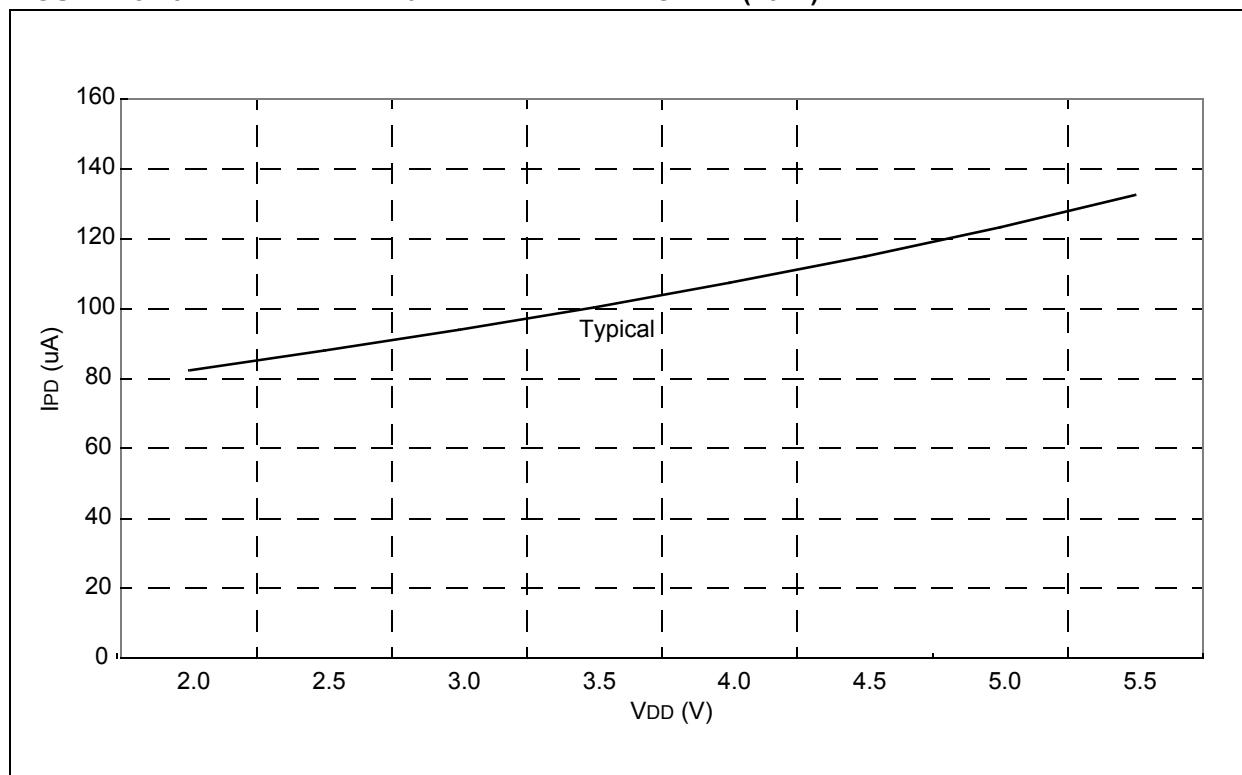


FIGURE 18-23: TYPICAL VP6 REFERENCE IPD VS. VDD (25°C)



PIC16F882/883/884/886/887

FIGURE 18-24: MAXIMUM VP6 REFERENCE IPD VS. VDD OVER TEMPERATURE

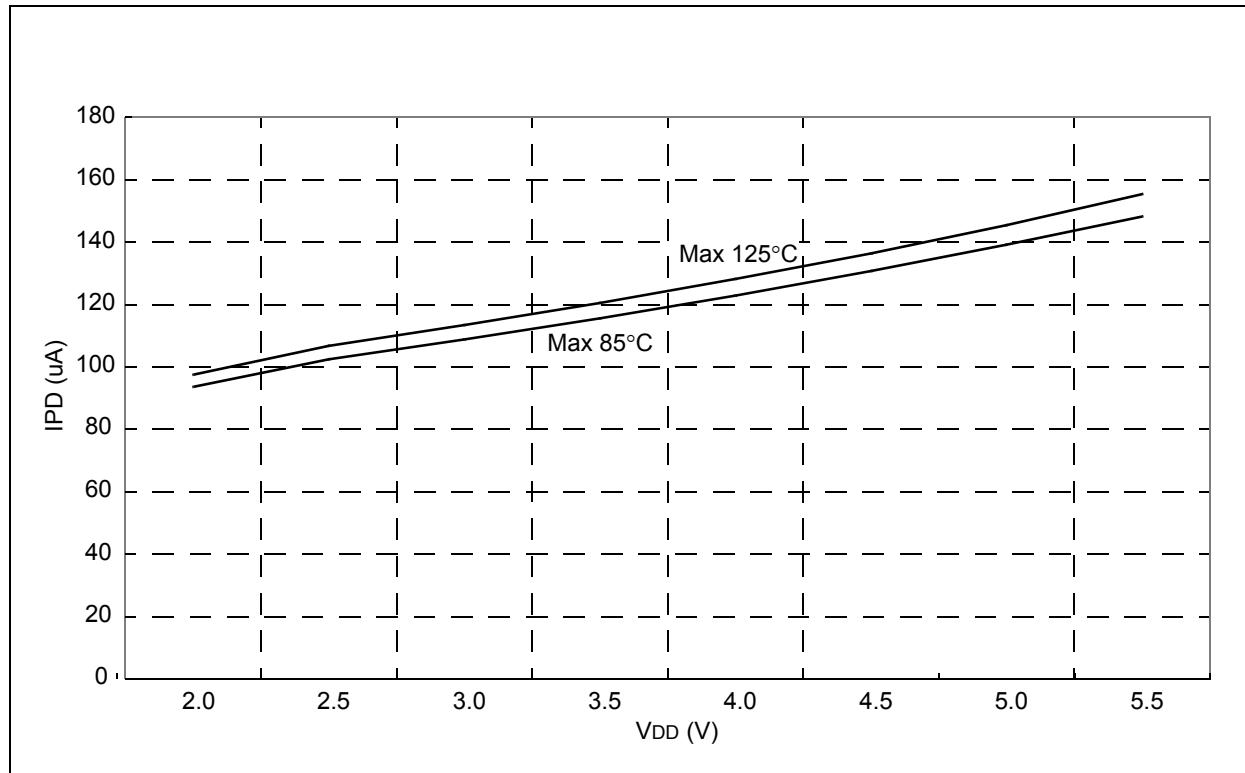
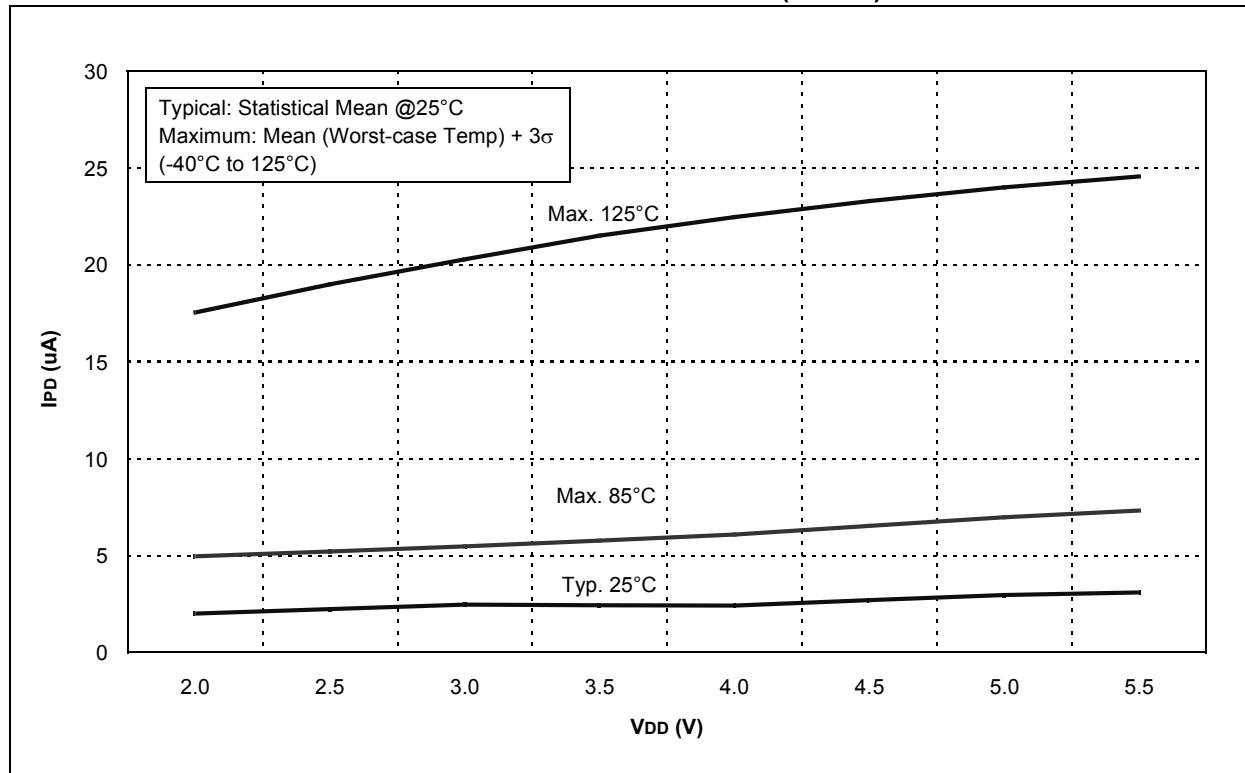


FIGURE 18-25: T1OSC IPD VS. VDD OVER TEMPERATURE (32 kHz)



PIC16F882/883/884/886/887

FIGURE 18-26: VOL vs. IO_L OVER TEMPERATURE (V_{DD} = 3.0V)

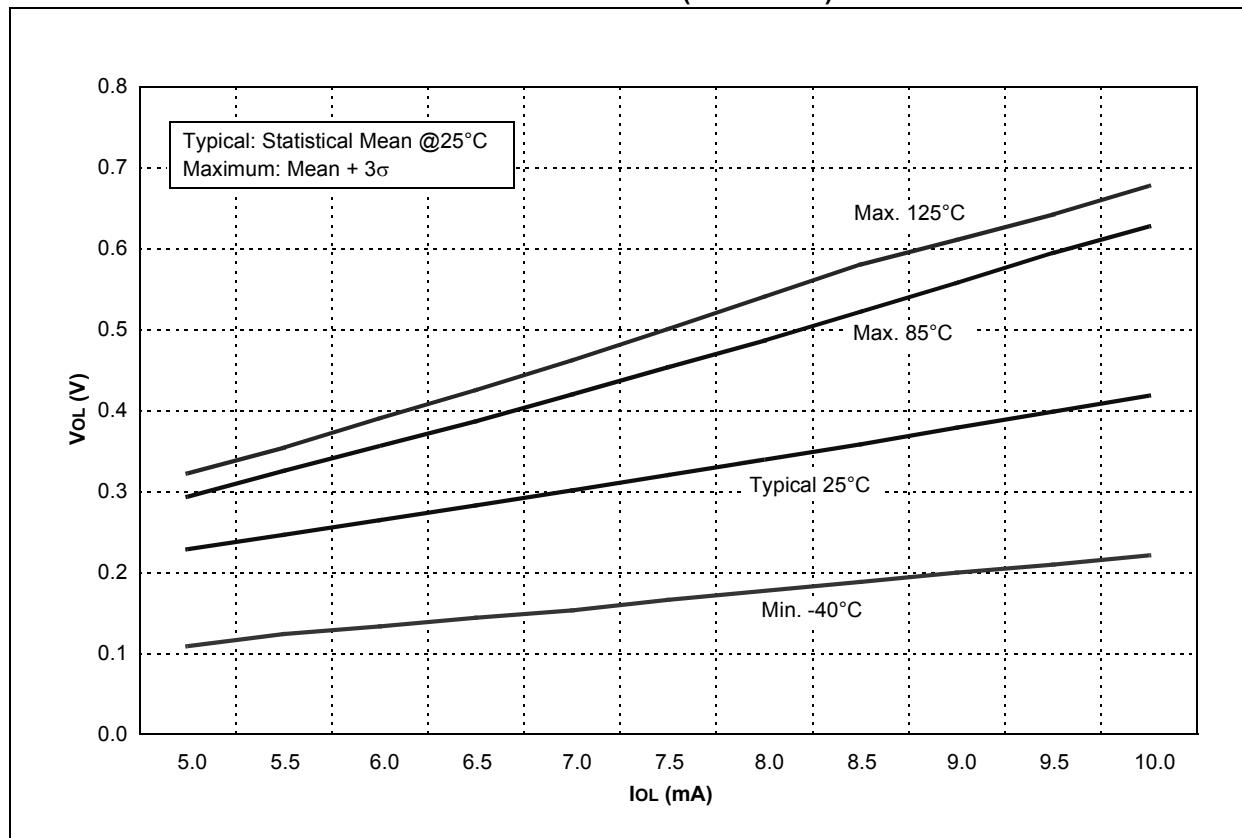


FIGURE 18-27: VOL vs. IO_L OVER TEMPERATURE (V_{DD} = 5.0V)

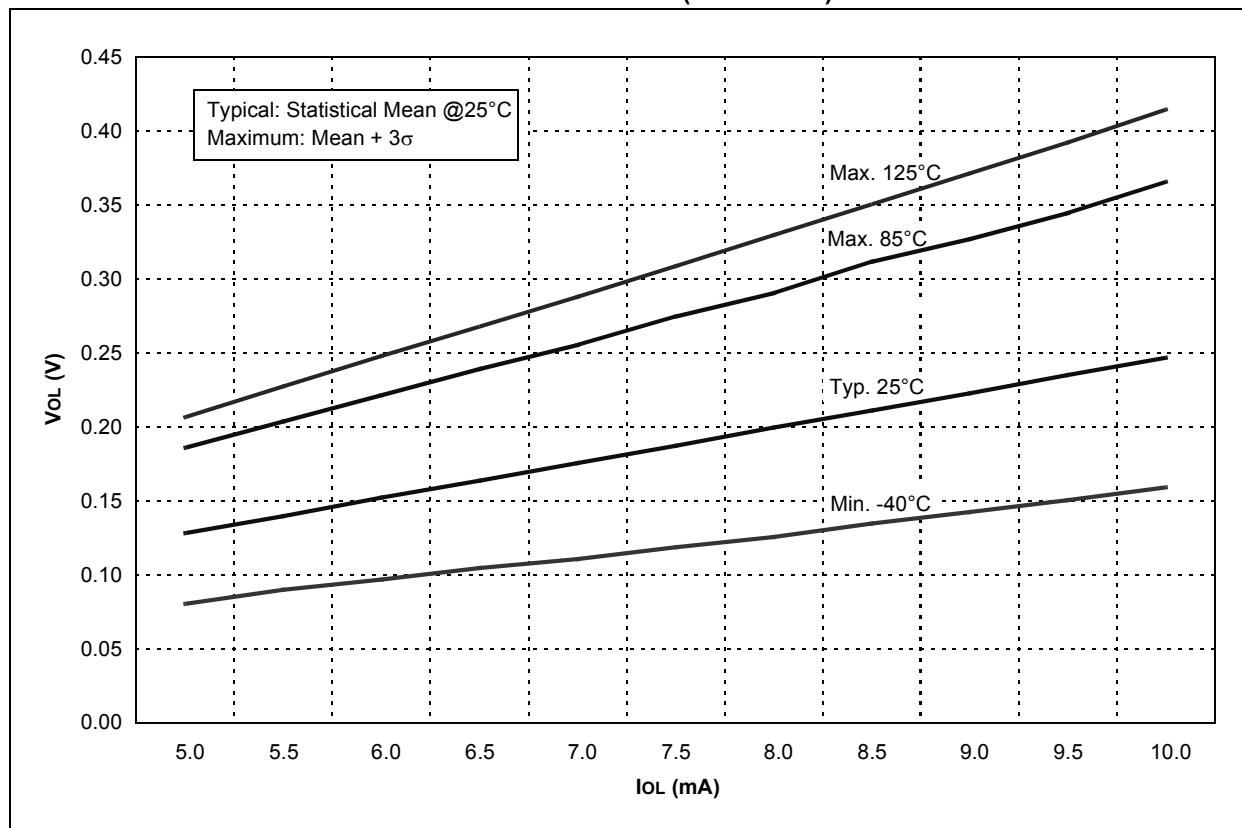


FIGURE 18-28: V_{OH} vs. I_{OH} OVER TEMPERATURE (V_{DD} = 3.0V)

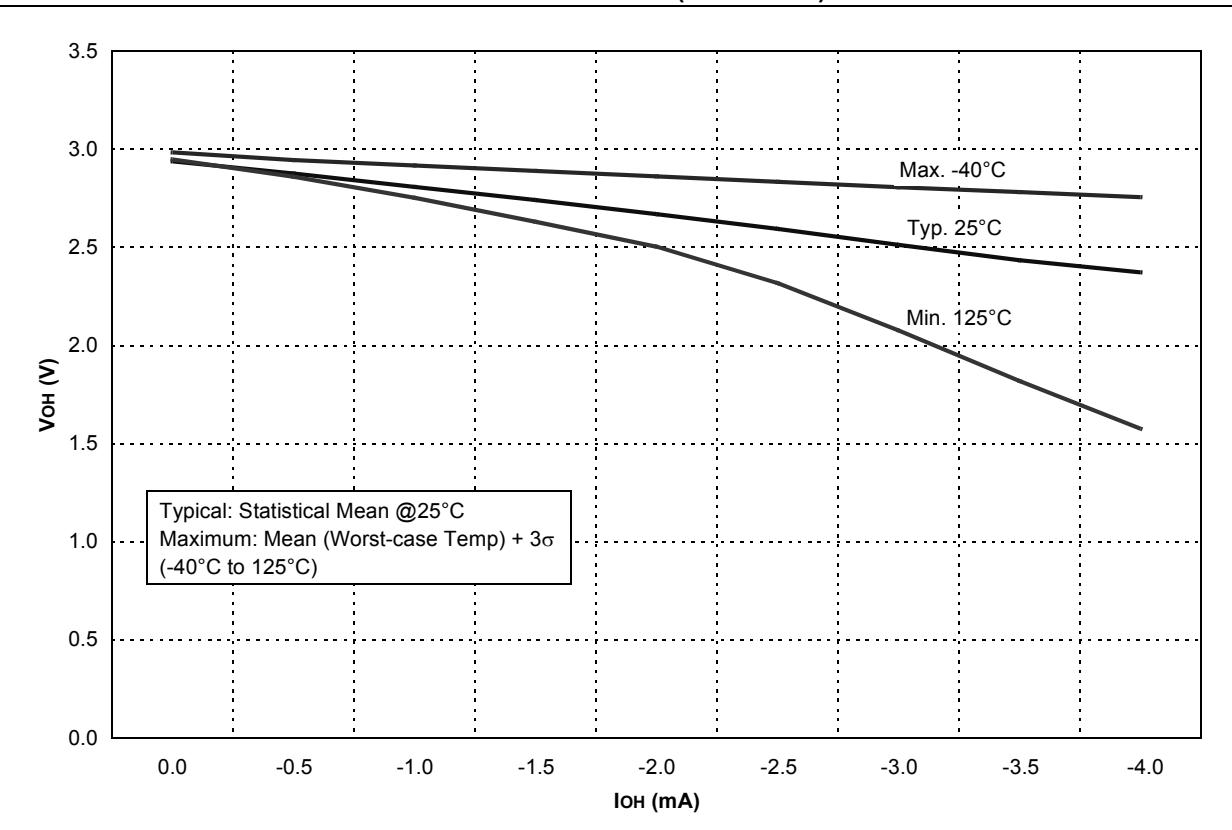
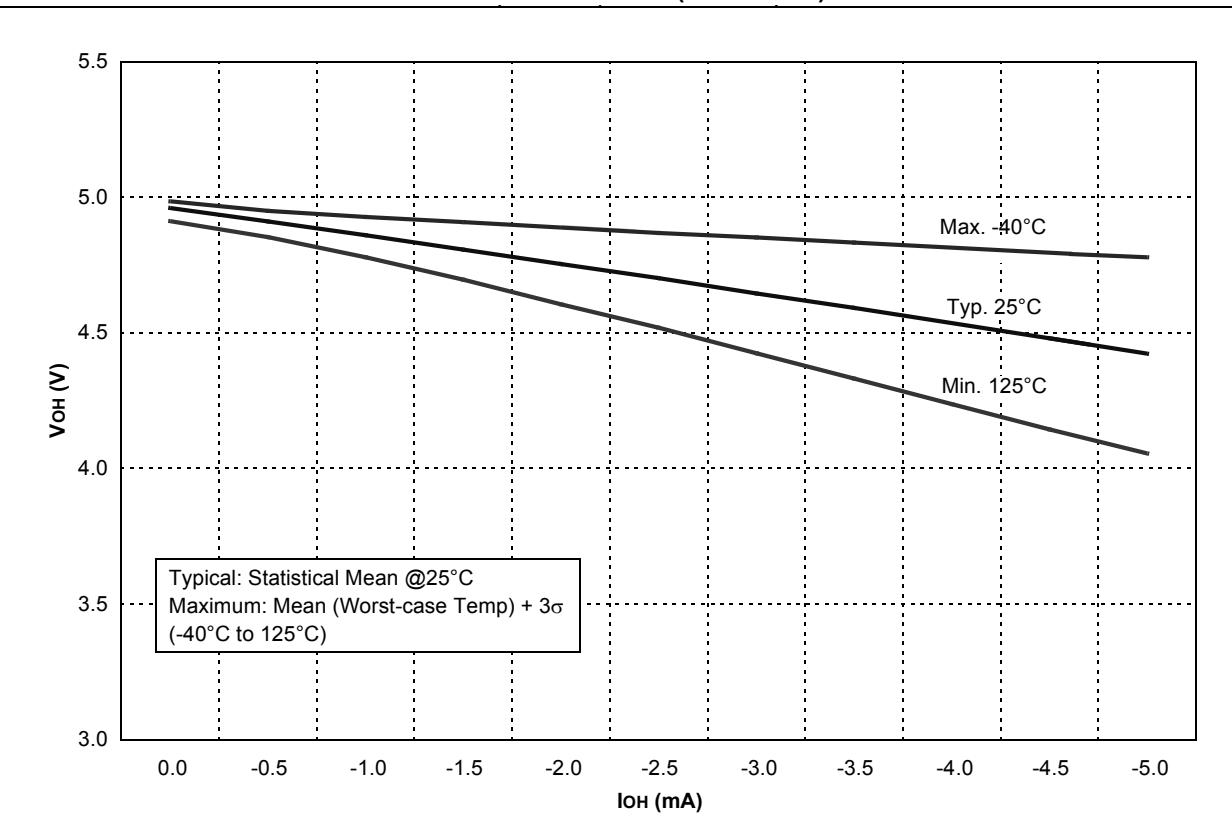


FIGURE 18-29: V_{OH} vs. I_{OH} OVER TEMPERATURE (V_{DD} = 5.0V)



PIC16F882/883/884/886/887

FIGURE 18-30: TTL INPUT THRESHOLD V_{IN} vs. V_{DD} OVER TEMPERATURE

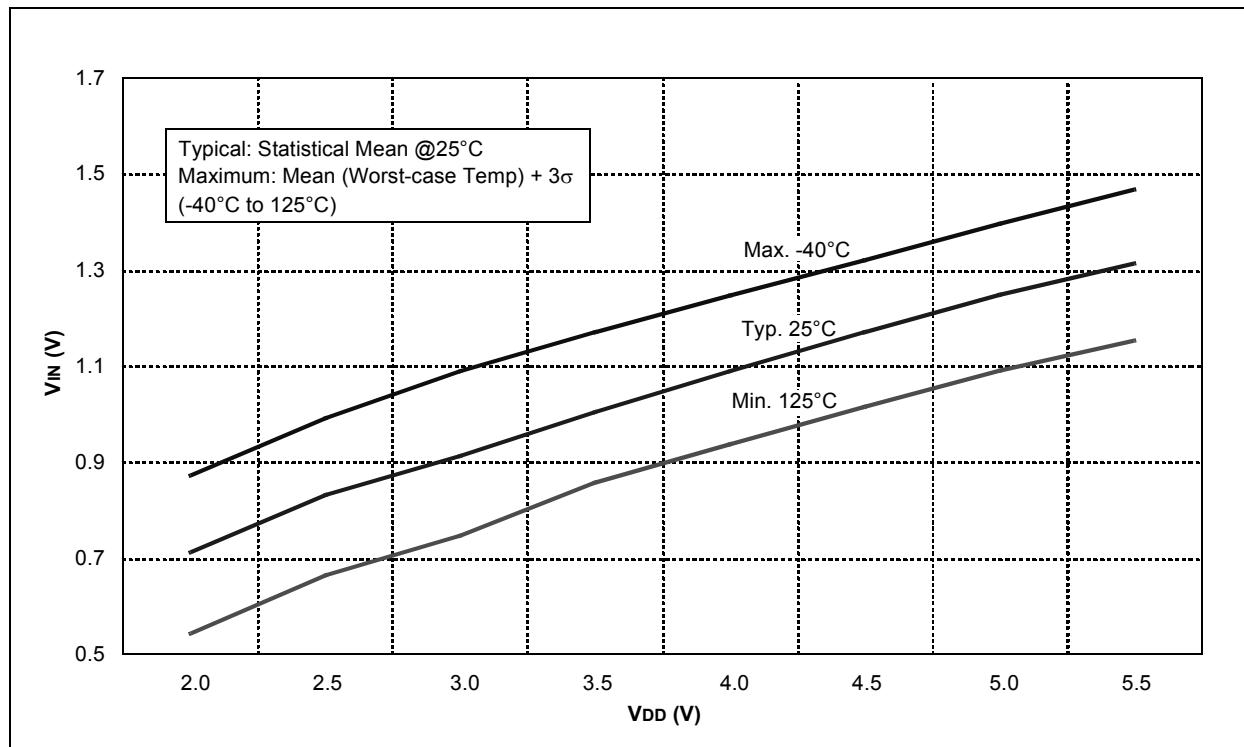


FIGURE 18-31: SCHMITT TRIGGER INPUT THRESHOLD V_{IN} vs. V_{DD} OVER TEMPERATURE

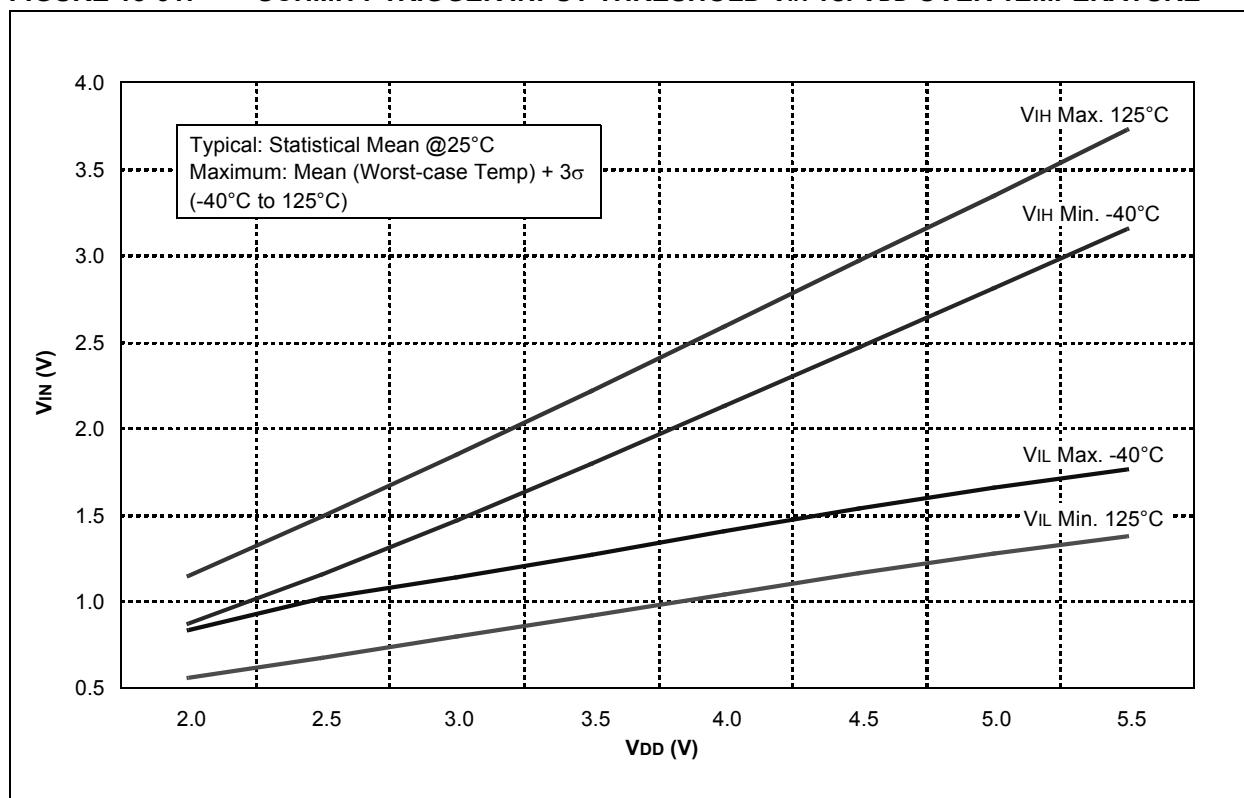


FIGURE 18-32: COMPARATOR RESPONSE TIME (RISING EDGE)

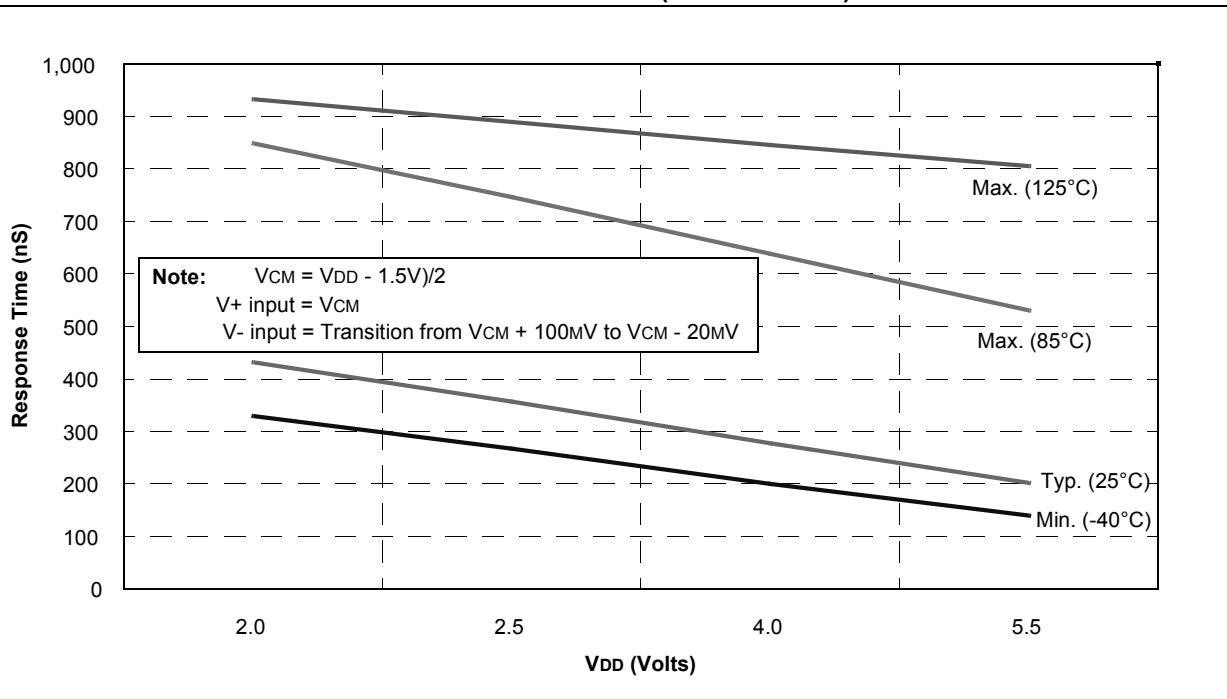
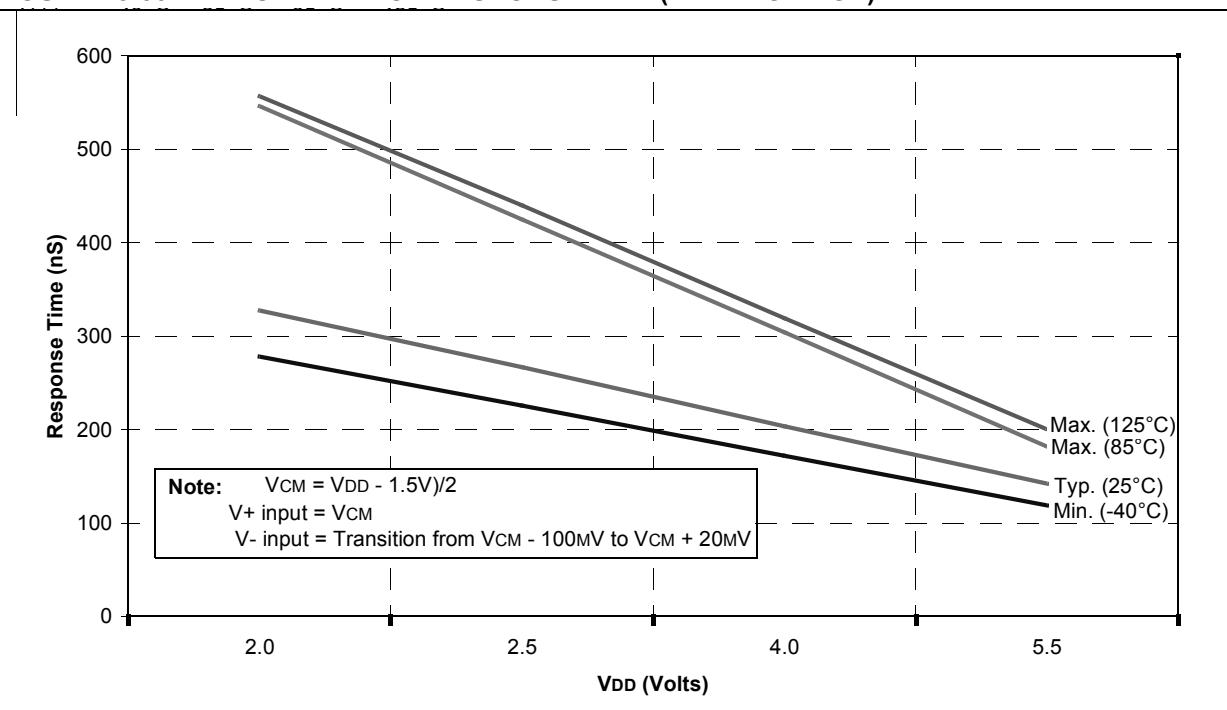


FIGURE 18-33: COMPARATOR RESPONSE TIME (FALLING EDGE)



PIC16F882/883/884/886/887

FIGURE 18-34: LFINTOSC FREQUENCY vs. VDD OVER TEMPERATURE (31 kHz)

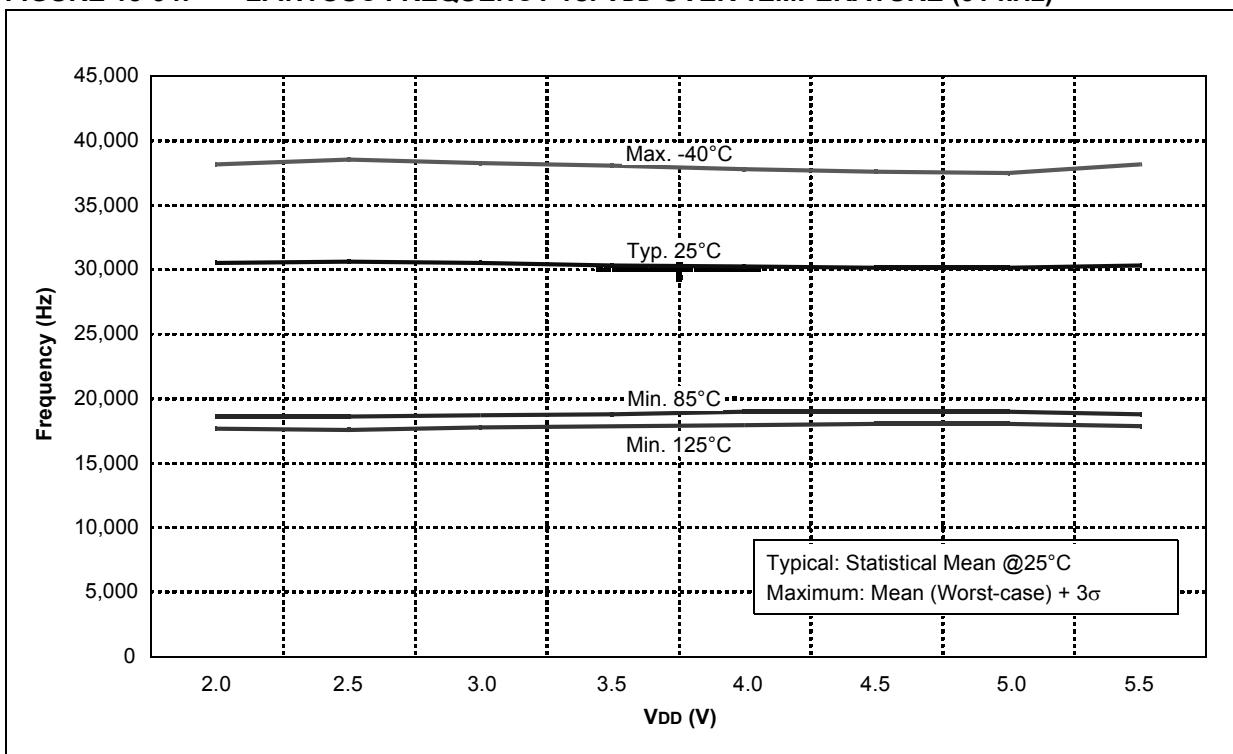


FIGURE 18-35: ADC CLOCK PERIOD vs. VDD OVER TEMPERATURE

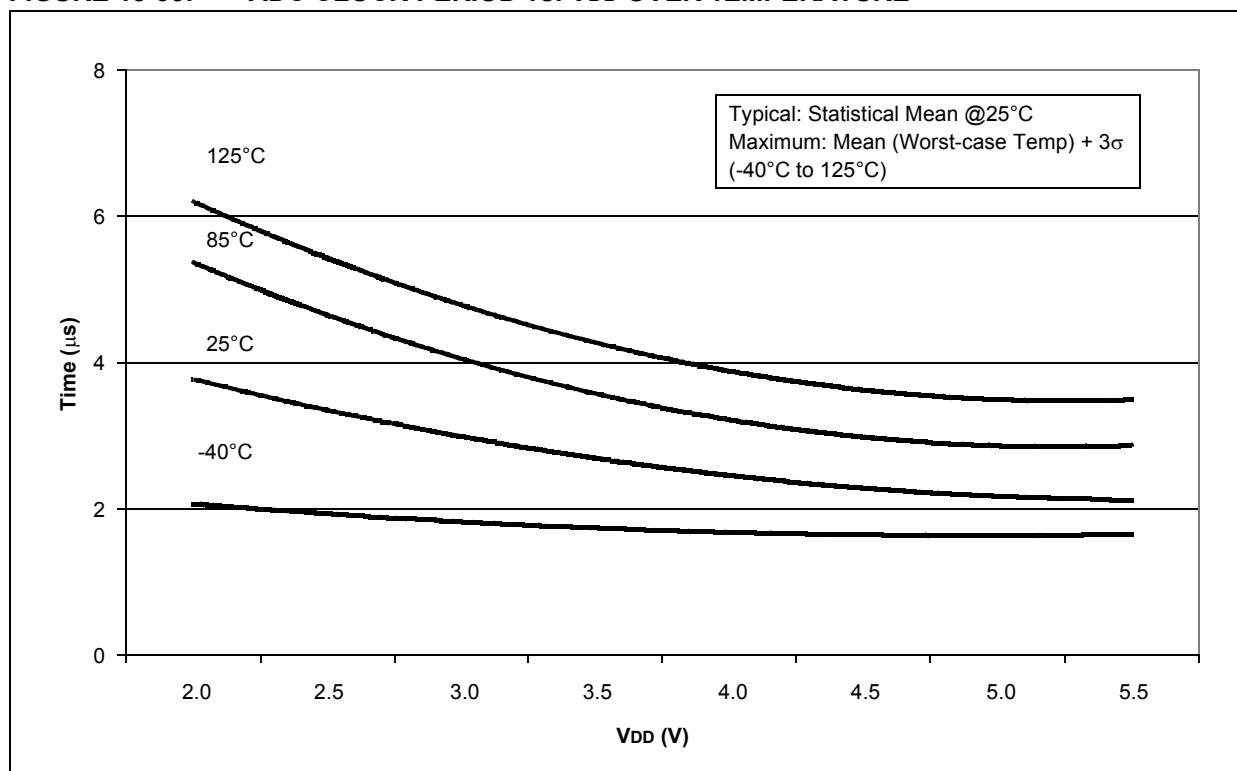


FIGURE 18-36: TYPICAL HFINTOSC START-UP TIMES vs. V_{DD} OVER TEMPERATURE

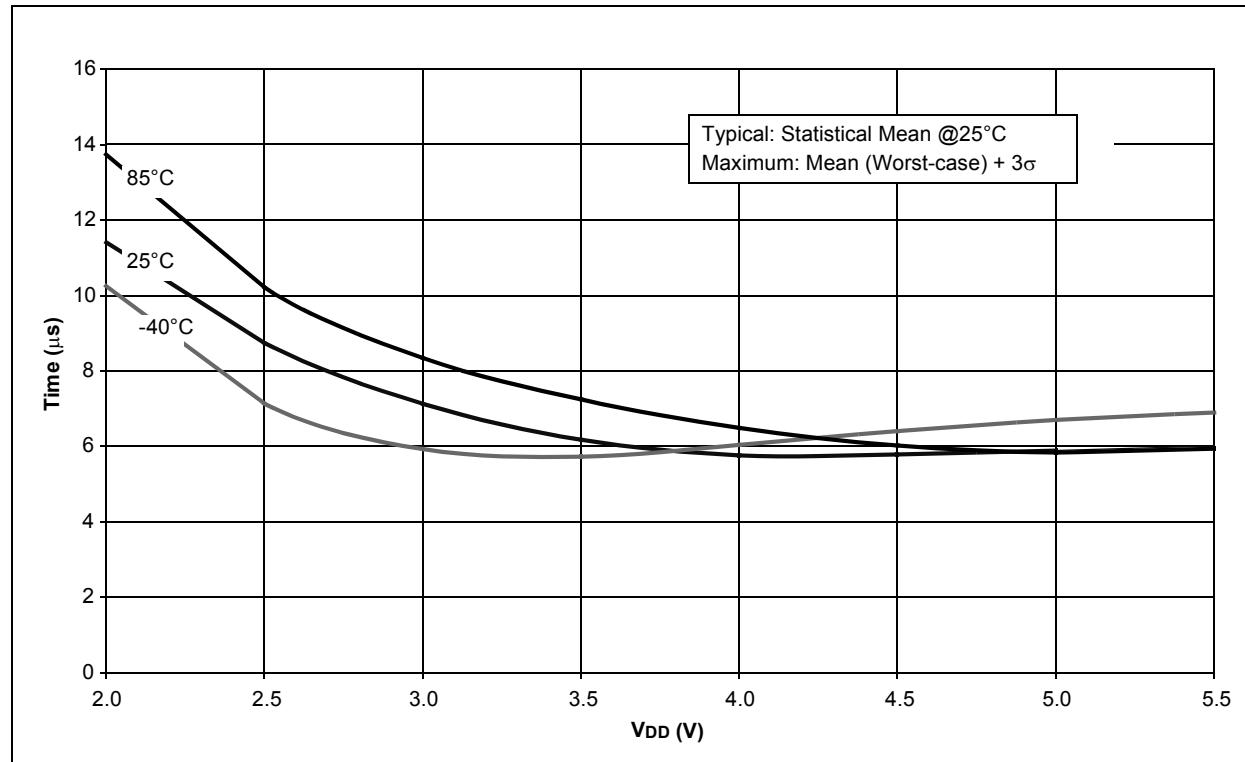
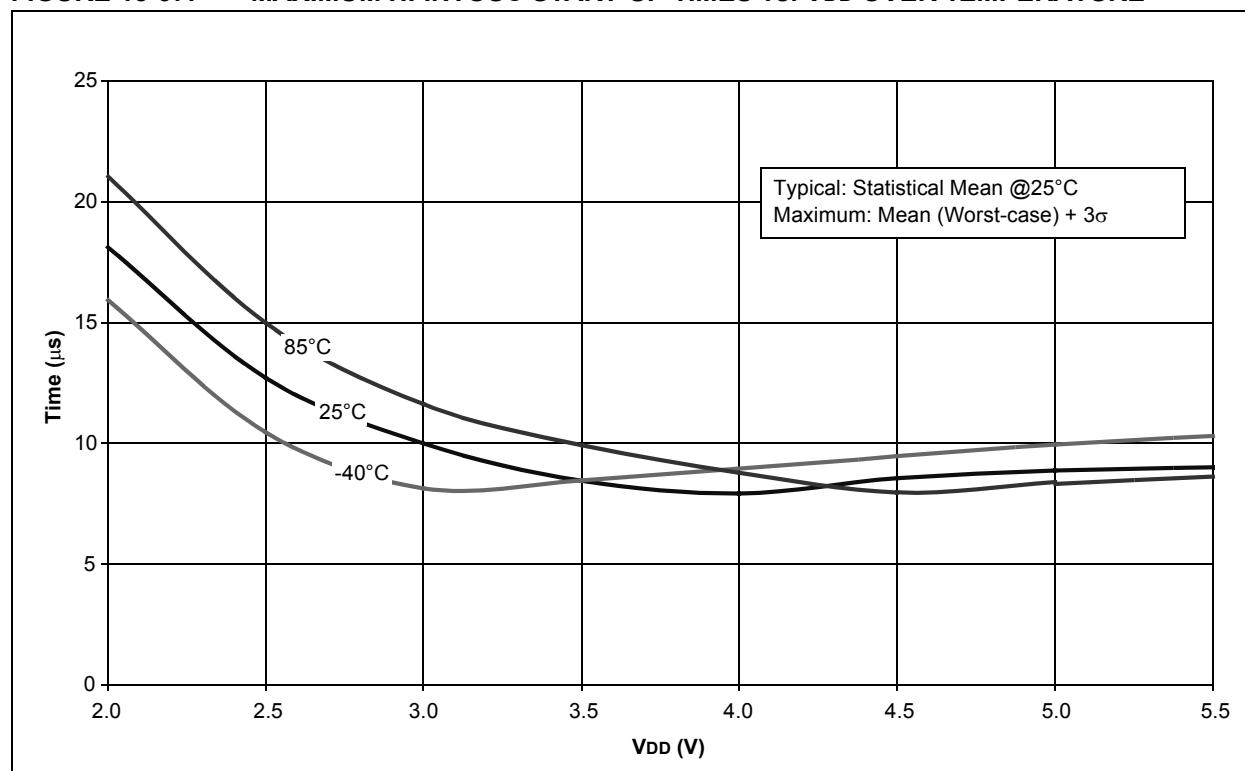


FIGURE 18-37: MAXIMUM HFINTOSC START-UP TIMES vs. V_{DD} OVER TEMPERATURE



PIC16F882/883/884/886/887

FIGURE 18-38: MINIMUM HFINTOSC START-UP TIMES vs. V_{DD} OVER TEMPERATURE

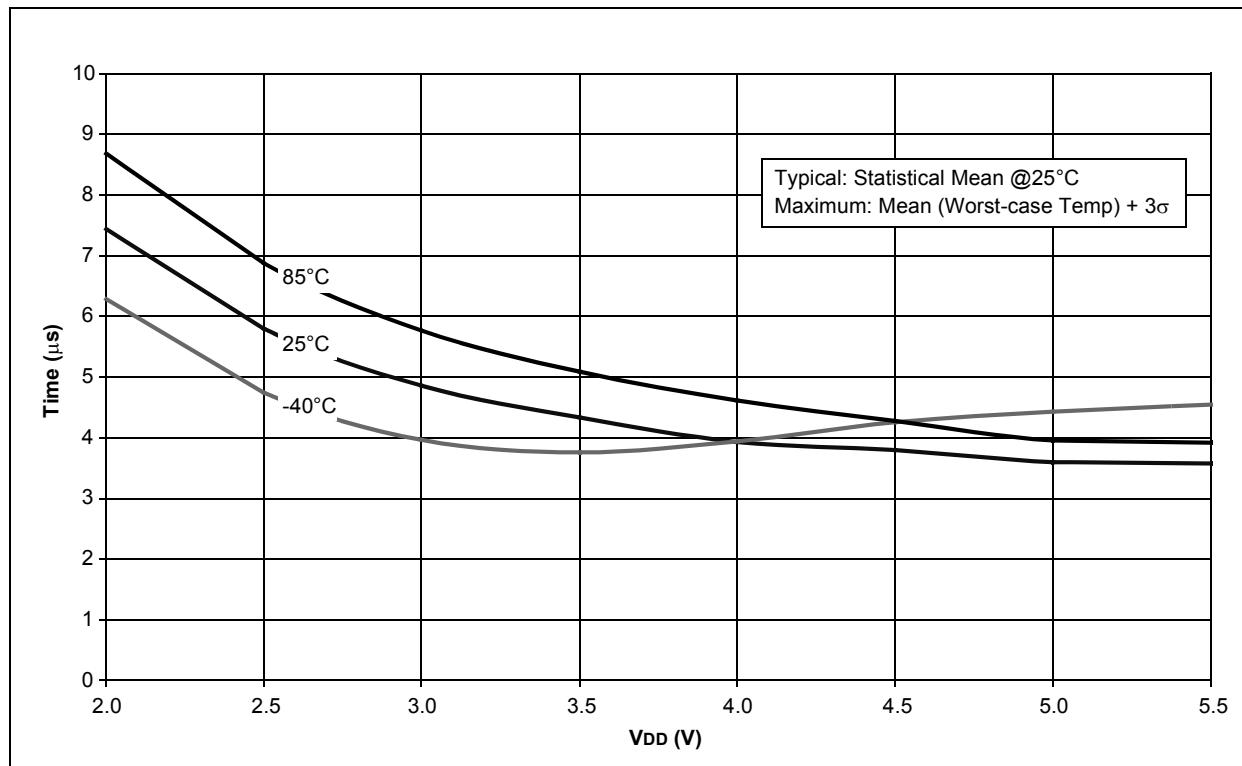
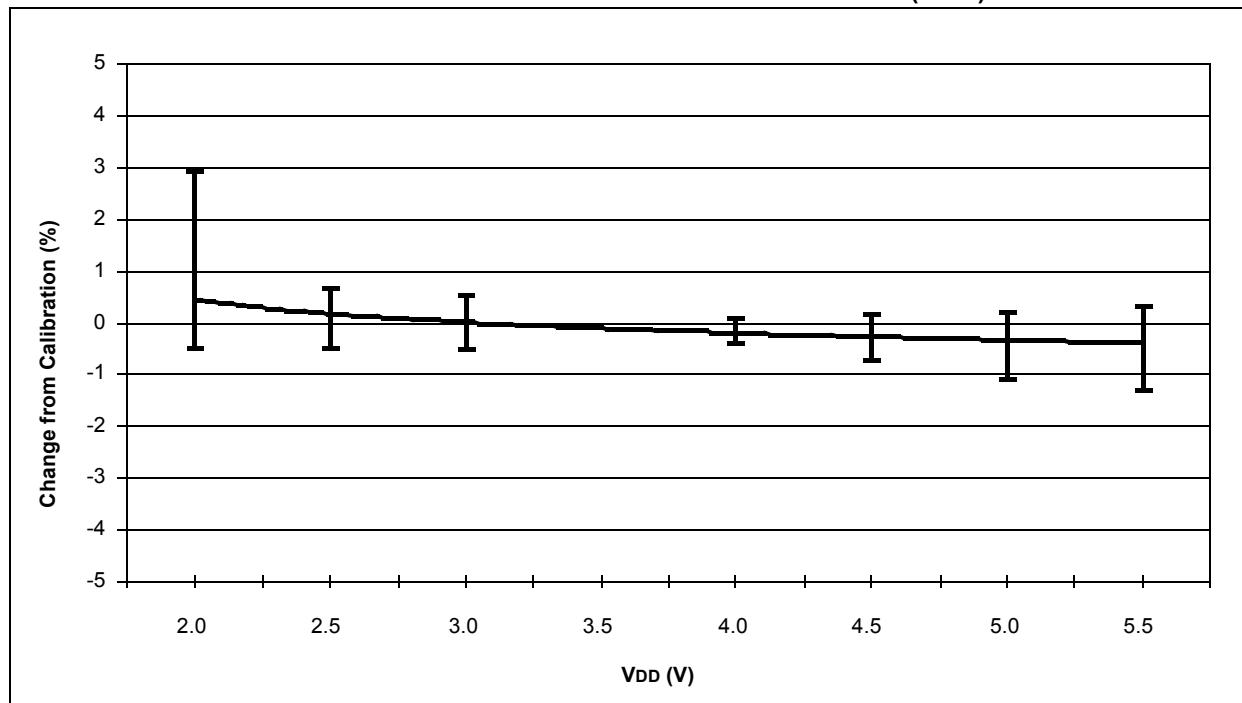


FIGURE 18-39: TYPICAL HFINTOSC FREQUENCY CHANGE vs. V_{DD} (25°C)



PIC16F882/883/884/886/887

FIGURE 18-40: TYPICAL HFINTOSC FREQUENCY CHANGE OVER DEVICE V_{DD} (85°C)

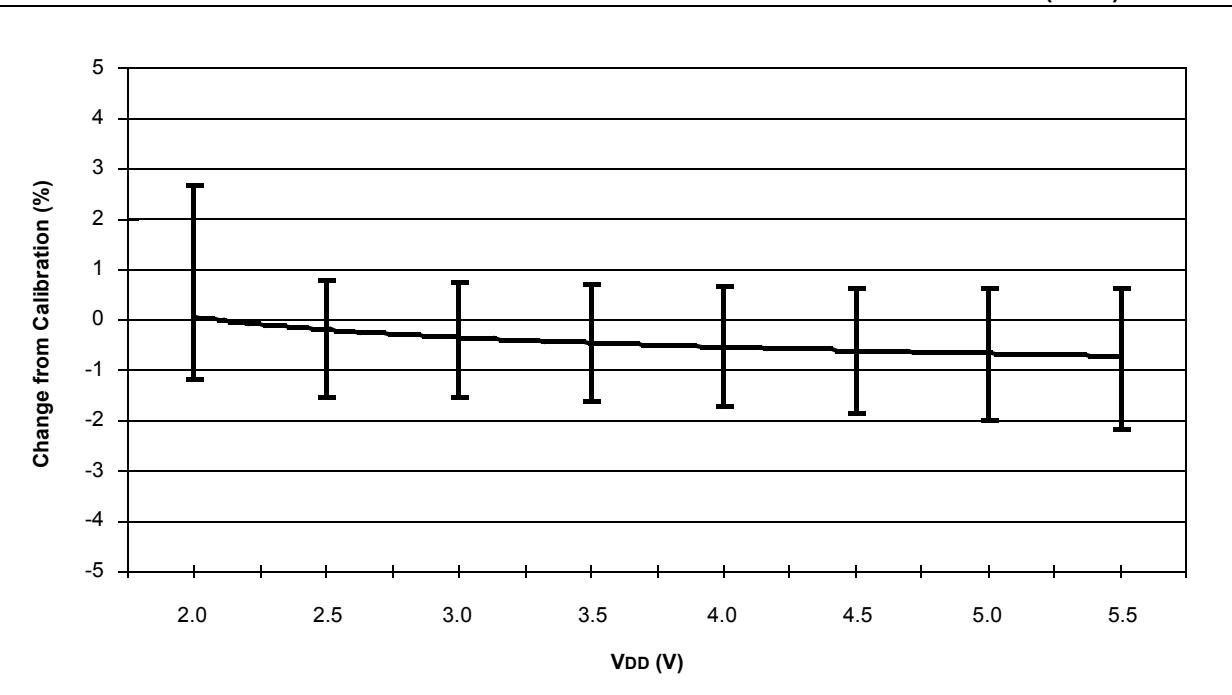
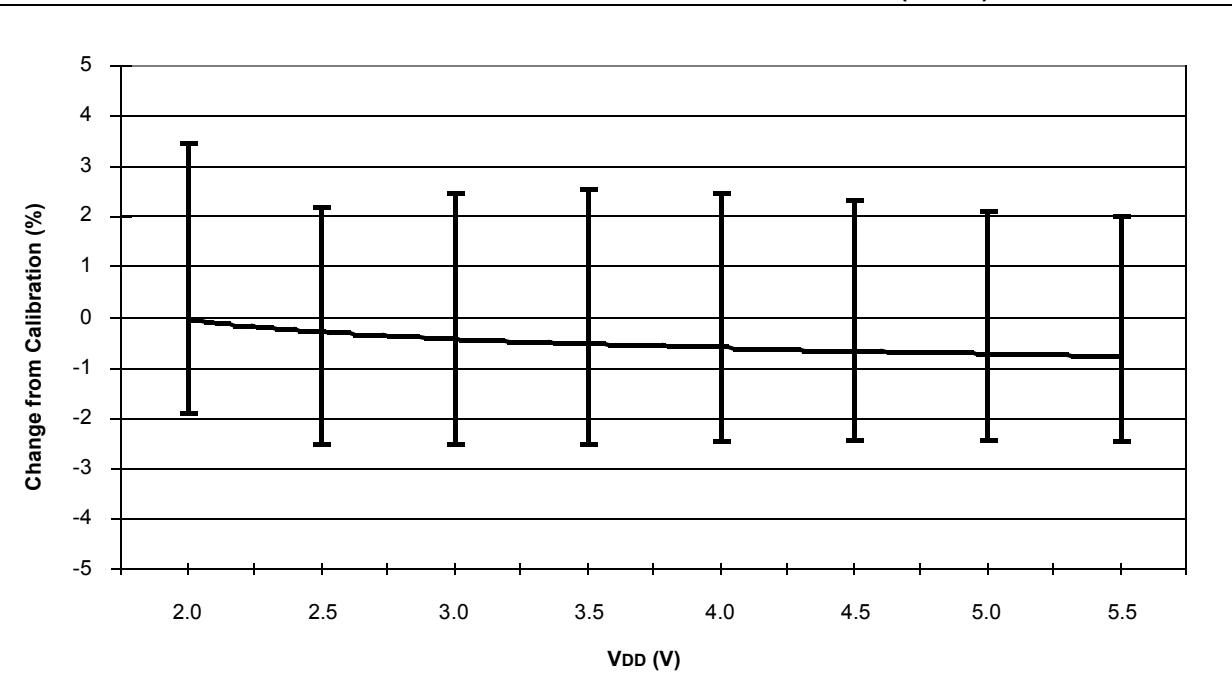


FIGURE 18-41: TYPICAL HFINTOSC FREQUENCY CHANGE vs. V_{DD} (125°C)



PIC16F882/883/884/886/887

FIGURE 18-42: TYPICAL HFINTOSC FREQUENCY CHANGE vs. V_{DD} (-40°C)

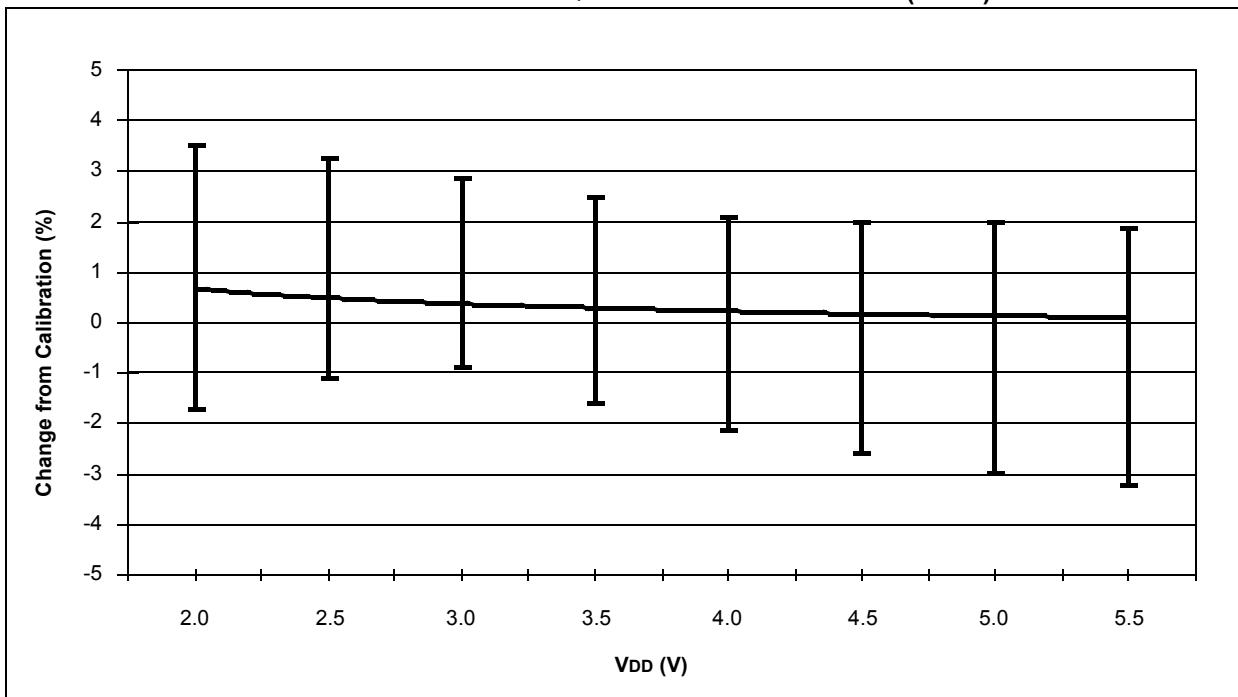


FIGURE 18-43: TYPICAL VP6 REFERENCE VOLTAGE vs. V_{DD} (25°C)

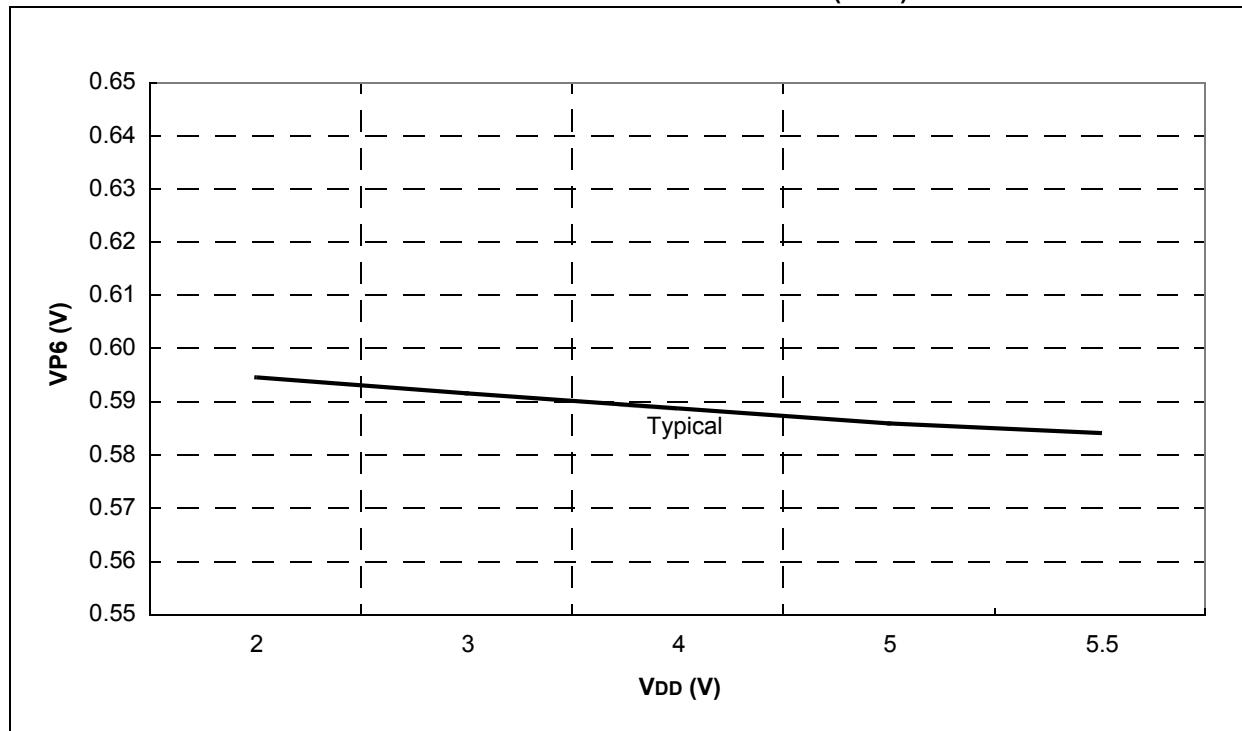


FIGURE 18-44: VP6 DRIFT OVER TEMPERATURE NORMALIZED AT 25°C (VDD 5V)

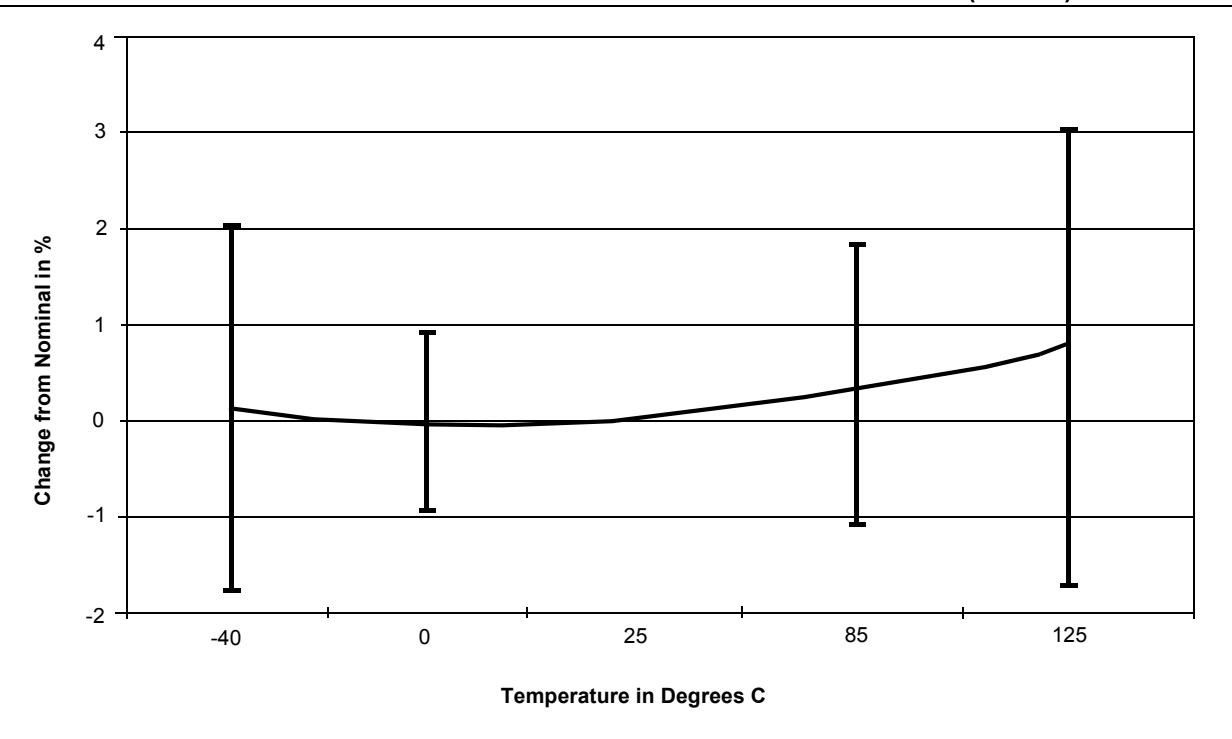
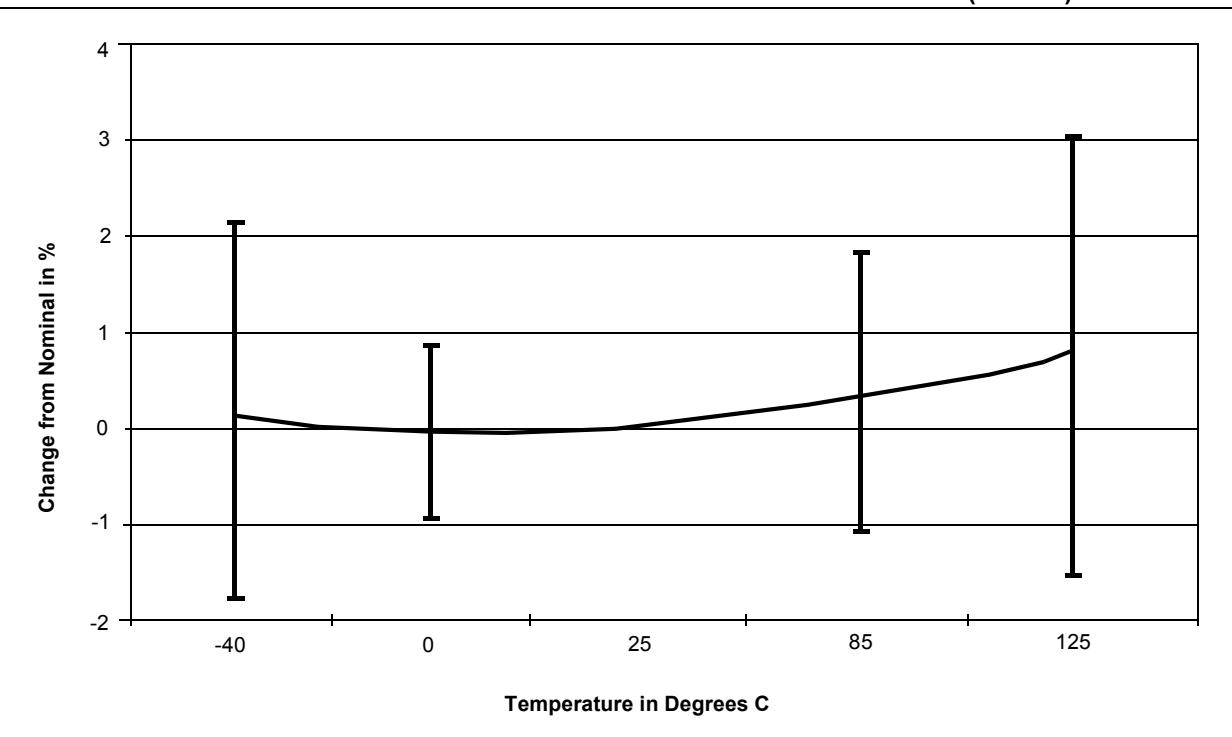


FIGURE 18-45: VP6 DRIFT OVER TEMPERATURE NORMALIZED AT 25°C (VDD 3V)



PIC16F882/883/884/886/887

FIGURE 18-46: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (3V, 25°C)

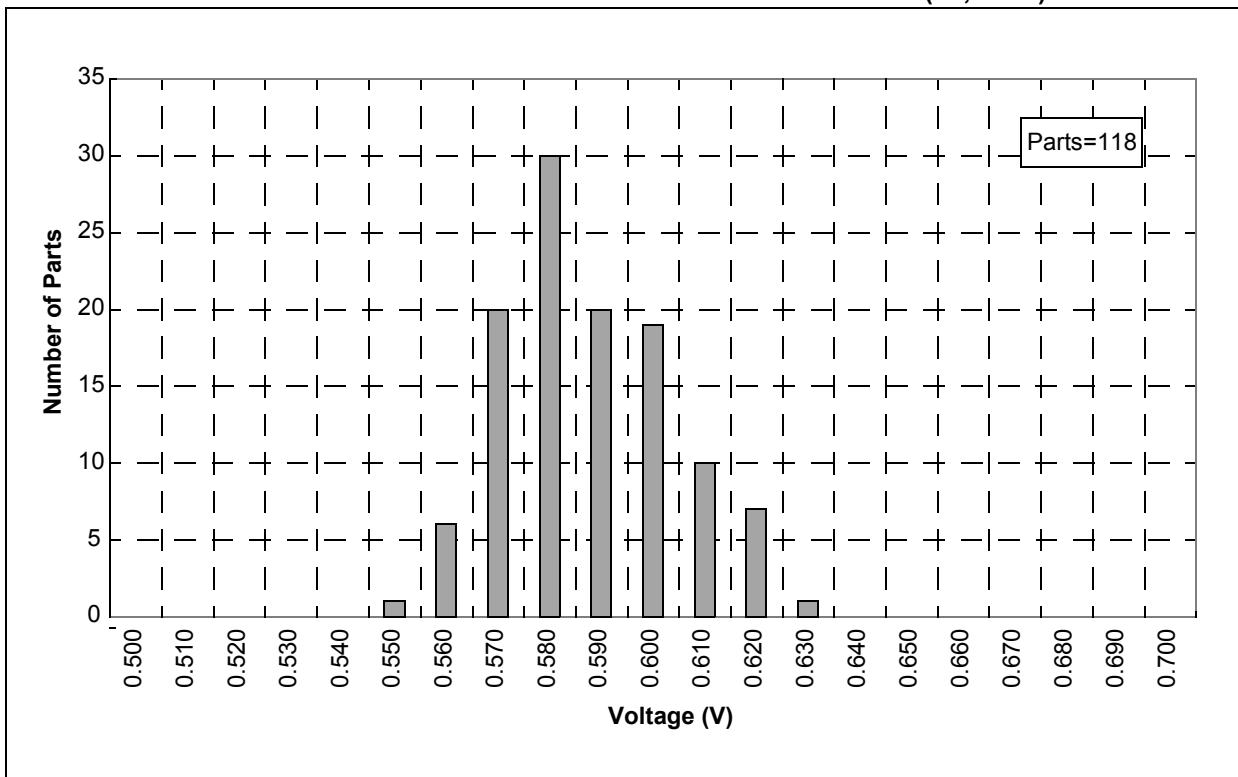


FIGURE 18-47: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (3V, 85°C)

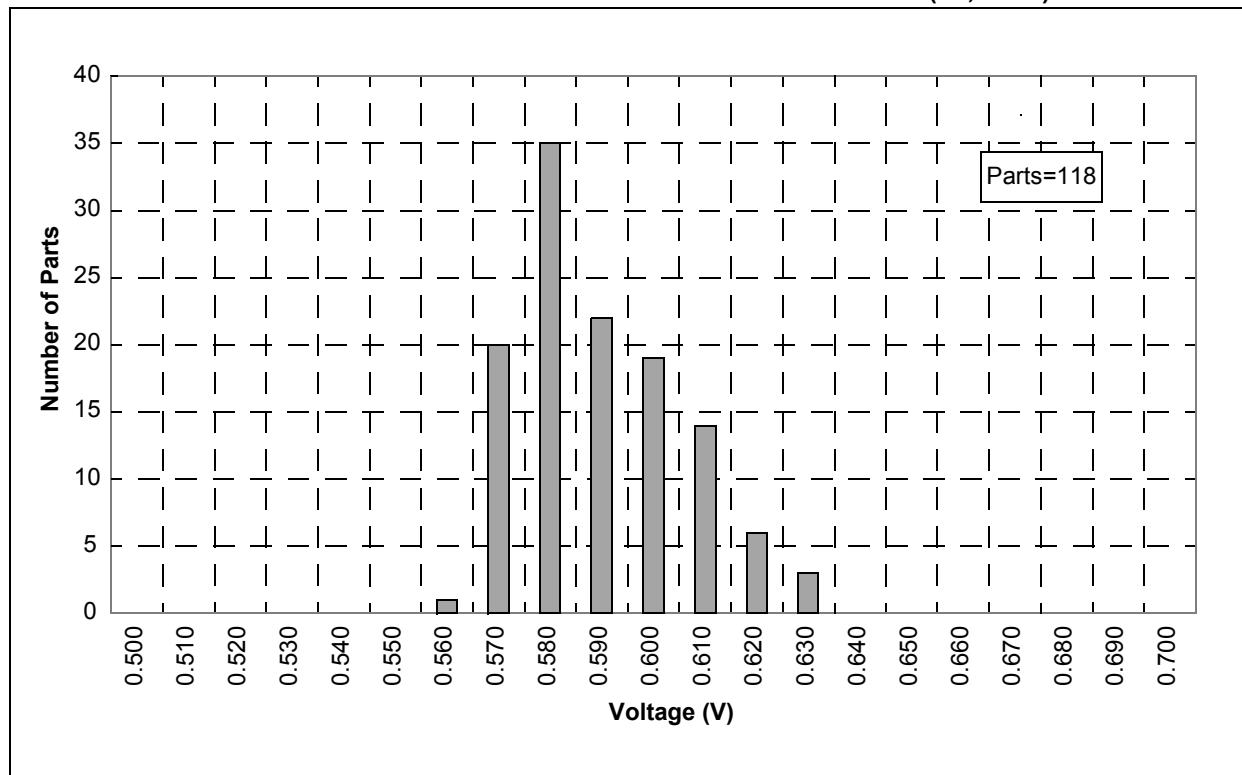


FIGURE 18-48: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (3V, 125°C)

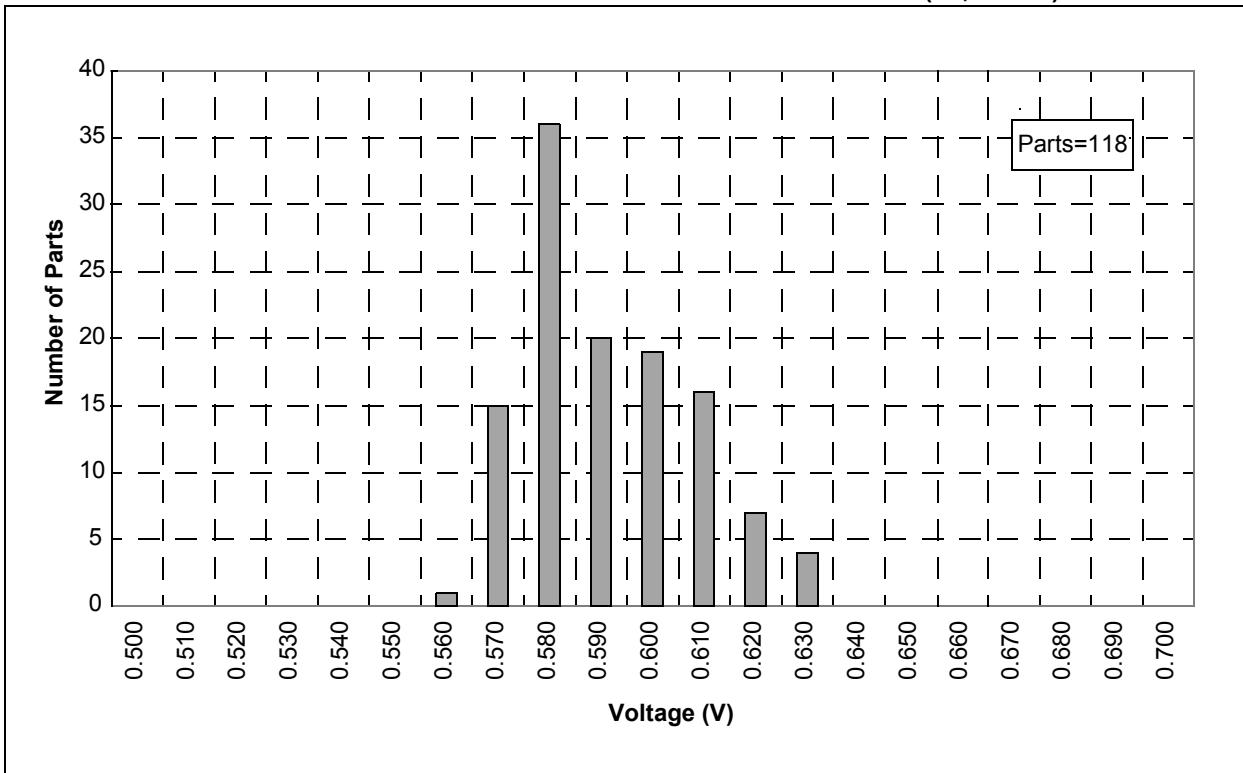
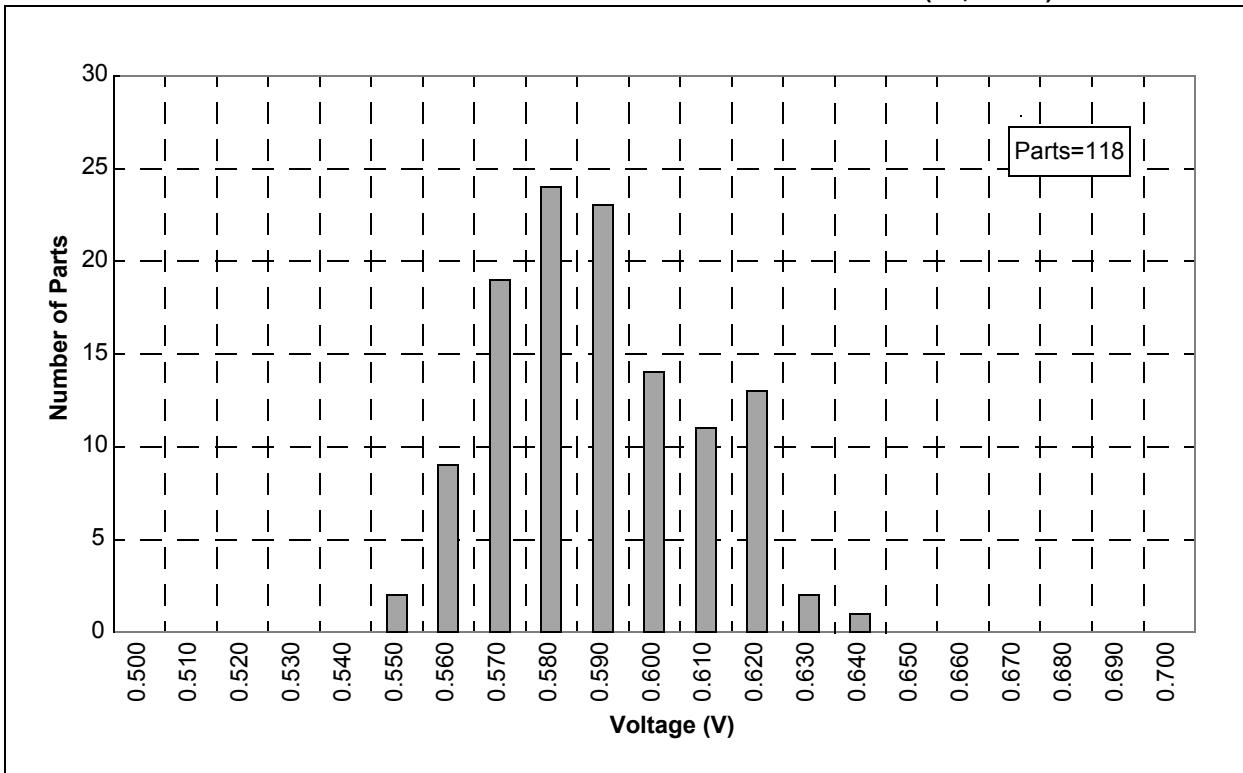


FIGURE 18-49: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (3V, -40°C)



PIC16F882/883/884/886/887

FIGURE 18-50: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (5V, 25°C)

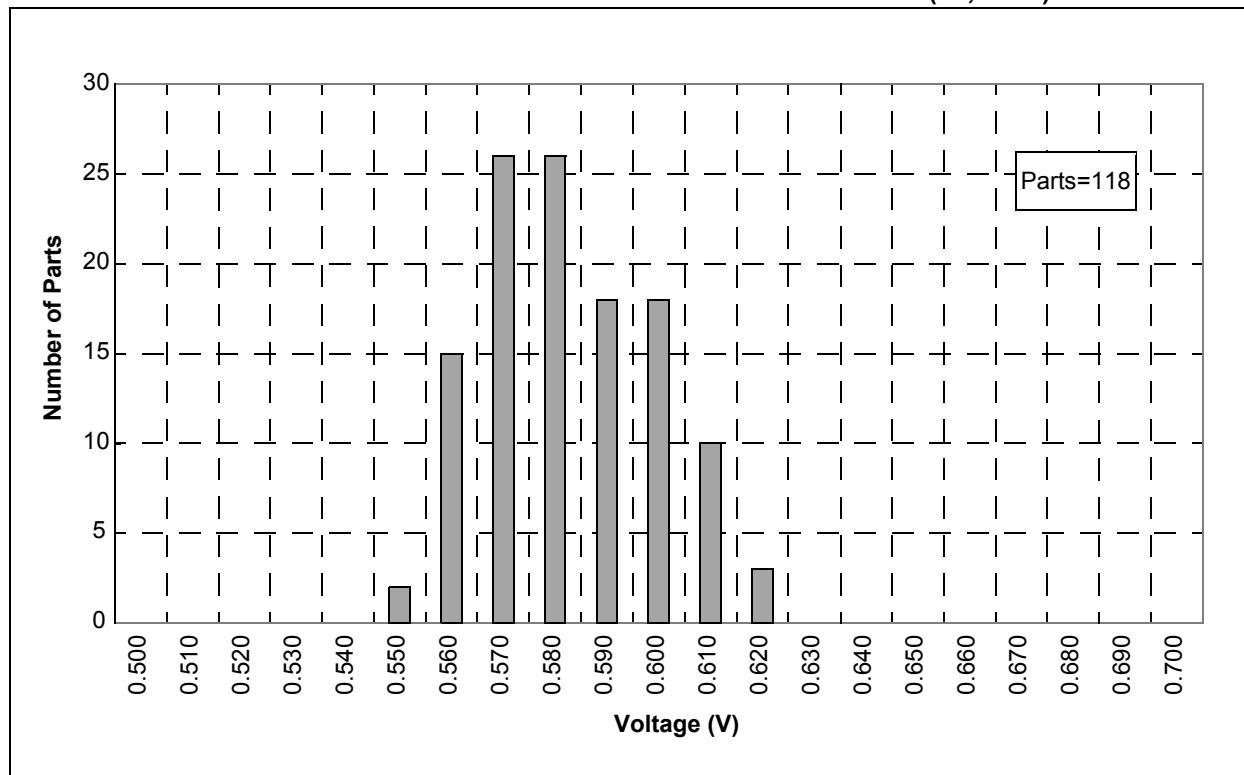


FIGURE 18-51: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (5V, 85°C)

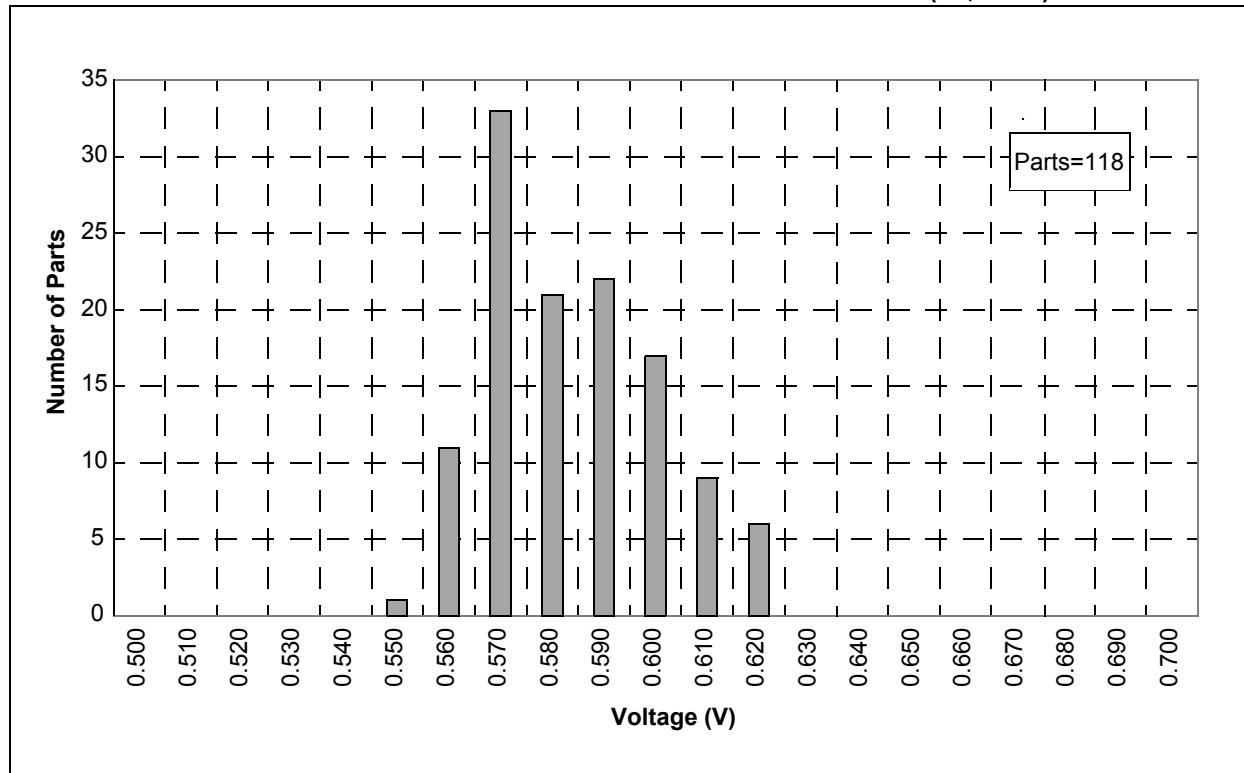


FIGURE 18-52: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (5V, 125°C)

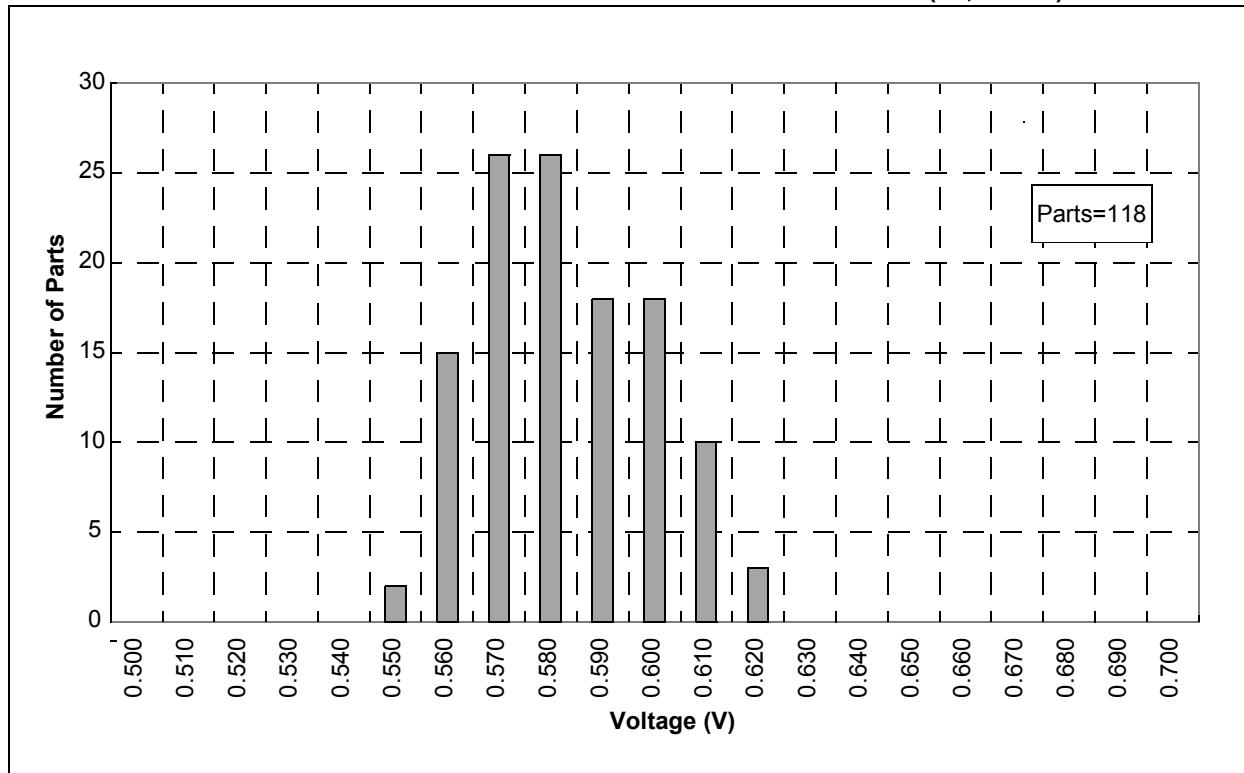
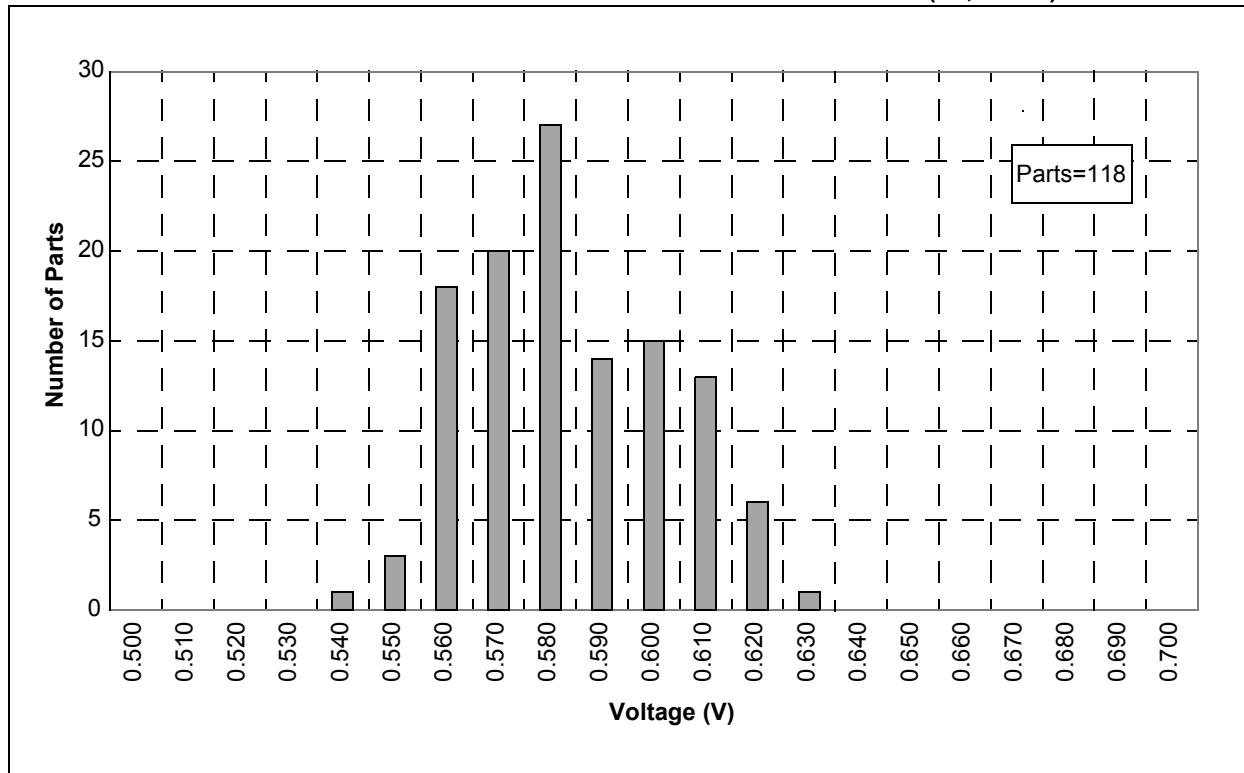


FIGURE 18-53: TYPICAL VP6 REFERENCE VOLTAGE DISTRIBUTION (5V, -40°C)



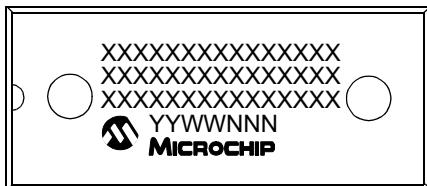
PIC16F882/883/884/886/887

NOTES:

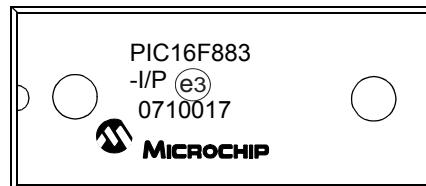
19.0 PACKAGING INFORMATION

19.1 Package Marking Information

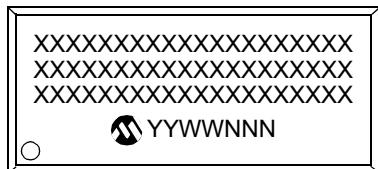
28-Lead PDIP



Example



28-Lead SOIC (7.50 mm)



Example



28-Lead SSOP



Example



28-Lead QFN



Example



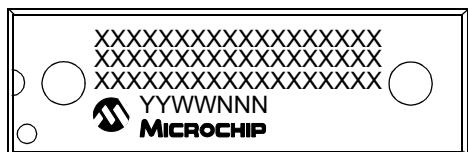
Legend:	XX...X Customer-specific information
Y	Year code (last digit of calendar year)
YY	Year code (last 2 digits of calendar year)
WW	Week code (week of January 1 is week '01')
NNN	Alphanumeric traceability code
(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

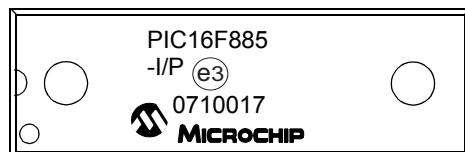
PIC16F882/883/884/886/887

19.1 Package Marking Information (Continued)

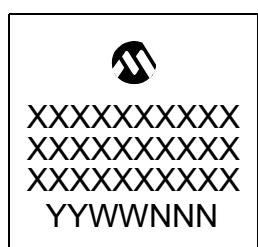
40-Lead PDIP



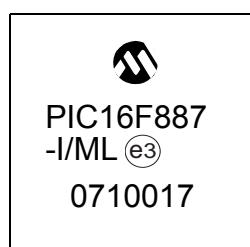
Example



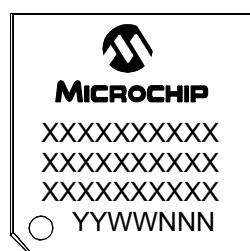
44-Lead QFN



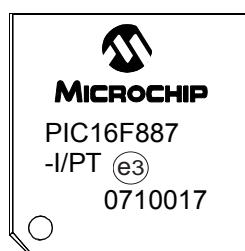
Example



44-Lead TQFP



Example



Legend:	XX...X Customer-specific information
Y	Year code (last digit of calendar year)
YY	Year code (last 2 digits of calendar year)
WW	Week code (week of January 1 is week '01')
NNN	Alphanumeric traceability code
(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

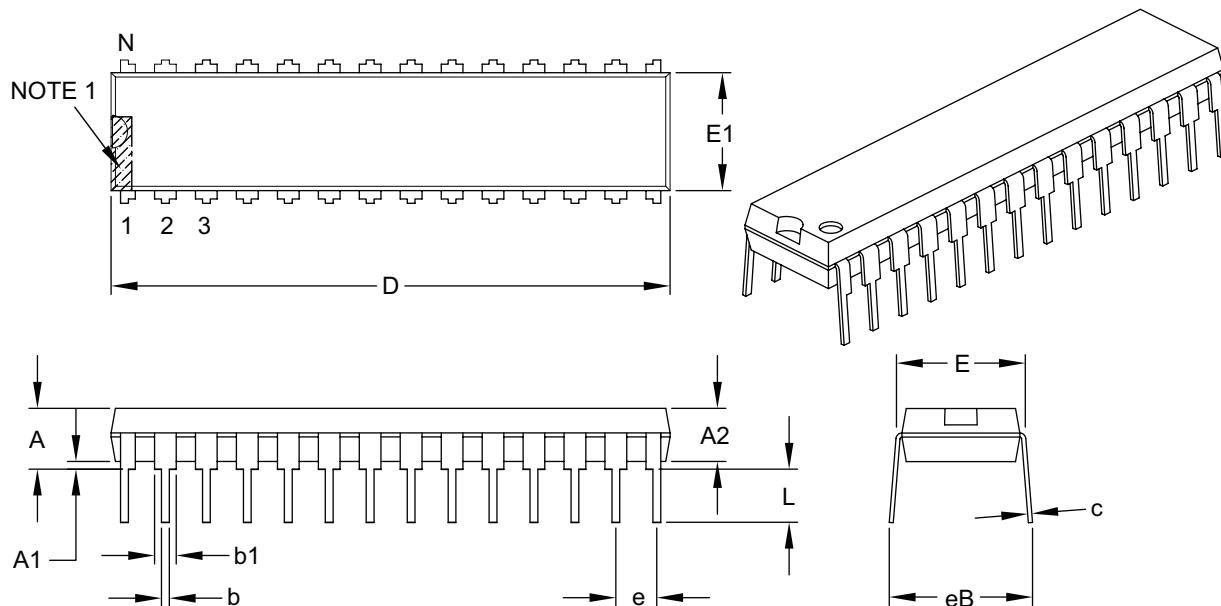
Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

19.2 Package Details

The following sections give the technical details of the packages.

28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	INCHES		
	MIN	NOM	MAX
Number of Pins	N	28	
Pitch	e	.100 BSC	
Top to Seating Plane	A	—	.200
Molded Package Thickness	A2	.120	.135
Base to Seating Plane	A1	.015	—
Shoulder to Shoulder Width	E	.290	.310
Molded Package Width	E1	.240	.285
Overall Length	D	1.345	1.365
Tip to Seating Plane	L	.110	.130
Lead Thickness	c	.008	.010
Upper Lead Width	b1	.040	.050
Lower Lead Width	b	.014	.018
Overall Row Spacing §	eB	—	.430

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

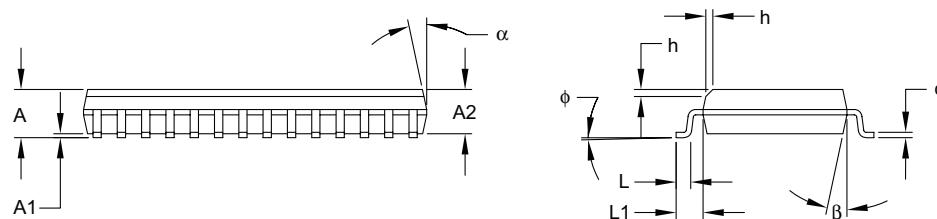
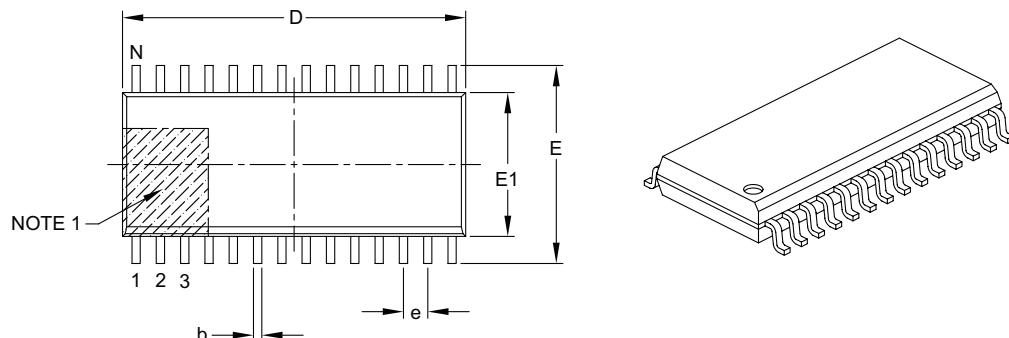
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

PIC16F882/883/884/886/887

28-Lead Plastic Small Outline (SO) – Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins		N		
Pitch		e		
Overall Height		A		
Molded Package Thickness		A2		
Standoff §		A1		
Overall Width		E		
Molded Package Width		E1		
Overall Length		D		
Chamfer (optional)		h		
Foot Length		L		
Footprint		L1		
Foot Angle Top		phi		
Lead Thickness		c		
Lead Width		b		
Mold Draft Angle Top		alpha		
Mold Draft Angle Bottom		beta		

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

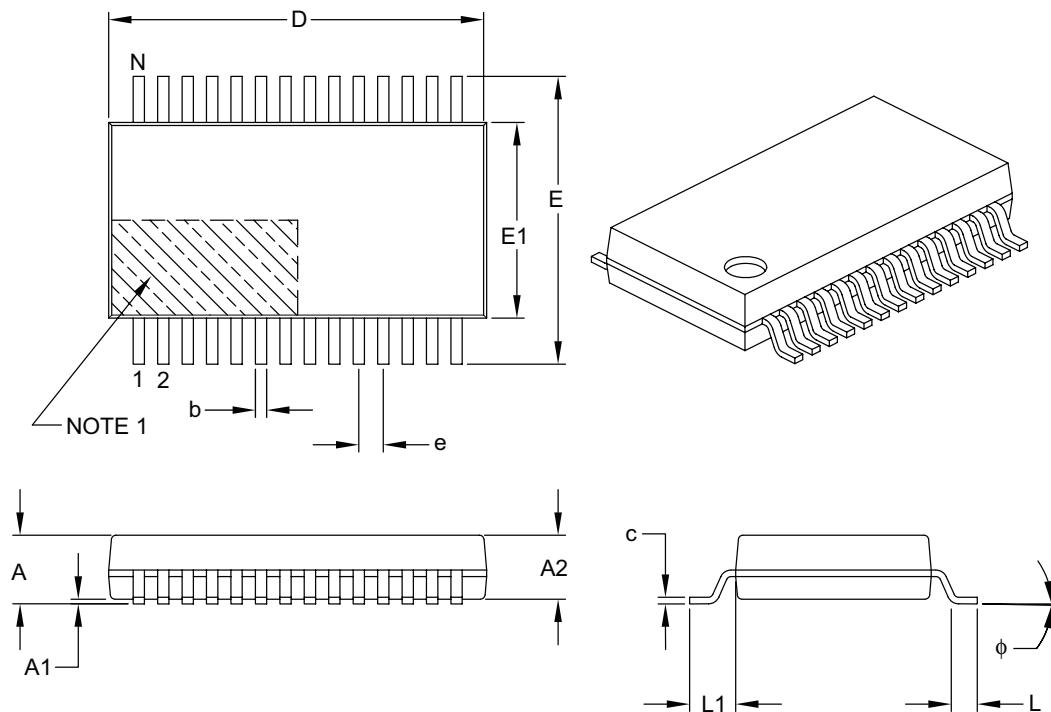
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-052B

PIC16F882/883/884/886/887

28-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



		Units	MILLIMETERS		
Dimension Limits			MIN	NOM	MAX
Number of Pins		N	28		
Pitch		e	0.65 BSC		
Overall Height		A	–		
Molded Package Thickness		A2	1.65	1.75	1.85
Standoff		A1	0.05	–	–
Overall Width		E	7.40	7.80	8.20
Molded Package Width		E1	5.00	5.30	5.60
Overall Length		D	9.90	10.20	10.50
Foot Length		L	0.55	0.75	0.95
Footprint		L1	1.25 REF		
Lead Thickness		c	0.09	–	0.25
Foot Angle		ϕ	0°	4°	8°
Lead Width		b	0.22	–	0.38

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

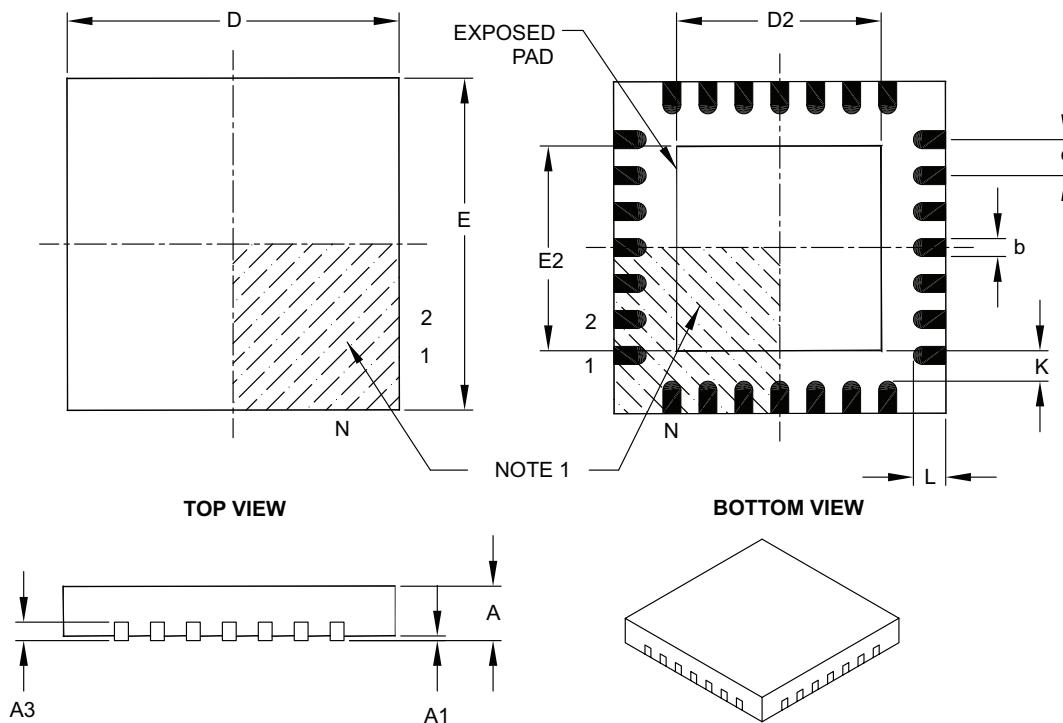
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-073B

PIC16F882/883/884/886/887

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins		N		
Pitch		e		
Overall Height		A		
Standoff		A1		
Contact Thickness		A3		
Overall Width		E		
Exposed Pad Width		E2		
Overall Length		D		
Exposed Pad Length		D2		
Contact Width		b		
Contact Length		L		
Contact-to-Exposed Pad		K		

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

3. Dimensioning and tolerancing per ASME Y14.5M.

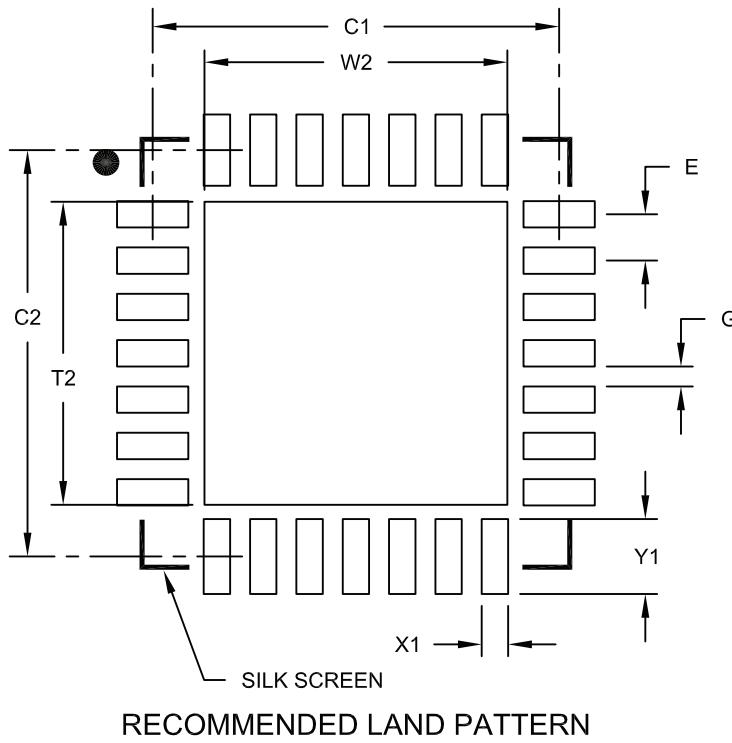
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105B

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch		0.65 BSC		
Optional Center Pad Width	W2			4.25
Optional Center Pad Length	T2			4.25
Contact Pad Spacing	C1		5.70	
Contact Pad Spacing	C2		5.70	
Contact Pad Width (X28)	X1			0.37
Contact Pad Length (X28)	Y1			1.00
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

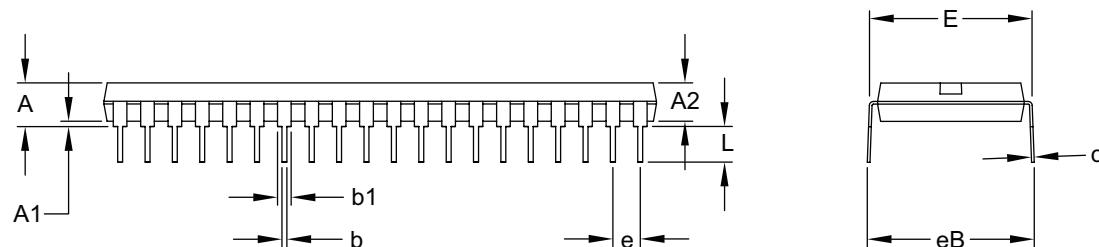
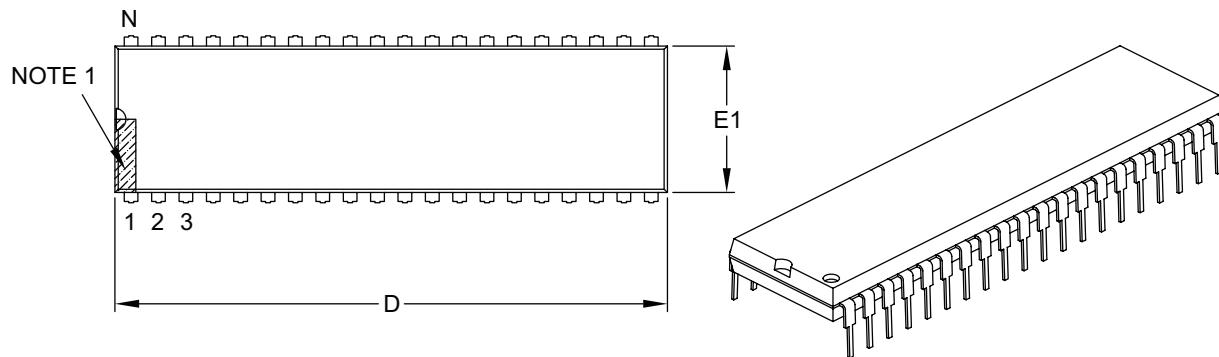
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

PIC16F882/883/884/886/887

40-Lead Plastic Dual In-Line (P) – 600 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N		40	
Pitch	e		.100 BSC	
Top to Seating Plane	A	—	—	.250
Molded Package Thickness	A2	.125	—	.195
Base to Seating Plane	A1	.015	—	—
Shoulder to Shoulder Width	E	.590	—	.625
Molded Package Width	E1	.485	—	.580
Overall Length	D	1.980	—	2.095
Tip to Seating Plane	L	.115	—	.200
Lead Thickness	c	.008	—	.015
Upper Lead Width	b1	.030	—	.070
Lower Lead Width	b	.014	—	.023
Overall Row Spacing §	eB	—	—	.700

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

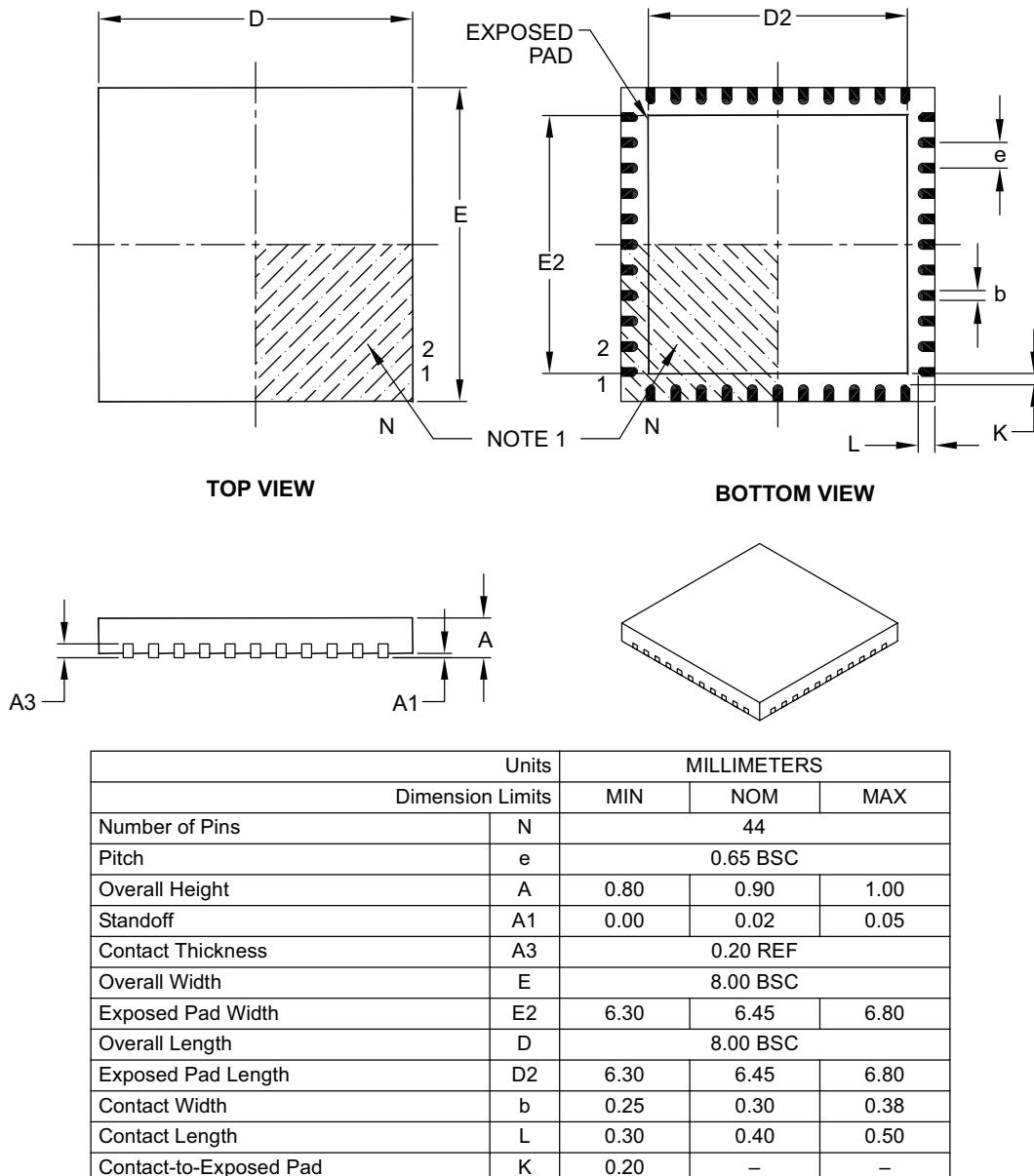
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-016B

PIC16F882/883/884/886/887

44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

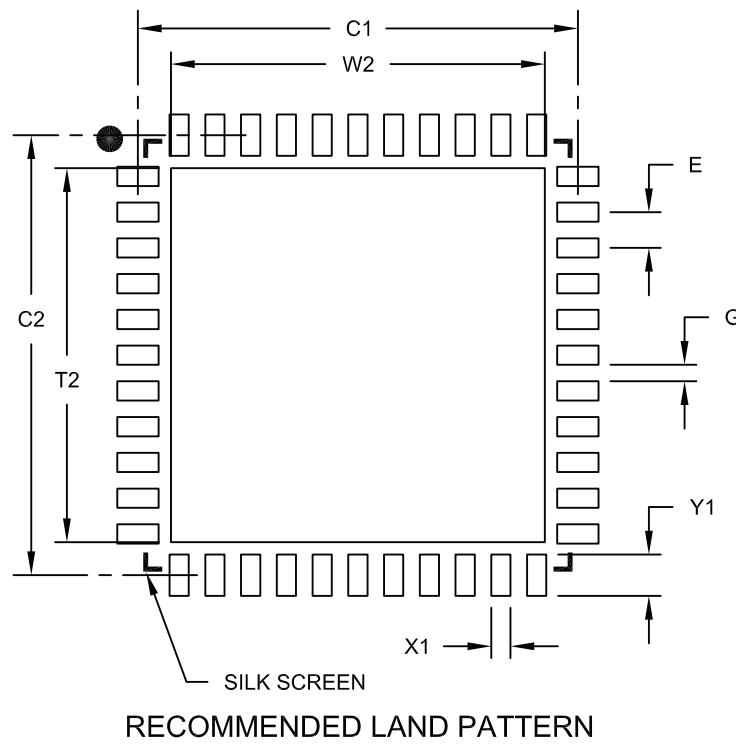
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103B

PIC16F882/883/884/886/887

44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension	Limits	MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			6.80
Optional Center Pad Length	T2			6.80
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.80
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

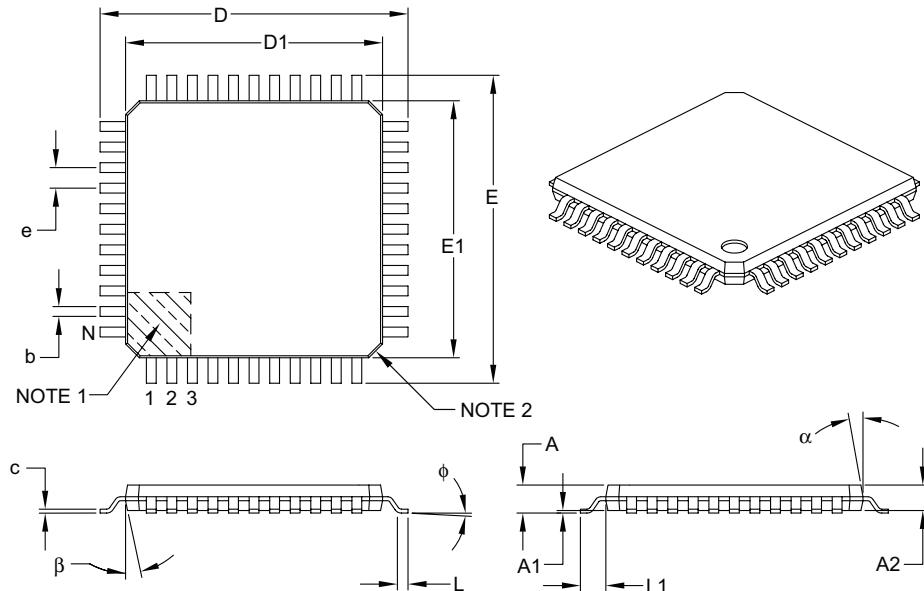
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103A

PIC16F882/883/884/886/887

44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Leads		N		
Lead Pitch		e		
Overall Height		A		
Molded Package Thickness		A2		
Standoff		A1		
Foot Length		L		
Footprint		L1		
Foot Angle		ϕ		
Overall Width		E		
Overall Length		D		
Molded Package Width		E1		
Molded Package Length		D1		
Lead Thickness		c		
Lead Width		b		
Mold Draft Angle Top		α		
Mold Draft Angle Bottom		β		

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Chamfers at corners are optional; size may vary.
3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

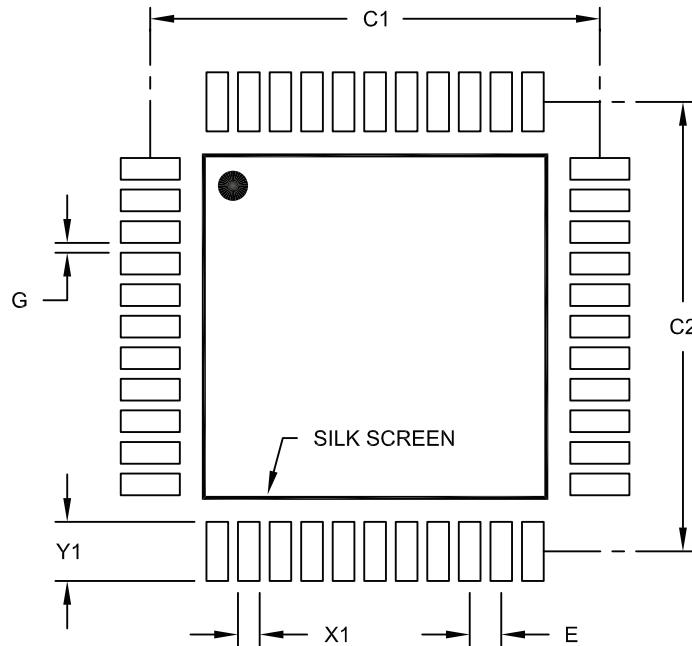
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-076B

PIC16F882/883/884/886/887

44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.80 BSC	
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076A

APPENDIX A: DATA SHEET REVISION HISTORY

Revision A (5/2006)

Initial release of this data sheet.

Revision B (7/2006)

Pin Diagrams (44-Pin QFN drawing); Revised Table 2-1, Addr. 1DH (CCP2CON); Section 3.0, 3.1; Section 3.4.4.6; Table 3; Table 3-1 (ANSEL); Table 3-3 (CCP2CON); Register 3-1; Register 3.2; Register 3-3; Register 3-4; Register 3-9; Register 3-10; Register 3-11; Register 3-12; Register 3-14; Table 3-5 (ANSEL); Figure 3-5; Figure 3-11; Figure 8-2; Figure 8-3; Figure 9-1; Register 9-1; Section 9.1.4; Example 10-4; Figure 11-5; Table 11-5 (P1M); Section 11.5.2; Section 11.5.7, Number 4; Table 11-7 (CCP2CON); Section 12.3.1 (Para. 3); Figure 12-6 (Title); Sections 14.2, 14.3 and 14.4 DC Characteristics (Max); Table 14-4 (OSCCON); Section 14.3 (TMR0); Section 14.3.2 (TMR0).

Revision C

Section 19.0 Packaging Information: Replaced package drawings and added note.
Added PIC16F882 part number.
Replaced PICmicro with PIC.

Revision D

Replaced Package Drawings (Rev. AM); Replaced Development Support Section; Revised Product ID Section.

Revision E (01/2008)

Added Char Data; Removed Preliminary status; Revised Device Table (PIC16F882, I/O); Revised the following: Pin Diagram 44 TQFP, pin 30; Table 5, I/O RA7; Table 1-1, RA1 and RA4; Section 2.2.1; Register 2-3, INTCON; Example 3-1; Section 3.2.2; Example 3-2; Figure 6-1; Section 6.2.2; Section 6.6; Section 8.10.3; Table 9-1; Equation 11-1; Added Figure 11-14 and renumbered remaining Figures; Register 11-3; Register 13-3; Section 14.0; Section 14.1; Section 14.9; Section 14.10; Section 17.0; Updated Package Drawings.

APPENDIX B: MIGRATING FROM OTHER PIC® DEVICES

This discusses some of the issues in migrating from other PIC devices to the PIC16F88X Family of devices.

B.1 PIC16F87X to PIC16F88X

TABLE B-1: FEATURE COMPARISON

Feature	PIC16F87X	PIC16F88X
Max Operating Speed	20 MHz	20 MHz
Max Program Memory (Words)	8192	8192
SRAM (bytes)	368	368
A/D Resolution	10-bit	10-bit
Data EEPROM (Bytes)	256	256
Timers (8/16-bit)	2/1	2/1
Oscillator Modes	4	8
Brown-out Reset	Y	Y (2.1V/4V)
Software Control Option of WDT/BOR	N	Y
Internal Pull-ups	RB<7:4>	RB<7:0>, MCLR
Interrupt-on-change	RB<7:4>	RB<7:0>
Comparator	2	2
References	CVREF	CVREF and VP6
ECCP/CCP	0/2	1/1
Ultra Low-Power Wake-Up	N	Y
Extended WDT	N	Y
INTOSC Frequencies	N	32 kHz-8 MHz
Clock Switching	N	Y
MSSP	Standard	w/Slave Address Mask
USART	AUSART	EUSART
ADC Channels	8	14

Note: This device has been designed to perform to the parameters of its data sheet. It has been tested to an electrical specification designed to determine its conformance with these parameters. Due to process differences in the manufacture of this device, this device may have different performance characteristics than its earlier version. These differences may cause this device to perform differently in your application than the earlier version of this device.

PIC16F882/883/884/886/887

NOTES:

INDEX

A

A/D	
Specifications	263, 264
Absolute Maximum Ratings	245
AC Characteristics	
Industrial and Extended	255
Load Conditions	254
ACKSTAT	198
ACKSTAT Status Flag	198
ADC	99
Acquisition Requirements	107
Associated Registers	109
Block Diagram	99
Calculating Acquisition Time	107
Channel Selection	100
Configuration	100
Configuring Interrupt	103
Conversion Clock	100
Conversion Procedure	103
Internal Sampling Switch (Rss) Impedance	107
Interrupts	101
Operation	102
Operation During Sleep	102
Port Configuration	100
Reference Voltage (VREF)	100
Result Formatting	102
Source Impedance	107
Special Event Trigger	102
Starting an A/D Conversion	102
ADCON0 Register	104
ADCON1 Register	105
ADRESH Register (ADFM = 0)	106
ADRESH Register (ADFM = 1)	106
ADRESL Register (ADFM = 0)	106
ADRESL Register (ADFM = 1)	106
Analog Input Connection Considerations	90
Analog-to-Digital Converter. See ADC	
ANSEL Register	40
ANSELH Register	48
Assembler	
MPASM Assembler	242

B

Baud Rate Generator	195
BAUDCTL Register	162
BF	198
BF Status Flag	198
Block Diagrams	
(CCП) Capture Mode Operation	126
ADC	99
ADC Transfer Function	108
Analog Input Model	90, 108
Auto-Shutdown	141
Baud Rate Generator	195
CCP PWM	128
Clock Source	61
Comparator C1	84
Comparator C1 and ADC Voltage Reference	95
Comparator C2	84
Compare	127
Crystal Operation	64
EUSART Receive	152
EUSART Transmit	151

External RC Mode	65
Fail-Safe Clock Monitor (FSCM)	71
In-Circuit Serial Programming Connections	228
Interrupt Logic	221
MSSP (I ² C Master Mode)	193
MSSP (I ² C Mode)	189
MSSP (SPI Mode)	183
On-Chip Reset Circuit	212
PIC16F883/886	14
PIC16F884/887	15
PWM (Enhanced)	132
RA0 Pins	42
RA1 Pin	43
RA2 Pin	43
RA3 Pin	44
RA4 Pin	44
RA5 Pin	45
RA6 Pin	45
RA7 Pin	46
RB0, RB1, RB2, RB3 Pins	50
RB4, RB5, RB6, RB7 Pins	51
RC0 Pin	54
RC1 Pin	54
RC2 Pin	54
RC3 Pin	55
RC4 Pin	55
RC5 Pin	55
RC6 Pin	56
RC7 Pin	56
RD0, RD1, RD2, RD3, RD4 Pins	58
RD5, RD6, RD7 Pins	58
RE3 Pin	60
Resonator Operation	64
Timer1	76
Timer2	81
TMR0/WDT Prescaler	73
Watchdog Timer (WDT)	224
Break Character (12-bit) Transmit and Receive	169
BRG	195
Brown-out Reset (BOR)	214
Associated	215
Specifications	259
Timing and Characteristics	258
Bus Collision During a Repeated Start Condition	206
Bus Collision During a Start Condition	204
Bus Collision During a Stop Condition	207
C	
C Compilers	
MPLAB C18	242
MPLAB C30	242
Capture Module. See Enhanced Capture/Compare/PWM(ECCP)	
Capture/Compare/PWM (CCP)	
Associated Registers w/ Capture, Compare and Timer1	149
Associated Registers w/ PWM and Timer2	149
Capture Mode	126
CCP Pin Configuration	126
Compare Mode	127
CCP Pin Configuration	127
Software Interrupt Mode	126, 127
Special Event Trigger	127
Timer1 Mode Selection	126, 127

PIC16F882/883/884/886/887

Prescaler.....	126
PWM Mode.....	128
Duty Cycle.....	129
Effects of Reset.....	131
Example PWM Frequencies and Resolutions, 20 MHz	130
Example PWM Frequencies and Resolutions, 8 MHz.....	130
Operation in Sleep Mode	131
Setup for Operation.....	131
System Clock Frequency Changes.....	131
PWM Period.....	129
Setup for PWM Operation.....	131
Timer Resources.....	125
CCP1CON (Enhanced) Register.....	124
CCP2CON Register	125
Clock Accuracy with Asynchronous Operation	160
Clock Sources	
External Modes	63
EC	63
HS	64
LP	64
OST.....	63
RC.....	65
XT	64
Internal Modes	65
Frequency Selection	67
HFINTOSC.....	65
HFINTOSC/LFINTOSC Switch Timing	67
INTOSC	65
INTOSCIOS	65
LFINTOSC	67
Clock Switching.....	69
CM1CON0 Register	88
CM2CON0 Register	89
CM2CON1 Register	91
Code Examples	
A/D Conversion	103
Assigning Prescaler to Timer0	74
Assigning Prescaler to WDT	74
Changing Between Capture Prescalers	126
Indirect Addressing	37
Initializing PORTA.....	39
Initializing PORTB	47
Initializing PORTC	53
Initializing PORTD	57
Initializing PORTE	59
Loading the SSPBUF Register	184
Saving STATUS and W Registers in RAM	223
Ultra Low-Power Wake-up Initialization	41
Write Verify	120
Writing to Flash Program Memory	119
Code Protection	227
Comparator	
C2OUT as T1 Gate	77, 91
Effects of a Reset.....	87
Operation	83
Operation During Sleep	87
Response Time	85
Specifications	262
Synchronizing COUT w/Timer1	91
Comparator Module	83
Associated Registers	97
C1 Output State Versus Input Conditions	85
Comparator Voltage Reference (CVREF)	
Response Time.....	85
Comparator Voltage Reference (CVREF).....	94
Effects of a Reset	87
Specifications	262
Compare Module. See Enhanced Capture/ Compare/PWM (ECCP)	
CONFIG1 Register	210
CONFIG2 Register	211
Configuration Bits	210
CPU Features	209
Customer Change Notification Service	323
Customer Notification Service	323
Customer Support.....	323
D	
Data EEPROM Memory.....	111
Associated Registers	121
Code Protection	120
Reading	114
Writing	114
Data Memory	22
DC Characteristics	
Extended	250
Industrial	249
Industrial and Extended	247, 248, 251
Development Support	241
Device Overview	13
E	
ECCP. See Enhanced Capture/Compare/PWM	
ECCPAS Register.....	142
EEADR Register	112
EEADR Registers	111
EEADRH Registers	111
EECON1 Register	111, 113
EECON2 Register	111
EEDAT Register	112
EEDATH Register	112
EEPROM Data Memory	
Avoiding Spurious Write	120
Write Verify	120
Effects of Reset	
PWM mode	131
Electrical Specifications	245
Enhanced Capture/Compare/PWM	123
Enhanced Capture/Compare/PWM (ECCP)	
Enhanced PWM Mode	132
Auto-Restart	143
Auto-shutdown	141
Direction Change in Full-Bridge Output Mode	138
Full-Bridge Application	136
Full-Bridge Mode	136
Half-Bridge Application	135
Half-Bridge Application Examples	144
Half-Bridge Mode	135
Output Relationships (Active-High and Active-Low)	133
Output Relationships Diagram	134
Programmable Dead Band Delay	144
Shoot-through Current	144
Start-up Considerations	140
Specifications	261
Timer Resources	124
Enhanced Universal Synchronous Asynchronous Receiver Transmitter (EUSART)	151
Errata	12

PIC16F882/883/884/886/887

EUSART	151	BRG Block Diagram	195
Associated Registers		BRG Reset Due to SDA Arbitration During	
Baud Rate Generator.....	163	Start Condition.....	205
Asynchronous Mode	153	BRG Timing	195
12-bit Break Transmit and Receive	169	Bus Collision	
Associated Registers		Acknowledge	203
Receive.....	159	Repeated Start Condition	206
Transmit.....	155	Repeated Start Condition Timing (Case1).....	206
Auto-Wake-up on Break	168	Repeated Start Condition Timing (Case2).....	206
Baud Rate Generator (BRG)	163	Start Condition.....	204
Clock Accuracy	160	Start Condition Timing	204, 205
Receiver.....	156	Stop Condition	207
Setting up 9-bit Mode with Address Detect.....	158	Stop Condition Timing (Case 1)	207
Transmitter.....	153	Stop Condition Timing (Case 2)	207
Baud Rate Generator (BRG)		Bus Collision timing	203
Auto Baud Rate Detect.....	167	Clock Arbitration	202
Baud Rate Error, Calculating	163	Clock Arbitration Timing (Master Transmit)	202
Baud Rates, Asynchronous Modes	164	Effect of a Reset	202
Formulas.....	163	General Call Address Support.....	192
High Baud Rate Select (BRGH Bit)	163	Master Mode.....	193
Synchronous Master Mode	171, 175	Master Mode 7-bit Reception Timing.....	200
Associated Registers		Master Mode Operation.....	194
Receive.....	174	Master Mode Start Condition Timing	196
Transmit.....	172	Master Mode Support	193
Reception.....	173	Master Mode Transmission	198
Requirements, Synchronous Receive	266	Master Mode Transmit Sequence	194
Requirements, Synchronous Transmission	266	Multi-Master Mode.....	203
Timing Diagram, Synchronous Receive	266	Repeat Start Condition Timing Waveform	197
Timing Diagram, Synchronous Transmission	266	Sleep Operation.....	202
Transmission	171	Stop Condition Receive or Transmit Timing	202
Synchronous Slave Mode		Stop Condition Timing	201
Associated Registers		Waveforms for 7-bit Reception	191
Receive.....	176	Waveforms for 7-bit Transmission	191
Transmit.....	175	ID Locations	227
Reception.....	176	In-Circuit Debugger.....	229
Transmission	175	In-Circuit Serial Programming (ICSP)	227
F		Indirect Addressing, INDF and FSR registers.....	37
Fail-Safe Clock Monitor.....	71	Instruction Format.....	231
Fail-Safe Condition Clearing	71	Instruction Set	231
Fail-Safe Detection	71	ADDLW	233
Fail-Safe Operation	71	ADDWF	233
Reset or Wake-up from Sleep.....	71	ANDLW	233
Firmware Instructions.....	231	ANDWF	233
Flash Program Memory	111	BCF	233
Writing	117	BSF	233
Fuses. See Configuration Bits		BTFS.....	233
G		BTFS.....	234
General Call Address Support	192	CALL	234
General Purpose Register File.....	22	CLRF	234
I		CLRW	234
I ² C (MSSP Module)		CLRWDT	234
ACK Pulse.....	189, 190	COMF	234
Addressing	190	DECFL	234
Read/Write Bit Information (R/W Bit)	190	DECFSZ	235
Reception.....	190	GOTO	235
Serial Clock (RC3/SCK/SCL).....	190	INCF	235
Slave Mode	189	INCFSZ	235
Transmission.....	190	IORLW	235
I ² C Master Mode Reception	198	IORWF	235
I ² C Master Mode Repeated Start Condition Timing.....	197	MOVFL	236
I ² C Module		MOVLW	236
Acknowledge Sequence Timing.....	201	MOVWF	236
Baud Rate Generator.....	195	NOP	236
		RETFIE	237
		RETLW	237

PIC16F882/883/884/886/887

RETURN	237
RLF	238
RRF	238
SLEEP	238
SUBLW	238
SUBWF	239
SWAPF	239
XORLW	239
XORWF	239
Summary Table	232
INTCON Register	31
Inter-Integrated Circuit. See I ² C	
Internal Oscillator Block	256
INTOSC	
Specifications	257
Internal Sampling Switch (Rss) Impedance	107
Internet Address	323
Interrupts	220
ADC	103
Associated Registers	222
Context Saving	223
Interrupt-on-Change	47
PORTB Interrupt-on-Change	221
RB0/INT	220
Timer0	221
TMR1	78
INTOSC	
Specifications	256
INTOSC Specifications	256, 257
IOCB Register	49
L	
Load Conditions	254
M	
Master Mode	193
Master Mode Support	193
Master Synchronous Serial Port. See MSSP	
MCLR	213
Internal	213
Memory Organization	21
Data	22
Program	21
Microchip Internet Web Site	323
Migrating from other PICmicro Devices	313
MPLAB ASM30 Assembler, Linker, Librarian	242
MPLAB ICD 2 In-Circuit Debugger	243
MPLAB ICE 2000 High-Performance Universal In-Circuit Emulator	243
MPLAB Integrated Development Environment Software	241
MPLAB PM3 Device Programmer	243
MPLAB REAL ICE In-Circuit Emulator System	243
MPLINK Object Linker/MPLIB Object Librarian	242
MSSP	179
Block Diagram (SPI Mode)	183
I ² C Mode. See I ² C	
SPI Mode	183
SPI Mode. See SPI	
MSSP Module	
Control Registers	179
I ² C Operation	189
SPI Master Mode	185
SPI Slave Mode	186
Multi-Master Communication, Bus Collision and Bus Arbitration	203
Multi-Master Mode	203
O	
OPCODE Field Descriptions	231
OPTION Register	30
OPTION_REG Register	75
OSCCON Register	62
Oscillator	
Associated Registers	72, 80
Oscillator Module	61
EC	61
HFINTOSC	61
HS	61
INTOSC	61
INTOSCIO	61
LFINTOSC	61
LP	61
RC	61
RCIO	61
XT	61
Oscillator Parameters	256
Oscillator Specifications	255
Oscillator Start-up Timer (OST) Specifications	259
Oscillator Switching	
Fail-Safe Clock Monitor	71
Two-Speed Clock Start-up	69
OSCTUNE Register	66
P	
P1A/P1B/P1C/P1D. See Enhanced Capture/Compare/PWM (ECCP)	132
Packaging	301
Marking	301, 302
PDIP Details	303
PCL and PCLATH	37
Stack	37
PCON Register	36, 215
PICSTART Plus Development Programmer	244
PIE1 Register	32
PIE2 Register	33
Pin Diagram	
PIC16F883/886, 28-pin (PDIP, SOIC, SSOP)	3
PIC16F883/886, 28-pin (QFN)	4
PIC16F884/887, 40-Pin (PDIP)	6
PIC16F884/887, 44-pin (QFN)	8
PIC16F884/887, 44-pin (TQFP)	10
Pinout Descriptions	
PIC16F883/886	16
PIC16F884/887	18
PIR1 Register	34
PIR2 Register	35
PORTA	39
Additional Pin Functions	40
ANSEL Register	40
Ultra Low-Power Wake-up	40, 41
Associated Registers	46
Pin Descriptions and Diagrams	42
RA0	42
RA1	43
RA2	43
RA3	44
RA4	44
RA5	45
RA6	45
RA7	46
Specifications	257

PIC16F882/883/884/886/887

PORTE Register	39
PORTE.....	47
Additional Pin Functions	47
ANSELH Register	47
Weak Pull-up	47
Associated Registers	52
Interrupt-on-Change.....	47
P1B/P1C/P1D. See Enhanced Capture/	
Compare/PWM+ (ECCP+).....	47
Pin Descriptions and Diagrams.....	50
RB0.....	50
RB1.....	50
RB2.....	50
RB3.....	50
RB4.....	51
RB5.....	51
RB6.....	51
RB7.....	51
PORTB Register	48
PORTC	53
Associated Registers	56
P1A. See Enhanced Capture/Compare/	
PWM+ (ECCP+)	53
RC0.....	54
RC1.....	54
RC2.....	54
RC3.....	55
RC3 Pin.....	190
RC4.....	55
RC5.....	55
RC6.....	56
RC7.....	56
Specifications.....	257
PORTC Register	53
PORTD	57
Associated Registers	58
P1B/P1C/P1D. See Enhanced Capture/	
Compare/PWM+ (ECCP+).....	57
RD0, RD1, RD2, RD3, RD4	58
RD5.....	58
RD6.....	58
RD7.....	58
PORTD Register	57
PORTE.....	59
Associated Registers	60
RE0.....	60
RE1.....	60
RE2.....	60
RE3.....	60
PORTE Register	59
Power-Down Mode (Sleep).....	226
Power-on Reset (POR).....	213
Power-up Timer (PWRT).....	213
Specifications.....	259
Precision Internal Oscillator Parameters.....	257
Prescaler	
Shared WDT/Timer0	74
Switching Prescaler Assignment.....	74
Program Memory	21
Map and Stack	21
Map and Stack (PIC16F883/884)	21
Map and Stack (PIC16F886/887)	21
Programming, Device Instructions	231
PSTRCON Register	146
Pulse Steering.....	146
PWM (ECCP Module)	
Pulse Steering	146
Steering Synchronization.....	148
PWM Mode. See Enhanced Capture/Compare/PWM.....	132
PWM1CON Register.....	145
R	
RCREG.....	158
RCSTA Register	161
Reader Response.....	324
Read-Modify-Write Operations	231
Register	
RCREG Register	167
Registers	
ADCON0 (ADC Control 0)	104
ADCON1 (ADC Control 1)	105
ADRESH (ADC Result High) with ADFM = 0)	106
ADRESH (ADC Result High) with ADFM = 1)	106
ADRESL (ADC Result Low) with ADFM = 0)	106
ADRESL (ADC Result Low) with ADFM = 1)	106
ANSEL (Analog Select)	40
ANSELH (Analog Select High)	48
BAUDCTL (Baud Rate Control).....	162
CCP1CON (Enhanced CCP1 Control)	124
CCP2CON (CCP2 Control)	125
CM1CON0 (C1 Control)	88
CM2CON0 (C2 Control)	89
CM2CON1 (C2 Control)	91
CONFIG1 (Configuration Word Register 1).....	210
CONFIG2 (Configuration Word Register 2).....	211
ECCPAS (Enhanced CCP Auto-shutdown Control)	142
EEADR (EEPROM Address)	112
EECON1 (EEPROM Control 1)	113
EEDAT (EEPROM Data)	112
EEDATH (EEPROM Data)	112
INTCON (Interrupt Control)	31
IOCB (Interrupt-on-Change PORTB).....	49
OPTION_REG (OPTION)	30, 75
OSCCON (Oscillator Control)	62
OSCTUNE (Oscillator Tuning)	66
PCON (Power Control Register)	36
PCON (Power Control)	215
PIE1 (Peripheral Interrupt Enable 1)	32
PIE2 (Peripheral Interrupt Enable 2)	33
PIR1 (Peripheral Interrupt Register 1)	34
PIR2 (Peripheral Interrupt Request 2)	35
PORTA	39
PORTB	48
PORTC	53
PORTD	57
PORTE	59
PSTRCON (Pulse Steering Control)	146
PWM1CON (Enhanced PWM Control)	145
RCSTA (Receive Status and Control)	161
Reset Values	217
Reset Values (special registers)	219
Special Function Register Map	
PIC16F883/884	23, 24
PIC16F886/887	25
Special Function Registers	22
Special Register Summary	
Bank 0	26
Bank 1	27
Bank 2	28
Bank 3	28
SRCON (SR Latch Control)	93

PIC16F882/883/884/886/887

SSPCON (MSSP Control 1).....	181
SSPCON2 (SSP Control 2).....	182
SSPMASK (SSP Mask).....	208
SSPSTAT (SSP Status).....	180
STATUS.....	29
T1CON.....	79
T2CON.....	82
TRISA (Tri-State PORTA).....	39
TRISB (Tri-State PORTB).....	48
TRISC (Tri-State PORTC).....	53
TRISD (Tri-State PORTD).....	57
TRISE (Tri-State PORTE).....	59
TXSTA (Transmit Status and Control).....	160
VRCON (Voltage Reference Control).....	97
WDTCON (Watchdog Timer Control).....	225
WPUB (Weak Pull-up PORTB).....	49
Reset.....	212
Revision History	313
S	
SCK.....	183
SDI.....	183
SDO.....	183
Serial Clock, SCK.....	183
Serial Data In, SDI	183
Serial Data Out, SDO.....	183
Serial Peripheral Interface. See SPI	
Shoot-through Current	144
Slave Mode General Call Address Sequence	192
Slave Select Synchronization.....	186
Slave Select, SS	183
Sleep.....	226
Wake-up.....	226
Wake-up Using Interrupts	226
Software Simulator (MPLAB SIM).....	242
SPBRG.....	163
SPBRGH.....	163
Special Event Trigger.....	102
Special Function Registers	22
SPI	
Master Mode	185
Serial Clock	183
Serial Data In	183
Serial Data Out	183
Slave Select	183
SPI clock	185
SPI Mode	183
SPI Bus Modes	188
SPI Mode	
Associated Registers with SPI Operation	188
Bus Mode Compatibility	188
Effects of a Reset.....	188
Enabling SPI I/O	184
Operation	183
Sleep Operation	188
SPI Module	
Slave Mode	186
Slave Select Synchronization	186
Slave Synchronization Timing.....	186
Slave Timing with CKE = 0	187
Slave Timing with CKE = 1	187
SRCON Register.....	93
SS	183
SSP	
SSPBUF.....	185
SSPSR.....	185
SSPCON Register	181
SSPCON2 Register	182
SSPMASK Register	208
SSPOV	198
SSPOV Status Flag	198
SSPSTAT Register	180
R/W Bit	190
STATUS Register	29
T	
T1CON Register	79
T2CON Register	82
Thermal Considerations.....	253
Time-out Sequence	215
Timer0.....	73
Associated Registers	75
External Clock	74
Interrupt	75
Operation	73, 76
Specifications	260
T0CKI	74
Timer1.....	76
Associated Registers	80
Asynchronous Counter Mode	77
Reading and Writing	77
Interrupt	78
Modes of Operation	76
Operation During Sleep	78
Oscillator	77
Prescaler	77
Specifications	260
Timer1 Gate	
Inverting Gate	77
Selecting Source	77, 91
SR Latch	92
Synchronizing COUT w/Timer1	91
TMR1H Register	76
TMR1L Register	76
Timer2	
Associated Registers	82
Timers	
Timer1	
T1CON	79
Timer2	
T2CON	82
Timing Diagrams	
A/D Conversion	265
A/D Conversion (Sleep Mode)	265
Acknowledge Sequence Timing	201
Asynchronous Reception	158
Asynchronous Transmission	154
Asynchronous Transmission (Back to Back)	154
Auto Wake-up Bit (WUE) During Normal Operation	168
Auto Wake-up Bit (WUE) During Sleep	169
Automatic Baud Rate Calibration	167
Baud Rate Generator with Clock Arbitration	195
BRG Reset Due to SDA Arbitration	205
Brown-out Reset (BOR)	258
Brown-out Reset Situations	214
Bus Collision	
Start Condition Timing	204
Bus Collision During a Repeated Start Condition (Case 1)	206
Bus Collision During a Repeated Start Condition (Case2)	206
Bus Collision During a Start Condition (SCL = 0)	205

Bus Collision During a Stop Condition	207
Bus Collision for Transmit and Acknowledge.....	203
CLKOUT and I/O.....	257
Clock Timing	255
Comparator Output	83
Enhanced Capture/Compare/PWM (ECCP).....	261
EUSART Synchronous Receive (Master/Slave).....	266
EUSART Synchronous Transmission (Master/Slave)	266
Fail-Safe Clock Monitor (FSCM).....	72
Full-Bridge PWM Output.....	137
Half-Bridge PWM Output	135, 144
I ² C Bus Data	270
I ² C Bus Start/Stop Bits.....	269
I ² C Master Mode First Start Bit Timing	196
I ² C Master Mode Reception Timing	200
I ² C Master Mode Transmission Timing.....	199
I ² C Module	
Bus Collision	
Transmit Timing	203
INT Pin Interrupt.....	222
Internal Oscillator Switch Timing.....	68
Master Mode Transmit Clock Arbitration.....	202
PWM Auto-shutdown	
Auto-restart Enabled	143
Firmware Restart	143
PWM Direction Change	138
PWM Direction Change at Near 100% Duty Cycle ...	139
PWM Output (Active-High).....	133
PWM Output (Active-Low)	134
Repeat Start Condition.....	197
Reset, WDT, OST and Power-up Timer	258
Send Break Character Sequence	170
Slave Synchronization	186
SPI Master Mode (CKE = 1, SMP = 1)	267
SPI Mode Timing (Master Mode) SPI Mode	
Master Mode Timing Diagram	185
SPI Mode Timing (Slave Mode with CKE = 0)	187
SPI Mode Timing (Slave Mode with CKE = 1)	187
SPI Slave Mode (CKE = 0)	268
SPI Slave Mode (CKE = 1)	268
Stop Condition Receive or Transmit	202
Synchronous Reception (Master Mode, SREN)	174
Synchronous Transmission.....	172
Synchronous Transmission (Through TXEN)	172
Time-out Sequence	
Case 1	216
Case 2	216
Case 3	216
Timer0 and Timer1 External Clock	260
Timer1 Incrementing Edge.....	78
Two Speed Start-up	70
Wake-up from Interrupt	227
Timing Parameter Symbology	254
Timing Requirements	
I ² C Bus Data.....	271
I ² C Bus Start/Stop Bits	270
SPI Mode	269
TRISA	39
TRISA Register	39
TRISB	47
TRISB Register	48
TRISC	53
TRISC Register	53
TRISD	57
TRISD Register.....	57
TRISE	59
TRISE Register.....	59
Two-Speed Clock Start-up Mode.....	69
TXREG	153
TXSTA Register	160
BRGH Bit	163
U	
Ultra Low-Power Wake-up	16, 18, 40, 41
V	
Voltage Reference (VR)	
Specifications	262
Voltage Reference. See Comparator	
Voltage Reference (CVREF)	
Voltage References	
Associated Registers	97
VP6 Stabilization	94
VREF. SEE ADC Reference Voltage	
W	
Wake-up on Break	168
Wake-up Using Interrupts	226
Watchdog Timer (WDT)	224
Associated Registers	225
Clock Source	224
Modes	224
Period	224
Specifications	259
Waveform for Slave Mode General Call	
Address Sequence	192
WCOL	196, 198, 201
WCOL Status Flag	196, 198, 201
WDTCON Register	225
WPUB Register	49
WWW Address	323
WWW, On-Line Support	12

PIC16F882/883/884/886/887

NOTES:

THE MICROCHIP WEB SITE

Microchip provides online support via our WWW site at www.microchip.com. This web site is used as a means to make files and information easily available to customers. Accessible by using your favorite Internet browser, the web site contains the following information:

- **Product Support** – Data sheets and errata, application notes and sample programs, design resources, user's guides and hardware support documents, latest software releases and archived software
- **General Technical Support** – Frequently Asked Questions (FAQ), technical support requests, online discussion groups, Microchip consultant program member listing
- **Business of Microchip** – Product selector and ordering guides, latest Microchip press releases, listing of seminars and events, listings of Microchip sales offices, distributors and factory representatives

CUSTOMER CHANGE NOTIFICATION SERVICE

Microchip's customer notification service helps keep customers current on Microchip products. Subscribers will receive e-mail notification whenever there are changes, updates, revisions or errata related to a specified product family or development tool of interest.

To register, access the Microchip web site at www.microchip.com, click on Customer Change Notification and follow the registration instructions.

CUSTOMER SUPPORT

Users of Microchip products can receive assistance through several channels:

- Distributor or Representative
- Local Sales Office
- Field Application Engineer (FAE)
- Technical Support
- Development Systems Information Line

Customers should contact their distributor, representative or field application engineer (FAE) for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in the back of this document.

Technical support is available through the web site at: <http://support.microchip.com>

PIC16F882/883/884/886/887

READER RESPONSE

It is our intention to provide you with the best documentation possible to ensure successful use of your Microchip product. If you wish to provide your comments on organization, clarity, subject matter, and ways in which our documentation can better serve you, please FAX your comments to the Technical Publications Manager at (480) 792-4150.

Please list the following information, and use this outline to provide us with your comments about this document.

To: Technical Publications Manager

Total Pages Sent _____

RE: Reader Response

From: Name _____

Company _____

Address _____

City / State / ZIP / Country _____

Telephone: (_____) _____ - _____ FAX: (_____) _____ - _____

Application (optional):

Would you like a reply? Y N

Device: PIC16F882/883/884/886/887 Literature Number: DS41291E

Questions:

1. What are the best features of this document?

2. How does this document meet your hardware and software development needs?

3. Do you find the organization of this document easy to follow? If not, why?

4. What additions to the document do you think would enhance the structure and subject?

5. What deletions from the document could be made without affecting the overall usefulness?

6. Is there any incorrect or misleading information (what and where)?

7. How would you improve this document?

PIC16F882/883/884/886/887

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>PART NO.</u>	X	<u>XX</u>	<u>XXX</u>	
Device	Temperature Range	Package	Pattern	
Device:		PIC16F883F ⁽¹⁾ , PIC16F883FT ^(1, 2) , PIC16F884F ⁽¹⁾ , PIC16F884FT ^(1, 2) , PIC16F886F ⁽¹⁾ , PIC16F886FT ^(1, 2) , PIC16F887F ⁽¹⁾ , PIC16F887FT ^(1, 2) VDD range 2.0V to 5.5V		
Temperature Range:	I = -40°C to +85°C (Industrial) E = -40°C to +125°C (Extended)			
Package:	ML = Quad Flat No Leads (QFN) P = Plastic DIP PT = Plastic Thin-Quad Flatpack (TQFP) SO = Plastic Small Outline (SOIC) (7.50 mm) SP = Skinny Plastic DIP SS = Plastic Shrink Small Outline			
Pattern:	QTP, SQTP, Code or Special Requirements (blank otherwise)			

Examples:

- a) PIC16F883-E/P 301 = Extended Temp., PDIP package, 20 MHz, QTP pattern #301
- b) PIC16F883-I/SO = Industrial Temp., SOIC package, 20 MHz

Note 1: F = Standard Voltage Range
2: T = in tape and reel SSOP, SOIC and QFN packages only.



MICROCHIP

WORLDWIDE SALES AND SERVICE

AMERICAS

Corporate Office
2355 West Chandler Blvd.
Chandler, AZ 85224-6199
Tel: 480-792-7200
Fax: 480-792-7277
Technical Support:
<http://support.microchip.com>
Web Address:
www.microchip.com

Atlanta

Duluth, GA
Tel: 678-957-9614
Fax: 678-957-1455

Boston

Westborough, MA
Tel: 774-760-0087
Fax: 774-760-0088

Chicago

Itasca, IL
Tel: 630-285-0071
Fax: 630-285-0075

Dallas

Addison, TX
Tel: 972-818-7423
Fax: 972-818-2924

Detroit

Farmington Hills, MI
Tel: 248-538-2250
Fax: 248-538-2260

Kokomo

Kokomo, IN
Tel: 765-864-8360
Fax: 765-864-8387

Los Angeles

Mission Viejo, CA
Tel: 949-462-9523
Fax: 949-462-9608

Santa Clara

Santa Clara, CA
Tel: 408-961-6444
Fax: 408-961-6445

Toronto

Mississauga, Ontario,
Canada
Tel: 905-673-0699
Fax: 905-673-6509

ASIA/PACIFIC

Asia Pacific Office
Suites 3707-14, 37th Floor
Tower 6, The Gateway
Harbour City, Kowloon
Hong Kong
Tel: 852-2401-1200
Fax: 852-2401-3431

Australia - Sydney
Tel: 61-2-9868-6733
Fax: 61-2-9868-6755

China - Beijing
Tel: 86-10-8528-2100
Fax: 86-10-8528-2104

China - Chengdu
Tel: 86-28-8665-5511
Fax: 86-28-8665-7889

China - Hong Kong SAR
Tel: 852-2401-1200
Fax: 852-2401-3431

China - Nanjing
Tel: 86-25-8473-2460
Fax: 86-25-8473-2470

China - Qingdao
Tel: 86-532-8502-7355
Fax: 86-532-8502-7205

China - Shanghai

Tel: 86-21-5407-5533

Fax: 86-21-5407-5066

China - Shenyang
Tel: 86-24-2334-2829
Fax: 86-24-2334-2393

China - Shenzhen
Tel: 86-755-8203-2660
Fax: 86-755-8203-1760

China - Wuhan
Tel: 86-27-5980-5300
Fax: 86-27-5980-5118

China - Xiamen
Tel: 86-592-2388138
Fax: 86-592-2388130

China - Xian
Tel: 86-29-8833-7252
Fax: 86-29-8833-7256

China - Zhuhai
Tel: 86-756-3210040
Fax: 86-756-3210049

ASIA/PACIFIC

India - Bangalore
Tel: 91-80-4182-8400
Fax: 91-80-4182-8422

India - New Delhi
Tel: 91-11-4160-8631
Fax: 91-11-4160-8632

India - Pune
Tel: 91-20-2566-1512
Fax: 91-20-2566-1513

Japan - Yokohama
Tel: 81-45-471-6166
Fax: 81-45-471-6122

Korea - Daegu
Tel: 82-53-744-4301
Fax: 82-53-744-4302

Korea - Seoul
Tel: 82-2-554-7200
Fax: 82-2-558-5932 or
82-2-558-5934

Malaysia - Kuala Lumpur
Tel: 60-3-6201-9857
Fax: 60-3-6201-9859

Malaysia - Penang
Tel: 60-4-227-8870
Fax: 60-4-227-4068

Philippines - Manila
Tel: 63-2-634-9065
Fax: 63-2-634-9069

Singapore
Tel: 65-6334-8870
Fax: 65-6334-8850

Taiwan - Hsin Chu
Tel: 886-3-572-9526
Fax: 886-3-572-6459

Taiwan - Kaohsiung
Tel: 886-7-536-4818
Fax: 886-7-536-4803

Taiwan - Taipei
Tel: 886-2-2500-6610
Fax: 886-2-2508-0102

Thailand - Bangkok
Tel: 66-2-694-1351
Fax: 66-2-694-1350

EUROPE

Austria - Wels
Tel: 43-7242-2244-39
Fax: 43-7242-2244-393

Denmark - Copenhagen
Tel: 45-4450-2828
Fax: 45-4485-2829

France - Paris
Tel: 33-1-69-53-63-20
Fax: 33-1-69-30-90-79

Germany - Munich
Tel: 49-89-627-144-0
Fax: 49-89-627-144-44

Italy - Milan
Tel: 39-0331-742611
Fax: 39-0331-466781

Netherlands - Drunen
Tel: 31-416-690399
Fax: 31-416-690340

Spain - Madrid
Tel: 34-91-708-08-90
Fax: 34-91-708-08-91

UK - Wokingham
Tel: 44-118-921-5869
Fax: 44-118-921-5820