ROSVM Package - Mathematical Background

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1 ToDo

Add derivations for the exterior product features.

2 Introduction

This documents describes the mathematical background of the Ranking Support Vector Machine (RankSVM) [2] implemented in the ROSVM package.

3 Method

3.1 Notation

3.2 Ranking Support Vector Machine (RankSVM)

The RankSVM's primal optimization problem is given as:

$$\min_{\mathbf{w}, \boldsymbol{\xi}} f(\mathbf{w}, \boldsymbol{\xi}) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{(i,j) \in P} \xi_{ij}$$
s.t.
$$y_{ij} \mathbf{w}^T (\phi_i - \phi_j) \ge 1 - \xi_{ij}, \quad \forall (i,j) \in \mathcal{P}$$

$$\xi_{ij} \ge 0, \quad \forall (i,j) \in \mathcal{P},$$

$$(1)$$

where C > 0 is the regularization parameter. We define the pairwise labels as the retention time difference of the corresponding molecules, i.e. $y_{ij} := \text{sign}(t_i - t_j)$. From the primal problem in Eq. (1) we can derive the following dual optimization problem:

$$\max_{\alpha} g(\alpha) = \mathbf{1}^{T} \alpha - \frac{1}{2} \alpha^{T} \left(\mathbf{y} \mathbf{y}^{T} \circ \mathbf{B} \mathbf{K} \mathbf{B}^{T} \right) \alpha$$
s.t. $0 \le \alpha_{ij} \le C, \quad \forall (i,j) \in \mathcal{P},$ (2)

where $\mathbf{y} \in \mathbb{R}^n$ is the vector of pairwise labels, and $\mathbf{B} \in \{-1,0,1\}^{m \times n}$ with row p = (i,j) being $[\mathbf{B}]_{p} = (0,\ldots,0,\underbrace{1}_{i},0,\ldots,0,\underbrace{-1}_{i},0,\ldots,0)$. For further details refer to the work by

[3]. Using the properties of the Hadamard product \circ we can reformulate the function $g(\alpha)$ of the problem in Eq. (2) [4]:

$$\begin{split} g(\boldsymbol{\alpha}) &= \mathbf{1}^T \boldsymbol{\alpha} - \frac{1}{2} \boldsymbol{\alpha}^T \left(\mathbf{y} \mathbf{y}^T \circ \mathbf{B} \mathbf{K} \mathbf{B}^T \right) \boldsymbol{\alpha} \\ &= \mathbf{1}^T \boldsymbol{\alpha} - \frac{1}{2} \boldsymbol{\alpha}^T \left(\mathbf{D}_{\mathbf{y}} \mathbf{B} \mathbf{K} \mathbf{B}^T \mathbf{D}_{\mathbf{y}} \right) \boldsymbol{\alpha} \\ &= \mathbf{1}^T \boldsymbol{\alpha} - \frac{1}{2} \boldsymbol{\alpha}^T \mathbf{A} \mathbf{K} \mathbf{A}^T \boldsymbol{\alpha}. \end{split}$$

Table 1: Notation table	
Notation	Description
\mathcal{P}	Set of preferences

Algorithm 1: Conditional gradient algorithm

Here, $\mathbf{D_y} \in \mathbb{R}^{m \times m}$ is a diagonal matrix storing the pairwise labels, and $\mathbf{A} := \mathbf{D_y} \mathbf{B} \in \{-1, 0, 1\}^{m \times n}$. The matrix \mathbf{A} now contains the pairwise labels as well by multiplying each row p = (i, j) of \mathbf{B} with y_{ij} , i.e. $[\mathbf{A}]_{p} = y_{ij} \cdot (0, \dots, 0, \underbrace{1}_{i}, 0, \dots, 0, \underbrace{-1}_{j}, 0, \dots, 0)$.

Check out '_build_A_matrix' for the actual implementation of the **A**-matrix construction from the data.

3.2.1 Optimizing the RankSVM Model Parameters

We find the optimal RankSVM model α^* in the dual space given a training dataset $\mathcal{D} = \{(x_i, t_i)\}_{i=1}^n$ using the conditional gradient algorithm [1]. The algorithm is shown in 1. The feasible set is defined as $\mathcal{A} := \{\alpha \in \mathbb{R}^m \mid 0 \leq \alpha_{ij} \leq C, \forall (i, j) \in \mathcal{P}\}$ which follows from the constraints of the dual optimization problem in Eq. (2). Note that \mathcal{A} is compact convex set.

The function '_assert_is_feasible' implements the feasibility check for a given $\alpha^{(k)}$ iterate.

Solving the Sub-problem: In each iteration of Algorithm 1 we need to solve the following linear optimization problem:

$$\mathbf{s} = \underset{\mathbf{s}' \in \mathcal{A}}{\arg \max} \left\langle \nabla g(\boldsymbol{\alpha}^{(k)}), \mathbf{s}' \right\rangle$$

$$= \underset{\mathbf{s}' \in \mathcal{A}}{\arg \max} \left\langle \underbrace{\mathbf{1} - \mathbf{A} \mathbf{K} \mathbf{A}^T \boldsymbol{\alpha}^{(k)}}_{:=\mathbf{d}}, \mathbf{s}' \right\rangle. \tag{3}$$

Eq. (3) can be solved by simply evaluating **d** and subsequently setting the components of $s \in \mathbb{R}^m$ as:

$$s_{ij} = \begin{cases} C & \text{if } d_{ij} > 0 \\ 0 & \text{else} \end{cases}.$$

The function '_solve_sub_problem' implements the sub problem solver.

Line-search: The optimal step-size $\gamma^{(k)}$ can be determined by solving an univariate problem:

$$\gamma_{LS}^{(k)} = \max_{\gamma \in [0,1]} g\left(\alpha^{(k)} - \gamma \left(\mathbf{s} - \alpha^{(k)}\right)\right). \tag{4}$$

For that, we set the derivative of (4) to zero:

$$\begin{split} &\frac{\partial g\left(\boldsymbol{\alpha}^{(k)} - \gamma\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right)}{\partial \gamma} \\ &= \left(\boldsymbol{\alpha}^{(k)} - \gamma\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\ &= \left(\boldsymbol{\alpha}^{(k)}\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \gamma \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\ &= 0 \end{split}$$

and solve for γ :

$$\gamma \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) = \left(\boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\
\Leftrightarrow \\
\gamma = \frac{\left(\boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)}{\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)} \\
\Leftrightarrow \\
\gamma_{LS}^{(k)} = \frac{\left\langle \nabla g \left(\boldsymbol{\alpha}^{(k)}\right), \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \right\rangle}{\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)}. \tag{5}$$

To ensure that $\gamma_{LS}^{(k)}$ we clip the value to the range of [0,1]. To evaluate the nominator in Eq. (5) we can reuse the value of $\mathbf{d} = \nabla g\left(\boldsymbol{\alpha}^{(k)}\right)$ calculated when solving the sub-problem (see Eq. (3))

Determine Convergence: Jaggi [1] propose to use the duality gap:

$$h\left(\boldsymbol{\alpha}^{(k)}\right) := \left\langle \nabla g\left(\boldsymbol{\alpha}^{(k)}\right), \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \right\rangle$$

as convergence criteria by defining a threshold ϵ and iterating until $h(\boldsymbol{\alpha}^{(k)}) < \epsilon$. The ratio behind this idea is, that the duality gap is an upper bound on the difference of the current function value for $\boldsymbol{\alpha}^{(k)}$ and the one of the global maximizer $\boldsymbol{\alpha}^*$ of Eq. (1), i.e. $h\left(\boldsymbol{\alpha}^{(k)}\right) \geq g\left(\boldsymbol{\alpha}^*\right) - g\left(\boldsymbol{\alpha}^{(k)}\right)^1$.

In practice it the duality gap $h\left(\boldsymbol{\alpha}^{(k)}\right)$ was observed to have very large values and never approaching a reasonable threshold. However, the model performance was nevertheless very good. That might be because the $\boldsymbol{\alpha}^{(k)}$ has many entries and those can have values up to C. A quadratic function of the dual vector, like

¹Note: Here we formulate the dual optimization as a maximization. In [1] the authors formulate it as a minimization which leads to slighly changed duality gap definition.

g in Eq. (2), can take on very large values. The "un-boundedness" or missing normalization might be an issue here.

The current implementation gets around this issue, by checking the following quantity for the convergence:

$$\frac{h(\boldsymbol{\alpha}^{(k)})}{h(\boldsymbol{\alpha}^{(0)})} < \epsilon,$$

where $\epsilon > 0$, e.g. $\epsilon = 0.005$, is the convergence threshold. Possible scaling factors of the function h are canceled out. This convergence criteria can be interpreted as the relative decrease of the duality gap given the initial model $\alpha^{(0)}$.

References

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