# ROSVM Package - Mathematical Background

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### 1 ToDo

Add derivations for the exterior product features.

## 2 Introduction

This documents describes the mathematical background of the Ranking Support Vector Machine (RankSVM) [2] implemented in the ROSVM package.

## 3 Method

#### 3.1 Notation

## 3.2 Ranking Support Vector Machine (RankSVM)

The RankSVM's primal optimization problem is given as:

$$\min_{\mathbf{w}, \boldsymbol{\xi}} f(\mathbf{w}, \boldsymbol{\xi}) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{(i,j) \in P} \xi_{ij}$$
s.t. 
$$y_{ij} \mathbf{w}^T (\phi_i - \phi_j) \ge 1 - \xi_{ij}, \quad \forall (i,j) \in \mathcal{P}$$

$$\xi_{ij} \ge 0, \quad \forall (i,j) \in \mathcal{P},$$

$$(1)$$

where C > 0 is the regularization parameter. We define the pairwise labels as the retention time difference of the corresponding molecules, i.e.  $y_{ij} := \text{sign}(t_i - t_j)$ . From the primal problem in Eq. (1) we can derive the following dual optimization problem:

$$\max_{\alpha} g(\alpha) = \mathbf{1}^{T} \alpha - \frac{1}{2} \alpha^{T} \left( \mathbf{y} \mathbf{y}^{T} \circ \mathbf{B} \mathbf{K} \mathbf{B}^{T} \right) \alpha$$
s.t.  $0 \le \alpha_{ij} \le C, \quad \forall (i,j) \in \mathcal{P},$  (2)

where  $\mathbf{y} \in \mathbb{R}^n$  is the vector of pairwise labels, and  $\mathbf{B} \in \{-1,0,1\}^{m \times n}$  with row p = (i,j) being  $[\mathbf{B}]_{p} = (0,\ldots,0,\underbrace{1}_{i},0,\ldots,0,\underbrace{-1}_{i},0,\ldots,0)$ . For further details refer to the work by

[3]. Using the properties of the Hadamard product  $\circ$  we can reformulate the function  $g(\alpha)$  of the problem in Eq. (2) [4]:

$$g(\alpha) = \mathbf{1}^{T} \alpha - \frac{1}{2} \alpha^{T} \left( \mathbf{y} \mathbf{y}^{T} \circ \mathbf{B} \mathbf{K} \mathbf{B}^{T} \right) \alpha$$
$$= \mathbf{1}^{T} \alpha - \frac{1}{2} \alpha^{T} \left( \mathbf{D}_{\mathbf{y}} \mathbf{B} \mathbf{K} \mathbf{B}^{T} \mathbf{D}_{\mathbf{y}} \right) \alpha$$
$$= \mathbf{1}^{T} \alpha - \frac{1}{2} \alpha^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \alpha.$$

Table 1: Notation table	
Notation	Description
$\mathcal{P}$	Set of preferences

#### Algorithm 1: Conditional gradient algorithm

Here,  $\mathbf{D_y} \in \mathbb{R}^{m \times m}$  is a diagonal matrix storing the pairwise labels, and  $\mathbf{A} := \mathbf{D_y} \mathbf{B} \in \{-1, 0, 1\}^{m \times n}$ . The matrix  $\mathbf{A}$  now contains the pairwise labels as well by multiplying each row p = (i, j) of  $\mathbf{B}$  with  $y_{ij}$ , i.e.  $[\mathbf{A}]_{p} = y_{ij} \cdot (0, \dots, 0, \underbrace{1}_{i}, 0, \dots, 0, \underbrace{-1}_{j}, 0, \dots, 0)$ .

Check out '\_build\_A\_matrix' for the actual implementation of the **A**-matrix construction from the data.

#### 3.2.1 Optimizing the RankSVM Model Parameters

We find the optimal RankSVM model  $\alpha^*$  in the dual space given a training dataset  $\mathcal{D} = \{(x_i, t_i)\}_{i=1}^n$  using the conditional gradient algorithm [1]. The algorithm is shown in 1. The feasible set is defined as  $\mathcal{A} := \{\alpha \in \mathbb{R}^m \mid 0 \leq \alpha_{ij} \leq C, \forall (i, j) \in \mathcal{P}\}$  which follows from the constraints of the dual optimization problem in Eq. (2). Note that  $\mathcal{A}$  is compact convex set.

The function '\_assert\_is\_feasible' implements the feasibility check for a given  $\alpha^{(k)}$  iterate.

**Solving the Sub-problem:** In each iteration of Algorithm 1 we need to solve the following linear optimization problem:

$$\mathbf{s} = \underset{\mathbf{s}' \in \mathcal{A}}{\operatorname{arg \, max}} \left\langle \nabla g(\boldsymbol{\alpha}^{(k)}), \mathbf{s}' \right\rangle$$
$$= \underset{\mathbf{s}' \in \mathcal{A}}{\operatorname{arg \, max}} \left\langle \underbrace{\mathbf{1} - \mathbf{A} \mathbf{K} \mathbf{A}^T \boldsymbol{\alpha}^{(k)}}_{:-\mathbf{d}}, \mathbf{s}' \right\rangle. \tag{3}$$

Eq. (3) can be solved by simply evaluating **d** and subsequently setting the components of  $s \in \mathbb{R}^m$  as:

$$s_{ij} = \begin{cases} C & \text{if } d_{ij} > 0\\ 0 & \text{else.} \end{cases}$$

The function '\_solve\_sub\_problem' implements the sub problem solver.

**Line-search:** The optimal step-size  $\gamma^{(k)}$  can be determined by solving an univariate problem:

$$\gamma^{(k)} = \max_{\gamma \in [0,1]} g\left(\alpha^{(k)} - \gamma\left(\mathbf{s} - \alpha^{(k)}\right)\right). \tag{4}$$

For that, we set the derivative of (4) to zero:

$$\begin{split} &\frac{\partial g\left(\boldsymbol{\alpha}^{(k)} - \gamma\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right)}{\partial \gamma} \\ &= \left(\boldsymbol{\alpha}^{(k)} - \gamma\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\ &= \left(\boldsymbol{\alpha}^{(k)}\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \gamma \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^T \mathbf{A} \mathbf{K} \mathbf{A}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^T \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\ &= 0 \end{split}$$

and solve for  $\gamma$ :

$$\begin{split} & \gamma = \left(\boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) \\ & \Leftrightarrow \\ & \gamma = \frac{\left(\boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right) - \mathbf{1}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)}{\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)} \\ & \gamma = \frac{\left\langle \nabla g \left(\boldsymbol{\alpha}^{(k)}\right), \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right\rangle}{\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)} = \frac{\left\langle \mathbf{d}, \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)\right\rangle}{\left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)^{T} \mathbf{A} \mathbf{K} \mathbf{A}^{T} \left(\mathbf{s} - \boldsymbol{\alpha}^{(k)}\right)} \end{split}$$

# References

- [1] Martin Jaggi. "Revisiting Frank-Wolfe: Projection-Free Sparse Convex Optimization". In: Proceedings of the 30th International Conference on Machine Learning. Ed. by Sanjoy Dasgupta et al. Vol. 28. Proceedings of Machine Learning Research 1. Atlanta, Georgia, USA: PMLR, 17–19 Jun 2013, pp. 427–435. URL: http://proceedings.mlr.press/v28/jaggi13.html.
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