

g4ntm

Library scope: global
Named arguments: supported

Introduction

A library provides control for Telescent Network Topology Management (NTM) robot patch.

Shortcuts

Add · **Delete** · **Get Connection Info**

Keywords

Keyword	Arguments	Documentation
Add	<i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i>	
Delete	<i>self, dev1, intf1, dev2, intf2, direction=bi, force=False</i>	Deletes the connection between dev1:intf1 - dev2:intf2
Get Connection Info	<i>self, dev, intf</i>	Returns information about the connection by router/interface

Altogether 3 keywords.

Generated by [Libdoc](#) on 2019-03-11 23:22:12.

