

1 Overview

In general, we aim to fit a line (or hyperplane in higher dimensions) to a scattering of data.

1.1 Notation and Modeling

Data for regression problems goes in the form of $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$ where $\mathbf{x}_i \in \mathbb{R}^d$ and $y_i \in \mathbb{R}$.

Each input in \mathbf{x} may be a column vector of length N .

Formally, the goal of regression is the following formula:

$$\operatorname{argmin}_{b, w} \sum_{p=1}^N (y_i - \mathbf{w}^T \mathbf{x}_i - b)^2 \quad (1)$$

where $\mathbf{w} \in \mathbb{R}^d$ is the weight vector and $b \in \mathbb{R}$ is the bias term.

The gradient of this cost after some chain rule:

$$\nabla g(w) = 2 \left(\sum_{p=1}^N x_p x_p^T \right) w - 2 \sum_{p=1}^N x_p y_p \quad (2)$$

Setting the gradient above to zero and solving for w gives the system of linear equations

$$\left(\sum_{p=1}^N x_p x_p^T \right) w = \sum_{p=1}^N x_p y_p \quad (3)$$

$$w^* = \left(\sum_{p=1}^N x_p x_p^T \right)^{-1} \sum_{p=1}^N x_p y_p \quad (4)$$

1.2 Efficacy of the Model

The efficacy of the model can be measured by the mean squared error (MSE) of the model:

$$\frac{1}{N} \sum_{p=1}^N (y_p - w^T x_p)^2 \quad (5)$$

However, as many functions are nonlinear, in order to fit a nonlinear function, we can use a nonlinear transformation, we can use an appropriate nonlinear feature transformation to describe nonlinear functions.

Problem 0. Model through a sin wave

Solution to Problem 0. Sinusoidal Regression One solution to this is to use a sinusoidal transformation. For example, we can use the following transformation:

$$b + f(x_p)w = b + \sin(2\pi x_p)w \approx y_p, p = 1, \dots, P \quad (6)$$

This transforms the feature space to $\{f(x_p), y_p\}_{p=1}^P$.

1.3 Computing w^*

$$\underset{w}{\operatorname{argmin}} = \sum_{p=1}^P (f_p w - y_p)^2$$

Deriving the derivative of the above equation gives us the following, setting to zero for the minimum:

$$\begin{aligned} 2 \sum_{p=1}^P f_p (f_p w - y_p) &= 0 \\ \sum_{p=1}^P f_p f_p w &= \sum_{p=1}^P f_p y_p \\ w^* &= \left(\sum_{p=1}^P f_p f_p^T \right)^{-1} \sum_{p=1}^P f_p y_p \end{aligned}$$

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References

- [1] Jeremy Wattós, Reza Borhanié Aggelos K. Katsaggelos, *Machine Learning Refined: Foundations, Algorithms, and Applications*, Northwestern University.