

# GSTE to “STE with tag invariants”

## term-level assertion graph definition

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```
1. (*b_types.ml *)
2. type scalar =
3.   | IntC of int * int (* value * size *)
4.   | BoolC of bool
5.   | SymbIntC of string * int
6.   | SymbBoolC of string
7.
8. type sort =
9.   | Int of int (* size *)
10.  | Bool
11.  | Array of int * sort
12.
13. type var =
14.   | Ident of string * sort
15.   | Para of var * expression
16. and expression =
17.   | IVar of var
18.   | Const of scalar
19.   | IteForm of formula * expression * expression
20. and formula =
21.   | Eqn of expression * expression
22.   | AndForm of formula * formula
23.   | Neg of formula
24.   | OrForm of formula * formula
25.   | ImplyForm of formula * formula
26.   | Chaos
```

## term-level tag invariant definition (non auto-generated)

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Define manually the tag invariants of a assertion graph.

## boolean-level assertion graph in Ocaml

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Because boolean theory is a subset of first-order theory, so it is feasible to define bit-level assertion graph in term-level. That is we keep the assertion graph skeleton the same as before and define the assertion graph formula just using following constructors:

1. BoolC
2. BoolV
3. AndForm
4. Neg

## boolean-level tag invariant in Ocaml

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For one term-level tag invariant, use SMT/Z3 to obtain all the possible boolean-level tag invariants corresponding with it's term-level form. (undone)

## symbolic trajectory evaluation formula in Ocaml

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Define the STE formula in Ocaml, and then it's convenient to transform boolean-level assertion graph formula into symbolic trajectory evaluation formula in Ocaml and pave the way for transforming AG in Ocaml to AG in Forte.

```
1. (* trajectory.ml *)
2. type bVar = Bvariable of string
3. type bExpr =
4.     | EVar of bVar
5.     | EAnd of bExpr * bExpr
6.     | EOr of bExpr * bExpr
7.     | ENeg of bExpr
8.
9. let rec bExpr2FLbExprList be =
10.     match be with
11.     | EVar (Bvariable name)-> Printf.sprintf "bvariable \"%s\"" name
12.     | EAnd (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bAND" ^ (bExpr2FLbExprList be2)^ ")"
13.     | EOr (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bOR" ^ (bExpr2FLbExprList be2) ^ ")"
14.     | ENeg be0 -> "(bNOT (" ^ (bExpr2FLbExprList be0) ^"))"
15.
16. type trajNode = Tnode of string
17.
18. type trajForm =
19.     | Is1 of trajNode
20.     | Is0 of trajNode
21.     | Next of trajForm
22.     | Guard of bExpr * trajForm
23.     | TAndList of trajForm list
24.     | TChaos
25.
26. let isb p tnode = TAndList [Guard (p, Is1 tnode); Guard ((ENeg p), Is0 tnode)]
```

## STE in Forte

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transform the assertion graph (AG) defined in Ocaml into complete STE verification program in Forte;

In the meantime, transform tag invariants defined in (STE formula in Ocaml) into Forte-accepted language.

```

1.  (** gsteSpec to forte input AG *)
2.  let toFL gs model_name binNodes=
3.      let rec trans trajf =
4.          match trajf with
5.          | TChaos -> []
6.          | Is1 (Tnode name) -> [Printf.sprintf "Is1 \"%s\"\" name]
7.          | Is0 (Tnode name) -> [Printf.sprintf "Is0 \"%s\"\" name]
8.          | Guard (be, tf) -> (
9.              match (trans tf) with
10.             | [] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
11.                 "Chaos"]
12.             | f::[] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList
13.                 be) f]
14.             | fs -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
15.                 "TAndList [" ^ (String.concat "," fs) ^ "]" ]
16.             )
17.          | TAndList ts -> List.flatten (List.map (fun f -> trans f) ts)
18.          | _ -> raise (Invalid_argument "this is for boolean level trajectory
19.                 formula")
20.      in
21.      let main_assertion_graph init_node node_set edge_set =
22.          match init_node with (Vertex inum) -> Printf.fprintf stdout "let ver
23.             texI = Vertex %d;\n" inum ;
24.          Printf.fprintf stdout "%s" ("let vertexL = [" ^ (String.concat ","
25.             (List.map (fun (Vertex i) -> Printf.sprintf "Vertex %d" i) node_set)) ^
26.             "];\n" );
27.          Printf.fprintf stdout "%s" ("let edgeL = [" ^ (String.concat "," (Li
28.             st.map (fun (Edge ((Vertex f),(Vertex t))) -> Printf.sprintf "Edge (Vertex %
29.             d) (Vertex %d)" f t) edge_set)) ^ "];\n");
30.      in
31.      let ant_function init_node node_set edge_set ants =
32.          let ants_traj e =
33.              let term_f = ants e in
34.              let bit_f = termForm2bitForm term_f in
35.              let traj_f = bitForm2trajForm bit_f in
36.              let add_myclk fs =
37.                  match fs with
38.                  | [] -> "TAndList []"
39.                  | s -> "TAndList ["^ (String.concat "," (s@[Printf.sprintf
40.                     "Is0 \"%s\"\" visCLKname ; Printf.sprintf "Next (Is1 \"%s\"") visCLKname]))
41.                     ^"]"
42.              in
43.              add_myclk (trans traj_f)
44.          in
45.          Printf.fprintf stdout "%s" (
46.              "let ant aEdge =
47.                  val (Edge (Vertex from) (Vertex to)) = aEdge
48.                  in
49.                  " ^
50.                  (
51.                      let items = List.map (fun e -> (
52.                          match e with

```

```

41.         |Edge ((Vertex f),(Vertex t)) ->
Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (ants_traj e)
42.     )
43.     ) edge_set
44.     in
45.     let cases = String.concat "\n\t| " items in
46.     let body = cases ^ "\n\t| error \"In cons: missing case\" in
47.     Printf.sprintf "\t%s\n;\n\n" body
48. )
49. )
50. in
51. let cons_function init_node node_set edge_set cons =
52.     let cons_traj e =
53.         let term_f = cons e in
54.         let bit_f = termForm2bitForm term_f in
55.         let traj_f = bitForm2trajForm bit_f in
56.         let add_tandlist ts =
57.             match ts with
58.             | [] -> "TAndList []"
59.             | s -> "TAndList [" ^ (String.concat "," s) ^ "]"
60.         in
61.         add_tandlist (trans traj_f)
62.     in
63.     Printf.fprintf stdout "%s" (
64. "let cons aEdge =
65.     val (Edge (Vertex from) (Vertex to)) = aEdge
66.     in
67.     "^ (
68.         let items = List.map (fun e -> (
69.             match e with
70.             |Edge ((Vertex f),(Vertex t)) ->
Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (cons_traj e)
71.         )
72.         ) edge_set
73.     in
74.     let cases = String.concat "\n\t| " items in
75.     let body = cases ^ "\n\t| error \"In cons: missing case\" in
76.     Printf.sprintf "\t%s\n;\n\n" body
77. )
78. )
79. in
80. let binNodesPart binNodes =
81.     let ivar2str iv =
82.         match iv with
83.         | IVar (Ident (str, Int n)) -> List.map (fun i -> formatMapVIS ~
axis1:i str) (upt 0 (n-1))
84.         | IVar (Ident (str, Bool)) -> [formatMapVIS str]
85.         | _ -> raise (Invalid_argument "In toFL binNodesPart: sry la")
86.     in
87.     match binNodes with
88.     | [] -> "[]"
89.     | bns -> (

```

```

90.         let strOfbns = (List.flatten (List.map (fun nd -> ivar2str nd) b
ns)) in
91.         let addQuoteMark = List.map (fun sob -> "\""^sob^"\"") strOfbns
in
92.         "[" ^ (String.concat "," addQuoteMark) ^ "]"
93.     )
94. in
95.     match gs with Graph (init_node , node_set, edge_set, ants, cons) -> (
96.         Printf.fprintf stdout
97.         "
98.         let ckt = load_exe \"%s.exe\";
99.         load \"gsteSymReduce.fl\";
100.        loadModel ckt;
101.        " model_name;
102.        main_assertion_graph init_node node_set edge_set;
103.        ant_function init_node node_set edge_set ants;
104.        cons_function init_node node_set edge_set cons ;
105.        Printf.fprintf stdout
106.        "
107.        let mainGoal = Goal [] (TGraph (Graph vertexL vertexI edgeL (Edge2Form ant)
(Edge2Form cons)));
108.        let binNodes = %s;
109.        lemma \"lemmaTMain\" mainGoal;
110.        by (gsteSymbSim binNodes);
111.        done 0;
112.        quit;
113.        " (binNodesPart binNodes)
114.        )

```

## GSTE to “STE with tag-invariants”

toFL : term-level (assertion graph & tag-invariants) to Forte-accepted input language:

At term-level: using SMT to solve the limited equation to get all possible instantiated invariants

then transform tag-invariants sets (instantiated) into boolean-level invariants sets,

then transform boolean-level invariants set into Forte-accepted tag invariants ( defined in gsteSymReduce.fl)

## STE with tag-invariants verification algorithm

```

1.     ## main function
2.     result = true;
3.     for edge in edgeL:
4.         result = result and check(edge)
5.     return result

```

```

1.     ## check function
2.     # input : edge

```

```

3.      # output : boolean
4.      val (Edge from to) = edge
5.      val (Vertex n1) = from
6.      val (Vertex n2) = to
7.      ants_set = [ TAndList ((ant edge) : x) for x in (tag from) ]
8.      cons_set = [ TAndList ((cons edge): (map(Next, x))) for x in (tag to)]
9.      return check_next_ant(ants_set, cons_set)

```

```

1.      ## check_next_ant function
2.      # input : antss: an antecedent set , contss: a consequent set
3.      # output : boolean
4.      for ant in antss:
5.          if check_helper(conss, ant):
6.              continue
7.          else:
8.              return false

```

```

1.      ## check_helper function
2.      # input : conss: a consequent set, ant: an antecedent
3.      # output : boolean
4.      result = false
5.      for con in conss:
6.          if steSymbSimGoalFDirect(ant, con):
7.              result = true
8.              break
9.      return result

```

## case analysis

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### ring buffer fifo

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Considering a ring buffer fifo circuit with concrete parameters, the concrete parameters are following:

```

1.  let depth = 4  (* fifo depth *)
2.  let last = depth - 1 (* fifo maximum index value*)
3.  let data_length = 2 (* element width of fifo *)
4.  let index_length = 2 (* the variable (indicating index) 's width *)

```

we can define the main assertion graph's skeleton as follow:

```

1.  (** main assertion graph *)
2.  let vertexI = Vertex 0

```

```

3. let vertexL = vertexI :: ((Vertex 1):: (List.map (fun i -> Vertex i) (upt 3
(2*last+4))))
4. (** odd-vertex selfloop edge, odd-vertex bidirection edge, odd-vertex to eve
n-vertex edge, even-vertex backward edge , Vertex 4 to Vertex 1 edge*)
5. let edgeL = [Edge (vertexI,(Vertex 1))] @
6.           (List.map (fun i -> Edge (Vertex (2*i+1), Vertex (2*i+1))) (upt
0 depth))@
7.           (List.map (fun i -> Edge (Vertex (2*i-1), Vertex (2*i+1))) (upt
1 depth))@
8.           (List.map (fun i -> Edge (Vertex (2*i+1), Vertex (2*i-1))) (dwt
depth 1))@
9.           (List.map (fun i -> Edge (Vertex (2*i-1), Vertex (2*i+2))) (upt
1 depth))@
10.          (List.map (fun i -> Edge (Vertex (2*i+2), Vertex (2*i))) (dwt
depth 2))@
11.          [Edge ((Vertex 4), (Vertex 1))]

```

and the antecedent formula set and the consequent formula set can be defined like following:

```

1. (** actions of assertion graph *)
2. let rst      : expression = IVar (Ident ("rst", Bool))
3. let push     : expression = IVar (Ident ("push", Bool))
4. let pop      : expression = IVar (Ident ("pop", Bool))
5. let empty    : expression = IVar (Ident ("empty", Bool))
6. let full     : expression = IVar (Ident ("full", Bool))
7. let dataIn   : expression = IVar (Ident ("dataIn", Int data_length))
8. let dataOut  : expression = IVar (Ident ("dataOut", Int data_length))
9. let low      : expression = Const (BoolC false)
10. let high     : expression = Const (BoolC true)
11. let readDataIn : expression = Const (IntC (1, data_length))
12. let symbolDataOut : expression = Const (SymbIntC ("dout", data_length))
13.
14. let rstFormula = Eqn (rst, high)
15. let nrstFormula = Eqn (rst, low)
16. let pushFormula = AndForm (nrstFormula, AndForm (Eqn (push, high), Eqn (po
p, low)))
17. let popFormula = AndForm (nrstFormula, AndForm (Eqn (push, low), Eqn (pop,
high)))
18. let noPopPushFormula = AndForm (nrstFormula, AndForm (Eqn (push,low), Eqn (po
p, low)))
19. let fullFormula = Eqn (full, high)
20. let noFullFormula = Eqn (full, low)
21. let emptyFormula = Eqn (empty, high)
22. let noEmptyFormula = Eqn (empty, low)
23.
24. let pushData data = AndForm (pushFormula, Eqn (dataIn, data))
25. let popData data = Eqn (dataOut, data)
26.
27. let antOfRbFIFO aEdge =
28.   let f = nodeToInt (source aEdge) in

```

```

29.   let t = nodeToInt (sink aEdge)   in
30.   (
31.     if( f == 0) then rstFormula
32.     else (
33.       if (f mod 2 == 1 ) then (
34.         if (f = t) then noPopPushFormula
35.         else if ((f + 2) == t) then pushFormula
36.         else if ( f == (t+2)) then popFormula
37.         else pushData readDataIn
38.       )else popFormula
39.     )
40.   )
41.
42. let consOfRbFIFO aEdge =
43.   let f = nodeToInt (source aEdge) in
44.   let t = nodeToInt (sink aEdge)   in
45.   (
46.     if ((f mod 2 == 1)&&(t mod 2 == 1)) then (
47.       if (f == 1) then AndForm (emptyFormula, noFullFormula)
48.       else if (f == (2*depth+1)) then AndForm (noEmptyFormula, fullFor
mula)
49.       else AndForm (noEmptyFormula, noFullFormula)
50.     )else (
51.       if ((f == 4) && (t == 1)) then popData readDataIn
52.       else if (f == (2*depth+2)) then AndForm (noEmptyFormula, fullFo
rmula)
53.       else if (f == 1) then AndForm (emptyFormula, noFullFormula)
54.       else if (f == 0) then Chaos
55.       else if (t == 4) then Chaos
56.       else AndForm (noEmptyFormula, noFullFormula)
57.     )
58.   )

```

A typical GSTE Assertion graph can be constructed by using following statement:

```

1. let rbfifoGsteSpec = Graph (vertexI, vertexL, edgeL, antOfRbFIFO, consOfRbFI
FO)

```

Next step it is about to construct the tag invariants set and transform the (GSTE assertion graph and tag invariants) into Forte-accepted input language by using `toFL` function

## memory

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