GSTE to "STE with tag invariants"

term-level GSTE theory

Constants, Variable, Expression and Formula

- A constant is either a natural number or boolean value, which also have corresponding symbolic version. Natural number in our theory consists of two parts: its value and its bit length, while a symbolic natural number consists of its name and its bit length. Each boolean constant carries a truth-value and each boolean symbolic constant just carries a name, which can be identified through Ocaml type constructor.
- there are two kinds of variable: (1) simple identifier, denoted by a string and the type of it; (2) element of an array, denoted by a variable followed by an expression representing index.
 - A simple expression is either a variable v or a constant c, in addition we allow using IteForm to construct a compound expression, which has the form of f?e1: e2.
 - A formula can be atomic formula or a compound formula. An atomic formula can be a constant Chaos or an equivalence formula e1=e2. Compound formula can be constructed from formulas using logic connectives, including And, Or, Neg, Imply.

term-level assertion graph definition

```
1. (*b_types.ml *)
 2. type scalar =
       IntC of int * int (* value * size *)
       | BoolC of bool
4.
 5.
       | SymbIntC of string * int
       | SymbBoolC of string
 6.
 7.
 8. type sort =
       | Int of int (* size *)
9.
10.
       Bool
       | Array of int * sort
11.
12.
13. type var =
14.
      | Ident of string * sort
15.
       | Para of var * expression
16. and expression =
       | IVar of var
17.
18.
       | Const of scalar
19.
       | IteForm of formula * expression * expression
20. and formula =
       | Eqn of expression * expression
21.
       | AndForm of formula * formula
22.
23.
       | Neg of formula
       OrForm of formula * formula
24.
```

```
25. | ImplyForm of formula * formula
26. | Chaos
```

term-level tag invariant definition (non auto-generated)

Define manually the tag invariants of a assertion graph.

boolean-level assertion graph in Ocaml

Because boolean theory is a subset of first-order theory, so it is feasible to define bit-level assertion graph in term-level. That is we keep the assertion graph skeleton the same as before and define the assertion graph formula just using following constructors:

```
    BoolC
    BoolV
    AndForm
    Neg
```

boolean-level tag invariant in Ocaml

For one term-level tag invariant, use SMT/Z3 to obtain all the possible boolean-level tag invariants corresponding with it's term-level form. (undone)

symbolic trajectory evaluation formula in Ocaml

Define the STE formula in Ocaml, and then it's convenient to transform boolean-level assertion graph formula into symbolic trajectory evaluation formula in Ocaml and pave the way for transforming AG in Ocaml to AG in Forte.

```
1. (* trajectory.ml *)
 2. type bVar = Bvariable of string
   type bExpr =
         | EVar of bVar
4.
         | EAnd of bExpr * bExpr
 5.
         | EOr of bExpr * bExpr
         | ENeg of bExpr
 7.
 8.
9.
   let rec bExpr2FLbExprList be =
         match be with
10.
         | EVar (Bvariable name)-> Printf.sprintf "bvariable \"%s\"" name
11.
         EAnd (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bAND" ^(bExpr2FLbEx
12.
     prList be2)^ ")"
         | EOr (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bOR" ^(bExpr2FLbExpr
13.
     List be2) ^ ")"
         | ENeg be0 -> "(bNOT (" ^ (bExpr2FLbExprList be0) ^"))"
14.
15.
    type trajNode = Tnode of string
```

```
17.
18.
   type trajForm =
         | Is1 of trajNode
19.
20.
         | Is0 of trajNode
         | Next of trajForm
21.
22.
         | Guard of bExpr * trajForm
         | TAndList of trajForm list
23.
         | TChaos
24.
25.
26.
   let isb p tnode = TAndList [Guard (p, Is1 tnode); Guard ((ENeg p), Is0 tnod
     e)]
```

STE in Forte

transfrom the assertion graph (AG) defined in Ocaml into complete STE verification program in Forte;

In the meantime, transform tag invariants defined in (STE formula in Ocaml) into Forte-accepted language.

```
1. (** gsteSpec to forte input AG *)
    let toFL gs model_name binNodes=
 3.
         let rec trans trajf =
4.
             match trajf with
             TChaos -> []
 5.
             Is1 (Tnode name) -> [Printf.sprintf "Is1 \"%s\"" name]
6.
             Is0 (Tnode name) -> [Printf.sprintf "Is0 \"%s\"" name]
7.
             | Guard (be, tf) -> (
8.
9.
                 match (trans tf) with
10.
                 [] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
     "Chaos"]
11.
                 f::[] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList
      be) f]
                 | fs -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
12.
      "TAndList [" ^ (String.concat "," fs) ^ "]"]
13.
             )
             | TAndList ts -> List.flatten (List.map (fun f -> trans f) ts)
14.
             | _ -> raise (Invalid_argument "this is for boolean level trajectory
15.
      formula")
16.
         in
         let main_assertion_graph init_node node_set edge_set =
17.
             match init_node with (Vertex inum) -> Printf.fprintf stdout "let ver
18.
     texI = Vertex %d;\n" inum ;
             Printf.fprintf stdout "%s" ("let vertexL = [" ^ (String.concat ","
19.
     (List.map (fun (Vertex i) -> Printf.sprintf "Vertex %d" i) node_set)) ^
             Printf.fprintf stdout "%s" ("let edgeL = [" ^ (String.concat "," (Li
20.
     st.map (fun (Edge ((Vertex f), (Vertex t))) -> Printf.sprintf "Edge (Vertex %
     d) (Vertex %d)" f t) edge_set)) ^ "];\n");
         in
21.
```

```
22.
         let ant_function init_node node_set edge_set ants =
23.
             let ants_traj e =
                 let term_f = ants e in
24.
25.
                 let bit_f = termForm2bitForm term_f in
                 let traj_f = bitForm2trajForm bit_f in
26.
27.
                 let add_myclk fs =
                     match fs with
28.
                      | [] -> "TAndList []"
29.
                      | s -> "TAndList ["^ (String.concat "," (s@[Printf.sprintf
30.
     "IsO \"%s\"" visCLKname ; Printf.sprintf "Next (Is1 \"%s\")" visCLKname]))
     ^"]"
31.
32.
                 add_myclk (trans traj_f)
33.
             in
             Printf.fprintf stdout "%s" (
34.
35.
     "let ant aEdge =
36.
         val (Edge (Vertex from) (Vertex to)) = aEdge
37.
         in
     "^
38.
             (
39.
                 let items = List.map (fun e -> (
40.
                                                   match e with
41.
                                                   |Edge ((Vertex f),(Vertex t)) ->
      Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (ants_traj e)
42.
43.
                                  ) edge_set
44.
                 in
45.
                 let cases = String.concat "\n\t| " items in
                 let body = cases ^ "\n\t| error \"In cons: missing case\"" in
46.
                 Printf.sprintf "\t%s\n;\n\n" body
47.
48.
             )
         )
49.
50.
         in
51.
         let cons_function init_node node_set edge_set cons =
52.
             let cons_traj e =
53.
                 let term_f = cons e in
54.
                 let bit_f = termForm2bitForm term_f in
                 let traj_f = bitForm2trajForm bit_f in
55.
56.
                 let add tandlist ts =
57.
                     match ts with
58.
                      | [] -> "TAndList []"
59.
                      s -> "TAndList ["^ (String.concat "," s) ^"]"
60.
                 in
61.
                 add_tandlist (trans traj_f)
62.
             in
             Printf.fprintf stdout "%s" (
63.
     "let cons aEdge =
64.
65.
         val (Edge (Vertex from) (Vertex to)) = aEdge
66.
         in
67.
             (
68.
                 let items = List.map (fun e -> (
69.
                                                   match e with
```

```
70.
                                                   |Edge ((Vertex f),(Vertex t)) ->
       Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (cons_traj e)
 71.
 72.
                                   ) edge_set
 73.
                  in
 74.
                  let cases = String.concat "\n\t| " items in
                  let body = cases ^ "\n\t| error \"In cons: missing case\"" in
 75.
                  Printf.sprintf "\t%s\n;\n\n" body
 76.
 77.
              )
 78.
          )
 79.
          in
 80.
          let binNodesPart binNodes =
              let ivar2str iv =
 81.
 82.
                  match iv with
                  | IVar (Ident (str, Int n)) -> List.map (fun i -> formatMapVIS ~
 83.
      axis1:i str) (upt 0 (n-1))
 84.
                   | IVar (Ident (str, Bool)) -> [formatMapVIS str]
 85.
                   | _ -> raise (Invalid_argument "In toFL binNodesPart: sry la")
 86.
              in
 87.
              match binNodes with
 88.
              | [] -> "[]"
 89.
              | bns -> (
 90.
                  let strOfbns = (List.flatten (List.map (fun nd -> ivar2str nd) b
      ns)) in
                  let addQuoteMark = List.map (fun sob -> "\""^sob^"\"") strOfbns
 91.
      in
 92.
                  "[" ^ (String.concat "," addQuoteMark) ^"]"
 93.
              )
 94.
          in
 95.
          match gs with Graph (init_node , node_set, edge_set, ants, cons) -> (
              Printf.fprintf stdout
 96.
 97.
 98.
      let ckt = load_exe \"%s.exe\";
      load \"gsteSymReduce.fl\";
99.
100.
      loadModel ckt;
101.
      " model_name;
102.
              main_assertion_graph init_node node_set edge_set;
103.
              ant_function init_node node_set edge_set ants;
104.
              cons_function init_node node_set edge_set cons ;
105.
              Printf.fprintf stdout
106.
     let mainGoal = Goal [] (TGraph (Graph vertexL vertexI edgeL (Edge2Form ant)
       (Edge2Form cons)));
108. let binNodes = %s;
109.
      lemma \"lemmaTMain\" mainGoal;
110.
          by (gsteSymbSim binNodes);
111. done 0;
112.
      quit;
      " (binNodesPart binNodes)
113.
114.
          )
```

GSTE to "STE with tag-invariants"

to FL: term-level (assertion graph & tag-invariants) to Forte-accepted input language: At term-level: using SMT to solve the limited equation to get all possible instantiated invariants then transform tag-invariants sets (instantiated) into boolean-level invariants sets, then transform boolean-level invariants set into Forte-accepted tag invariants (defined in gsteSymReduce.fl)

STE with tag-invariants verification algorithm

```
    ## main function
    result = true;
    for edge in edgeL:
    result = result and check(edge)
    return result
```

```
1.
        ## check function
        # input : edge
2.
3.
        # output : boolean
4.
        val (Edge from to) = edge
        val (Vertex n1) = from
5.
6.
        val (Vertex n2) = to
7.
        ants_set = [ TAndList ((ant edge) : x) for x in (tag from) ]
        cons_set = [ TAndList ((cons edge): (map(Next, x))) for x in (tag to)]
8.
9.
        return check_next_ant(ants_set, cons_set)
```

```
## check_next_ant function
1.
2.
        # input : antss: an antecedent set , contss: a consequent set
3.
        # ouput : boolean
        for ant in antss:
4.
            if check_helper(conss, ant):
5.
                continue
6.
7.
            else:
8.
               return false
```

```
## check_helper function
1.
2.
        # input : conss: a consequent set, ant: an antecedent
3.
        # output : boolean
        result = false
4.
        for con in conss:
            if steSymbSimGoalfDirect(ant, con):
6.
                result = true
7.
8.
                break
9.
        return result
```

case analysis

ring buffer fifo

Considering a ring buffer fifo circuit with concrete parameters, the concrete parameters are following:

```
    let depth = 4 (* fifo depth *)
    let last = depth - 1 (* fifo maximum index value*)
    let data_length = 2 (* element width of fifo *)
    let index_length = 2 (* the variable (indicating index) 's width *)
```

we can define the main assertion graph's skeleton as follow:

```
1. (** main assertion graph *)
2. let vertexI = Vertex 0
3. let vertexL = vertexI :: ((Vertex 1):: (List.map (fun i -> Vertex i) (upt 3
     (2*last+4))))
4. (** odd-vertex selfloop edge, odd-vertex bidirection edge, odd-vertex to eve
     n-vertex edge, even-vertex backward edge, Vertex 4 to Vertex 1 edge*)
5. let edgeL = [Edge (vertexI,(Vertex 1))] @
                 (List.map (fun i -> Edge (Vertex (2*i+1), Vertex (2*i+1))) (upt
6.
      0 depth))@
                 (List.map (fun i -> Edge (Vertex (2*i-1), Vertex (2*i+1)))
7.
                                                                              (upt
      1 depth))@
                 (List.map (fun i \rightarrow Edge (Vertex (2*i+1), Vertex (2*i-1)))
8.
                                                                               (dwt
      depth 1))@
                 (List.map (fun i \rightarrow Edge (Vertex (2*i-1), Vertex (2*i+2)))
 9.
                                                                               (upt
      1 depth))@
10.
                 (List.map (fun i -> Edge (Vertex (2*i+2), Vertex (2*i)))
                                                                               (dwt
      depth 2))@
                 [Edge ((Vertex 4), (Vertex 1))]
11.
```

and the antecedent formula set and the consequent formula set can be defined like following:

```
1. (** actions of assertion graph *)
                : expression = IVar (Ident ("rst", Bool))
 let rst
                : expression = IVar (Ident ("push", Bool))
let push
4. let pop
                : expression = IVar (Ident ("pop", Bool))
5. let empty : expression = IVar (Ident ("empty", Bool))
               : expression = IVar (Ident ("full", Bool))
let full
                : expression = IVar (Ident ("dataIn", Int data_length))
7. let dataIn
8. let dataOut : expression = IVar (Ident ("dataOut", Int data_length))
let low
                : expression = Const (BoolC false)
                : expression = Const (BoolC true)
10.
   let high
```

```
let readDataIn : expression = Const (IntC (1, data_length))
12.
    let symbolDataOut : expression = Const (SymbIntC ("dout", data_length))
13.
14. let rstFormula = Eqn (rst, high)
15. let nrstFormula = Eqn (rst, low)
    let pushFormula = AndForm (nrstFormula, AndForm (Eqn (push, high), Eqn (po
     p, low)))
17. let popFormula = AndForm (nrstFormula, AndForm (Eqn (push, low), Eqn (pop,
     high)))
18. let noPopPushFormula = AndForm (nrstFormula, AndForm(Eqn (push,low), Eqn (po
     p, low)))
19. let fullFormula = Eqn (full, high)
20. let noFullFormula = Eqn (full, low)
21. let emptyFormula = Eqn (empty, high)
22. let noEmptyFormula = Eqn (empty, low)
23.
24. let pushData data = AndForm (pushFormula, Eqn (dataIn, data))
25.
    let popData data = Eqn (dataOut, data)
26.
27. let antOfRbFIFO aEdge =
28.
      let f = nodeToInt (source aEdge) in
29.
       let t = nodeToInt (sink aEdge)
30.
31.
         if( f == 0) then rstFormula
         else (
32.
33.
             if (f \mod 2 == 1) then (
34.
                 if (f = t) then noPopPushFormula
35.
                 else if ((f + 2) == t) then pushFormula
36.
                 else if (f == (t+2)) then popFormula
37.
                 else pushData readDataIn
38.
             )else popFormula
39.
         )
40.
       )
41.
    let consOfRbFIFO aEdge =
42.
43.
         let f = nodeToInt (source aEdge) in
         let t = nodeToInt (sink aEdge)
44.
45.
         (
46.
             if ((f mod 2 == 1)&&(t mod 2 == 1)) then (
47.
                 if (f == 1) then AndForm (emptyFormula, noFullFormula)
48.
                 else if (f == (2*depth+1)) then AndForm (noEmptyFormula, fullFor
     mula)
49.
                 else AndForm (noEmptyFormula, noFullFormula)
50.
             )else (
51.
                 if ((f == 4) && (t == 1)) then popData readDataIn
52.
                 else if (f == (2*depth+2)) then AndForm (noEmptyFormula, fullFo
     rmula)
53.
                 else if (f == 1) then AndForm (emptyFormula, noFullFormula)
                 else if (f == 0) then Chaos
54.
55.
                 else if (t == 4) then Chaos
                 else AndForm (noEmptyFormula, noFullFormula)
56.
57.
             )
```

```
58. )
```

A typical GSTE Assertion graph can be constructed by using following statement:

```
    let rbfifoGsteSpec = Graph (vertexI, vertexL, edgeL, antOfRbFIFO, consOfRbFI
    FO)
```

Next step it is about to construct the tag invariants set and transfrom the (GSTE assertion graph and tag invariants) into Forte-accepted input language by using tofl function

memory