

GSTE to “STE with tag invariants”

term-level GSTE theory

Constants, Variable, Expression and Formula

- A constant is either a natural number or boolean value, which also have corresponding symbolic version. Natural number in our theory consists of two parts: its value and its bit length, while a symbolic natural number consists of its name and its bit length. Each boolean constant carries a truth-value and each boolean symbolic constant just carries a name, which can be identified through Ocaml type constructor.

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term-level assertion graph definition

```
1. (*b_types.ml *)
2. type scalar =
3.   | IntC of int * int (* value * size *)
4.   | BoolC of bool
5.   | SymbIntC of string * int
6.   | SymbBoolC of string
7.
8. type sort =
9.   | Int of int (* size *)
10.  | Bool
11.  | Array of int * sort
12.
13. type var =
14.   | Ident of string * sort
15.   | Para of var * expression
16. and expression =
17.   | IVar of var
18.   | Const of scalar
19.   | ITEForm of formula * expression * expression
20. and formula =
21.   | Eqn of expression * expression
22.   | AndForm of formula * formula
23.   | Neg of formula
24.   | OrForm of formula * formula
25.   | ImplyForm of formula * formula
26.   | Chaos
```

term-level tag invariant definition (non auto-generated)

Define manually the tag invariants of a assertion graph.

boolean-level assertion graph in Ocaml

Because boolean theory is a subset of first-order theory, so it is feasible to define bit-level assertion graph in term-level. That is we keep the assertion graph skeleton the same as before and define the assertion graph formula just using following constructors:

1. BoolC
2. BoolV
3. AndForm
4. Neg

boolean-level tag invariant in Ocaml

For one term-level tag invariant, use SMT/Z3 to obtain all the possible boolean-level tag invariants corresponding with it's term-level form. (undone)

symbolic trajectory evaluation formula in Ocaml

Define the STE formula in Ocaml, and then it's convenient to transform boolean-level assertion graph formula into symbolic trajectory evaluation formula in Ocaml and pave the way for transforming AG in Ocaml to AG in Forte.

```
1. (* trajectory.ml *)
2. type bVar = Bvariable of string
3. type bExpr =
4.     | EVar of bVar
5.     | EAnd of bExpr * bExpr
6.     | EOr of bExpr * bExpr
7.     | ENeg of bExpr
8.
9. let rec bExpr2FLbExprList be =
10.     match be with
11.     | EVar (Bvariable name)-> Printf.sprintf "bvariable \"%s\"" name
12.     | EAnd (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bAND" ^ (bExpr2FLbExpr
prList be2)^ ")"
13.     | EOr (be1, be2) -> "(" ^ (bExpr2FLbExprList be1)^ "bOR" ^ (bExpr2FLbExpr
List be2) ^ ")"
14.     | ENeg be0 -> "(bNOT (" ^ (bExpr2FLbExprList be0) ^"))"
15.
16. type trajNode = Tnode of string
17.
18. type trajForm =
19.     | Is1 of trajNode
20.     | Is0 of trajNode
21.     | Next of trajForm
22.     | Guard of bExpr * trajForm
23.     | TAndList of trajForm list
24.     | TChaos
```

```

25.
26. let isb p tnode = TAndList [Guard (p, Is1 tnode); Guard ((ENeg p), Is0 tnode)]

```

STE in Forte

transform the assertion graph (AG) defined in Ocaml into complete STE verification program in Forte;

In the meantime, transform tag invariants defined in (STE formula in Ocaml) into Forte-accepted language.

```

1. (** gsteSpec to forte input AG *)
2. let toFL gs model_name binNodes=
3.   let rec trans trajf =
4.     match trajf with
5.     | TChaos -> []
6.     | Is1 (Tnode name) -> [Printf.sprintf "Is1 \"%s\"\" name]
7.     | Is0 (Tnode name) -> [Printf.sprintf "Is0 \"%s\"\" name]
8.     | Guard (be, tf) -> (
9.       match (trans tf) with
10.      | [] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
11.        "Chaos"]
12.      | f::[] -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList
13.        be) f]
14.      | fs -> [Printf.sprintf "Guard (%s) (%s)" (bExpr2FLbExprList be)
15.        "TAndList [" ^ (String.concat "," fs) ^ "]" ]
16.      )
17.     | TAndList ts -> List.flatten (List.map (fun f -> trans f) ts)
18.     | _ -> raise (Invalid_argument "this is for boolean level trajectory
19.       formula")
20.   in
21.   let main_assertion_graph init_node node_set edge_set =
22.     match init_node with (Vertex inum) -> Printf.fprintf stdout "let vertexI = Vertex %d;\n" inum ;
23.     Printf.fprintf stdout "%s" ("let vertexL = [" ^ (String.concat ","
24.       (List.map (fun (Vertex i) -> Printf.sprintf "Vertex %d" i) node_set)) ^
25.       "];\n" );
26.     Printf.fprintf stdout "%s" ("let edgeL = [" ^ (String.concat "," (List.map (fun (Edge ((Vertex f),(Vertex t))) -> Printf.sprintf "Edge (Vertex %d) (Vertex %d)" f t) edge_set)) ^ "];\n");
27.   in
28.   let ant_function init_node node_set edge_set ants =
29.     let ants_traj e =
30.       let term_f = ants e in
31.       let bit_f = termForm2bitForm term_f in
32.       let traj_f = bitForm2trajForm bit_f in
33.       let add_myclk fs =
34.         match fs with
35.         | [] -> "TAndList []"

```

```

30.         | s -> "TAndList ["^ (String.concat "," (s@[Printf.sprintf
    "Is0 \"%s\""" visCLKName ; Printf.sprintf "Next (Is1 \"%s\"") visCLKName]))
    ^"]"
31.         in
32.         add_myclk (trans traj_f)
33.         in
34.         Printf.fprintf stdout "%s" (
35. "let ant aEdge =
36.     val (Edge (Vertex from) (Vertex to)) = aEdge
37.     in
38.     "^      (
39.         let items = List.map (fun e -> (
40.             match e with
41.             | Edge ((Vertex f),(Vertex t)) ->
    Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (ants_traj e)
42.             )
43.         ) edge_set
44.         in
45.         let cases = String.concat "\n\t| " items in
46.         let body = cases ^ "\n\t| error \"In cons: missing case\""" in
47.         Printf.sprintf "\t%s\n;\n\n" body
48.     )
49. )
50. in
51. let cons_function init_node node_set edge_set cons =
52.     let cons_traj e =
53.         let term_f = cons e in
54.         let bit_f = termForm2bitForm term_f in
55.         let traj_f = bitForm2trajForm bit_f in
56.         let add_tandlist ts =
57.             match ts with
58.             | [] -> "TAndList []"
59.             | s -> "TAndList ["^ (String.concat "," s) ^"]"
60.         in
61.         add_tandlist (trans traj_f)
62.     in
63.     Printf.fprintf stdout "%s" (
64. "let cons aEdge =
65.     val (Edge (Vertex from) (Vertex to)) = aEdge
66.     in
67.     "^      (
68.         let items = List.map (fun e -> (
69.             match e with
70.             | Edge ((Vertex f),(Vertex t)) ->
    Printf.sprintf "((from = %d) AND (to = %d)) => %s " f t (cons_traj e)
71.             )
72.         ) edge_set
73.         in
74.         let cases = String.concat "\n\t| " items in
75.         let body = cases ^ "\n\t| error \"In cons: missing case\""" in
76.         Printf.sprintf "\t%s\n;\n\n" body
77.     )

```

```

78.     )
79.     in
80.     let binNodesPart binNodes =
81.         let ivar2str iv =
82.             match iv with
83.             | IVar (Ident (str, Int n)) -> List.map (fun i -> formatMapVIS ~
axis1:i str) (upt 0 (n-1))
84.             | IVar (Ident (str, Bool)) -> [formatMapVIS str]
85.             | _ -> raise (Invalid_argument "In toFL binNodesPart: sry la")
86.         in
87.         match binNodes with
88.         | [] -> "[]"
89.         | bns -> (
90.             let strOfbns = (List.flatten (List.map (fun nd -> ivar2str nd) b
ns)) in
91.             let addQuoteMark = List.map (fun sob -> "\""^sob^"\"") strOfbns
in
92.             "[" ^ (String.concat "," addQuoteMark) ^ "]"
93.         )
94.     in
95.     match gs with Graph (init_node , node_set, edge_set, ants, cons) -> (
96.         Printf.fprintf stdout
97.         "
98.         let ckt = load_exe \"%s.exe\";
99.         load \"gsteSymReduce.fl\";
100.        loadModel ckt;
101.        " model_name;
102.        main_assertion_graph init_node node_set edge_set;
103.        ant_function init_node node_set edge_set ants;
104.        cons_function init_node node_set edge_set cons ;
105.        Printf.fprintf stdout
106.        "
107.        let mainGoal = Goal [] (TGraph (Graph vertexL vertexI edgeL (Edge2Form ant)
(Edge2Form cons)));
108.        let binNodes = %s;
109.        lemma \"lemmaTMain\" mainGoal;
110.            by (gsteSymbSim binNodes);
111.        done 0;
112.        quit;
113.        " (binNodesPart binNodes)
114.    )

```

GSTE to “STE with tag-invariants”

toFL : term-level (assertion graph & tag-invariants) to Forte-accepted input language:

At term-level: using SMT to solve the limited equation to get all possible instantiated invariants
then transform tag-invariants sets (instantiated) into boolean-level invariants sets,
then transform boolean-level invariants set into Forte-accepted tag invariants (defined in
gsteSymReduce.fl)

STE with tag-invariants verification algorithm

```
1.    ## main function
2.    result = true;
3.    for edge in edgeL:
4.        result = result and check(edge)
5.    return result
```

```
1.    ## check function
2.    # input : edge
3.    # output : boolean
4.    val (Edge from to) = edge
5.    val (Vertex n1) = from
6.    val (Vertex n2) = to
7.    ants_set = [ TAndList ((ant edge) : x) for x in (tag from) ]
8.    cons_set = [ TAndList ((cons edge): (map(Next, x))) for x in (tag to)]
9.    return check_next_ant(ants_set, cons_set)
```

```
1.    ## check_next_ant function
2.    # input : antss: an antecedent set , contss: a consequent set
3.    # output : boolean
4.    for ant in antss:
5.        if check_helper(conss, ant):
6.            continue
7.        else:
8.            return false
```

```
1.    ## check_helper function
2.    # input : conss: a consequent set, ant: an antecedent
3.    # output : boolean
4.    result = false
5.    for con in conss:
6.        if steSymbSimGoalFDirect(ant, con):
7.            result = true
8.            break
9.    return result
```

case analysis

ring buffer fifo

Considering a ring buffer fifo circuit with concrete parameters, the concrete parameters are following:

```

1. let depth = 4 (* fifo depth *)
2. let last = depth - 1 (* fifo maximum index value*)
3. let data_length = 2 (* element width of fifo *)
4. let index_length = 2 (* the variable (indicating index) 's width *)

```

we can define the main assertion graph's skeleton as follow:

```

1. (** main assertion graph *)
2. let vertexI = Vertex 0
3. let vertexL = vertexI :: ((Vertex 1):: (List.map (fun i -> Vertex i) (upt 3
(2*last+4))))
4. (** odd-vertex selfloop edge, odd-vertex bidirection edge, odd-vertex to eve
n-vertex edge, even-vertex backward edge , Vertex 4 to Vertex 1 edge*)
5. let edgeL = [Edge (vertexI,(Vertex 1))] @
6.             (List.map (fun i -> Edge (Vertex (2*i+1), Vertex (2*i+1))) (upt
0 depth))@
7.             (List.map (fun i -> Edge (Vertex (2*i-1), Vertex (2*i+1))) (upt
1 depth))@
8.             (List.map (fun i -> Edge (Vertex (2*i+1), Vertex (2*i-1))) (dwt
depth 1))@
9.             (List.map (fun i -> Edge (Vertex (2*i-1), Vertex (2*i+2))) (upt
1 depth))@
10.            (List.map (fun i -> Edge (Vertex (2*i+2), Vertex (2*i))) (dwt
depth 2))@
11.            [Edge ((Vertex 4), (Vertex 1))]

```

and the antecedent formula set and the consequent formula set can be defined like following:

```

1. (** actions of assertion graph *)
2. let rst      : expression = IVar (Ident ("rst", Bool))
3. let push     : expression = IVar (Ident ("push", Bool))
4. let pop      : expression = IVar (Ident ("pop", Bool))
5. let empty    : expression = IVar (Ident ("empty", Bool))
6. let full     : expression = IVar (Ident ("full", Bool))
7. let dataIn   : expression = IVar (Ident ("dataIn", Int data_length))
8. let dataOut  : expression = IVar (Ident ("dataOut", Int data_length))
9. let low      : expression = Const (BoolC false)
10. let high     : expression = Const (BoolC true)
11. let readDataIn : expression = Const (IntC (1, data_length))
12. let symbolDataOut : expression = Const (SymbIntC ("dout", data_length))
13.
14. let rstFormula = Eqn (rst, high)
15. let nrstFormula = Eqn (rst, low)
16. let pushFormula = AndForm (nrstFormula, AndForm (Eqn (push, high), Eqn (po
p, low)))
17. let popFormula = AndForm (nrstFormula, AndForm (Eqn (push, low), Eqn (pop,
high)))

```

```

18. let noPopPushFormula = AndForm (nrstFormula, AndForm(Eqn (push,low), Eqn (pop, low)))
19. let fullFormula = Eqn (full, high)
20. let noFullFormula = Eqn (full, low)
21. let emptyFormula = Eqn (empty, high)
22. let noEmptyFormula = Eqn (empty, low)
23.
24. let pushData data = AndForm (pushFormula, Eqn (dataIn, data))
25. let popData data = Eqn (dataOut, data)
26.
27. let antOfRbFIFO aEdge =
28.   let f = nodeToInt (source aEdge) in
29.   let t = nodeToInt (sink aEdge) in
30.   (
31.     if( f == 0) then rstFormula
32.     else (
33.       if (f mod 2 == 1 ) then (
34.         if (f = t) then noPopPushFormula
35.         else if ((f + 2) == t) then pushFormula
36.         else if ( f == (t+2)) then popFormula
37.         else pushData readDataIn
38.       )else popFormula
39.     )
40.   )
41.
42. let consOfRbFIFO aEdge =
43.   let f = nodeToInt (source aEdge) in
44.   let t = nodeToInt (sink aEdge) in
45.   (
46.     if ((f mod 2 == 1)&&(t mod 2 == 1)) then (
47.       if (f == 1) then AndForm (emptyFormula, noFullFormula)
48.       else if (f == (2*depth+1)) then AndForm (noEmptyFormula, fullFormula)
49.       else AndForm (noEmptyFormula, noFullFormula)
50.     )else (
51.       if ((f == 4) && (t == 1)) then popData readDataIn
52.       else if (f == (2*depth+2)) then AndForm (noEmptyFormula, fullFormula)
53.       else if (f == 1) then AndForm (emptyFormula, noFullFormula)
54.       else if (f == 0) then Chaos
55.       else if (t == 4) then Chaos
56.       else AndForm (noEmptyFormula, noFullFormula)
57.     )
58.   )

```

A typical GSTE Assertion graph can be constructed by using following statement:

```

1. let rbfifoGsteSpec = Graph (vertexI, vertexL, edgeL, antOfRbFIFO, consOfRbFIFO)

```


Next step it is about to construct the tag invariants set and transfrom the (GSTe assertion graph and tag invariants) into Forte-accepted input language by using `toFL` function

memory
