# Automating detection of near-Earth asteroids with LISA

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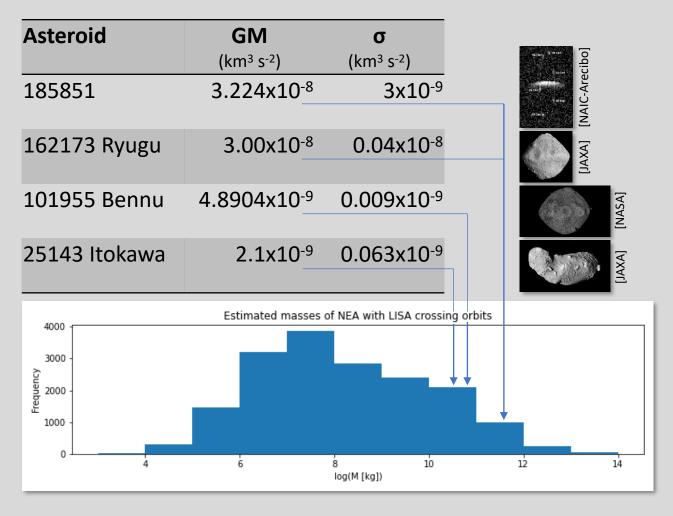




### Automating detection of NEA with LISA

- Known NEA masses
- Modelling NEA encounters
- Simulating LISA telemetry
- Neural networks used
- Interim results
- Summary and remaining tasks

#### Known NEA masses [1]



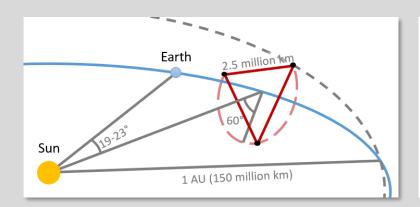
#### Gravitational measurements [2]

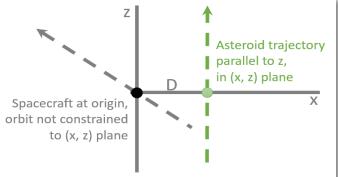
- Asteroid-asteroid / -planet
- Spacecraft fly-by / orbit
- Binary asteroids' orbits

#### **Estimation methods**

- Yarkovsky effect [3]
- Absolute magnitude + albedo + shape + density

### Modelling NEA encounters





$$\vec{v}(t) = \frac{GM}{DV} \begin{bmatrix} 1 + \frac{Vt/D}{\sqrt{1 + V^2 t^2/D^2}} \\ 0 \\ -\frac{Vt/D}{\sqrt{1 + V^2 t^2/D^2}} \end{bmatrix}_{[4]}$$

Then, for any combination of incident angles  $(\chi, \psi, \omega)$  about X, Y and Z axes:

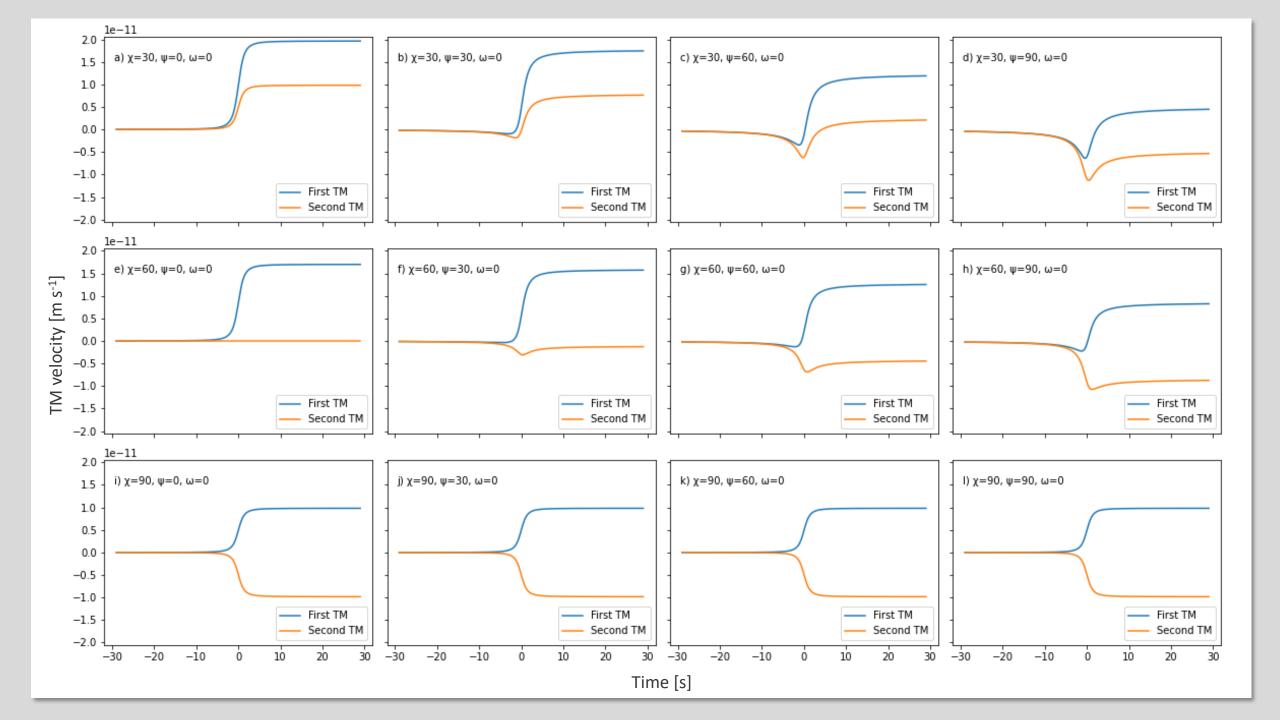
$$\overrightarrow{v_i}(t) = \frac{GM}{DV} R_Z(\omega) \cdot R_Y(\psi) \cdot R_X(\chi) \cdot R_Z(\beta_i) \cdot \begin{bmatrix} 1 + \frac{Vt/D}{\sqrt{1 + V^2 t^2/D^2}} \\ 0 \\ -\frac{Vt/D}{\sqrt{1 + V^2 t^2/D^2}} \end{bmatrix} \qquad R_Z(\beta_i) = \begin{bmatrix} \cos \beta_i & \sin \beta_i & 0 \\ -\sin \beta_i & \cos \beta_i & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 And the two test masses have: 
$$\beta_i = \pm \pi/6$$

Where:

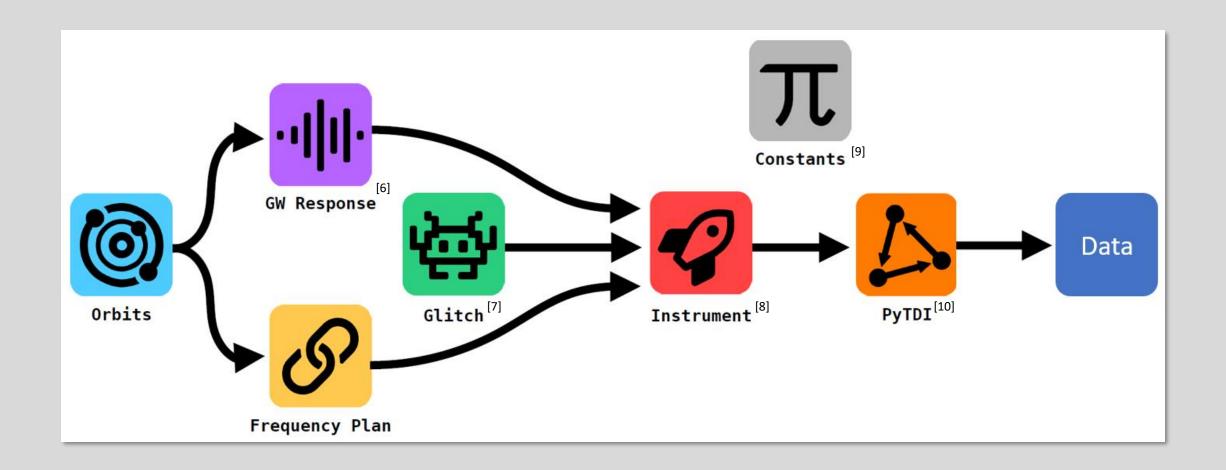
$$R_Z(\beta_i) = \begin{bmatrix} \cos \beta_i & \sin \beta_i & 0 \\ -\sin \beta_i & \cos \beta_i & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\beta_i = \pm \pi/6$$

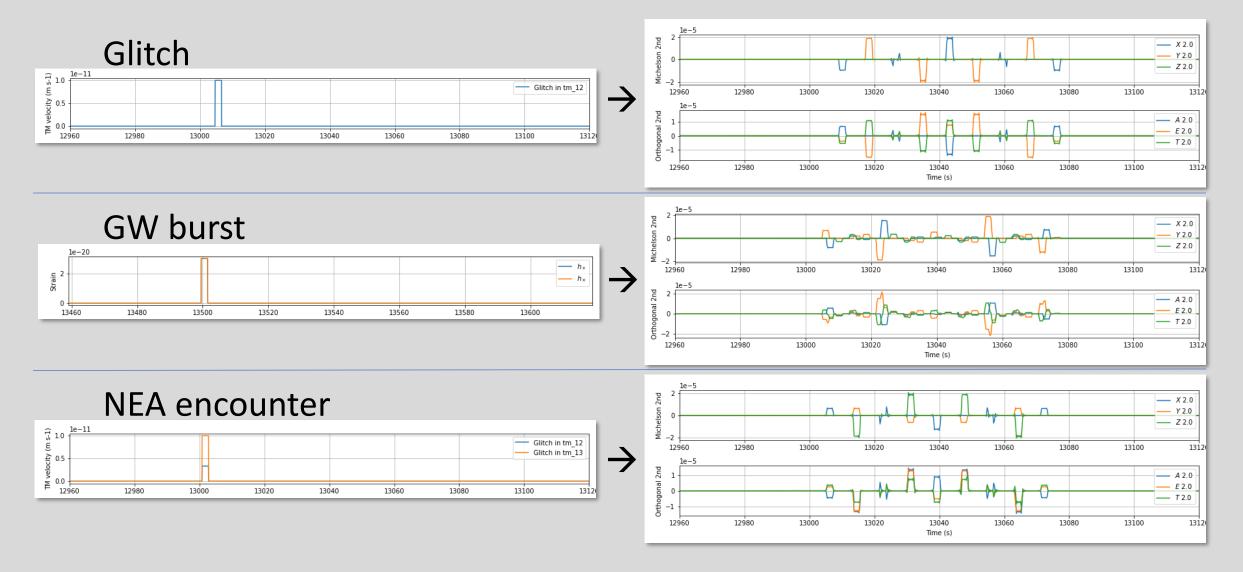
[5]



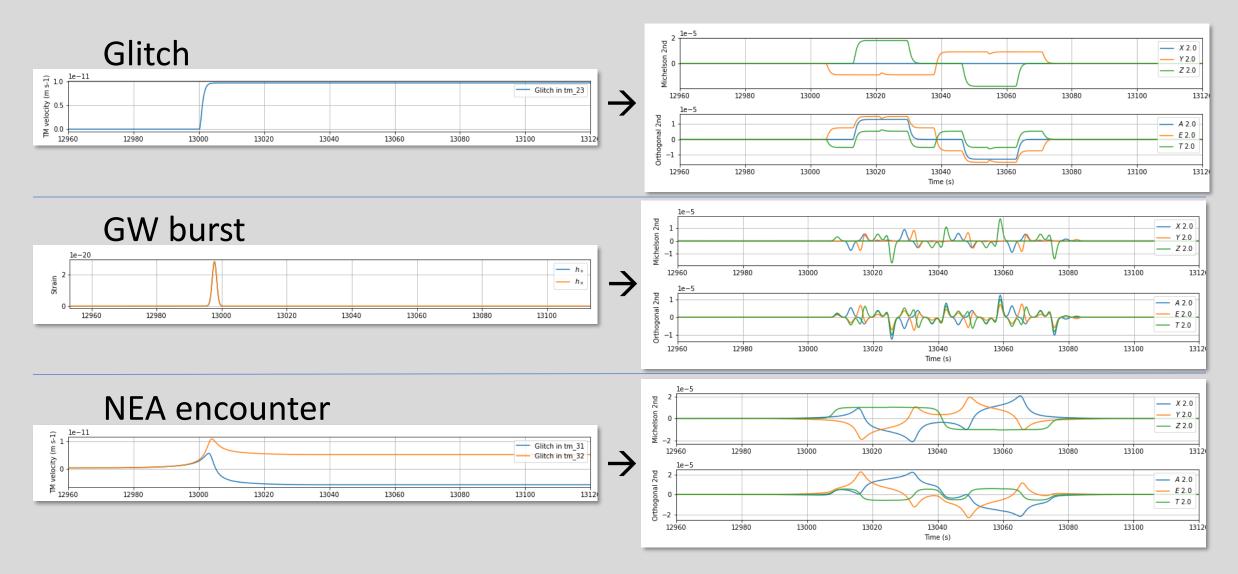
## Simulating LISA telemetry



# Simulating LISA telemetry: rectangular



## Simulating LISA telemetry: various



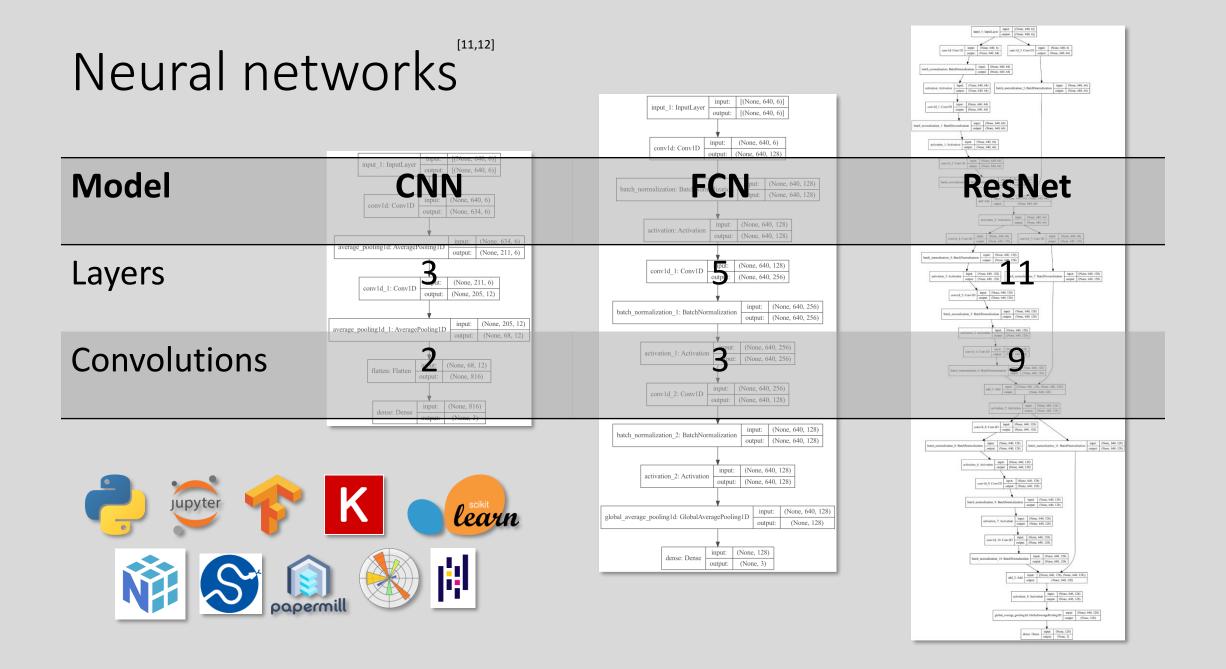
### Simulating LISA telemetry: datasets

#### # Rectangular shapes and no instrument noise

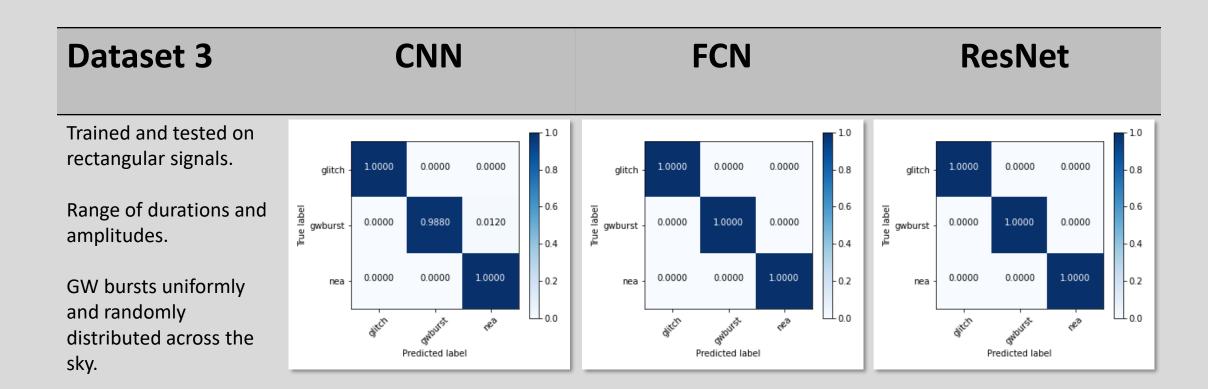
- 1 Fixed duration, amplitude and sky location.
- 2 Durations and amplitudes drawn from normal distributions.
- 3 GW bursts uniformly distributed across the sky.

#### # Different shapes for each instance type

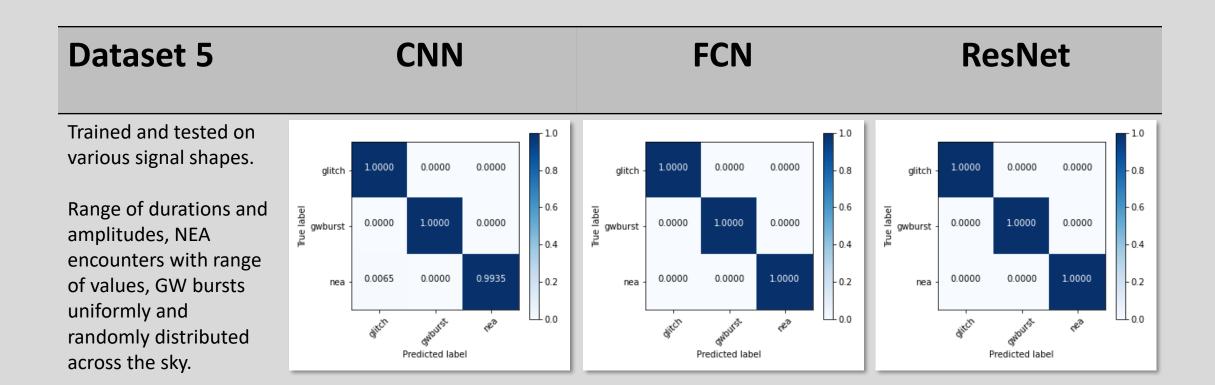
- 4 LISA Glitch shapelet. GW bursts use a gaussian shape.
  - Fixed NEA mass, velocity and impact parameter over all incident angles.
- 5 NEA mass and velocity distributed uniformly over a range of values.
- 6 With instrument noise added.
- 7 NEA mass, velocity and impact parameter distributed over wider ranges.



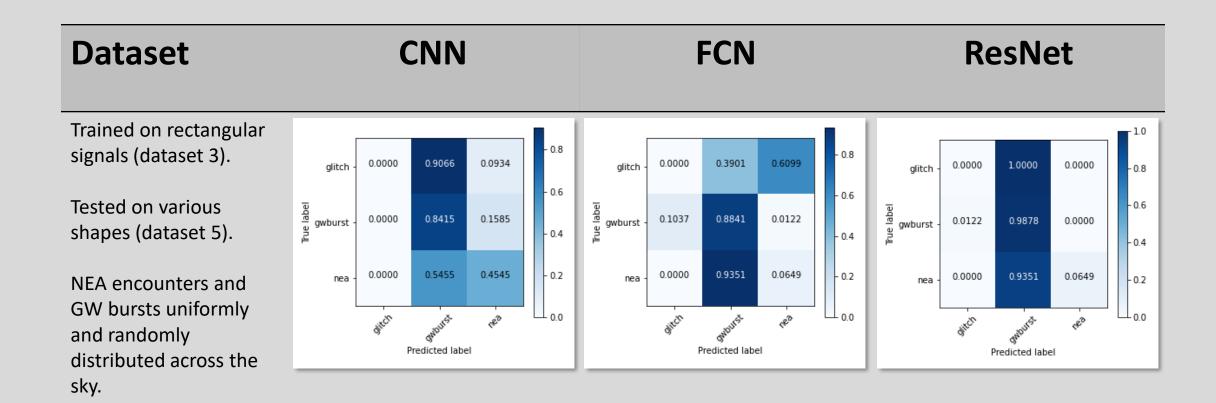
### Interim results: rectangular



#### Interim results: various



### Interim results: cross-testing



### Summary, so far...

- NEA encounters can be differentiated from glitches and GW bursts
- Neural networks trained on rectangular shaped signals did not successfully differentiate between different shapes
- CNN was the most efficient neural network

### Remaining tasks

- Add noise to LISA simulations
- Use a wider range of NEA parameters

### Thank you to LECS and LISA Consortium

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- [5] Purdue, P. and Larson, S.L. (2007) "Spurious acceleration noise in spaceborne gravitational wave interferometers," Classical and Quantum Gravity, 24(23), p. 5869. DOI: 10.1088/0264-9381/24/23/010.
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