

VISHNU INSTITUTE OF TECHNOLOGY (AUTONOMOUS)
VISHNUPUR: BHIMAVARAM
Mid – I Examinations
Deep Learning

BRANCH : AI&DS, AIML

YEAR/SEM : III B. Tech. II Sem.

UNIT-I

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|----|---|-------|----|-------|
| 1 | Explain various paradigms of deep learning problems. | [CO1] | L1 | [12M] |
| 2 | What is deep learning framework. Explain the Perspectives, and Issues in the deep learning framework. | [CO1] | L1 | [12M] |
| 3 | Explain the concept of a Perceptron with a neat diagram. | [CO1] | L3 | [12M] |
| 4 | What is Artificial Neural Network and its architecture? | [CO1] | L1 | [12M] |
| 5 | Explain the structure of biological neuron in detail. What is the motivation for Neural network. | [CO1] | L1 | [12M] |
| 6 | Discuss the XOR problem and suggest a solution using Neural Network. | [CO1] | L3 | [12M] |
| 7 | Explain Multi-layer perceptron in detail | [CO1] | L2 | [12M] |
| 8 | Summarize the mathematical model of neural unit | [CO1] | L1 | [12M] |
| 9 | Explain the following non-linear functions by covering mathematical intuition, plots and derivatives
a. Sigmoid
b. ReLU
c. Tanh | [CO1] | L2 | [12M] |
| 10 | Consider a unit with the following input vector, weight vector, and bias and compute the output by applying sigmoid, relu and tanh activation functions. a. $w = [0.2, 0.3, 0.9]$ b. $b = 0.5$ c. $x = [0.5, 0.6, 0.1]$ | [CO1] | L3 | [12M] |

UNIT-II

1	What is RMSprop, and how does it address some of the issues with traditional gradient descent?	[CO2]	L2	[12M]
2	How does early stopping prevent overfitting in deep neural networks?	[CO2]	L2	[12M]
3	Explain Gradient Descent. How does stochastic gradient descent differ from batch gradient descent?	[CO2]	L2	[12M]
4	What are the challenges associated with training deep neural networks compared to shallow networks?	[CO2]	L1	[12M]
5	Explain in detail about multilayer neural network	[CO2]	L1	[12M]
6	Illustrate the data augmentation technique in detail.	[CO2]	L2	[12M]
7	Explain the following loss functions a) Binary cross entropy loss b) Categorical cross entropy loss	[CO2] [CO2]	L3 L3	[6M] [6M]
8	Explain back propagation algorithm for neural networks.	[CO2]	L3	[12M]
9	How does dropout prevent overfitting, and what is its impact on training?	[CO2]	L1	[12M]
10	Explain in detail about the concept of gradient based learning.	[CO2]	L3	[12M]

UNIT-III

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| 1 | What is the role of a convolutional layer in a CNN, and how does it differ from fully connected layers in traditional neural networks? | [CO3] | L3 | [6M] |
| 2 | How does the stride parameter affect the output size of the convolutional layer? | [CO3] | L1 | [6M] |
| 3 | What is the purpose of the fully connected layers at the end of a CNN? | [CO3] | L1 | [6M] |
| 4 | How can CNNs handle input images of different sizes without altering the network architecture? | [CO3] | L2 | [6M] |
| 5 | Can you outline the typical architecture of a CNN and the sequence of its building blocks? | [CO3] | L2 | [6M] |
| 6 | What is global average pooling, and how does it contribute to handling input size variations? | [CO3] | L1 | [6M] |
| 7 | Describe the difference between max pooling and average pooling. | [CO3] | L2 | [6M] |
| 8 | Why is padding used in convolutional layers, and what are its effects on the output size? | [CO3] | L2 | [6M] |
| 9 | Can you explain the concept of filters or kernels in the context of the convolution operation? | [CO3] | L1 | [6M] |
| 10 | What is the purpose of the convolution operation in a Convolutional Neural Network (CNN)? | [CO3] | L2 | [6M] |