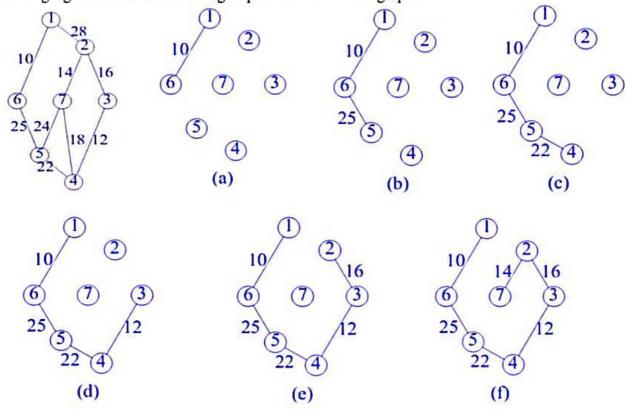
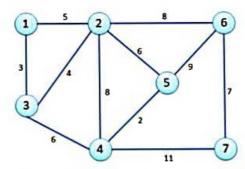
Prim's Algorithm:

- · The set of edges selected by this algorithm should form a tree.
- · Start from an arbitrary vertex and store it in A.
- Thus, if A is the set of edges selected so far, then A forms a tree.
 - The next edge (u, v) to be included in A is a minimum-cost edge not in A with the property that AU((u,v)) is also a tree.

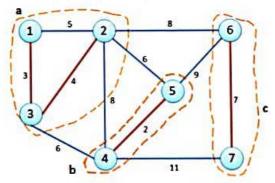
Following figures shows the working of prim's method on a graph.



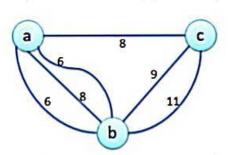
Example:
Given input graph G is

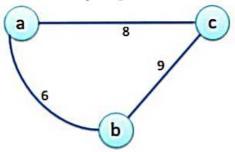


Randomly sampled 4 edges (1,3), (2,3), (4,5) and (6,7) Selected edges are forming three trees (forest). They should be minimum spanning trees.

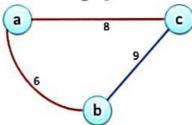


Using F translate the given Graph G into G1 and remove the heavy edges.

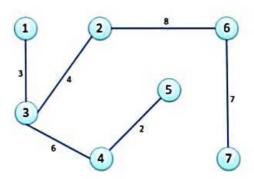




Apply the same process recursively on obtained graph



The resultant minimum spanning tree is



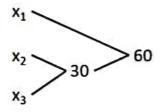
4

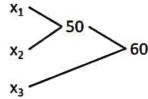
Optimal Merge Patterns

Problem: Determining an optimal way (one requiring the fewest comparisons) to pair-wise merge n sorted files.

- Merging two sorted files having n and m records to obtain one sorted file takes O(n+m) time.
- When more than two sorted files are to be merged together, the merge can be accomplished by repeatedly merging sorted files in pairs.
- · Given n sorted files, there are many ways in which to pairwise merge them into a single sorted file.
- Different pairings require different computing time.

Eg: Consider three files x1, x2, x3 with record lengths 30, 20, 10.





This merge pattern is taking 90 comparisons

This merge pattern is taking 110 comparisons.

Greedy method to obtain an optimal merge pattern:

<u>Selection criterion:</u> since merging n-record and m-record files requires n+m record moves, the obvious choice is at each step merge the two smallest size files together.

Eg: no.of files = 5

(x1, x2, x3, x4, x5) sizes (20, 30, 10, 5, 30)

Merge x3 and x4 to get z1 \rightarrow |z1| = 15

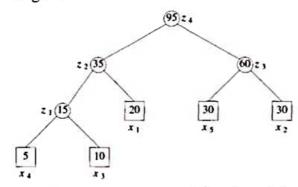
Merge z1 and x1 to get z2 \rightarrow |z2| = 35

Merge x2 and x5 to get z3 \rightarrow |z3| = 60

Merge z2 and z3 to get z4 \rightarrow |z4| = 95

The total number of record moves = 205

It can be represented as a binary merge tree.



- The leaf nodes are drawn as squares and represent the given five files. These nodes are called external nodes.
- Remaining nodes are drawn as circles and are called internal nodes.
- Each internal node has exactly two children.
- The number in each node is the length (no.of records) of the file represented by that node.

- The external node x4 is at a distance of 3 from the root node z4. i.e., the records of file x4 are moved three times, once to get z1, once to get z2 and finally to get z4.
- Total number of record moves for the binary merge tree is $\sum_{i=1}^{n} d_i q_i$
 - o di is the distance from the root to the external node for file xi
 - o qi is the length of xi
- This sum is the weighted external path length of the tree.

Algorithm to generate a 2-way merge tree:

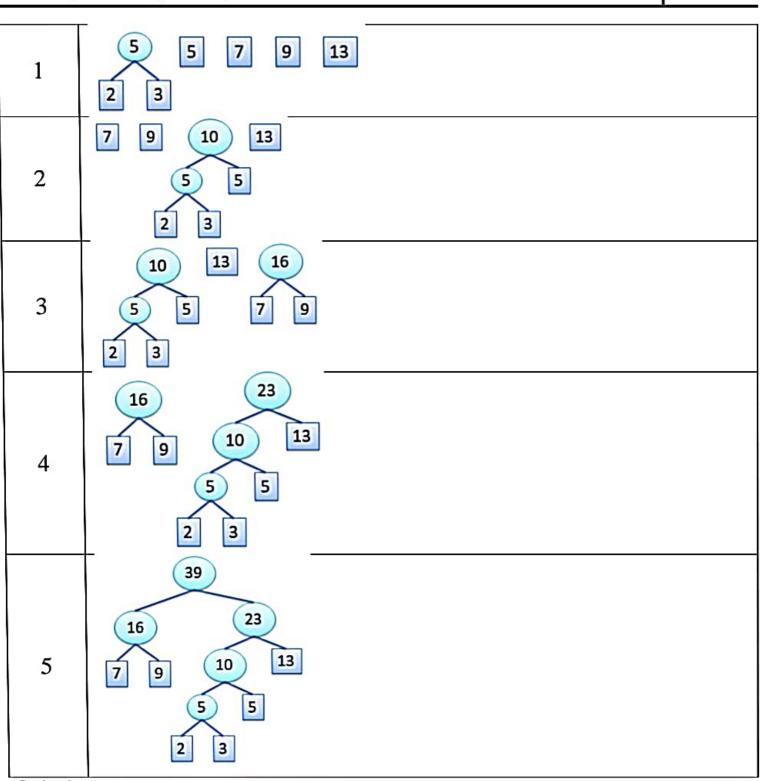
- Input to this algorithm is list of n trees. Each node in a tree has 3 fields Ichild, rchild, weight.
- Initially, each tree in list has exactly one node.
- Least(list) function finds a tree in list whose root has least weight.
- Insert() function is used to insert a node into the list.

Analysis:

- Main for loop is executed (n-1) times
- If list is kept in nondecreasing order according to weight value in the roots, then Least(list) requires
 O(1) time
- Insert(list, t) can be done in O(n) time.
- Hence, the total time taken is O(n²)

Eg: Trace the algorithm for 6 files with lengths 2, 3, 5, 7, 9, 13

Iteration							List		
Initially	2	3	5	7	9	13			



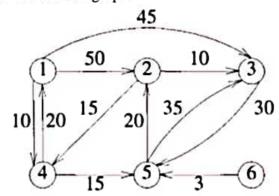
Optimal merge pattern

- 1. Merge files whose lengths are 2 and 3
- 2. Merge files whose lengths are 5 and 5
- 3. Merge files whose lengths are 7 and 9
- 4. Merge files whose lengths are 10 and 13
- 5. Merge files whose lengths are 16 and 23

Exercise:

Find an optimal binary merge pattern for ten files whose lengths are 28, 32, 12, 5, 84, 53, 91, 35, 3, 11

6 Example: Use algorithm ShortestPaths to obtain in non-decreasing order the lengths of the shortest paths from vertex Ito all remaining vertices in the digraph.



$$V_0 = 1$$

Cost matrix =
$$\begin{bmatrix} 0 & 50 & 45 & 10 & \infty & \infty \\ \infty & 0 & 13 & 15 & \infty & \infty \\ \infty & \infty & 0 & \infty & 30 & \infty \\ 20 & \infty & \infty & 0 & 15 & \infty \\ \infty & 20 & 35 & \infty & 0 & \infty \\ \infty & \infty & \infty & \infty & 3 & 0 \end{bmatrix}$$

Trace of the algorithm

Iteration	S	Vertex	Distance							
	3	selected	[1]	[2]	[3]	[4]	[5]	[6]		
Initially			0	50	45	10	∞	000		
1	{1}	4	0	50	45	10	25	œ		
2	{1, 4}	5	0	45	45	10	25	8		
3	{1,4,5}	2	0	45	45	10	25	8		
4	{1,2,4,5}	-3	0	45	45	10	25	00		
5	{1,2,3,4,5}	6	0	45	45	10	25	∞		
6	{1,2,3,4,5,6}									

7 Single Source Shortest Paths

- <u>Problem</u>: Given a directed graph G = (V, E), a weighting function cost for the edges of G, and a source vertex v₀, The problem is to determine the shortest paths from v₀ to all the remaining vertices of G.
- It is assumed that all the weights are positive.
- The shortest path between v₀ and other node v is an ordering among a subset of the edges. Hence this
 problem fits the ordering paradigm.
- A multistage solution must be conceived to formulate a greedy-based algorithm to generate shortest paths.
- Here the optimization measure is, each individual path must be of minimum length.
- The greedy way to generate the shortest paths from v₀ to the remaining vertices is to generate these paths in increasing order of the path length.
- First, a shortest path to the nearest vertex is generated, and then a shortest path to the second nearest vertex is generated, and so on.

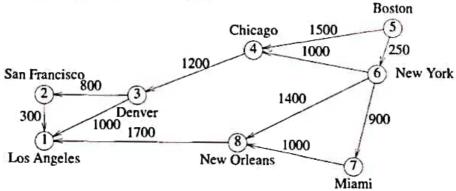
```
• For eg: nearest vertex to (v0 = 1) is 4 cost[1, 4] = 10
Second nearest vertex to (v0 = 1) is 5 distance = 25 path 1, 4, 5 is generated.
```

- Inorder to generate the shortest paths in this order, we need to determine
 - 1. The next vertex to which a shortest path must be generated &
 - 2. A shortest path to this vertex.
- Greedy algorithm to generate shortest paths is Algorithm ShortestPaths(v, cost, dist, n)

```
// dist[j], 1 \le j \le n, is set to the length of the shortest path from vertex v to vertex j in a digraph G with
// n vertices. dist[v] is set to zero. G is represented by its cost adjacency matrix cost[l:n,1:n].
        for i := 1 to n do
        {
                S[i] := false;
                dist[i] := cost[v, i];
        S[v] := true;
        for num := 1 to n-1 do
                choose u from among those vertices not in S such that dist[u] is minimum;
                S[u] := false;
                for (each w adjacent to u with S[w]=false) do
                        //update the distances
                        if (dist[w] > dist[u] + cost[u,w]) then
                               dist[w] := dist[u] = cost[u, w];
        }
}
```

- Let S denote the set of vertices (including v₀) to which the shortest paths have already been generated.
- For w, not in S, let dist[w] be the length of the shortest path starting from v₀, going through only
 those vertices that are in S, and ending at w.

8 Example 2: Use algorithm ShortestPaths to obtain in non-decreasing order the lengths of the shortest paths from city Boston to all remaining cities in the digraph.



16 Department of CSE

Design and Analysis of Algorithms

Unit-I

Length-adjacency matrix

	. 1	2	3	4	5	6	7	8
1.	0							
2	300	0						
3	100	800	0					ì
4			1200	0				
5				1500	0	250		
6				1000		0	900	1400
7							0	1000
8	1700							0

Tracing

Iteration			Distance									
	S	Vertex	LA	SF	DEN	СНІ	BOST	NY	MIA	NO		
		selected	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]		
Initial	•		+00	+∞	+∞	1500	0	250	+00	+00		
1	15)	6	+∞	+∞	+00	1250	0	250	1150	1650		
2	(5.6)	7	+∞	+00	+00	1250	0	250	1150	1650		
3	{5,6,7}	4	+00	+00	2450	1250	0	250	1150	1650		
4	{5,6,7,4}	8	3350	+∞	2450	1250	0	250	1150	1650		
5	15.6,7,4,8}	3	3350	3250	2450	1250	0	250	1150	1650		
6	{5,6,7,4,8,3}	2	3350	3250	2450	1250	0	250	1150	1650		
	{5,6,7,4,8,3,2}	j.)									