Unlocking the support from DER via risk-constrained optimization

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Paper:

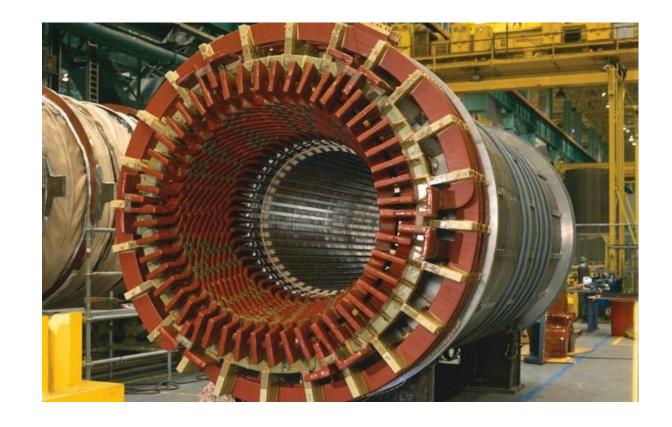
C. O'Malley, L. Badesa *et al.*, "Frequency Response from Aggregated V2G Chargers With Uncertain EV Connections," *IEEE Trans. on Power Systems*, 2023

Paper available <u>here</u>

Lower inertia on the road to lower emissions

Thermal generators

(nuclear, gas, coal...)







Most renewables: no inertia



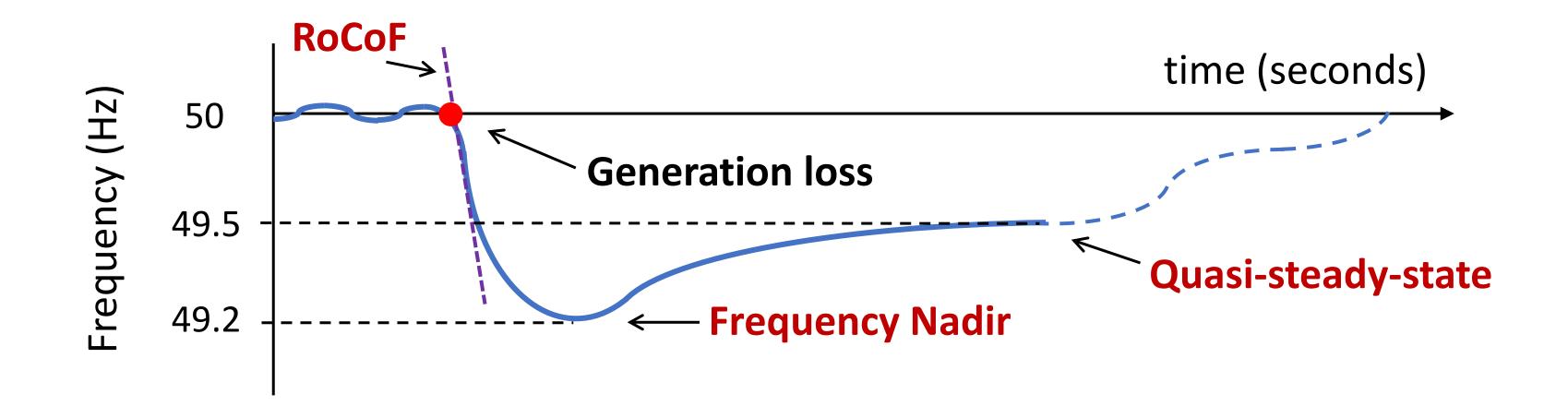
The risk of instability has increased!



Inertia stores kinetic energy:

this energy gave us time to contain a sudden generation-demand imbalance

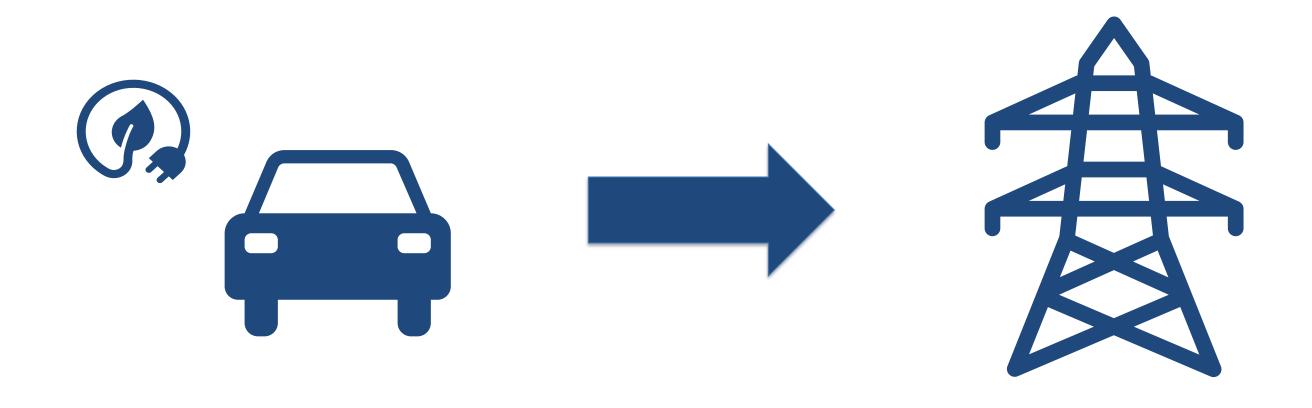
Frequency stability



Key to keep frequency within safe limits to avoid demand disconnection!

Unlocking support from Distributed Energy Resources

- DER could be very valuable to support system stability, but they
 are inherently uncertain
- We focus on **Vehicle-to-Grid (V2G)**: the system operator cannot control when the EV owners plug in their vehicles



Why is this important?

Now



Future

Stability through gas plants

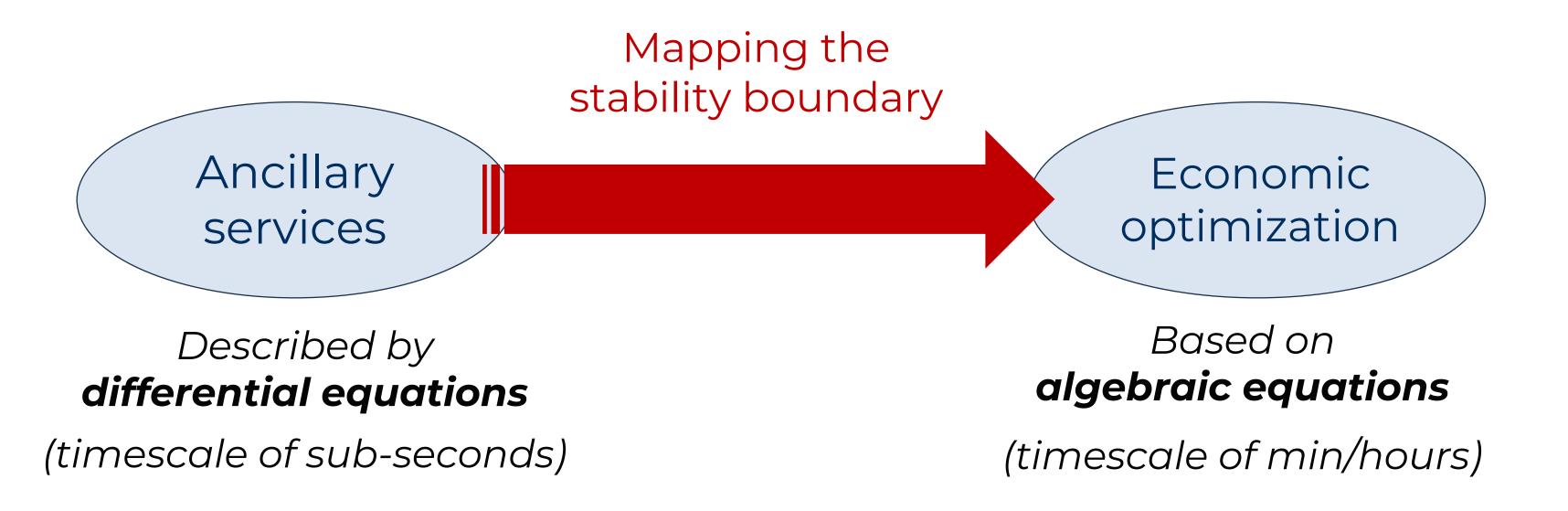
- Pros: certain + reliable
- Cons: expensive + polluting

Stability services from **DER**

- Pros: abundant + cheap
- Cons: uncertain

Stability conditions for optimization

What is the value of V2G as a countermeasure to low inertia?



Uncertainty within the stability conditions

We propose the use of chance constraints:

Probability of complying with **stability limit** ≥ 1 - €



Uncertainty in **EV plug-in** times



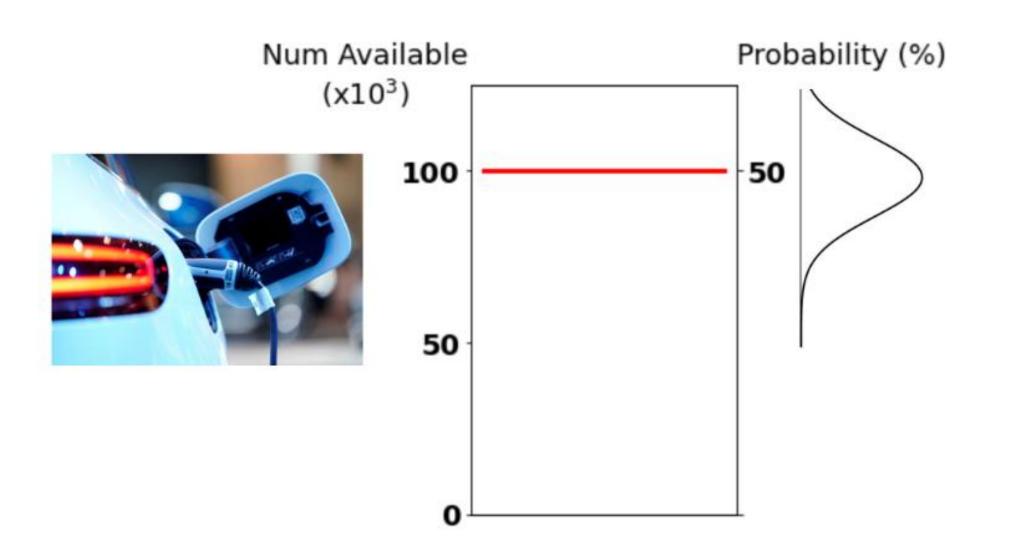


Risk appetite (e.g., 1% chance of under-delivery)

What do we mean by risk?

Probabilistic forecast

for EV connections



Naïve scheduling:

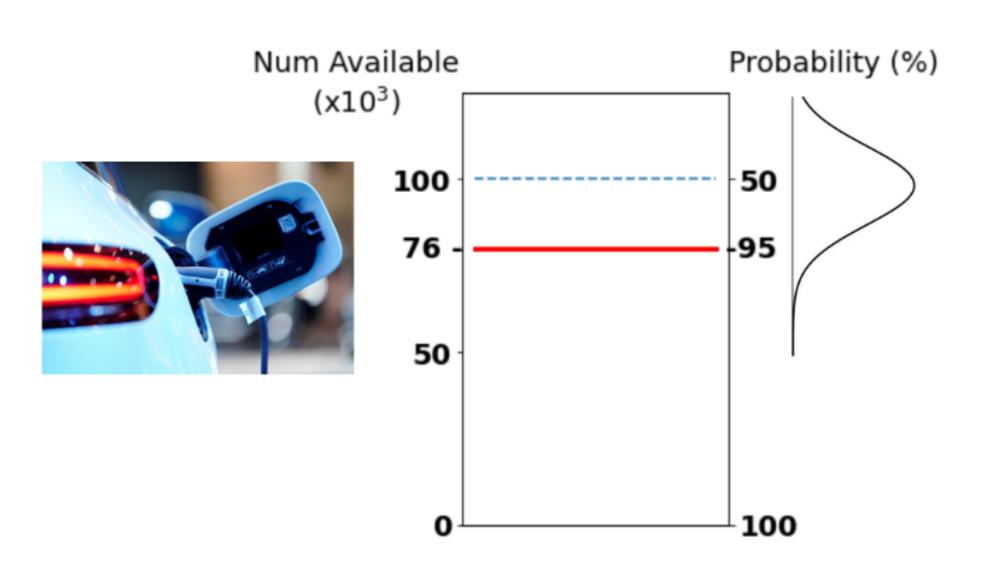
- Use deterministic
 forecast (mean)
- Count on 100k EVs
- 50% chance of having less than expected

Risky!

What do we mean by risk?

Probabilistic forecast

for EV connections



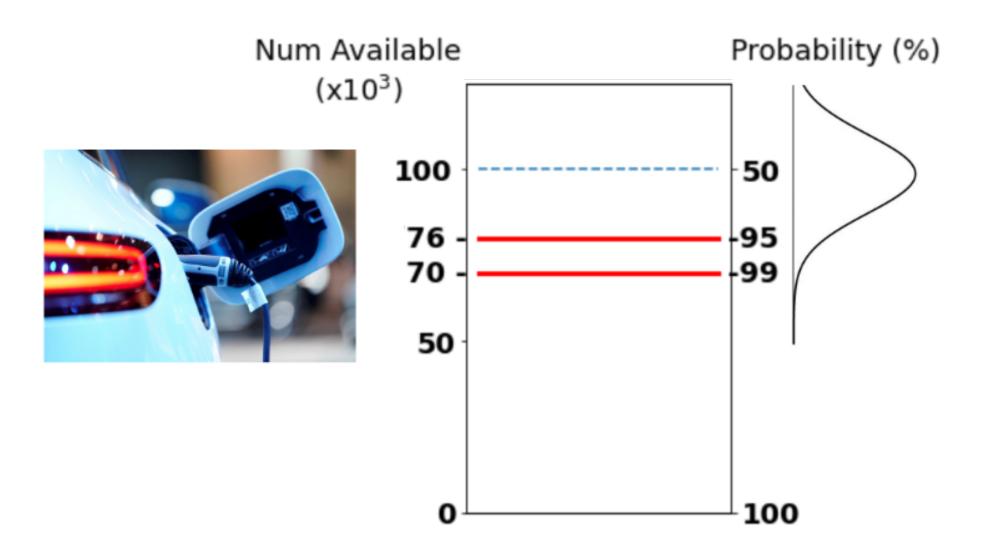
Risk-limited scheduling:

- Specify risk tolerance (e.g., 5%)
- Count on 76k EVs

What do we mean by risk?

Probabilistic forecast

for EV connections



Risk-limited scheduling:

- Specify risk tolerance
 (e.g., 1%)
- Count on 70k EVs

Lower risk implies

less support from EVs

considered

Steps for deducing chance constraints

1. Model system frequency via single-machine swing equation:

$$\frac{2H}{f_0}\frac{d\Delta f}{dt} = R^{EV}(t) + R^{ND}(t) + R^{G}(t) - PL_{max}$$

2. Solve swing equation to obtain RoCoF and nadir constraints:

$$\mathbb{P}\left[\left(\frac{\boldsymbol{H}}{f_0} - \frac{(\boldsymbol{R^{ND}} + \boldsymbol{R^{EV}}) \cdot T_1}{4\Delta f_{max}}\right) \frac{\boldsymbol{R^G}}{T_2} \quad \geq \left(\frac{\boldsymbol{PL_{max}} - (\boldsymbol{R^{ND}} + \boldsymbol{R^{EV}})}{2\sqrt{\Delta f_{max}}}\right)^2\right] \geq 1 - \epsilon$$

3. Use a convex reformulation for the non-convex chance constraints

Convexification of chance constraint

Several options for the convex reformulation:

The more information available in the forecast, the less conservative the reformulation:

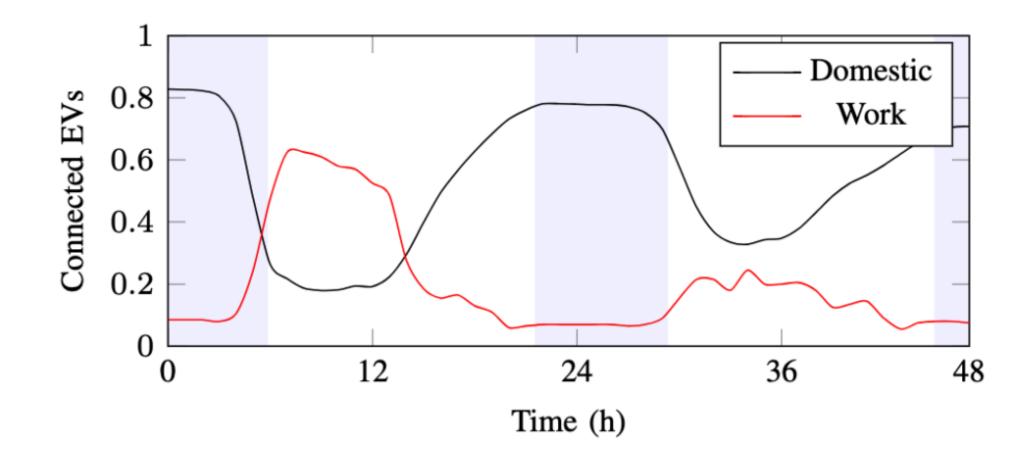
- Gaussian uncertainty?
- Unimodal distribution? (single peak)
- Only mean and variance known? **Distributionally-robust** formulation (most conservative)

Results for Great Britain

- Frequency-secured UC run for a full year in 2030
- Two EV fleets considered:
 - > 'Domestic V2G': 85,000 units, 10 kW chargers
 - > 'Work V2G': 15,000 units, 20 kW chargers
- Risk of under-delivery set at 1%
 - ➤ Does **not mean** 1% risk of **violating security**: that risk is extremely small (largest *N*-1 contingency needs to happen too)

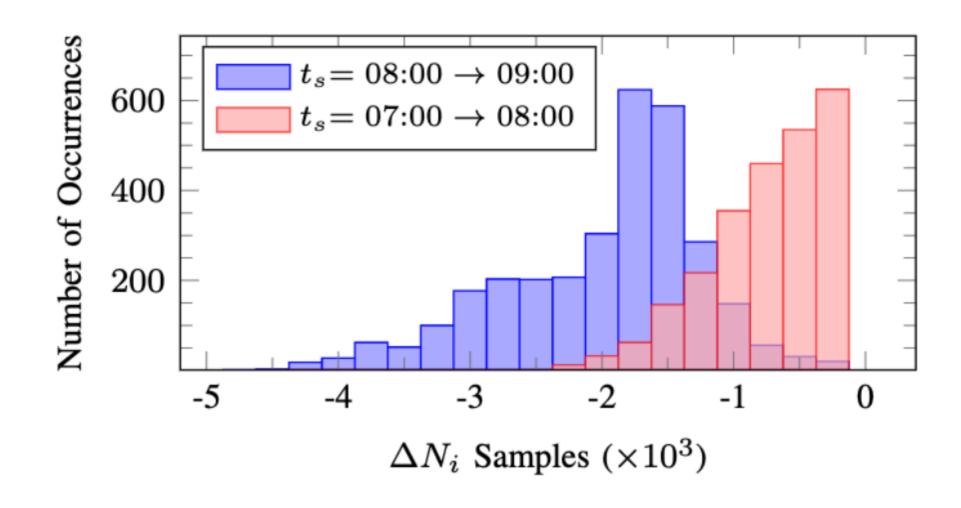
EV connectivity forecasting and data analysis

Data from UK Department of Transport, 2017



Test for ambiguity set

Domestic fleet disconnections on weekday

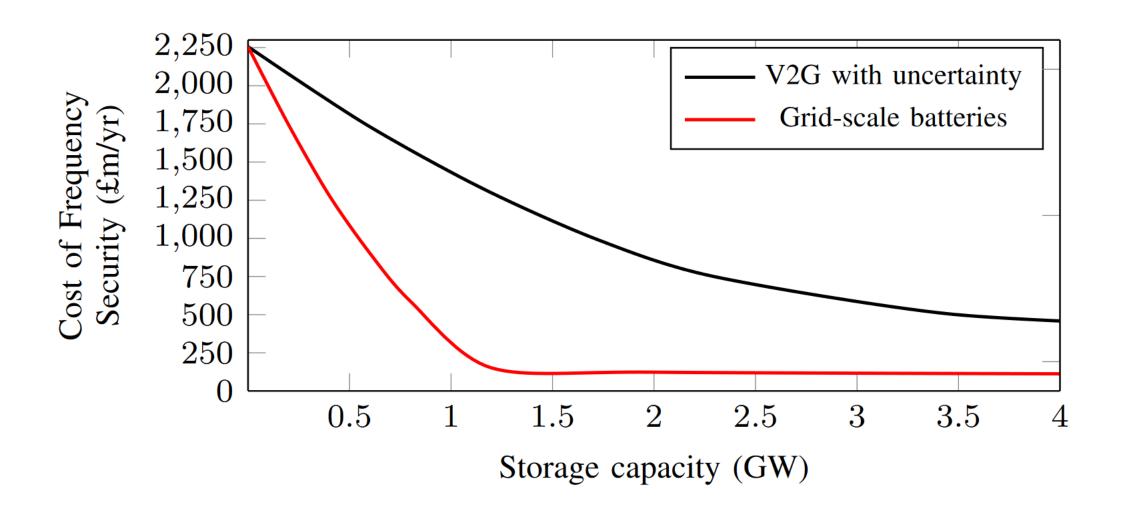


- Not Gaussian
- Unimodal with high confidence (from Shapiro-Wilk test)

Results: comparison of V2G to BESS

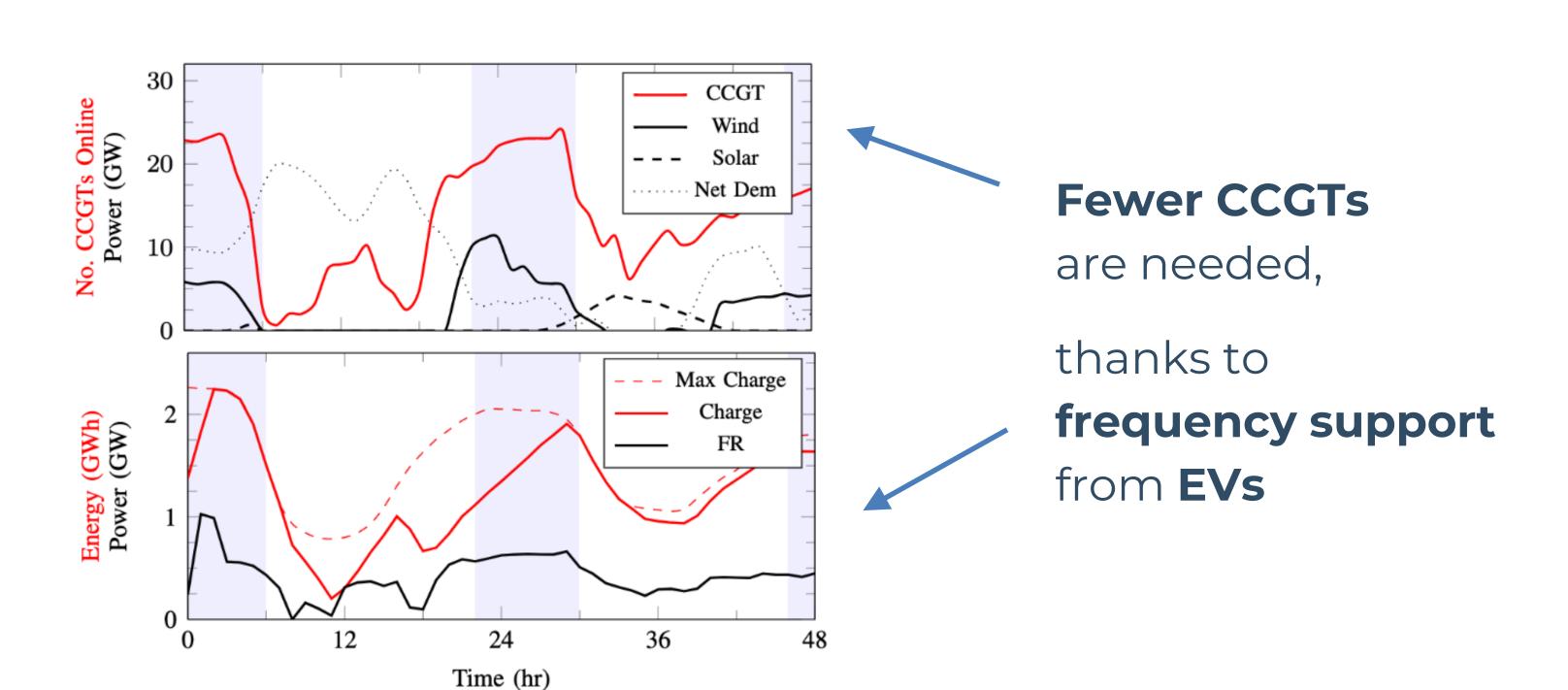
V2G capacity shown to be one third as valuable as stationary BESS

- > EV chargers only have an EV connected ~40% of the time
- > EV chargers are subject to uncertainty



But EVs have no additional investment cost!

Where does this value come from?



Thank you for your attention!