Concepts and Models of Knowledge Engineering

REPORT

Domain: Smart City

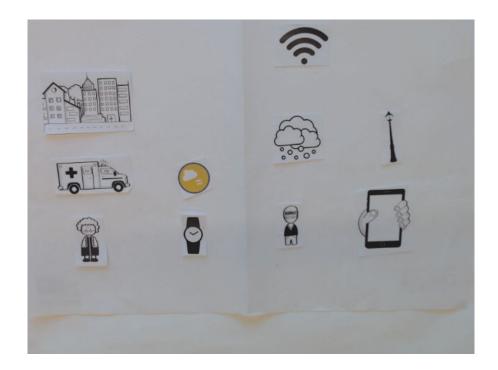
Group number:	04
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Introduction

For this project we used Smarty City Domain to train the network and recognize the objects. There are 6 photos according to the Smart City domain and extra 4 photos for testing the training process. Car (from hospital domain), Watch (from production domain), Cloud (from ski tourism domain) and Woman (from university domain) are extra objects.



10 classes were used: boy, woman, watch, scaner, phone, lamp, internet, car, cloud, street.

Because of the lack of resources at home, we used OMiLab resources like Camera, Computer, GPU and softwares we needed.

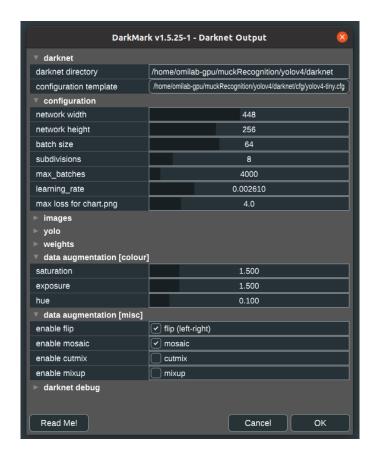
Net 1

Configuration for Net 1:

Batch size: 64 Subdivisions: 8 Max bathes: 4000

Other configurations are shown in the figure below, according to software DarkMark that was

used:

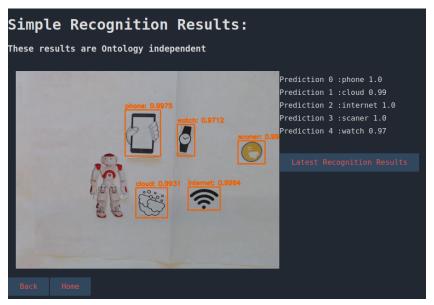


We also used augmented figures produced by DarkMark with different techniques like flipped, noise and blur, perspective, affine.

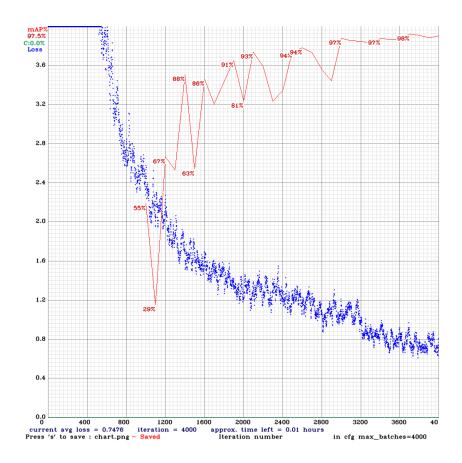
The training took around 14 minutes as we see in the figure below:

```
omilab-gpu@omilabgpu: ~/Desktop/CMKE/WS22/G4/N1
data /home/omilab-gpu/Desktop/CMKE/WS22/G4/N1/N1.cfg"
         User time (seconds): 4013.77
         System time (seconds): 1048.07
         Percent of CPU this job got: 602%
Elapsed (wall clock) time (h:mm:ss or m:ss): 13:59.88
         Average shared text size (kbytes): 0
         Average unshared data size (kbytes): 0
         Average stack size (kbytes): 0
Average total size (kbytes): 0
         Maximum resident set size (kbytes): 1559688
Average resident set size (kbytes): 0
         Major (requiring I/O) page faults: 0
Minor (reclaiming a frame) page faults: 1451051
Voluntary context switches: 23832364
         Involuntary context switches: 110438270
         Swaps: 0
         File system inputs: 0
         File system outputs: 2504472
         Socket messages sent: 0
         Socket messages received: 0
Signals delivered: 0
         Page size (bytes): 4096
Exit status: 0
(base) omilab-gpu@omilabgpu:~/Desktop/CMKE/WS22/G4/N1$
```

After training we used OMiLab camera and ran the server on Computer of Lab to test the network.



We also decided to use a robot figure that was in the Lab to test the network with an unusual shape and complex object. For recognized objects we got acceptable results with this configuration and time, although sum objects were flipped but prediction rates were high.



As it has been shown in the chart, Mean average of precision equals 97.5% after 4000 iterations but the average loss is 0.

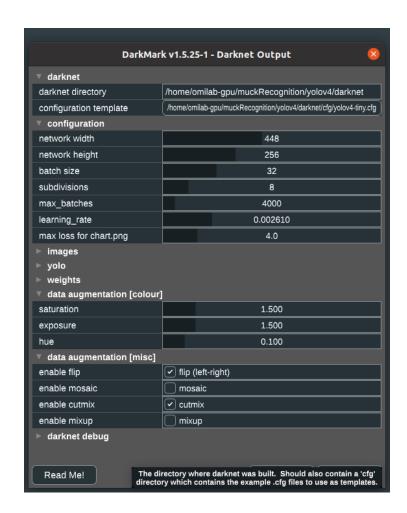
Net 2

Configuration for Net 2:

Batch size: 32 Subdivisions: 8 Max bathes: 4000

Other configurations are shown in the figure below, according to software DarkMark that was

used:

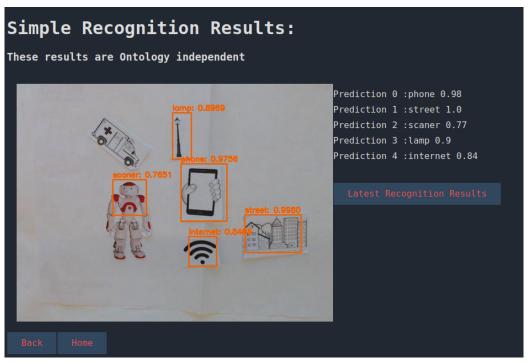


We also used augmented figures produced by DarkMark with different techniques like cutout, flipped, noise and blur, perspective.

As we expected, because of less batch size in compare with Net 1, training lasted faster and took about 7.28 mins as we see in the figure below:

```
omilab-gpu@omilabgpu: ~/Desktop/CMKE/WS22/G4/N2
data /home/omilab-gpu/Desktop/CMKE/WS22/G4/N2/N2.cfg"
        User time (seconds): 986.58
        System time (seconds): 223.72
        Percent of CPU this job got: 269%
        Elapsed (wall clock) time (h:mm:ss or m:ss): 7:28.49
Average shared text size (kbytes): 0
        Average unshared data size (kbytes): 0
        Average stack size (kbytes): 0
        Average total size (kbytes): 0
Maximum resident set size (kbytes): 1422216
Average resident set size (kbytes): 0
        Major (requiring I/O) page faults: 0
         Minor (reclaiming a frame) page faults: 351415
         Voluntary context switches: 4533806
         Involuntary context switches: 24603742
        Swaps: 0
         File system inputs: 0
        File system outputs: 2364664
         Socket messages sent: 0
         Socket messages received: 0
        Signals delivered: 0
         Page size (bytes): 4096
        Exit status: 0
(base) omilab-gpu@omilabgpu:~/Desktop/CMKE/WS22/G4/N2$
```

After training we used OMiLab camera and ran the server on Computer of Lab to test the network.

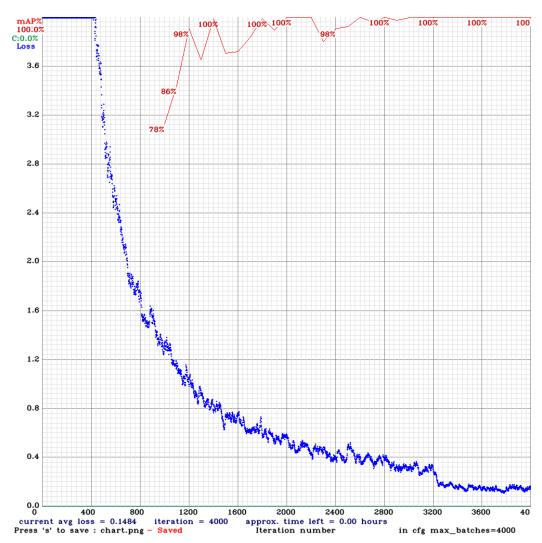


Similar like in Net 1, we used a robot schema that was in the Lab to test the network with an unusual shape and complex object. For recognized objects we got less accuracy in comparison

with Net 1, as we see in prediction rates. Interesting that it recognized the robot as a scanner that we used for sensor medium:



It seems this result is because of the different color and also the circle shape of the head of the robot and its curly form.



As it has been shown in the chart, Mean average of precision is 100% after 4000 iterations but the average loss is 0.

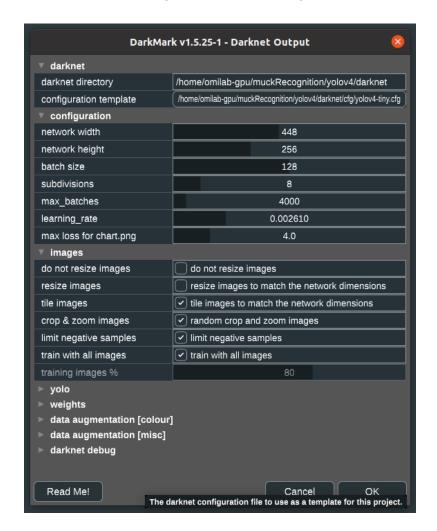
Net 3

Configuration for Net 3:

Batch size: 128 Subdivisions: 8 Max bathes: 4000

Other configurations are shown in the figure below, according to software DarkMark that was

used:

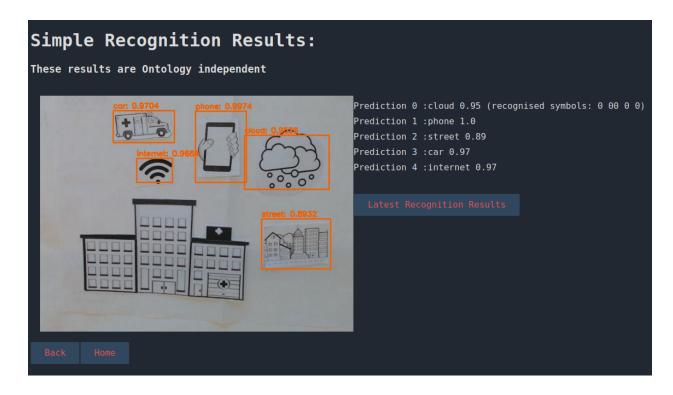


We decided to make more changes in Net 3 in comparison with Net 2 and Net 1. Different augmented techniques were used, such as random crop and zoom images. For more accuracy we chose 128 for batch size and expected more time for training.

Training took about 26 mins as we see in the figure below:

```
omilab-gpu@omilabgpu: ~/Desktop/CMKE/WS22/G4/N3
                                                                Q |
data /home/omilab-gpu/Desktop/CMKE/WS22/G4/N3/N3.cfg"
        User time (seconds): 4793.76
        System time (seconds): 1188.33
        Percent of CPU this job got: 381%
Elapsed (wall clock) time (h:mm:ss or m:ss): 26:09.95
        Average shared text size (kbytes): 0
        Average unshared data size (kbytes): 0
        Average stack size (kbytes): 0
        Average total size (kbytes): 0
        Maximum resident set size (kbytes): 1719064
Average resident set size (kbytes): 0
        Major (requiring I/O) page faults: 0
        Minor (reclaiming a frame) page faults: 3628780
        Voluntary context switches: 24093979
        Involuntary context switches: 117290813
        Swaps: 0
        File system inputs: 0
        File system outputs: 2318864
        Socket messages sent: 0
        Socket messages received: 0
        Signals delivered: 0
        Page size (bytes): 4096
        Exit status: 0
(base) omilab-gpu@omilabgpu:~/Desktop/CMKE/WS22/G4/N3$
```

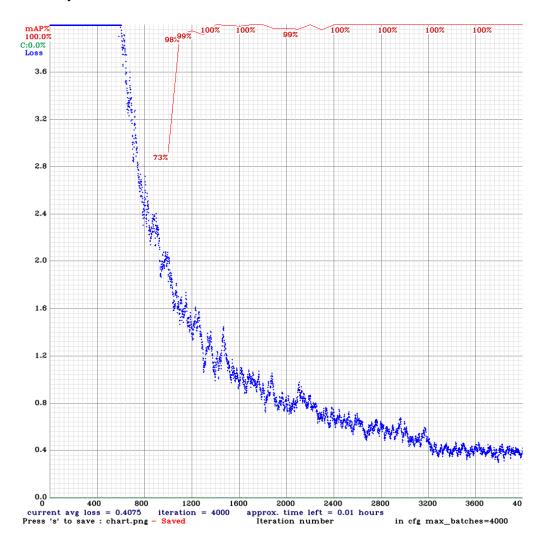
After training we used OMiLab camera and ran the server on Computer of Lab to test the network.



As it is seen in the result, in Net3, the car object could be recognized, but other objects have less prediction rates in comparison to Net 1, as results depend on different parameters. We used different augmented techniques in Net 1, Net 2 and Net 3.

On the other side, as it is shown in the chart below, in Net 3, we reached 100% mAP after 1200 iterations, but in Net 1, we had less stability to reach final mAP and it was a complicated path to reach 97.5%.

As we see, these 3 scenarios that have different parameters, give us different result with different accuracy.



As it has been shown on the chart, Mean average of precision is 100% after 4000 iterations but the average loss is 0.