

Task-1a

I take a list adj-mat. In this list we have no. ^{vertex} ~~edges~~ + 1 indexes and in each index I created a list which ~~will~~ have no. ^{vertex} ~~edges~~ + 1 indexes and initially values are 0. Then from the inputs, I updated the values which indicate weight.

Task-1b

For making adjacency list, I take a list adj-list. In this list we have ~~nodes~~ no. vertex + 1 index and in each index I created a empty list. So, in the empty list, I stored the connected ~~to~~ nodes and weight in a tuple.

Task-2

Firstly I represented the graph in adjacency matrix. Then took a list which tracked the nodes are visited or not initially values are 0. In BFS() I take a Q list first enqueue the source node and then dequeue it and again enqueue

its neighbour nodes into the Q list until the Q is [] \rightarrow empty. and every time update the value ~~0~~ to 1 in visited list(G1) if the node visited.

Task \rightarrow 3

Here I represented the graph in dictionary. Here also I take a visited list which track the nodes are visited or not, initially value is 0. Here in DFS() if the node not visited I appended the node in output and update in the visited list and ^{for} every neighbour I call the same DFS().

Task \rightarrow 4

In this task, I use topological sort algorithm which is Kahn's algo. Since we know, topological sort only possible in DAG. So after the sort, if the sorted list length = no. vertex then there is no cycle. Otherwise there is a cycle.

I created a distance array, and modified the BFS algorithm.

$d \leftarrow \infty$

Task \rightarrow 5

Here I take a list which counts the distance, initially -1 value and a ancestor list which track the ancestor of every nodes. Then I used BFS algorithm and every time I enqueue the nodes I updated both the distance list (d) and ancestor list.

Task → 6

The code uses a flood-fill algorithm to explore a 2D grid representing a jungle with diamonds ('D') and obstacles ('#'). It finds the max number of diamonds that can be collected by starting from each empty cell ('.') and avoiding obstacles.