

EE 514 Homework 2

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$$1. [x, p] \psi(x) = (xp - px) \psi(x)$$

$$= \left[x \left(-i\hbar \frac{d}{dx} \right) - \left(-i\hbar \frac{d}{dx} \right) x \right] \psi(x)$$

$$= -i\hbar \left(x \frac{d\psi(x)}{dx} - \frac{d}{dx} (x \psi(x)) \right)$$

$$= -i\hbar \left(x \cancel{\frac{d\psi(x)}{dx}} - \psi - x \cancel{\frac{d\psi(x)}{dx}} \right)$$

$$= i\hbar \psi(x)$$

$$\begin{aligned} \Delta x \Delta p &\geq \frac{1}{2} |\langle [x, p] \rangle| \\ &\geq \frac{1}{2} |\langle i\hbar \rangle| \\ &\geq \frac{1}{2} \hbar \end{aligned}$$

The result does not depend on $|\psi\rangle$

$$2. a) \frac{1}{2} |\langle [\sigma_x, \sigma_y] \rangle|$$

$$\sigma_x \sigma_y = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \quad \sigma_y \sigma_x = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix}$$

$$\frac{1}{2} |\langle \sigma_x \sigma_y - \sigma_y \sigma_x \rangle|$$

$$\sigma_x \sigma_y - \sigma_y \sigma_x = \begin{pmatrix} 2i & 0 \\ 0 & -2i \end{pmatrix} = 2i \sigma_z$$

$$\frac{1}{2} |\langle 2i \sigma_z \rangle| \quad |i|=1$$

$$= |\langle \sigma_z \rangle| \begin{cases} \text{if } |\psi\rangle = |\uparrow\rangle, & |\langle \uparrow | \sigma_z | \uparrow \rangle| = |\text{Tr}(\sigma_z |\uparrow\rangle \langle \uparrow|)| \\ \text{if } |\psi\rangle = |\downarrow\rangle, & = |\text{Tr}(\sigma_z \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix})| \end{cases}$$

$$\Delta \sigma_x \Delta \sigma_y \geq 1$$

$$= |\text{Tr} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}| = 1$$

This tells us there will always be some uncertainty in our ability to measure spin in both the x and y directions on the same state.

$$\begin{aligned} |\langle \downarrow | \sigma_z | \downarrow \rangle| &= |\text{Tr}(\sigma_z |\downarrow\rangle \langle \downarrow|)| \\ &= |\text{Tr}(\sigma_z \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix})| \\ &= |\text{Tr} \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix}| = 1 \end{aligned}$$

$$\begin{aligned}
3. \quad \langle \sigma_x \rangle &= \langle \uparrow | \sigma_x | \uparrow \rangle \\
&= \text{Tr}(\sigma_x | \uparrow \rangle \langle \uparrow |) \\
&= \text{Tr}(\sigma_x \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}) \\
&= \text{Tr}(\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}) \\
&= \text{Tr} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0
\end{aligned}$$

$$\begin{aligned}
\Delta \sigma_x &= \sqrt{\langle (\sigma_x - \langle \sigma_x \rangle)^2 \rangle} \\
&= \sqrt{\langle (\sigma_x - 0)^2 \rangle} \\
&= \sqrt{\langle \sigma_x^2 \rangle} \\
&= \sqrt{\langle \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \rangle} \\
&= \sqrt{\langle \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \rangle} \\
&= \sqrt{1} = 1
\end{aligned}$$

4. a) $v_x \sigma_x$

$$\begin{aligned}
\det(\sigma_x - \lambda I) &= 0 \\
\det\left(\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) \\
\det \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix} &= (-\lambda \cdot -\lambda) - (1 \cdot 1) \\
&= \lambda^2 - 1 \\
&= (\lambda - 1)(\lambda + 1) = 0 \\
\lambda &= \pm 1
\end{aligned}$$

$v_z \sigma_z$

$$\begin{aligned}
\det(\sigma_z - \lambda I) &= 0 \\
\det\left(\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) \\
\det \begin{pmatrix} 1-\lambda & 0 \\ 0 & -1-\lambda \end{pmatrix} &= (1-\lambda)(-1-\lambda) = 0 \\
\lambda &= \pm 1
\end{aligned}$$

$$V_y \sigma_y$$

$$\det(\sigma_y - \lambda I) = 0$$

$$\det\left(\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right)$$

$$\det\begin{pmatrix} -\lambda & -i \\ i & -\lambda \end{pmatrix} = (-\lambda \cdot -\lambda) - (-i \cdot i)$$

$$= \lambda^2 - 1$$

$$= (\lambda - 1)(\lambda + 1) = 0$$

$$\lambda = \pm 1$$

$$\vec{V} \cdot \vec{\sigma} = \begin{pmatrix} V_z & V_x - iV_y \\ V_x + iV_y & -V_z \end{pmatrix}$$

$$\det \begin{pmatrix} V_z - \lambda & V_x - iV_y \\ V_x + iV_y & -V_z - \lambda \end{pmatrix}$$

$$(V_z - \lambda)(-V_z - \lambda) - (V_x - iV_y)(V_x + iV_y)$$

$$-V_z^2 + \lambda^2 - V_x^2 - V_y^2 = 0$$

$$\lambda^2 - (V_x^2 + V_y^2 + V_z^2) = 0$$

$$\lambda^2 - 1 = 0 \quad \text{unit vector} = 1$$

$$\lambda = \pm 1$$

$$b) \vec{v} \cdot \vec{\sigma} |\pm v\rangle = (\pm 1) |\pm v\rangle$$

$$|\psi\rangle = \alpha |+v\rangle + \beta |-v\rangle$$

$$P_+ |\psi\rangle = \alpha |+v\rangle$$

$$P_- |\psi\rangle = \beta |-v\rangle$$

$$P_{\pm} |\psi\rangle = \frac{1}{2} (I \pm \vec{v} \cdot \vec{\sigma}) (\alpha |+v\rangle + \beta |-v\rangle)$$

$$= \frac{1}{2} (\alpha |+v\rangle + \beta |-v\rangle \pm \alpha (+1) |+v\rangle \pm \beta (-1) |-v\rangle)$$

$$\text{if } +: \frac{1}{2} (\alpha |+v\rangle + \cancel{\beta |-v\rangle} + \alpha |+v\rangle - \cancel{\beta |-v\rangle})$$

$$= \frac{1}{2} (2\alpha |+v\rangle) = \alpha |+v\rangle$$

$$\text{if } -: \frac{1}{2} (\cancel{\alpha |+v\rangle} + \beta |-v\rangle - \cancel{\alpha |+v\rangle} + \beta |-v\rangle)$$

$$= \frac{1}{2} (2\beta |-v\rangle) = \beta |-v\rangle$$

$$5. a) P_x = \langle \pm 1 | \sigma_x | \pm 1 \rangle$$

$$= \text{Tr}(\sigma_x |\pm 1\rangle \langle \pm 1|)$$

$$= \text{Tr}(\sigma_x \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}) \text{ or } \text{Tr}(\sigma_x \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix})$$

$$= \text{Tr} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0 \text{ or } \text{Tr} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = 0$$

$$P_y = \langle \pm 1 | \sigma_y | \pm 1 \rangle$$

$$= \text{Tr}(\sigma_y |\pm 1\rangle \langle \pm 1|)$$

$$= \text{Tr}(\sigma_y \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}) \text{ or } \text{Tr}(\sigma_y \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix})$$

$$= \text{Tr} \begin{pmatrix} 0 & 0 \\ i & 0 \end{pmatrix} = 0 \text{ or } \text{Tr} \begin{pmatrix} 0 & -i \\ 0 & 0 \end{pmatrix} = 0$$

$$\begin{aligned}
P_z &= \langle \pm 1 | \sigma_z | \pm 1 \rangle \\
&= \text{Tr}(\sigma_z | \pm 1 \rangle \langle \pm 1 |) \\
&= \text{Tr}(\sigma_z \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}) \quad \text{or} \quad \text{Tr}(\sigma_z \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}) \\
&= \text{Tr} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = 1 \quad \text{or} \quad \text{Tr} \begin{pmatrix} 0 & 0 \\ 0 & -1 \end{pmatrix} = -1
\end{aligned}$$

$$P = (0, 0, \pm 1)$$

b)

$$\rho = \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix}$$

$$P_x = \text{Tr}(\rho \sigma_x) = \text{Tr} \left(\begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right) = \text{Tr} \begin{pmatrix} \rho_{12} & \rho_{11} \\ \rho_{22} & \rho_{21} \end{pmatrix}$$

$$= \rho_{12} + \rho_{21}$$

$$P_y = \text{Tr}(\rho \sigma_y) = \text{Tr} \left(\begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \right) = \text{Tr} \begin{pmatrix} i\rho_{12} & -i\rho_{11} \\ i\rho_{22} & -i\rho_{21} \end{pmatrix}$$

$$= i(\rho_{12} - \rho_{21})$$

$$P_z = \rho_{11} - \rho_{22}$$

$$\text{Tr}(\rho) = \rho_{11} + \rho_{22} = 1$$

$$P_z = \rho_{11} - \rho_{22}$$

$$1 + P_z = 2\rho_{11}$$

$$\frac{1 + P_z}{2} = \rho_{11}$$

$$1 - P_z = \cancel{\rho_{11}} + \rho_{22} - (\cancel{\rho_{11}} - \rho_{22}) = 2\rho_{22}$$

$$1 - P_z = 2P_{22}$$

$$1 - P_z = P_{22}$$

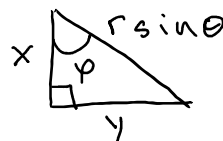
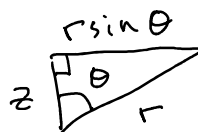
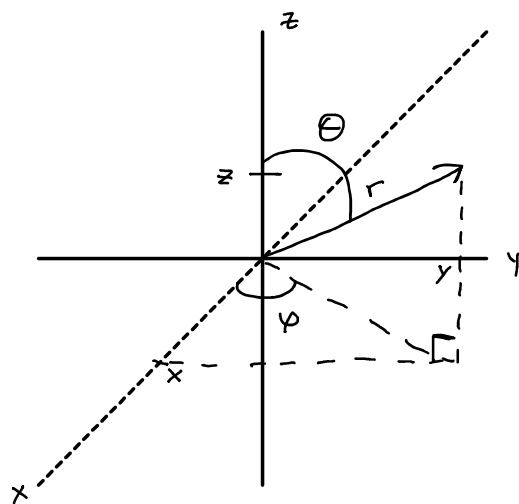
$$\begin{aligned} P_x + iP_y &= P_{12} + P_{21} + i(P_{12} - P_{21}) \\ &= P_{12} + P_{21} + (-1)(P_{12} - P_{21}) \\ &= P_{12} + P_{21} - P_{12} + P_{21} \\ &= 2P_{21} \end{aligned}$$

$$\frac{P_x + iP_y}{2} = P_{21}$$

$$\begin{aligned} P_x - iP_y &= P_{12} + P_{21} - i(P_{12} - P_{21}) \\ &= P_{12} + P_{21} - (-1)(P_{12} - P_{21}) \\ &= P_{12} + P_{21} + P_{12} - P_{21} \end{aligned}$$

$$\begin{aligned} &= 2P_{12} \\ \frac{P_x - iP_y}{2} &= P_{12} \end{aligned}$$

C.



$$P_x = r \sin \theta \cos \varphi$$

$$P_y = r \sin \theta \sin \varphi$$

$$P_z = r \cos \theta$$

$$1 + P_z = 1 + r \cos \theta$$

$$\begin{aligned} P_x - iP_y &= r \sin \theta \cos \varphi - i r \sin \theta \sin \varphi \\ &= r \sin \theta (\cos \varphi - i \sin \varphi) \\ &= r \sin \theta (e^{-i\varphi}) \end{aligned}$$

$$\begin{aligned} P_x + iP_y &= r \sin \theta (\cos \varphi + i \sin \varphi) \\ &= r \sin \theta (e^{i\varphi}) \end{aligned}$$

$$1 - P_z = 1 - r \cos \theta$$

$$\rho = \frac{1}{2} \begin{pmatrix} 1 + r \cos \theta & r \sin \theta e^{-i\varphi} \\ r \sin \theta e^{i\varphi} & 1 - r \cos \theta \end{pmatrix}$$

$$P = (0, 0, 1)$$

$$6. \text{Tr}[(C - \langle C \rangle)^2 \rho] \text{Tr}[\rho (D - \langle D \rangle)^2]$$

$$|\text{Tr}[(C - \langle C \rangle) \rho^{1/2} \rho^{1/2} (D - \langle D \rangle)^2]|^2$$

$$|\text{Tr}[\rho (D - \langle D \rangle)(C - \langle C \rangle)]|^2 = |Z|^2$$

$$[\text{Re}(Z)]^2 + [\text{Im}(Z)]^2 \geq [\text{Im}(Z)]^2$$

$$\left[\frac{1}{2i} (Z - Z^*) \right]^2 = \left[\frac{1}{2i} (\text{Tr}(\rho D C) - \langle D \times C \rangle - (\text{Tr}(\rho C D) - \langle C \times D \rangle)) \right]^2$$

$$\left(\frac{1}{2i} \text{Tr}[\rho (D C - C D)] \right)^2 = \left(\frac{1}{2i} \langle [D, C] \rangle \right)^2 = \frac{1}{2} |\langle [C, D] \rangle|$$

$$7. E_1 = \alpha |1X1\rangle = \alpha \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & \alpha \end{pmatrix}$$

$$E_2 = \alpha |-X-1\rangle$$

$$= \alpha \cdot \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \cdot \frac{1}{\sqrt{2}} (\langle 0| - \langle 1|)$$

$$= \frac{\alpha}{2} (|0\rangle\langle 0| - |0\rangle\langle 1| - |1\rangle\langle 0| + |1\rangle\langle 1|)$$

$$= \frac{\alpha}{2} \left[\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right]$$

$$= \frac{\alpha}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{\alpha}{2} & -\frac{\alpha}{2} \\ -\frac{\alpha}{2} & \frac{\alpha}{2} \end{pmatrix}$$

$$E_3 = I - E_1 - E_2$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \alpha \end{pmatrix} - \begin{pmatrix} \frac{\alpha}{2} & -\frac{\alpha}{2} \\ -\frac{\alpha}{2} & \frac{\alpha}{2} \end{pmatrix}$$

$$= \begin{pmatrix} 1 - \frac{\alpha}{2} & \frac{\alpha}{2} \\ \frac{\alpha}{2} & 1 - \frac{3\alpha}{2} \end{pmatrix}$$

$$P_3 = \langle \psi | E_3 | \psi \rangle$$

$$\det(E_3 - \lambda I) = 0$$

$$\det\left(\begin{pmatrix} 1 - \frac{\alpha}{2} & \frac{\alpha}{2} \\ \frac{\alpha}{2} & 1 - \frac{3\alpha}{2} \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}\right) = 0$$

$$\det\left(\begin{pmatrix} 1 - \frac{\alpha}{2} - \lambda & \frac{\alpha}{2} \\ \frac{\alpha}{2} & 1 - \frac{3\alpha}{2} - \lambda \end{pmatrix}\right) = 0$$

$$(1 - \frac{\alpha}{2} - \lambda)(1 - \frac{3\alpha}{2} - \lambda) - \left(\frac{\alpha}{2}\right)^2 = 0$$

$$1 - \frac{3\alpha}{2} - \lambda - \frac{\alpha}{2} + \frac{3\alpha^2}{4} + \frac{\alpha}{2}\lambda - \lambda + \frac{3\alpha}{2}\lambda + \lambda^2 - \frac{\alpha^2}{4} = 0$$

$$1 - 2\alpha - 2\lambda + \frac{\alpha^2}{2} + 2\alpha\lambda + \lambda^2 = 0$$

$$\lambda^2 + (2\alpha - 2)\lambda + 1 - 2\alpha + \frac{\alpha^2}{2} = 0$$

$$\lambda = \frac{-2(\alpha - 1) \pm \sqrt{4(\alpha - 1)^2 - 4(1 - 2\alpha + \frac{\alpha^2}{2})}}{2}$$

$$\lambda = 1 - \alpha \pm \sqrt{\alpha^2 - 2\alpha + 1 - 1 + 2\alpha - \frac{\alpha^2}{2}}$$

$$\lambda = 1 - \alpha \pm \sqrt{\frac{\alpha^2}{2}}$$

$$\lambda = 1 - \alpha \pm \frac{\alpha}{\sqrt{2}} \geq 0$$

$$1 \geq \alpha \pm \frac{\alpha}{\sqrt{2}}$$

$$1 \geq \alpha \left(1 \pm \frac{1}{\sqrt{2}}\right)$$

$$1 \geq \alpha \left(\frac{\sqrt{2} \pm 1}{\sqrt{2}}\right)$$

$$\frac{\sqrt{2}}{\sqrt{2} \pm 1} \geq \alpha$$

$$\frac{\sqrt{2}}{\sqrt{2} + 1} \geq \alpha$$

$$8. \rho_1 \otimes \rho_2 \otimes \dots \otimes \rho_N$$

$$= \frac{1}{2} (I_1 + \vec{v}_1 \cdot \vec{\sigma}_1) \otimes \dots \otimes \frac{1}{2} (I_N + \vec{v}_N \cdot \vec{\sigma}_N)$$

$$= \left(\frac{1}{2}\right)^N [I_1 \otimes \dots \otimes I_N + \vec{v}_1 \cdot \vec{\sigma}_1 \otimes I_2 \otimes \dots \otimes I_N$$

$$+ I_1 \otimes \vec{v}_2 \cdot \vec{\sigma}_2 \otimes \dots \otimes I_N$$

$$+ \vec{v}_1 \cdot \vec{\sigma}_1 \otimes \vec{v}_2 \cdot \vec{\sigma}_2 \otimes I_3 \otimes \dots \otimes I_N$$

$$+ \vec{v}_1 \cdot \vec{\sigma}_1 \otimes I_2 \otimes \vec{v}_3 \cdot \vec{\sigma}_3 \otimes I_4 \otimes \dots \otimes I_N$$

$$+ \dots$$

$$\left(\frac{1}{2}\right)^N \sum_{i < j} v_i \sigma_i \otimes v_j \sigma_j \otimes I^{\otimes N}$$

$$\begin{aligned}
9. a) \quad \text{Tr}_B \rho_{AB} &= \text{Tr}_B \sum_{ij} \lambda_{ij} |a_i \rangle \langle a_i| \otimes |b_j \rangle \langle b_j| \\
&= \sum_{ij} \lambda_{ij} \underbrace{\text{Tr}_B (|a_i \rangle \langle a_i| \otimes |b_j \rangle \langle b_j|)} \\
&= \sum_{ij} \lambda_{ij} |a_i \rangle \langle a_i| \underbrace{\text{Tr}_B (|b_j \rangle \langle b_j|)} \\
&= \sum_k \langle v_k | b_j \rangle \langle b_j | v_k \rangle \\
&\quad \sum_k \langle v_k | \left(\sum_{ij} \lambda_{ij} |a_i \rangle \langle a_i| \otimes |b_j \rangle \langle b_j| \right) | v_k \rangle \\
&= \sum_k \langle v_k | \rho_{AB} | v_k \rangle
\end{aligned}$$

b) No

$$\begin{aligned}
c) \quad &\sum_{\mu} \sum_{ij\eta\xi} \sum_{k\lambda\alpha\beta} \lambda_{\mu} U_{ij\eta\xi} U_{k\lambda\alpha\beta}^+ \cdot \leftarrow \\
&\cdot \text{Tr}_B [|i \rangle \langle j| \rho_A |k \rangle \langle l| \otimes |\eta \rangle \langle \xi| |\mu \rangle \langle \nu| \alpha \rangle \langle \beta|]
\end{aligned}$$

$$\begin{aligned}
&\sum_{\mu} \sum_{ij\eta\xi} \sum_{k\lambda\alpha\beta} \lambda_{\mu} U_{ij\eta\xi} U_{k\lambda\alpha\beta}^+ \cdot \leftarrow \\
&\cdot |i \rangle \langle j| \rho_A |k \rangle \langle l| \text{Tr}_B [|\eta \rangle \langle \xi| |\mu \rangle \langle \nu| \alpha \rangle \langle \beta|]
\end{aligned}$$

$$\sum_{\mu} \sum_{ij\eta\xi} \sum_{kl\alpha\beta} \lambda_{\mu} U_{ij\eta\xi} U_{kl\alpha\beta}^{\dagger} |iXj\rangle P_A |kXl\rangle \delta_{\eta\beta} \delta_{\xi\mu} \delta_{\mu\alpha}$$

$$\sum_{\mu\eta} \sum_{ij} \sum_{kl} \lambda_{\mu} U_{ij\eta\mu} U_{kl\mu\eta}^{\dagger} |iXj\rangle P_A |kXl\rangle$$

$$\sum_{\mu\eta} \lambda_{\mu} \left[\underbrace{\sum_{ij} U_{ij\eta\mu} |iXj\rangle}_{\sum_{ij} \langle \eta | U_{ij} | \mu \rangle |iXj\rangle = \langle \eta | U | \mu \rangle} \right] P_A \left[\underbrace{\sum_{kl} U_{kl\mu\eta}^{\dagger} |kXl\rangle}_{\sum_{kl} \langle \mu | U_{kl}^{\dagger} | \eta \rangle |kXl\rangle = \langle \mu | U^{\dagger} | \eta \rangle} \right]$$

$$\sum_{\mu\eta} \lambda_{\mu} \langle \eta | U | \mu \rangle P_A \langle \mu | U^{\dagger} | \eta \rangle$$

$$10. \sum_{\alpha} K_{\alpha}^{\dagger} K_{\alpha} = I$$

$$P' = \sum_{\alpha} K_{\alpha} P K_{\alpha}^{\dagger}$$

$$\text{Tr}[P'] = 1 \quad \text{Tr}[P] = 1$$

$$\text{Tr}[\sum_{\alpha} K_{\alpha} P K_{\alpha}^{\dagger}] = 1$$

$$\text{Tr}(P \sum_{\alpha} K_{\alpha}^{\dagger} K_{\alpha}) = 1$$

$$K = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \quad K^{\dagger} = \begin{pmatrix} \alpha^{*} & \gamma^{*} \\ \beta^{*} & \delta^{*} \end{pmatrix}$$

$$K^{\dagger} K = \begin{pmatrix} |\alpha|^2 + |\gamma|^2 & \alpha^{*}\beta + \gamma^{*}\delta \\ \alpha\beta^{*} + \gamma\delta^{*} & |\beta|^2 + |\delta|^2 \end{pmatrix}$$

$$= \begin{pmatrix} A & Z \\ Z^{*} & B \end{pmatrix}$$

$$\rho = \begin{pmatrix} a & b \\ b^* & 1-a \end{pmatrix}$$

$$\rho K^\dagger K = \begin{pmatrix} aA + bZ^* & aZ + bB \\ b^*A + (1-a)Z^* & b^*Z + (1-a)B \end{pmatrix}$$

$$\text{Tr}(\rho K^\dagger K) = aA + bZ^* + b^*Z + (1-a)B$$

$$\text{let } a = \frac{1}{2}, b = 0$$

$$\text{Tr}(\rho) = a + 1-a = \frac{1}{2} + 1 - \frac{1}{2} = 1$$

$$\begin{aligned} \text{Tr}(\rho K^\dagger K) &= \frac{1}{2}A + 0 \cdot Z^* + 0 \cdot Z + (1 - \frac{1}{2})B \\ &= \frac{1}{2}A + \frac{1}{2}B = 1 \end{aligned}$$

$$\text{let } A = 1, B = 1$$

$$\frac{1}{2}(1) + \frac{1}{2}(1) = 1$$

$$K^\dagger K = \begin{pmatrix} 1 & Z \\ Z^* & 1 \end{pmatrix}$$

$$\text{let } \alpha = \frac{1}{\sqrt{2}}, \beta = \frac{1}{\sqrt{2}}, \gamma = \frac{i}{\sqrt{2}}, \delta = \frac{i}{\sqrt{2}}$$

$$K^\dagger K = \begin{pmatrix} |\alpha|^2 + |\gamma|^2 & \alpha^*\beta + \gamma^*\delta \\ \alpha\beta^* + \gamma\delta^* & |\beta|^2 + |\delta|^2 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{2} + \frac{1}{2} & \frac{1}{2} + \frac{1}{2} \\ \frac{1}{2} + \frac{1}{2} & \frac{1}{2} + \frac{1}{2} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \neq I$$