Cat concept Mi = motor i leg zoom in double duty, rotating le prehonously (, Lvsg)

concept moving, but unjowered components Le heard, tail; Constrained -ation | swive | (torsion spring s hard stops Soul creey! front view isometric view hordsty! neck snact

cat head X-section mile body wel stops bashing forsion spring? bottom vier fossion stans a neck forsion 264 Fred wat work She

at top view tail Cat concept hard shi Sushing tail spring same as head torsion hard stops shaft fixed points

Out Concept 3 Grinsp. N. Ž Compo went Button grimsn9

Actual size: emulate a small kitten 6 4-5 lbs ~ 2 kg each leg is ~7" li=3" terral to body with a small-kithen-scale, robot should be able to balance on 2 pows at a time