## **Autonomous Robot Tour Guide**

Commercial mobile robots are fast becoming a reality. Robots such as Pepper [1], Sanbot [2], Asimo [3], and others [4] [5] [6] represent the potential future for commercial robotics. These autonomous robots are capable of operating in uncontrolled environments (supermarkets, hotels, conventions) and interacting with customers. However, there is currently a gap in this market for a mobile commercial robot that can operate outdoors and interact with customers.

## Outline of Project Outcome

We intend to develop a robot that can autonomously navigate an uncontrolled outdoor environment. Such difficult conditions (variable lighting, challenging terrain, and dynamic obstacles) will require an advanced and well-executed navigation system combined with dependable mobile robot platform, in order to achieve robust autonomous navigation.

## Outline Applications for the Robot

With that said, the potential commercial applications of a fully realized consumer version are vast.

- \* Public and private events: Such as conventions, forums and exhibits. Serving as a guide, hospitality aid, or entertainer.
- \* Museums, theme parks, gardens: As a tour guide, and information point.
- \* Company headquarters: To provide tours of offices and facilities to clients and guests, providing information about the company and its products & services.
- \* Shopping malls & supermarkets: As an in-store greeter, information point, capable of leading the customer to where they need to go.
- \* Restaurants and parties: As a drinks & canapé waiter. The robot would need to be fitted with a tray and be capable of keeping it stable.

To that end, we will be targeting an example commercial application as one of the main objectives of our project; a robot capable of serving as a tour guide for the University of Plymouth campus, by leading a group of prospective students and parents around the campus, and to provide information about the buildings.

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