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% Laborversuch Mechatronik
% Motor Ausmessen
```

```
v2hz = @(v) v/14.3*1000/60;
rpm2v = @(rpm) rpm/1000*14.3;
```

```
%% Aufgabe 1
% Widerstand variiert je nach Rotorstellung:
```

```
r1 = mean([3.3 2.7 3.0 3.6])
r2 = mean([2.4 2.7 2.9 3.2])
```

```
%% Aufgabe 4
%  $U_q = c \cdot \phi \cdot n \rightarrow c \cdot \phi = U_q / n$ 
```

```
% Gegeben:
Uq1 = 8.61;
Uq2 = 8.63;
```

```
% Gemessen:
n1 = v2hz(13.13);
n2 = v2hz(13.15);
```

```
% Resultat:
c_phi1 = Uq2/n2
c_phi2 = Uq2/n2
```

```
%% Aufgabe 5
% Soll Umdrehungen: 1800rpm und 900rpm
Un_soll_900 = rpm2v(900);
Un_soll_1800 = rpm2v(1800);
```

```
Motor2_1800rpm = xlsread('Messresultate.xlsx', 'Tabelle1', 'B3:F11');
P_Motor2_1800rpm = polyfit(Motor2_1800rpm(3:end,4), Motor2_1800rpm(3:end,5), 1);
r2_1800rpm = -P_Motor2_1800rpm(1)
ub_r2_1800rpm = (Motor2_1800rpm(1,3) - P_Motor2_1800rpm(2))/2
```

```
Motor2_900rpm = xlsread('Messresultate.xlsx', 'Tabelle1', 'B13:F18');
P_Motor2_900rpm = polyfit(Motor2_900rpm(3:end,4), Motor2_900rpm(3:end,5), 1);
r2_900rpm = -P_Motor2_900rpm(1)
ub_r2_900rpm = (Motor2_900rpm(1,3) - P_Motor2_900rpm(2))/2
```

```
Motor1_1800rpm = xlsread('Messresultate.xlsx', 'Tabelle1', 'B25:F31');
P_Motor1_1800rpm = polyfit(Motor1_1800rpm(3:end,2), Motor1_1800rpm(3:end,3), 1);
r1_1800rpm = -P_Motor1_1800rpm(1)
ub_r1_1800rpm = (Motor1_1800rpm(1,3) - P_Motor1_1800rpm(2))/2
```

```
Motor1_900rpm = xlsread('Messresultate.xlsx', 'Tabelle1', 'B34:F38');
P_Motor1_900rpm = polyfit(Motor1_900rpm(3:end,2), Motor1_900rpm(3:end,3), 1);
r1_900rpm = -P_Motor1_900rpm(1)
ub_r1_900rpm = (Motor1_900rpm(1,3) - P_Motor1_900rpm(2))/2
```

```
%% Aufgabe 7
% Soll Speisespannungen: 20V und 40V
Motor1_20V = xlsread('Messresultate.xlsx', 'Tabelle2', 'B3:F9');
Motor1_40V = xlsread('Messresultate.xlsx', 'Tabelle2', 'B12:F16');
Motor2_20V = xlsread('Messresultate.xlsx', 'Tabelle2', 'B23:F27');
Motor2_40V = xlsread('Messresultate.xlsx', 'Tabelle2', 'B30:F34');
```

```
%% Aufgabe 8
% Soll Speisespannung: 40V (mit Vorwiderstand)
Motor1_40V_100hm = xlsread('Messresultate.xlsx', 'Tabelle3', 'B3:F8');
```

```
Motor2_40V_100hm = xlsread('Messresultate.xlsx', 'Tabelle3', 'B16:F20');
```

```
%% Aufgabe 9
```

```
r1_warm = mean([2.6 2.4 2.4 2.5])
```

```
r2_warm = mean([2.3 2.2 2.5])
```