

# Resolution of singularities via combinatorics of the Newton polygon

An introduction to toric varieties and the monodromy conjecture.

Oriol Baeza Guasch

- 1 Introduction
- 2 Resolution of singularities
- 3 Newton non-degenerate
- 4 Monodromy conjecture

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# Introduction

The monodromy conjecture is an open problem in the theory of singularities, formulated by Igusa in the 70s.

## Monodromy conjecture, topological version

Let  $f \in \mathbb{C}[x_1, \dots, x_n]$  be non-constant. If  $s_0$  is a pole of  $Z_{\text{top}}(f, \varphi; s)$ , then

- (*standard*)  $e^{2\pi i \Re(s_0)}$  is a monodromy eigenvalue of  $f: \mathbb{C}^n \rightarrow \mathbb{C}$  at some point of  $\{f = 0\}$ .
- (*strong*)  $s_0$  is a root of the Bernstein-Sato polynomial  $b_f$ .

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Known cases:

- Plane curves (Loeser '88)
- Newton non-degenerate polynomials\* (Loeser '90)
- Some types of hyperplanes arrangements (Budur-Saito-Yuzvinsky '10, Walther '17, Bapat-Walters '15)
- Semi-quasihomogeneous singularities (Budur-Blanco-van der Veer '21)

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# Singularities

- $f: U \rightarrow \mathbb{C}$  a holomorphic function defined on an open set  $U \subset \mathbb{C}^n$
- Hypersurface  $X = f^{-1}(0)$

## Definition (Singularity)

We define the set of singular points of  $X$  by the set

$$\text{Sing}(X) := \left\{ x \in U \mid f(x) = \frac{\partial f}{\partial x_1} = \cdots = \frac{\partial f}{\partial x_n} = 0 \right\}$$

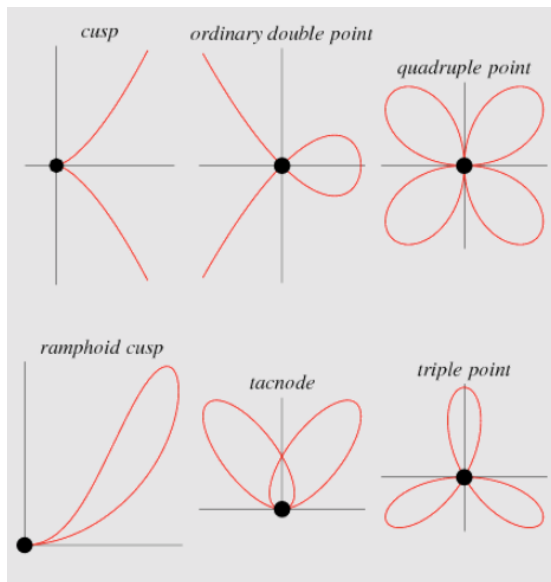
Additionally, if  $x \in \text{Sing}(X)$  is the only singularity in a small enough neighborhood  $V \ni x$  we will say it is *isolated*.

# Examples of singularities I

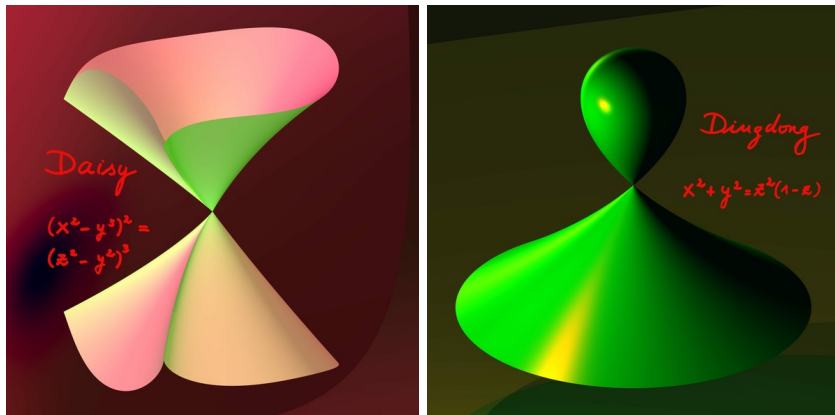




# Examples of singularities I



# Examples of singularities II



**Figure:** Herwig Hauser's algebraic surfaces. IMAGINARY exhibition (CC BY-NC-SA-3.0)

See more: <https://www.imaginary.org/gallery/herwig-hauser-classic>

# Examples of singularities II

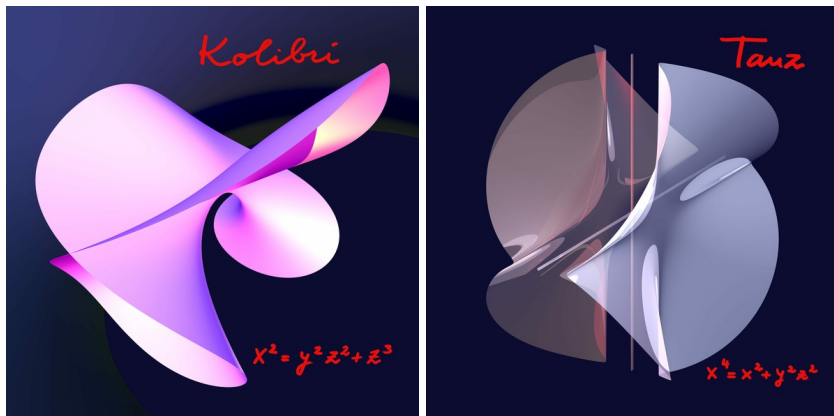


Figure: Herwig Hauser's algebraic surfaces. IMAGINARY exhibition (CC BY-NC-SA-3.0)

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# Resolution of singularities

## Definition (Resolution)

A *resolution* of  $X$  is a proper morphism  $\pi: Y \rightarrow X$  where

- 1  $Y$  is a smooth variety.
- 2 The restriction outside the singular locus  
 $\pi|_{Y \setminus \pi^{-1}(\text{Sing}(X))}: Y \setminus \pi^{-1}(\text{Sing}(X)) \rightarrow X \setminus \text{Sing}(X)$  is an isomorphism.

Additionally, we will say that the resolution is *good* if also

- 3 For every singular point  $p \in \pi^{-1}(\text{Sing}(X))$ , there exists an open neighborhood  $U_p \subset Y$ , and open  $V \subset \mathbb{K}^n$  with a chart

$$\begin{aligned} y: U_p &\xrightarrow{\cong} V \\ p &\mapsto 0 \end{aligned}$$

such that  $U \cap \pi^{-1}(\text{Sing}(X)) = \{y_{i_1} = \cdots = y_{i_r} = 0\}$  for certain indices  $0 < i_1 < \cdots < i_r \leq n$ .

# Resolution of singularities

## Definition (Embedded resolution)

Let  $X$  be a smooth algebraic variety,  $f: X \rightarrow \mathbb{K}$  a polynomial and abbreviate  $S = \text{Sing}(f^{-1}(0))$  be the set of singular points on the zero set of  $f$ . An *embedded resolution* of  $f$  is a proper morphism  $\pi: Y \rightarrow X$  where

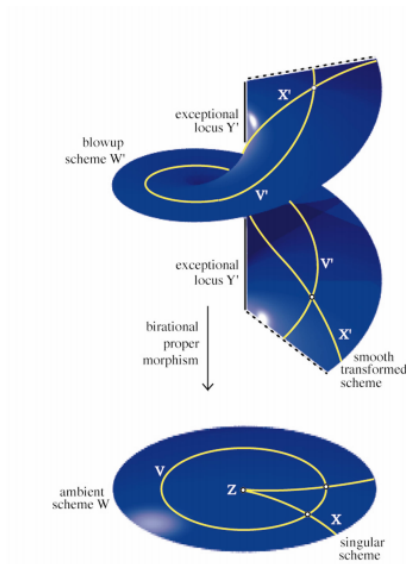
- 1  $Y$  is a smooth variety.
- 2 The restriction outside the singular locus  $\pi|_{Y \setminus \pi^{-1}(S)}: Y \setminus \pi^{-1}(S) \rightarrow X \setminus S$  is an isomorphism.
- 3 For every singular point  $p \in \pi^{-1}(S)$ , there exists an open neighborhood  $U_p \subset Y$ , and an open  $V \subset \mathbb{K}^n$  with a chart

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over which  $\pi^*f = u(y) y_{i_1}^{N_1} \cdots y_{i_r}^{N_r}$ , with  $u(0) \neq 0$  a unit, and  $N_i \geq 0$  integers.

Guaranteed in characteristic zero, thanks to a result by Hironaka [Hir64].

# Picture of a resolution



# Geometric description

Let  $f \in \mathbb{C}[x_1, \dots, x_n]$  be non-constant,  $\pi: X \rightarrow \mathbb{C}$  an embedded resolution of  $f$ . Let  $(E_i)_{i \in J}$  the irreducible components of  $\pi^{-1}(f^{-1}(0))$ . Locally  $E_i: \{x_i = 0\}$ .

## Geometric setup

In the resolved space, the intersection of exceptional divisors is, at worst, like intersection of coordinate hyperplanes.

- Normal crossings: divisors are smooth and intersect transversely.
- Simple normal crossings: additionally, no three intersect at the same point.

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## Numerical data

Denote the order of vanishing of  $\pi^*f$  and  $\pi^*(dx)$  on a generic point of  $E_j$  by  $N_j$ ,  $k_j - 1$ , respectively. We can write globally the divisors

$$\operatorname{div}(\pi^*f) = \sum_{j \in J} N_j E_j$$

$$\operatorname{div}(\pi^*(dx_1 \wedge \dots \wedge dx_n)) = \sum_{j \in J} (k_j - 1) E_j$$



# Plane curves

Given a curve  $C$  in a smooth algebraic surface  $S$ , singular at a point  $P$ .  
Construct surface  $T$  and map  $\pi: T \rightarrow S$  such that  $\pi$  restricts to an isomorphism between  $T \setminus E \rightarrow S \setminus \{P\}$ , where  $E = \pi^{-1}(P)$  is basically a projective line.

- Only need a finite number of blowups to obtain smooth strict transform.
- Can be extended so that  $\pi^{-1}(C)$  has simple normal crossings.

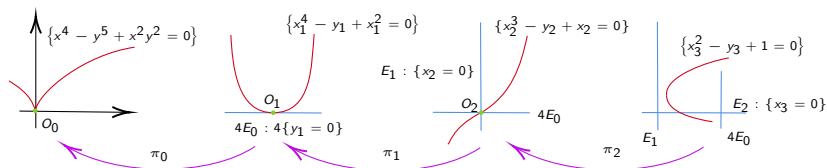
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For example, a resolution of one branch of the curve  $f = x^4 - y^5 + x^2y^2$  is given by

$$\begin{aligned} (x, y) &\mapsto (x_1y_1, y_1), & (x_1, y_1) &\mapsto (x_2, x_2y_2), & (x_2, y_2) &\mapsto (x_3, x_3y_3) \\ \implies \pi^*f &= x_3^{10}y_3^4(x_3^2 - y_3 + 1) \end{aligned}$$



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# Newton polyhedron

We consider a polynomial  $f(x_1, \dots, x_n) = \sum_{p \in \mathbb{N}^n} a_p x_1^p \dots x_n^p$  such that  $f(0) = 0$ , and define the support  $\text{supp}(f) = \{p \in \mathbb{N}^n \mid a_p \neq 0\}$ .

## Definition (Newton polyhedron)

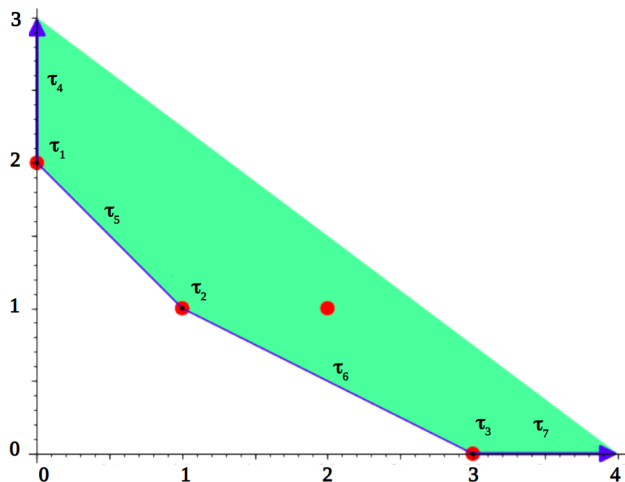
Let  $f = \sum_{p \in \mathbb{N}^n} a_p x^p \in \mathbb{C}[x]$  with  $f(0) = 0$ . We define the *global Newton polyhedron*  $\Gamma_{gl}(f)$  of  $f$  as the convex hull of  $\text{supp}(f)$ . Also, we define the *local Newton polyhedron*  $\Gamma(f)$  as the convex hull of the set

$$\bigcup_{p \in \text{supp}(f)} p + (\mathbb{R}_{\geq 0})^n$$

In particular, it is immediate that  $\Gamma(f) = \Gamma_{gl}(f) + (\mathbb{R}_{\geq 0})^n$ .

# Example

Consider the polynomial  $f = x^3 - y^2 + 4xy + 3x^2y$ .



# Example

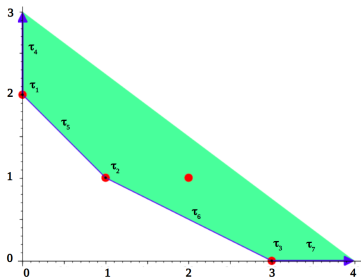
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- Faces of dimension  $\dim \tau = 0$ :

$$\tau_1 = \{(0, 2)\} \quad f^{\tau_1} = -y^2$$

$$\tau_2 = \{(1, 1)\} \quad f^{\tau_2} = 4xy$$

$$\tau_3 = \{(3, 0)\} \quad f^{\tau_3} = x^3$$



- Faces of dimension  $\dim \tau = 1$ :

$$\tau_4 = \{(0, 2) + \mathbb{R}_{>0}(0, 1)\}$$

$$f^{\tau_4} = -y^2$$

$$\tau_5 = \{(1 - \lambda)(0, 2) + \lambda(1, 1) \mid 0 < \lambda < 1\}$$

$$f^{\tau_5} = -y^2 + 4xy$$

$$\tau_6 = \{(1 - \lambda)(1, 1) + \lambda(3, 0) \mid 0 < \lambda < 1\}$$

$$f^{\tau_6} = x^3 + 4xy$$

$$\tau_7 = \{(3, 0) + \mathbb{R}_{>0}(1, 0)\}$$

$$f^{\tau_7} = x^3$$

# Non-degeneracy

## Definition (Newton non-degenerate)

We say that  $f$  is Newton non-degenerate at 0 if for any face  $\tau \subset \Gamma(f)$ , the hypersurface  $f^\tau = 0$  satisfies the condition

$$x_1 \frac{\partial f^\tau}{\partial x_1} = \cdots = x_n \frac{\partial f^\tau}{\partial x_n} = 0 \quad \implies \quad x_1 \cdots x_n = 0$$

that is, the polynomials  $x_i \frac{\partial f^\tau}{\partial x_i}$  do not vanish at the same time in  $(\mathbb{C} \setminus 0)^n$ .

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For example,  $f = y^4 - 2y^2x^3 - 4yx^5 + x^6 - x^7 = (y^2 - x^3)^2 - 4yx^5 - x^7$  is degenerate: the truncation on the face (edge)  $\tau$  with endpoints  $(0, 4)$  and  $(6, 0)$  is

$$f^\tau = (y^2 - x^3)^2 \quad \implies \quad \begin{cases} x \cdot 2(y^2 - x^3) \cdot 3x^2 = 0 \\ y \cdot 2(y^2 - x^3) \cdot 2y = 0 \end{cases}$$

and the system considered has solutions outside  $(\mathbb{C} \setminus 0)^2$ .



## Definition (N,k)

Let  $\Gamma(f)$  be the Newton diagram of  $f$  as defined. For  $a \in (\mathbb{R}^+)^n$ , we define

$$N(a) := \inf_{x \in \Gamma(f)} \{\langle a, x \rangle\} = \min_{\substack{x \text{ vertex} \\ \text{of } \Gamma(f)}} \{\langle a, x \rangle\}$$

We may recover the face by considering  $F(a) := \{x \in \Gamma(f) \mid \langle a, x \rangle = N(a)\}$  the first meet locus. Lastly, denote  $k(a) := \sum_{i=1}^n a_i$ .

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## Definition (Dual cone)

For  $\tau$  a face of  $\Gamma(f)$ , we define the *cone associated* to  $\tau$  as

$$\Delta_\tau := \{a \in (\mathbb{R}_{>0})^n \mid F(a) = \tau\} / \sim$$

where the equivalence relation is given by  $a \sim a' \iff F(a) = F(a')$ .

Additionally, we will refer to the collection of these cones for all faces of the Newton polytope as the *dual fan*.

# Computing the dual fan

Notice that for every proper face  $\tau$  we have

$$\tau = \bigcap_{\substack{\tau \subset \gamma \\ \dim \gamma = n-1}} \gamma$$

Moreover, for every face of  $\Gamma(f)$  of codimension 1, there exists a unique integral primitive vector (meaning that all of its coordinates are relatively coprime) perpendicular to the face.

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## Lemma

Let  $\tau$  be a proper face of  $\Gamma(f)$  and  $\gamma_1, \dots, \gamma_r$  the faces of  $\Gamma(f)$  of dimension  $n - 1$  that contain it. Let  $a_1, \dots, a_r$  be the unique primitive normal vectors to  $\gamma_1, \dots, \gamma_r$ , respectively. Then,

$$\Delta_\tau = \{ \lambda_1 a_1 + \dots + \lambda_r a_r \mid \lambda_i \in \mathbb{R}_{>0} \}$$

with  $\dim \Delta_\tau = n - \dim \tau$ .

# Example

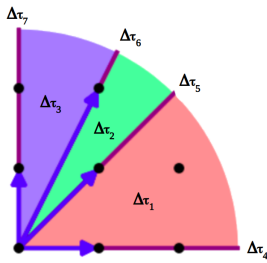
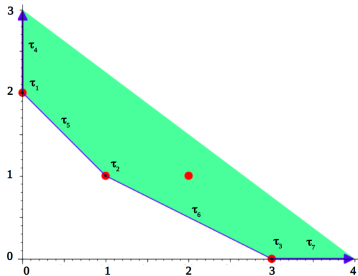
Consider again  $f = x^3 - y^2 + 4xy + 3x^2y$ .

- $\tau_4 = \{(0, 2) + \mathbb{R}_{>0}(0, 1)\} \implies a_4 = (1, 0)$
- $\tau_5 = \{(1 - \lambda)(0, 2) + \lambda(1, 1) \mid 0 < \lambda < 1\} \implies a_5 = (1, 1)$
- $\tau_6 = \{(1 - \lambda)(1, 1) + \lambda(3, 0) \mid 0 < \lambda < 1\} \implies a_6 = (1, 2)$
- $\tau_7 = \{(3, 0) + \mathbb{R}_{>0}(1, 0)\} \implies a_7 = (0, 1)$

Then, the cones associated to each face

$$\Delta_{\tau_1} = \mathbb{R}_{>0}(1, 0) + \mathbb{R}_{>0}(1, 1), \quad \Delta_{\tau_4} = \mathbb{R}_{>0}(1, 0), \quad \dots$$

Altogether, the associated dual fan is (right)



# Cones and subdivisions

## Definition (Cone)

A *convex polyhedral cone* is a set

$$C = \{\lambda_1 v_1 + \cdots + \lambda_r v_r \in V \mid \lambda_i \geq 0\} = \mathbb{R}_{\geq 0} v_1 + \cdots + \mathbb{R}_{\geq 0} v_r$$

where  $V$  is an  $n$ -dimensional vector space over  $\mathbb{R}$ , and the vectors  $\{v_i\}$  are called the *generators* of the cone.

We will say that a cone is...

- *simplicial* if its generating vectors  $v_1, \dots, v_r$  are linearly independent over  $\mathbb{R}$ .
- *regular* if  $\{v_1, \dots, v_r\}$  is a subset of a base of the  $\mathbb{Z}$ -module  $\mathbb{Z}^n$ .

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## Theorem

Each cone admits a partition in simplicial subcones. Moreover, they can be made regular cones by introducing suitable new generating rays.

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## Lemma 8.7 [AVG12]

There exists a regular fan subordinate to a Newton polyhedron.



# Toric blowups

## Definition (Toric blowup)

Consider a unimodular integral  $n \times n$  matrix  $\sigma$

$$\sigma = \begin{pmatrix} \sigma_{1,1} & \sigma_{1,2} & \cdots & \sigma_{1,n} \\ \sigma_{2,1} & \sigma_{2,2} & \cdots & \sigma_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{n,1} & \sigma_{n,2} & \cdots & \sigma_{n,n} \end{pmatrix}$$

We define the *toric blowup* associated to  $\sigma$  as the birational morphism

$$\begin{aligned} \pi_\sigma: (\mathbb{C}^*)^n &\rightarrow (\mathbb{C}^*)^n \\ (x_1, \dots, x_n) &\mapsto (x_1^{\sigma_{1,1}} x_2^{\sigma_{1,2}} \cdots x_n^{\sigma_{1,n}}, \dots, x_1^{\sigma_{n,1}} x_2^{\sigma_{n,2}} \cdots x_n^{\sigma_{n,n}}) \end{aligned}$$

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For a regular simplicial cone of maximum dimension in the subdivided dual fan  $\Sigma^*(f)$  given by vectors  $\{r_1, \dots, r_n\}$ , we can consider the matrix  $\sigma = (r_1 \cdots r_n)$ .

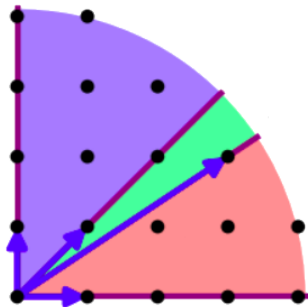
Gluing adequately these charts  $\pi_\sigma$ , we obtain a non-singular variety  $X$ , and a proper analytic map  $\pi: X \rightarrow \mathbb{C}^n$ : the toric blowup associated with  $\Sigma^*(f)$ .

# Resolution of singularities

## Theorem [Oka96, p. 101]

If  $f$  is Newton non-degenerate, then the associated toric blowup  $\pi: X \rightarrow \mathbb{C}^n$  is a good resolution of the  $f$  as a germ at the origin.

Consider again  $f = x^4 - y^5 + x^2y^2$ .

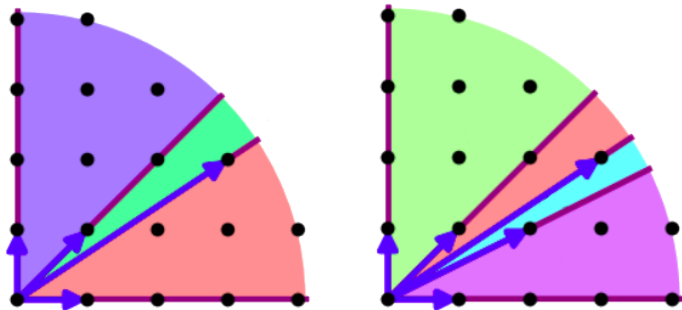


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The rays of the regular subdivision are

$$\begin{pmatrix} 1 & 2 & 3 & 1 & 0 \\ 0 & 1 & 2 & 1 & 1 \end{pmatrix}$$

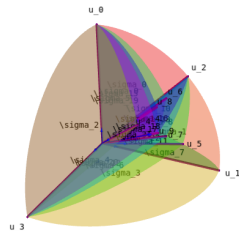
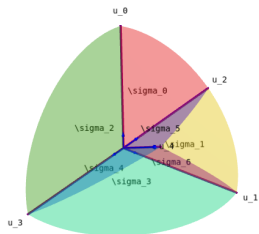
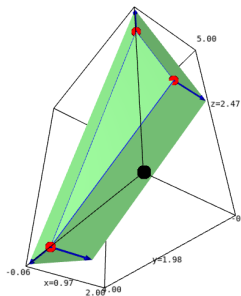
taking one of the charts, we perform the toric blowup as

$$\begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \implies (x, y) \mapsto (z^3w, z^2w)$$
$$\pi^*f = z^{10}w^4(z^2 - w + 1)$$



# 3 dimensional example

Consider  $f = xz^3 + z^4 + y^3 \in \mathbb{C}[x, y, z]$ . Construct Newton polyhedron, dual cone and a regular simplicial subdivision.



Take the chart  $\{(1, 0, 0), (3, 4, 3), (1, 1, 1)\}$ , then the resolution gives

$$(x, y, z) \xrightarrow{\begin{pmatrix} 1 & 0 & 0 \\ 3 & 4 & 3 \\ 1 & 1 & 1 \end{pmatrix}} (u, u^3 v^4 z^3, uvw) \implies \pi^* f = u^4 v^3 w^3 (u^5 v^9 w^6 + vw + 1)$$

Note that the partial derivatives vanish all only on  $v = w = 0$ , which are not points on the curve  $\pi^* f = 0$ .

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# Bernstein-Sato polynomial

- Bernstein [Ber72] in the case of polynomials
- Kashiwara [Kas76] in the case of holomorphic functions
- Björk [Bjö73] in the case of formal power series

## Theorem

Let  $f \in R$  be a polynomial. Then, there exists a polynomial  $P(s) \in \mathcal{D}[s]$  and a polynomial  $e_{f,P}(s) \in \mathbb{C}[s]$  such that the relation

$$P(s)f^{s+1} = e_{f,P}(s)f^s$$

holds formally in the  $\mathcal{D}$ -module  $R_f[s] \cdot f^s$ .



# Bernstein-Sato polynomial

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## Definition (Bernstein-Sato polynomial)

The Bernstein-Sato polynomial  $b_f(s)$  is the monic generator of the ideal in  $\mathbb{C}[s]$  consisting of polynomials  $e_{f,P}(s)$  satisfying such a functional equation.

First algorithm to compute it introduced by Oaku in [Oak97], using non-commutative Gröbner basis in the Weyl algebra.

# Bernstein-Sato polynomial

## Example

Let  $f = x_1^2 + \cdots + x_n^2$  in  $\mathbb{C}[x_1, \dots, x_n]$ . Then, we have

$$\left( \frac{\partial^2}{\partial x_1^2} + \cdots + \frac{\partial^2}{\partial x_n^2} \right) f^{s+1} = 4(s+1) \left( s + \frac{n}{2} \right) f^s$$

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Roots of the Bernstein-Sato polynomial

- $-1$  is always a root. We write  $\tilde{b}_f(s) = b_f(s)/(s+1)$  for the *reduced* BS.
- All roots are negative rational numbers [Mal75; Kas76].
- A set of candidate roots can be obtained from a resolution of singularities [Kol97; Lic89].

## Theorem

With the notations introduced for the resolution of singularities, we have that every root of the Bernstein-Sato polynomial  $b_f$  is of the form

$$-\frac{k_j + \nu}{N_j}, \quad j \in J, \nu \in \mathbb{Z}_{\geq 0}$$

# Topological zeta function

## Definition (Topological zeta function) [DL92, Thm. 3.2]

Let  $f \in \mathbb{C}[x_1, \dots, x_n]$  be a non-constant polynomial and choose an embedded resolution  $\pi: Y \rightarrow \mathbb{A}_{\mathbb{C}}^n$  of  $\{f = 0\}$ . The *local topological zeta function* of  $f$  at  $a \in \{f = 0\}$  is

$$Z_{\text{top},a}(f; s) := \sum_{I \subset J} \chi(E_I^\circ \cap \pi^{-1}\{a\}) \prod_{i \in I} \frac{1}{k_i + N_i s}$$

where  $I$  runs through all possible subsets of  $J$ .

# Monodromy conjecture

- Formulated by the Igusa in the late seventies, after some examples computed.
- Originally stated in terms of the  $p$ -adic zeta function, but has analogous statements in topological and motivic settings.

## Monodromy conjecture, topological version

Let  $f \in \mathbb{C}[x_1, \dots, x_n]$  be non-constant. If  $s_0$  is a pole of  $Z_{\text{top}}(f, \varphi; s)$ , then

- (*standard*)  $e^{2\pi i \Re(s_0)}$  is a monodromy eigenvalue of  $f: \mathbb{C}^n \rightarrow \mathbb{C}$  at some point of  $\{f = 0\}$ .
- (*strong*)  $s_0$  is a root of the Bernstein-Sato polynomial  $b_f$ .

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Strong version implies the standard one

## Proposition 7.1 [Mal83]

If  $-\alpha$  is a root of  $\tilde{b}_{f,0}(s)$ , then  $e^{2\pi i \alpha}$  is an eigenvalue of the monodromy of  $f$  at the origin.

# Topological zeta function for NND

Let  $\tau$  be a face in  $\Gamma(f)$ , and consider a decomposition of the associated cone  $\Delta_\tau = \cup_{i=1}^r \Delta_i$  in simplicial cones of dimension  $\dim \Delta_\tau = l$  such that  $\dim(\Delta_i \cap \Delta_j) < l$ , for all  $i \neq j$ . Then, define

$$J(\tau, s) := \sum_{i=1}^r J_{\Delta_i}(s), \quad \text{with} \quad J_{\Delta_i}(s) = \frac{\text{mult}(\Delta_i)}{(N(a_{i_1})s + k(a_{i_1})) \cdots (N(a_{i_l})s + k(a_{i_l}))}$$

being  $a_{i_1}, \dots, a_{i_l} \in \mathbb{N}^n$  the linearly independent primitive integral vectors that generate  $\Delta_i$ . Lastly, if  $\tau = \Gamma(f)$ , we rather take  $J(\tau, s) = 1$ .

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## Theorem 5.3 [DL92]

Let  $f: (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$  be a germ of a holomorphic function Newton non-degenerate for  $\Gamma_0(f)$ , then

$$Z_0(s) = \sum_{\substack{\tau \text{ vertex} \\ \text{of } \Gamma(f)}} J(\tau, s) + \left( \frac{s}{s+1} \right) \sum_{\substack{\tau \text{ compact} \\ \text{face of } \Gamma(f) \\ \dim \tau \geq 1}} (-1)^{\dim \tau} (\dim \tau)! \text{Vol}(\tau) J(\tau, s)$$



# Sketch of the proof for NND

## Theorem 4.2 [Loe90]

Let  $f$  be a germ of an analytic function, Newton non-degenerate at the origin. Let  $\tau_0$  be a compact face of codimension 1 of  $\Gamma(f)$ . Suppose that the following two conditions are verified

- ①  $\frac{k(\tau_0)}{N(\tau_0)} \notin \mathbb{Z}$ ,
- ② For every face  $\tau$  of codimension 1 of  $\Gamma(f, 0)$ , distinct of  $\tau_0$  and having non-empty intersection with  $\tau_0$ , we have  $\varepsilon(\tau_0, \tau) \notin \mathbb{Z}$ .

Then, there exists a horizontal multiform section  $\gamma(t)$  of the fibration  $H_n$  over  $T'$  such that

$$\lim_{t \rightarrow 0} t^{1 - \frac{k(\tau_0)}{N(\tau_0)}} \int_{\gamma(t)} \frac{dx_1 \wedge \cdots \wedge dx_n}{df} = C$$

with  $C$  a non-zero constant.

## Proposition 3.3 [Mal73]

The polynomial  $(s + \mu_1) \cdots (s + \mu_p)$  divides  $\tilde{b}$ .

# Resolution of singularities via combinatorics of the Newton polygon

An introduction to toric varieties and the monodromy conjecture.

`https://github.com/baezaguasch/MonodromyNND  
ob410 (at) cam.ac.uk`

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