

Quantum correlated recording through scattering from turbulent media



JCEP

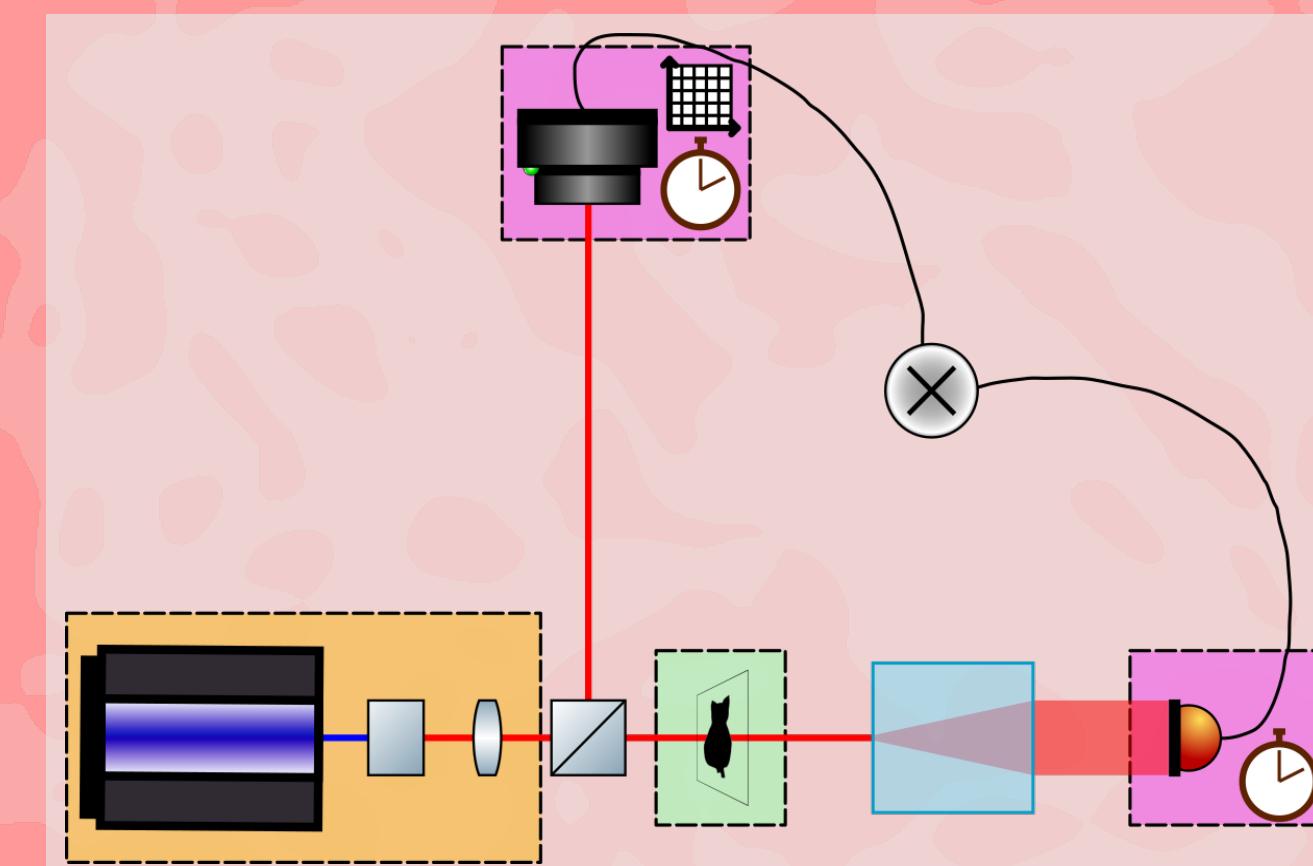
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Motivation

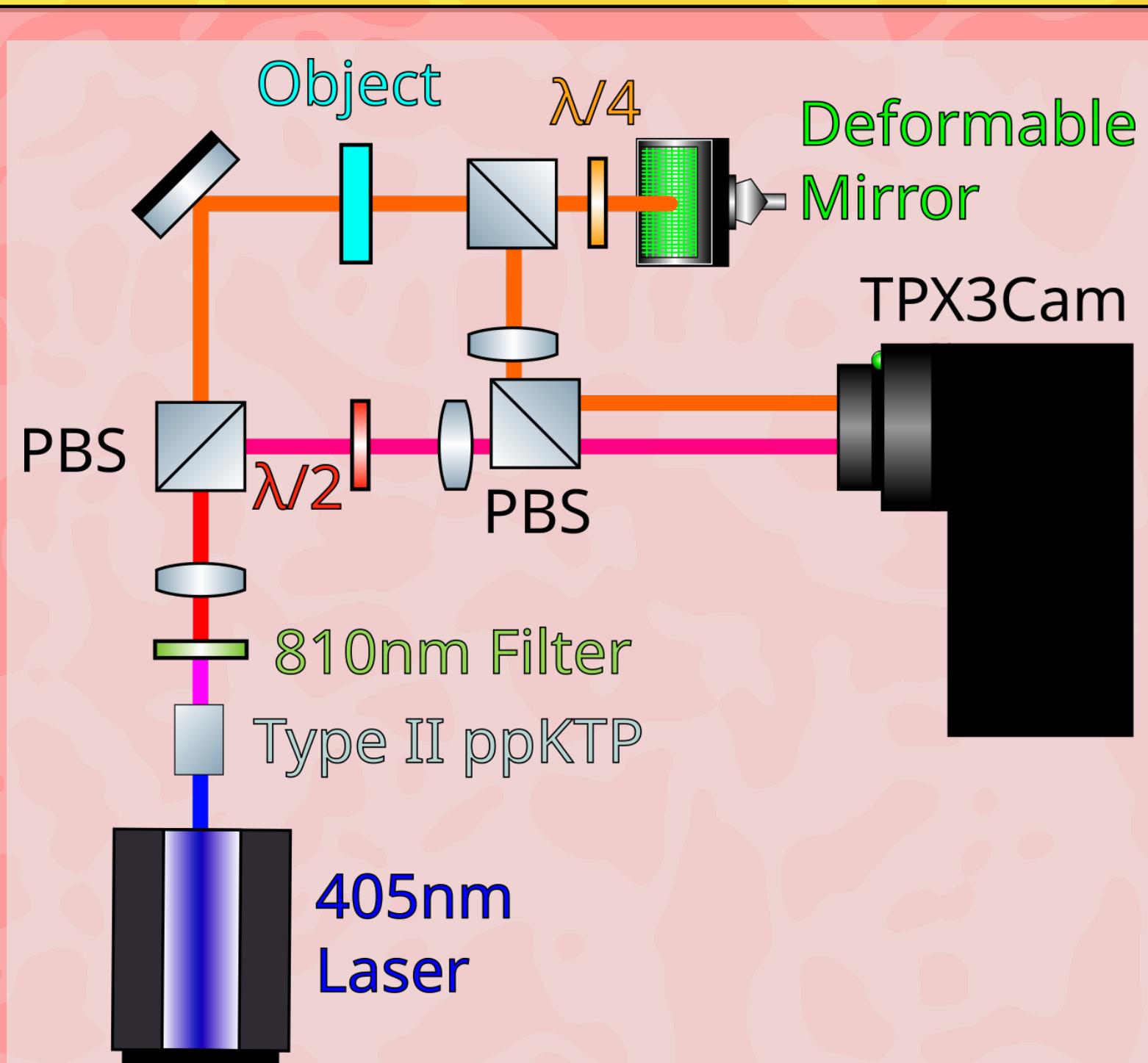
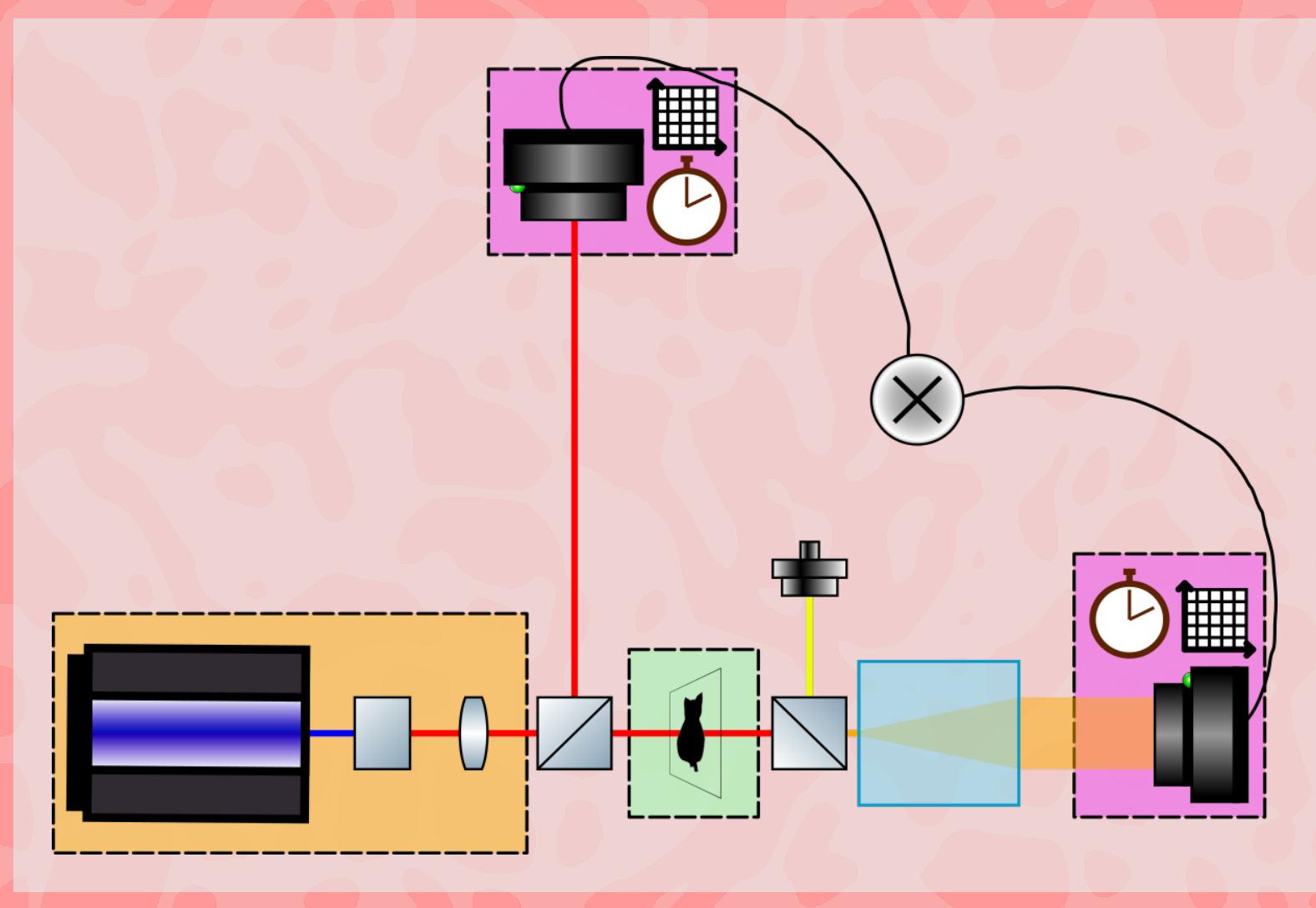
Ghost imaging (GI) is a method of imaging an object indirectly via timing and momentum correlations between a signal and idler beam^[1]. GI has been shown to be **robust against post-object scattering**^[2].



Quantum illumination (QI) is a method of distinguishing light which interacted with an object by taking advantage of timing (and optionally momentum) correlations between a signal and idler beam^[3]. QI has been shown to be robust against noise in the object arm^[4].

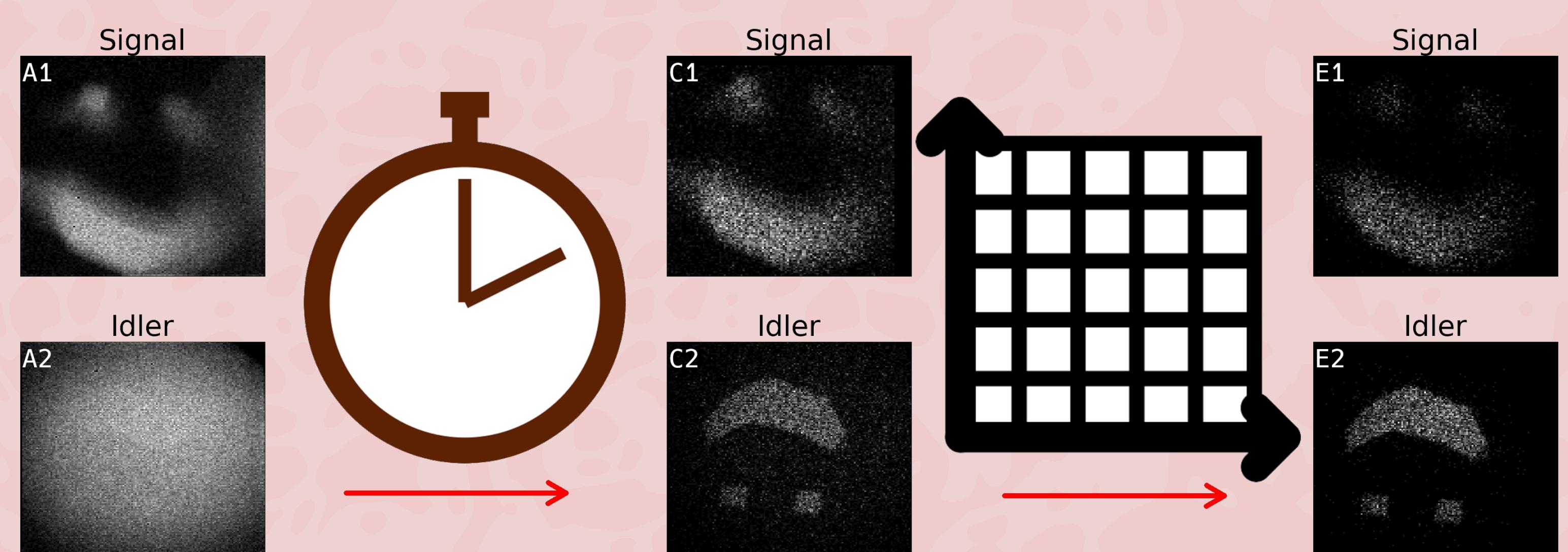
Can the scattering robustness of GI be combined with the noise robustness of QI?

Design

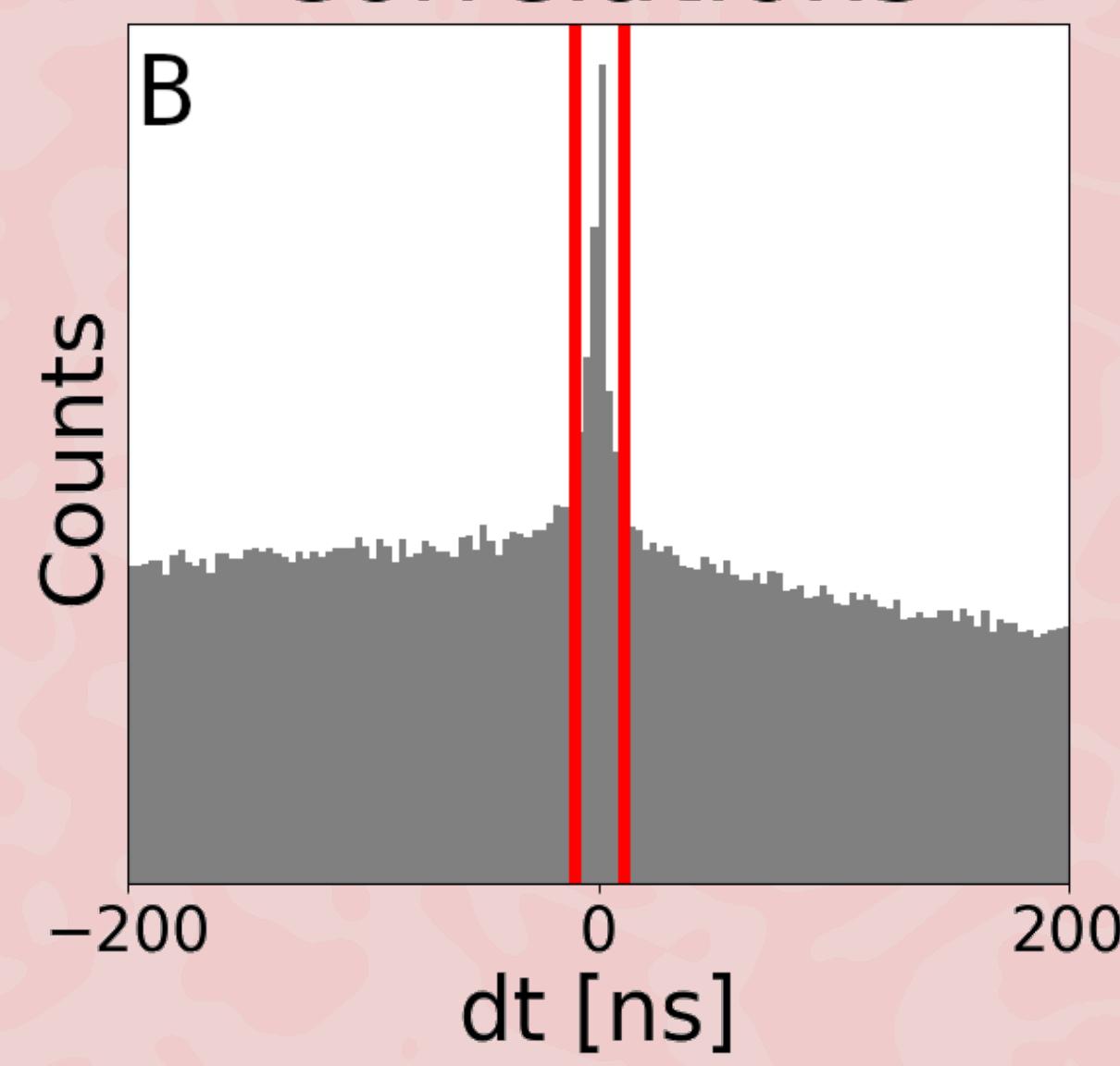


High SPDC flux and room lights used as source of **noise**. Scattering is caused by a **deformable mirror** which emulates turbulent media.

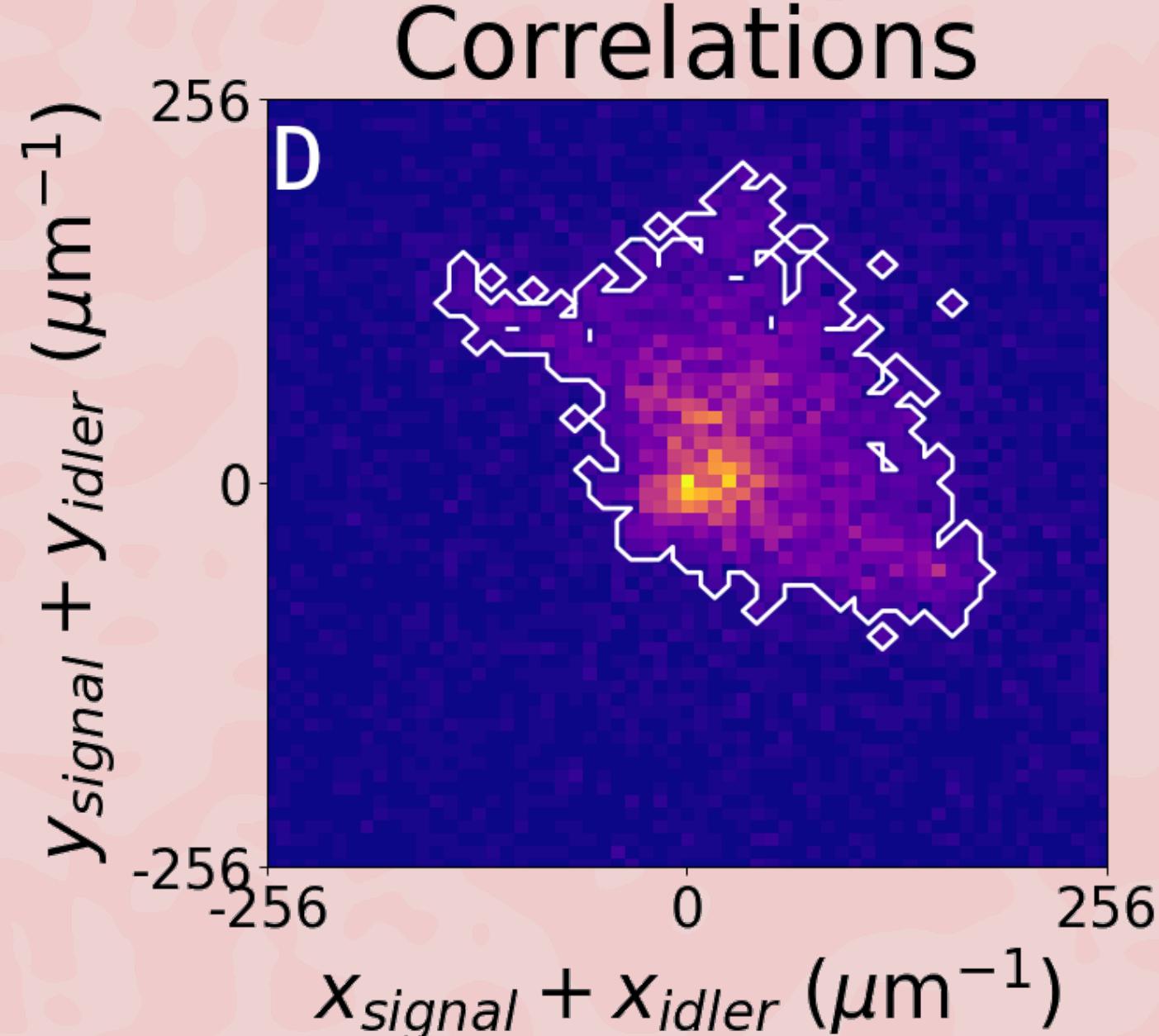
Two steps are required to perform spatially-filtered quantum correlated (SFQC) imaging: **time filtering**, and **space filtering**^[4,5].



Temporal Correlations

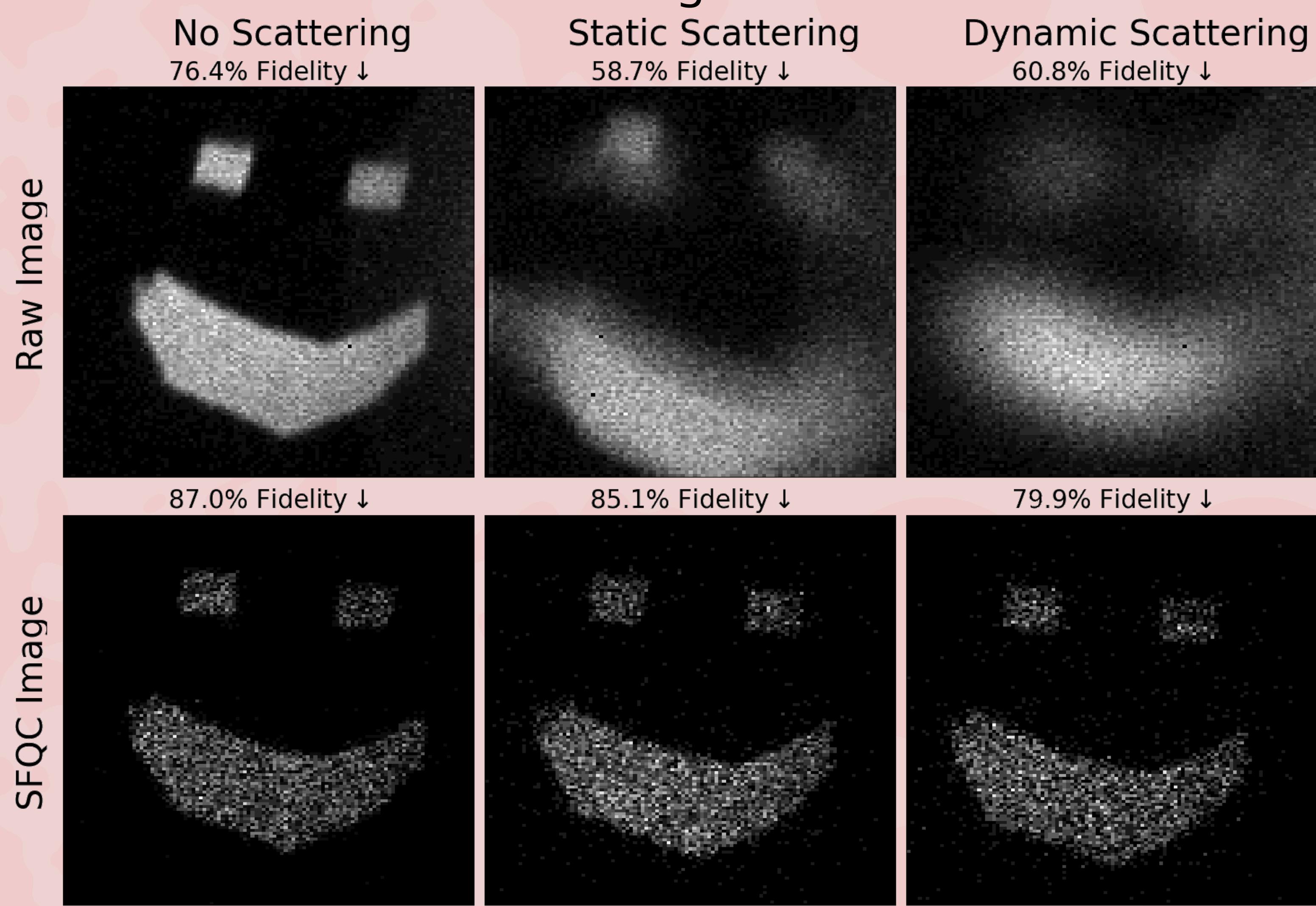


Spatial Correlations



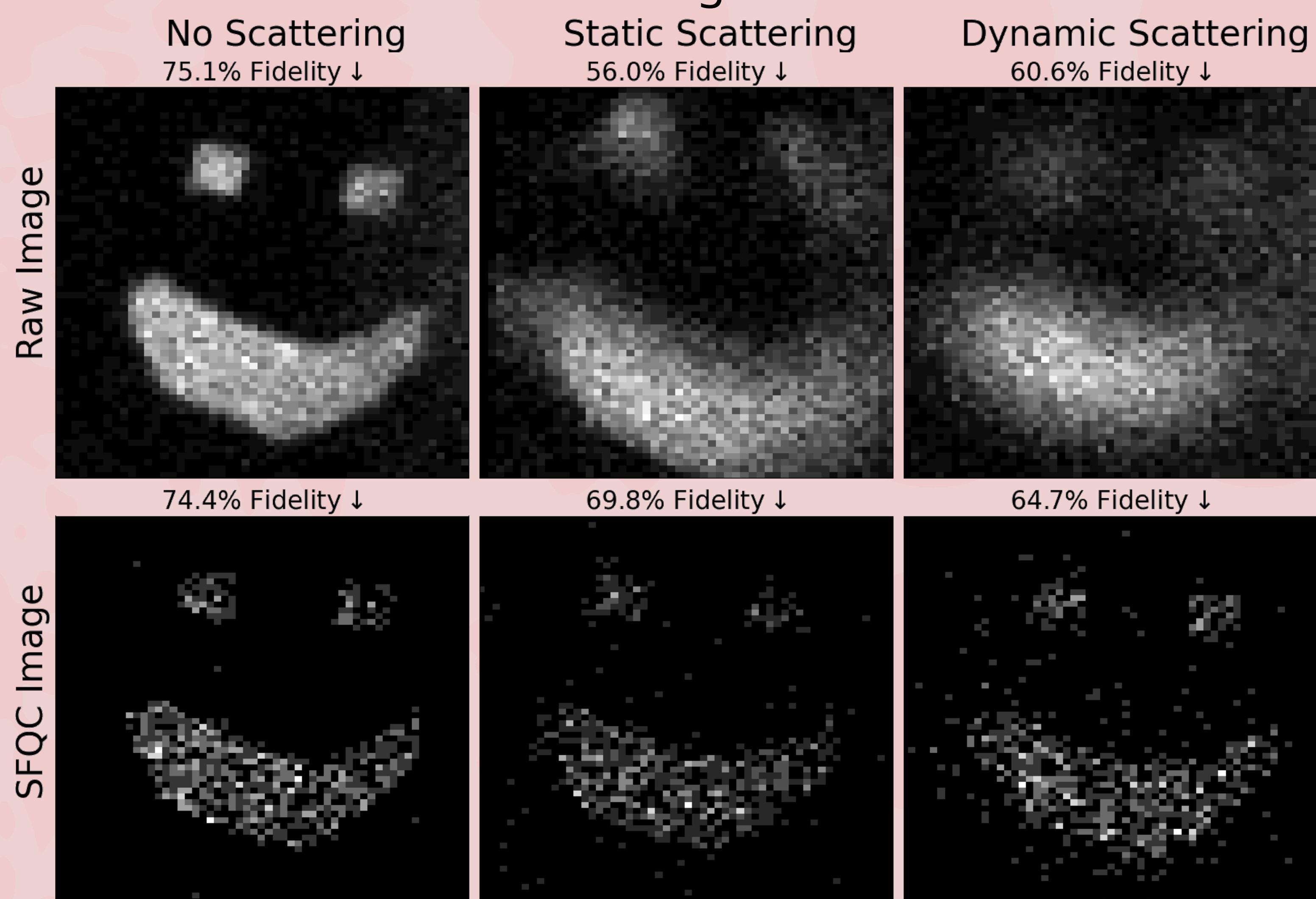
Results

5 Second Integration Time

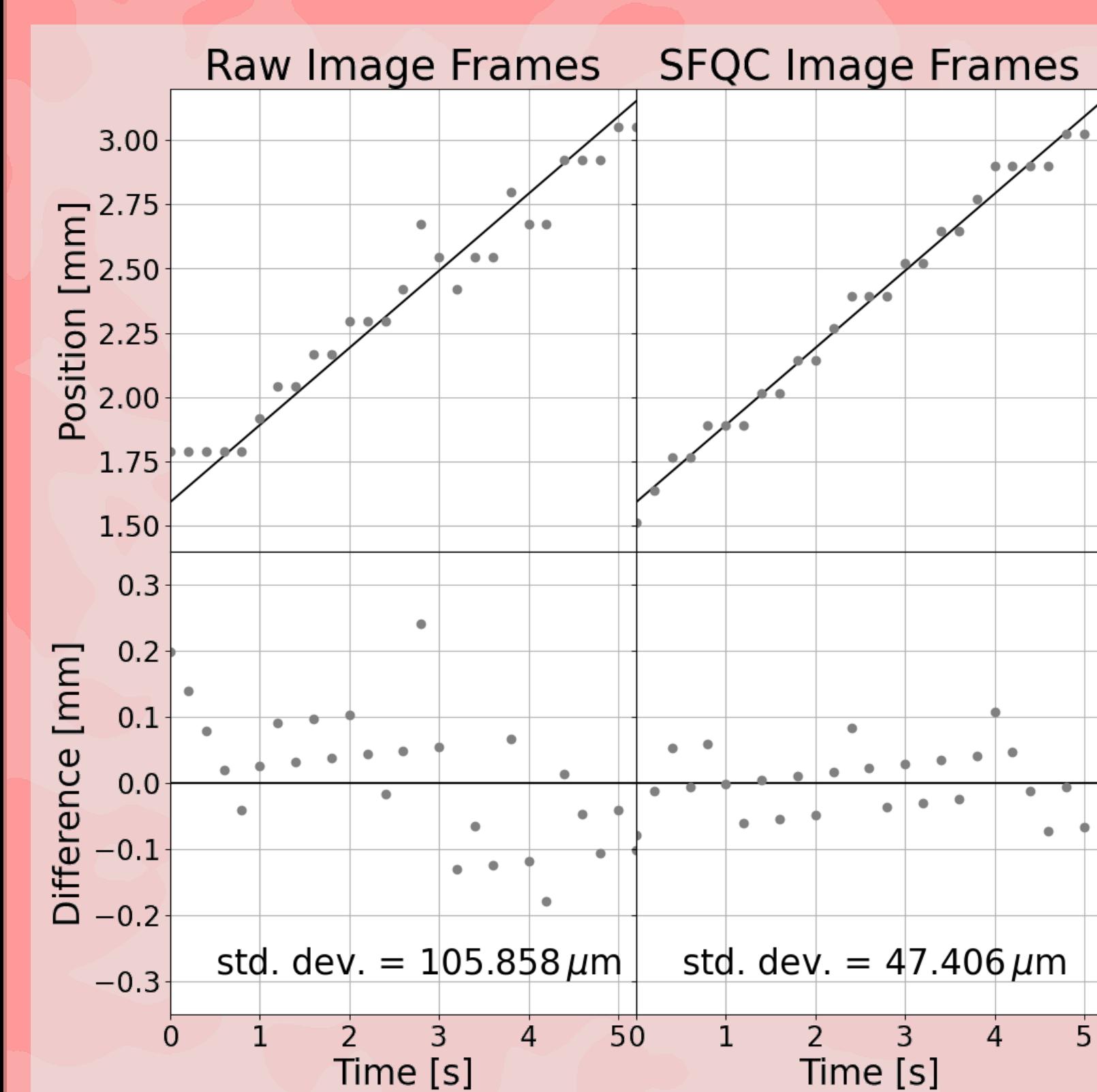


Results from **5 second integration time**. Fidelity measurement comes from the maximum of a cross-correlation measurement, where the reference image was taken classically from a 30 second integration time exposure. **The fidelity of the SFQC images were consistently significantly higher than the corresponding raw image in all three imaging schemes.**

0.5 Second Integration Time



Results from **0.5 second integration time**. The fidelity measurement increase were either insignificant or small. Qualitatively, however, there appears to be an improvement in the SFQC image similarity to the reference.



An alternative **object tracking metric** (location of the maximum of the cross-correlation measurement) was used to quantify this improvement for short integration times. The target was translated across the transverse beam profile. The SFQC recording showed a less than half the uncertainty in **object location** compared to the raw recording with 0.2 second integration times.

Link to real-time video:



References and Acknowledgements

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Special thanks to Andrew Proppe, Kyle Jordan, and Guillaume Thekkadeth for advice in lab and in theory

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