Solve
$$\alpha = 0$$

$$y = 0$$

$$x + y = 1$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Prof. Kedukodi Babushri Srinivas, Deparement of Mathematics, MIT Manipal

al decomposition:

- * veeful for moonsistent systems.
- # Gives Prof. Prof. Babushri Sfinivas, Department of Mathematics, MIT Manipal

QR decomposition $A = \begin{bmatrix} 2 & 2 & 0 \\ 0 & 4 & 0 \\ 0 & -3 & 5 \end{bmatrix}$ A sparce matrices Grom-Sehnidt -> Produces numerical errors.

procuss

1 Salution Solution Length invariant operations one useful handle these numerical errors.

Length invariant ophations.

- 1) Rotations (Giren's rotation)

2) Reflections (Householder reflection method) or Householder transformation)

Rotation matrix: [who -kind] > orthogonal matrix.

Notations:

 $cos\theta = c$ $sin\theta = s$

(As o ned not be calculated explicitly)

$$\begin{bmatrix} C & -S \\ S & C \end{bmatrix} \begin{bmatrix} 9L \\ 4 \end{bmatrix} = \begin{bmatrix} Y \\ 0 \end{bmatrix}, \quad Y = \begin{bmatrix} 9V + 4V \\ 0 \end{bmatrix}$$

$$\Rightarrow c_{x} - s_{y} = r$$

$$s_{x} + c_{y} = 0$$

$$\Rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c & -s \\ s & c \end{bmatrix} \begin{bmatrix} r \\ o \end{bmatrix}$$

$$\begin{bmatrix} c & -s \\ s & c \end{bmatrix}^{\mathsf{T}} \begin{bmatrix} \mathsf{Y} \\ \mathsf{o} \end{bmatrix}$$

Take
$$x = 4$$
 ; $y = -3$
 $r = \sqrt{4^{2} + (-3)^{2}} = 5$
 $c = \frac{2}{r} = \frac{4}{5}$

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

Giren's
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & C & -S \\ 0 & g & c \end{bmatrix} \begin{bmatrix} x & x & 0 \\ 0 & 4 & 0 \\ 0 & -3 & S \end{bmatrix}$$

The strict $\begin{bmatrix} 1 & 0 & 0 \\ 0 & g & c \end{bmatrix} \begin{bmatrix} x & x & 0 \\ 0 & 4 & 0 \\ 0 & 3/S & 4/S \end{bmatrix} \begin{bmatrix} x & x & 0 \\ 0 & 4 & 0 \\ 0 & -3 & S \end{bmatrix}$

$$\begin{bmatrix} 2 & 2 & 0 \\ 0 & 5 & -3 \\ 0 & 0 & 4 \end{bmatrix} = 2 \quad (upper triangular)$$

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

Giren's matrices:

$$xy$$
 -plane: [$use - kine = 0$] (notation in $kine = use = 0$) xy -plane)

.

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

Soln:
$$\begin{bmatrix} 3 & -1 & 2 \\ 0 & 0 & 9 \\ 4 & 7 & 11 \end{bmatrix} \begin{bmatrix} 92 \\ 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 9 \\ 40 \end{bmatrix}$$

$$P_{132} A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 3 & -1 & 2 \\ 0 & 0 & 9 \\ 4 & 7 & 11 \end{bmatrix}$$

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

$$T : \sqrt{92 + 9^{2}} = \sqrt{3^{2} + 4^{2}} : 5.$$

$$C : \frac{92}{7} = \frac{3}{5}$$

$$S : -\frac{4}{7} = -\frac{4}{5}$$
Using firm's refation on B,
$$G_{1}B : \begin{bmatrix} c & -s & 0 \\ s & c & 0 \\ 0 & 0 & 1 \end{bmatrix} B : = \begin{bmatrix} 3/5 & -4/6 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 9 \end{bmatrix}$$

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

$$G_{1}B = \begin{bmatrix} 5 & 5 & 10 \\ 0 & 5 & 5 \\ 0 & 0 & 9 \end{bmatrix} = R.$$

$$B = G_{1}^{T}R$$

$$= \begin{bmatrix} 3/5 & -4/5 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 5 & 10 \\ 0 & 5 & 5 \\ 0 & 0 & 9 \end{bmatrix}$$

= 8L

$$\Rightarrow BX = P_{132} \begin{bmatrix} 5 \\ 9 \\ 40 \end{bmatrix} = \begin{bmatrix} 5 \\ 40 \\ 9 \end{bmatrix}$$

$$\Rightarrow RX : \begin{bmatrix} 3/5 & 415 & 0 \\ -4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 40 \\ 9 \end{bmatrix}$$

$$= \begin{bmatrix} 35 \\ 20 \\ 9 \end{bmatrix}$$

$$= \begin{bmatrix} 3 \\ 2 \\ 2 \\ 0 \end{bmatrix} \begin{bmatrix} 4 \\ 2 \\ 2 \\ 0 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}$$

Prof. Kedukodi Babushri Srinivas, Department of Mathematics, MIT Manipal

$$3 92 = 9$$
 $3 2 = 1$

$$5 y + 5 2 = 20$$
 $3 y = 3$

$$5 9 + 5 9 + 10 2 = 35$$
 $3 9 = 1$