Praktikum 1-c: Analysis of LTI Using Z-transform

Consider a discrete-time causal LTI (linear time-invariant) system whose input- output relationship is described by the following difference equation:

$$y[n] - \frac{1}{4}y[n-1] - \frac{1}{8}y[n-2] = x[n-1]$$

a) Find the system function G[z].

Applying the linearity and time-shifting properties of the z-transform

$$G[z] = \frac{Y[z]}{X[z]} = \frac{z^{-1}}{1 - (1/4)z^{-1} - (1/8)z^{-2}} = \frac{z}{(z - 1/2)(z + 1/4)}$$

b) Find the impulse response g[n].

Noting that the system is causal and accordingly, the ROC of G[z] is z > 1/2 (the outside of the circle passing through the outermost pole), we obtain the inverse z-transform of G[z] as

$$g[n] = \mathcal{Z}^{-1} \left\{ \frac{z}{(z - 1/2)(z + 1/4)} \right\}^{\text{partial fraction expansion}} \stackrel{\text{expansion}}{=}$$

$$\mathcal{Z}^{-1} \left\{ \frac{4}{3} \left(\frac{z}{z - 1/2} - \frac{z}{z + 1/4} \right) \right\} \stackrel{\text{B.9(5)}}{=} \frac{4}{3} \left(\left(\frac{1}{2} \right)^n - \left(-\frac{1}{4} \right)^n \right) u_s[n]$$

Alternatively, the impulse response can be obtained directly from the difference equation, which can be solved iteratively with the unit impulse input $x[n] = \delta[n]$ and zero initial conditions:

$$y[n] = \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] + x[n-1]$$

where y[-1]=y[-2]=0 and $x[n-1]=\delta[n-1]=1$ only for n=1.

$$n = 0$$
: $y[0] = (1/4)y[-1] + (1/8)y[-2] + x[-1] = 0 - 0 + 0 = 0$

n = 1:
$$y[1] = (1/4)y[0] + (1/8)y[-1] + x[0] = 0 - 0 + 1 = 1$$

$$n = 2$$
: $y[2] = (1/4)y[1] + (1/8)y[0] + x[1] = 1/4 - 0 + 0 = 1/4$

n = 3:
$$y[3] = (1/4)y[2] + (1/8)y[1] + x[2] = 1/16 + 1/8 + 0 = 3/16$$