view frames Result Recorded at time: 1598.976 world Broadcaster: /world_CW/world_CW Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 HzAverage rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec ceiling_track_base link wall track base link zerog_room frame Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec wall track base link inertia ceiling track base link inertia Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec ceiling track slider link wall_track_slider_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ceiling arm base link wall arm base link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec wall arm base link inertia ceiling arm base ceiling arm base link inertia wall arm base Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec ceiling_arm_shoulder_link wall_arm_shoulder_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec wall_arm_upper_arm_link ceiling arm upper arm link Broadcaster: /robot state_publisher Broadcaster: /robot_state_publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec ceiling arm forearm link wall arm forearm link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec wall_arm_wrist_1 link ceiling_arm_wrist_1 link Broadcaster: /robot state_publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec ceiling arm wrist 2 link wall arm wrist 2 link Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 50.369 Hz Average rate: 50.369 Hz Most recent transform: 1598.960 (0.016 sec old) Most recent transform: 1598.960 (0.016 sec old) Buffer length: 2.442 sec Buffer length: 2.442 sec ceiling arm wrist 3 link wall arm wrist 3 link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec wall_arm_flange ceiling_arm_flange Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1598.976 sec old) Most recent transform: 0.000 (1598.976 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ceiling_arm_tool0 wall_arm_tool0