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L. 
$$\tau(n) = a. \tau(\frac{h}{b}) + \Theta(\frac{1}{h}. \log n)$$

a = number of subproblems in the recursion and <math>a > 1 $\frac{1}{b} = site of each problem.$ 

b) 1, k) o and pi3 a real number.

if 
$$a = b^k$$
, then

if p>-1, then  $T(n) = \Theta(n^{\log \frac{\alpha}{b}} \log n)$ if p=-1, then  $T(n) = \Theta(n^{\log \frac{\alpha}{b}} \log \log n)$ if p<-1, then  $T(n) = \Theta(n^{\log \frac{\alpha}{b}} \log \log n)$ 

if a < b then

if p>0, then Thn) = 0 (nklogh)

if  $\rho < 0$ , then  $\tau(n) = \theta(n^k)$ 

**a.** 
$$a=2$$
,  $b=4$ ;  $(nlogn)^{\frac{1}{2}} = n^{\frac{1}{2}} \cdot logh_n$ ;  $k=\frac{1}{2}$ ,  $p=\frac{1}{2}$ 

$$=) 2 = 4^{\frac{1}{2}} \cdot so$$

$$T(n) = \Theta\left(\log^{q} \log n\right) = \Theta\left(\sqrt{\log^{3} n}\right)$$

b. 
$$q=9$$
,  $b=3$ ;  $5n^2$ ;  $k=2$ ,  $p=0$ 
 $9=3^2$   $\Rightarrow$  50

$$T(n) = \Theta(n^{\log p}, \log n) = \Theta(n^2, \log n)$$

c. We can not solve this equation with moster theorem because a < 1.

e. We can not solve this equation with master theorem because the form of equation is wrong f  $\alpha = 7$ , b = 4, k = 1, p = 1

$$\frac{a}{7}$$
  $\frac{b}{41}$   $\Rightarrow$   $a > b^{\ell}$   $\Rightarrow$   $\tau(n) = \Theta(n^{\log_a b}) = \Theta(n^{\log_4 7})$ 

9. a=2 b=3 k=-1, we can not solve this equation with moster theorem because k < 0h. a=2/5 we can not solve this equation with moster theorem because a < 1

Borodir Etta Kılıncı

```
2. Implemented algorithm.
    void insertion Sort (int arr [], int n) {
         int i, key, j;
       for ( =1; T(n; T++) {
             key = arr [i];
            J = I-T
         while (j >=0 da arrij] > key) {
              : [[] = [[+[] ]]
```

5= 5-1;

3 3

	5							
	1 2 2	0	6		3	an [j.	6 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	t Heratra
	2	1	-2		6	2	2 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	
	2	0	6		3	6		
	2	1	6	3	3	6	2 \$ 3,3,6,1,4,5}	Sectord
-							2 { 3,3,6,1,4,5}	lteration
							arr [j+1] = key -> } 2,3,6,1,4,5	-7
	3	2	1	6	6 1			
	3	1	6	3		6	1 { 2,3,6,1,4,5}	
	3	0	6	2		3	1 & 2,3,6,6,4,5 }	Chird Heratra
-	3		6	null	-		1 {2,3,3,6,4,5}	
	3	-1	6	null	-	2	1 { 2,2,3, 6,4,5}	
						an	[j+1]=key + \21,2,3,6,4,5}	
	4	3	4	6	4		4 { 1,2,3,6,6,5}	_
	4	2	6	3	6		4 { 1,2,3,6,65 }	Fourth Heratron
						arr	[j+1] = key -> {1,2,3,6,4,5}	ाजवना <b>र</b>
4	5	4	S	6	5	(	5 \( \)	
	5	3	6	4	6	Q	5 { 1, 2, 3, 4, 6, 6}	Fifth Herotron.
							2 1, 4, 3, 4, 6, 6 }	Herotron.
							j+1] = key > £ 1,2,3,4,5,6}	

### 3. or Operation

## Array

### Linked List

Accessing the first element

In array we can use the indexing to access first element. We can use o mdex

O(T)

Itead will points to the first node so we can easly access the hard. & in single operation

0(1)

Accessing the last element

We can use the indexing here also length - 1 in modex is used to acress the bit element

Tail will points to the last node in the linked list. So we can access the bst element in single operation

Acessing any element in the middle

we can use the middle element index to access the element in middle so it takes single operation

Accessing element in the middle, we need to had temporarily current pointer and more to middle from head. So it takes n/2 operations at worst

Adding a new element

we can use He indexing to set the last madex with some value so it takes constant amortized

ue can make the tail. Next as new node and then make the new inserted element hode as tarl.

04)

Adding new element at the beginning

at the end

Adding new element at the beginning takes single operation only. But after addition we need to shift all existing element right by are position

we can occess the head and then we can create the new node. Then assign new rede as head

Adding new element in the middle.

Deleting 1 the first

element

Deleting any element

in the modele.

element

Adding element at middle take single operation only. But ofter adding we need to shift all indexes ofter middle to right by one position.

we need to loop from head to middle and then we need to create a new node and change the links. It takes n operation at worst case

we red to change head node only. After changing head node, we need to free the previous head node.

node of tail and then we need to free

the tail node and assign the before node

After deleting the first element we need to shift the all the elements from index I to length by one to the left side

Deleting the lost

ve reed to delete or unset the last index value only. There is no shifting reeded.

of tail as tail node.

After deleting the element we need to shift the elements in the rightside by one position to left side

we need to loop the 1st from head to the middle. node and then we need to remove the middle node and then we need to change the links.

we need to loop the list from head to last before

Operation Name Asyl)

Inter Liston)

Behody Ethe kiling

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3.b. the space complexity of the array is O(n) which is fixed and the space complexity of the linked list at worst case is o(n) and it will decreases during the best case. But we need to consider in worst case so it will takes O(n).

3)

4.

1. Creating the morder traversal array of a given binary tree.

2. It sorts the created morder array

3. It again traverses given bring tree in morder fashron and simultaneously it traverses sorted morder array. At each node visit of brings tree, the value of that node is changed to aurrespending element in the morder array. That is value of first node visited during morder traversal is changed to value of element at 0th index in sorted morder array value of second nace united during morder traversal is changed to value of element at 1st index so on.

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Mgorthan

```
void charetree To BST() }
      That( I moder = new mt[treesrie];
       mt [] index = new mt [s]
       create Inorder Array (root, morder, index);
       Arrays. sort (morder);
       mdex [07 =0;
       Chargellade Values (not, morder, index);
void change Nade Values (Tree Node purrent Node, int [] morder, int [] index) }
          If (current Node = = null) return;
       change Nobellolwes (currently bde. left, inardor, index);
        currentlade.volue = morder[index(0]];
        Index [0] +=1
        change Node Values ( current Nade . right, morder, mdex);
  void anotelnorderArray ( treeNade currentable, int[] inorder, mt(] index) {
       If (arrent Node = = Null) return )
        create Inader Array (current Note left, inoder, index);
        marde [mdex[0]] = currentlade + Value)
        mdex [0] +=1;
        create Inorder Array (aument Node . right, morder, index);
```

The time complexity of algorithm is olnlogn) where n is the number of nodes in the tree. This is because we need to do an in-order traversel of the tree, which takes our time, and then we need to sort the array which takes of linlogn) time.

# Best Case:

the best time complexity of this algorithm is Oln), where n is the number of nodes in the tree. This is because if the tree is already a BST, then we just need to do an inverder traversal of the tree, which takes idn) time.

#### Worst Case

The worst case time complexity of this algorithm is Ounlogn), where n is the number of nodes in the tree. This is because if the tree is not a BST then we need to do an inorder traversal of the tree, which takes O(n) time, and then we need to sort the array which takes O(n) time, and then we need to sort the array which takes O(n) time.

## Avarage Case:

the average case time complexity of this algorithm is a (nlogn), where n is the number of nodes in the tree. This is becomes we need to do an inorder traversal of the tree, which takes Oln) time, and then we need to sert array, which takes a (nlogn) time.

Bahoder Ether letting

find Pairs (arroy, x):

dictionary + {}

n = length of arroy

for i from 0 to n;

if x +arroy(i) is indictiony then

return (array [i], i + array [i])

else
append array [i] to dictionary

end if

end for

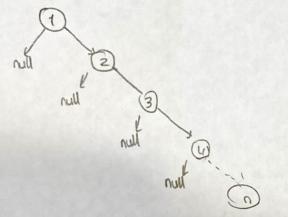
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Another In best case, the algorithm returns the firstly compared point. That means the loop will sterete only once, there for the best case complexity B 20)

In worst case, there might not be such a pair in the array or the pair hight be the last are to compared. Since we go overthe array once, we will make at most a comparisons and then return. There fore, the worst case complexity is old).

- 6. a. False. The shape of BST depends on the order in which elements are added. A new element is added to the BST as a new leafned, potentially increasing the depth of the tree. It is possible for the BST with a nodes to be chain of nodes of height n. This happens, for example, if all items are added in a sequential order. In general, it is preferable for a BST to be as shall ow as possible. This keeps the avarage cost of a BST transaction low.
  - b. True. The binary search tree is a balanced binary search tree. Height of the binary search tree becomes log(n). So time complexity of BST operations = O(logn)
    But in some cases the complexity is linear, time complexity of BST operations = O(n)
    When the tree is skewed:



- C. True. If the array is ordered, it takes constant time to find the largest and smallest element. If the array is not sorted we may need to sterate the whole array to find the largest or smallest element of this array then the time complexity is O(n).
- d. False In asse of arrays, the middle element can be accessed in O(1) time, but in linked 19ts, there is no concepts of indices as the element is allocated in a non-contiguous manner. So, the time complexity to find the middle of a linked 19t is O(n) Hence, binary search on arrays proves to be more efficient than in the linked list
- e-false. The insertion sort algorithm has two loops. One which iterates from 2 to array length and inner loop which iterates from the picked up element to all of the sorted array elements. The first loop executed n-1 time irrespective of input order of elements so the differentiation factor is inner loop execution. If the input array is neversely sorted then inner loop will execute maximum times.

  Below the kuling

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