

18 TTP229 touch module

1 Project process:

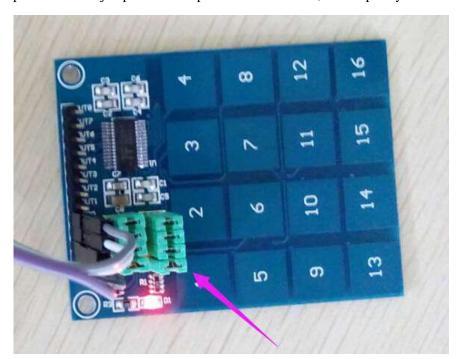
```
P pi@raspberrypi: ~/keyes_錁雞城娲鵑珮缜x增濂楠欢豎勬枡/TTP229鐢靛 瑙二傳妯"澈
Makefile TTP229 TTP229.c TTP229.o
pi@raspberrypi ~/keyes_树莓派高级版套件资料/TTP229电容触摸模块 $ sudo ./TTP229
start.....
TTP229:0
TTP229:0
TTP229:0
TTP229:0
TTP229:0
TTP229:0
TTP229:0
TTP229:0
TTP229:31744
TTP229:0
TTP229:0
Cpi@raspberrypi ~/keyes_树莓派高级版套件资料/TTP229电容触摸模块 $
```

2 Project source code:

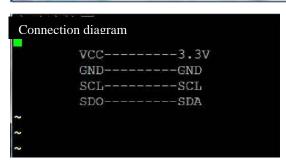
```
- - X
P pi@raspberrypi: ~/keyes_鍵發板踢鵑隔缩x增達櫛欢豎動枡/TTP229整靛 瑙(传烛"激
    include <bcm2835.h>
    #include <stdio.h>
    #include <unistd.h>
    unsigned char WriteBuf;
    unsigned char WriteBufl;
    unsigned int ReadBuf0;
    int main(int argc, char **argv)
        if (!bcm2835 init())
        return 1;
        bcm2835 i2c begin();
        bcm2835 i2c setSlaveAddress(0x57);
        bcm2835 i2c set baudrate(10000);
        printf("start.....\n");
        while(1)
                WriteBuf = 0x00;
                bcm2835_i2c_write_read_rs(&WriteBuf, 2, &WriteBuf1, 2);
                bcm2835 i2c read (&ReadBuf0,2);
                printf("TTP229:%d\n", ReadBuf0);
                printf ("\r");
"TTP229.c" [dos] 33L, 810C
                                                           1,5
                                                                         Top
```

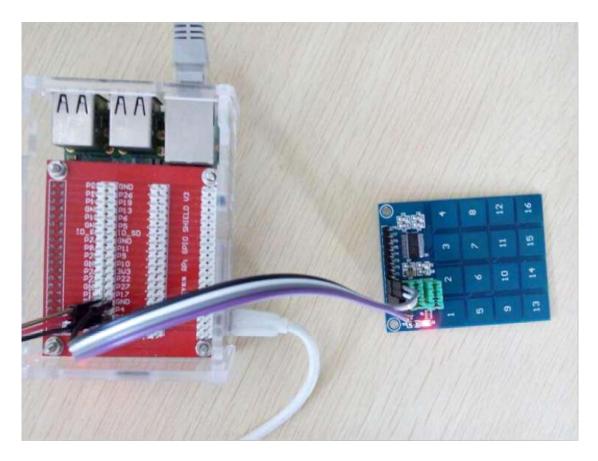
3 Project circuit connection:

Before connecting the TTP229 module to the Raspberry Pi, you need to short circuit some interfaces. Solder some pins and put on the wire jumper as below pic shows. Otherwise, the Raspberry Pi cannot recognize the TTP229 module.



raspl	perrypi 	~/keyes_	树莓派品	5级龙 +	(套件			9电容触	摸模块 \$ gg	oio rea	adall ++
всм	wPi	Name	Mode	V	Physical		I V	Mode	Name	wPi	BCM
		3.3v			1	2	i	i I	5v		
2	8 1	SDA.1	ALT0	1 0	3	4	1	1	5V	l l	1 1
3	9 1	SCL.1	ALT0	1	5	6			0v		
4	7 1	GPIO. 7	IN	1	7 1	8	1 1	ALT0	TXD	15	14
		0ν			9	10	1	ALT0	RXD	16	15
17	0 1	GPIO. 0	IN	1 0	11	12	0	IN	GPIO. 1	1	18
27	2	GPIO. 2	IN	1 0	13	14			0v	1	
22	3 1	GPIO. 3	IN	1 0	15	16	0	IN	GPIO. 4	4	23
		3.3v	Î	1	17	18	1 0	IN	GPIO. 5	5	24
10	12	MOSI	ALT0	1 0	19	20			0v		
9	l 13 l	MISO	ALT0	1 0	21	1 22	0	IN	GPIO. 6	1 6	25
11	14	SCLK	ALT0	0	23	24	1	ALT0	CE0	10	8
		0 v		1	25	26	1	ALT0	CE1	11	7 1
0	30	SDA.0	IN	1	27	28	1	IN	SCL.0	31	1
5	21	GPIO.21	IN	1	29	30	1		0v	I	1
6	22	GPIO.22	IN	1 1	31	32	0	IN	GPIO.26	26	12
13	23	GPIO.23	IN	1 0	33	34	ı		0v		
19	24	GPIO.24	IN	0	35	36	0	IN	GPIO.27	27	16
26	25	GPIO.25	IN	10	37	38	0	IN	GPIO.28	28	20
		0 v	I		39	40	0	IN	GPIO.29	29	21
всм	wPi	Name	Mode	∨	++ Physical +B Plus		∨	Mode	Name	WPi	BCM





4 Result

When the Raspberry Pi run the program, you can touch the 16 keys. For each key, the initial value is 0. When you touch the key, the value increases. When you release the key, the value decreases to 0.

