

## 13 ULN2003 stepper motor driving

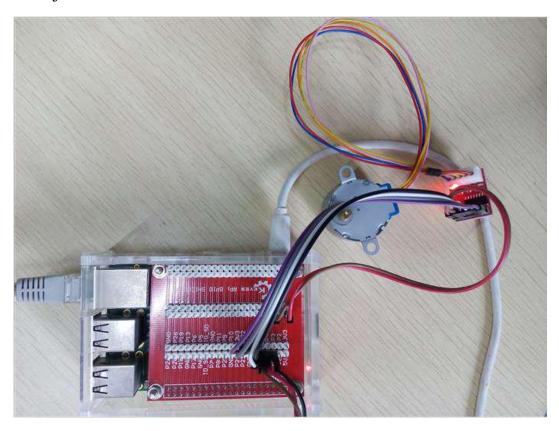
## 1 Project process:

```
pi@raspberrypi ~/keyes_树莓源域指摘的复数版套件资料/ULN2003 $ 1s
ULN2003.c
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $ vi ULN2003.c
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $ g++ ULN2003.c -o ULN2003
-lwiringPi
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $ 1s
ULN2003 ULN2003.c
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $ sudo ./ULN2003 0 1 2 3
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $
pi@raspberrypi ~/keyes_树莓派高级版套件资料/ULN2003 $
```

2 Project source code:

```
Pi@raspberrypi: ~/keyes_螺雞被娲鹃珮绾x增濂楠欢鑒動枡/ULN2003
  moto.c
  A program to control a stepper motor through the GPIO on Raspberry Pi.
 Author: Darran Zhang (http://www.codelast.com)
#include <wiringPi.h>
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
#define CLOCKWISE 1
#define COUNTER CLOCKWISE 2
void delayMS(int x);
void rotate(int* pins, int direction);
int main(int argc,char* argv[]) {
  if (argc < 4) {
    printf("Usage example: ./motor 0 1 2 3 \n");
    return 1;
  /* number of the pins which connected to the stepper motor driver board */
'ULN2003.c" 83L, 1996C
```

## 3 Project circuit connection:



## 4 Pin definition

Red circled area are GPIO ports corresponding to ULN2003 IN1 IN2 IN3 IN4.

BCM	wPi	Name	Mode	I V	Phys	ical	I V	Mode	Name	wPi	BCM
	+		+	+	++	+	+	+	·	+	+
		3.3v		1	1 1 1	1 2	1		5v		
2	8	SDA.1	ALTO	1	1 3 1	4	1	1	5⊽		
3	9	SCL.1	ALT0	11	1 5 1	16	1		0v		
4	7	GPIO. 7	IN	1	1 7 1	1 8	11	ALTO	TXD	15	14
		0v		1	1 9 1	10	11	ALTO	RXD	16	15
17	0	GPIO. 0	OUT	1	11	12	0	OUT	GPIO. 1	1	18
27	2	GPIO. 2	OUT	10	13	14			0v		1
22	3	GPIO. 3	OUT	0	15	16	10	IN	GPIO. 4	4	23
		3.3v			17	18	10	IN	GPIO. 5	5	24
10	12	MOSI	ALTO	10	1 19 1	1 20	1	1	0v		
9	13	MISO	ALT0	1 0	21	1 22	10	IN	GPIO. 6	1 6	25
11	14	SCLK	ALT0	0	23	1 24	11	ALTO	CEO	10	1 8
		0v		1	25	26	11	ALTO	CE1	11	1 7
0	30	SDA.0	I IN	11	1 27 1	28	11	IN	SCL.0	31	1
5	21	GPIO.21	IN	11	1 29 1	1 30	1	1	0v		
6	22	GPIO.22	IN	1	31	1 32	10	IN	GPIO.26	26	1 12
13	23	GPIO.23	IN	1 0	33	1 34	1	1	0v		
19	24	GPIO.24	I	1 0	35	1 36	10	IN	GPIO.27	1 27	1 16
26	25	GPIO.25	IN	1 0	1 37 1	1 38	10	IN	GPIO.28	1 28	1 20
	1	0Δ	I		39	40	1 0	IN	GPI0.29	29	21
BCM	wPi	Name	!   Mode	+ I ∇	tt   Phvs	+ ical	+	+   Mode	Name	+   wPi	+   BCM
JOH	MT T	Name	+		+B P			+		+	+

