Project 8: Buzzer control

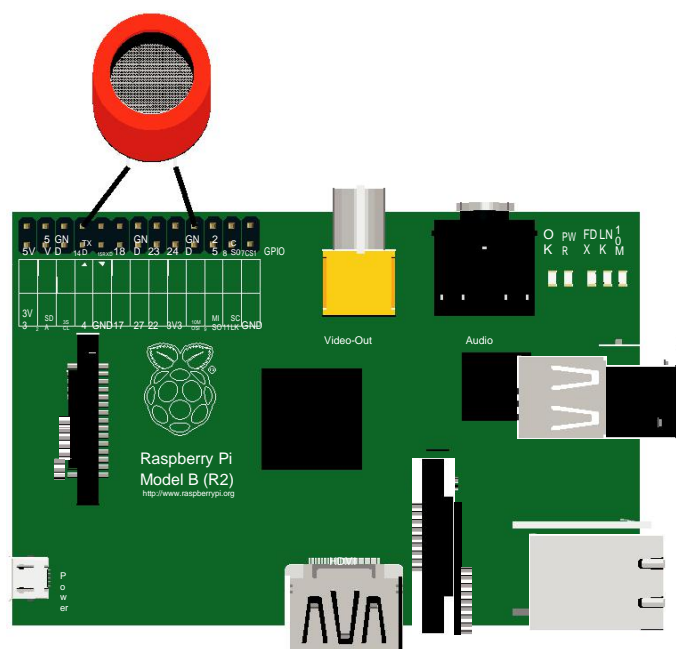Pic.1

```
GNU nano 2.2.6                    File: buzzer.c

#include <wiringPi.h>

int main()
{
        wiringPiSetup();
        int i=0;
        pinMode(15,OUTPUT);
        for(;;)
        {
                for(i=0;i<100;i++)

                {
                 digitalWrite(15,HIGH);
                 delay(1);
                 digitalWrite(15,LOW);
                 delay(1);
                        }

                for(i=0;i<100;i++)
                {
                        digitalWrite(15,HIGH);
                        delay(2);
                        digitalWrite(15,LOW);
                        delay(2);

                }
```

```
^G Get Help    ^O WriteOut    ^R Read File   ^Y Prev Page   ^K Cut Text    ^C Cur Pos
^X Exit        ^J Justify     ^W Where Is    ^V Next Page   ^U UnCut Text  ^T To Spell
```

Pic.2

pic. 3