

Rule-Based Graph Cleaning with GPUs on a Single Machine

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MOTIVATION

Graph Data Quality Matters.

Ubiquitous graphs, inevitable errors.

Single Machine Systems.

Limited budget, privacy concerns.

Trilemma.

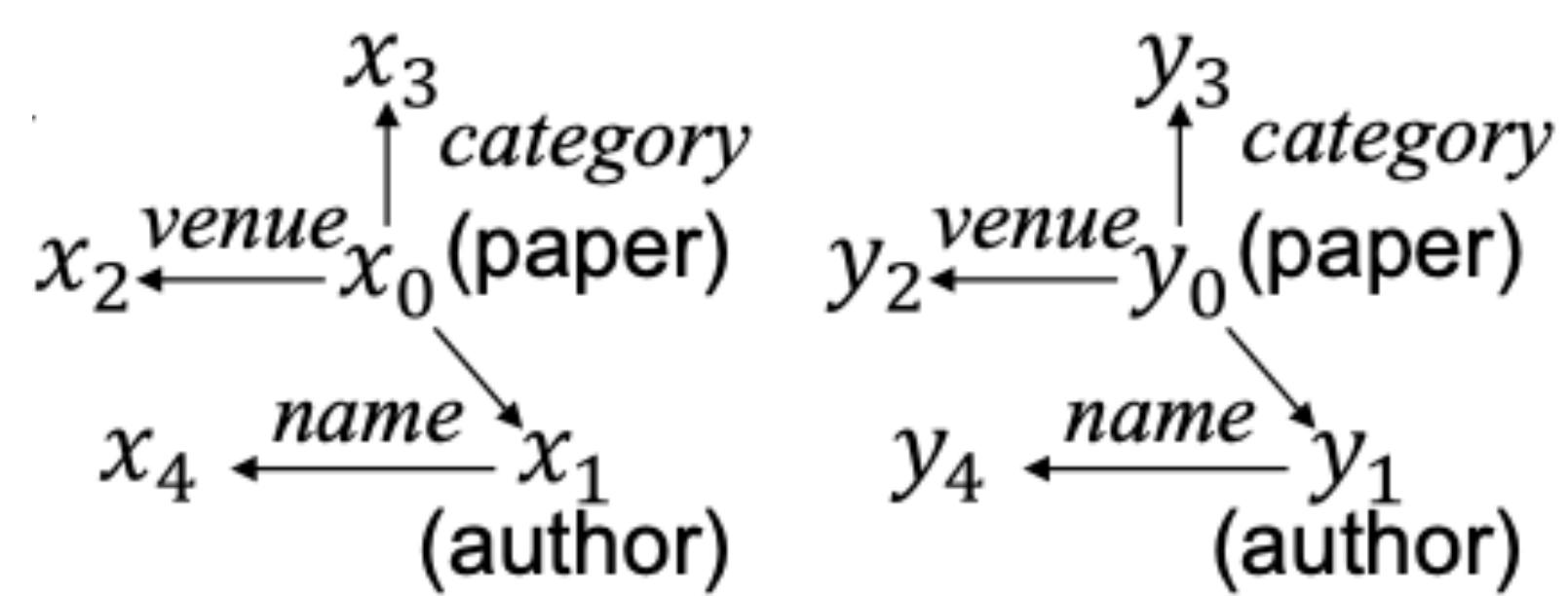
Generalizability, reliability, explainability.

PROBLEM DEFINITION

Graph Cleaning Rules (GCRs).

$$Q[x_0, y_0](X \rightarrow p_0)$$

$$p ::= x.A \oplus y.B \mid z.A \oplus c|M(x.A, y.B)$$



Graph Cleaning with GCRs.

- ✓ Rule Discovery $(G) \rightarrow \Sigma$
- ✓ Error Detection $(G, \Sigma) \rightarrow err$
- ✓ Error Correction $(G, \Sigma, err) \rightarrow fix$

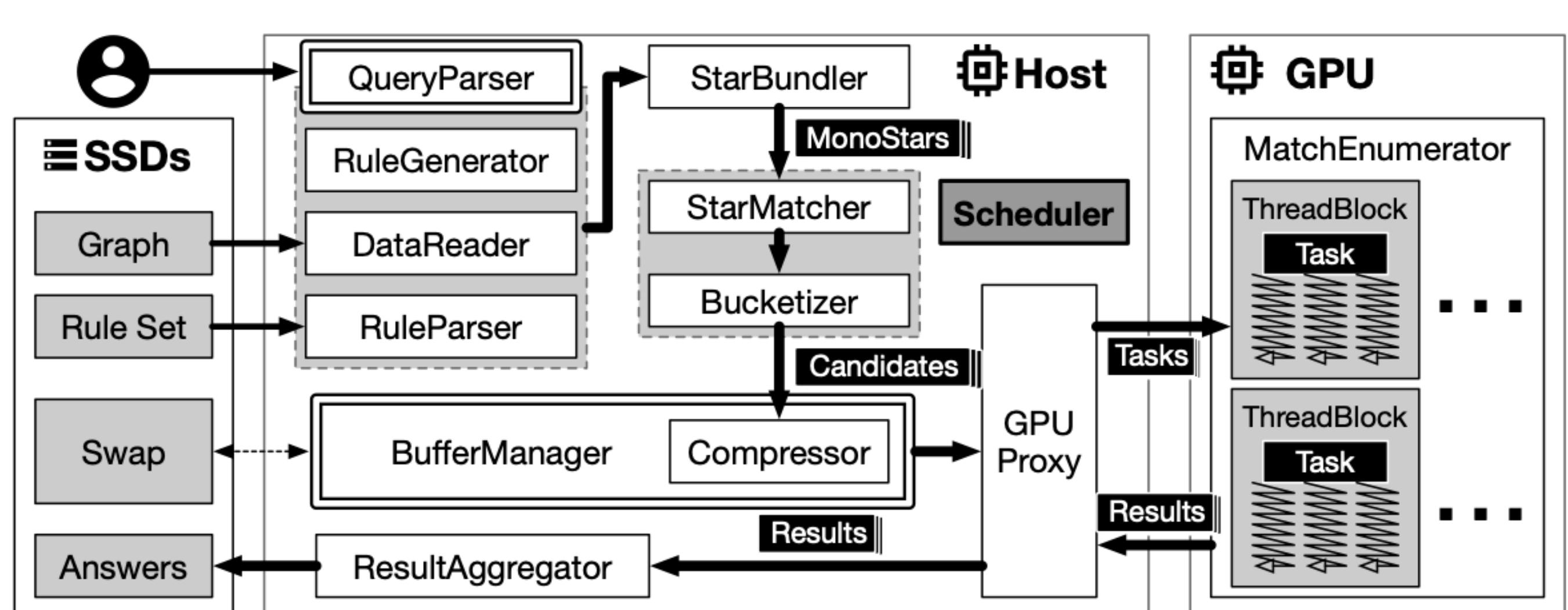
ARCHITECTURE

Hybrid Parallel Computing.

Multicore (CPU), SIMD (GPU).

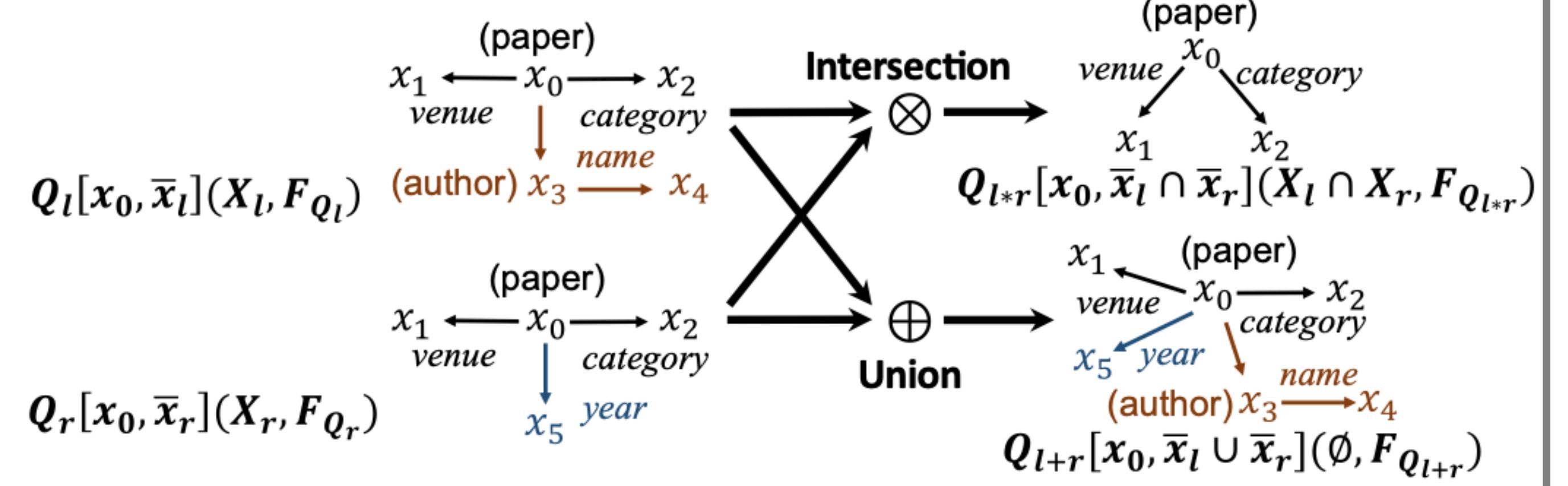
Pipelined Architecture.

Eliminating data transferring overhead.



METHODOLOGIES

Computation: Bundled Matching

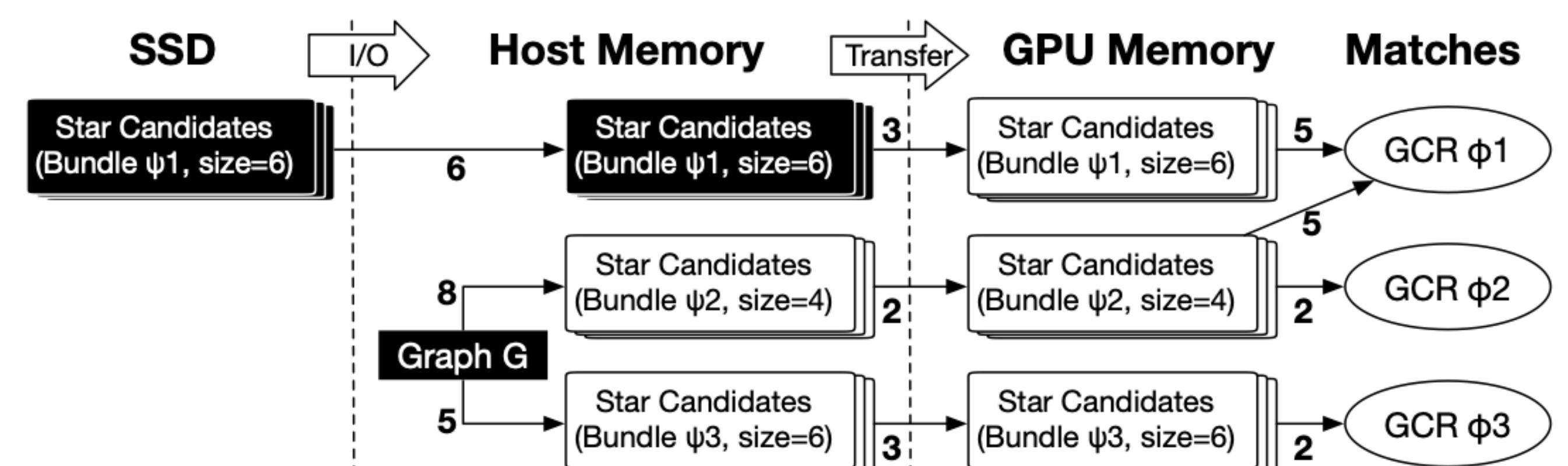


I/O: Conditional Succinct Table

Conditional succinct matches						Unfolded matches
Matches			Conditions			
$x_0.id$	$x_1.val$	$x_2.val$	$x_4.val$	$x_0.title$	$x_5.val$	
u_3	OSDI	CS	{J, S}	MR	null	
u_4	OSDI	CS	{J, S}	GFS	null	
u_1	OSDI	null	{M, P, J, S}	TF	2016	
u_2	OSDI	null	{M, P, J, S}	tf	2016	

Filtered out by $x_2.val = CS$

Utilization: Task Scheduling



EVALUATION

Table 3. Error detection efficiency with single-machine systems.

Graph & Metric	BioGRID		IMDB		SemScholar	
	Time (s)	I/O (GB)	Time (s)	I/O (GB)	Time (s)	I/O (GB)
MiniClean	259.6	18.97	325.5	23.82	2993.7	92.54
CoroGraph/Blaze	OOM	OOM	OOM	OOM	OOM	OOM
MiniGraph	65.34×	10.73×	TO	TO	TO	TO
HyperBlocker	11.29×	5.74×	OOM (GPU)	OOM (GPU)	OOM (GPU)	OOM (GPU)

◊ “OOM” denotes out-of-memory, “TO” denotes timeout after 8h.

Table 4. Efficiency and accuracy of MiniClean vs. ML models.

System	BioGRID			IMDB			SemScholar		
	Time	ER-F1% all (real)	CR-F1% synthetic	Time	ER-F1% all (real)	CR-F1% synthetic	Time	ER-F1% real	CR-F1% real
MiniClean	312.7s	98.7 (97.5)	97.2	409.1s	99.9 (94.0)	80.4	4089.1s	94.6	70.6
Ditto	7.7×	91.2 (91.0)	N/A	8.0×	95.6 (90.8)	N/A	4.3×	90.3	N/A
KGClean	11.9×	N/A	54.9	64.2×	N/A	20.0	11.9×	N/A	29.8

Findings.

- ✓ **More Efficient.** Faster than SOTA GPU-based system by over 11×.
- ✓ **More Accurate.** Outperform SOTA ER model by 4.3% and CR model by 40.4%