

# 1 Various Forms of DFT

## 1.1 The most general form of DFT

$$x_j = \frac{2\pi}{N}j, \quad j \in \mathbb{Z} \quad (1)$$

$$u(x_{j+N}) = u(x_j) \quad (2)$$

$$\tilde{u}_k = A \sum_{j=j_0}^{j_0+N-1} u(x_j) e^{-ikx_j}, \quad k \in \mathbb{Z} \quad (3)$$

$$\tilde{u}_{k+N} = \tilde{u}_k \quad (4)$$

$$u(x_j) = B \sum_{k=k_0}^{k_0+N-1} \tilde{u}_k e^{ikx_j}, \quad j \in \mathbb{Z} \quad (5)$$

$$AB = \frac{1}{N} \quad (6)$$

## 1.2 David's Implementing Spectral Methods for PDEs

$$x_j = \frac{2\pi}{N}j, \quad j = 0, 1, \dots, N-1 \quad (7)$$

$$\tilde{u}_k = \frac{1}{N} \sum_{j=0}^{N-1} u(x_j) e^{-ikx_j}, \quad k = 0, 1, \dots, N-1 \quad (8)$$

$$u(x_j) = \sum_{k=0}^{N-1} \tilde{u}_k e^{ikx_j}, \quad j = 0, 1, \dots, N-1 \quad (9)$$

## 1.3 Scipy

$$x_j = \frac{2\pi}{N}j, \quad j = 0, 1, \dots, N-1 \quad (10)$$

$$\tilde{u}_k = \sum_{j=0}^{N-1} u(x_j) e^{-ikx_j}, \quad k = 0, 1, \dots, N-1 \quad (11)$$

$$u(x_j) = \frac{1}{N} \sum_{k=0}^{N-1} \tilde{u}_k e^{ikx_j}, \quad j = 0, 1, \dots, N-1 \quad (12)$$

## 1.4 Hussaini, Spectral Methods in Fluid Dynamics

$$x_j = \frac{2\pi}{N}j, \quad j = 0, 1, \dots, N-1 \quad (13)$$

$$\tilde{u}_k = \frac{1}{N} \sum_{j=0}^{N-1} u(x_j) e^{-ikx_j}, \quad k = -\frac{N}{2}, \dots, \frac{N}{2}-1 \quad (14)$$

$$u(x_j) = \sum_{k=-N/2}^{N/2-1} \tilde{u}_k e^{ikx_j}, \quad j = 0, 1, \dots, N-1 \quad (15)$$

## 1.5 Trefethen, Spectral Methods in Matlab

$$x_j = \frac{2\pi}{N}j, \quad j = 1, 2, \dots, N \quad (16)$$

$$\tilde{u}_k = \frac{2\pi}{N} \sum_{j=1}^N u(x_j) e^{-ikx_j}, \quad k = -\frac{N}{2} + 1, \dots, \frac{N}{2} \quad (17)$$

$$u(x_j) = \frac{1}{2\pi} \sum_{k=-N/2+1}^{N/2} \tilde{u}_k e^{ikx_j}, \quad j = 1, \dots, N \quad (18)$$

## 1.6 Matlab

$$Y(k) = \sum_{j=1}^n X(j) e^{-i(k-1)x_{j-1}}, \quad k = 1, 2, \dots, N \quad (19)$$

$$X(j) = \frac{1}{N} \sum_{k=1}^n Y(k) e^{i(k-1)x_{j-1}}, \quad j = 1, 2, \dots, N \quad (20)$$

$$Y(k) = \tilde{u}_{k-1}, \quad k = 1, 2, \dots, N \quad (21)$$

$$X(j) = u(x_{j-1}) \quad j = 1, 2, \dots, N \quad (22)$$

## 1.7 DFT differentiation

Fourier interpolation:

$$I_N f(x) = \sum_{k=-N/2}^{N/2} \frac{\tilde{f}_k}{\tilde{c}_k} e^{ikx} \quad (23)$$

Derivative approximation:

$$f^{(m)}(x) \approx (I_N f)^{(m)}(x) = \sum_{k=-N/2}^{N/2} \frac{(ik)^m \tilde{f}_k}{\tilde{c}_k} e^{ikx} \quad (24)$$

Derivatives at the Fourier nodes:

$$(I_N f)^{(m)}(x_j) = \begin{cases} \sum_{k=-N/2}^{N/2-1} (ik)^m \tilde{f}_k e^{ikx_j}, & m \text{ even} \\ \sum_{k=-N/2+1}^{N/2-1} (ik)^m \tilde{f}_k e^{ikx_j}, & m \text{ odd} \end{cases} \quad (25)$$

## 1.8 Real DFT

$N$  even,  $\{f_j : j = 0, 1, \dots, N-1\}$  real

David's version:

$$\begin{aligned} f_j &= \frac{a_0}{2} + \sum_{k=1}^{N/2-1} [a_k \cos(kx_j) + b_k \sin(kx_j)] + \frac{(-1)^j a_{N/2}}{2} \\ &= \frac{a_0}{2} + \sum_{k=1}^{N/2-1} [a_k \cos(k \frac{2\pi j}{N}) + b_k \sin(k \frac{2\pi j}{N})] + \frac{(-1)^j a_{N/2}}{2}, \quad j = 0, 1, \dots, N-1 \end{aligned} \quad (26)$$

This is actually the inverse real DFT. Real DFT refers to formulas of  $a_k$  and  $b_k$ . We don't need these formulas since we can use DFT to get  $a_k$  and  $b_k$ .

DFT:

$$\begin{aligned} f_j &= \sum_{k=0}^{N-1} \tilde{f}_k e^{ikx_j} \\ &= \tilde{f}_0 + 2 \sum_{k=1}^{N/2-1} (\Re(\tilde{f}_k) \cos(kx_j) - \Im(\tilde{f}_k) \sin(kx_j)) + (-1)^j \tilde{f}_{N/2} \end{aligned} \quad (27)$$

Relation:

$$a_k = 2\Re(\tilde{f}_k), \quad b_k = -2\Im(\tilde{f}_k), \quad k = 0, 1, \dots, N/2 \quad (28)$$

In fact,  $b_0 = b_{N/2} = 0$  since  $\tilde{f}_0, \tilde{f}_{N/2} \in \mathbb{R}$ . To do the inverse real DFT, we again use DFT. We just need to construct:

$$\tilde{f}_k = \frac{a_k}{2} - i \frac{b_k}{2}, \quad k = 0, 1, \dots, \frac{N}{2}, \quad (29)$$

$$\tilde{f}_k = F_{N-k}^*, \quad k = \frac{N}{2} + 1, \dots, N-1 \quad (30)$$

## 2 Discrete Cosine Transform (DCT)

Gauss-Lobatto points underlie the DCT and the Chebyshev transform:

$$x_j = \cos \frac{j\pi}{N}, \quad j = 0, 1, \dots, N \quad (31)$$

Input  $\{f_j : j = 0, 1, \dots, N\}$

$$f_j = \sum_{k=0}^N \frac{a_k}{\bar{c}_k} \cos \left( k \frac{\pi j}{N} \right) = \sum_{k=0}^N \frac{a_k}{\bar{c}_k} \cos(kx_j), \quad (32)$$

$$a_k = \frac{2}{N} \sum_{j=0}^N \frac{f_j}{\bar{c}_j} \cos \left( k \frac{\pi j}{N} \right) = \frac{2}{N} \sum_{j=0}^N \frac{f_j}{\bar{c}_j} \cos(kx_j), \quad (33)$$

$$\bar{c}_k = \begin{cases} 2, & k = 0, N \\ 1, & k = 1, 2, \dots, N-1 \end{cases} \quad (34)$$

To reduce computation cost, assume  $N$  is even and let

$$e_j = \frac{1}{2}(f_j + f_{N-j}) - (f_j - f_{N-j}) \sin \frac{j\pi}{N}, \quad j = 0, 1, \dots, N-1. \quad (35)$$

Plugging the inverse DCT for  $f_j$  gives

$$e_j = \frac{a_0}{2} + \sum_{k=1}^{N/2-1} [\cos(2k \frac{\pi}{N} j) a_{2k} + \sin(2k \frac{\pi}{N} j) (a_{2k+1} - a_{2k-1})] + \frac{a_N}{2} (-1)^j. \quad (36)$$

Real DFT of  $\{e_j\}$ :

$$e_j = \frac{\bar{a}_0}{2} + \sum_{k=1}^{N/2-1} [\cos(2k \frac{\pi}{N} j) \bar{a}_k + \sin(2k \frac{\pi}{N} j) \bar{b}_k] + \frac{a_{N/2}}{2} (-1)^j. \quad (37)$$

By comparison

$$a_0 = \bar{a}_0, \quad a_N = \bar{a}_{N/2} \quad (38)$$

$$a_{2k} = \bar{a}_k, \quad (39)$$

$$a_{2k+1} - a_{2k-1} = \bar{b}_k \quad k = 1, \dots, N/2 - 1 \quad (40)$$

$$(41)$$

$a_1$  is calculated directly:

$$a_1 = \frac{2}{N} \sum_{j=0}^N \frac{f_j}{\bar{c}_j} \cos \left( \frac{\pi j}{N} \right). \quad (42)$$

The DCT and its inverse follow the same pattern:

$$DCT : \quad output_k = \frac{2}{N} \sum_{j=0}^N \frac{input_j}{\bar{c}_j} \cos \left( \frac{\pi k j}{N} \right), \quad (43)$$

$$invDCT : \quad output_k = \sum_{j=0}^N \frac{input_j}{\bar{c}_j} \cos \left( \frac{\pi k j}{N} \right), \quad (44)$$

where in the second equation we have swapped  $j$  and  $k$  in the original formula. Now we can see that both relation are the same up to a constant factor  $2/N$ . Therefore, once we get a subroutine to do DCT, we can use the same program and multiply the result by  $N/2$  to get the inverse DCT.

In scipy, the type-1 DCT is

$$\begin{aligned} a_k &= 2 \sum_{j=0}^N \frac{f_j}{\bar{c}_j} \cos \left( \frac{\pi k j}{N} \right) \\ &= f_0 + 2 \sum_{j=0}^{N-1} f_j \cos \left( \frac{\pi k j}{N} \right) + (-1)^k f_N, \end{aligned} \quad (45)$$

which is  $N$  times our DCT.

### 3 Chebyshev Transformation (ChebT)

#### 3.1 The transformations

Target function:

$$f(x), x \in [-1, 1] \quad (46)$$

Gauss-Lobatto points:

$$x_j = \cos \frac{j\pi}{N}, \quad j = 0, 1, \dots, N \quad (47)$$

Chebyshev interpolation:

$$F(x) = \sum_{k=0}^N \tilde{f}_k T_k(x), \quad (48)$$

$$F(x_j) = f(x_j), \quad j = 0, 1, \dots, N \quad (49)$$

$$f_j = f(x_j) = F(x_j) = \sum_{k=0}^N \tilde{f}_k T_k(x_j) = \sum_{k=0}^N \tilde{f}_k \cos(k \frac{j\pi}{N}). \quad (50)$$

Comparing with DCT:

$$f_j = \sum_{k=0}^N \frac{a_k}{\bar{c}_k} \cos\left(k \frac{\pi j}{N}\right) \quad (51)$$

Thus,

$$\tilde{f}_k = \frac{a_k}{\bar{c}_k}, \quad k = 0, 1, \dots, N \quad (52)$$

Therefore, to get the Chebyshev coefficients  $\tilde{f}_k$ , we only need to do DCT, and divide the first and the last coefficients by 2.

To do the inverse Chebyshev transform, again we compare it with the inverse DCT:

$$f_j = \sum_{k=0}^N \tilde{f}_k T_k(x_j) = \sum_{k=0}^N \tilde{f}_k \cos(k \frac{j\pi}{N}), \quad (53)$$

$$f_j = \sum_{k=0}^N \frac{a_k}{\bar{c}_k} \cos\left(k \frac{\pi j}{N}\right). \quad (54)$$

Thus, we multiply  $\tilde{f}_0$  and  $\tilde{f}_N$  by 2, and then use the inverse DCT.

#### 3.2 Derivatives

$$f^{(1)}(x) \approx \frac{d}{dx} \sum_{k=0}^N \tilde{f}_k T_k(x) = \sum_{k=0}^N \tilde{f}_k^{(1)} T_k(x). \quad (55)$$

Since the interpolating polynomial's degree is reduced by 1 by differentiation, we have  $\tilde{f}_N^{(1)} = 0$ . Since no terms for higher order polynomials exist, we have  $\tilde{f}_{N+1}^{(1)} = 0$ .  $\tilde{f}_k^{(1)}$  is calculated recursively, from  $\tilde{f}_{N-1}^{(1)} = 0$  to  $\tilde{f}_0^{(1)} = 0$ :

$$\tilde{f}_k^{(1)} = \frac{1}{c_k} (\tilde{f}_{k+2}^{(1)} + 2(k+1)\tilde{f}_{k+1}^{(1)}). \quad (56)$$

Once we get  $\{\tilde{f}_k^{(1)}\}$ , we use the backward ChebyT to find approximation to  $\{f^{(1)}(x_j) : j = 0, 1, \dots, N\}$

#### 3.3 Derivatives, a method of Trefethen

$$f(x) : \text{target function} \quad (57)$$

$$x_j = \cos \frac{\pi}{N} j, \quad j = 0, 1, \dots, N \quad (58)$$

$$f_j = f(x_j), \quad (59)$$

$$\text{Goal: Find } \frac{df}{dx}(x_j) \quad (60)$$

Change of variable:

$$x = \cos(\theta), \quad (61)$$

$$\theta_j = \frac{\pi}{N}j, \quad j = 0, 1, \dots, N \quad (62)$$

$$f(x) \rightarrow f(\theta) \quad (63)$$

$\{\theta_j : j = 0, 1, \dots, N\}$  are part of the Fourier nodes, so we make an extension:

$$\theta_j = \frac{\pi}{N}j, \quad j = 0, 1, \dots, 2N-1. \quad (64)$$

Then we make an even extension of  $\{f_j : j = 0, 1, \dots, N\}$ :

$$f_j = f_{2N-j}, \quad (65)$$

$$f_j : j = 0, 1, \dots, 2N-1. \quad (66)$$

Fourier interpolation of  $f(\theta)$ :

$$I_{2N}f(\theta) = \sum_{k=-N}^N \frac{\tilde{f}_k}{\bar{c}_k} e^{ik\theta_j}, \quad (67)$$

where

$$\bar{c}_k = \begin{cases} 2, & k = \pm N \\ 1, & \text{otherwise} \end{cases} \quad (68)$$

Derivatives at Fourier nodes:

$$I_{2N}f^{(1)}(\theta_j) = \sum_{k=-N+1}^{N-1} ik\tilde{f}_k e^{ik\theta_j}. \quad (69)$$

Derivatives wrt  $x$ :

$$\frac{df}{dx}(x_j) = \frac{\frac{df}{d\theta}(\theta_j)}{\frac{dx}{d\theta}\theta_j} \approx \frac{I_{2N}f^{(1)}(\theta_j)}{-\sin(\theta_j)}, \quad j = 1, \dots, N-1 \quad (70)$$

This formula does not apply to  $\theta_0$  and  $\theta_N$  since the denominator is zero at these nodes. The derivatives at these nodes require special treatment.

$$f_j \in \mathbb{R}, f_j = f_{2N-j} \Rightarrow \tilde{f}_k \in \mathbb{R}, \tilde{f}_k = \tilde{f}_{-k}. \quad (71)$$

This implies

$$I_{2N}f(\theta) = \tilde{f}_0 + \sum_{k=1}^{N-1} 2\tilde{f}_k \cos(k\theta) + \tilde{f}_N \cos(N\theta) = \sum_{k=0}^N a_k \cos(k\theta) = \sum_{k=0}^N a_k T_k(x) \quad (72)$$

$$a_0 = \tilde{f}_0, a_N = \tilde{f}_N, a_k = 2\tilde{f}_k, k = 1, \dots, N-1 \quad (73)$$

This implies that the Fourier interpolation is essentially the same as a Chebyshev interpolation. They give the same approximation of the derivatives. Finally, we have special treatment at  $\theta_0$  and  $\theta_N$ :

$$\frac{df}{dx}(x_0) = \lim_{x \rightarrow x_0} \frac{df}{dx}(x) \approx \lim_{\theta \rightarrow \theta_0} \frac{\frac{d \sum_{k=0}^N a_k \cos(k\theta)}{d\theta}}{-\sin(\theta)} = \sum_{k=0}^N a_k k^2, \quad (74)$$

$$\frac{df}{dx}(x_N) = -\sum_{k=0}^N a_k (-1)^k k^2 \quad (75)$$

## 4 Differentiation Matrix

### 4.1 Fourier Differentiation Matrix

$$x_j = \frac{2\pi}{N}j, \quad j = 0, 1, \dots, N-1, \quad (76)$$

$$f_j = f(x_j), \quad (77)$$

$$I_N f(x) = \sum_{k=-N/2}^{N/2} \frac{\tilde{f}_k}{\tilde{c}_k} e^{ikx}, \quad (78)$$

$$\tilde{f}_k = \frac{1}{N} \sum_{j=0}^{N-1} f_j e^{-ikx_j}. \quad (79)$$

Lagrange Form:

$$I_N f(x) = \sum_{j=0}^{N-1} f_j h_j(x), \quad (80)$$

$$h_j(x) = \frac{1}{N} \sum_{k=-N/2}^{N/2} \frac{1}{\tilde{c}_k} e^{ik(x-x_j)}. \quad (81)$$

Real form of  $h_j(x)$ :

$$h_j(x) = \frac{\sin(\frac{N}{2}(x-x_j))}{N \tan(\frac{1}{2}(x-x_j))}. \quad (82)$$

When the demonimator is 0 or  $\infty$ , the value of the form is understood in the limit sense.

$$D_{nj} = h'_j(x_n) = \begin{cases} 0, & j = n \\ \frac{1}{2}(-1)^{n-j} \cot(\frac{(n-j)\pi}{N}), & j \neq n \end{cases} \quad (83)$$

Negative Sum Trick:

$$\sum_{j=0}^{N-1} D_{nj} = 0, \quad (84)$$

$$\Rightarrow D_{nn} = - \sum_{j=0, j \neq n}^{N-1} D_{nj} \quad (85)$$

### 4.2 Differentiation of Lagrange Form Polynomials

The target function and the interpolation nodes:

$$f(x), \quad (86)$$

$$x_j, j = 0, 1, \dots, N \quad (87)$$

$$f_j = f(x_j) \quad (88)$$

The Lagrange form interpolating polynomial:

$$p_N(x) = \sum_{j=0}^N f_j l_j(x), \quad (89)$$

$$l_j = \frac{(x-x_0) \cdots (x-x_{j-1})(x-x_{j+1}) \cdots (x-x_N)}{(x_j-x_0) \cdots (x_j-x_{j-1})(x_j-x_{j+1}) \cdots (x_j-x_N)} = w_j \prod_{m=0, m \neq j}^N (x-x_m), \quad (90)$$

$$w_j = \frac{1}{\prod_{m=0, m \neq j}^N (x_j-x_m)} \quad (91)$$

Derivatives:

$$p'_N(x) = \sum_{j=0}^N f_j l'_j(x), \quad (92)$$

$$l'_j(x) = w_j \sum_{\substack{k=0 \\ k \neq j}}^N \prod_{\substack{m=0 \\ m \neq j \\ m \neq k}}^N (x - x_m), \quad (93)$$

$$l'_j(x_i) = w_j \prod_{\substack{m=0 \\ m \neq j \\ m \neq i}}^N (x_i - x_m) = \frac{w_j}{w_i} \frac{1}{x_i - x_j}, \quad i \neq j, \quad (94)$$

$$l'_j(x_j) = w_j \sum_{\substack{k=0 \\ k \neq j}}^N \prod_{\substack{m=0 \\ m \neq j \\ m \neq k}}^N (x_j - x_m) = \sum_{\substack{k=0 \\ k \neq j}}^N \frac{1}{x_j - x_m}, \quad (95)$$

$$p'_N(x_i) = \sum_{\substack{j=0 \\ j \neq i}}^N \left( f_j + \frac{f_j w_j}{w_i} \right) \frac{1}{x_i - x_j}. \quad (96)$$

Trick:

$$f(x) = c \Rightarrow f_j = c \Rightarrow \sum_{j=0}^N l_j(x) = 1 \Rightarrow \sum_{j=0}^N l'_j(x) = 0, \quad (97)$$

$$\Rightarrow \sum_{j=0}^N l'_j(x_i) = 0 \Rightarrow l'_i(x_i) = - \sum_{\substack{j=0 \\ j \neq i}}^N l'_j(x_i), \quad (98)$$

$$p'_N(x_i) = \sum_{\substack{j=0 \\ j \neq i}}^N f_j l'_j(x_i) + f_i l'_i(x_i) \quad (99)$$

$$= \sum_{\substack{j=0 \\ j \neq i}}^N f_j l'_j(x_i) - f_i \sum_{\substack{j=0 \\ j \neq i}}^N l'_j(x_i) \quad (100)$$

$$= \sum_{\substack{j=0 \\ j \neq i}}^N (f_j - f_i) l'_j(x_i) \quad (101)$$

$$= \sum_{\substack{j=0 \\ j \neq i}}^N (f_j - f_i) \frac{w_j}{w_i} \frac{1}{x_i - x_j} \quad (102)$$

$$= - \frac{1}{w_i} \sum_{\substack{j=0 \\ j \neq i}}^N w_j \frac{f_i - f_j}{x_i - x_j}. \quad (103)$$

Derivative at  $x$  that is not a node:

$$p_N(x) = \frac{\sum_{j=0}^N f_j \frac{w_j}{x - x_j}}{\sum_{j=0}^N \frac{w_j}{x - x_j}}, \quad (104)$$

$$p'_N(x) = \frac{\sum_{j=0}^N \frac{[p_N(x) - f_j] w_j}{(x - x_j)^2}}{\sum_{j=0}^N \frac{w_j}{x - x_j}} \quad (105)$$

### 4.3 General Differentiation Matrix

$$f'(x_i) \approx (I_N f(x_i))' = \sum_{j=0}^N f_j l_j'(x_i) = \sum_{j=0}^N f_j D_{ij}, \quad (106)$$

$$D_{ij} = l_j'(x_i) = \frac{w_j}{w_i} \frac{1}{x_i - x_j}, \quad i \neq j \quad (107)$$

$$l_i'(x_i) = - \sum_{\substack{j=0 \\ j \neq i}}^N l_j'(x_i) \Rightarrow D_{ii} = - \sum_{\substack{j=0 \\ j \neq i}}^N D_{ij} \quad (108)$$

For Chebyshev nodes:

$$x_j = \cos\left(\frac{\pi}{N}j\right), \quad j = 0, 1, \dots, N \quad (109)$$

$$D_{ij} = \frac{\bar{c}_i}{\bar{c}_j} \frac{(-1)^{i+j}}{x_i - x_j}, \quad i \neq j \quad (110)$$



## 5 The Fourier Collocation Method

### 5.1 Outline

Problem:

$$u_t + u_x = \nu u_{xx}, \quad 0 < x < 2\pi, t > 0 \quad (111)$$

$$u(x, 0) = u_0(x), \quad 0 \leq x \leq 2\pi, \quad (112)$$

$$u(0, t) = u(2\pi, t), \quad t \geq 0. \quad (113)$$

Interpolation:

$$u(x, t) \approx p(x, t) = \sum_{n=0}^{N-1} u_n(t) h_n(x), \quad (\text{Fourier interpolation in Lagrange form}) \quad (114)$$

$$h_n(x) = \frac{1}{N} \sum_{k=-N/2}^{N/2} \frac{e^{ik(x-x_j)}}{\bar{c}_k}, \quad (115)$$

$$x_n = \frac{2\pi}{N} n, \quad n = 0, 1, \dots, N-1, \quad (116)$$

$$\bar{c}_k = \begin{cases} 2, & k = \pm N/2, \\ 1, & k = -N/2 + 1, \dots, k = N/2 - 1 \end{cases} \quad (117)$$

Collocation:

$$p_t + p_x - \nu p_{xx}|_{x=x_j} = 0. \quad (118)$$

About  $p_t(x_j)$ :

$$p_t(x) = \sum_{n=0}^{N-1} \dot{u}_n(t) h_n(x), \quad (119)$$

$$h_n(x_j) = \delta_{nj}, \quad (120)$$

$$p_t(x_j) = \dot{u}_n(t), \quad (121)$$

$p_x(x_j)$  given by the matrix multiplication

$$p_x(x_j) = \sum_{n=0}^{N-1} D_{jn} u_n. \quad (122)$$

$p_{xx}(x_j)$  given by the matrix multiplication:

$$p_{xx}(x_j) = \sum_{n=0}^{N-1} D_{jn}^{(2)} u_n, \quad (123)$$

$$[p_{xx}] = D^{(2)}[u_n] \approx D^2[u_n] \quad (\text{Matrix form}) \quad (124)$$

The resulting ODE system:

$$[\dot{u}_n(t)] = \nu D^2[u_n] - D[u_n] = D(\nu D[u_n] - [u_n]), \quad (125)$$

$$u_n(0) = u_0(x_n), \quad n = 0, 1, \dots, N-1 \quad (126)$$

$[p_{xx}]$  and  $[p_x]$  can also be calculated by DFT.

### 5.2 An ODE solver

An ODE system:

$$\dot{u} = F(u, t), \quad (127)$$

$$\Delta t, \quad (128)$$

$$t_n = n\Delta t, \quad (129)$$

$$u^n \approx u(t_n) \quad (130)$$

A 3rd-order Runge-Kutta solver:

Initializing:

$$u^{(0)} = u^n, \quad (131)$$

$$g^{(0)} = 0, \quad (132)$$

$$(133)$$

First update:

$$g^{(1)} = g^{(0)} + F(u^{(0)}, t_n), \quad (134)$$

$$u^{(1)} = u^{(0)} + \frac{1}{3}\Delta t g^{(1)}, \quad (135)$$

Second update:

$$g^{(2)} = -\frac{5}{9}g^{(1)} + F(u^{(1)}, t_n + \frac{1}{3}\Delta t), \quad (136)$$

$$u^{(2)} = u^{(1)} + \frac{15}{16}\Delta t g^{(2)}, \quad (137)$$

Third update:

$$g^{(3)} = -\frac{153}{128}g^{(2)} + F(u^{(2)}, t_n + \frac{3}{4}\Delta t), \quad (138)$$

$$u^{(3)} = u^{(2)} + \frac{8}{15}\Delta t g^{(3)}, \quad (139)$$

General form:

$$g^{(i)} = cg[i]g^{(i-1)} + F(u^{(i-1)}, t_n + ct[i]\Delta t), \quad (140)$$

$$u^{(i)} = u^{(i-1)} + cu[i]\Delta t g^{(i)}, \quad (141)$$

Implementation:

$$g \leftarrow cg[i]g + F(u, t_n + ct[i]\Delta t), \quad (142)$$

$$u \leftarrow u + cu[i]\Delta t g \quad (143)$$

$i$	$cg$	$ct$	$cu$
1	0	0	1/3
2	-5/9	1/3	15/16
3	-153/128	3/4	8/15

(144)

## 6 The Fourier Galerkin Method

### 6.1 Outline

Problem:

$$u_t + u_x = \nu u_{xx}, \quad 0 < x < 2\pi, t > 0 \quad (145)$$

$$u(x, 0) = u_0(x), \quad 0 \leq x \leq 2\pi, \quad (146)$$

$$u(0, t) = u(2\pi, t), \quad t \geq 0. \quad (147)$$

Weak form:

$$\int_0^{2\pi} (u_t + u_x - \nu u_{xx}) \phi^* dx = 0, \quad (148)$$

$$\Rightarrow \int_0^{2\pi} u_t \phi^* dx + \int_0^{2\pi} u_x \phi^* dx = \nu u_x \phi^*|_0^{2\pi} - \int_0^{2\pi} u_x \phi_x^* dx \quad (149)$$

The second line is the weak form since it only contains the first-order derivatives. The weak form is obtained by integration by parts.

Galerkin:

$$\text{Fourier interpolation: } u(x, t) = \sum_{n=-N/2}^{N/2} \tilde{u}_n(t) e^{inx}, \quad (150)$$

$$\text{Test functions identical to the basis functions: } \phi = e^{inx}, \quad (151)$$

$$\frac{d\tilde{u}_n(t)}{dt} + in\tilde{u}_n(t) = -\nu n^2 \tilde{u}_n(t), \quad n = -N/2, \dots, N/2. \quad (152)$$

IC:

$$\sum_{n=-N/2}^{N/2} \tilde{u}_n(0) e^{inx} \approx u_0(x) \approx P_N u_0(x) = \sum_{n=-N/2}^{N/2} \hat{u}_{0,n} e^{inx}, \quad (153)$$

$$\Rightarrow \tilde{u}_n(0) = \hat{u}_{0,n} = \frac{1}{2\pi} \int_0^{2\pi} u_0(x) e^{-inx} dx \quad (154)$$

Note that the initial coefficients are set to be the coefficients of the truncated series, not the coefficients of the Fourier interpolation of  $u_0(x)$ . The two sets of coefficients are not the same.