



Coláiste na Tríonóide, Baile Átha Cliath  
Trinity College Dublin

Ollscoil Átha Cliath | The University of Dublin

Faculty of Engineering, Mathematics and Science  
School of Computer Science and Statistics

ALGORITHMS AND DATA  
STRUCTURES II  
2023/24

Semester 2 2024

ALGORITHMS AND DATA STRUCTURES II

26 April 2024

SC

14.00 – 16.00

Dr Anthony Ventresque

**Instructions to Candidates:**

Answer **ALL** of the five questions. All questions carry equal marks. The paper is marked out of 100. No books or notes are permitted. No calculator permitted.

Answer all the questions **in the answer book** (not the exam paper).

All the multiple choice questions require **only 1 answer** – the question will receive a 0 if multiple answers are chosen.

**Instructions for invigilators:**

No books or notes are permitted. No calculator permitted.

## Question 1

(20 Marks)

- a) What problem does Dijkstra's algorithm solve? **(1 Mark)**
- Finding the minimum spanning tree in a graph.
  - Finding the shortest path from a single source to all other vertices in a weighted graph.
  - Sorting a list of numbers.
  - Finding the maximum flow in a network.
- b) Kruskal's algorithm builds the minimum spanning tree by: **(1 Mark)**
- Selecting edges in decreasing weight order without forming a cycle.
  - Selecting edges in increasing weight order without forming a cycle.
  - Starting from the highest-degree vertex.
  - Starting from the lowest-degree vertex.
- c) Prim's algorithm starts with: **(1 Mark)**
- An empty graph and adds edges.
  - A single vertex and adds edges and vertices until the tree spans all vertices in the graph.
  - The shortest edge in the graph.
  - The longest edge in the graph.
- d) Prim's and Kruskal's algorithms always yield the same minimum spanning tree for a given graph. **(1 Mark)**
- True
  - False
- e) Assume that **Vertex** is the vertex type for a connected, directed, acyclic graph in which each vertex has a maximum out-degree of 3 – and assume there exists a Java method **find** that looks for a particular value **x** in a graph starting at **Vertex v**
- ```

boolean find(Vertex v, int x) {
    for (Vertex s : v.successors()) {
        if (s.getLabel() == x || find(s, x)) {
            return true;
        }
    }
    return false;
}

```
- Let **N** be the number of edges in the graph. For **Vertex w**, estimate the worst-case running time of **find(w, 42)**; as a function of **N**. **(4 Marks)**

- f) Draw the graph corresponding to the following adjacency matrix (vertex labels A–D for the rows and columns are above and to the left): **(2 Marks)**

|   | A | B | C | D |
|---|---|---|---|---|
| A | 0 | 1 | 0 | 0 |
| B | 0 | 1 | 0 | 1 |
| C | 1 | 0 | 0 | 1 |
| D | 0 | 0 | 0 | 0 |

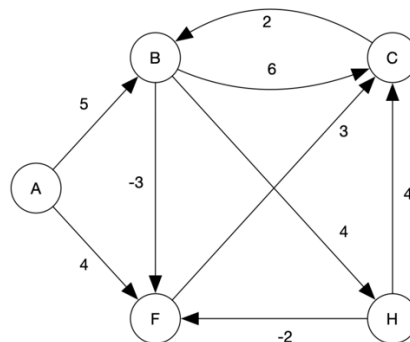
- g) Give the adjacency-list representation of the above graph (question f). **(2 Marks)**
- h) Using an adjacency-list representation of a graph, what is the running time in the worst case to check for the existence of an edge between two vertices? **(3 Marks)**
- i) What is the running time of the same operation using an adjacency matrix, in the worst case? **(2 Marks)**
- j) Why does Dijkstra's algorithm not work for graphs with negative edges? **(3 Marks)**

## Question 2

CSU22012-2  
(20 Marks)

- a) What is the defining characteristic of a greedy best-first search algorithm? **(1 Mark)**
- a. It always selects the path that appears best at that moment.
  - b. It evaluates paths based on their historical cost from the start.
  - c. It uses a random selection strategy to determine the next step.
  - d. It considers the cost to the goal and the cost from the start equally.
- b) What is the primary difference between the greedy best-first search and A\* algorithms? **(1 Mark)**
- a. A\* is a type of greedy best-first search.
  - b. Greedy best-first search considers the cost from the start node to the current node.
  - c. A\* considers both the cost from the start to the current node and an estimate of the cost from the current node to the goal.
  - d. Greedy best-first search is optimal, whereas A\* is not.
- c) Which of the following is true about the heuristic function used in A\* search? **(1 Mark)**
- a. It should overestimate the cost to the nearest goal.
  - b. It should underestimate or exactly estimate the cost to the nearest goal.
  - c. It has no impact on the performance of the algorithm.
  - d. It only considers the cost from the start node to the current node.
- d) Describe a situation where the greedy best-first search might fail to find the shortest path. **(3 Marks)**
- e) What problem does the Bellman-Ford algorithm solve? **(1 Mark)**
- a. Finding the minimum spanning tree in a graph
  - b. Searching for a target value in a sorted array
  - c. Finding the shortest paths from a single source to all other vertices in a weighted graph
  - d. Sorting a list of numbers in ascending order
- f) Which of the following is a feature of the Bellman-Ford algorithm? **(1 Mark)**
- a. It cannot handle graphs with negative weight edges.
  - b. It has a faster runtime than Dijkstra's algorithm for all types of graphs.
  - c. It can detect negative weight cycles in a graph.
  - d. It requires a graph to be acyclic.
- g) What is the time complexity of the Bellman-Ford algorithm? **(1 Mark)**
- a.  $O(V + E)$
  - b.  $O(V^2)$
  - c.  $O(VE)$
  - d.  $O(E \log V)$

- h) What is the primary reason the Bellman-Ford algorithm can handle negative weight edges? **(1 Mark)**
- It calculates distances only once.
  - It uses a greedy strategy to pick the next vertex to process.
  - It relaxes edges in a specific order based on their weights.
  - It relaxes all edges a certain number of times equal to the number of vertices minus one.
- i) Under what condition does the Bellman-Ford algorithm report that no solution exists? **(1 Mark)**
- When it finds an edge with a positive weight
  - When it detects a negative weight cycle
  - When there are disconnected components in the graph
  - When the graph is directed
- j) What does the relaxation process in the Bellman-Ford algorithm involve? **(1 Mark)**
- Removing all negative weight edges from the graph
  - Updating the distance to a vertex if a shorter path is found
  - Increasing the weight of all edges to remove negative cycles
  - Swapping vertices until all distances are minimized
- k) Fill-in the following matrix with the different values at different steps of the Bellman-Ford algorithm: **(4 Marks)**



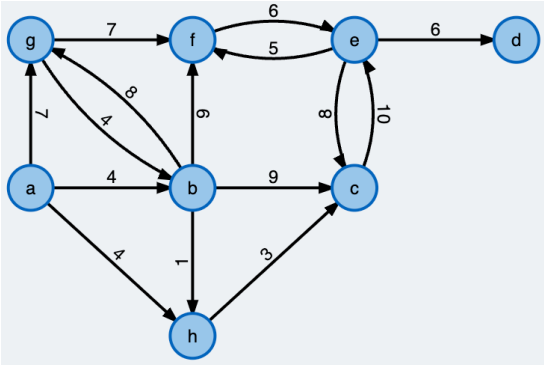
|     | S | A        | B        | C        | D        | E        |
|-----|---|----------|----------|----------|----------|----------|
| 0   | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ |
| 1   |   |          |          |          |          |          |
| 2   |   |          |          |          |          |          |
| ... |   |          |          |          |          |          |

- l) How does the Bellman-Ford algorithm ensure that it relaxes all edges in the correct order? **(4 Marks)**

**Question 3**

- a) What problem does the Floyd-Warshall algorithm solve? **(1 Mark)**
- a. Finding the minimum spanning tree
  - b. Finding the shortest path between all pairs of vertices
  - c. Searching for a target value in a binary tree
  - d. Detecting cycles in a directed graph
- b) Which of the following best describes the Floyd-Warshall algorithm? **(1 Mark)**
- a. A greedy algorithm
  - b. A divide and conquer algorithm
  - c. A dynamic programming algorithm
  - d. A backtracking algorithm
- c) What is the time complexity of the Floyd-Warshall algorithm? **(1 Mark)**
- a.  $O(V^2)$
  - b.  $O(V^2 \log V)$
  - c.  $O(V^3)$
  - d.  $O(VE)$
- d) What initial values are used in the Floyd-Warshall algorithm for the distance matrix? **(1 Mark)**
- a. 0 for all pairs
  - b. Infinity for all pairs except the diagonals, which are 0
  - c. The weights of the edges for direct connections, and infinity otherwise
  - d. 1 for connected vertices and 0 for non-connected vertices
- e) Which of the following is a characteristic of the Floyd-Warshall algorithm? **(1 Mark)**
- a. It updates the shortest paths in a greedy manner.
  - b. It recalculates paths to include each vertex as an intermediate vertex.
  - c. It uses depth-first search to find the shortest path.
  - d. It only works with directed acyclic graphs.
- f) Explain how the Floyd-Warshall algorithm updates the distance between two vertices (give the formula). **(3 Marks)**

Given the following Graph, answer the next 3 questions:



g) Initialise the following matrix (step 0 of Floyd-Warshall) (4 Marks)

|   | A | B | C | D | E | F | G | H |
|---|---|---|---|---|---|---|---|---|
| A |   |   |   |   |   |   |   |   |
| B |   |   |   |   |   |   |   |   |
| C |   |   |   |   |   |   |   |   |
| D |   |   |   |   |   |   |   |   |
| E |   |   |   |   |   |   |   |   |
| F |   |   |   |   |   |   |   |   |
| G |   |   |   |   |   |   |   |   |
| H |   |   |   |   |   |   |   |   |

h) Give the value of the matrix at step 2 of Floyd-Warshall (4 Marks)

i) Give the value of the matrix at the last step of Floyd-Warshall (4 Marks)

**Question 4**

- a) What does a Trie primarily store? **(1 Mark)**
- a. Numbers
  - b. Strings
  - c. Graphs
  - d. Arrays
- b) Which of the following best describes a key characteristic of a Trie? **(1 Mark)**
- a. Each node represents the entire key.
  - b. Nodes store the common prefix of keys.
  - c. Each node represents a single character of a string.
  - d. Nodes are connected in a linear fashion.
- c) Tries are most commonly used for which application? **(1 Mark)**
- a. Balancing binary trees
  - b. Storing relational database entries
  - c. Performing arithmetic operations on large numbers
  - d. Implementing dictionaries for spell-checking
- d) What is the space complexity of creating a Trie that stores N keys, each of length M? **(1 Mark)**
- a.  $O(N)$
  - b.  $O(M)$
  - c.  $O(N + M)$
  - d.  $O(N * M)$
- e) Assuming all strings are of length N, what is the time complexity for searching and inserting in a Trie? **(1 Mark)**
- a.  $O(\log N)$
  - b.  $O(N)$
  - c.  $O(N \log N)$
  - d.  $O(1)$
- f) Why are Tries efficient for prefix searching? **(1 Mark)**
- a. Because they can store keys with common prefixes in shared nodes
  - b. Because they automatically sort the keys alphabetically
  - c. Because they use hash tables for indexing prefixes
  - d. Because they reduce the search space by half at each step
- g) What does each node in a Trie typically contain? (Assuming an alphabet of size A) **(1 Mark)**
- a. A list of A pointers, each to a child node
  - b. A single character from the alphabet
  - c. The complete string stored up to that point
  - d. A numeric value representing the position of the node in the trie



h) Construct a Trie with the following key-value pairs.

| Key  | Value |
|------|-------|
| cat  | 1     |
| cap  | 2     |
| can  | 3     |
| bat  | 4     |
| ball | 5     |

i) What is a Ternary Search Trie (TST)? (1 Mark)

- a. A data structure that stores characters at tree nodes with each node having three children.
- b. A type of binary search tree optimized for searching numeric data.
- c. A trie where each node can have up to three parents.
- d. A data structure where each node has two or three children, randomly assigned.

j) In a TST, what does the middle child of a node represent? (1 Mark)

- a. The next character in a string if the current character matches.
- b. A lesser value in the character set.
- c. A greater value in the character set.
- d. The end of a string.

k) Construct a TST with the following key-value pairs. (4 Marks)

| Key      | Value |
|----------|-------|
| she      | 1     |
| sells    | 2     |
| sea      | 3     |
| shells   | 4     |
| by       | 5     |
| the      | 6     |
| seashore | 7     |

l) How does searching in a TST differ from searching in a traditional Trie, and what benefits does this bring? Detail how search is performed with each data structure. (3 Marks)

**Question 5**

- a) What type of sorting algorithm is Radix Sort? **(1 Mark)**
- a. Comparison-based
  - b. Divide and conquer
  - c. Non-comparison based
  - d. Recursive
- b) What is a critical step in Radix Sort? **(1 Mark)**
- a. Choosing a suitable pivot
  - b. Splitting the array into two halves
  - c. Distributing elements into buckets based on their digits
  - d. Swapping elements to their correct position
- c) How does Radix Sort achieve sorting of integers? **(1 Mark)**
- a. By comparing pairs of elements
  - b. By creating a binary search tree
  - c. By distributing elements into buckets based on their radix
  - d. By partitioning the dataset into smaller subsets
- d) What is the time complexity of Radix Sort in the best case? **(1 Mark)**
- a.  $O(n \log n)$
  - b.  $O(n)$
  - c.  $O(n+k)$
  - d.  $O(\log n)$
- e) Most Significant Digit (MSD) Radix Sort is particularly effective for sorting what type of data? **(1 Mark)**
- a. Integers
  - b. Floating-point numbers
  - c. Strings
  - d. All of the above
- f) Which of the following best describes the LSD Radix Sort algorithm? **(1 Mark)**
- a. Starts sorting from the most significant digit
  - b. Starts sorting from the least significant digit
  - c. Uses a pivot element to sort
  - d. Divides the array into two halves and sorts each half
- g) What role does the choice of radix (base) play in the efficiency of Radix Sort? **(3 Marks)**
- h) Describe a scenario where Radix Sort would be preferred over a comparison-based sorting algorithm. **(3 Marks)**

- i) Provide the trace of sorting the array of strings given in the table below using LSD sort, providing an equivalent table for each of the 3 passes of the algorithm.

**(4 Marks)**

|   |   |   |
|---|---|---|
| B | A | T |
| C | A | R |
| C | A | T |
| A | R | C |
| T | A | B |
| R | A | T |
| B | A | R |

- j) Provide the trace of sorting the array of strings given in the table below using MSD sort, providing an equivalent table for each of the 3 passes of the algorithm.

**(4 Marks)**

|   |   |   |
|---|---|---|
| B | A | T |
| C | A | R |
| C | A | T |
| A | R | C |
| T | A | B |
| R | A | T |
| B | A | R |

[oOo]