GLOBAL OPTIMIZATION

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Other Global Optimization:

- Constant Propagation
- Dead-code elimination
- Liveness analysis
- Common subexpression elimination
- Loop optimization

Local Optimization

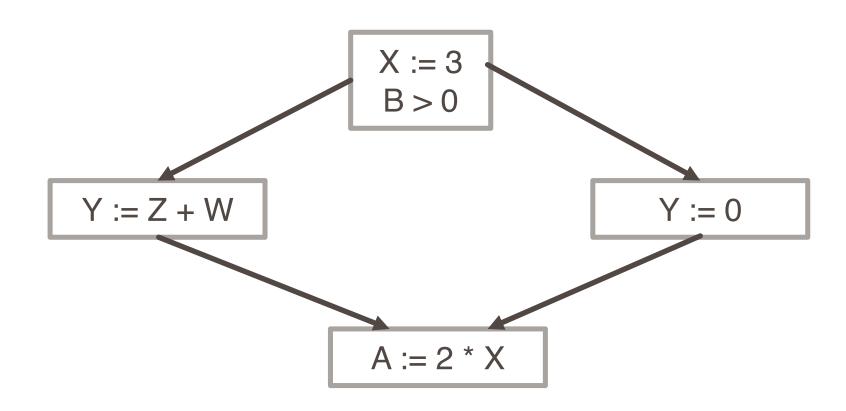
- Recall the simple basic-block optimizations
 - Constant propagation
 - Dead code elimination

$$X := 3$$

 $Y := Z * W$
 $Q := X + Y$
 $X := 3$
 $Y := Z * W$
 $Q := 3 + Y$

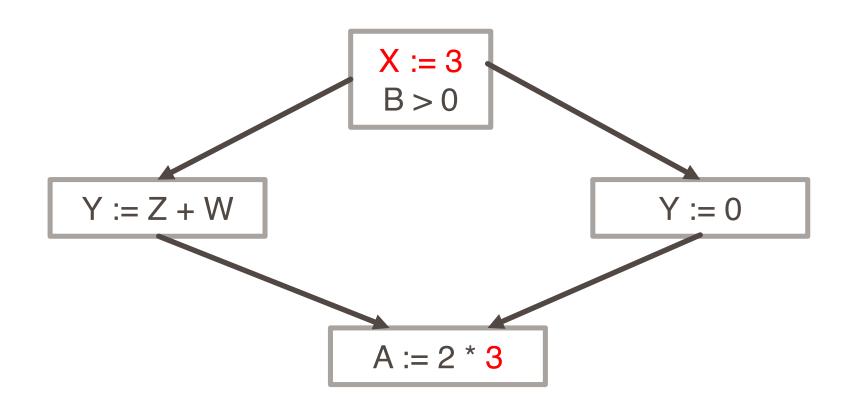
Global Optimization

These optimizations can be extended to an entire control-flow graph



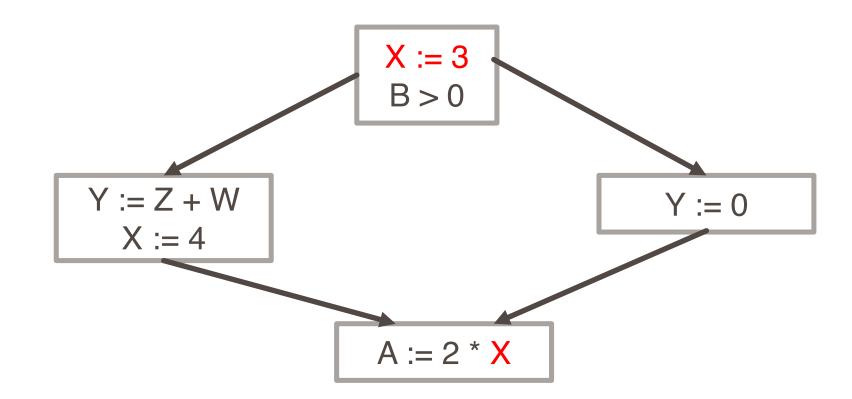
Global Optimization

These optimizations can be extended to an entire control-flow graph



Correctness

- How do we know it is OK to globally propagate constants?
- There are situations where it is incorrect:



Correctness (cont..)

To replace a use of x by a constant k we must know that:

On every path to the use of x, the last assignment to x is

$$x := k$$

- The correctness condition is not trivial to check
- "All paths" includes paths around loops and through branches of conditionals
- Checking the condition requires global analysis
 - An analysis of the entire control-flow graph

Global Analysis

- Global optimization tasks share several traits:
 - The optimization depends on knowing a property X at a particular point in program execution
 - Proving X at any point requires knowledge of the entire program
 - It is OK to be conservative. If the optimization requires X to be true, then want to know either
 - X is definitely true
 - Don't know if X is true
 - It is always safe to say "don't know"

Global Analysis (cont..)

- Global dataflow analysis is a standard technique for solving problems with these characteristics
- Global constant propagation is one example of an optimization that requires global dataflow analysis

Common subexpression elimination

Example:

$$a := b + c$$
 $a := b + c$
 $c := b + c$ \Rightarrow $c := a$
 $d := b + c$ $d := b + c$

- Example in array index calculations
 - c[i+1] := a[i+1] + b[i+1]
 - During address computation, i+1 should be reused
 - Not visible in high level code, but in intermediate code

Code Elimination

Unreachable code elimination

- Construct the control flow graph
- Unreachable code block will not have an incoming edge
- After constant propagation/folding, unreachable branches can be eliminated

Dead code elimination

Ineffective statements

```
    x := y + 1 (immediately redefined, eliminate!)
    y := 5 ⇒ y := 5
    x := 2 * z
    x := 2 * z
```

- A variable is dead if it is never used after last definition
 - Eliminate assignments to dead variables
- Need to do data flow analysis to find dead variables

Function Optimization

Function inlining

- Replace a function call with the body of the function
- Save a lot of copying of the parameters, return address, etc.

Function cloning

Create specialized code for a function for different calling parameters

Loop optimization

- Consumes 90% of the execution time
 - ⇒ a larger payoff to optimize the code within a loop

Techniques

- Loop invariant detection and code motion
- Induction variable elimination
- Strength reduction in loops
- Loop unrolling
- Loop peeling
- Loop fusion

Loop invariant detection

- If the result of a statement or expression does not change within a loop, and it has no external side-effect
- Computation can be moved to outside of the loop
- Example

```
for (i=0; i<n; i++) a[i] := a[i] + x/y;
```

Three address code

```
for (i=0; i<n; i++) { c := x/y; a[i] := a[i] + c; } 
 \Rightarrow c := x/y; 
 for (i=0; i<n; i++) a[i] := a[i] + c;
```

Code Motion

- Reduce frequency with which computation performed
 - If it will always produce same result
 - Especially moving code out of loop

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    a[n*i + j] = b[j];

for (i = 0; i < n; i++) {
    int ni = n*i;
    for (j = 0; j < n; j++)
        a[ni + j] = b[j];
}</pre>
```

- Strength reduction in loops
 - Replace costly operation with simpler one
 - Shift, add instead of multiply or divide

$$16*x --> x << 4$$

- Depends on cost of multiply or divide instruction
- Recognize sequence of products

```
for (i = 0; i < n; i++)
for (j = 0; j < n; j++)
a[n*i + j] = b[j];
```

```
int ni = 0;
for (i = 0; i < n; i++) {
  for (j = 0; j < n; j++)
    a[ni + j] = b[j];
  ni += n;
}</pre>
```

- Strength reduction in loops
 - Replace costly operation with simpler one
 - Shift, add instead of multiply or divide

```
16*x --> x << 4
```

- Depends on cost of multiply or divide instruction
- Recognize sequence of products

```
s := 0;
for (i=0; i<n; i++)
{
    v := 4 * i;
    s := s + v;
}</pre>
s := 0;
for (i=0; i<n; i++)
{
    v := v + 4;
    s := s + v;
}</pre>
```

- Induction variable elimination
 - If there are multiple induction variables in a loop, can eliminate the ones which are used only in the test condition
 - Example

```
s := 0; for (i=0; i<n; i++) { s := 4 * i; ... } -- i is not referenced in loop \Rightarrow s := 0; e := 4*n; while (s < e) { s := s + 4; }
```

```
s := 0;
for (i=0; i<n; i++)
{ s := 4 * i; ... }
-- i is not referenced in loop</pre>
s := 0;
e := 4*n;
while (s < e) {
s := s + 4;
}
```

Code Optimization Techniques

Loop unrolling

- Execute loop body multiple times at each iteration
- Get rid of the conditional branches, if possible
- Allow optimization to cross multiple iterations of the loop
 - Especially for parallel instruction execution
- Space time tradeoff
 - Increase in code size, reduce some instructions

Loop peeling

- Similar to unrolling
- But unroll the first and/or last few iterations

Loop fusion

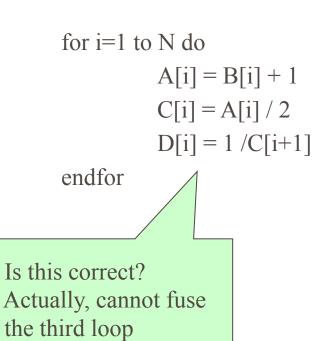
```
Example
for i=1 to N do
A[i] = B[i] + 1
endfor
for i=1 to N do
C[i] = A[i] / 2
endfor
for i=1 to N do
D[i] = 1 / C[i+1]
endfor
```

```
for i=1 to N do A[i] = B[i] + 1 C[i] = A[i] / 2 D[i] = 1 / C[i+1] endfor
```

Before Loop Fusion

Loop fusion

```
Example
for i=1 to N do
A[i] = B[i] + 1
endfor
for i=1 to N do
C[i] = A[i] / 2
endfor
for i=1 to N do
D[i] = 1 / C[i+1]
endfor
```



Before Loop Fusion

Limitations of Compiler Optimization

- Operate Under Fundamental Constraint
 - Must not cause any change in program behavior under any possible condition
 - Often prevents it from making optimizations when would only affect behavior under pathological conditions.
- Behavior that may be obvious to the programmer can be obfuscated by languages and coding styles
 - e.g., data ranges may be more limited than variable types suggest
- Most analysis is performed only within procedures
 - whole-program analysis is too expensive in most cases
- Most analysis is based only on static information
 - compiler has difficulty anticipating run-time inputs
- When in doubt, the compiler must be conservative