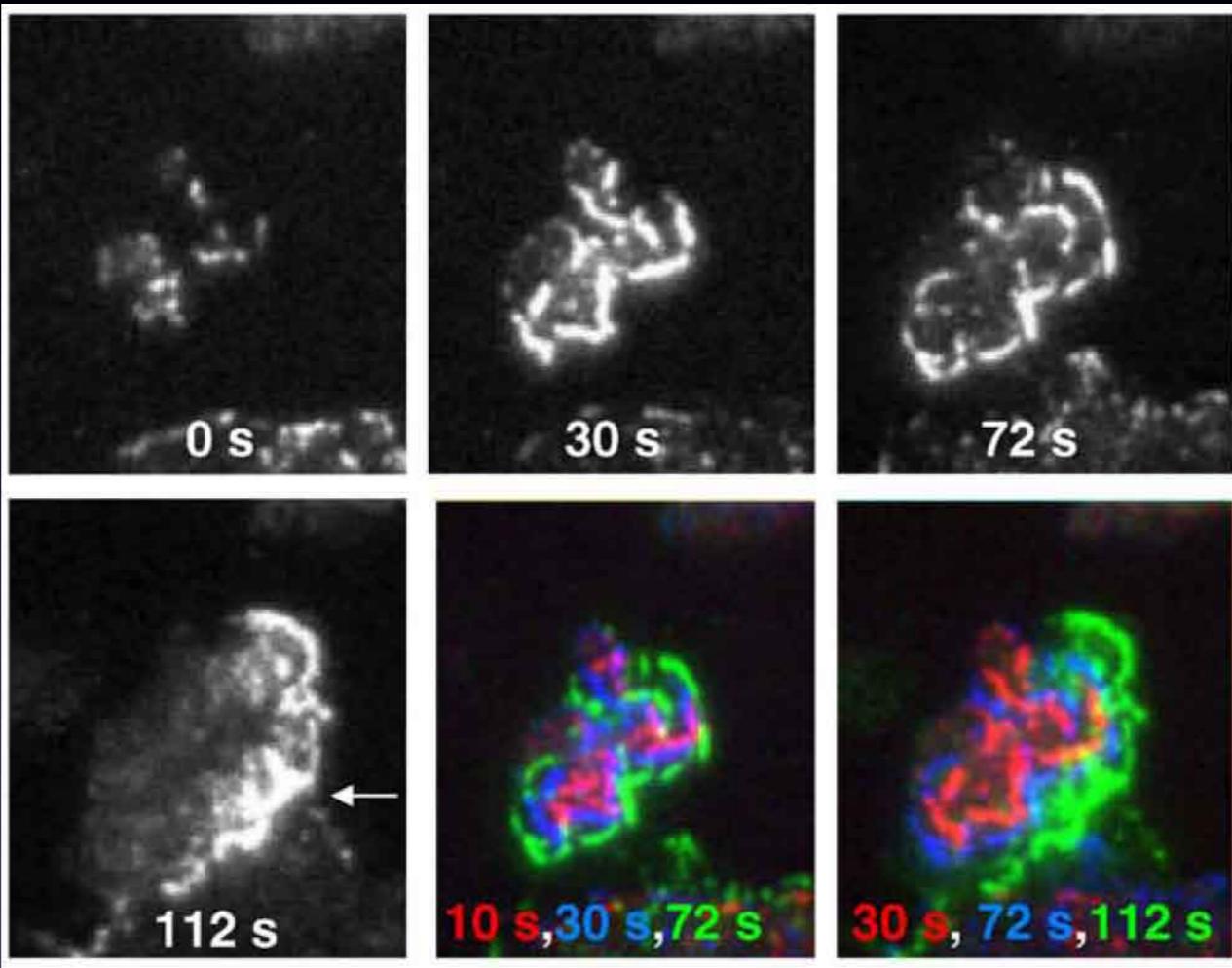


# Wave Pinning, Actin Waves, and LPA

MCB 2012  
William R. Holmes

# Intercellular Waves



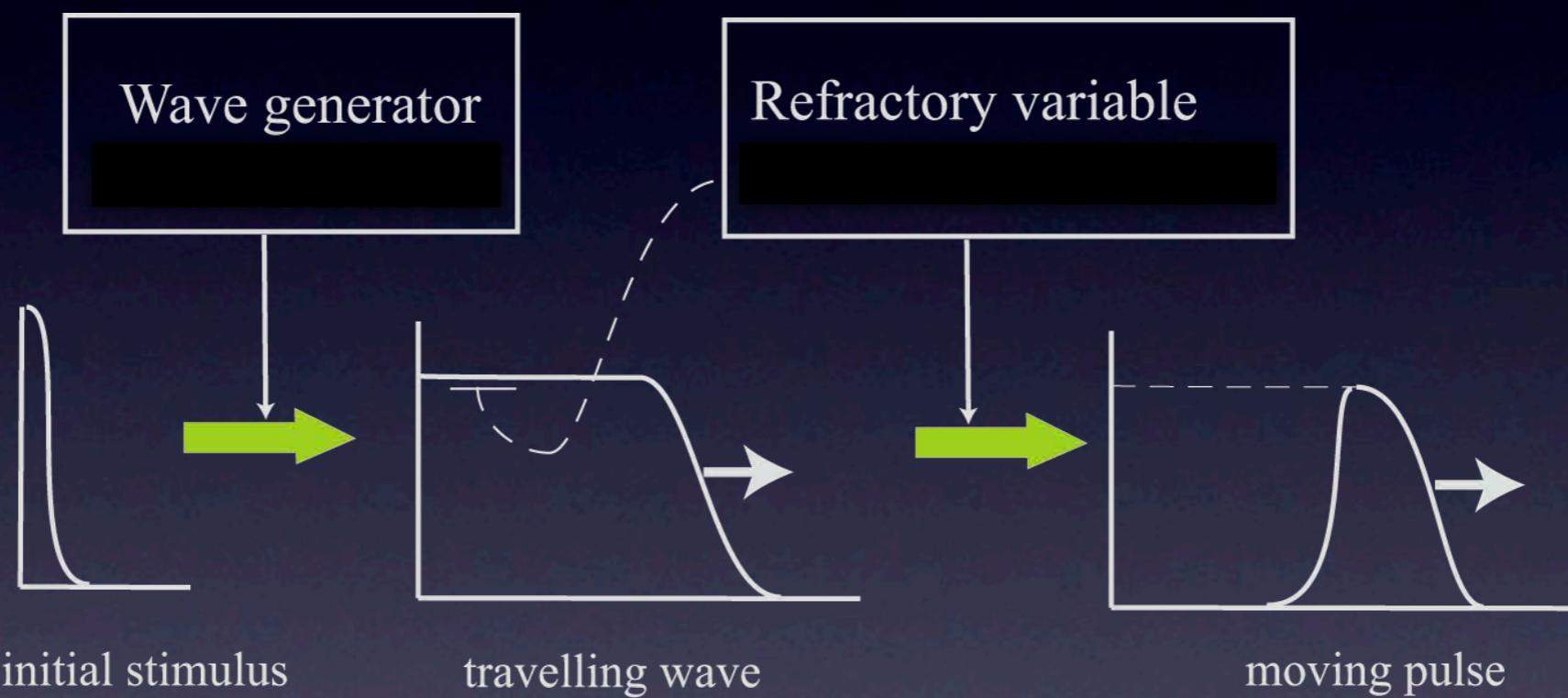
Weiner et al., 2007, PLoS Biology

- Dynamic HemI waves in neutrophils

# Questions?

- How can such waves / pulses form?
- What molecular constituents play a role?

# FitzHugh Nagumo Idea



- Positive feedback induces a wave.
- Slower negative feedback yields a pulse.

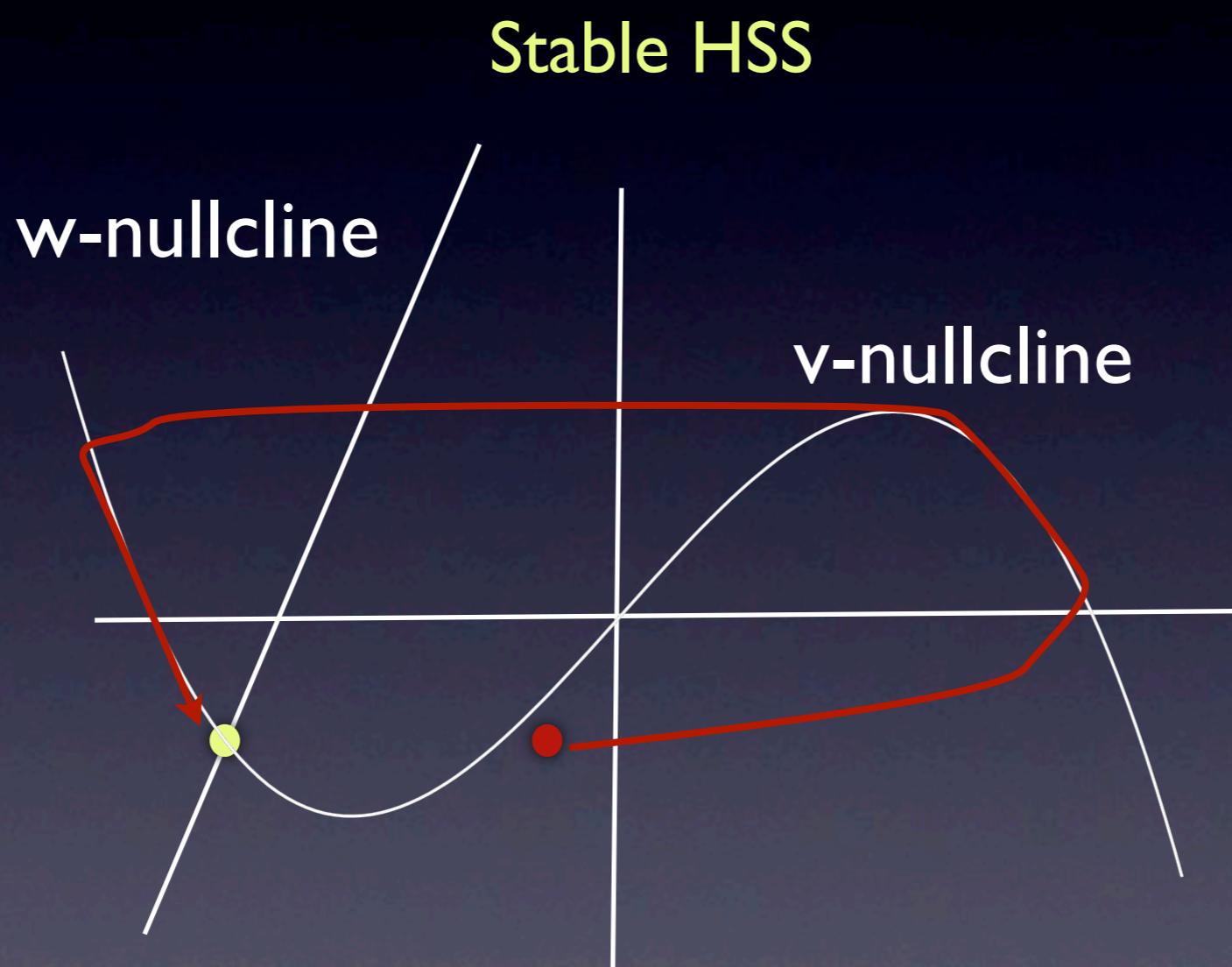
# FitzHugh Nagumo

$$v_t = v - v^3 - w + I + D_v \Delta v,$$

$$\tau w_t = v - bw - a$$

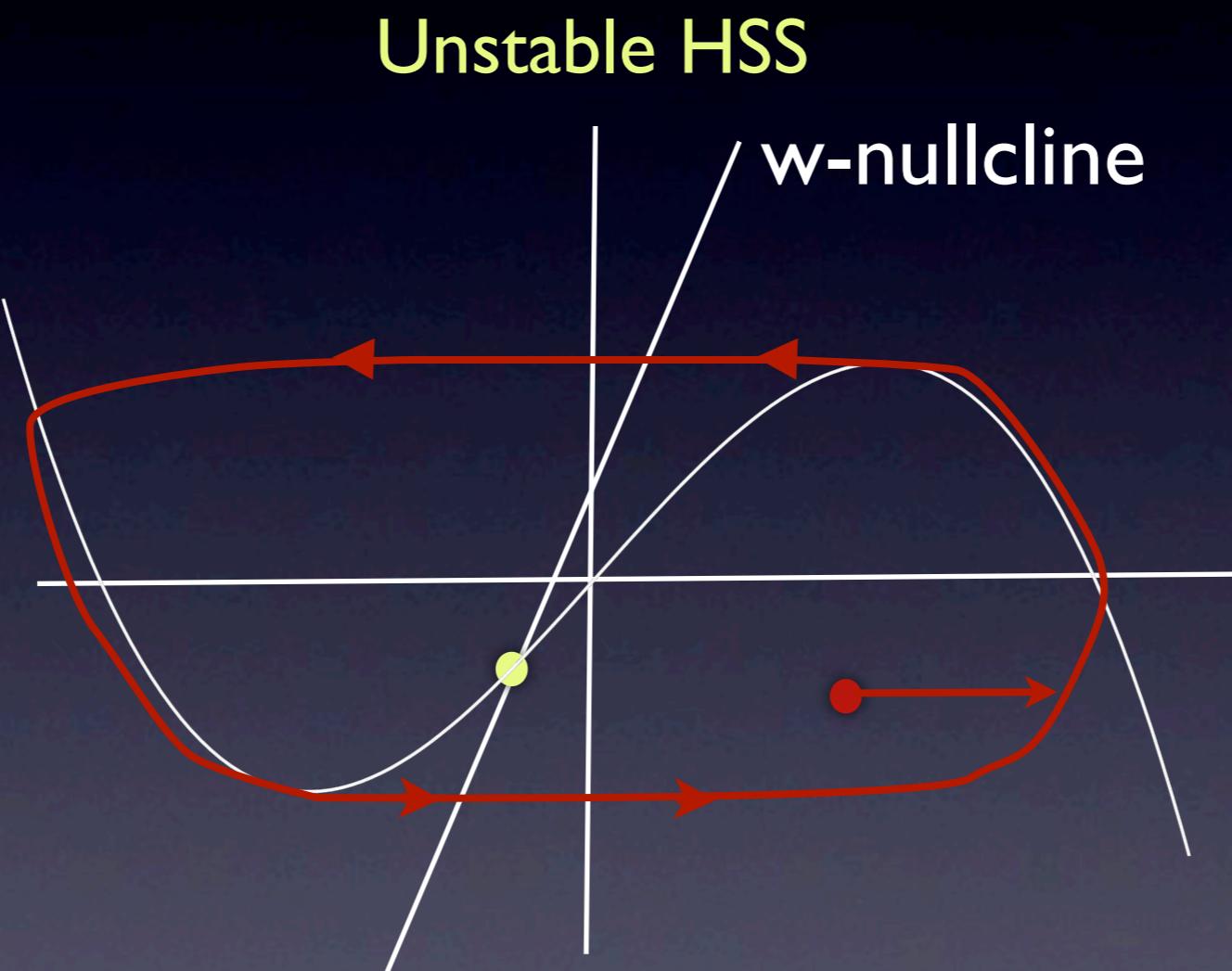
- Used to describe signal propagation in nerves.
- $v$  = membrane voltage
- $w$  = ion concentration

# FitzHugh Nagumo



- Stable HSS leads to transient dynamics.

# FitzHugh Nagumo



- Unstable HSS leads to a limit cycles and persistent dynamics

# FN Feature

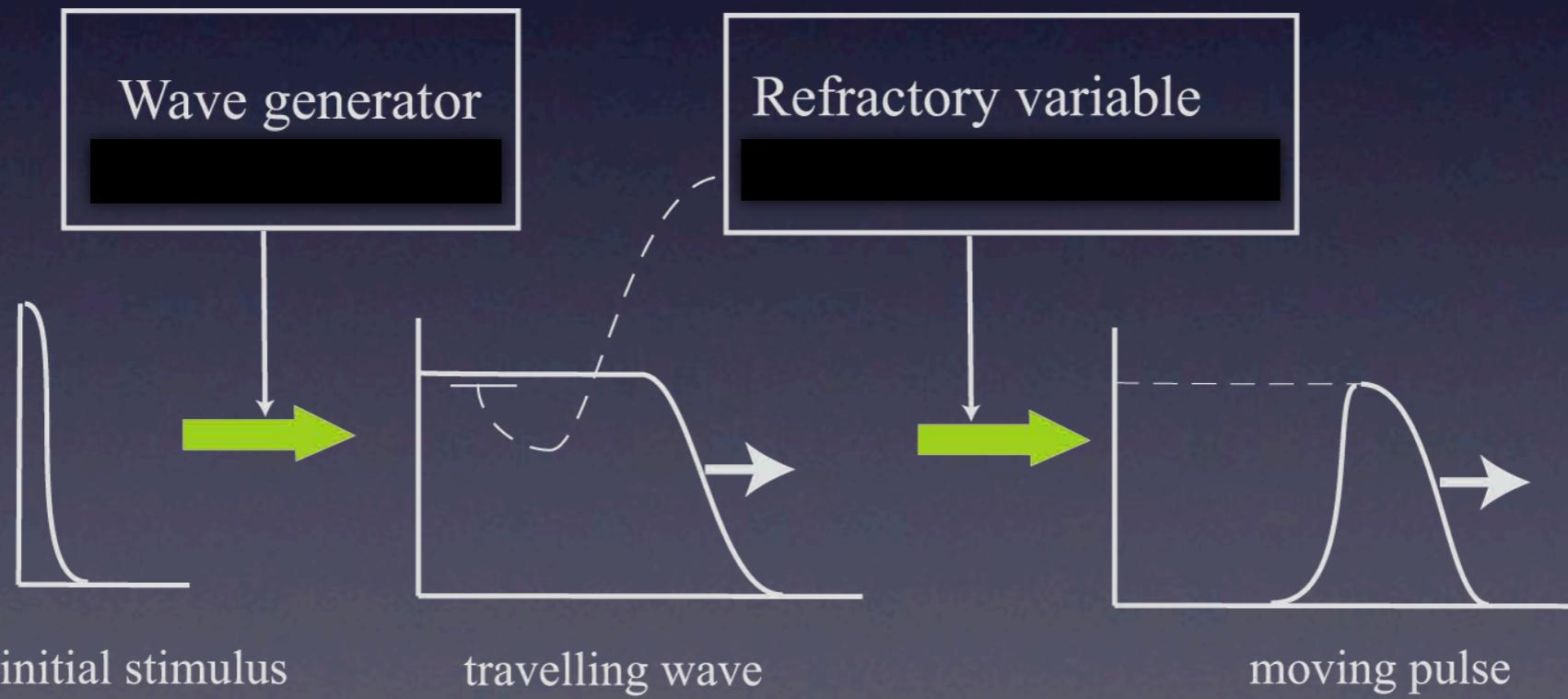
- Stable HSS = transient excitable dynamics
- Unstable HSS = unstable persistent dynamics

# Relationship to cell dynamics

- Cells are not always all or nothing.
- Some cells exhibit dynamics even after a stimulus is removed.
- Some cells are excitable and persistent.

# FN Extension

- We will consider an augmentation of the standard FN framework.



# Hypothesis

- We still consider a basic ‘wave generator + refractory feedback’ model.
- Wave Generator = Actin Regulators
- Refractory feedback = Actin

# Hypothesis

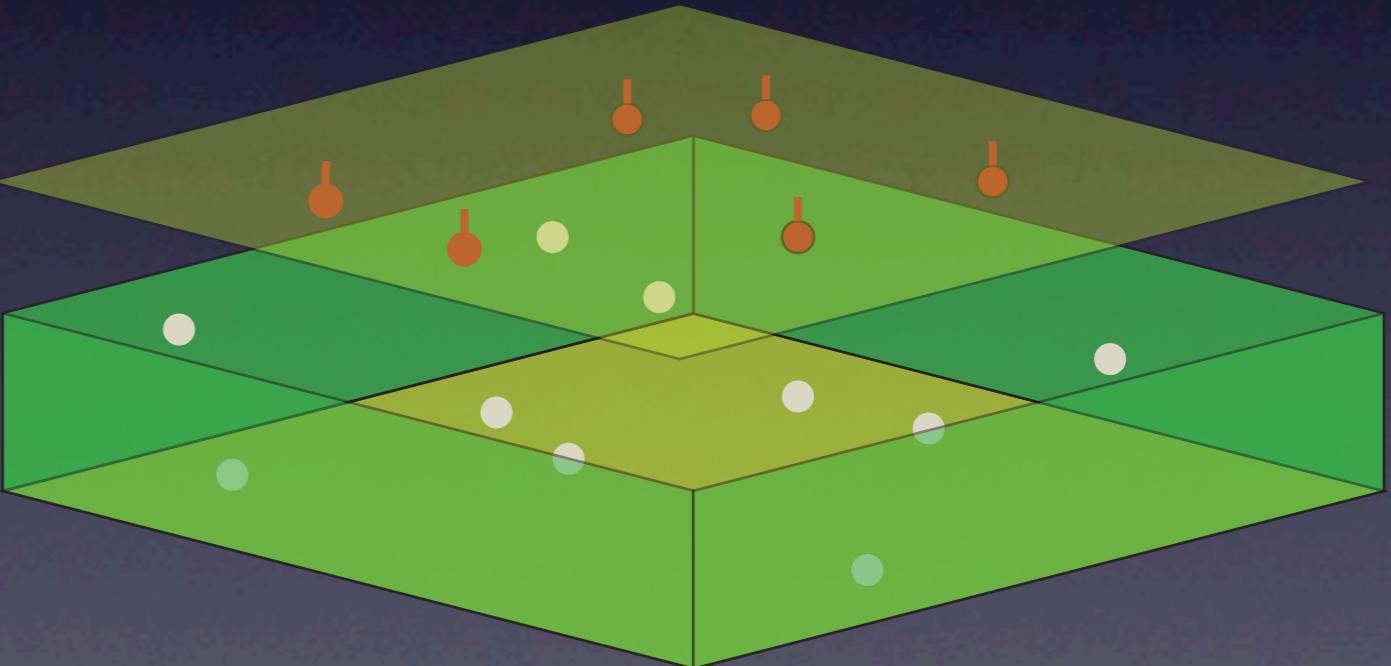
- Polarity proteins such as GTPases or Phosphoinositides serve as a wave generator.
- Actin polymerization inactivates these proteins acting as a refractory feedback.

# Wave Generator

- Consider a wave pinning (WP) model indicative of GTPase function.

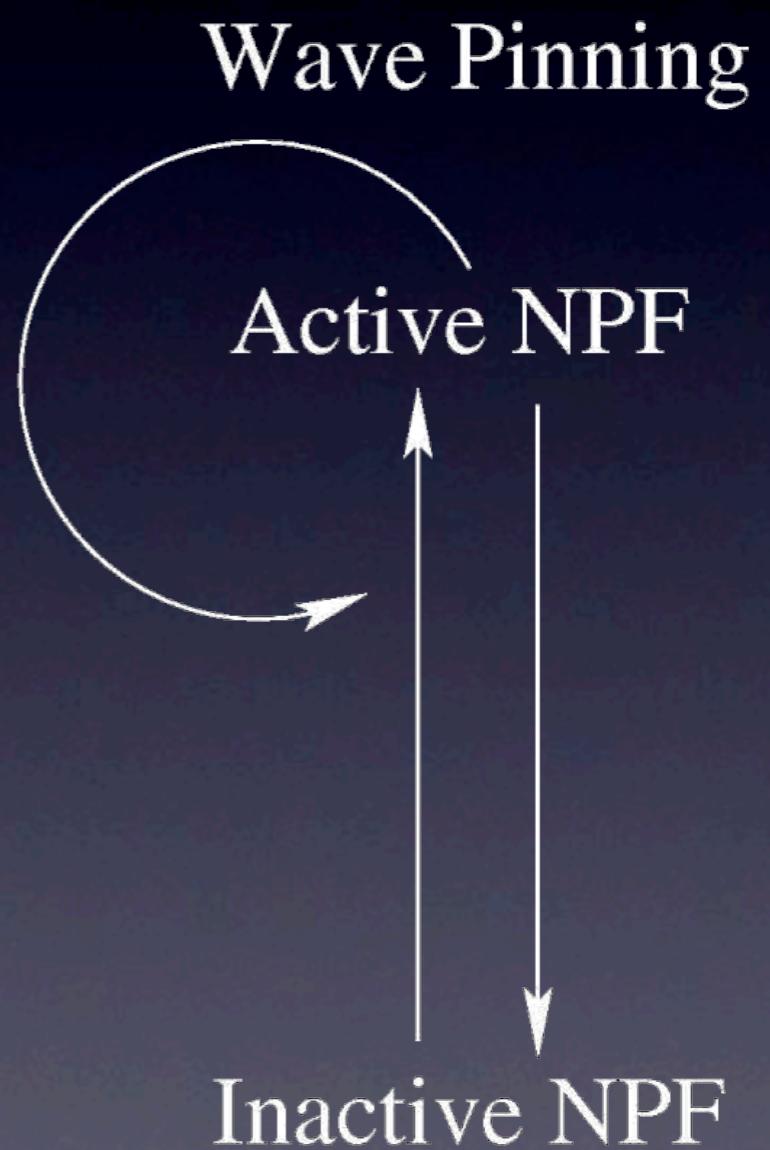
# Wave Generator : GTPases

- NPF = actin nucleating protein
- Exists in 2 forms.
- Only the active NPF nucleates F-Actin
- Active NPF
  - Inactive NPF



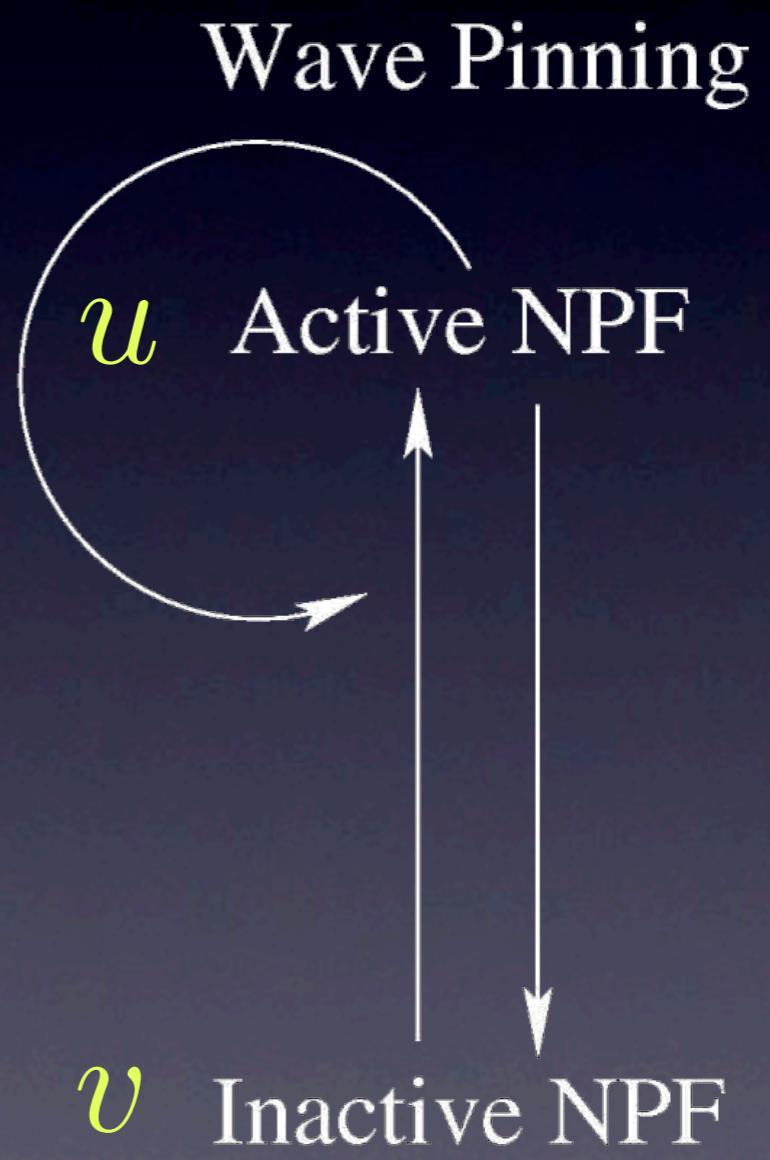
# Model Features

- Primary features
  - Slow Fast Diffusion
  - Autocatalysis
  - Conservation



# Wave Pinning: Equations

$$u_t(x, t) = f(u, v) + D_u \Delta u$$
$$v_t(x, t) = -f(u, v) + D_v \Delta v$$
$$f(u, v) = v\left(k_0 + \frac{\gamma u^n}{K^n + u^n}\right) - \delta u$$
$$D_u \ll D_v$$

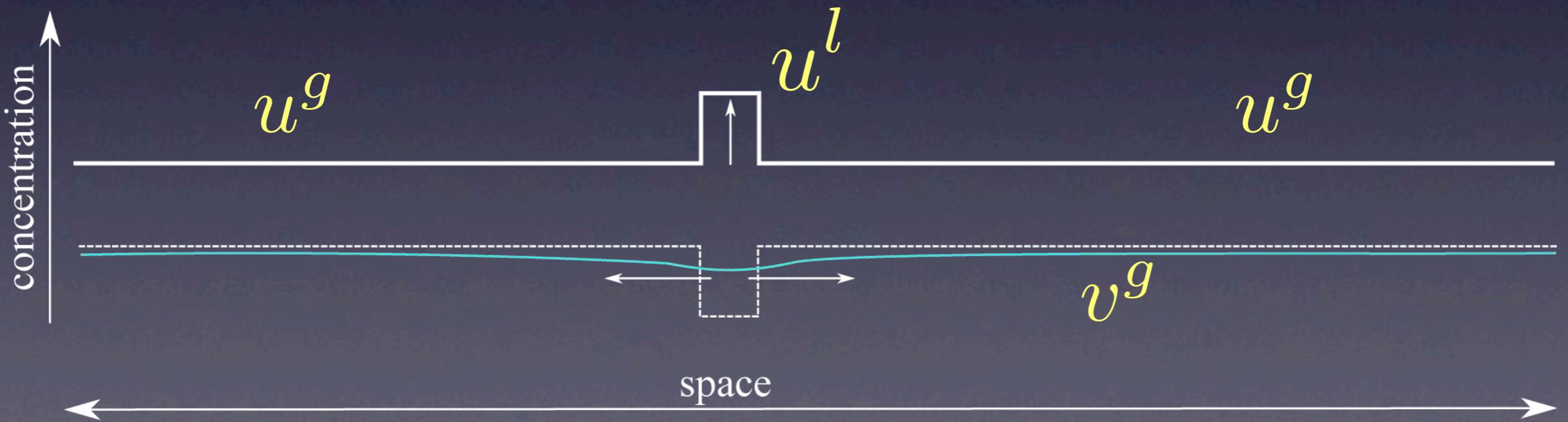


# LPA Reduction

$$u_t^l(t) = f(u^l, v^g)$$

$$u_t^g(t) = f(u^g, v^g)$$

$$v_t^g(t) = -f(u^g, v^g)$$



# Conservation Reduction

- Assume the perturbation is highly localized.

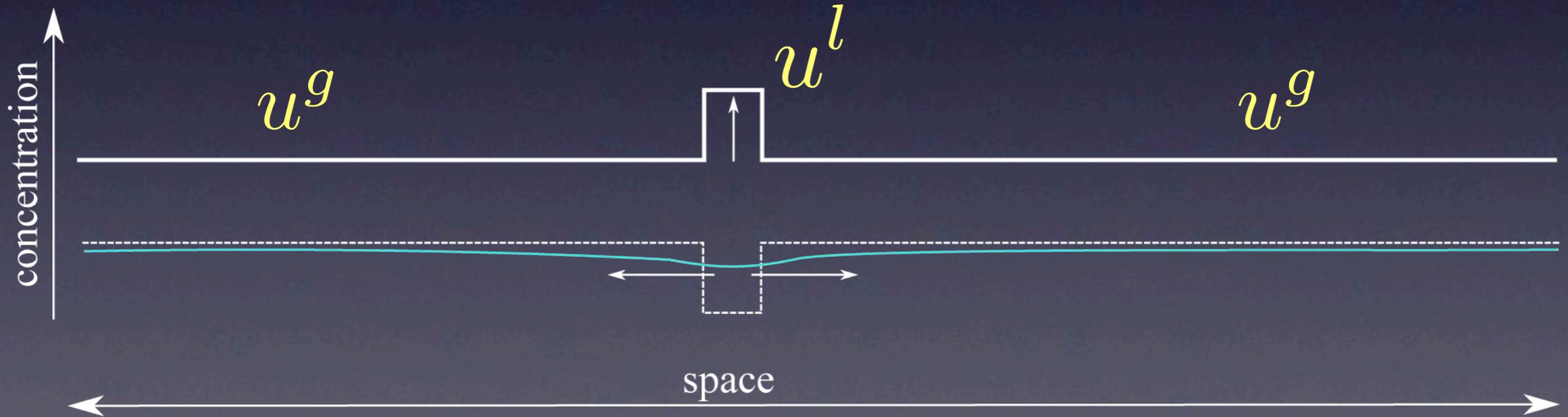
$$\int u^g(t) + v^g(t) \, dx \approx \int u(x, t) + v(x, t) \, dx = C$$

- So  $v^g(t) = T - u^g(t)$

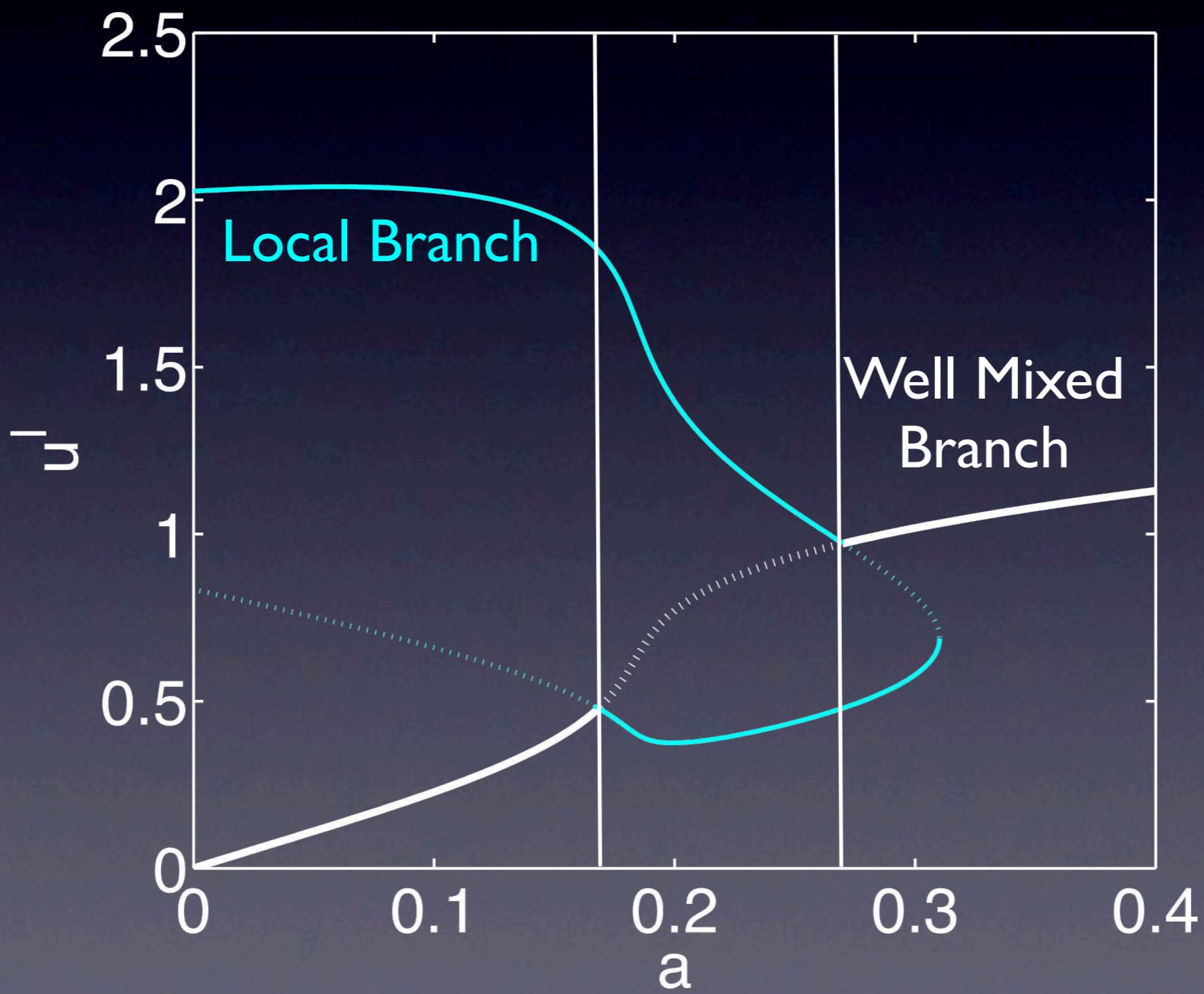
# LPA System

$$u_t^l(t) = f(u^l, T - u^g)$$

$$u_t^g(t) = f(u^g, T - u^g)$$

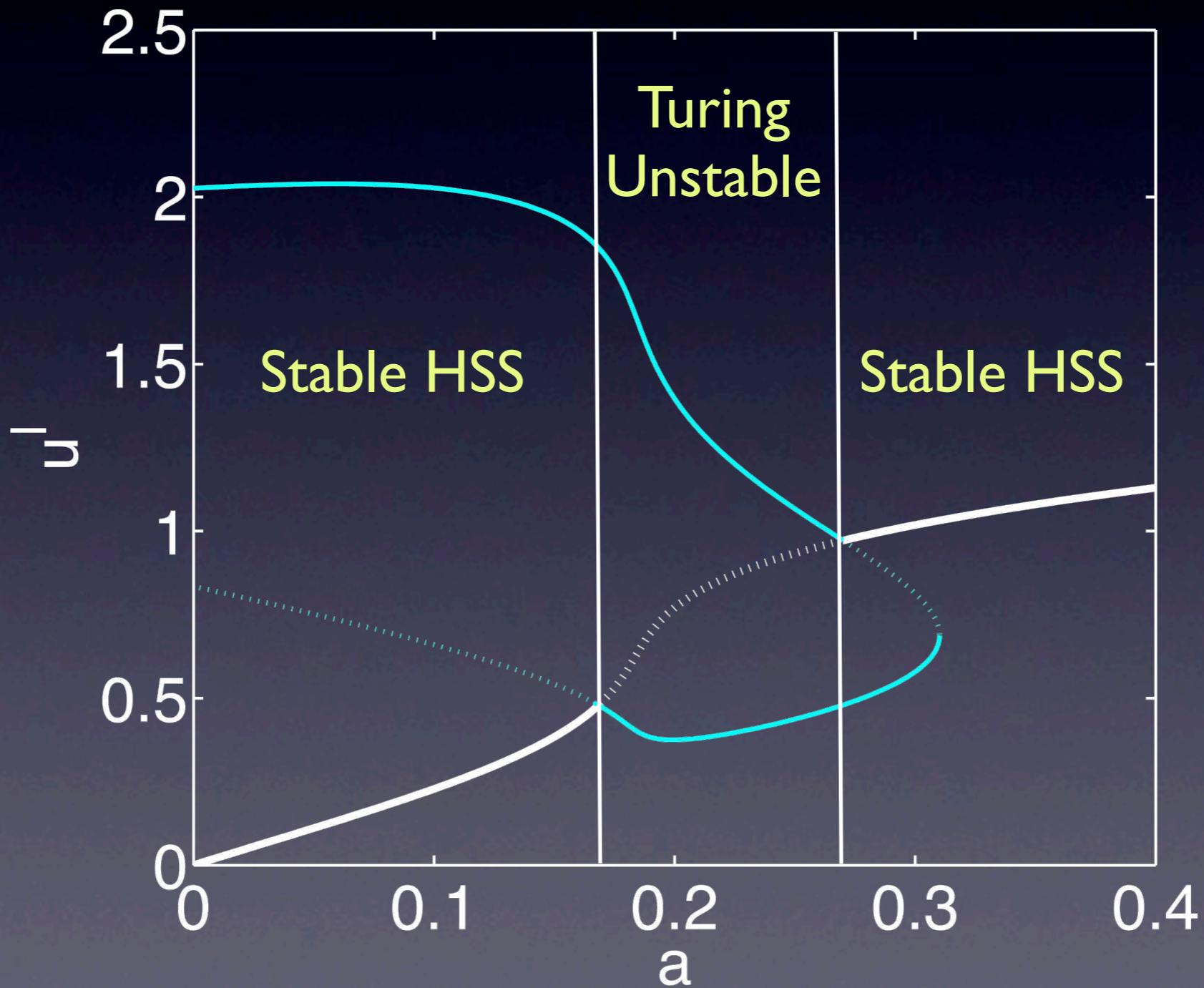


# Wave Pinning LPA



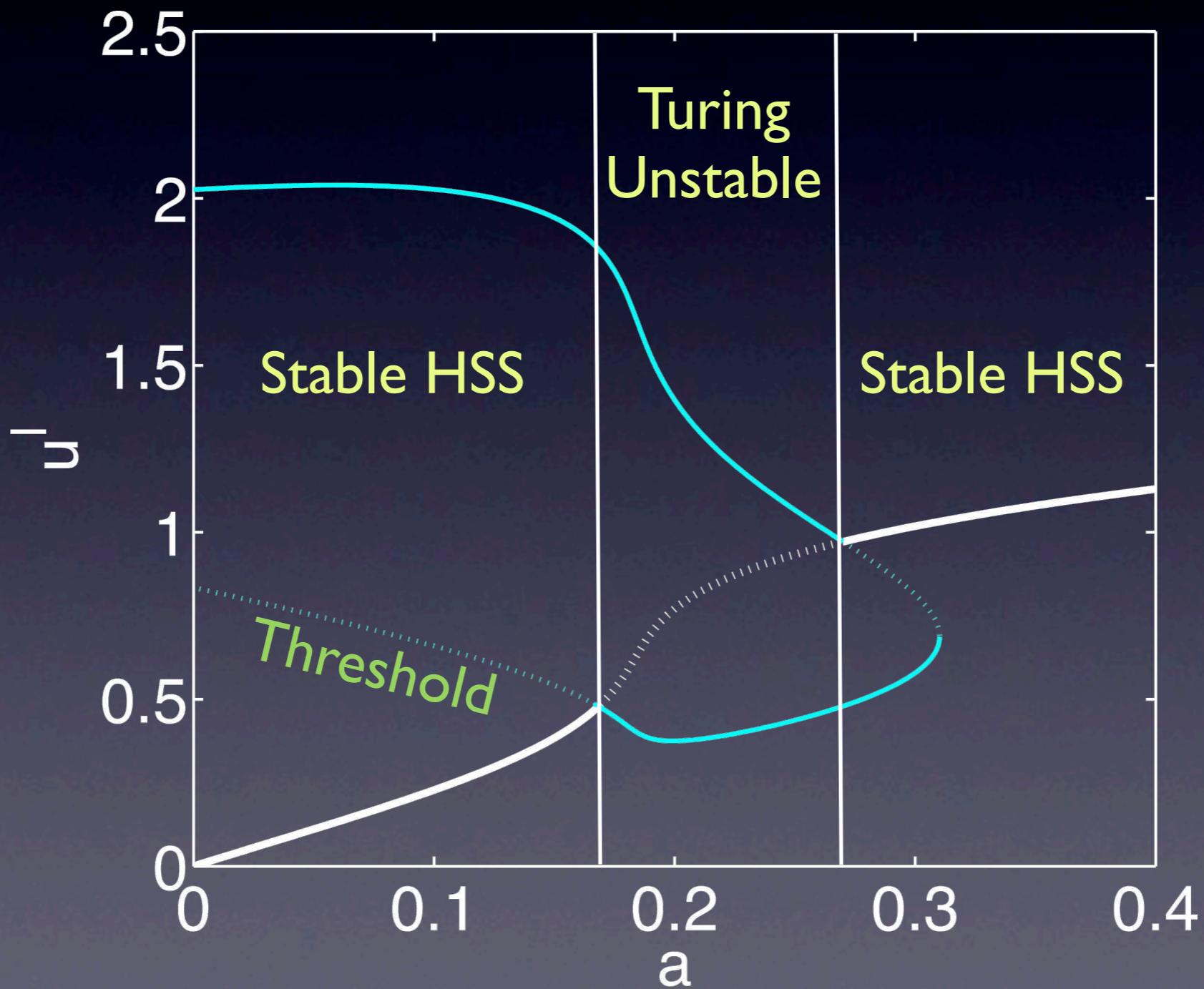
# Wave Pinning: Stability

Wave Pinning LPA



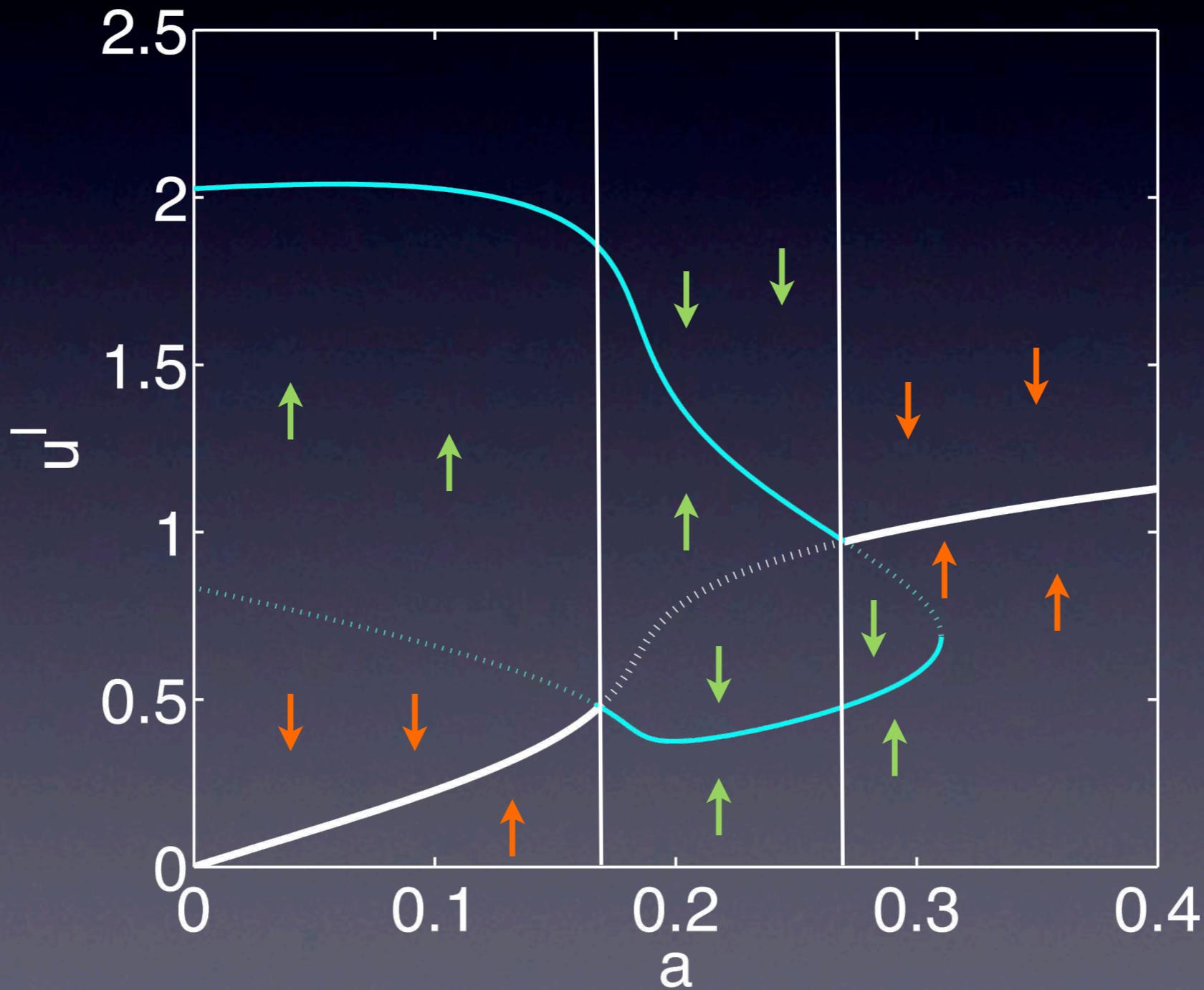
# Wave Pinning: Stability

Wave Pinning LPA



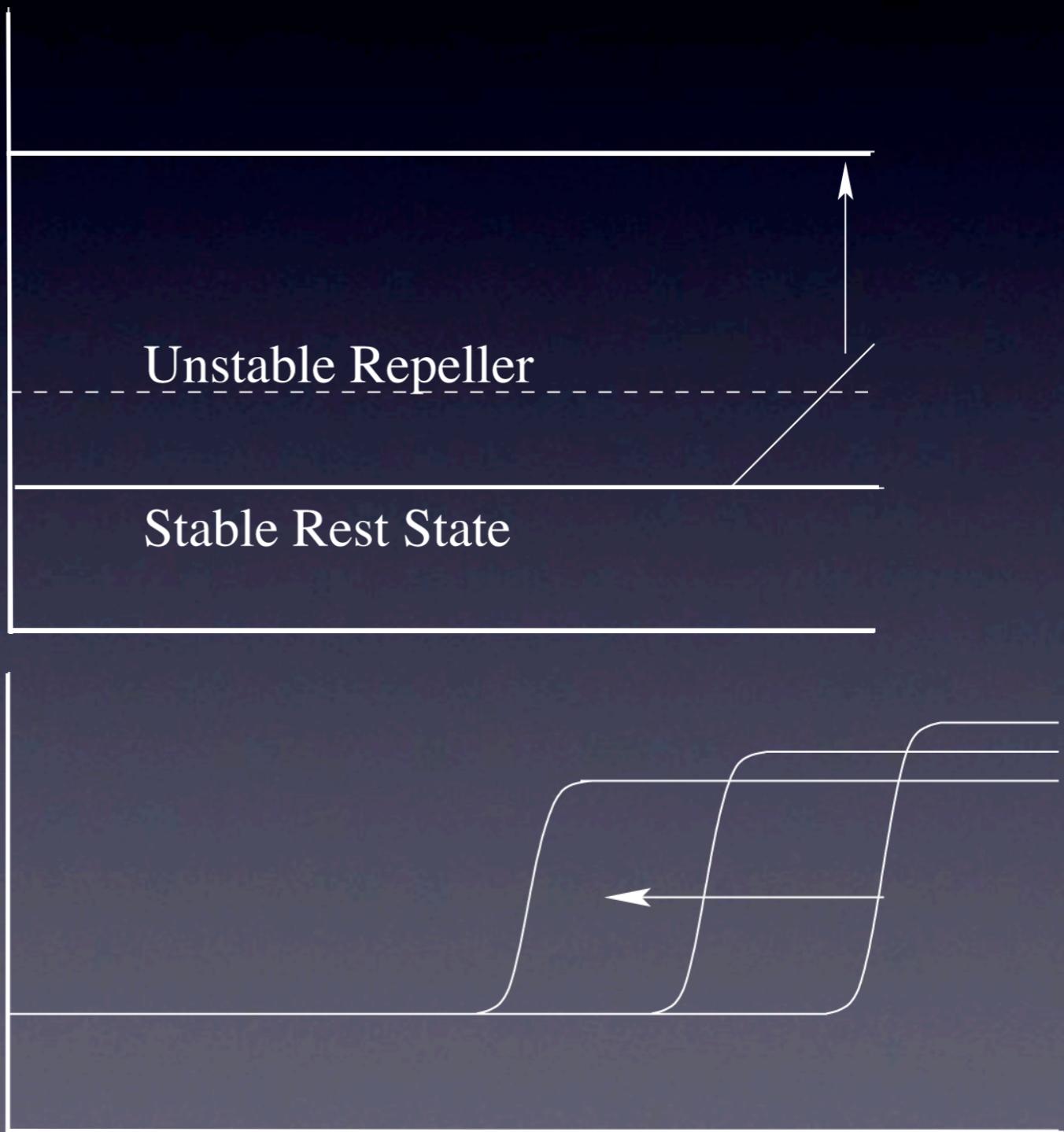
# Wave Pinning: Stability

Wave Pinning LPA



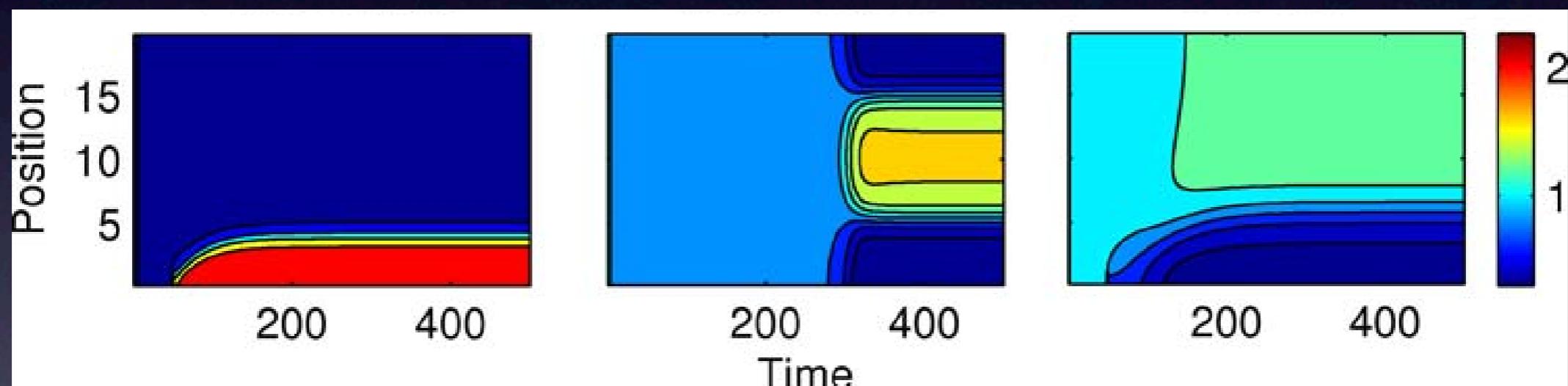
# Wave Pinning

- + feedback yields a threshold response
- Conservation causes stalling.
- As the wave propagates, it depletes the inactive NPF



# Wave Pinning: Simulations

Active NPF

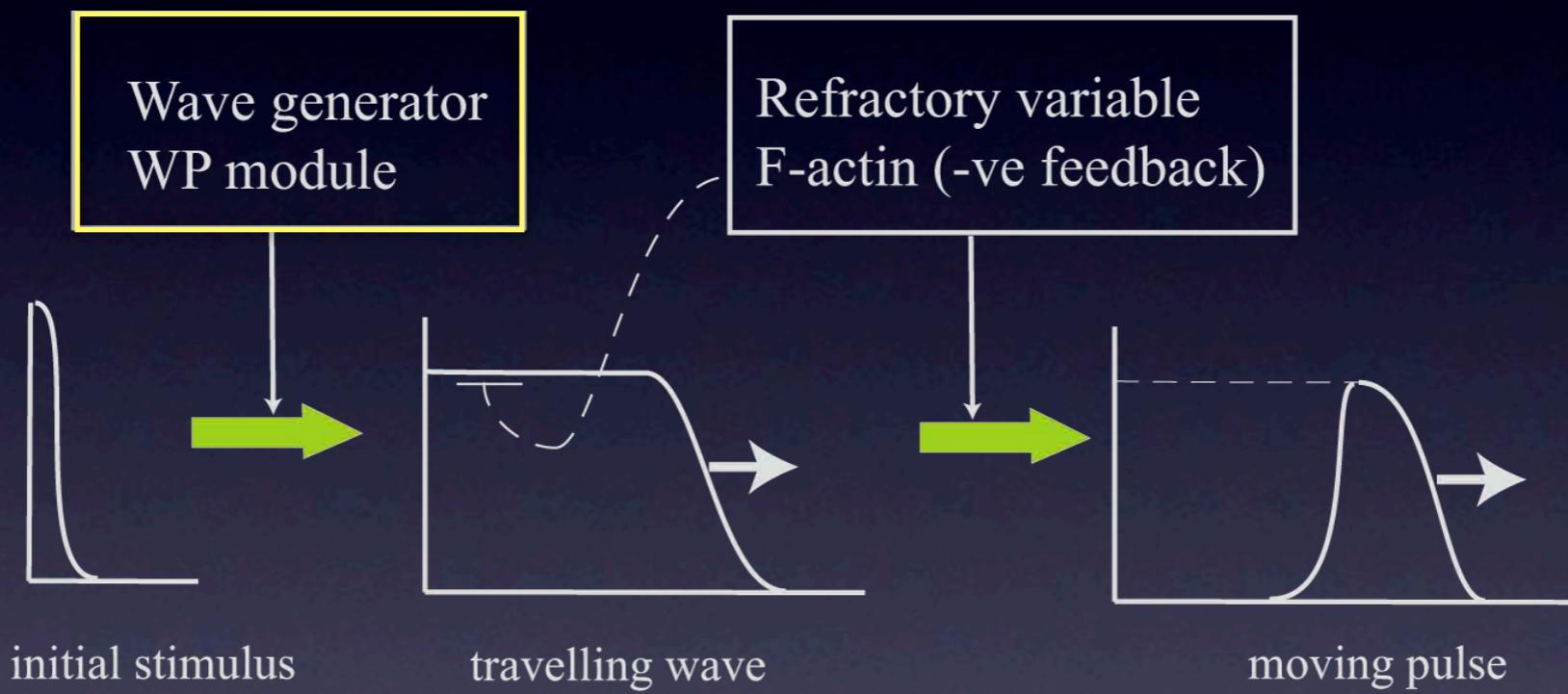


Wave Pinning  
+ Perturbation

Turing  
Noise

Wave Pinning  
- Perturbation

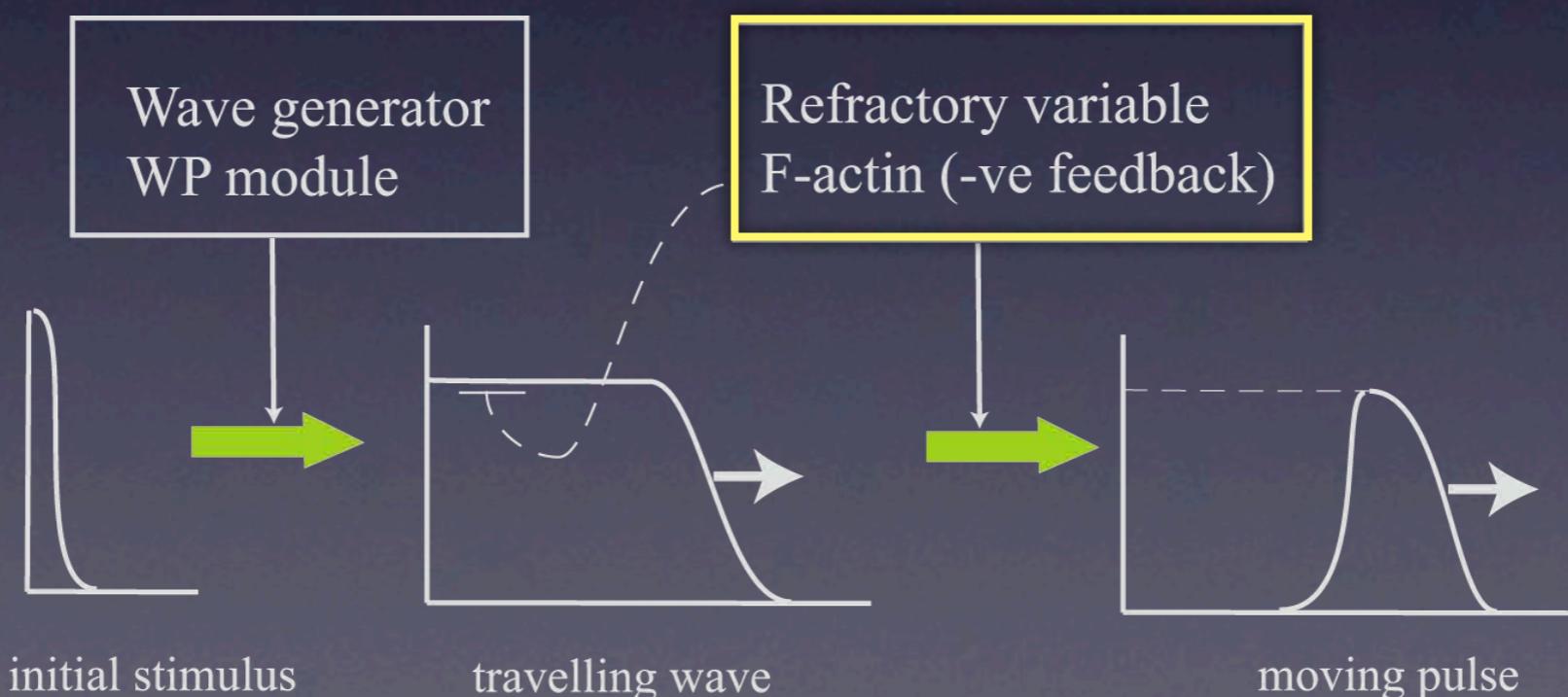
# Wave Pinning: Wave Generator



- We will assume this WP model acts as a wave generator.

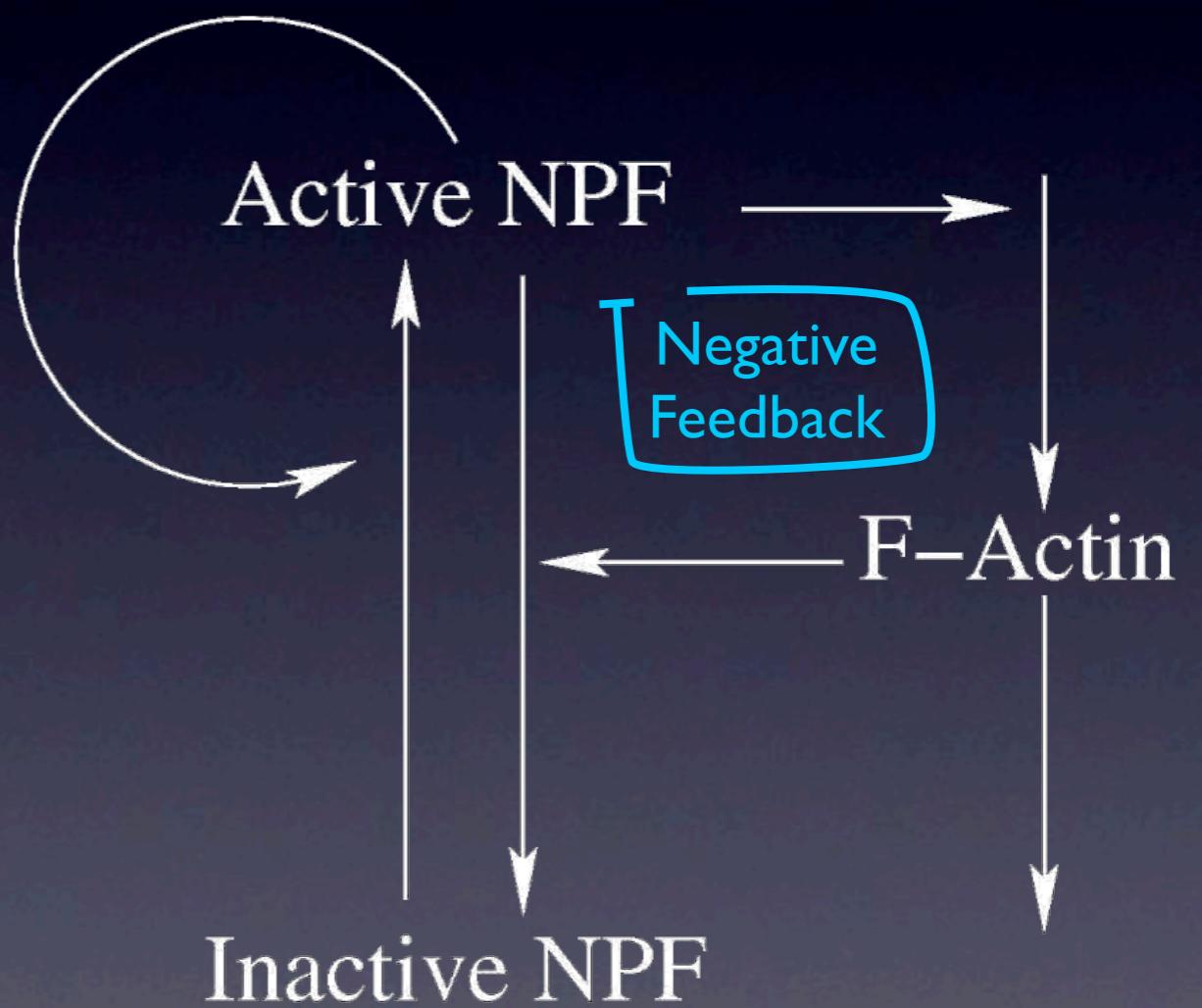
# Refractory Feedback

- Polarity related proteins (GTPases) nucleate actin and initiate a wave.
- Growing actin ‘inactivates’ these proteins.



# Actin Wave Model

- Active NPF promotes F-Actin.
  - Wave Generator
- F-Actin inactivates NPF
  - Refractory feedback



# Actin Wave Model

$$A_t = f + D_A \Delta A,$$

$$I_t = -f + D_I \Delta I$$

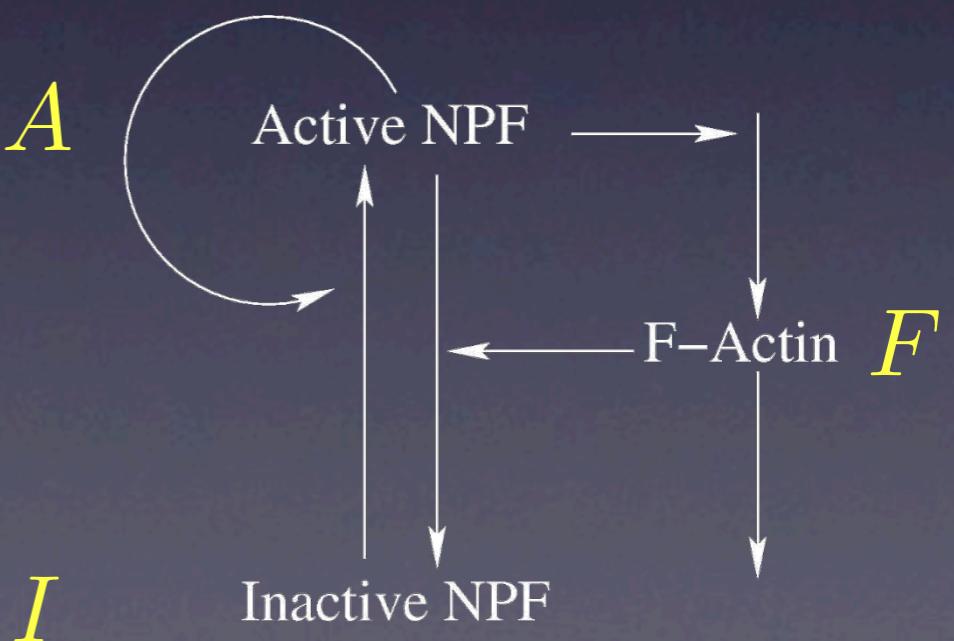
$$f(A, I, F) = \left( k_0 + \frac{\gamma A^3}{A_0^3 + A^3} \right) I - \delta \left( s_1 + s_2 \frac{F}{F_0 + F} \right) A$$

NPF Equations

F-Actin Equations

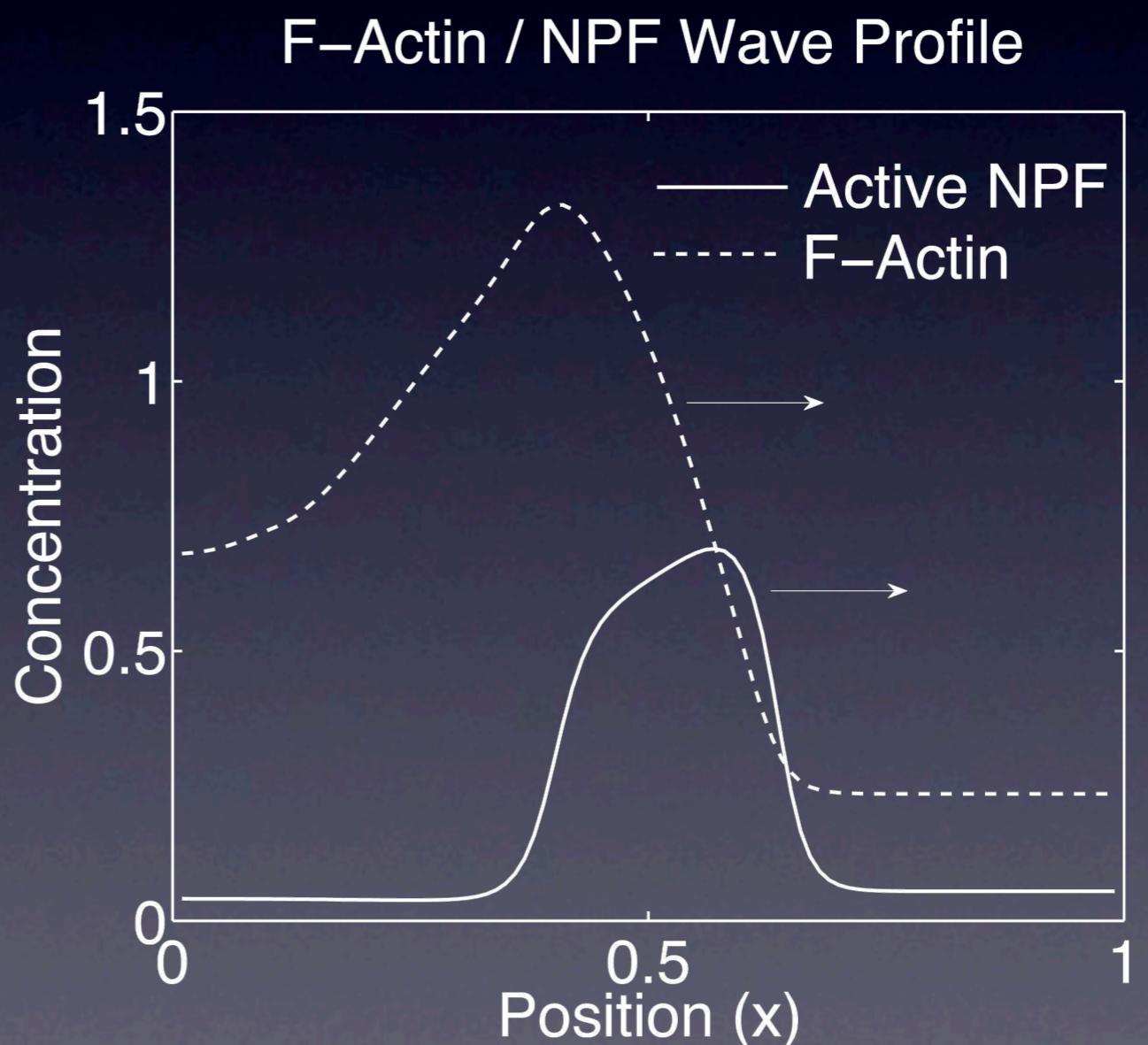
$$F_t = \epsilon h$$

$$h(A, F) = k_n A - k_s F$$



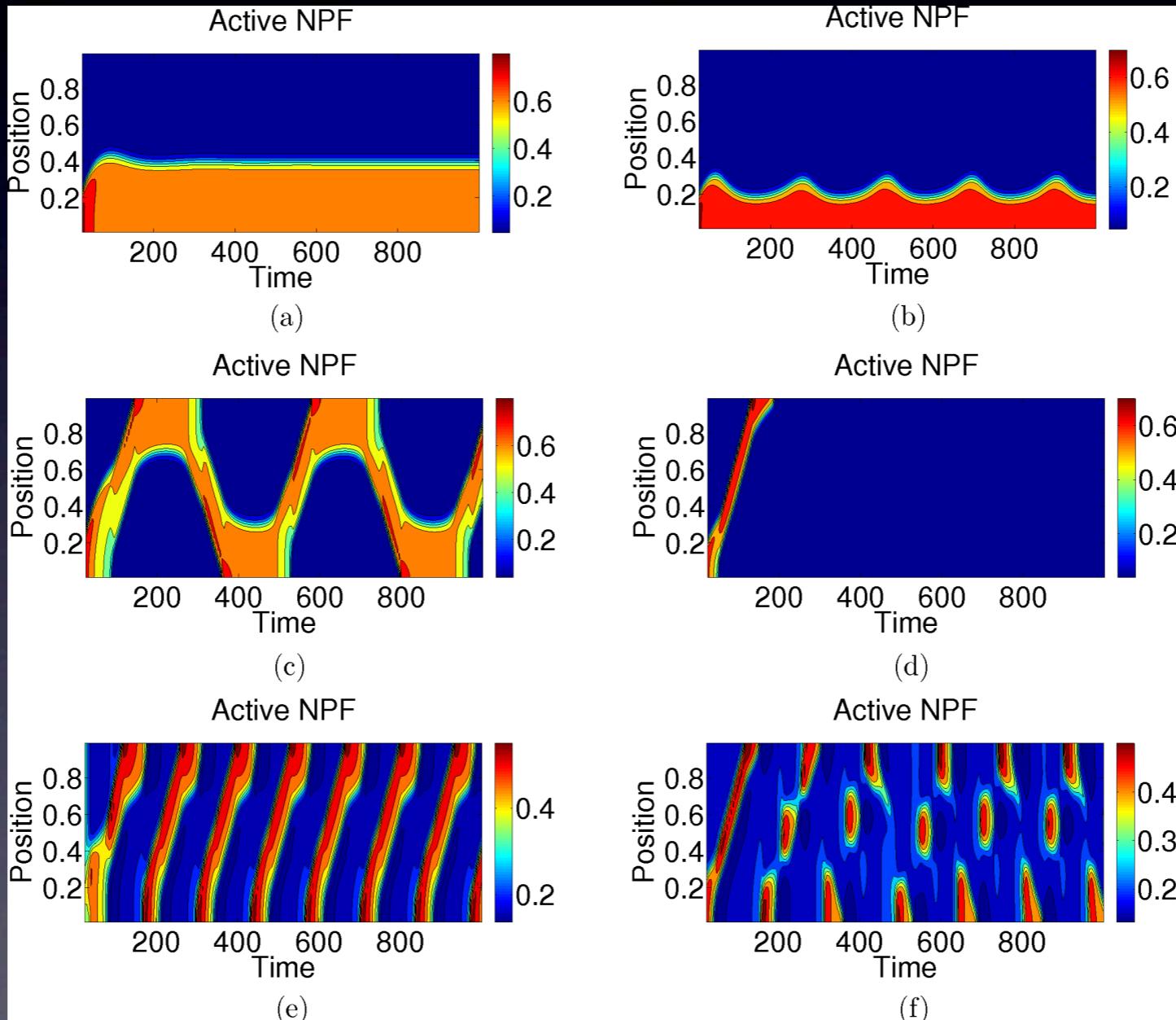
# Pulse Snapshot

- F-Actin wave trails  
NPF wave



# Spatio-Temporal Behaviour

Pinned Wave



Reflecting  
Pulse

Pulse  
Train

Oscillating  
Wave

Single  
Pulse

Exotic

- Kymograph =  $(x,t)$  plot

Use LPA to map  
parameter space

# Actin Wave LP-System

$$A_t^l = f(A^l, I^g, F^l),$$

$$A_t^g = f(A^g, I^g, F^g),$$

$$I_t^g = -f(A^g, I^g, F^g),$$

$$F_t^l = \epsilon h(A^l, F^l),$$

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# Actin Wave LP-System

$$A_t^l = f(A^l, I^g, F^l),$$

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$$I_t^g = -f(A^g, I^g, F^g),$$

$$F_t^l = \epsilon h(A^l, F^l),$$

$$F_t^g = \epsilon h(A^g, F^g)$$

# Actin Wave LPA

- Applying NPF conservation.

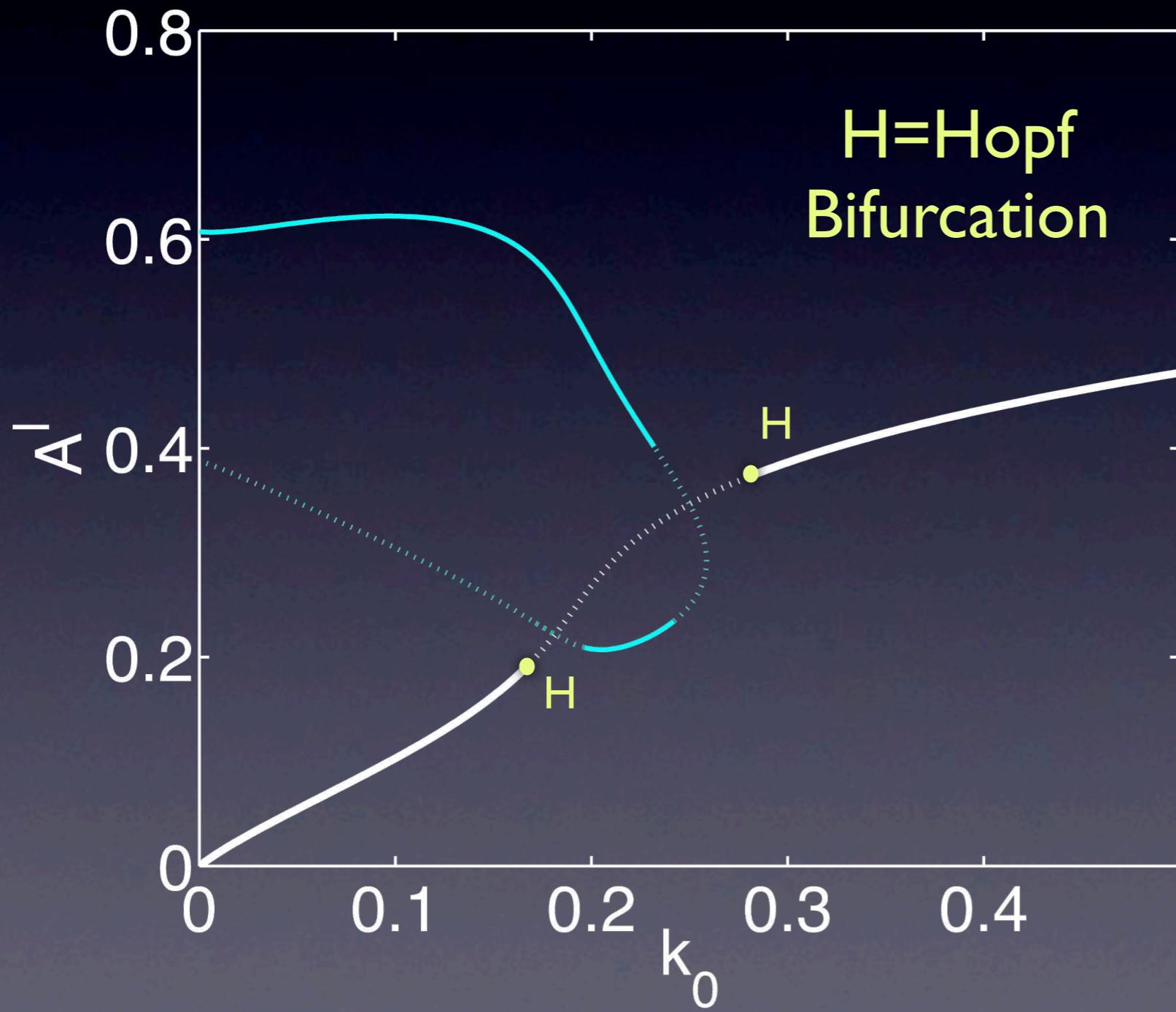
$$A_t^l = f(A^l, C - A^g, F^l),$$

$$A_t^g = f(A^g, C - A^g, F^g),$$

$$F_t^l = \epsilon h(A^l, F^l),$$

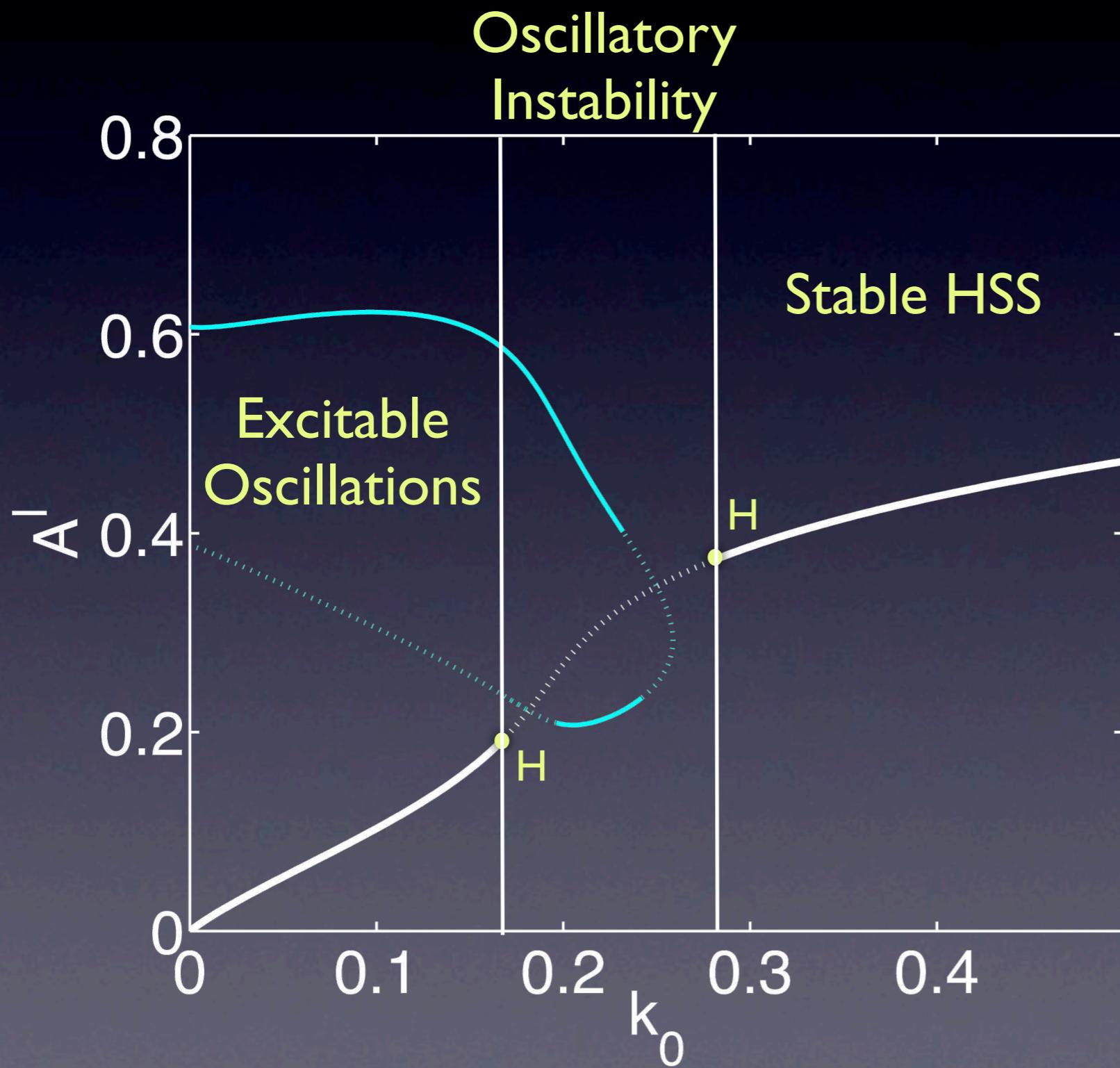
$$F_t^g = \epsilon h(A^g, F^g)$$

# Actin Wave LPA



- Branch Points are retained from wave pinning.
- Hopf bifurcations are new and indicate oscillations.

# Actin Wave LPA

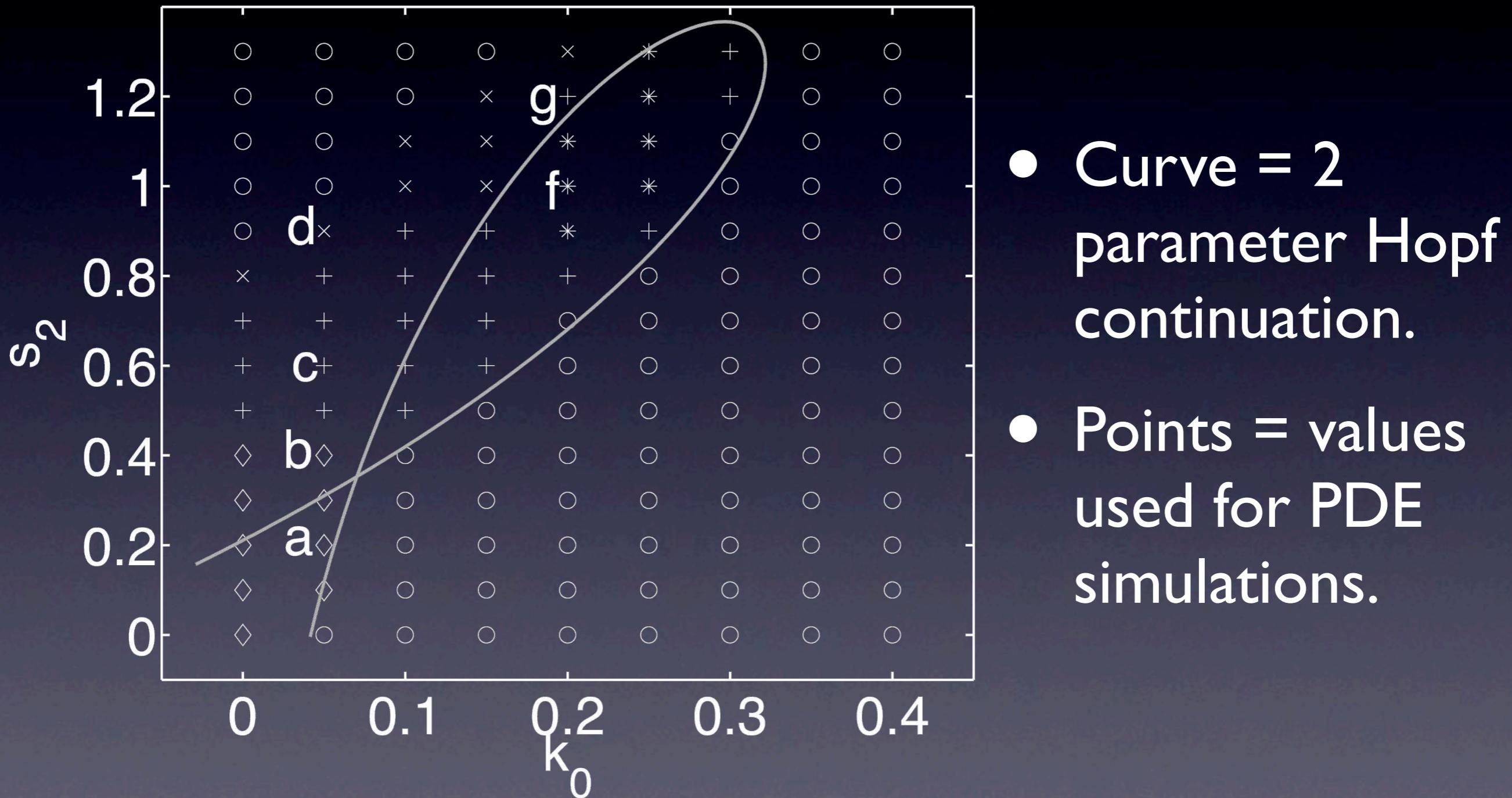


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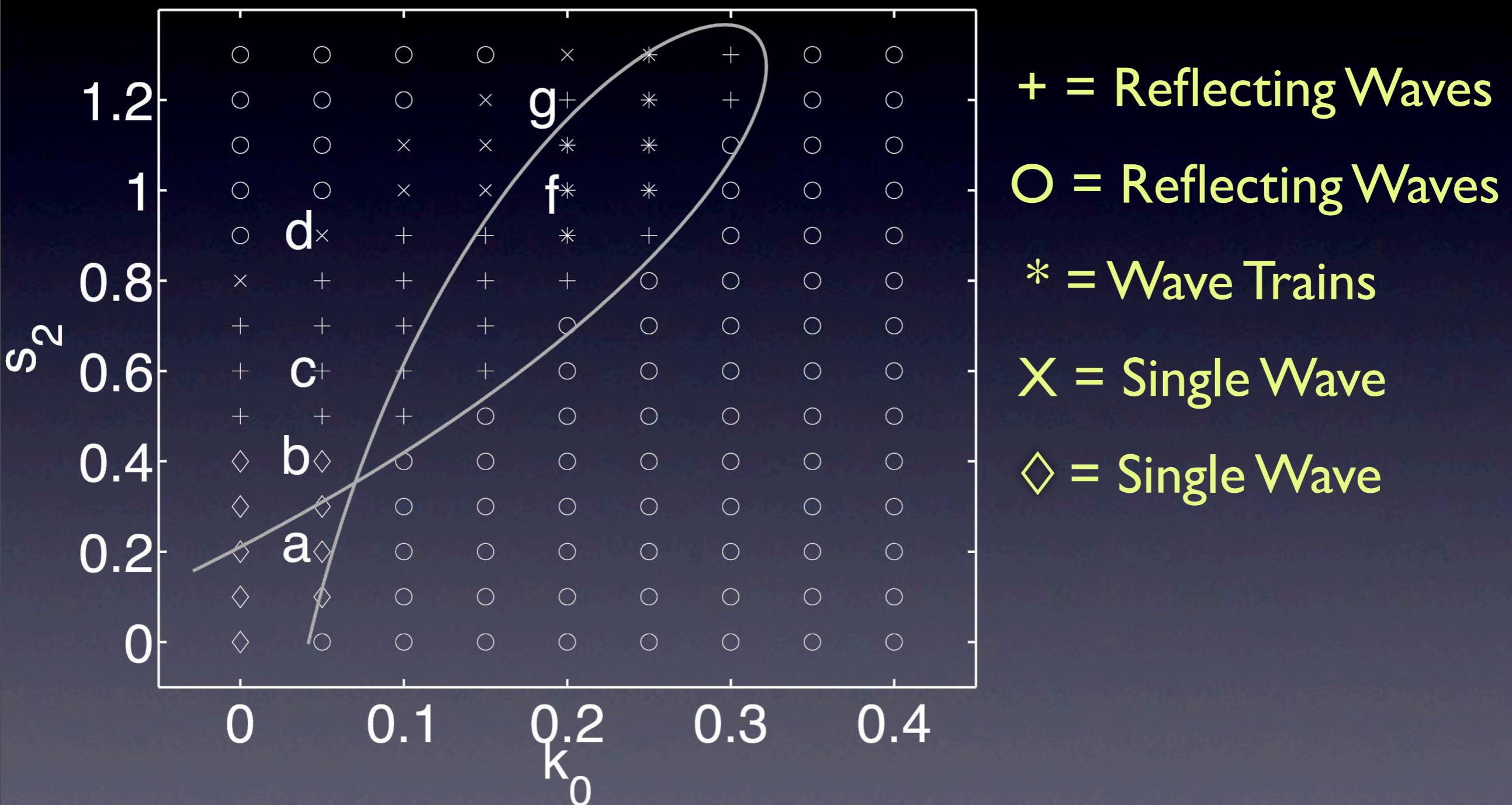
# Questions?

- How do the positive and negative feedback loops interact to initiate patterning?
- What role do they play in determining the resulting behaviour on a longer time scale?

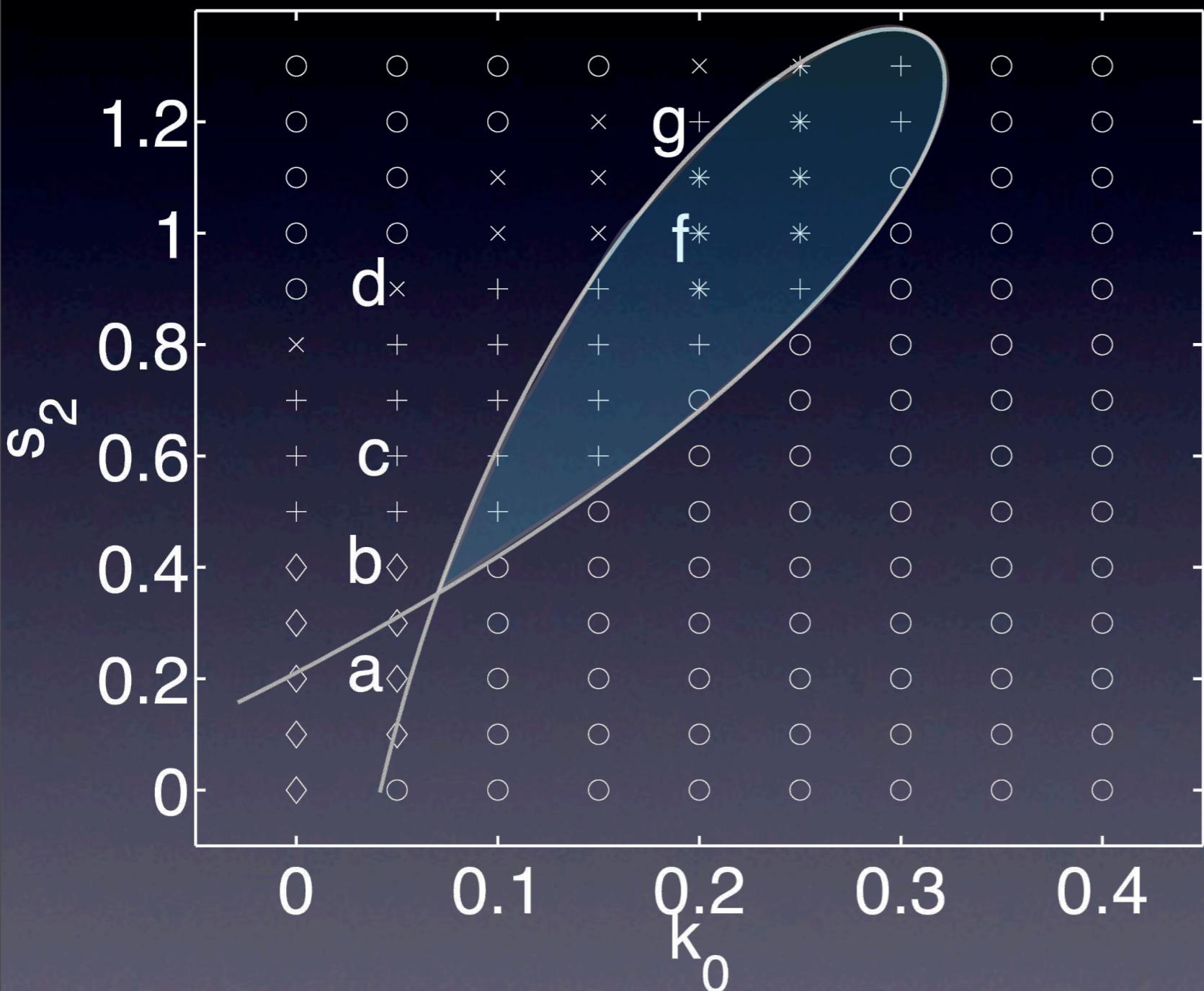
# LPA + Simulation



# LPA + Simulation

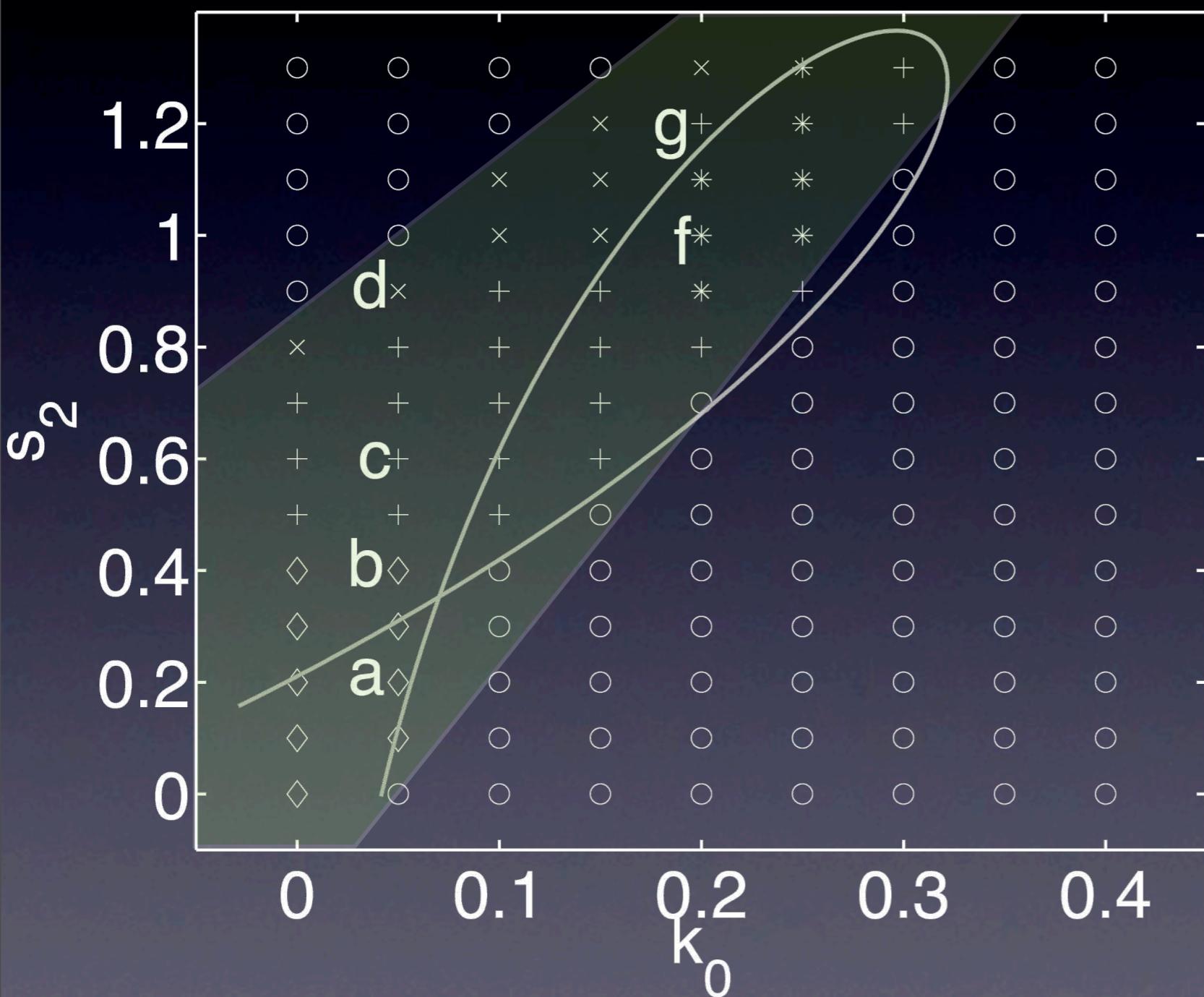


# LPA + Simulation



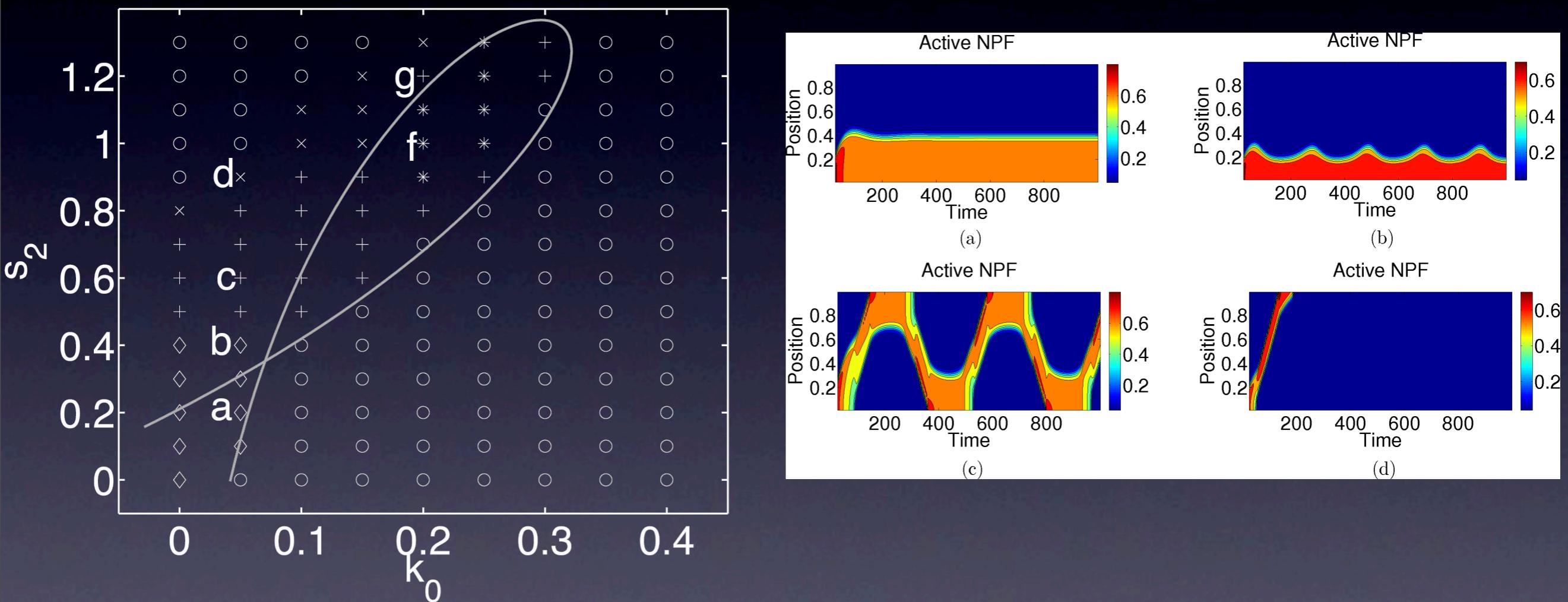
- Inside the fish tail, patterning arises from instability.
- Outside, from excitability.

# Patterning Region



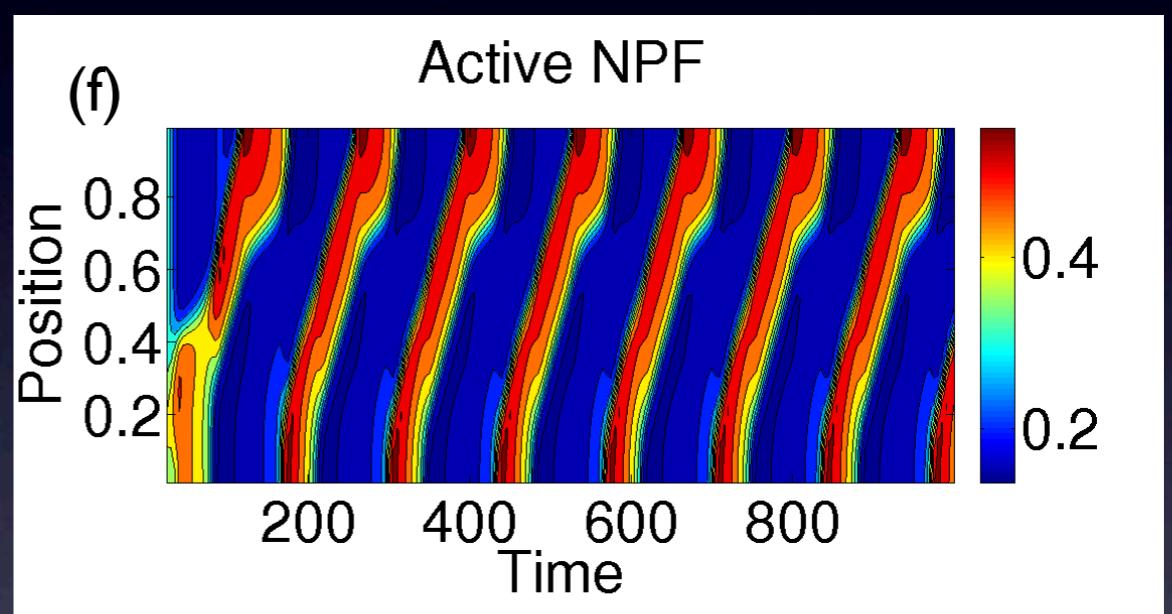
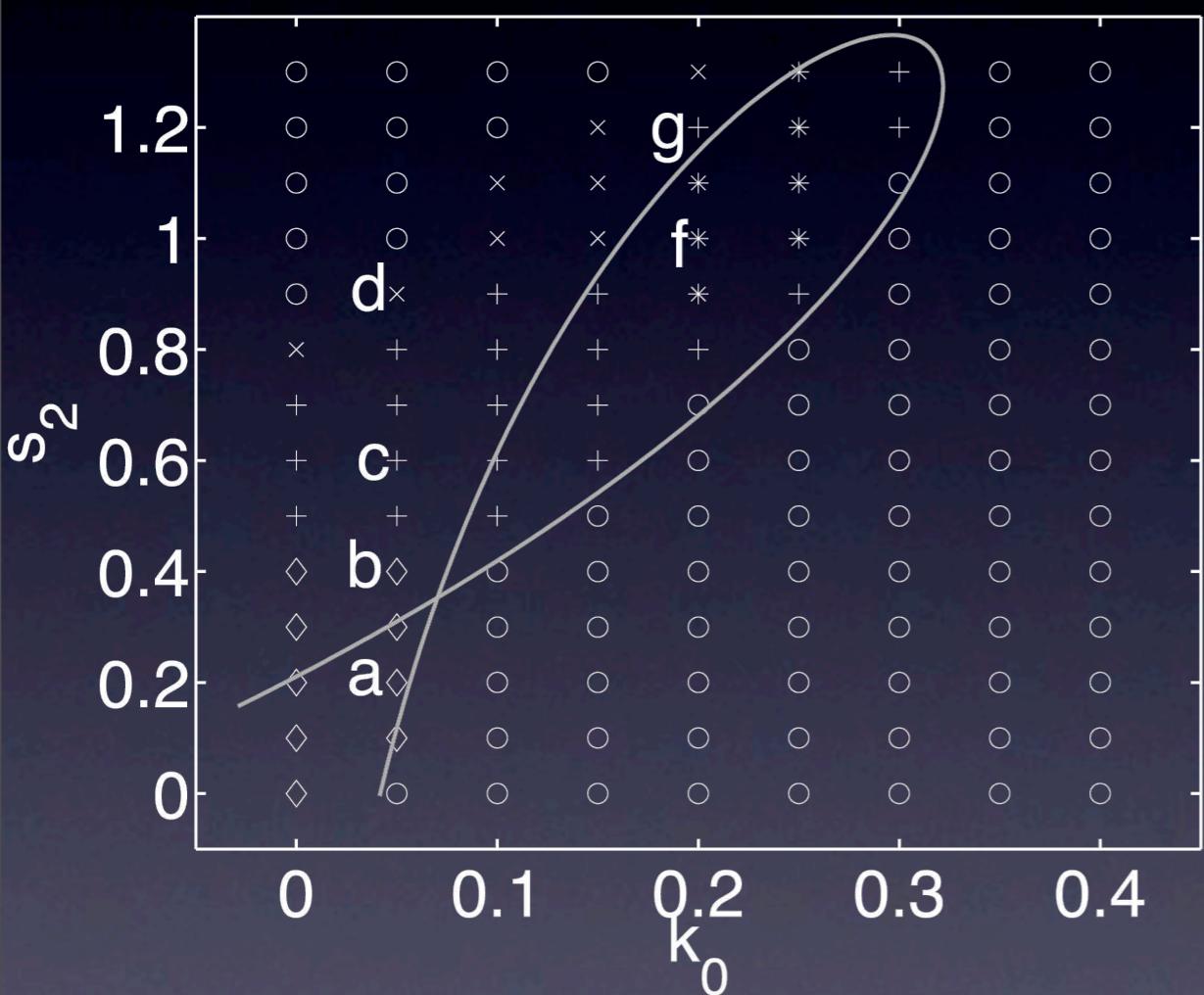
- Feedback is necessary for patterning, but too much suppresses it.

# Static to Dynamic Transition



- Increasing feedback yields a progression from static, to dynamic, to no patterning.

# Wave Trains

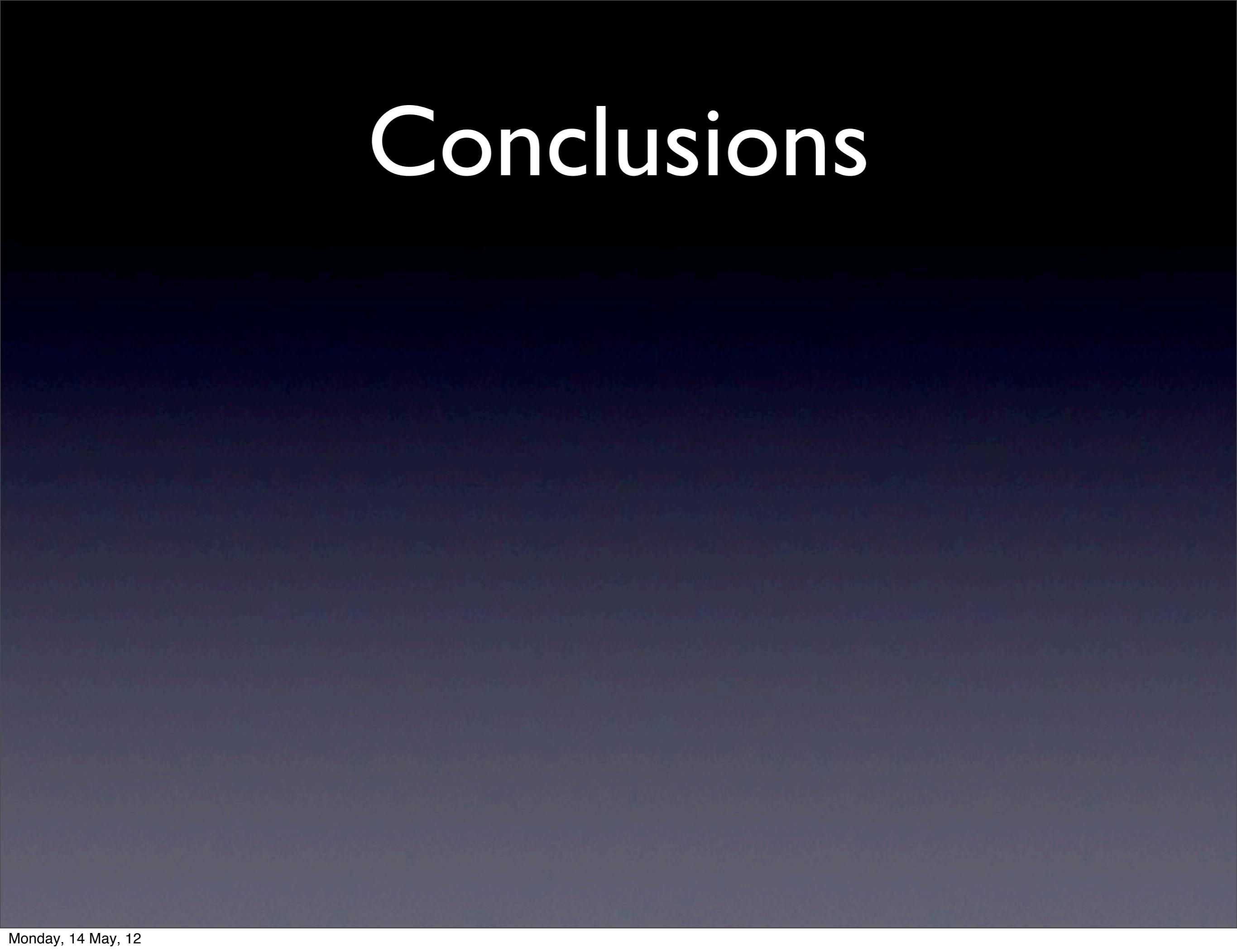


- Wave trains, indicative of target waves (in 2D), only occur inside the fish tail

# Conclusions

- GTPase like kinetics coupled with F-actin feedback is capable of producing a wealth of static and dynamic behaviours.

# Conclusions



# Conclusions

- The inclusion of a WP model (ie. conservation) as the ‘wave generator’ in the FitzHugh Nagumo framework yields substantially different behaviour.

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# Conclusions

- The inclusion of a WP model (ie. conservation) as the ‘wave generator’ in the FitzHugh Nagumo framework yields substantially different behaviour.
- Static to dynamic transition.
- Reflecting waves vs wave trains.
- Persistent patterning in excitable regimes.

# Conclusions

- Increasing levels of feedback lead to a transition from static to dynamic behaviour and finally to the suppression of all patterning.