Analysis of Algorithms, I CSOR W4231.002

Eleni Drinea Computer Science Department

Columbia University

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Outline

- 1 Recap
- 2 Binary search
- 3 Integer multiplication
- 4 Fast matrix multiplication
- 5 Quicksort

Today

- 1 Recap
- 2 Binary search
- 3 Integer multiplication
- 4 Fast matrix multiplication
- 5 Quicksort

Review of the last lecture

- Asymptotic notation $(O, \Omega, \Theta, o, \omega)$
- ► The divide & conquer principle
 - ▶ **Divide** the problem into a number of subproblems that are smaller instances of the same problem.
 - ▶ Conquer the subproblems by solving them recursively.
 - ▶ Combine the solutions to the subproblems into the solution for the original problem.
- ► Application: Mergesort
- Solving recurrences

Mergesort

```
\begin{aligned} & \text{Mergesort } (A, left, right) \\ & \text{if } right == left \ \text{then} \\ & \text{return} \\ & \text{end if} \\ & middle = left + \lfloor (right - left)/2 \rfloor \\ & \text{Mergesort } (A, left, middle) \\ & \text{Mergesort } (A, middle + 1, right) \\ & \text{Merge} (A, left, middle, right) \end{aligned}
```

- ▶ Initial call: Mergesort(A, 1, n)
- ▶ Subroutine Merge merges two sorted lists of sizes $\lceil n/2 \rceil$, $\lfloor n/2 \rfloor$ into one sorted list of size n in time $\Theta(n)$.

Running time of Mergesort

The running time of Mergesort satisfies:

$$T(n) = 2T(n/2) + cn$$
, for $n \ge 2$, constant $c > 0$
 $T(1) = c$

This structure is typical of recurrence relations:

- ▶ an inequality or equation bounds T(n) in terms of an expression involving T(m) for m < n
- ▶ a base case generally says that T(n) is constant for small constant n

Remarks

- ▶ We ignore floor and ceiling notations
- ▶ A recurrence does **not** provide an asymptotic bound for T(n): to this end, we must solve the recurrence

Solving recurrences, method 1: recursion trees

The technique consists of three steps

- 1. Analyze the first few levels of the tree of recursive calls
- 2. Identify a pattern
- 3. Sum over all levels of recursion

Example: analysis of running time of Mergesort

$$T(n) = 2T(n/2) + cn, n \ge 2$$

$$T(1) = c$$

A general recurrence and its solution

Often we can express the running time of a recursive algorithm by the following recurrence

$$T(n) = aT(n/b) + cn^k$$
, for $a, c > 0, b > 1, k \ge 0$

What is the recursion tree for this recurrence?

- \triangleright a is the branching factor
- \triangleright b is the factor by which the size of each subproblem shrinks
- \Rightarrow at level i, there are a^i subproblems, each of size n/b^i
- \Rightarrow each subproblem at level *i* requires $c(n/b^i)^k$ work
 - the height of the tree is $\log_b n$ levels
- \Rightarrow Total work: $\sum_{i=0}^{\log_b n} a^i c(n/b^i)^k = cn^k \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i$

Solving recurrences, method 2: Master theorem

Theorem 1 (Master theorem).

If $T(n) = aT(\lceil n/b \rceil) + O(n^k)$ for some constants $a > 0, b > 1, k \ge 0$, then

$$T(n) = \begin{cases} O(n^{\log_b a}) & \text{, if } a > b^k \\ O(n^k \log n) & \text{, if } a = b^k \\ O(n^k) & \text{, if } a < b^k \end{cases}$$

Example: running time of Mergesort

►
$$T(n) = 2T(n/2) + cn$$
:
 $a = 2, b = 2, k = 1, b^k = 2 = a \Rightarrow T(n) = O(n \log n)$

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Searching a sorted array

- ▶ **Input: sorted** list A of n integers, integer x
- ▶ Output:
 - 1. index j s.t. $1 \le j \le n$ and A[j] = x; or
 - 2. **no** if x is not in A

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Example:
$$A = \{0, 2, 3, 5, 6, 7, 9, 11, 13\}, n = 9, x = 7$$

Searching a sorted array

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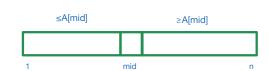
Idea: use the fact that the array is **sorted** and probe specific entries in the array.

Binary search

First, probe the middle entry. Let $mid = \lceil n/2 \rceil$.

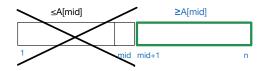
- If x == A[mid], return mid.
- ▶ If x < A[mid] then look for x in A[1, mid 1];
- ▶ Else if x > A[mid] look for x in A[mid + 1, n].

Initially, the entire array is "active", that is, x might be anywhere in the array.



Suppose x > A[mid].

Then the active area of the array, where x might be, is to the right of mid.



Binary search pseudocode

```
\begin{aligned} & \operatorname{binarysearch}(A, \operatorname{left}, \operatorname{right}) \\ & \operatorname{mid} = \operatorname{left} + \lceil (\operatorname{right} - \operatorname{left})/2 \rceil \\ & \text{if } A[\operatorname{mid}] == x \text{ then} \\ & \operatorname{return } \operatorname{mid} \\ & \text{else if } \operatorname{right} == \operatorname{left} \text{ then} \\ & \operatorname{return } \mathbf{no} \\ & \text{else if } A[\operatorname{mid}] < x \text{ then} \\ & \operatorname{left} = \operatorname{mid} + 1 \\ & \text{else } \operatorname{right} = \operatorname{mid} - 1 \\ & \text{end if} \\ & \operatorname{binarysearch}(A, \operatorname{left}, \operatorname{right}) \end{aligned}
```

Binary search running time

Observation: At each step there is a region of A where x could be and we **shrink** the size of this region by a factor of 2 with every probe:

- ▶ If n is odd, then we are throwing away $\lceil n/2 \rceil$ elements.
- ▶ If n is even, then we are throwing away at least n/2 elements.

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Hence the recurrence for the running time is

$$T(n) \le T(n/2) + O(1)$$

Sublinear running time

Here are two ways to argue about the running time:

- 1. Master theorem: $b = 2, a = 1, k = 0 \Rightarrow T(n) = O(\log n)$.
- 2. We can reason as follows:
 - Starting with an array of size n, after k probes, we are left with an array of size at most $\frac{n}{2^k}$ (since every time we probe an entry the active portion of the array halves).
 - ▶ Hence after $k = \log n$ probes, we are left with an array of **constant** size (i.e., O(1)). Now we can search **linearly** for x in the constant size array.

Concluding remarks on binary search

- 1. The right data structure can improve the running time of the algorithm significantly.
 - ▶ What if we used a **linked list** to store the input?
 - Arrays allow for **random access** of their elements: given an index, we can read any entry in an array in time O(1) (constant time)
- 2. In general, we obtain running time $O(\log n)$ when the algorithm does a **constant amount of work** to throw away a **constant fraction** of the input.

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Integer multiplication

- ▶ How do we multiply two integers x and y?
- ▶ Elementary school method: compute a partial product by multiplying every digit of *y* separately with *x* and then add up all the partial products.
- ▶ Remark: this method works the same in base 10 or base 2.

Examples: $(12)_{10} \cdot (11)_{10}$ and $(1100)_2 \cdot (1011)_2$

12	1100
× 11	× 1011
12 + 12 132	1100 1100 0000 + 1100 10000100

Elementary algorithm running time

A more reasonable model of computation: a **single** operation on a pair of digits (bits) is a primitive computational step.

Assume we are multiplying n-digit (bit) numbers.

- ightharpoonup O(n) time to compute a partial product.
- ightharpoonup O(n) time to combine it in a running sum of all partial products so far.
- \Rightarrow There are *n* partial products, each consisting of *n* bits, hence total number of operations is $O(n^2)$.

Can we do better?

A first divide & conquer approach

Consider n-digit decimal numbers x, y.

$$x = x_{n-1}x_{n-2}\dots x_0$$

$$y = y_{n-1}y_{n-2}\dots y_0$$

Idea: rewrite each number as the sum of the n/2 high-order digits and the n/2 low-order digits.

$$x = \underbrace{x_{n-1} \dots x_{n/2}}_{x_H} \underbrace{x_{n/2-1} \dots x_0}_{x_L} = x_H \cdot 10^{n/2} + x_L$$

$$y = \underbrace{y_{n-1} \dots y_{n/2}}_{y_H} \underbrace{y_{n/2-1} \dots y_0}_{y_L} = y_H \cdot 10^{n/2} + y_L$$

where each of x_H, x_L, y_H, y_L is an n/2-digit number.

Examples

n = 2, x = 12, y = 11

$$\underbrace{\frac{12}{x}}_{x} = \underbrace{\frac{1}{x_{H}} \cdot \underbrace{\frac{10^{1}}{10^{n/2}} + \underbrace{\frac{2}{x_{L}}}}_{y_{L}}$$

$$\underbrace{\frac{11}{y}}_{y} = \underbrace{\frac{1}{y_{H}} \cdot \underbrace{\frac{10^{1}}{10^{n/2}} + \underbrace{\frac{1}{y_{L}}}_{y_{L}}}_{y_{L}}$$

$$n = 4, x = 1000, y = 1110$$

$$\underbrace{1000}_{x} = \underbrace{10}_{x_{H}} \cdot \underbrace{10^{2}}_{10^{n/2}} + \underbrace{0}_{x_{L}}$$

$$\underbrace{1110}_{y} = \underbrace{11}_{y_{H}} \cdot \underbrace{10^{2}}_{10^{n/2}} + \underbrace{10}_{y_{L}}$$

A first divide & conquer approach

$$x \cdot y = (x_H 10^{n/2} + x_L) \cdot (y_H 10^{n/2} + y_L)$$

= $x_H y_H \cdot 10^n + (x_H y_L + x_L y_H) 10^{n/2} + x_L y_L$

In words, we reduced the problem of solving 1 instance of size n (i.e., one multiplication between two n-digit numbers) to the problem of solving 4 instances, each of size n/2 (i.e., computing the products $x_H y_H, x_H y_L, x_L y_H$ and $x_L y_L$).

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This is a divide and conquer solution!

- ▶ Recursively solve the 4 subproblems.
- ▶ Multiplication by 10^n is easy (**shifting**): O(n) time.
- ▶ Combine the solutions from the 4 subproblems to an overall solution using 3 additions on O(n)-digit numbers: O(n) time.

Karatsuba's observation

Running time: $T(n) \le 4T(n/2) + cn$

- ▶ by the Master Theorem: $T(n) = O(n^2)$
- ▶ no improvement

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However, if we only needed three n/2-digit multiplications, then by the Master theorem

$$T(n) \le 3T(n/2) + cn = O(n^{1.59}) = o(n^2).$$

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However, if we only needed three n/2-digit multiplications, then by the Master theorem

$$T(n) \le 3T(n/2) + cn = O(n^{1.59}) = o(n^2).$$

Recall that

$$x \cdot y = x_H y_H \cdot 10^n + (x_H y_L + x_L y_H) 10^{n/2} + x_L y_L$$

Key observation: we do not need each of $x_H y_L, x_L y_H$. We only need their sum, $x_H y_L + x_L y_H$.

Gauss's observation on multiplying complex numbers

A similar problem: multiply two complex numbers a+bi, c+di

$$(a+bi)(c+di) = ac + (ad+bc)i + bdi^{2}$$

Gauss's observation on multiplying complex numbers

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$$(a+bi)(c+di) = ac + (ad+bc)i + bdi^{2}$$

Gauss's observation: can be done with just 3 multiplications

$$(a+bi)(c+di) = ac + ((a+b)(c+d) - ac - bd)i + bdi^2,$$

at the cost of few extra additions and subtractions.

* Unlike multiplications, additions and subtractions of n-digit numbers are cheap: O(n) time!

Karatsuba's algorithm

$$x \cdot y = (x_H 10^{n/2} + x_L) \cdot (y_H 10^{n/2} + y_H)$$

= $x_H y_H \cdot 10^n + (x_H y_L + x_L y_H) 10^{n/2} + x_L y_L$

Similarly to Gauss's method for multiplying two complex numbers, compute only the three products

$$x_H y_H$$
, $x_L y_L$, $(x_H + x_L)(y_H + y_L)$

and obtain the sum $x_H y_L + x_L y_H$ from

$$(x_H + x_L)(y_H + y_L) - x_H y_H - x_L y_L = x_H y_L + x_L y_H.$$

Combining requires O(n) time hence

$$T(n) \le 3T(n/2) + cn = O(n^{\log_2 3}) = O(n^{1.59})$$

Pseudocode

Let k be a small constant.

```
Integer-Multiply(x, y)
  if n == k then
      return xy
  end if
  write x = x_H 10^{n/2} + x_L, y = y_H 10^{n/2} + y_L
  compute x_H + x_L, y_H + y_L
  product = Integer-Multiply(x_H + x_L, y_H + y_L)
  x_H y_H = \text{Integer-Multiply}(x_H, y_H)
  x_L y_L = \text{Integer-Multiply}(x_L, y_L)
  return x_H y_H 10^n + (product - x_H y_H - x_L y_L) 10^{n/2} + x_L y_L
```

Concluding remarks

- ➤ To reduce the number of multiplications we do few more additions/subtractions: these are fast compared to multiplications.
- ▶ There is no reason to continue with recursion once n is small enough: the conventional algorithm is probably more efficient since it uses fewer additions.
- ▶ When we recursively compute $(x_H + x_L)(y_H + y_L)$, each of $x_H + x_L$, $y_H + y_L$ might be (n/2 + 1)-digit integers. This does not affect the asymptotics.

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Fast matrix multiplication

Matrix multiplication: a fundamental primitive in numerical linear algebra, scientific computing, machine learning and large-scale data analysis.

- ▶ Input: $m \times n$ matrix A, $n \times p$ matrix B
- Output: $m \times p$ matrix C = AB

Example:
$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, B = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, C = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Lower bounds on matrix multiplication algorithms for $m, p = \Theta(n)$?

Conventional matrix multiplication

```
\begin{array}{l} \mathbf{for} \ 1 \leq i \leq m \ \mathbf{do} \\ \mathbf{for} \ 1 \leq j \leq p \ \mathbf{do} \\ c_{i,j} = 0 \\ \mathbf{for} \ 1 \leq k \leq n \ \mathbf{do} \\ c_{i,j} + = a_{i,k} \cdot b_{k,j} \\ \mathbf{end} \ \mathbf{for} \\ \mathbf{end} \ \mathbf{for} \\ \mathbf{end} \ \mathbf{for} \\ \mathbf{end} \ \mathbf{for} \\ \end{array}
```

- ► Running time?
- ► Can we do better?

A first divide & conquer approach: 8 subproblems

Assume square A, B where $n = 2^k$ for some k > 0. **Idea:** express A, B as 2×2 block matrices and use the conventional algorithm to multiply the two block matrices.

$$\begin{pmatrix} \overbrace{A_{11}}^{n/2 \times n/2} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix} = \begin{pmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{pmatrix}$$

where

$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22}$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21}$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$

Running time?

Strassen's breakthrough: 7 subproblems suffice (part 1)

Compute the following ten $n/2 \times n/2$ matrices.

1.
$$S_1 = B_{11} - B_{22}$$

2.
$$S_2 = A_{11} + A_{12}$$

3.
$$S_3 = A_{21} + A_{22}$$

4.
$$S_4 = B_{21} - B_{11}$$

$$5. S_5 = A_{11} + A_{22}$$

6.
$$S_6 = B_{11} + B_{22}$$

7.
$$S_7 = A_{12} - A_{22}$$

8.
$$S_8 = B_{21} + B_{22}$$

9.
$$S_9 = A_{11} - A_{21}$$

10.
$$S_{10} = B_{11} + B_{12}$$

Running time?

Strassen's breakthrough: 7 subproblems suffice (part 2)

Compute the following seven products of $n/2 \times n/2$ matrices.

- 1. $P_1 = A_{11}S_1$
- 2. $P_2 = S_2 B_{22}$
- 3. $P_3 = S_3 B_{11}$
- 4. $P_4 = A_{22}S_4$
- 5. $P_5 = S_5 S_6$
- 6. $P_6 = S_7 S_8$
- 7. $P_7 = S_9 S_{10}$

Compute C as follows:

- 1. $C_{11} = P_4 + P_5 + P_6 P_2$
- $2. C_{12} = P_1 + P_2$
- 3. $C_{21} = P_3 + P_4$
- 4. $C_{22} = P_1 + P_5 P_3 P_7$

Running time?

Strassen's running time and concluding remarks

- Recurrence: $T(n) = 7T(n/2) + cn^2$
- ▶ By the Master theorem:

$$T(n) = O(n^{\log_2 7}) = O(n^{2.81})$$

▶ Recently, there is renewed interest in Strassen's algorithm for **high-performance computing**: thanks to its lower communication cost (number of bits exchanged between machines in the network or data center), it is better suited than the traditional algorithm for multi-core processors.

Today

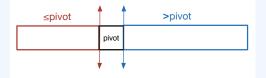
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Quicksort facts

- Quicksort is a divide and conquer algorithm
- ▶ It is the standard algorithm used for sorting
- ▶ It is an **in-place** algorithm
- ▶ Its worst-case running time is $\Theta(n^2)$ but its average-case running time is $\Theta(n \log n)$
- ▶ We will use it to introduce **randomized** algorithms

Quicksort: main idea

- ▶ Pick an input item, call it *pivot*, and place it in its final location in the sorted array by re-organizing the array:
 - ▶ all items $\leq pivot$ are placed before pivot
 - ightharpoonup all items > pivot are placed after pivot



- Recursively sort the subarray to the left of pivot (items $\leq pivot$).
- Recursively sort the subarray to the right of pivot (items > pivot).

Remark: I haven't explained how to pick *pivot*.

Quicksort pseudocode

```
\begin{aligned} &\textbf{Quicksort}(A, left, right) \\ &\textbf{if} \ |A| = 0 \ \textbf{then} \ \text{return} \qquad //A \ \text{is empty} \\ &\textbf{end if} \\ &split = \texttt{Partition}(A, left, right) \\ &\texttt{Quicksort}(A, left, split - 1) \\ &\texttt{Quicksort}(A, split + 1, right) \end{aligned}
```

Initial call: Quicksort(A, 1, n)

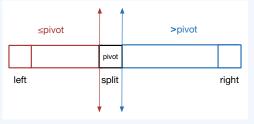
${ m Subroutine} \ { t Partition}(A, left, right)$

Notation: A[i, j] denotes the portion of A starting at position i and ending at position j.

Partition

- 1. picks a pivot item
- 2. re-organizes A[left, right] so that
 - ▶ all items before pivot are $\leq pivot$
 - ightharpoonup all items after pivot are > pivot
- 3. returns *split*, the index of *pivot* in the re-organized array

After Partition, A[left, right] looks as follows:



Implementing Partition

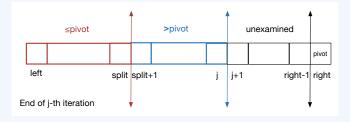
- 1. Pick a *pivot* item: for simplicity, always pick the last item of the array as pivot, i.e., pivot = A[right].
 - ► Thus A[right] will be placed in its final location when Partition returns and will never be used (or moved) again until the algorithm terminates.
- 2. Re-organize the input array A in place.

(What if we didn't care to implement Partition in place?)

Implementing Partition in place

Partition examines the items in A[left, right] one by one and maintains three regions in A. Specifically, after examining the j-th item for $j \in [left, right - 1]$, the regions are:

- 1. First region: starts at A[left] and ends at A[split]; it contains all items examined so far that are $\leq pivot$.
- 2. Second region: starts at A[split+1] and ends at A[j]; it contains all items > pivot examined so far;
- 3. Third region: starts at A[j+1] and ends at A[right-1]; it contains all items yet to be examined.



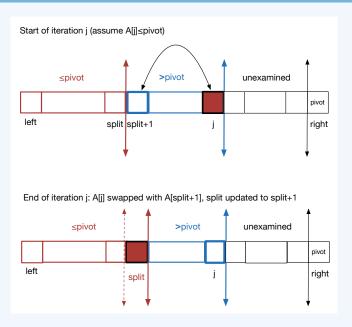
Implementing Partition in place (cont'd)

At the beginning of iteration j, A[j] is compared with pivot.

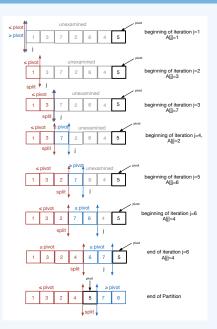
If $A[j] \leq pivot$

- 1. swap A[j] with A[split+1], the first element of the second region: since A[split+1] > pivot, it's "safe" to move it to the end of the second region (recall that the second region ends at position j after examining the j-th item);
- 2. increment split to include A[j] in the first region, where all items are $\leq pivot$ (recall that the first region ends at split).

Iteration j, when $A[j] \leq pivot$



Example: $A = \{1, 3, 7, 2, 6, 4, 5\}$, Partition(A, 1, 7)



Pseudocode for Partition

```
Partition(A, left, right)
  pivot = A[right]
  split = left - 1
  for j = left to right - 1 do
      if A[j] \leq pivot then
         swap(A[j], A[split + 1])
         split = split + 1
      end if
  end for
  \operatorname{swap}(pivot, A[split+1]) //place pivot after A[split] (why?)
  return split + 1
                                //the final position of pivot
```

Analysis of Partition: correctness

Notation: A[a, ..., b] denotes the portion of A starting at position a and ending at position b.

Claim 1.

For $left \leq j \leq right - 1$, at the end of loop j, all items from A[left, j] that appear in

- 1. A[left, split] are less or equal to pivot
- 2. A[split + 1, j] are greater than pivot

Remark: If the claim is true, correctness of Partition follows (why?).

Proof of Claim 1

By induction on j.

- 1. Base case: For j = left (that is, during the first execution of the for loop), there are two possibilities:
 - ▶ if $A[left] \leq pivot$, then A[left] is swapped with itself and split is incremented to equal left;
 - ▶ otherwise, nothing happens.

In both cases, the claim holds for j = left.

- 2. **Hypothesis:** Assume that the claim is true for some $left \leq j < right 1$.
 - ▶ That is, at the end of loop j, all items in A[left, split] are $\leq pivot$ and all items in A[split+1, j] are > pivot.

Proof of Claim 1 (cont'd)

3. Step: We will show the claim for j + 1.

Thus we will show that after loop j+1, all items in A[left, split] are $\leq pivot$ and all items in A[split+1, j+1] are > pivot.

- ▶ At the beginning of loop j+1, by the hypothesis, items in A[left, split] are $\leq pivot$ and items in A[split+1, j] are > pivot.
- ▶ Inside loop j + 1, there are two possibilities:
 - 1. $A[j+1] \leq pivot$: then A[j+1] is swapped with A[split+1]. At this point, items in A[left, split+1] are $\leq pivot$ and items in A[split+2, j+1] are > pivot. Incrementing split (the next step in the pseudocode) yields that the claim holds for j+1.
 - 2. A[j+1] > pivot: nothing is done. The truth of the claim follows from the hypothesis.

This completes the proof of the inductive step.

Analysis of Partition: running time and space

- ▶ Running time: on input size n, Partition goes through each of the n-1 leftmost elements once and performs constant amount of work per element
 - \Rightarrow Partition requires $\Theta(n)$ time.
- ▶ **Space:** in-place algorithm