# Baiyu Shi

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## RESEARCH INTERESTS

**Robotics**: Chemical and Haptics Sensing, Human-robot Interaction, Medical Robotics, Robot Learning and Manipulation. **Wellness Monitoring**: Biosensors, BioMEMS, Wearables.

#### **EDUCATION**

Stanford University

Stanford, CA

1st year PhD. In Mechanical Engineering

September 2023 - Present

- GPA: **4.187/4.3**.
- Advisor: Professor Zhenan Bao

University of California, Berkeley

Berkeley, CA

B.S. Bioengineering, Electrical Engineering and Computer Science (High Honors)

September 2019 - May 2023

- GPA: **3.965**/4.00.
- Advisors: Professor Robert J. Full, Professor Ken Goldberg, and Professor Gerard Marriott.
- Awards: UC Berkeley **Departmental Citation** in Bioengineering, 2023 Outstanding Graduate Student Instructor.

#### **PUBPLICATION**

#### [4] Bagging by Learning to Singulate Layers Using Interactive Perception.

Lawrence Yunliang Chen, Baiyu Shi, Roy Lin, Daniel Seita, Ayah Ahmad, Richard Cheng, Thomas Kollar, David Held,

Ken Goldberg. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), October 2023, Detroit, USA.

# [3] A Trimodal Framework for Robot-Assisted Vascular Shunt Insertion When a Supervising Surgeon is Local, Remote, or Unavailable.

Karthik Dharmarajan\*, Will Panitch\*, **Baiyu Shi**, Huang Huang, Lawrence Yunliang Chen, Thomas Low, Danyal Fer,

Ken Goldberg. IEEE International Symposium on Medical Robotics (ISMR), April 2023, Atlanta, USA.

# [2] AutoBag: Learning to Open Plastic Bags and Insert Objects.

Lawrence Yunliang Chen, Baiyu Shi, Daniel Seita, Richard Cheng, Thomas Kollar, David Held, Ken Goldberg.

IEEE International Conference on Robotics and Automation (ICRA), May 2023, London, UK.

# [1] Automating Vascular Shunt Insertion with the dVRK Surgical Robot.

Karthik Dharmarajan\*, Will Panitch\*, Muyan Jiang, Kishore Srinivas, **Baiyu Shi**, Yahav Avigal, Huang Huang, Thomas Low, Danyal Fer, Ken Goldberg. *IEEE International Conference on Robotics and Automation (ICRA)*, May 2023, London, UK.

# **WORK & TEACHING EXPERIENCE**

# Shanghai View Precision Machinery Co.

Shanghai, China

Jan 2021- Mar 2021

# Role: Mechanical Engineer Intern in Mold Design and Quality Control

- Designed molds via AutoCAD for cold forging presses and coded Mazak CNC machines to manufacture gears in electrical tools.
- Conducted metallographic analysis to examine the quality of heat treatment.

#### BioE 163 & BioE 163L Principles of Molecular and Cellular Biophotonics

Role: Graduate Student Instructor (GSI)

Aug 2022 - May 2023

Berkeley, CA

- Led weekly discussions of 30 students covering lecture contents, worksheets, and relevant publications.
- Helped design lab procedures, prepare chemicals, and introduced wet lab experiments on biosensor development.
- Drafted and graded assignments on Gradescope.

## PROFESSIONAL SERVICE

Conference Reviewer for IEEE International Conference on Robotics and Automation (ICRA), 2023 and IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023

#### **SKILLS**

- **Programming Languages (descending proficiency):** Python, MATLAB, ROS, C++, Java, HTML & CSS, R.
- Software: AutoCAD, COMSOL, ImageJ, LaTeX, SolidWorks.
- **Skills:** BioMEMS Design and Fabrication, Circuit Design, CNC Fabrication, ELISA, Fluorescence Microscopy, Metallographic Analysis, PCR, Western Blots, 3D printing.

#### **ACTIVITIES**

#### Berkeley Showcase Volunteer

Berkeley, CA, Oct.8th

• Conducted robotics demos for Bay Area/Northern California students who are underrepresented, first generation, or attending an under-resourced school.