TTIC 31230 Fundamentals of Deep Learning, winter 2020 ${\it Quiz~2}$

In these problems capital letter indeces are used to indicate subtensors (slices) so that, for example, M[I, J] denotes a matrix while M[i, j] denotes one element of the matrix, M[i, J] denotes the *i*th row, and M[I, j] denotes the *j*th collumn.

Throughout these problems we assume a word embedding matrix e[W, I] where e[w, I] is the word vector for word w. We then have that $e[w, I]^{\top}h[t, I]$ is the inner product of the word vector w[w, I] and the hidden state vector h[t, I].

We will adopt the convention, similar to true Einstein notation, that repeated capital indeces in a product of tensors are implicitly summed. We can then write the inner product $e[w, I]^{\top} h[t, I]$ simply as e[w, I] h[t, I] without the need for the (meaningless) transpose operation.

The batch index is ommitted in all equations in this quiz.

Problem 1. Image captioning as translation with attention. We consider a simple version of machine translation with attention. We first run a right-to-left (backward) RNN on the input sentence to get a sequence $\bar{h}[T_{\rm in}, J]$ of hidden vectors $\bar{h}[t, J]$ for $1 \leq t \leq T_{\rm in}$ where $T_{\rm in}$ is the length of the input sentence. We then define an autoregressive conditional language model

$$P_{\Phi}(w_1,\ldots,w_{T_{\mathrm{out}}}\mid \overleftarrow{h}[T_{\mathrm{in}},J])$$

as follows.

$$\vec{h}[0,J] = \overleftarrow{h}[1,J]$$

for t from 1 to T_{out}

$$\begin{array}{lcl} P(w_t \mid w_0, \cdots, w_{t-1}) & = & \operatorname{softmax} \ e[w_t, I] W^{\operatorname{auto}}[I, J] \vec{h}[t-1, J] \\ \\ & \alpha[t_{\operatorname{in}}] & = & \operatorname{softmax} \ h[t-1, J_1] W^{\operatorname{key}}[J_1, J_2] \overleftarrow{h}[t_{\operatorname{in}}, J_2] \\ \\ & V[J] & = & \sum_{t_{\operatorname{in}}} \alpha[t_{\operatorname{in}}] \overleftarrow{h}[t_{\operatorname{in}}, J] \\ \\ & \vec{h}[t, J] & = & \operatorname{CELL}_{\Phi}(\vec{h}[t-1, J], \ V[J], \ e[w_t, I]) \end{array}$$

Here CELL is some function taking (objects for) two vectors of dimensions J and one vector of dimension I and returning (an object for) a vector of dimension J.

Rewrite these equations for image captioning where instead of $\bar{h}[t_{\rm in},J]$ we are given an image feature tensor L[x,y,J]

Solution:

$$P_{\Phi}(w_1,\ldots,w_{T_{\mathrm{out}}}\mid L[X,Y,J])$$

$$\vec{h}[0,J] = \frac{1}{XY} \sum_{x,y} L[x,y,J]$$
 Any function of the image gets full credit

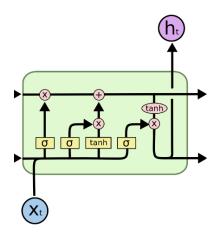
for t from 1 to T_{out}

$$\begin{array}{lcl} P(w_t \mid w_0, \cdots, w_{t-1}) & = & \operatorname{softmax} \ e[w_t, I] \ W^{\operatorname{auto}}[I, J] \ \vec{h}[t-1, J] \\ \\ & \alpha[x, y] & = & \operatorname{softmax} \ h[t-1, J_1] W^{\operatorname{key}}[J_1, J_2] \ L[x, y, J_2] \\ \\ & V[J] & = & \sum_{x, y} \alpha[x, y] L[x, y, J] \\ \\ & \vec{h}[t, J] & = & \operatorname{CELL}_{\Phi}(\vec{h}[t-1, J], \ V[J], \ e[w_t, I]) \end{array}$$

Problem 2. Translating diagrams into equations. A UGRNN cell for computing h[t, J] from h[t-1, J] and x[t, J] can be written as

$$\begin{split} G[t,j] &= \sigma \left(W^{h,G}[j,\tilde{J}] h[t-1,\tilde{J}] + W^{x,G}[j,K] x[t,K] - B^G[j] \right) \\ R[t,j] &= \tanh \left(W^{h,R}[j,\tilde{J}] h[t-1,\tilde{J}] + W^{x,R}[j,K] x[t,K] - B^R[j] \right) \\ h[t,j] &= G[t,j] h[t-1,j] + (1-G[t,j]) R[t,j] \end{split}$$

Modify the above equations so that they correspond to the following diagram for an LSTM.



The top line in the diagram is the "carry vector" c_t . The equations for an LSTM should define h[t,j] and c[t,j] in terms of h[t-1,J], c[t-1,J] and x[t,K].

Solution:

$$G_{1}[t,j] = \sigma \left(W^{h,G_{1}}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,G_{1}}[j,K]x[t,K] - B^{G_{1}}[j] \right)$$

$$G_{2}[t,j] = \sigma \left(W^{h,G_{2}}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,G_{2}}[j,K]x[t,K] - B^{G_{2}}[j] \right)$$

$$G_{3}[t,j] = \sigma \left(W^{h,G_{3}}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,G_{3}}[j,K]x[t,K] - B^{G_{3}}[j] \right)$$

$$R_{c}[t,j] = \tanh \left(W^{h,c}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,c}[j,K]x[t,K] - B^{c}[j] \right)$$

$$c[t,j] = G_{1}[t,j]c[t-1,j] + G_{2}[t,j]R_{c}[t,j]$$

$$R_{h}[t,j] = \tanh \left(W^{c,h}[j,\tilde{J}]c[t,\tilde{J}] - B^{h}[j] \right)$$

$$h[t,j] = G_{3}[t,j]R_{h}[t,j]$$

Problem 3. Gated CNNs

Again, A UGRNN is defined by the following equations.

$$\begin{split} G[t,j] &= \sigma(W^{h,G}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,G}[j,k]x_t[t,k] - B^G[j]) \\ R[t,j] &= \tanh(W^{h,R}[j,\tilde{J}]h[t-1,\tilde{J}] + W^{x,R}[j,K]x[t,K] - B^R[j]) \\ h[t,j] &= G[t,j]h[t-1,j] + (1-G[t,j])R[t,j] \end{split}$$

Modify these to form a data-dependent data-flow CNN for vision — an Update-Gate CNN (UGCNN). More specifically, give equations analogous to those for UGRNN for computing a CNN "box" $L_{\ell+1}[x,y,j]$ from $L_{\ell}[x,y,i]$ (stride 1) using a computed "gate box" $G_{\ell+1}[x,y,j]$ and an "update box" $R_{\ell+1}[x,y,j]$. In the CNN case there is no x[t,I], just the previous layer $L_{\ell}[x,y,J]$.

Solution:

$$R_{\ell+1}[x,y,j] = \tanh(W_{\ell+1}^{L,R}[\Delta X, \Delta Y, I, j] L_{\ell}[x + \Delta X, y + \Delta Y, I] - B_{\ell+1}^{R}[j])$$

$$G_{\ell+1}[x,y,j] = \sigma(W_{\ell+1}^{L,G}[\Delta X, \Delta Y, I, j] L_{\ell}[x + \Delta X, y + \Delta Y, I] - B_{\ell+1}^{G}[j])$$

$$L_{\ell+1}[x,y,j] = G_{\ell+1}[x,y,j]L_{\ell}[x,y,j] + (1 - G_{t}[x,y,j])R_{t}[x,y,j]$$

Problem 4. Variance of running averages. For two independent random variables x and y and a weighted sum s = ax + by we have

$$\sigma_s^2 = a^2 \sigma_x^2 + b^2 \sigma_y^2$$

Now consider a runing average for computing $\hat{\mu}_1, \dots, \hat{\mu}_t$ from x_1, \dots, x_t

$$\mu_0 = 0$$

$$\hat{\mu}_t = \left(1 - \frac{1}{N}\right)\hat{\mu}_{t-1} + \frac{1}{N}x_t$$

(a) Assume that the values of x_t are independent and identically distributed with variance σ_x^2 . We now have that $\hat{\mu}_t$ is a random variable depending on the draws of x_t . The random variable $\hat{\mu}_t$ has a variance $\sigma_{\hat{\mu},t}^2$. Assume that as $t \to \infty$ we have that $\sigma_{\hat{\mu},t}^2$ converges to a limit (it does). Solve for this limit $\sigma_{\hat{\mu},\infty}^2$. Your solution should yield that for N=1 we have $\sigma_{\hat{\mu},\infty}^2=\sigma_x^2$ (a sanity check).

Solution: The limit must satisfy

$$\sigma_{\hat{\mu},\infty}^2 = \left(1 - \frac{1}{N}\right)^2 \sigma_{\hat{\mu},\infty}^2 + \frac{1}{N^2} \sigma_x^2$$

We can then solve for $\sigma^2_{\hat{\mu},\infty}$

$$\begin{split} \sigma_{\hat{\mu},\infty}^2 &= \left(1 - \frac{2}{N} + \frac{1}{N^2}\right) \sigma_{\hat{\mu},\infty}^2 + \frac{1}{N^2} \sigma_x^2 \\ 0 &= \left(\frac{-2}{N} + \frac{1}{N^2}\right) \sigma_{\hat{\mu},\infty}^2 + \frac{1}{N^2} \sigma_x^2 \\ &= \left((-2) + \frac{1}{N}\right) \sigma_{\hat{\mu},\infty}^2 + \frac{1}{N} \sigma_x^2 \\ \sigma_{\hat{\mu},\infty}^2 &= \frac{1}{(2 - \frac{1}{N}) N} \sigma_x^2 \end{split}$$

(b) Compare your answer to (a) with the variance of an average of N values of x_t defined by

$$\hat{\mu} = \frac{1}{N} \sum_{t=1}^{N} x_t$$

Solution: For an average of N we have $\sigma_{\hat{\mu}}^2 = \sigma_x^2/N$. For N large we have that the answer to part (a) is about half as large.