

Calibration results

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Camera-system parameters:

cam0 (/camera/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.06812024 -0.08957874 -0.00033661 0.00061771] +- [0.01770054 0.1548021 0.00128229 0.00137083]

projection: [990.36694836 989.98507375 488.05741955 294.53444673] +- [14.50476626 14.50105107 6.42401905 6.07887824]

reprojection error: [-0.000001, 0.000001] +- [0.182244, 0.160726]

Target configuration

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Type: aprilgrid

Tags:

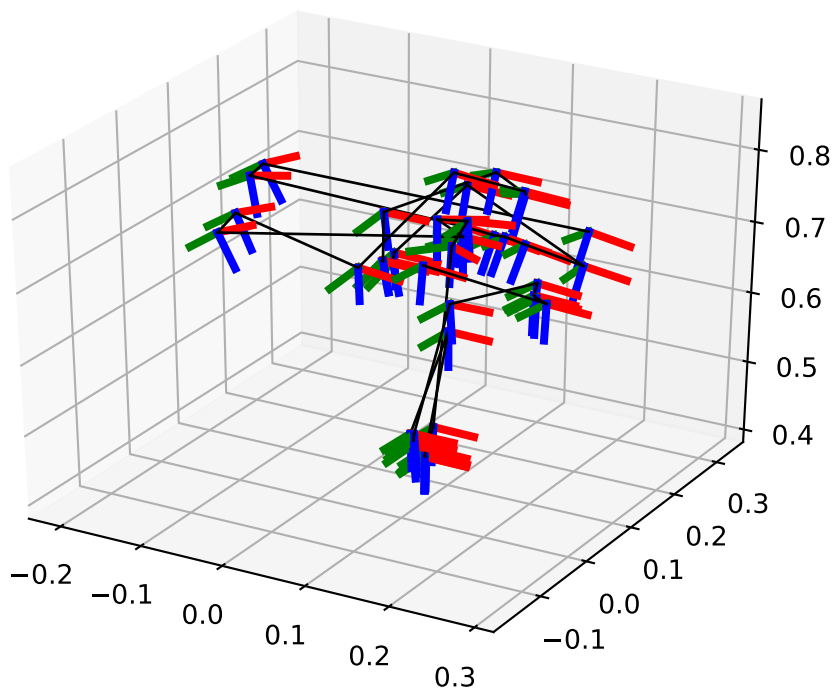
Rows: 6

Cols: 6

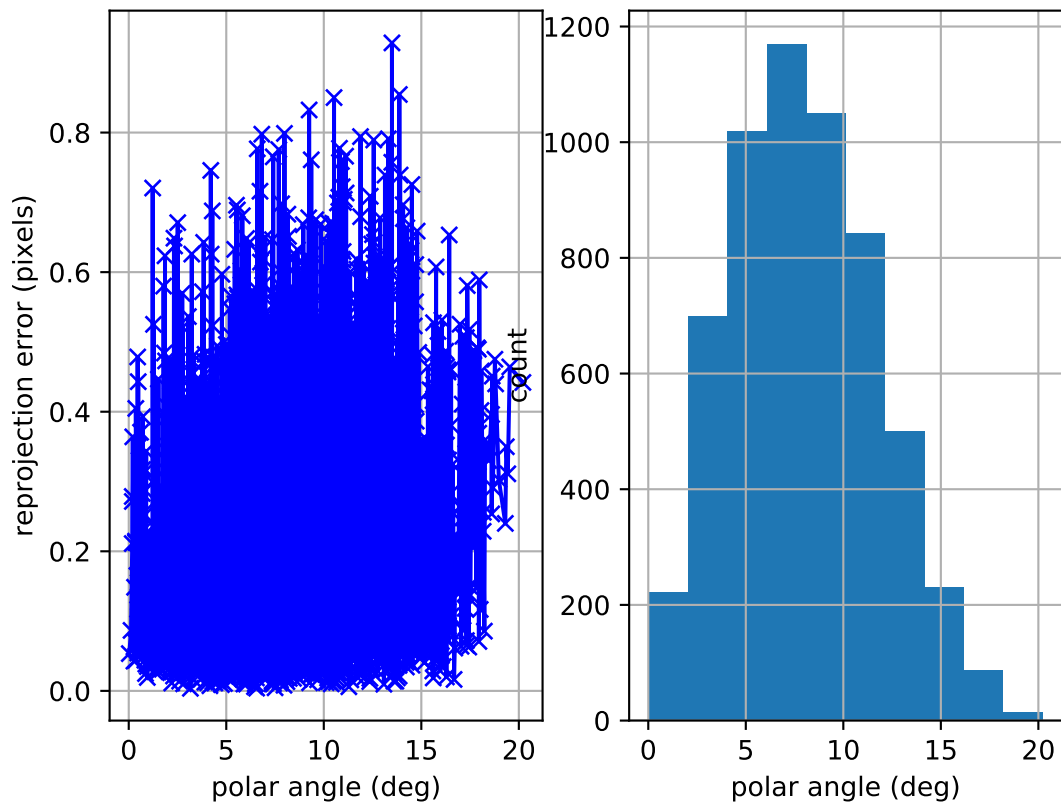
Size: 0.02 [m]

Spacing 0.006 [m]

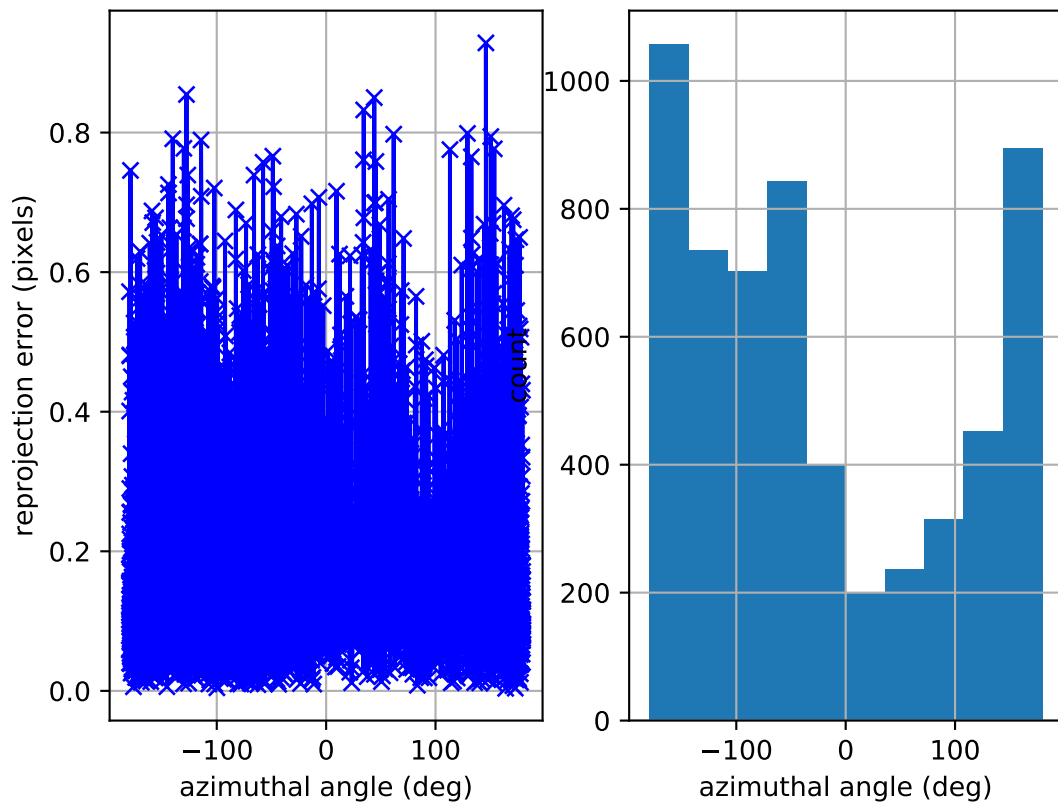
cam0: estimated poses



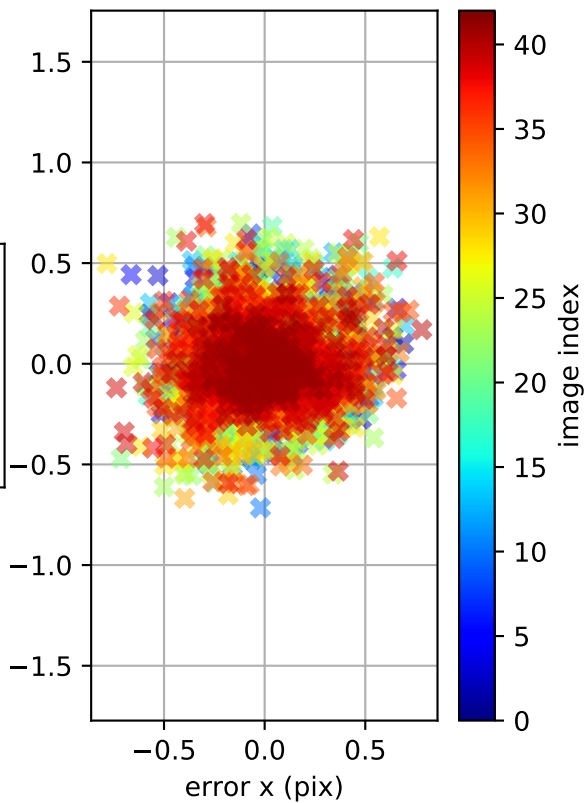
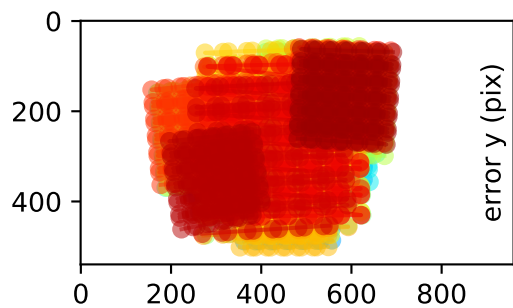
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

