

Calibration results

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Camera-system parameters:

cam0 (/camera/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.06347756 -0.02115002 0.00016724 0.00192058] +- [0.01510409 0.08816247 0.00121859 0.00127179]

projection: [1336.42426316 1335.99784892 654.70062799 398.55488616] +- [18.62572805 18.695321 7.79525906 7.72201933]

reprojection error: [-0.000000, 0.000000] +- [0.258390, 0.228922]

Target configuration

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Type: aprilgrid

Tags:

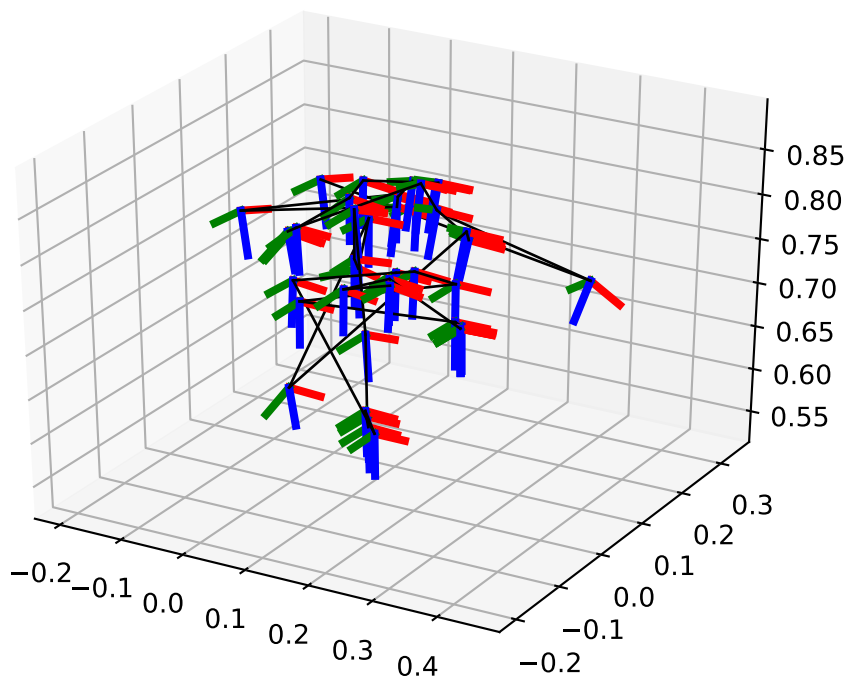
Rows: 6

Cols: 6

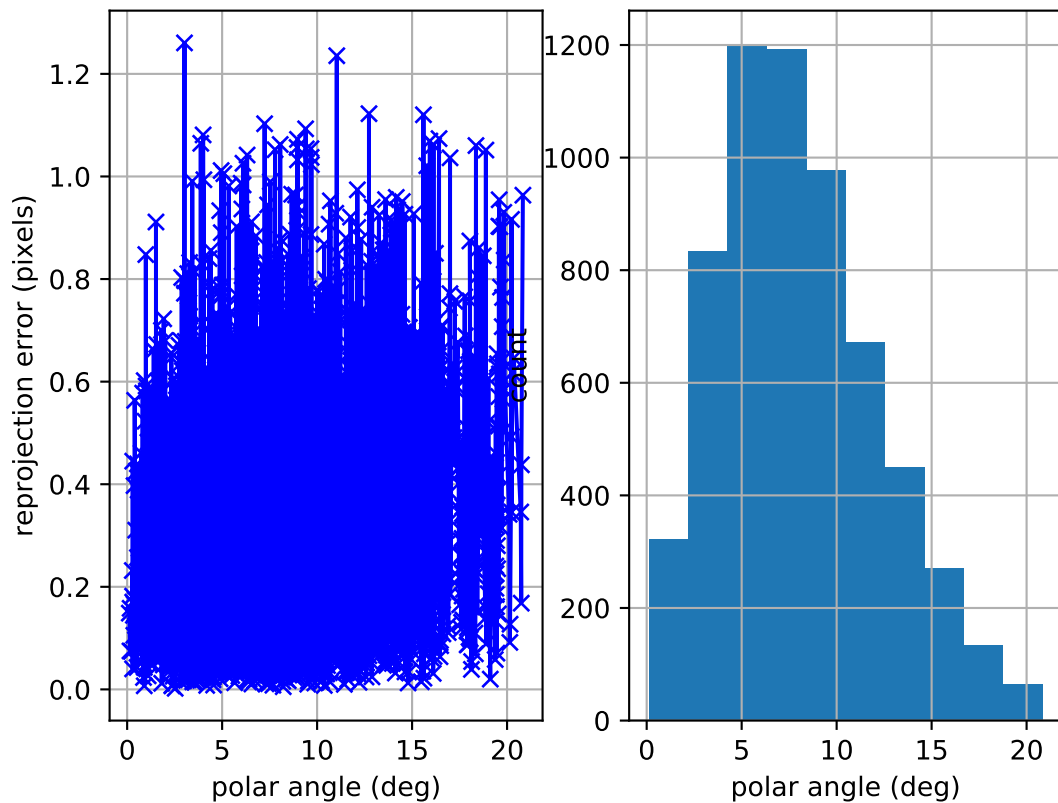
Size: 0.02 [m]

Spacing 0.006 [m]

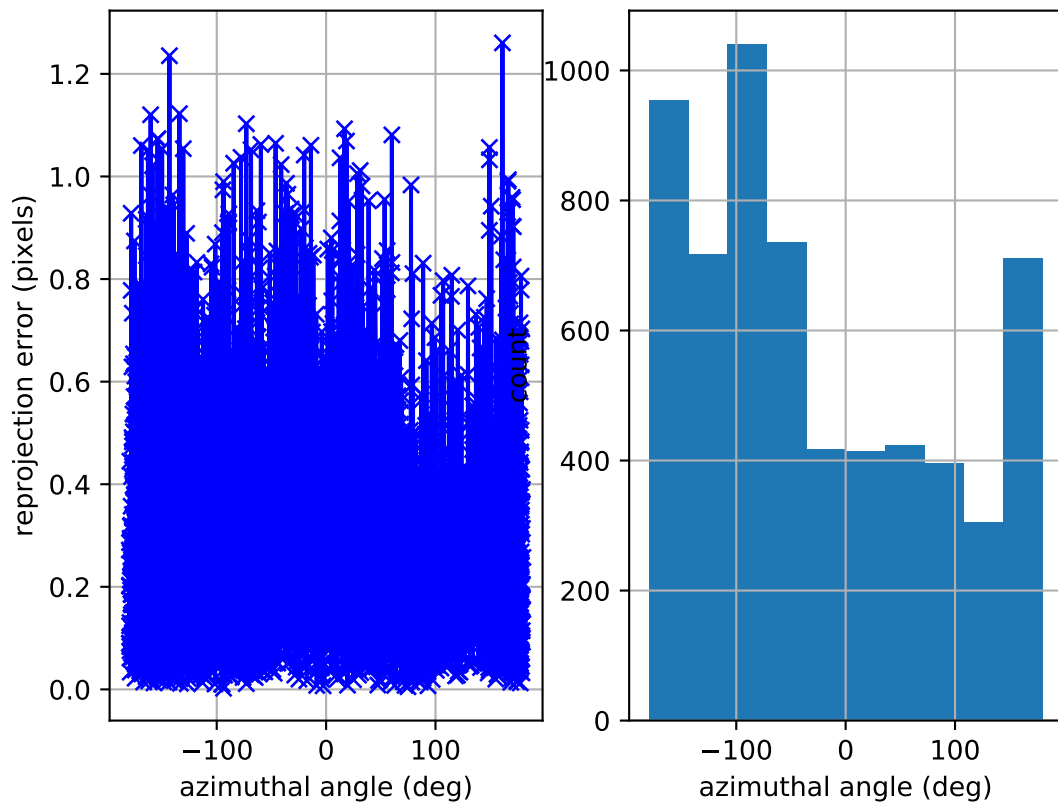
cam0: estimated poses



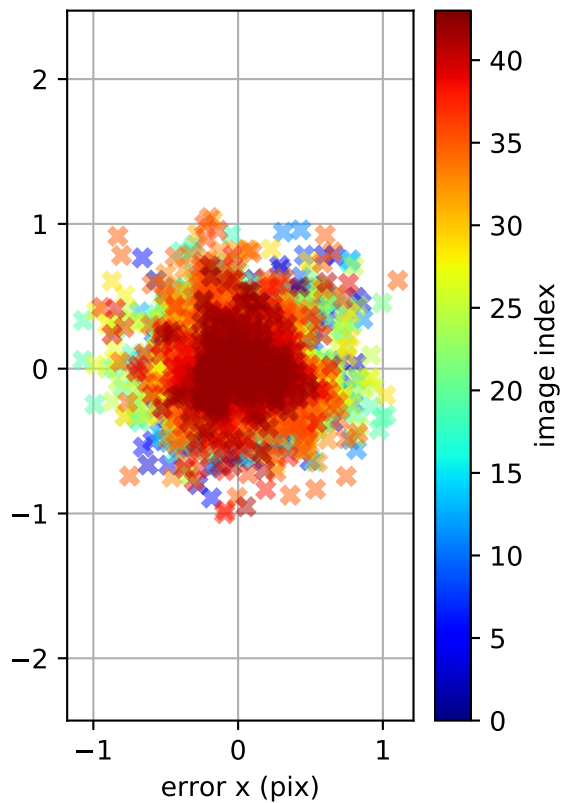
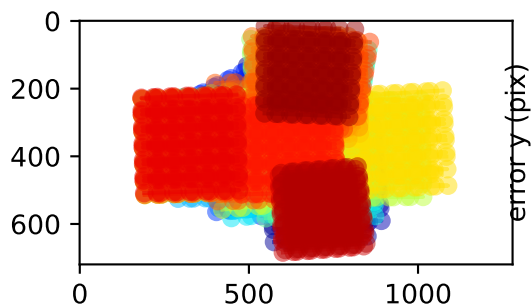
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

