

Calibration results

=====

Camera-system parameters:

cam0 (/camera/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.10355964 0.14174791 0.00279258 0.00231721] +- [0.00394246 0.01462219 0.00046015 0.00046719]

projection: [1988.47063182 1988.20715551 970.41520111 612.61767572] +- [8.92641233 9.00028071 4.26183134 4.38699382]

reprojection error: [0.000001, -0.000000] +- [0.908710, 0.792593]

Target configuration

=====

Type: aprilgrid

Tags:

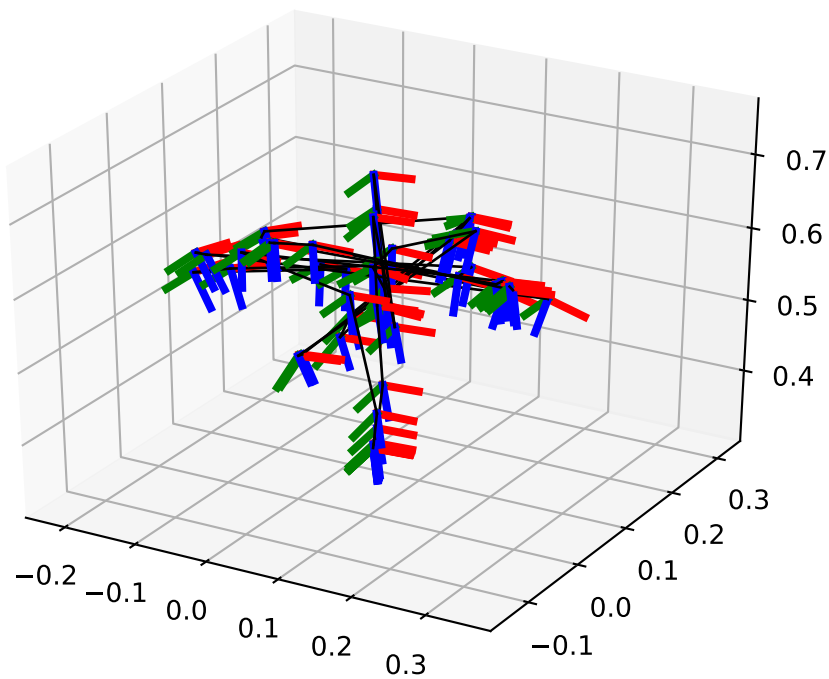
Rows: 6

Cols: 6

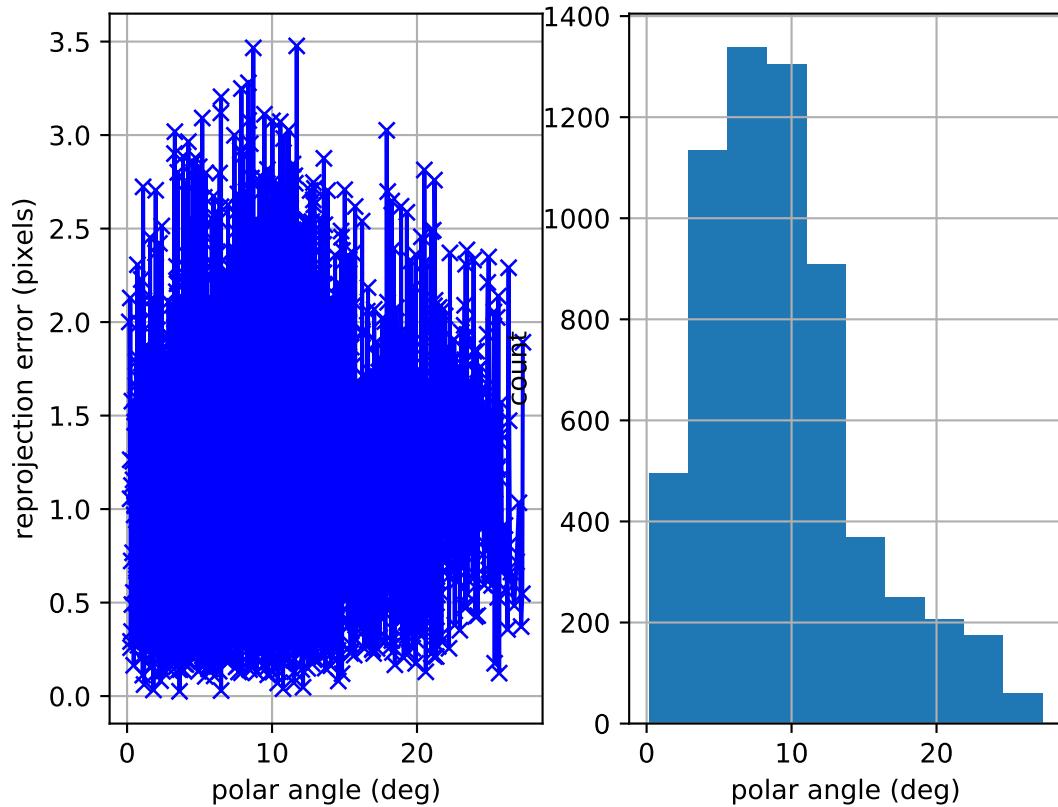
Size: 0.02 [m]

Spacing 0.006 [m]

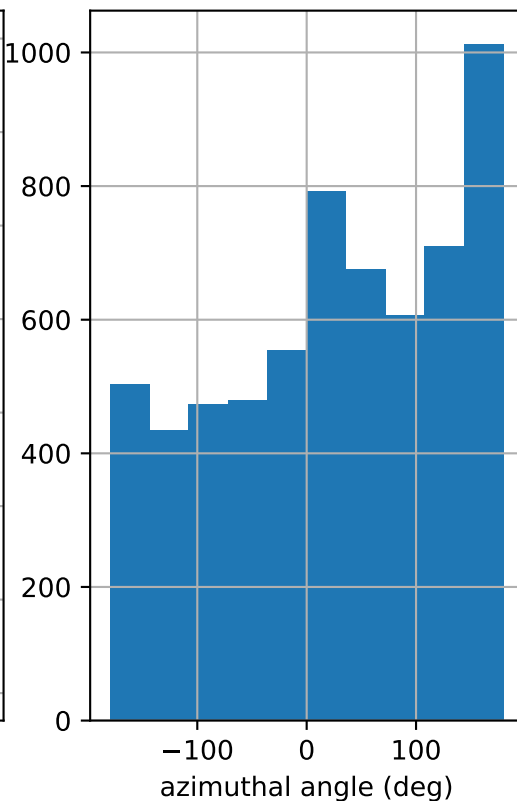
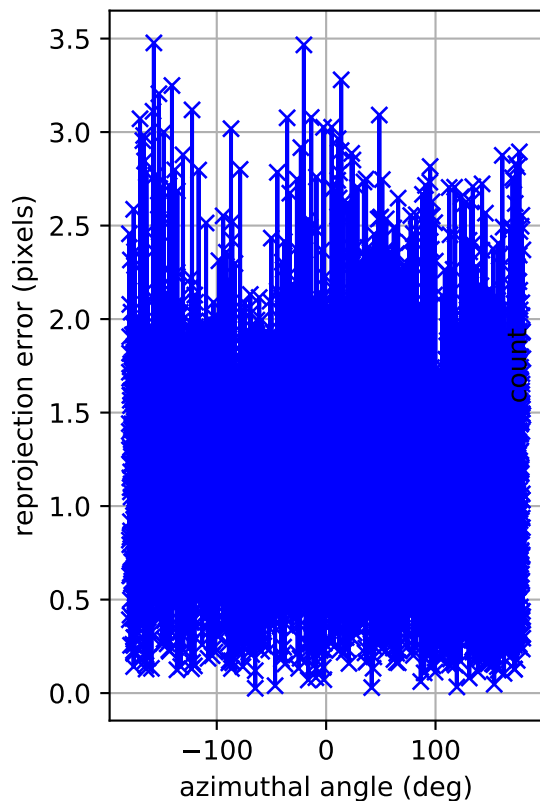
cam0: estimated poses



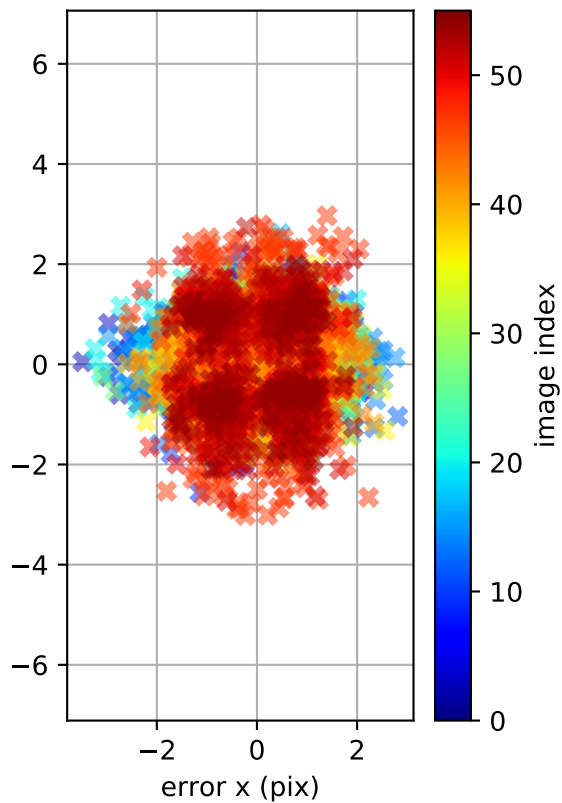
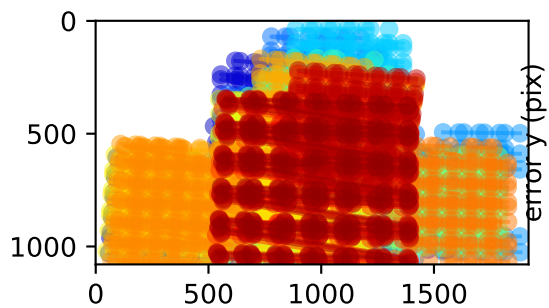
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

