

Calibration results

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Camera-system parameters:

cam0 (/camera/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.09488277 -0.03544157 -0.00133969 -0.00575013] +- [0.01801778 0.17638463 0.00109329 0.00068859]

projection: [1965.35409194 1962.64580175 419.38429954 288.78950119] +- [0.96735815 0.90152193 2.47609946 10.81625204]

reprojection error: [0.000076, -0.000030] +- [0.258146, 0.376068]

Target configuration

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Type: aprilgrid

Tags:

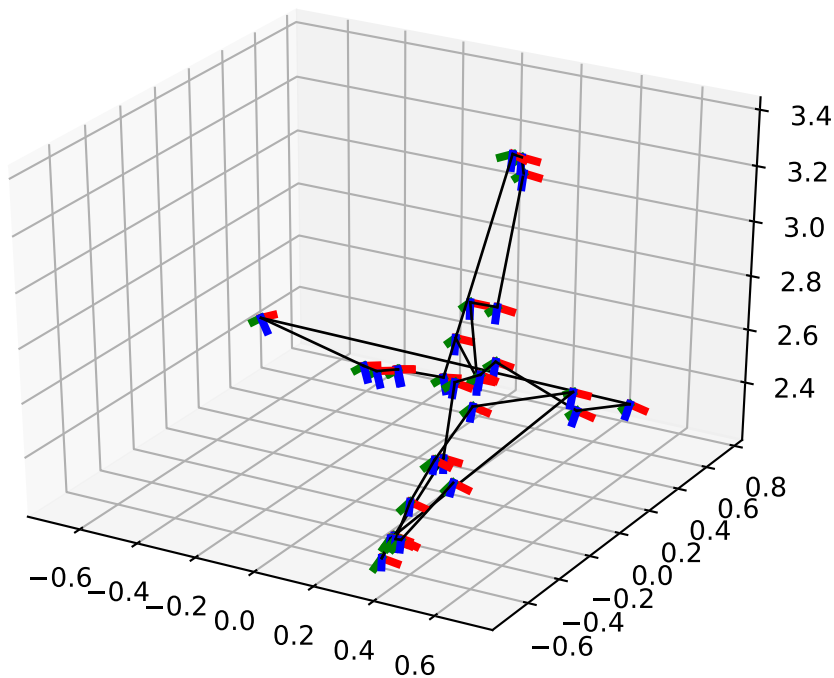
Rows: 6

Cols: 6

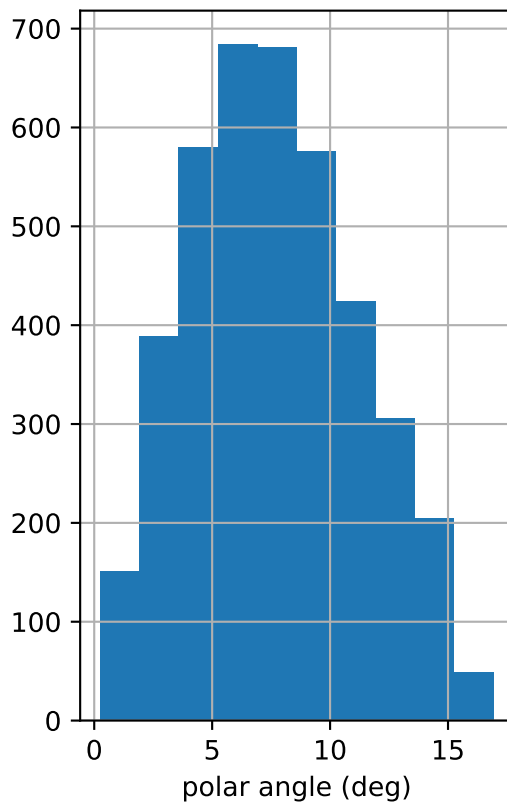
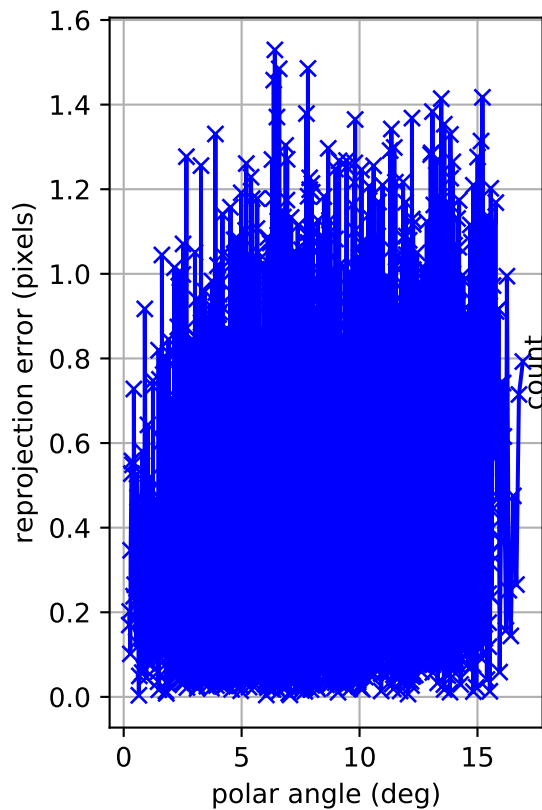
Size: 0.06 [m]

Spacing 0.018 [m]

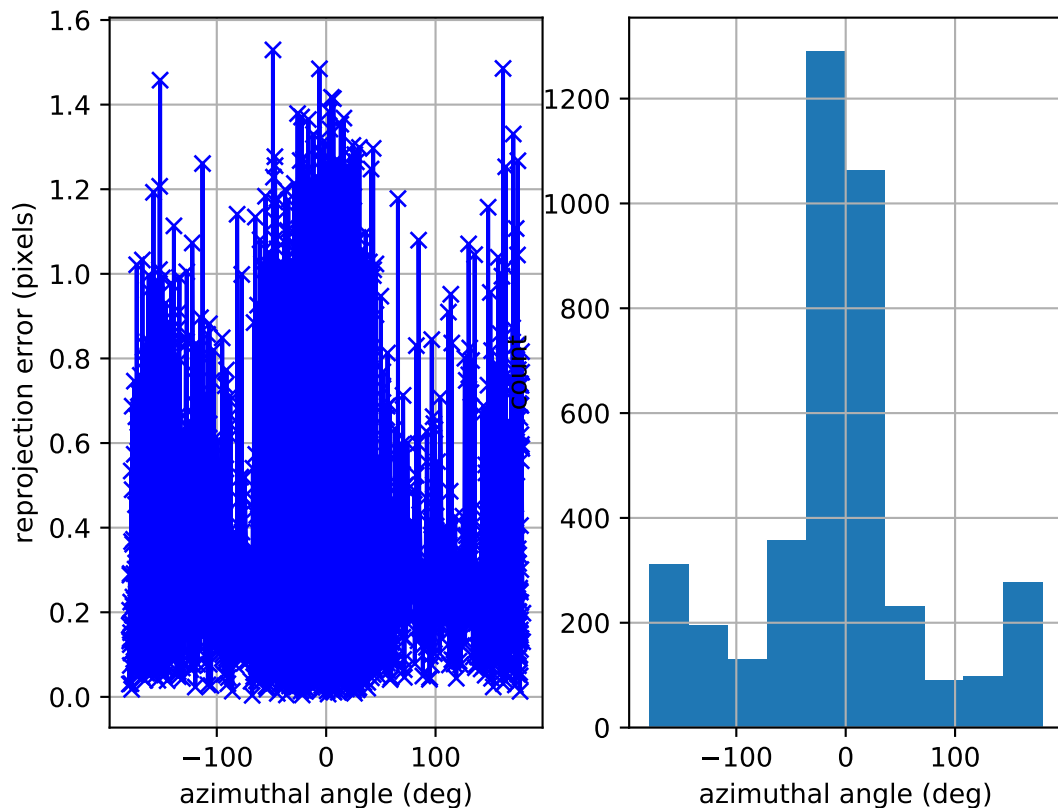
cam0: estimated poses



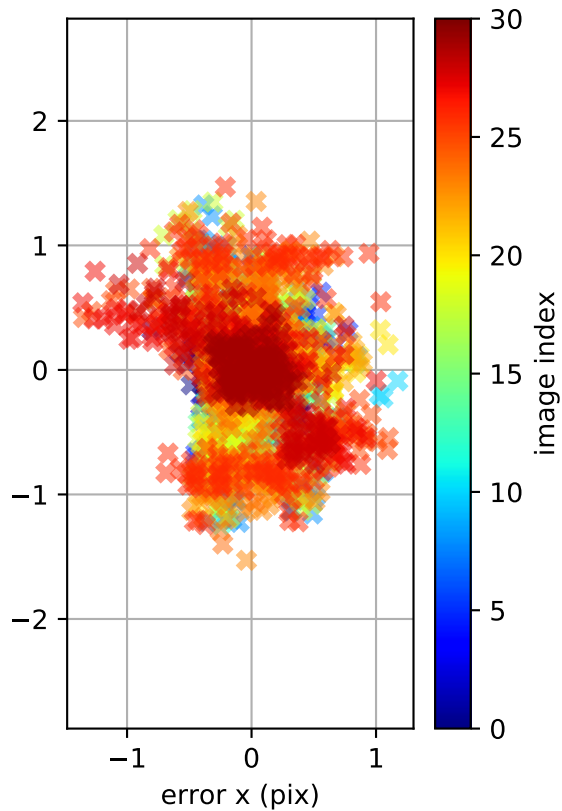
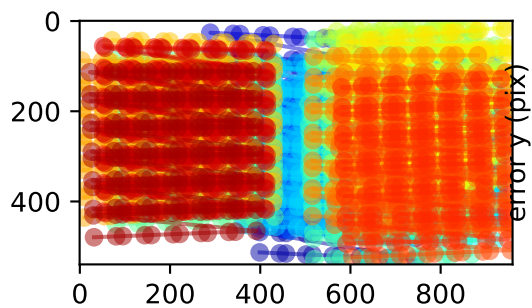
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

