

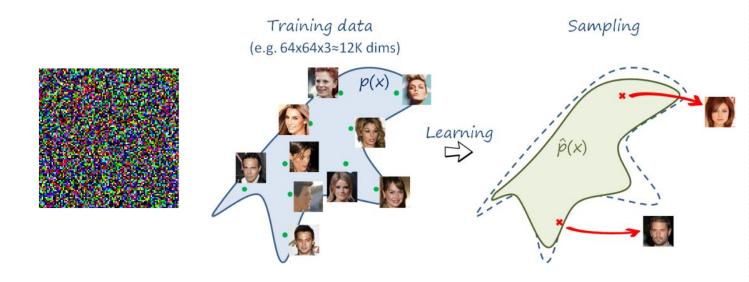
Deep Learning

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Generative Models

Generative models

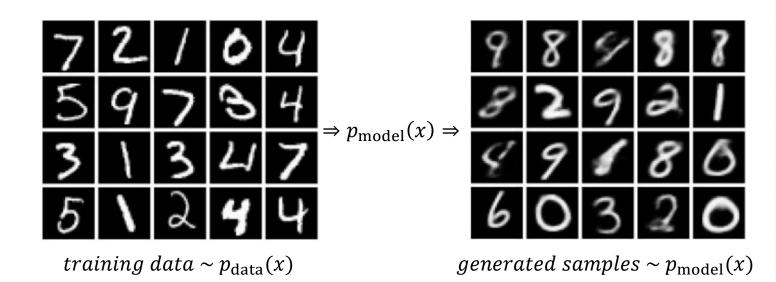
• Given training data, generate new samples from same distribution



- Training data $\sim p_{data}(x)$
- Want to learn $p_{model}(x)$ similar to $p_{data}(x)$
- Generated samples $\sim p_{model}(x)$

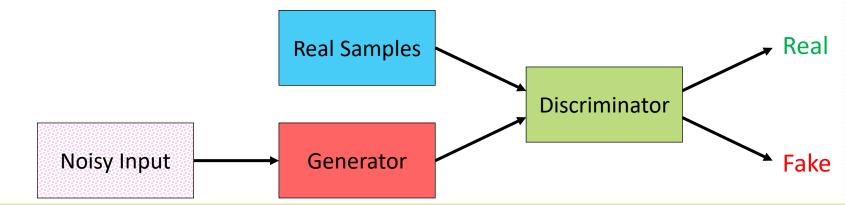
Generative adversarial networks

- Generative Adversarial Networks (GAN) don't work with any explicit density function!
- Instead, take game-theoretic approach:
 - Learn to generate from training distribution through 2-player game



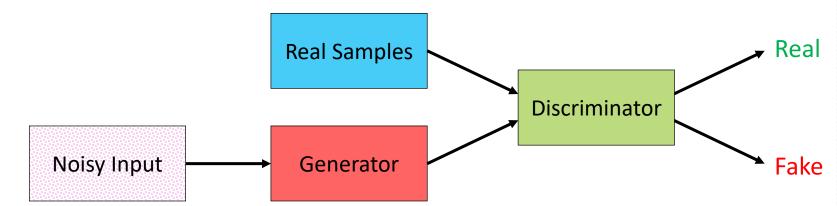
GAN

- The GAN model architecture involves two sub-models
 - Generator: Model that is used to generate new plausible examples from the problem domain
 - Discriminator: Model that is used to classify examples as real (from the domain) or fake (generated)

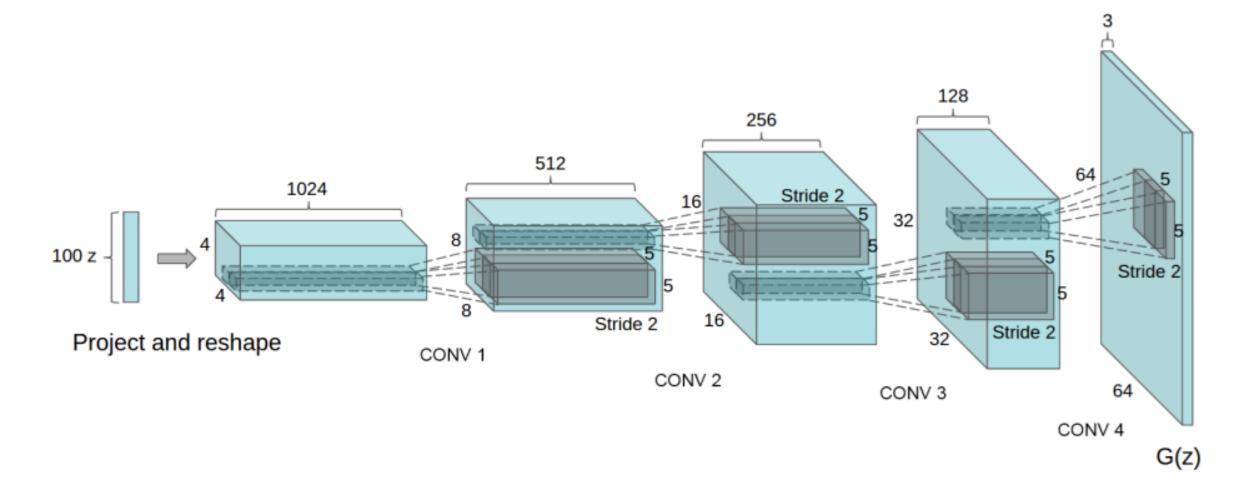


Generator network

- Want to sample from complex, high-dimensional training distribution
 - No direct way to do this!
 - Solution:
 - Sample from a simple distribution, e.g. random noise
 - Learn transformation to training distribution
 - We use a deep neural network to represent this complex transformation

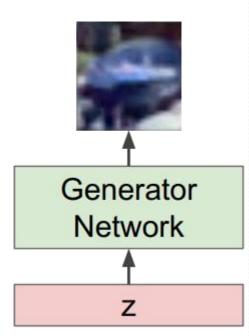


Generator network

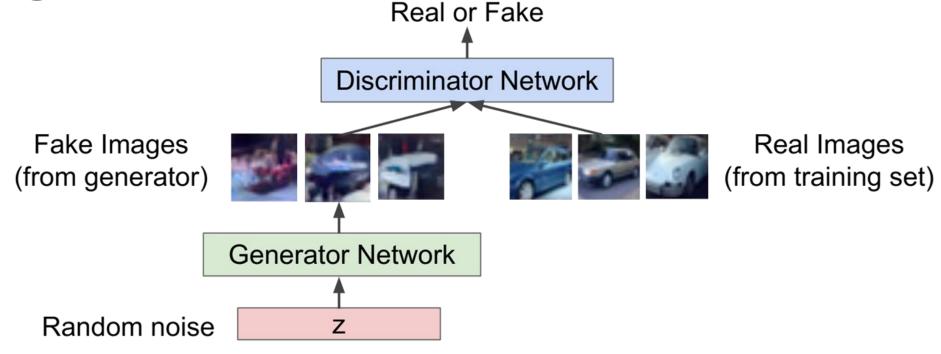


- How to optimize parameters?
- We need to evaluate the quality of the images produced
 - We use a discriminator network!

Output: Sample from training distribution

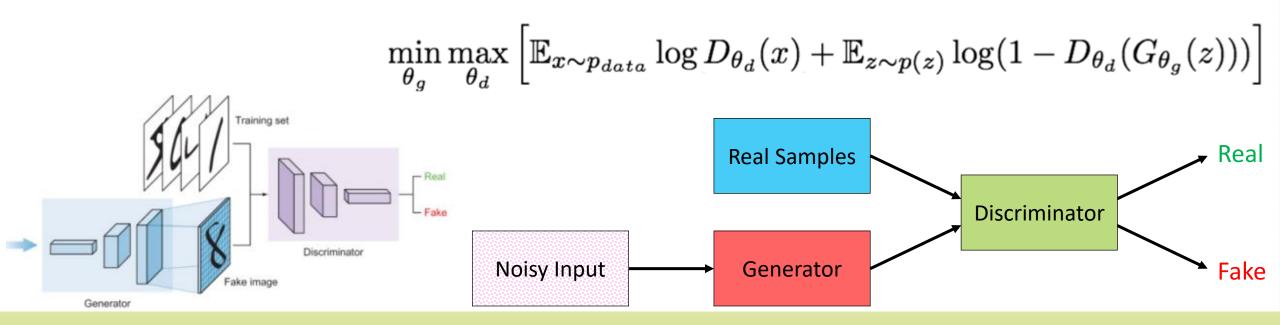


Input: Random noise



$$\min_{\theta_g} \max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log (1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$
 Discriminator output for real data x penerated fake data G(z)

- Discriminator (θ_d) wants to maximize objective such that D(x) is close to 1 (real) and D(G(z)) is close to 0 (fake)
- Generator $(heta_g)$ wants to minimize objective such that Dig(G(z)ig) is close to 1



Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log (1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- Alternate between:
 - Gradient ascent on discriminator

$$\max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log (1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- Gradient descent on generator

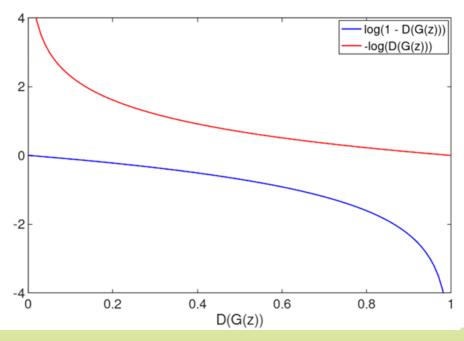
$$\min_{\theta_g} \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z)))$$

$$\min_{\theta_g} \max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log (1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

$$\max_{\theta_d} \left[\mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log (1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

$$\min_{\theta_g} \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z)))$$

$$\max_{\theta_g} \mathbb{E}_{z \sim p(z)} \log(D_{\theta_d}(G_{\theta_g}(z)))$$



GAN pseudocode

for number of training iterations do

for k steps do

- Sample minibatch of m noise samples $\{z^{(1)}, \ldots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Sample minibatch of m examples $\{x^{(1)}, \dots, x^{(m)}\}$ from data generating distribution $p_{\text{data}}(x)$.
- Update the discriminator by ascending its stochastic gradient:

$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^{m} \left[\log D_{\theta_d}(x^{(i)}) + \log(1 - D_{\theta_d}(G_{\theta_g}(z^{(i)}))) \right]$$

end for

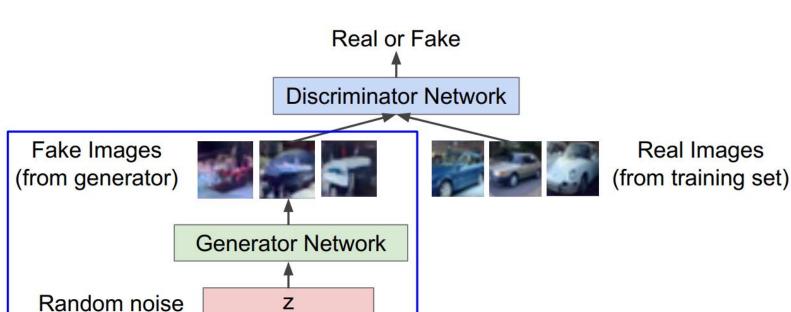
- Sample minibatch of m noise samples $\{z^{(1)}, \ldots, z^{(m)}\}$ from noise prior $p_g(z)$.
- Update the generator by ascending its stochastic gradient (improved objective):

$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m \log(D_{\theta_d}(G_{\theta_g}(z^{(i)})))$$

end for

Generator

 After training, use generator network to generate new images





Conditional GAN

• In a CGAN, the generator and the discriminator are conditioned on c, which could be a class label or some data from another modality

• In Auxiliary Classifier GANs, the discriminator is forced to identify fake and real images, as well as the class of the image, irrespective of whether it is

fake or real

