

OPTIMAL CYCLES AND LP/IP

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OPTIMAL CYCLES AND LP/IP CHAINS

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OHCP

The Optimal Homologous Cycle Problem:
Given p-cycle c in simplicial complex K ,
find homologous cycle x that is "optimal".

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$$x - c = \partial_{ph} s$$

is min.

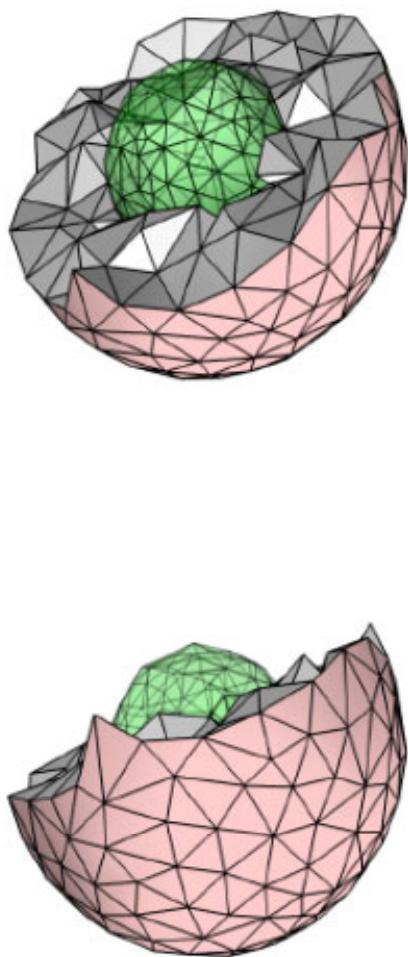
$$\sum w_i |x_i|$$

OHCP

The Optimal Homologous Cycle Problem :

Given p-cycle c in simplicial complex K ,
find homologous cycle x that is "optimal".

$$x \sim c$$
$$x - c = \partial_{\text{PH}} s$$



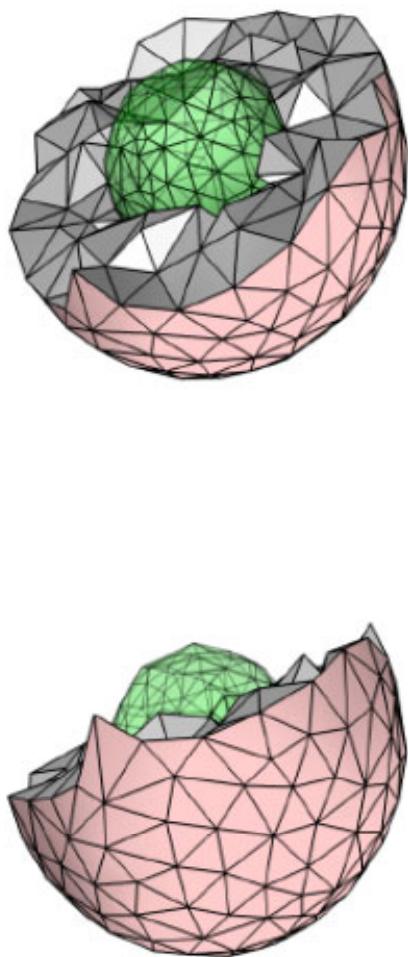
$\sum w_{il} |x_{il}|$
is min.

OHCP

The Optimal Homologous Chain Problem :

Given β -chain c in simplicial complex K ,
find "homologous" cycle x that is "optimal".

$$x \sim c$$
$$x - c = \partial_{\text{PH}} s$$



w_i

$$\sum w_i |x_i|$$

is min.

OHCP

The Optimal Homologous Chain Problem :

Given p -chain c in simplicial complex K ,
find "homologous" cycle x that is "optimal".

$$x \sim c$$

$$\sum w_i |x_i|$$

is min.

$$x - c = \partial_{ph} s$$

$$\min w^T x$$

s.t.

$$x = c + [\partial_{ph}] s$$

$$x \in \mathbb{Z}^m, s \in \mathbb{Z}^n$$

OBCP

The Optimal Bounding Chain Problem :

Given p -boundary c in simplicial complex K ,
find $(p+1)$ -chain s bounding c that is "optimal".

$$c = \partial_{p+1} s$$
$$\sum_{i=1}^n v_i |s_i|$$

is min.

OBCP

The Optimal Bounding Chain Problem :

Given p -boundary c in simplicial complex K ,
find $(p+1)$ -chain s bounding c that is "optimal".

$$c = \partial_{p+1} s$$

min

s.t.

$$\nabla^T s$$

$$c = [\partial_{p+1}] s$$

$$s \in \mathbb{Z}^n$$

$\sum |v_i| s_i$
is min.

MSFN

Ibrahim, K, Vixie (2013)

Multiscale Simplicial Flat Norm:

Given p -chain c in simplicial complex K ,
find homologous chain x that is optimal:

$$x \sim c$$

$$\sum_i w_i |x_i| + \lambda \sum_{j \in S} v_j s_j$$

$$\lambda \geq 0$$

$$x = c - \partial_p s$$

MSFN

Ibrahim, K, Vixie (2013)

Multiscale Simplicial Flat Norm:

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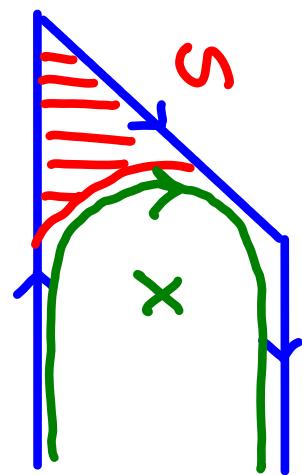
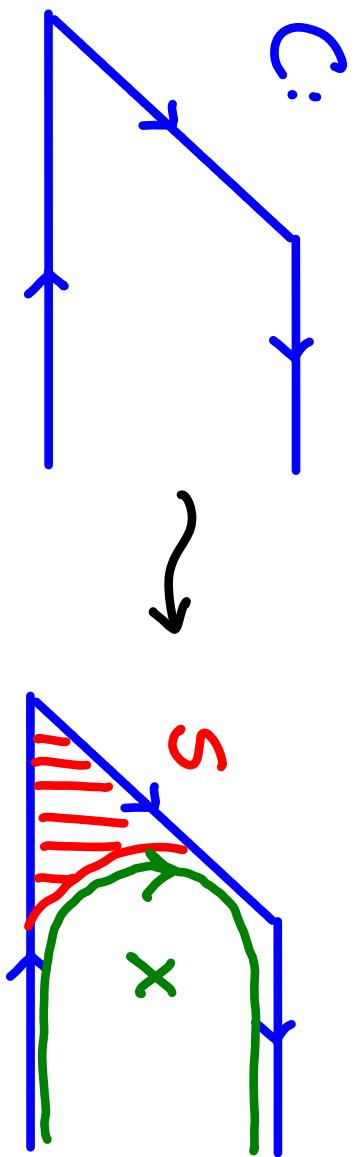
$$\min \quad w^T x + \lambda v^T s \quad \lambda \geq 0$$

s.t.

$$x = c - [\partial_{ph}] s$$

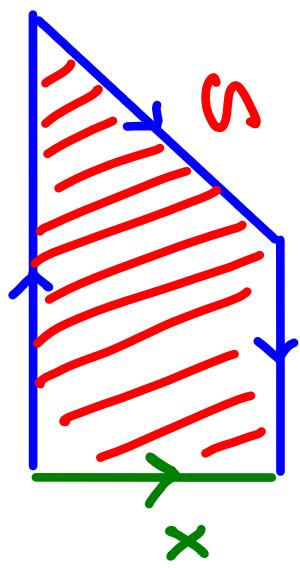
$$x \in \mathbb{Z}^m, \quad s \in \mathbb{Z}^n$$

MFN EXAMPLE

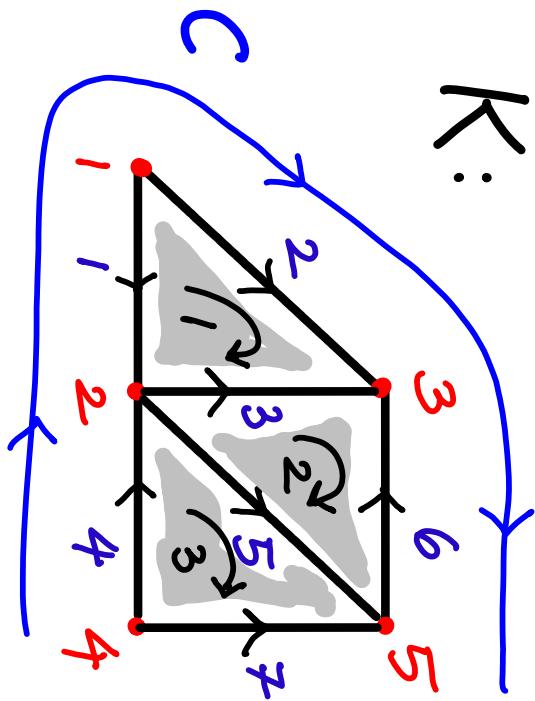


$$X = C - \partial S$$

on

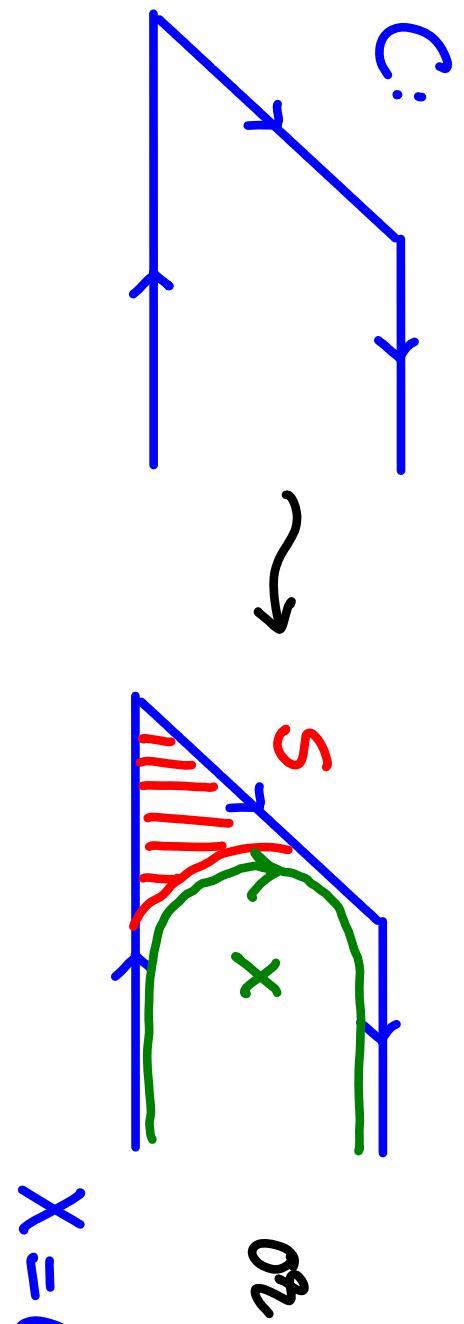


MFN EXAMPLE

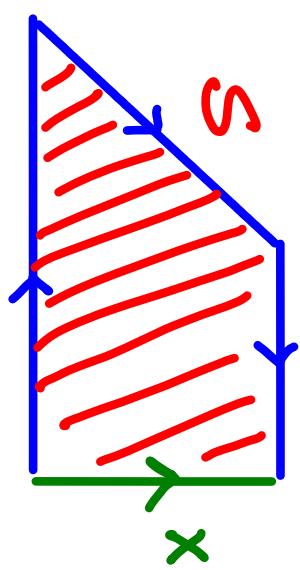


$$w_i = \begin{cases} 1, & i=1,3,4,6,7 \\ \sqrt{2}, & i=2,5 \end{cases} \text{ lengths}$$

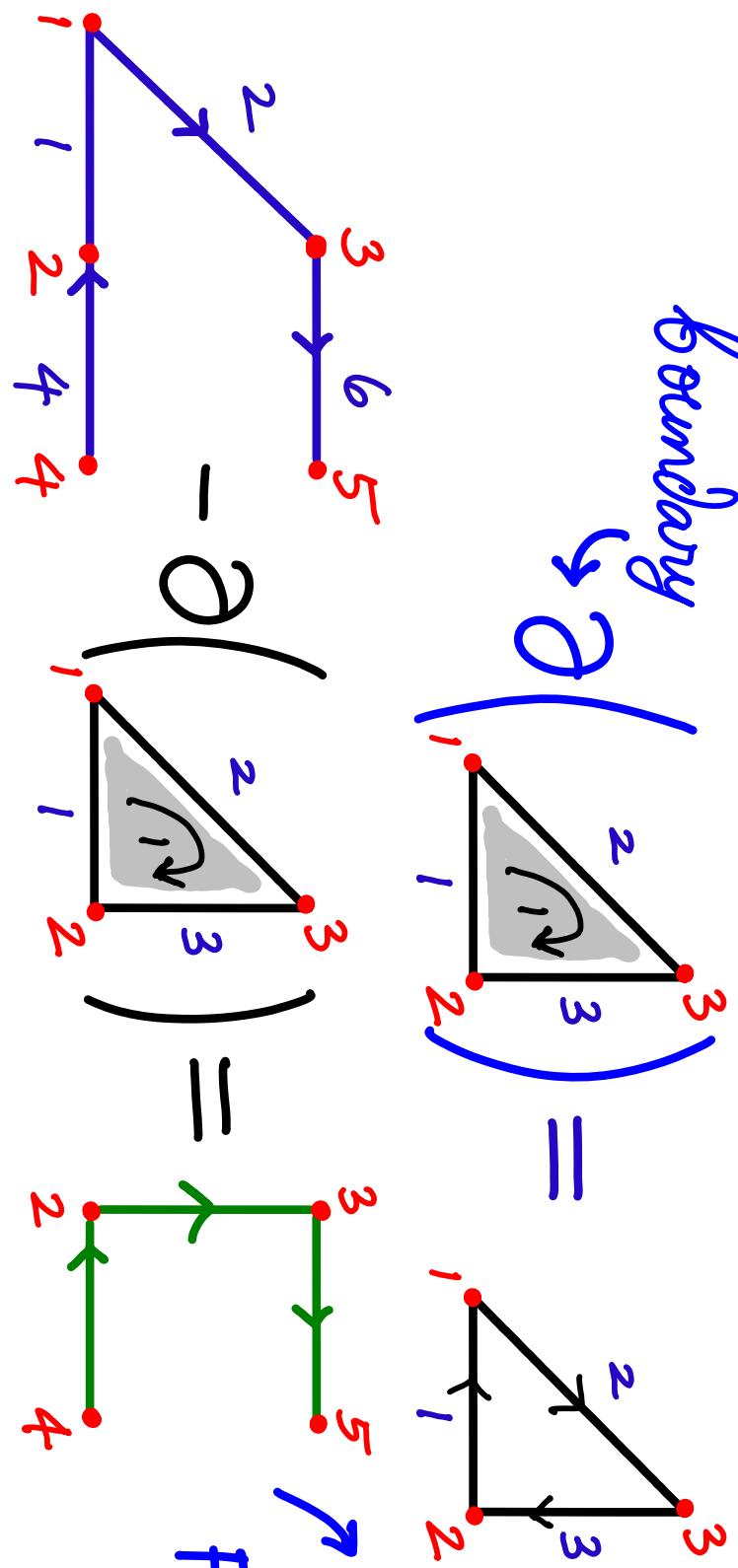
$v_j = \frac{1}{2}, j=1,2,3 \}$ areas



$$X = C - \partial S$$



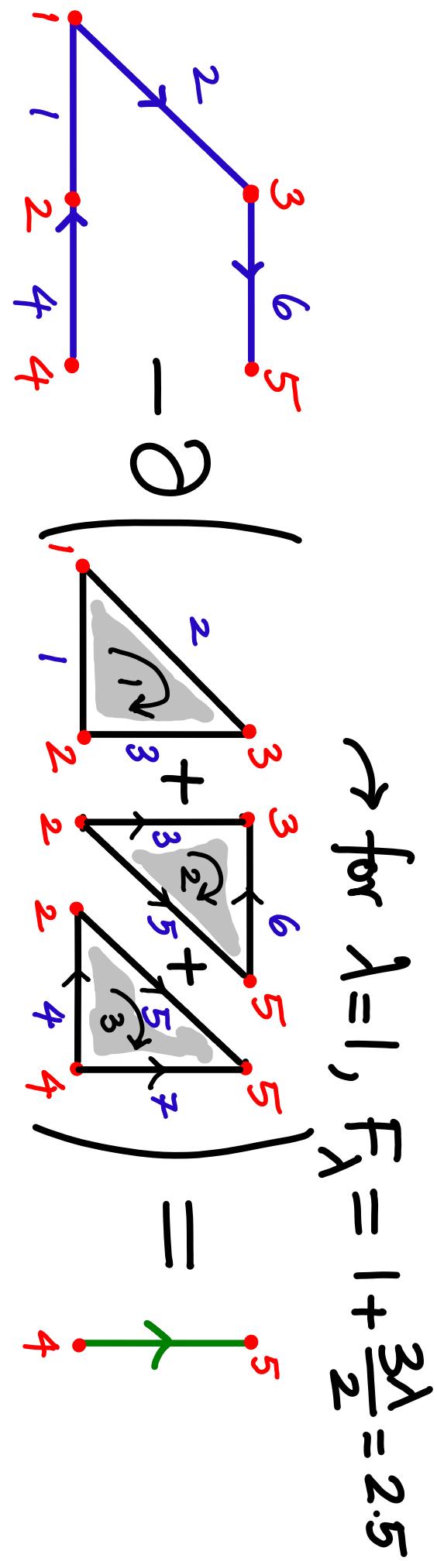
MSFN EXAMPLE



$$F_1 = 3 + \frac{1}{2} \rightarrow \text{for } \lambda = 2.5,$$

$$= 4.25$$

MSFIN Example

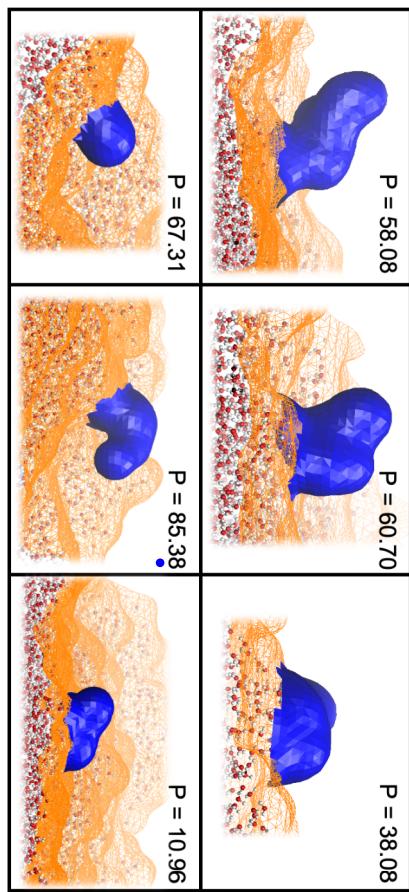


MFN: APPLICATIONS

* protrusions in chemistry

E Alvarado, Z Liu, M Servi^z, BK, A Clark

JCTC 2020

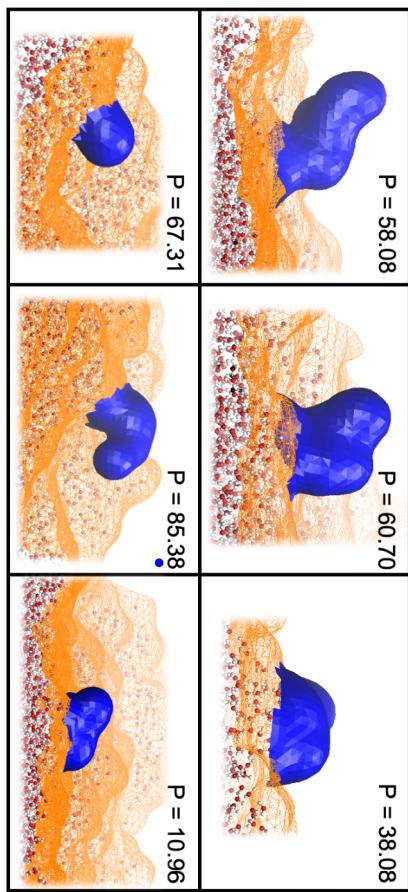


MFN: APPLICATIONS

* protrusions in chemistry

E Alvarado, Z Liu, M Servizi, BK, A Clark

JCTC 2020



* validating synthetic power networks

K Lyman, R Meyer, BK, M Halappanavar

IJCA 2025

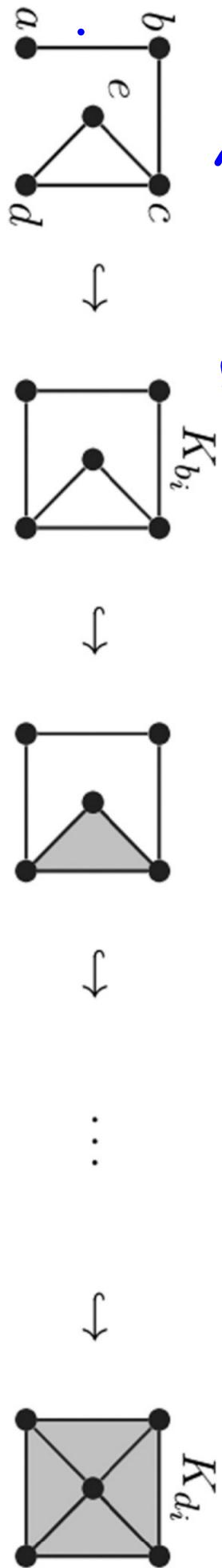


OHCP UNDER PERSISTENCE

- * volume-optimal cycles: Obayashi, 2018
- * minimal persistent cycles: Dey, Hou, Mandal, 2020
(over \mathbb{Z}_2)

OHCP UNDER PERSISTENCE

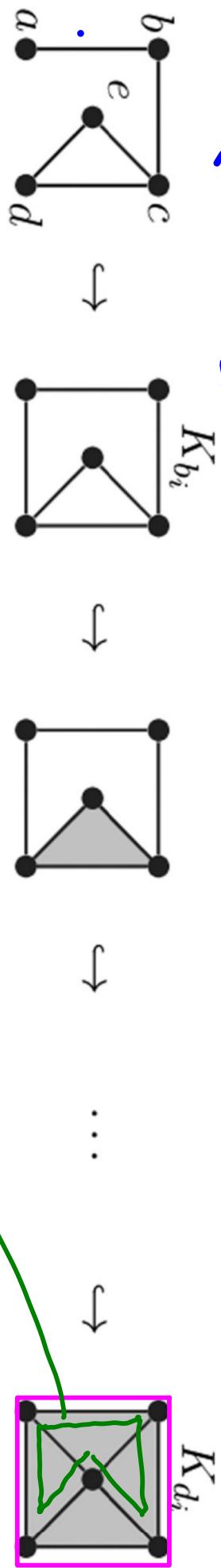
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↳ Example from Li et al., 2021

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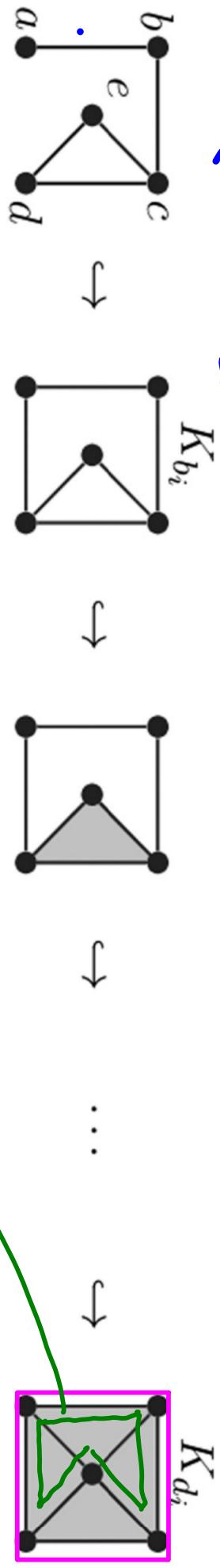


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\hookrightarrow l_0 -min per cycle
vol-optimal cycle

OHCP UNDER PERSISTENCE

- * volume-optimal cycles: Obayashi, 2018
- * minimal persistent cycles: Dey, Hou, Mandal, 2020 (over \mathbb{Z}_2)



↳ Example from Li et al., 2021

ℓ_0 -min per cycle
vol-optimal cycle

! Today: OHCP in a single simplicial complex
with homology over \mathbb{Z}

OHC P AS AN INTEGER PROGRAM

$$\begin{aligned} & \min_{x, y} \sum_i w_i |x_i| \quad \text{such that} \\ & x = c + \lfloor \theta p \rfloor s, \quad x \in \mathbb{Z}^m, \quad s \in \mathbb{Z}^n \quad (w_i \geq 0) \end{aligned} \quad (\text{OHC P})$$

OHC_P AS AN INTEGER PROGRAM

piecewise linear

$$\min_{x, y} \sum_i w_i |x_i| \text{ such that}$$

(OHC_P)

$$x = c + \lfloor \partial_{P+} \rfloor s, \quad x \in \mathbb{Z}^m, \quad s \in \mathbb{Z}^n \quad (w_i \geq 0)$$

$$\min \sum_i w_i (x_i^+ + x_i^-)$$

$$\text{s.t. } x^+ - x^- = c + \lfloor \partial_{P+} \rfloor (s^+ - s^-) \quad (\text{IP})$$

$$x^+, x^-, s^+, s^- \geq 0 \quad x^+, x^- \in \mathbb{Z}^m, \quad s^+, s^- \in \mathbb{Z}^n$$

OHC P AS AN INTEGER PROGRAM

piecewise linear
(OHC P)

$$\min_{x, y} \sum_i w_i |x_i| \text{ such that}$$

$$x = c + \lfloor \partial_{p+1} \rfloor s, \quad x \in \mathbb{Z}^m, \quad s \in \mathbb{Z}^n \quad (w_i \geq 0)$$

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ignore to get LP

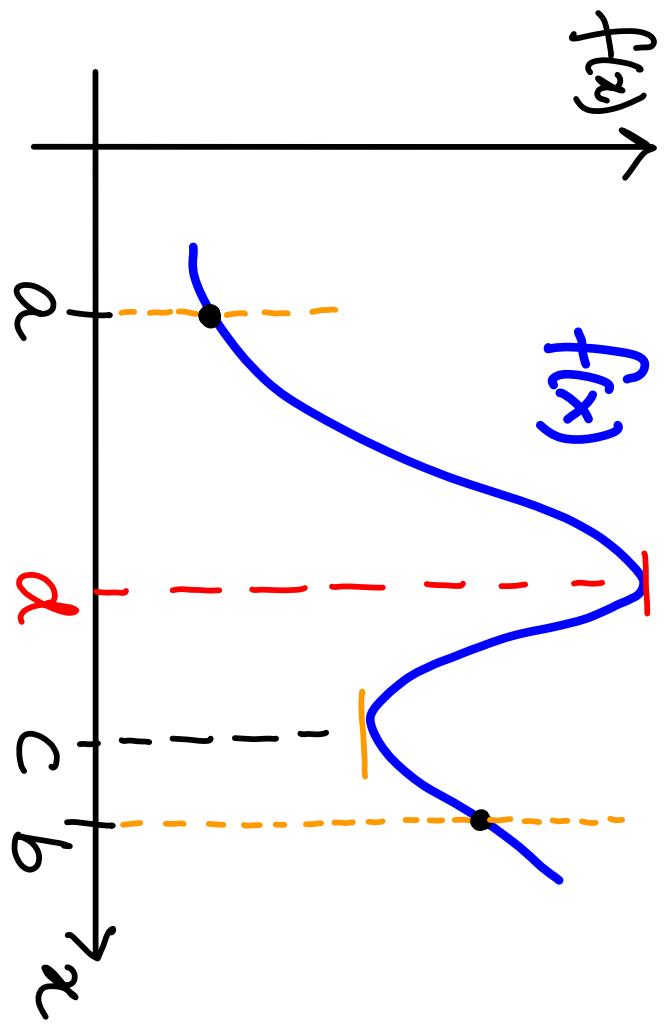
LINEAR PROGRAMMING (LP)

Optimization in Calculus I

$$\min f(x)$$

$$a \leq x \leq b$$

$$f'(x) = 0, \quad f''(x) > 0$$



LINEAR PROGRAMMING (LP)

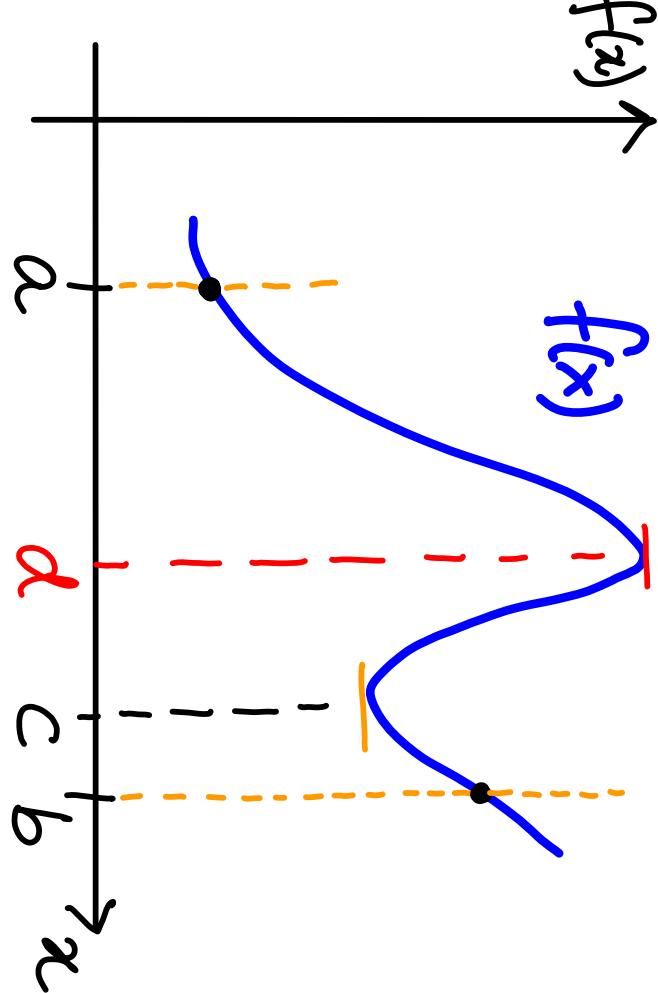
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also check end points!



Here, minimum is
at $x=a$

LINEAR PROGRAMMING (LP)

Optimization in Calculus I

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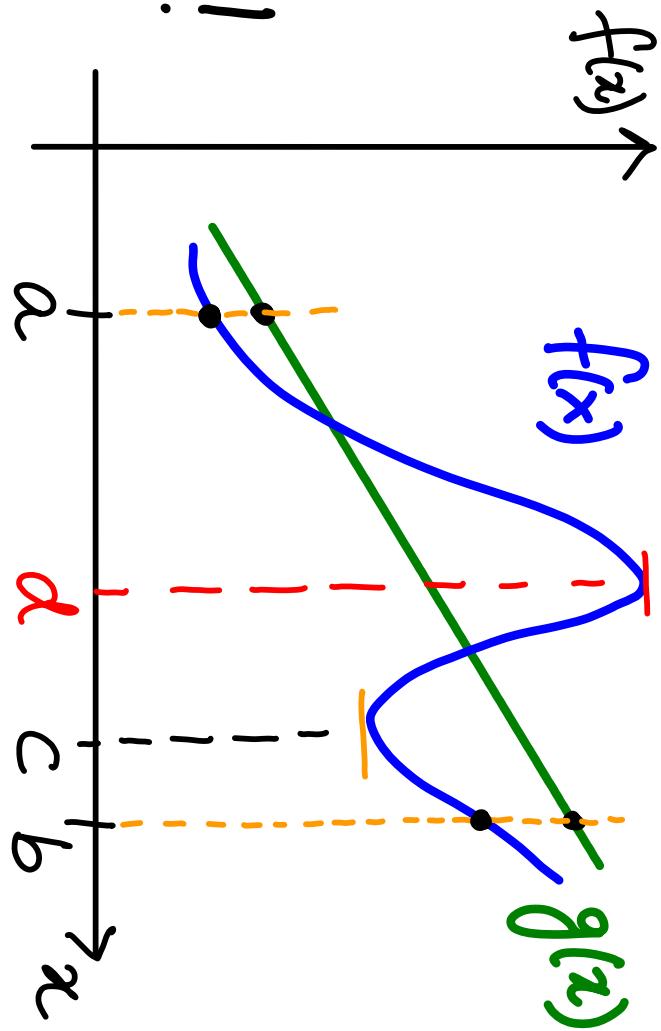
also check end points!

Here, minimum is

at $x = a$

$\left\{ \min g(x) \right\}$ where $g(x)$ is linear?

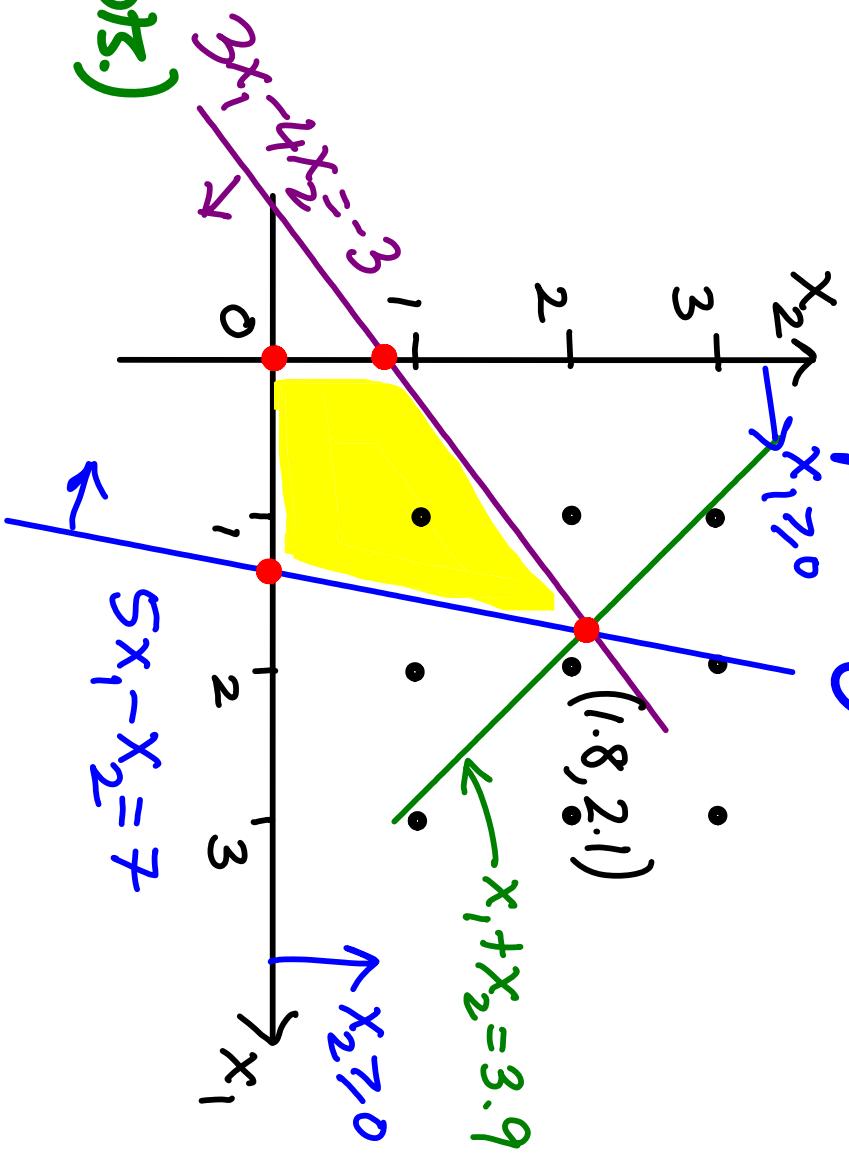
Need to check ONLY the end points!



LINEAR PROGRAMMING (LP)

Extend linear case to high dimensions \Rightarrow LP
(also called linear optimization)

$$\begin{aligned} \max \quad & x_1 + x_2 \\ \text{s.t.} \quad & 5x_1 - x_2 \leq 7 \\ & 3x_1 - 4x_2 \geq -3 \\ & x_1, x_2 \geq 0 \end{aligned}$$

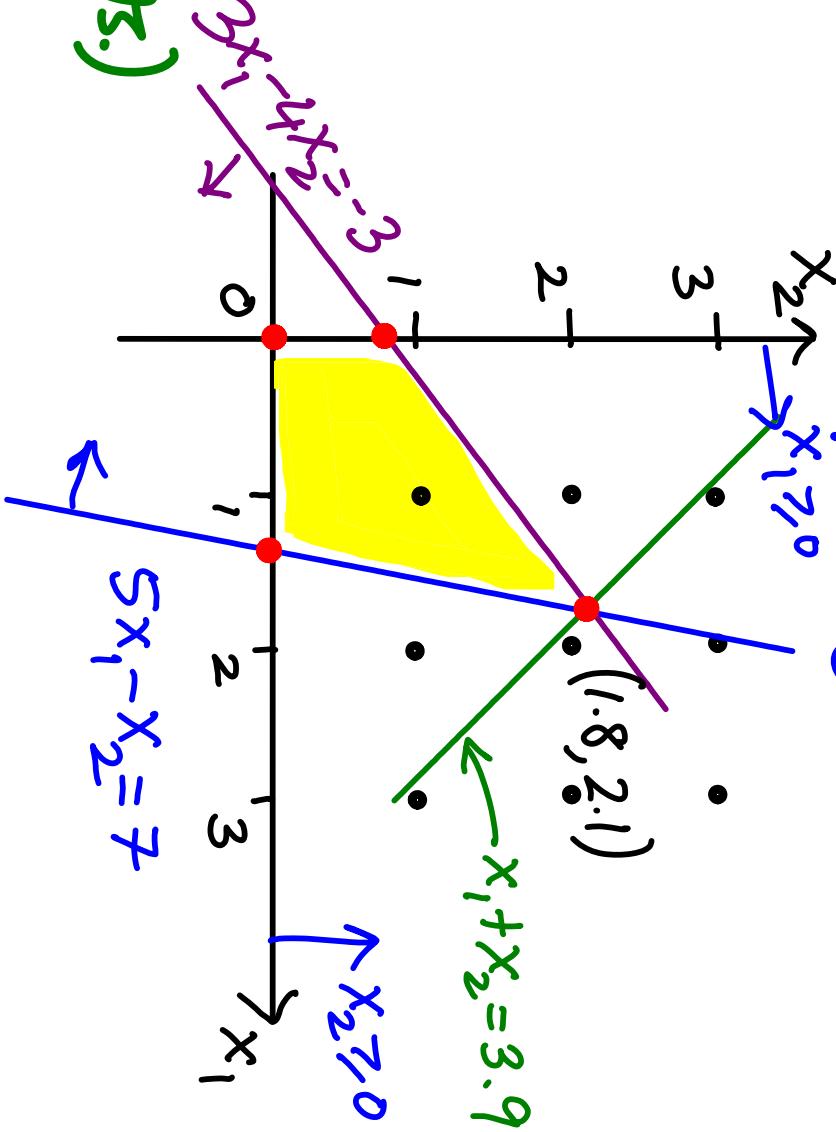


Need to check ONLY corner points (\equiv end pts.)

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Need to check ONLY corner points (\equiv end pts.)

Require $x_j \in \mathbb{Z} \Rightarrow$ integer programming (IP)

IP AND TOTAL UNIMODULARITY

$$\min \{ c^T x \mid Ax = b, x \geq 0, x \in \mathbb{Z}^n \} \quad (\text{IP})$$

$$\min \{ c^T x \mid Ax = b, x \geq 0 \} \quad (\text{LP})$$

IP AND TOTAL UNIMODULARITY

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Result: (IP) can always be solved in polynomial time by solving (LP) iff A is totally unimodular (TU).

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A is TU if every square submatrix has determinant $-1, 0$, or 1 .

In particular, $A_{ij} \in \{-1, 0, 1\}$ $\forall i, j$.

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In particular, $A_{ij}^{ij} \in \{-1, 0, 1\}$ $\forall i, j$.

e.g., node-arc incidence matrix of directed graph

OHC P AND TU OF $\left[\begin{smallmatrix} \partial_{\rho+} \\ \partial_{\rho-} \end{smallmatrix} \right]$

$$\begin{aligned} & \min \sum_i w_i (x_i^+ + x_i^-) \\ \text{s.t. } & x^+ - x^- = C + [\partial_{\rho+}] (s^+ - s^-) \\ & x^+, x^-, s^+, s^- \geq 0 \end{aligned}$$

\downarrow
total unimodularity

(LP)

OHC P AND TU OF $[\partial_{\rho^+}]$

$$\min \sum_i w_i (x_i^+ + x_i^-)$$

\downarrow
total unimodularity

$$\text{s.t. } x^+ - x^- = C + [\partial_{\rho^+}] (s^+ - s^-) \quad (\text{LP})$$

$$x^+, x^-, s^+, s^- \geq 0$$

The constraint matrix of above LP is
 TU iff $[\partial_{\rho^+}]$ is TU .

OHC_P AND TU OF $[\partial_{pt}]$

$$\min \sum_i w_i (x_i^+ + x_i^-)$$

total unimodularity

$$\text{s.t. } x^+ - x^- = C + [\partial_{pt}] (s^+ - s^-) \quad (\text{LP})$$

$$x^+, x^-, s^+, s^- \geq 0$$

The constraint matrix of above LP is TU iff $[\partial_{pt}]$ is TU.

\Rightarrow OHC_P is solvable in poly time when $[\partial_{pt}]$ is TU.

OHC_P AND TU OF $[\partial_{pt}]$

$$\min \sum_i w_i (x_i^+ + x_i^-)$$

↗ total unimodularity

$$\text{s.t. } x^+ - x^- = C + [\partial_{pt}] (s^+ - s^-) \quad (\text{LP})$$

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The constraint matrix of above LP is TU iff $[\partial_{pt}]$ is TU.

\Rightarrow OHC_P is solvable in poly time when

$[\partial_{pt}]$ is TU.

\hookrightarrow OBCP, MSFN as well

WHEN IS $[\partial_{pt}]$ TU?

Dey, Hiranik, K, 2010: $[\partial_{pt}]$ is TU iff K has
 $(DHK)_{10}$
"no relative torsion".

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Poincaré: TU
in 1899!

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Special cases

✓ K is an *orientable manifold*

Poincaré: TU
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WHEN IS $[\partial_{\text{pt}_!}]$ TU?

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Special cases

- ✓ K is an *orientable manifold*
- ✓ $\dim(K) = d$, K in \mathbb{R}^d
e.g., tetrahedra in \mathbb{R}^3



Poincaré: TU
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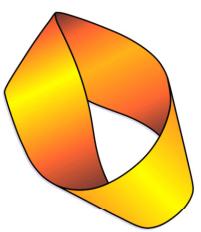
WHEN IS $[\partial_{\text{pt}_1}]$ TU?

Dey, Hirani, K, 2010: $[\partial_{\text{pt}_1}]$ is TU iff K has
(DHK'10)
"no relative torsion".

Special cases

- ✓ K is an *orientable manifold*
- ✓ $\dim(K) = d$, K in \mathbb{R}^d
e.g., tetrahedra in \mathbb{R}^3
- ✓ $[\partial_2]$ is TU $\Leftrightarrow K$ has "Möbius strip"

Poincaré: TU
in 1899!



DUAL GRAPH: MAX FLOW

- * Chen & Freedman, 2008 (OHC_P, \mathbb{Z}_2)
- * Dey, Hou, Mandal, 2020 (min. pers. cycle, \mathbb{Z}_2)

DUAL GRAPH: MAX FLOW

- * Chen & Freedman, 2008 (OBCP, \mathbb{Z}_2)
- * Dey, Hou, Mandal, 2020 (min. pers. cycle, \mathbb{Z}_2)
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DUAL GRAPH: MAX FLOW

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- * Chambers, Erickson, Nayyeri, 2009, 2012 (OHP, R)

DUAL GRAPH: MAX FLOW

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- * Borradale, Maxwell, Mayyeri, 2020 (OBCP, \mathbb{Z}_2)
- * Chambers, Erickson, Nayyeri, 2009, 2012 (OBCP, \mathbb{R})
- * Sullivan, Iqbal (OBCP, \mathbb{Z})

DUAL GRAPH: MAX FLOW

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- * Sullivan, 1990 (OBCP, \mathbb{Z})
! dual graph: tricky when C is not a cycle, MSFN

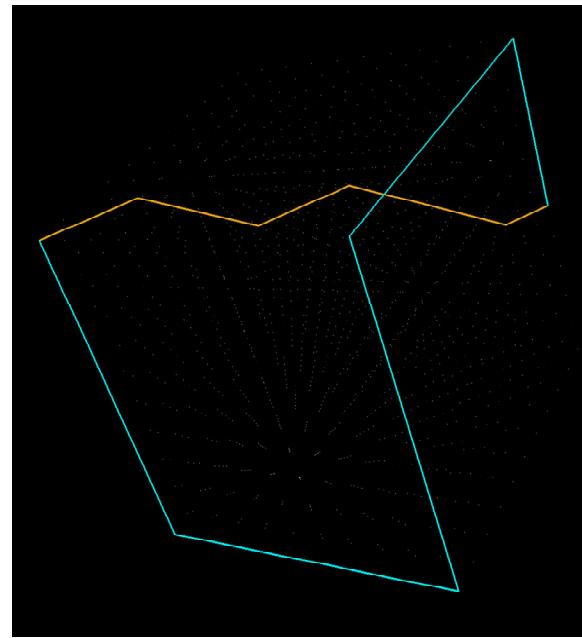
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- ! dual graph: tricky when C is not a cycle, MSFN
- Q: What happens when boundary matrix is not TU ?

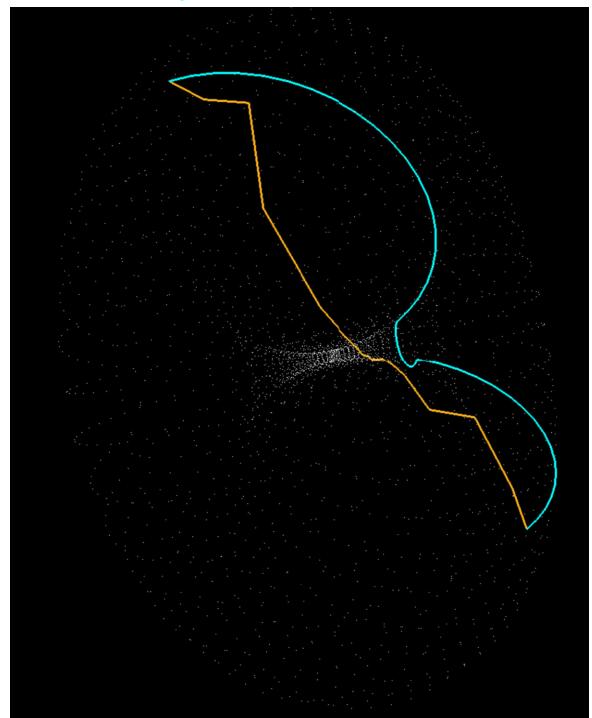
MSFN IN CODIM. 2

\equiv
 X C

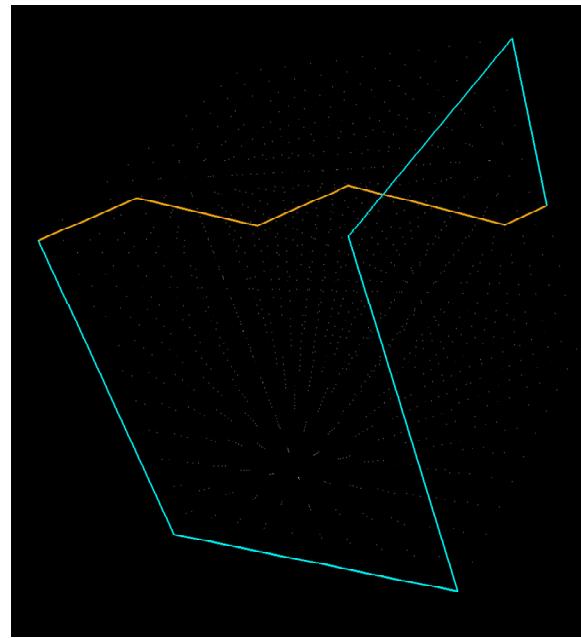
K : 2-skeleton of solid cube



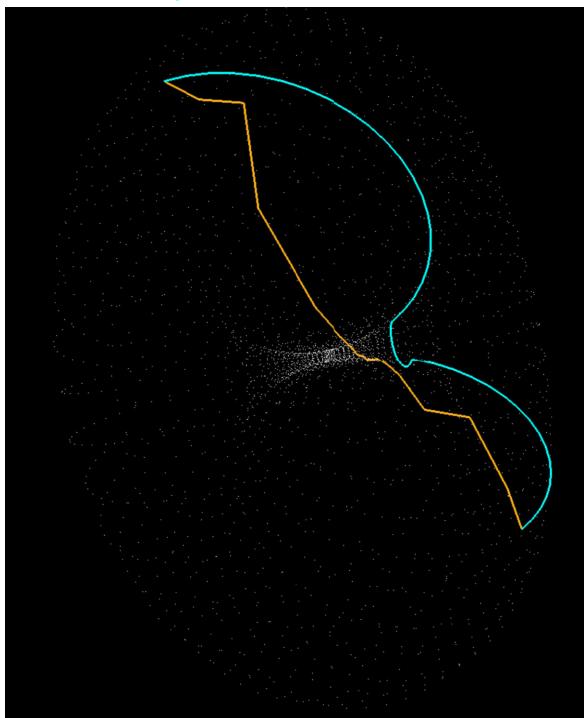
2-skeleton of solid torus



MSFN IN CODIM. 2



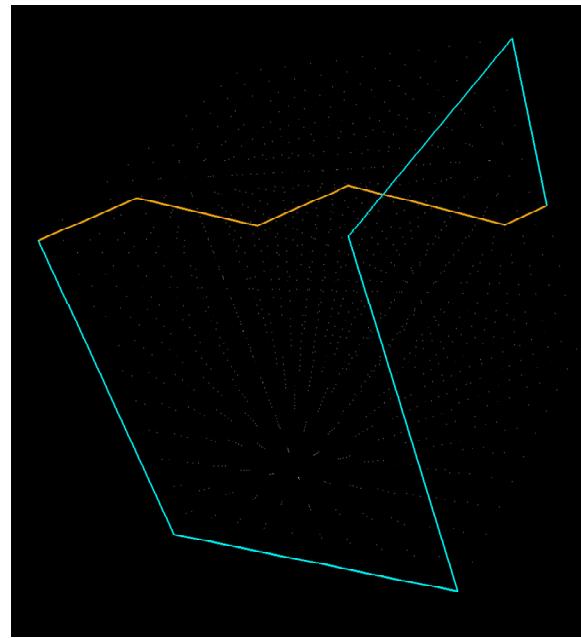
K : 2-skeleton of solid cube 2-skeleton of solid torus



$[\partial_2]$ is not TU, but MSFN LP gives integer soln!

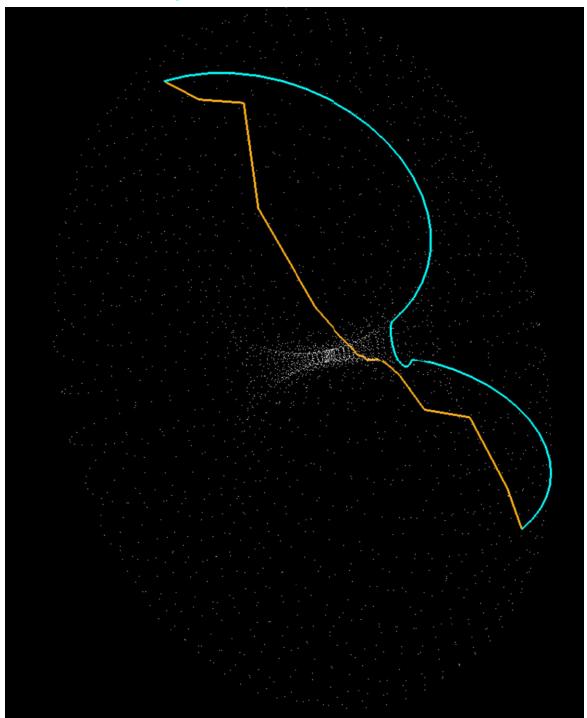
$$x = c$$

MSFN IN CODIM. 2



K : 2-skeleton of solid cube

2-skeleton of solid torus

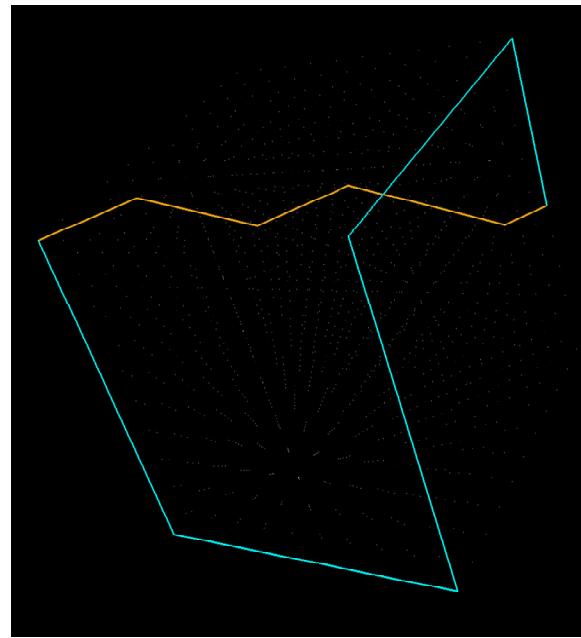


$[2_2]$ is not TU, but MSFN LP gives integer soln!

Q1: When/why does MSFN LP in codim. 2 give integer solutions for free?

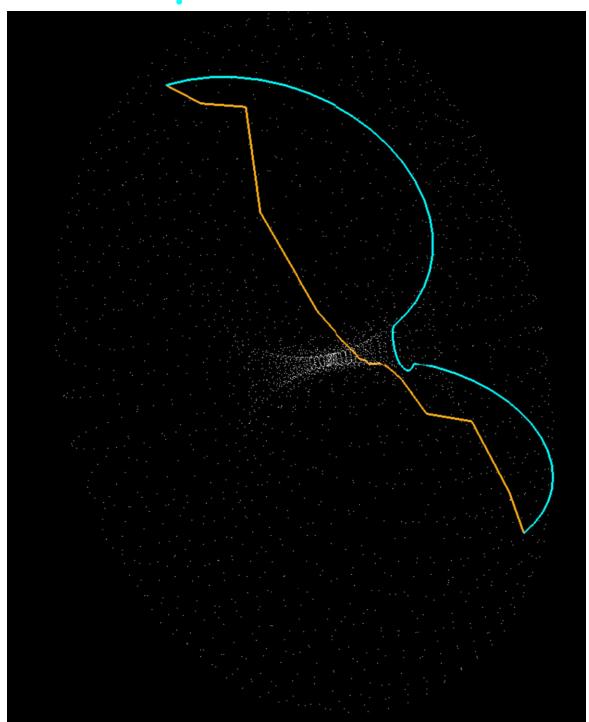
$$= \begin{matrix} C \\ X \end{matrix}$$

MSFN IN CODIM. 2



K : 2-skeleton of solid cube

2-skeleton of solid torus



$$x = c$$

$[2_2]$ is not TU, but MSFN LP gives integer soln!

Q1: When/why does MSFN LP in codim. 2

give integer solutions for free?

— Li et al, 2021: mostly $\{-1, 0, 1\}$ sol's Why?

NON-TU NEUTRALIZED K

- K, G, Smith , 2018

- ✓ Define a condition when simplicial complex K is non total-unimodularity neutralized (NTUN)

NON-TU NEUTRALIZED K

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- ✓ Define a condition when simplicial complex K is non total-unimodularity neutralized (NTUN)
 - boundary matrix is not T_d

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- ✓ Define a condition when simplicial complex K is non total-unimodularity neutralized (NTUN)
 - boundary matrix is not T_d , but
 - every OHCP LP, i.e., for every input chain, has an integer optimal solution

NON-TU NEUTRALIZED K

- K, G, Smith, 2018

- ✓ Define a condition when simplicial complex K is non total-unimodularity neutralized (NTUN)
 - boundary matrix is not T_d , but
 - every OHCP LP, i.e., for every input chain, has an integer optimal solution
- ✓ property of K (independent of weights on simplices and input chain)

NON-TU NEUTRALIZED K

Theorem Every OHCP LP on K has an integer optimal solution if every elementary chain in each relative torsion in K has a "neutralizing chain" in K .

NON-TU NEUTRALIZED K

Theorem

Every OHCP LP on K has an integer optimal solution if every elementary chain in each relative torsion in K has a "neutralizing chain" in K .



ensures that every fractional basic solution is a convex combination of two integral basic solutions.

NON-TU NEUTRALIZED K

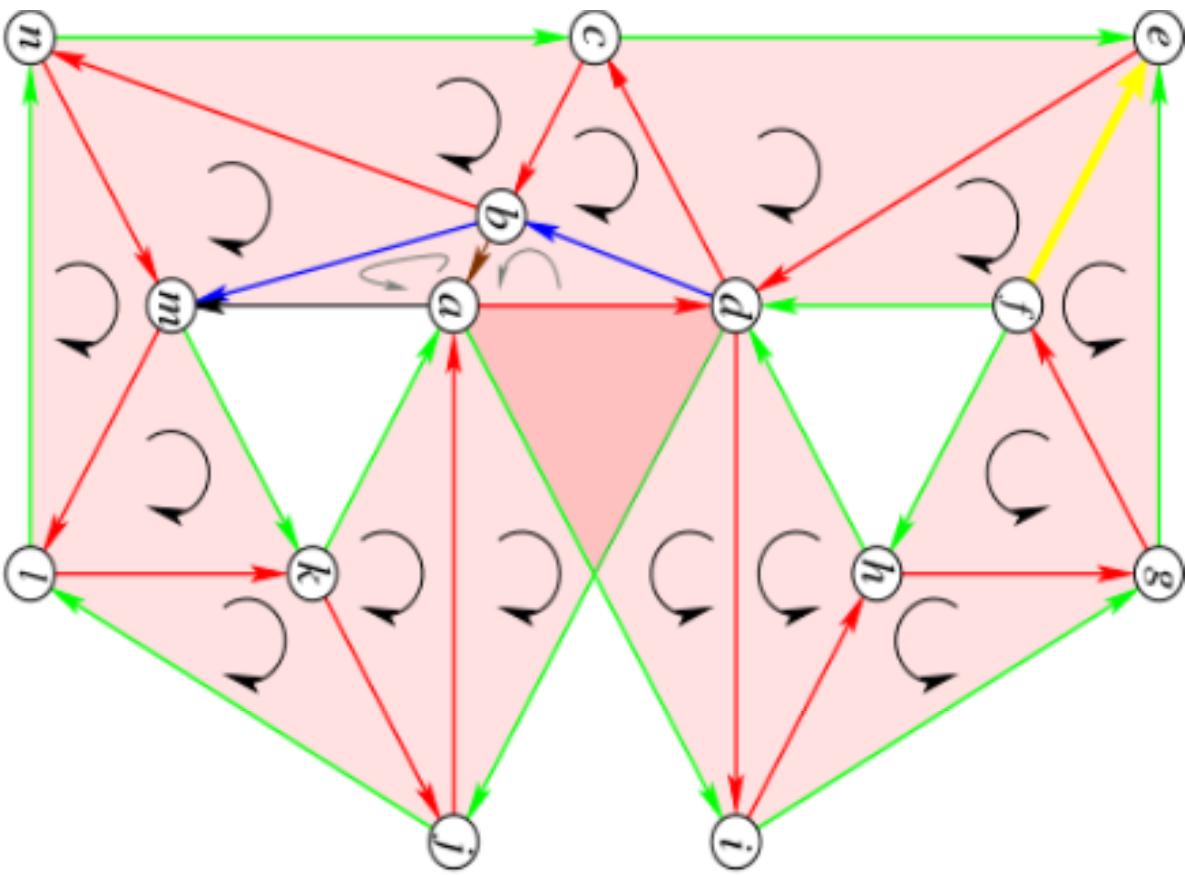
Theorem

Every OHCP LP on K has an integer optimal solution if every elementary chain in each relative torsion in K has a "neutralizing chain" in K .

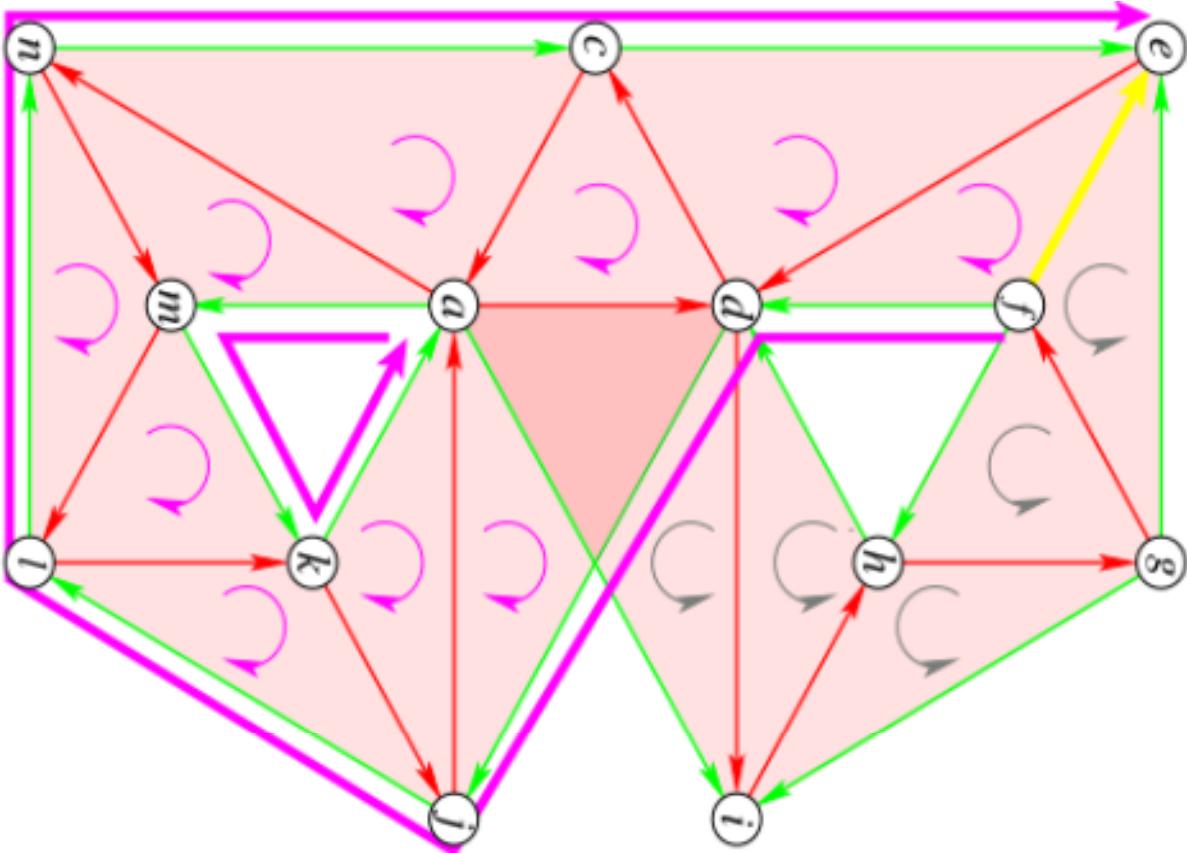


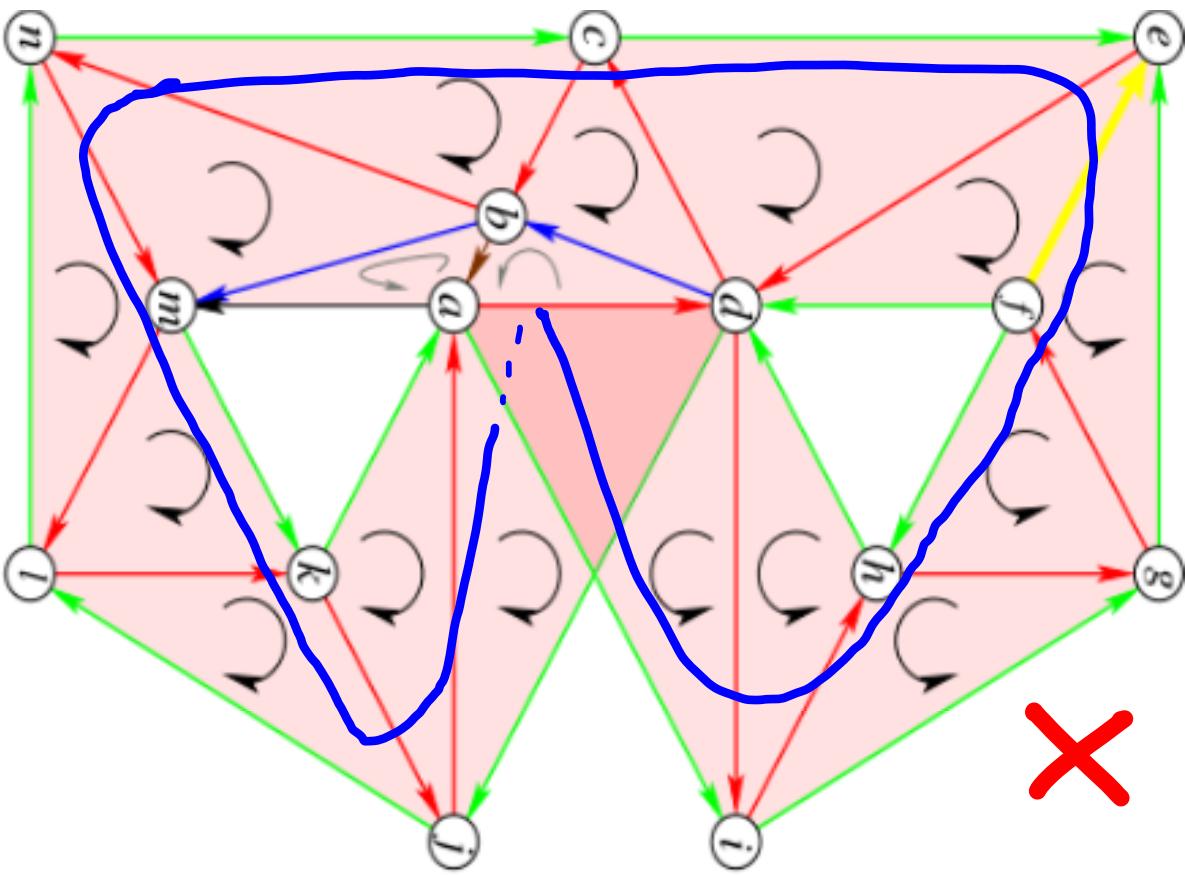
ensures that every fractional basic solution is a convex combination of two integral basic solutions.

K is non-TU neutralized (NTUN)

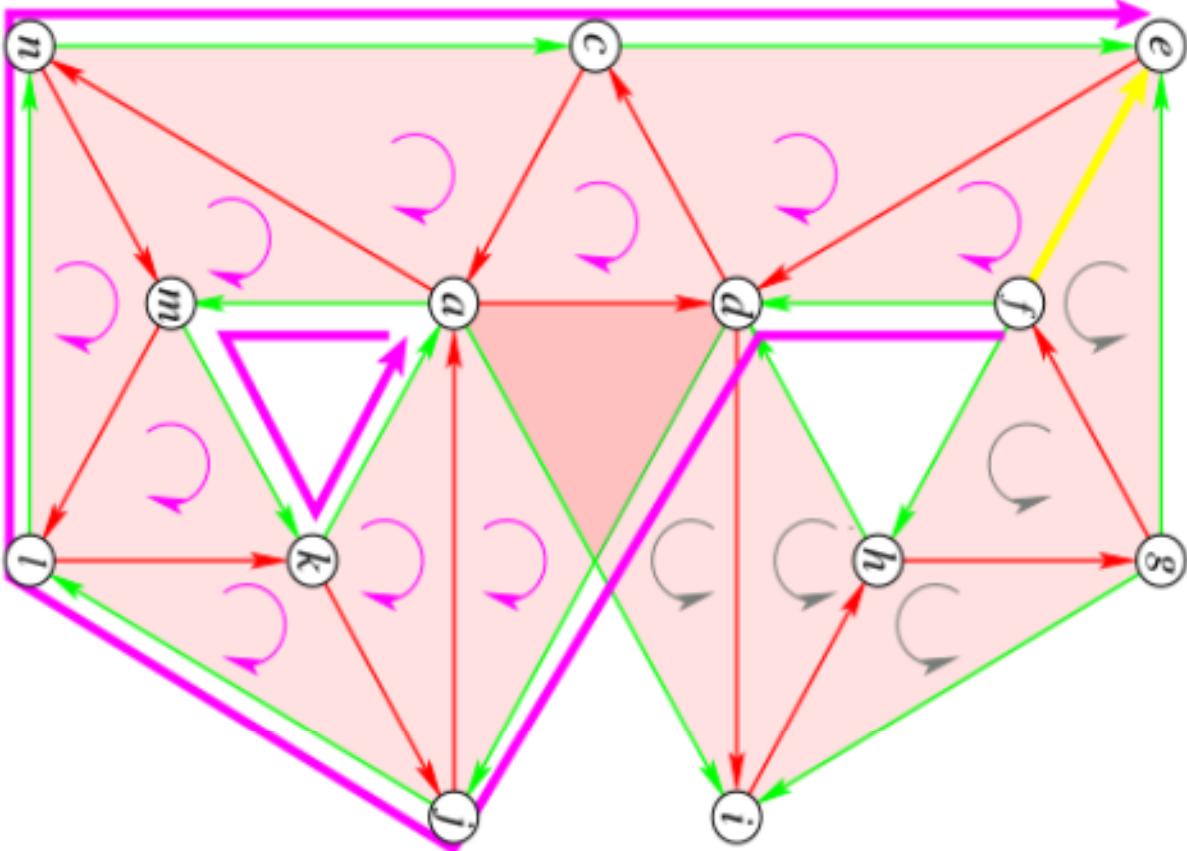


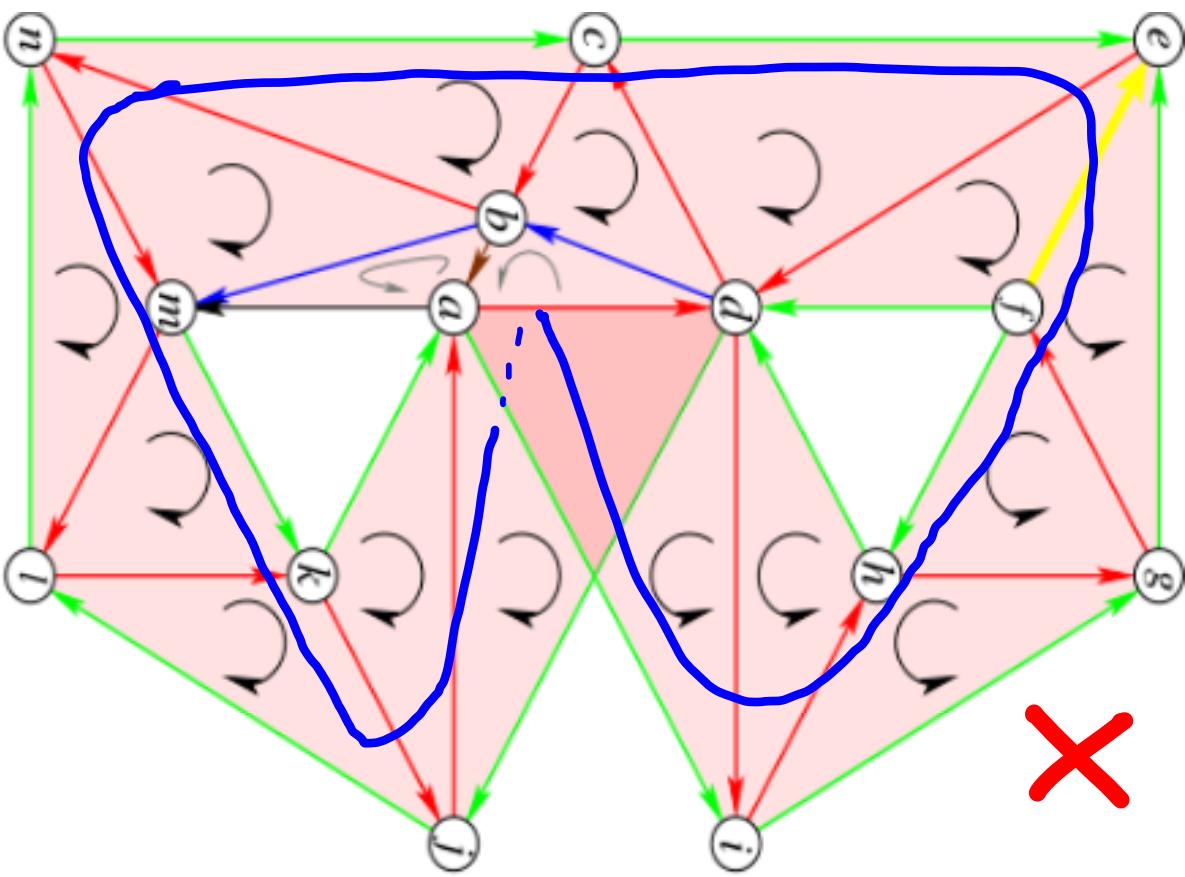
TUTOR NOT?



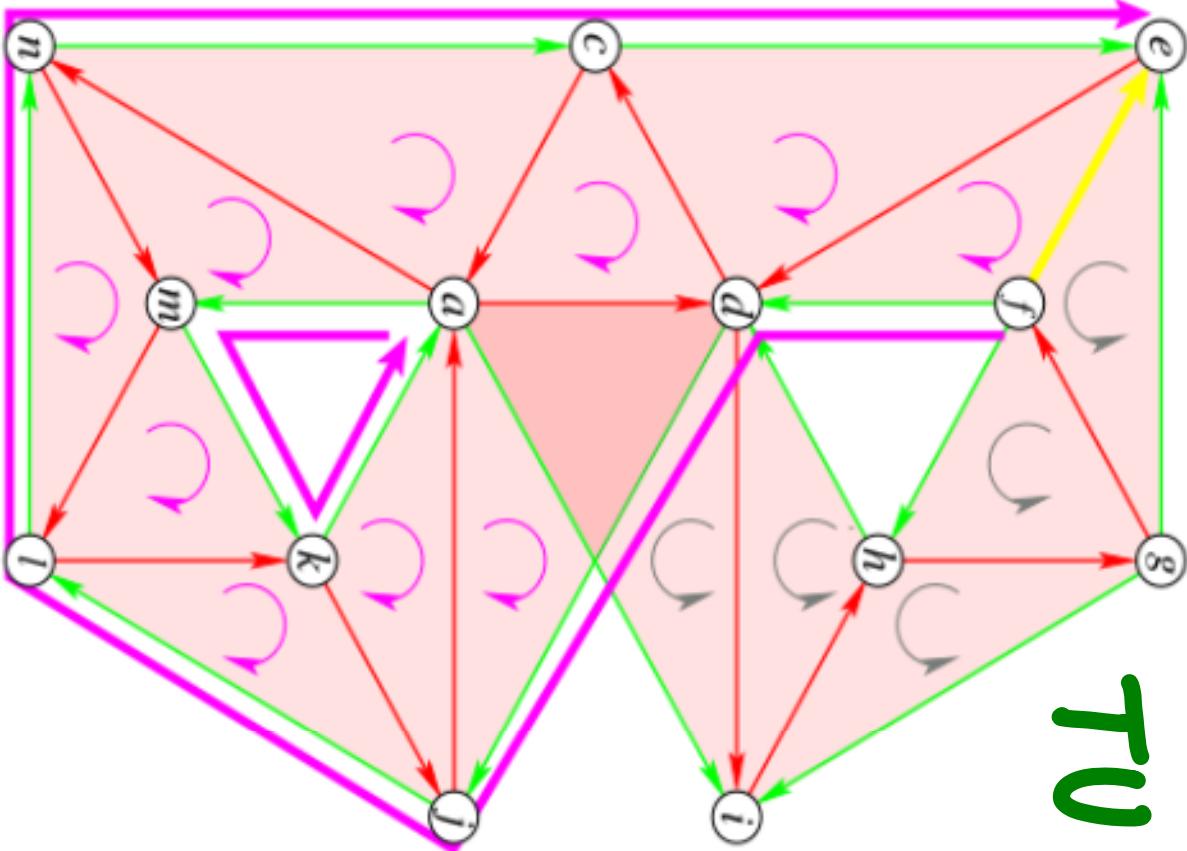


TUTOR NOT ?





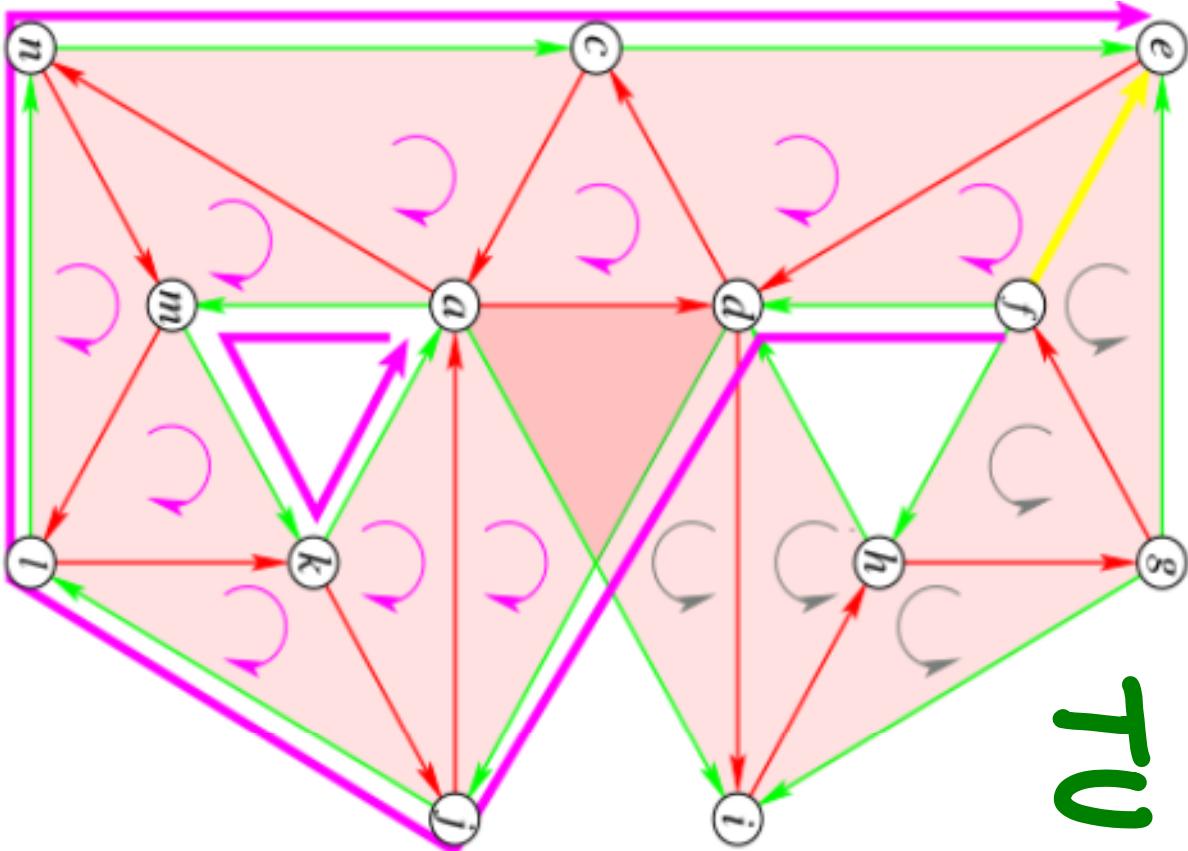
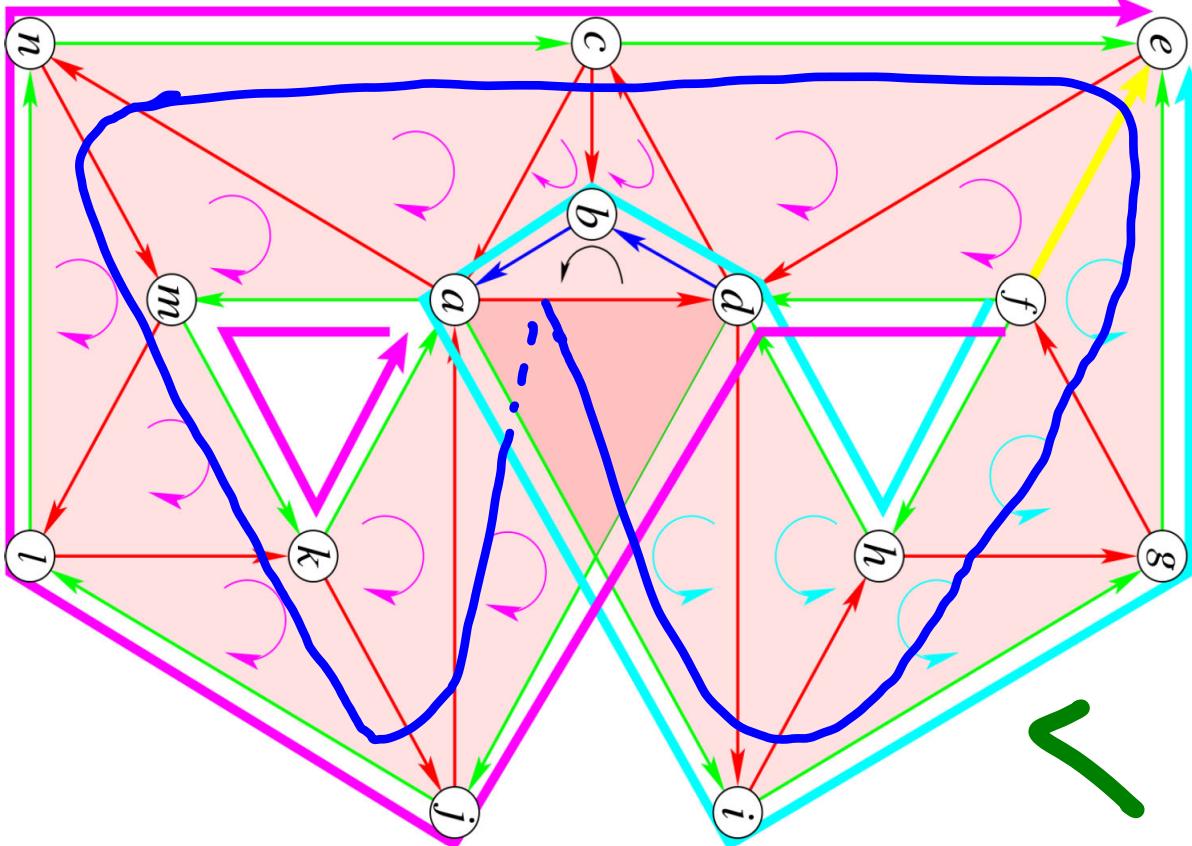
TU OR NOT ?



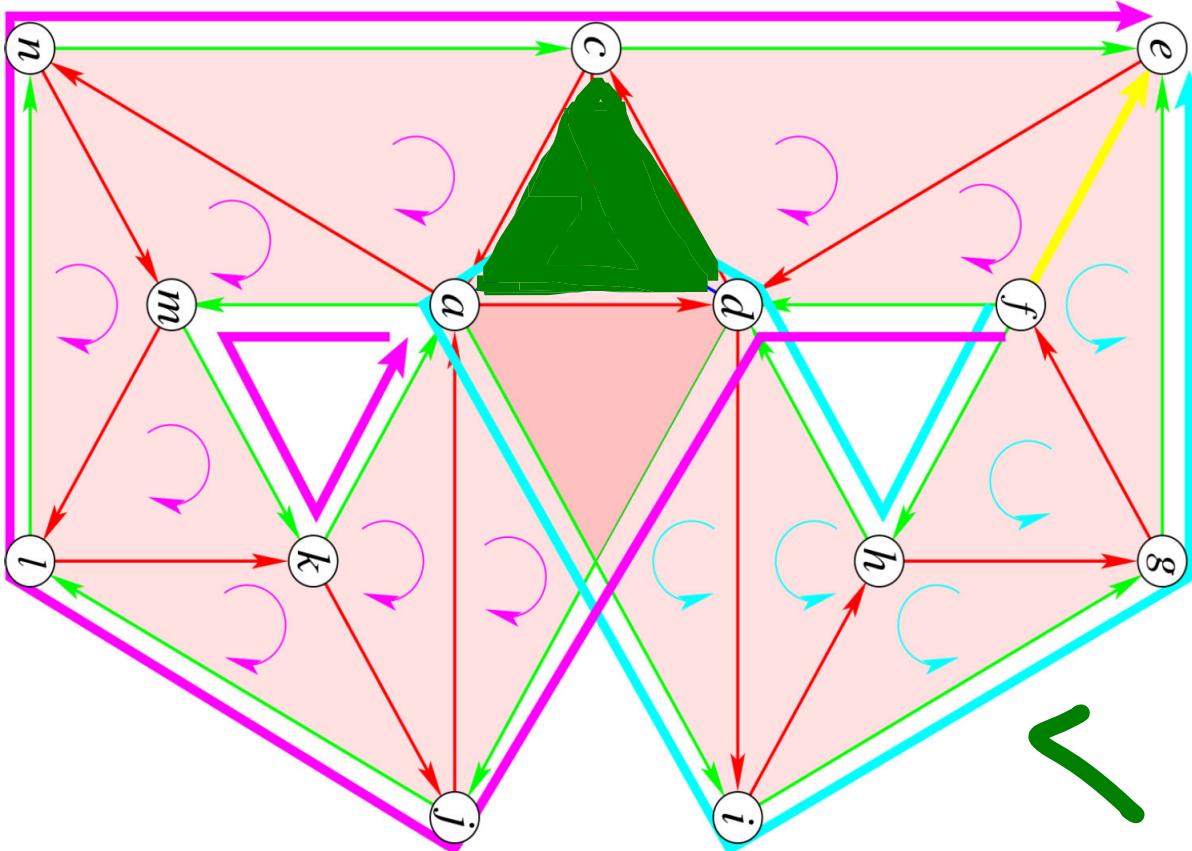
TU ✓

Non-TU
Neutralized

TU
✓



NEUTRALIZING CHAIN



a disc whose boundary consists of an odd number of red (heavy/manifold) edges

NON-TU NEUTRALIZED K

- ✓ Property of K - holds for every choice of weights on simplices and input chain

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Q2: NTUN result for MSFN?

MEDIAN SHAPE

Hu, Hudelson, K, Turmooch, Vixie, 2019

* flat distance between T, T' : $\mathbb{H}_\lambda(T, T') = \mathbb{E}_\lambda(T - T')$

flat norm w/ scale λ

MEDIAN SHAPE

Hu, Hudelson, K, Turmooch, Vixie, 2019

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flat norm w/ scale λ

* median of $\{T_i\}$:

$$\hat{T} = \arg \min_T \sum_i \mathbb{E}_\lambda (T - T_i)$$

MEDIAN SHAPE: LP

$$\begin{array}{l} \min \left[\begin{bmatrix} \mathbf{w} & \mathbf{w} & \lambda_{\mathbf{v}} & \lambda_{\mathbf{v}} \end{bmatrix} \begin{bmatrix} \mathbf{w} & \mathbf{w} & \lambda_{\mathbf{v}} & \lambda_{\mathbf{v}} \end{bmatrix} \dots \begin{bmatrix} \mathbf{w} & \mathbf{w} & \lambda_{\mathbf{v}} & \lambda_{\mathbf{v}} \end{bmatrix} \mathbf{x} \right. \\ \text{s.t.} \end{array}$$

$$\left[\begin{bmatrix} I & -I \\ I & -I \\ \vdots \\ I & -I \end{bmatrix} \begin{bmatrix} -I & I & -B & B \\ -I & I & -B & B \\ \ddots \\ -I & I & -B & B \end{bmatrix} \mathbf{x} = \begin{bmatrix} \mathbf{t}_1 \\ \mathbf{t}_2 \\ \vdots \\ \mathbf{t}_N \end{bmatrix} \right]$$

$$\begin{bmatrix} \mathbf{t}^+ & \mathbf{t}^- & \mathbf{r}_1^+ & \mathbf{r}_1^- & \mathbf{s}_1^+ & \mathbf{s}_1^- & \mathbf{r}_2^+ & \mathbf{r}_2^- & \mathbf{s}_2^+ & \mathbf{s}_2^- & \dots & \mathbf{r}_N^+ & \mathbf{r}_N^- & \mathbf{s}_N^+ & \mathbf{s}_N^- \end{bmatrix} \geq 0.$$

$$\mathcal{B} = [\partial_{ph}]$$

MEDIAN SHAPE: LP

$$\begin{aligned} \min & \left[\begin{bmatrix} w & w & \lambda v & \lambda v \end{bmatrix} \begin{bmatrix} w & w & \lambda v & \lambda v \end{bmatrix} \dots \begin{bmatrix} w & w & \lambda v & \lambda v \end{bmatrix} \mathbf{x} \right. \\ \text{s.t.} & \quad \left. \begin{bmatrix} I & -I \\ I & -I \\ \vdots \\ I & -I \end{bmatrix} \begin{bmatrix} -I & I & -B & B \\ -I & I & -B & B \\ \ddots \\ -I & I & -B & B \end{bmatrix} \mathbf{x} = \begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ t_N \end{bmatrix} \right] \end{aligned}$$

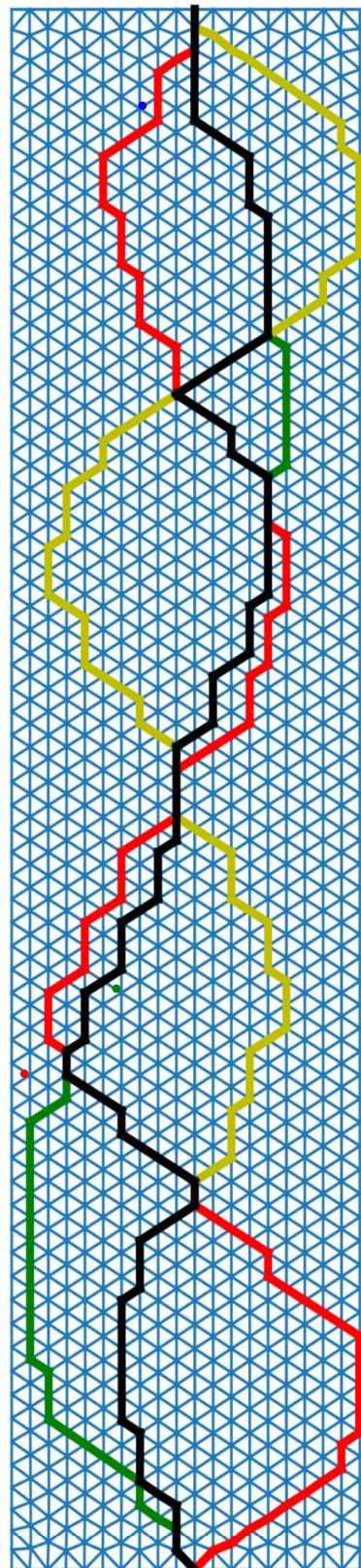
$$\begin{bmatrix} t^+ & t^- & r_1^+ & r_1^- & s_1^+ & s_1^- & r_2^+ & r_2^- & s_2^+ & s_2^- & \dots & r_N^+ & r_N^- & s_N^+ & s_N^- \end{bmatrix} \geq 0.$$

$$B = [\partial_{\rho_i}]$$

X constraint matrix not TU even if $[\partial_{\rho_i}]$ is !

MEDIAN SHAPE : EXAMPLES

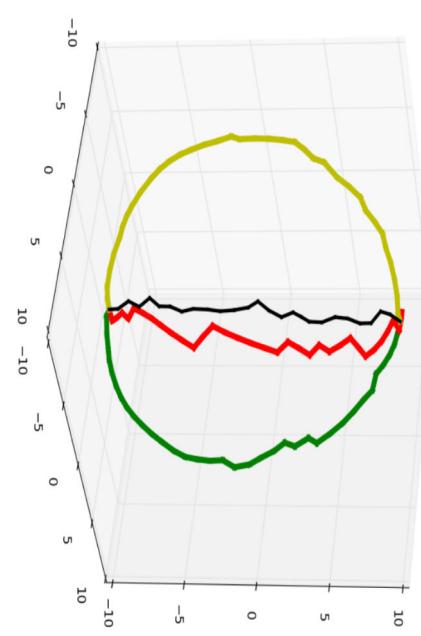
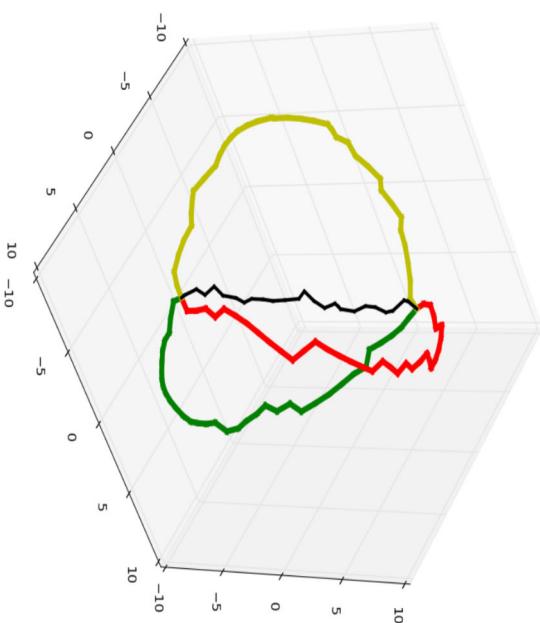
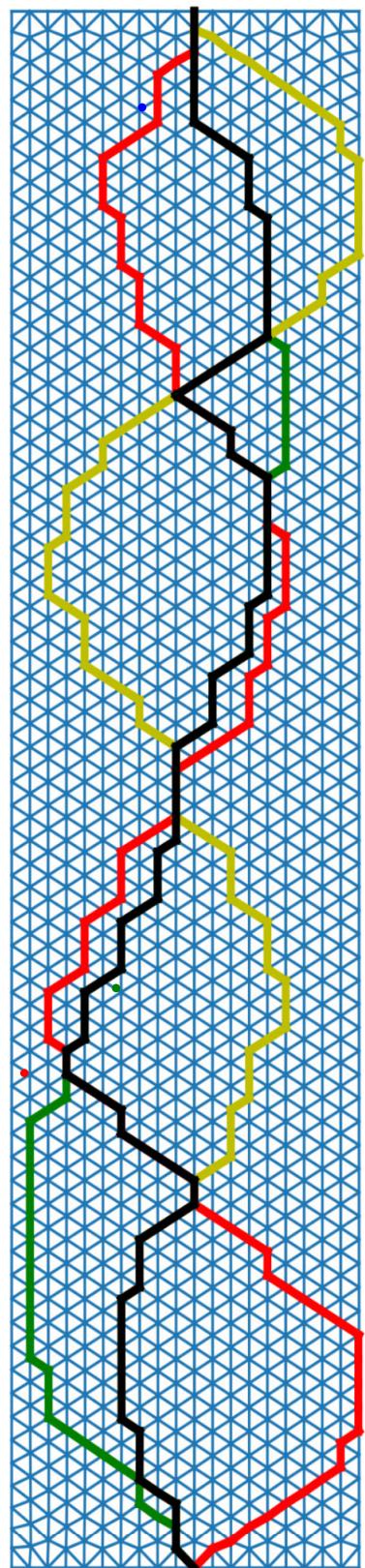
$[Q_2]$ is TU, but LP matrix is not



$\hat{\tau}$ T_3 T_2 T_1

MEDIAN SHAPE: EXAMPLES

$[2_2]$ is TU , but LP matrix is not



$[2_2]$ is not TU

MEDIAN SHAPE : QUESTIONS

Q3: When/Why does median shape LP give integer solutions for free?

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Q4: Network flow (dual graph) model for median shape ?

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Thank you !