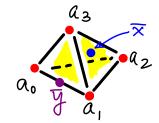
MATH 524 - Lecture 3 (08/29/2023)

Today: * Properties of Simplices * Simplicial complexes * underlying Space

Recall $\{\bar{a}_{s},...,\bar{a}_{n}\}$. GI set of points in \mathbb{R}^{d} , P: n-plane spanned by \bar{a}_{i} 's; havy centric coordinates n-simplex $\sigma = \{x \in \mathbb{R}^{d} \mid \overline{x} = \sum_{i=0}^{n} t_{i}a_{i}, \sum_{i=0}^{n} t_{i} = 1, t \neq 0\}$. We continue with properties of simplices. σ could be σ itself!

Given $\overline{X} \in \mathcal{T}$, there is exactly one face \mathcal{T} 8-t. $\overline{X} \in \mathbb{I}$ nt \mathcal{T} . \mathcal{T} is that face of \mathcal{T} Spanned by those $\overline{a_i}$ for which $\overline{t_i}(\overline{X}) > 0$.

 \overline{x} is interior to $\triangle a_1 a_2 a_3$ \overline{y} is interior to $\overline{a_0}a_1$

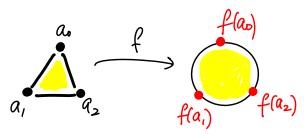


- (3) of is a compact, convex set in IRd, and is the intersection of all convex sets in IRd containing $\bar{a}_0,...,\bar{a}_n$.
- (4) There exists one and only one GI set of points $\xi \bar{a}_0, ..., \bar{a}_n \xi$ Spanning σ .
- (5) Into is convex, and is open in P, and Cl (Int o) = o. Int o is the union of all closure "open line segments" joining as with points in Into, where T is the face opposite as.

Def Unit ball: $B^n = \{ x \in \mathbb{R}^n \mid ||x|| \le 1 \}$ Unit sphere: $S^{n-1} = \{ x \in \mathbb{R}^n \mid ||x|| = 1 \}$ We will supper/lower hamisphere: $E^{n-1} \neq F^{n-1} = F^{n-1}$

(6) There is a homeomorphism of with Br that carries 20 to Sint

(proof in Munkres [M] EAT)

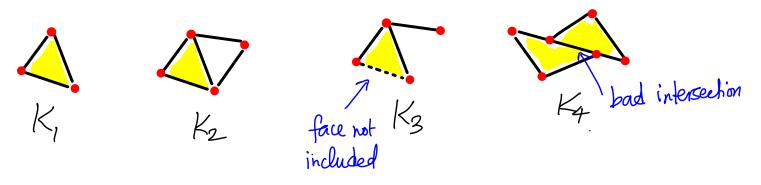


S'ee [M] (Munkres-Elements of Algebraic Topology) for the proof.

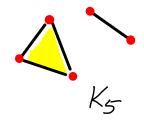
In summary, Simplices are "nice" elementary objects that can be used as building blocks to build larger spaces or objects. We will now introduce these larger objects, which are quite general, but are still "nice" since we which are quite general, but are still "nice" since we are "glwing" simplices together nicely to build them.

Def A simplicial complex K in Rd is a collection of simplices in Rd such that

- (1) every face of a simplex in K is in K, and
 (2) the intersection of any two simplifies of K, when
 non-empty is a face of each of them.



K1, K2 are simplicial complexes, while K3, K4 are not.



K= is a simplicial complex— in particular, a simplicial complex need not be a single connected component.

Here is another equivalent definition:

Lenna 2.1 [M] A collection of simplices K is a simplicial complex iff

- (1) every face of a simpler in K is in K; and (2) every pair of distinct simplices in K have disjoint interiors,

Def If L is a subcollection of K that contains all faces of its elements, then it is a simplicial complex on its own, called a subcomplex of K.



A subcomplex of K5

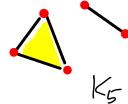
Def The subcomplex of K that is the collection of all simplices in K of dimension at most p is the simplices in K of denoted K.

K⁽⁰⁾ are the vertices of K.



 $K_{5}^{(1)}$ (the 1-skeleton of K_{5}).

Def The dimension of a simplicial complex K is the largest dimension of any simplex in K. dim (K) = max {dim(\sigm)}.



 $dim(K_5) = 2$, also referred to as a 2-complex.

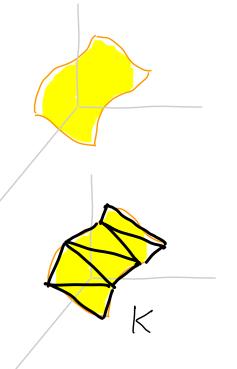
A p-dimensional simplicial complex is referred to, in short, as a p-complex.

Q. What is dim (K(p))? p-skeleton of K

One can immediately conclude $\dim(K^{(p)}) \leq p$. But notice that $\dim(K^{(p)})$ need not always be = p. For instance, $\dim(K_5^{(3)}) = 2$, since $K_5^{(3)} = K_5$ itself. But if we avoid this somewhat trivial case, $\dim(K^{(p)}) = p$, typically. Or more generally, $\dim(K^{(p)}) = \min(p, \dim(K))$.

Recall that we want to use simplicial complexes as a "nice" structured way to model spaces. We now outline the somewhat subtle distinction between the simplicial complex and the (sub) space that it models.

Let's start with an illustration.



Consider a subspace of, say, IR3 modeled by a sheet of paper. We could capture this space by a simplicial complex K consisting of six triangles.

Complementarily, if we start with K we could talk about the subspace of R3 that it captures. We can specify the usual topology on this subspace (as inherited from R3).

Def Let |K| be the subset of IRd which is the unim of all simplices in K. Give each simplex its natural topology as a subspace of IRd. Then we can topologize |K| by declaring a subset A of |K| is closed in |K| |K| by declaring a subset A of |K| is closed in |K| if A 100 is closed in K + 000 K. |K| is called the underlying space of K, or the polytope of K.

The underlying space of K, or the polytope of K.

also referred to as "polyhedron"

Some people use the word polytope only when K is finite, i.e., it has a finite number of simplices, while using the word polyhedron more generally, i.e., even for the case where K is not finite. In convex geometry, $P = \{\overline{x} \in \mathbb{R}^d \mid A\overline{x} \leq b\}$ is a polyhedron, and a closed polyhedron is referred to as a polytope.

The two topologies — one as a subspace of Rd, and the other defined using the simplices as above — need not be identical in all cases. But if K is finite, they usually concide. In fact, typical examples where they differ come from infinite simplicial complexes K.

|K| topologized in two different ways: here is an example where the two topologies are different.

Example $K = \{U[m,mt] \mid \forall m \in \mathbb{Z}[\{0\}]\} \}$ included $\{[\frac{1}{nt},\frac{1}{n}] \mid \forall n \in \mathbb{Z}_{>0}\} \}$ and all faces.

K is an infinite 1-complex. Infinitely many simplices $|K| = \mathbb{R}$ as a set, but not as a topological space. Indeed, $A = \{\frac{1}{2}, n \in \mathbb{Z}_{70}\}$ is closed in |K|, but not in |R|. But if K is finite, the topologies are the same.