

MATH 230 - Lecture 4 (01/20/2011)

Vector equations

$$\left. \begin{array}{l} 3x_1 + x_2 = 7 \\ x_1 + 2x_2 = 4 \end{array} \right\} \quad \left[\begin{matrix} 3 \\ 1 \end{matrix} \right] x_1 + \left[\begin{matrix} 1 \\ 2 \end{matrix} \right] x_2 = \left[\begin{matrix} 7 \\ 4 \end{matrix} \right] \quad x_1 = 2, x_2 = 1 \text{ is the unique solution}$$

Notation: The set of all n -vectors is denoted by \mathbb{R}^n .

e.g., $\bar{x} = \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} \in \mathbb{R}^3$ when $\alpha, \beta, \gamma \in \mathbb{R}$.

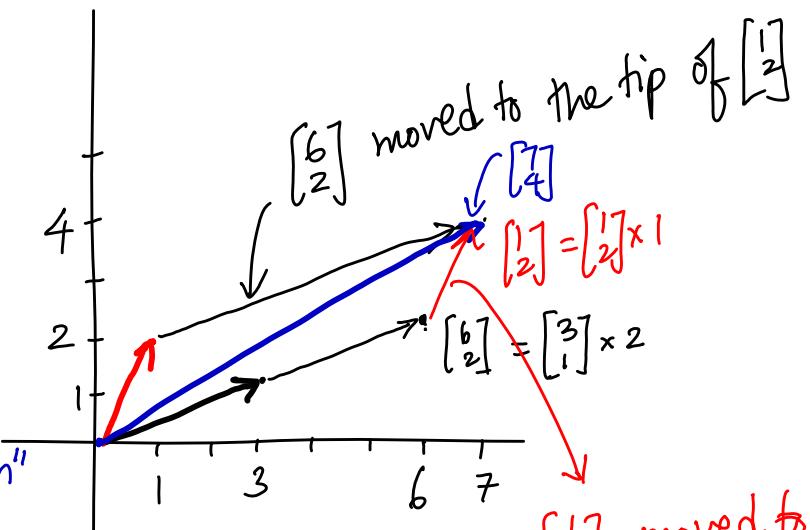
$\begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 7 \\ 4 \end{bmatrix}$ are vectors in \mathbb{R}^2 .

$c\bar{x}$ for $c \in \mathbb{R}$, $\bar{x} \in \mathbb{R}^n$

is vector-scalar multiplication.

If $\bar{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$, then also called "scalar multiplication"

$c\bar{x} = \begin{bmatrix} cx_1 \\ cx_2 \\ \vdots \\ cx_n \end{bmatrix}$. Also, $c\bar{x}$, "stretches" the vector \bar{x} by the factor c .



$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ moved to the tip of $\begin{bmatrix} 6 \\ 2 \end{bmatrix}$

In words, can you find multipliers x_1 and x_2 , which when used to scale the vectors $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$, and added, gives $\begin{bmatrix} 7 \\ 4 \end{bmatrix}$?

Note: $\bar{u} = [2 \ 3 \ 5]$ is a row-vector. It is NOT the same as $\bar{v} = \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$, which is a column vector.

By default, we assume vectors are column vectors.

Adding scalar multiples of vectors is called "taking a linear combination" of the vectors.

Def: For vectors $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n \in \mathbb{R}^m$, the vector

$\bar{v} = c_1 \bar{v}_1 + c_2 \bar{v}_2 + \dots + c_n \bar{v}_n$ for $c_i \in \mathbb{R}$ for all i , is a linear combination of $\bar{v}_1, \dots, \bar{v}_n$.

Note: We can add vectors \bar{u} and \bar{v} only if they have the same # entries.

So, $\begin{bmatrix} 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 3 \\ 5 \\ 2 \end{bmatrix}$ is not defined.

The c_i 's in the linear combination $\bar{v} = c_1 \bar{v}_1 + \dots + c_n \bar{v}_n$ are called weights of the linear combination.

$$\text{e.g. } -3 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -3 \times 3 \\ -3 \times 1 \end{bmatrix} + \begin{bmatrix} 4 \times 1 \\ 4 \times 2 \end{bmatrix} = \begin{bmatrix} -9 + 4 \\ -3 + 8 \end{bmatrix} = \begin{bmatrix} -5 \\ 5 \end{bmatrix}$$

So, $\begin{bmatrix} -5 \\ 5 \end{bmatrix}$ is a linear combination of $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ with weights $c_1 = -3$ and $c_2 = 4$.

Note that $\begin{cases} 3x_1 + x_2 = -5 \\ x_1 + 2x_2 = 5 \end{cases}$ has the solution $x_1 = -3, x_2 = 4$.

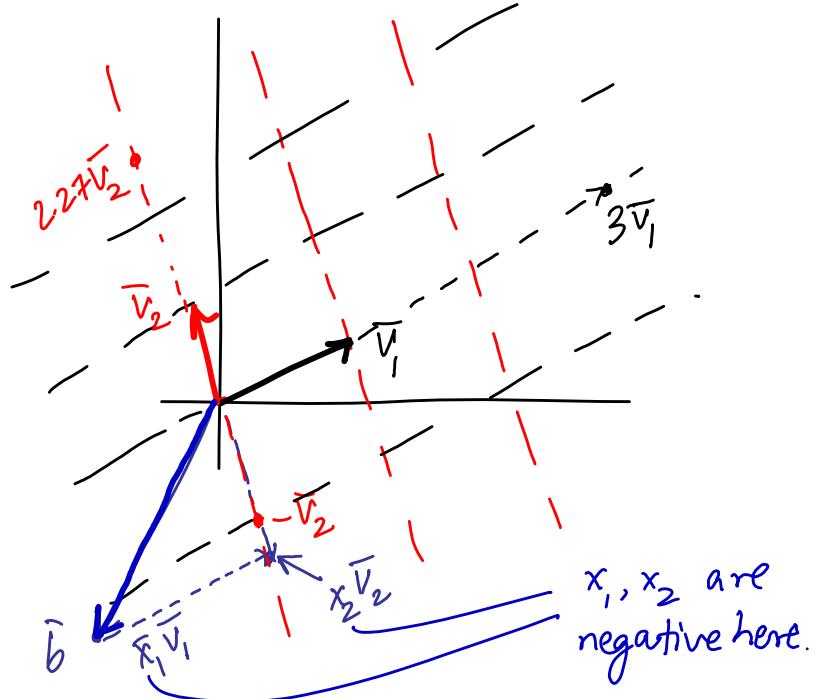
In general, if $\bar{b} = c_1 \bar{a}_1 + c_2 \bar{a}_2 + \dots + c_n \bar{a}_n$, then the system of linear equations whose augmented matrix is $\left[\begin{array}{ccc|c} \bar{a}_1 & \bar{a}_2 & \dots & \bar{a}_n & | & \bar{b} \end{array} \right]$ has a solution $x_1 = c_1, x_2 = c_2, \dots, x_n = c_n$.

Equivalently, to answer the question "Is the system with augmented matrix $\left[\begin{array}{ccc|c} \bar{a}_1 & \bar{a}_2 & \dots & \bar{a}_n & | & \bar{b} \end{array} \right]$ consistent?", we can answer the question "Can \bar{b} be written as a linear combination of $\bar{a}_1, \bar{a}_2, \dots, \bar{a}_n$?".

Def: The set of all linear combinations of $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n \in \mathbb{R}^m$ is called the **span** of $\{\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n\}$, and written $\text{span}\{\bar{v}_1, \dots, \bar{v}_n\}$.

We can write any vector in \mathbb{R}^2 as a linear combination of $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ & $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

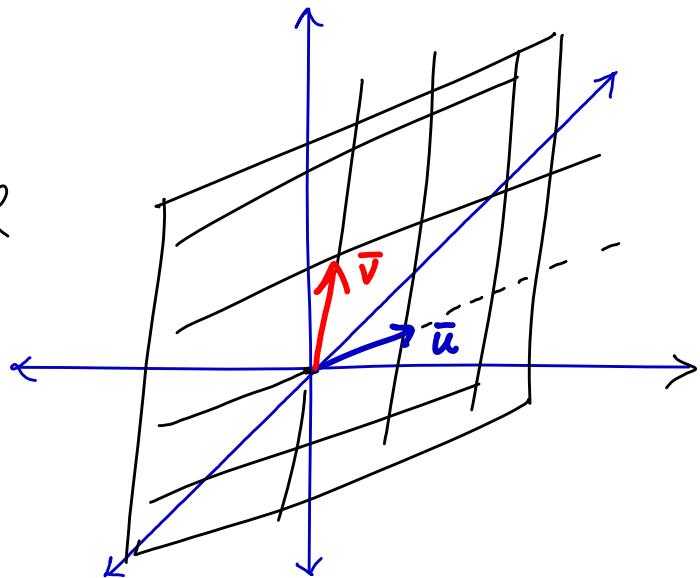
$$\text{span}\left\{\begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}\right\} = \mathbb{R}^2.$$



Note that the zero vector, or origin, is in every span.

$$\bar{0} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = 0 \cdot \bar{v}_1 + 0 \cdot \bar{v}_2 + \dots + 0 \cdot \bar{v}_n \quad (\text{take all weights as zero}).$$

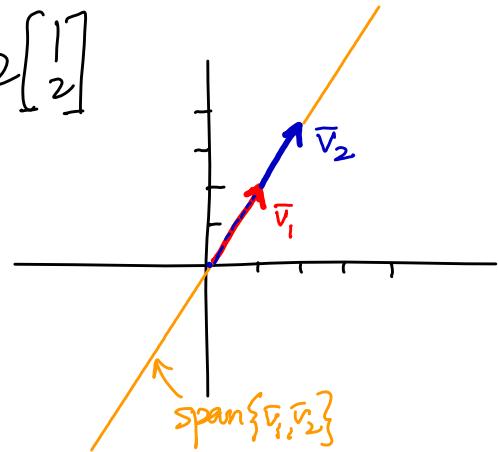
In \mathbb{R}^3 , the span of the two vectors \bar{u}, \bar{v} shown here is a plane passing through the origin.



But $\text{Span}\left\{\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}\right\}$ is just a line in \mathbb{R}^2 through the origin, as

$$\bar{v} = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 4 \end{bmatrix} = c_3 \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \text{ since } \begin{bmatrix} 2 \\ 4 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

\downarrow
 $[c_1 + 2c_2]$



Prob 18, pg 38

$$\bar{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}, \bar{v}_2 = \begin{bmatrix} -3 \\ 1 \\ 8 \end{bmatrix}, \bar{v}_3 = \begin{bmatrix} h \\ -5 \\ -3 \end{bmatrix}. \text{ For what values of } h$$

is \bar{v}_3 in the plane generated by \bar{v}_1 and \bar{v}_2 ?

refers to $\text{span}\{\bar{v}_1, \bar{v}_2\}$.

Reword: For what h is \bar{v}_3 in $\text{span}\{\bar{v}_1, \bar{v}_2\}$?

Equivalently, for what h is $\begin{bmatrix} 1 & -3 & h \\ 0 & 1 & -5 \\ -2 & 8 & -3 \end{bmatrix}$ the augmented

matrix of a consistent system?

$$\begin{bmatrix} 1 & -3 & h \\ 0 & 1 & -5 \\ -2 & 8 & -3 \end{bmatrix} \xrightarrow{R_3+2R_1} \begin{bmatrix} 1 & -3 & h \\ 0 & 1 & -5 \\ 0 & 2 & -3+2h \end{bmatrix} \xrightarrow{R_3-2R_2} \begin{bmatrix} 1 & -3 & h \\ 0 & 1 & -5 \\ 0 & 0 & 7+2h \end{bmatrix}$$

Need $7+2h=0$ to avoid $[0 \ 0 | \square]$ row.

$$\text{So, } h = -\frac{7}{2}.$$

Properties of \mathbb{R}^n (n-vectors)

$\bar{u}, \bar{v}, \bar{w} \in \mathbb{R}^n$, $c, d \in \mathbb{R}$, $\bar{0}$ is the zero vector
scalars

- (i) $\bar{u} + \bar{v} = \bar{v} + \bar{u}$ (v) $c(\bar{u} + \bar{v}) = c\bar{u} + c\bar{v}$
- (ii) $\bar{u} + (\bar{v} + \bar{w}) = (\bar{u} + \bar{v}) + \bar{w}$ (vi) $(c+d)\bar{u} = c\bar{u} + d\bar{u}$
- (iii) $\bar{u} + \bar{0} = \bar{0} + \bar{u} = \bar{u}$ (vii) $c(d\bar{u}) = (cd)\bar{u} = (c\bar{u})d$
- (iv) $\bar{u} + (-\bar{u}) = \bar{0}$

These are properties of addition and multiplication for scalars (i.e., real numbers) extended to the case of vectors.

TRUE/FALSE (Prob 23, pg 38)

- (c) An example of linear combination of \bar{v}_1 and \bar{v}_2 is $\frac{1}{2}\bar{v}_1$.

TRUE. $\frac{1}{2}\bar{v}_1 = \left(\frac{1}{2}\right)\bar{v}_1 + 0\bar{v}_2$ is a linear combination of \bar{v}_1 and \bar{v}_2 with weights $\frac{1}{2}, 0$.

- (e) $\text{span}\{\bar{u}, \bar{v}\}$ is always a plane through origin.

FALSE. If \bar{u} and \bar{v} are scalar multiples of each other, we get a line, not a plane - see page 4-5 above.

Introduction to MATLAB on <http://my.math.wsu.edu>.

`rref(A)` gives the reduced row echelon form of matrix A.