

MATH230 - Lecture 13 (02/22/2011)

Matrix Operations (Section 2.1)

$$A = [\bar{a}_1 \ \bar{a}_2 \dots \bar{a}_n] = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1j} & \dots & a_{1n} \\ \vdots & & & \boxed{a_{ij}} & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{ij} & \dots & a_{in} \\ \vdots & & & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mj} & \dots & a_{mn} \end{bmatrix}$$

→ i^{th} row

↓ j^{th} column

$\bar{a}_j \in \mathbb{R}^m$

A_{ij} is used sometimes in place of a_{ij} .

Notation: uppercase letters stand for matrices,
e.g., $A \in \mathbb{R}^{m \times n}$, $B, C \in \mathbb{R}^{n \times n}$ etc.

Matrix Addition

$A + B$ is defined when A and B have the same size. If $G = A + B$, then

$$c_{ij} = a_{ij} + b_{ij} \quad (\text{or } c_{ij} = A_{ij} + B_{ij}).$$

(add corresponding entries)

Scalar multiplication

$B = rA$ for scalar r , then

$$b_{ij} = r \cdot a_{ij} \quad (\text{multiply each entry by scalar } r).$$

Properties of matrix addition & scalar multiplication

(Theorem 1, pg 108).

$$A, B, C \in \mathbb{R}^{m \times n}, \quad r, s \in \mathbb{R}$$

(a) $A + B = B + A$

(b) $(A + B) + C = A + (B + C)$

(c) $A + 0 = A \rightarrow m \times n \text{ zero matrix}$

(d) $r(A + B) = rA + rB$

(e) $(r+s)A = rA + sA$

(f) $r(sA) = (rs)A$

Matrix multiplication

We have seen $A\bar{x}$ for $m \times n$ matrix A and n -vector \bar{x} , or an $n \times 1$ matrix \bar{x} .

Def $C = AB$ is defined when A is $m \times n$ and B is $n \times p$, i.e., when # columns in A = # rows in B .

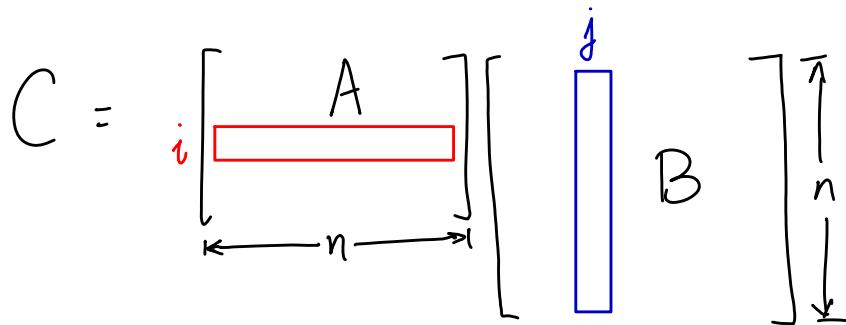
$$A = [\bar{a}_1 \dots \bar{a}_n] \quad \bar{a}_j \in \mathbb{R}^m$$

$$B = [\bar{b}_1 \dots \bar{b}_p] \rightarrow \begin{bmatrix} \bar{b}_1 \\ \bar{b}_2 \\ \bar{b}_3 \\ \vdots \\ \bar{b}_n \end{bmatrix} \quad \bar{b}_i \in \mathbb{R}^n$$

need to be same.

$$C = AB = A [\bar{b}_1 \dots \bar{b}_p] , \quad \bar{b}_i \in \mathbb{R}^n$$

$$= [A\bar{b}_1 \ A\bar{b}_2 \ \dots \ A\bar{b}_p]$$



$$c_{ij} = \begin{matrix} a_{i1} a_{i2} \dots a_{in} \\ \boxed{b_{1j}} \\ b_{2j} \\ \vdots \\ b_{nj} \end{matrix} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj}$$

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

Example

$$A = \begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 3 & 0 \\ -1 & 2 & 4 \end{bmatrix}$$

$2 \times 2 \qquad \qquad \qquad 2 \times 3$

$C = AB$ is defined, but
 BA is not defined.

$$C = \begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix} \quad \begin{bmatrix} 2 & -1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 & 4 & -4 \\ 3 & 9 & 0 \end{bmatrix}$$

$2 \times 1 + (-1) \times (-1)$
 $3 \times 3 + 0 \times 2$

$C = AB$ for $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{n \times p}$ will have size $m \times p$, i.e., $C \in \mathbb{R}^{m \times p}$.

Prob 10, pg 116

$$A = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix}, B = \begin{bmatrix} 8 & 4 \\ 5 & 5 \end{bmatrix}, C = \begin{bmatrix} 5 & -2 \\ 3 & 1 \end{bmatrix}. \text{ Is } AB = AC? \\ \text{What about } AB \stackrel{?}{=} BA?$$

$$AB = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix} \begin{bmatrix} 8 & 4 \\ 5 & 5 \end{bmatrix} = \begin{bmatrix} 2 \cdot 8 - 3 \cdot 5 & 2 \cdot 4 - 3 \cdot 5 \\ -4 \cdot 8 + 6 \cdot 5 & -4 \cdot 4 + 6 \cdot 5 \end{bmatrix} = \begin{bmatrix} 1 & -7 \\ -2 & 14 \end{bmatrix}$$

$$AC = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix} \begin{bmatrix} 5 & -2 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 2 \cdot 5 - 3 \cdot 3 & 2 \cdot -2 - 3 \cdot 1 \\ -4 \cdot 5 + 6 \cdot 3 & -4 \cdot -2 + 6 \cdot 1 \end{bmatrix} = \begin{bmatrix} 1 & -7 \\ -2 & 14 \end{bmatrix}$$

$$\text{So, } AB = AC.$$

$$BA = \begin{bmatrix} 8 & 4 \\ 5 & 5 \end{bmatrix} \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix} = \begin{bmatrix} 8 \cdot 2 + 4 \cdot -4 & 8 \cdot 3 + 4 \cdot 6 \\ 5 \cdot 2 - 5 \cdot 4 & 5 \cdot -3 + 5 \cdot 6 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ -10 & 15 \end{bmatrix}$$

$$AB \neq BA \text{ here.}$$

In general, $AB \neq BA$. In fact, BA may not even be defined. If $A \in \mathbb{R}^{2 \times 2}$, $B \in \mathbb{R}^{2 \times 3}$, then AB is defined, but BA is not.

Properties of matrix multiplication

(Theorem 2, pg 113)

* AB is not typically equal to BA (BA may not even be defined)

- (a) $A(BC) = (AB)C$ (associativity)
 - (b) $A(B+C) = AB+AC$ (left distributive property)
 - (c) $(B+C)A = BA+CA$ (right distributive property)
 - (d) $r(AB) = (rA)B = A(rB)$
 - (e) $I_m A = A = AI_n$ (identity)
- I_m : $m \times m$ identity, I_n : $n \times n$ identity matrix
-

Proof of (b). $A(B+C) = AB+AC$

$$B = \begin{bmatrix} \bar{b}_1 & \bar{b}_2 & \cdots & \bar{b}_p \end{bmatrix}$$

$$C = \begin{bmatrix} \bar{c}_1 & \bar{c}_2 & \cdots & \bar{c}_p \end{bmatrix}$$

$A_{m \times n}$

$B_{n \times p}$

$C_{n \times p}$

$$A(B+C) = A \left(\begin{bmatrix} \bar{b}_1 & \bar{b}_2 & \cdots & \bar{b}_p \end{bmatrix} + \begin{bmatrix} \bar{c}_1 & \bar{c}_2 & \cdots & \bar{c}_p \end{bmatrix} \right)$$

$$= A \left[(\bar{b}_1 + \bar{c}_1) \quad (\bar{b}_2 + \bar{c}_2) \quad \cdots \quad (\bar{b}_p + \bar{c}_p) \right]$$

$$= \left[A(\bar{b}_1 + \bar{c}_1) \quad A(\bar{b}_2 + \bar{c}_2) \quad \cdots \quad A(\bar{b}_p + \bar{c}_p) \right]$$

from matrix addition
of B & C

$$= \begin{bmatrix} A\bar{b}_1 + A\bar{c}_1 & A\bar{b}_2 + A\bar{c}_2 & \dots & A\bar{b}_p + A\bar{c}_p \end{bmatrix} \quad \text{from matrix-vector multiplication}$$

$$= [A\bar{b}_1 \ A\bar{b}_2 \ \dots \ A\bar{b}_p] + [A\bar{c}_1 \ A\bar{c}_2 \ \dots \ A\bar{c}_p]$$

$$= AB + AC$$

Transpose of a matrix A (A^T) T in superscript

Interchange rows and columns of A to get A^T .

e.g. $A = \begin{bmatrix} 2 & 1 & 0 \\ 4 & -3 & 6 \end{bmatrix}_{2 \times 3} \Rightarrow A^T = \begin{bmatrix} 2 & 4 \\ 1 & -3 \\ 0 & 6 \end{bmatrix}_{3 \times 2}$

If $A \in \mathbb{R}^{m \times n}$, then $A^T \in \mathbb{R}^{n \times m}$.

Properties of matrix transposes

(a) $(A^T)^T = A$

(b) $(A+B)^T = A^T + B^T$ transpose of product = product of transposes in reverse order

(c) $(rA)^T = rA^T$

(d) $(AB)^T = B^T A^T$

Prob 10, pg 116 (contd...)

$$A = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix}, B = \begin{bmatrix} 8 & 4 \\ 5 & 5 \end{bmatrix}. \quad \text{Verify that } (AB)^T = B^T A^T.$$

$$AB = \begin{bmatrix} 1 & -7 \\ -2 & 14 \end{bmatrix} \quad (\text{from before - see page 13-4})$$

$$\Rightarrow (AB)^T = \begin{bmatrix} 1 & -2 \\ -7 & 14 \end{bmatrix}$$

$$B^T A^T = \begin{bmatrix} 8 & 5 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 2 & -4 \\ -3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & -2 \\ -7 & 14 \end{bmatrix}$$

$$A^T B^T = \begin{bmatrix} 2 & -4 \\ -3 & 6 \end{bmatrix} \begin{bmatrix} 8 & 5 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} 0 & -10 \\ 0 & 15 \end{bmatrix} = (BA)^T$$

Power of a matrix

If $A \in \mathbb{R}^{n \times n}$, then $A^k = \underbrace{A \cdot A \cdots A}_{k \text{ times}}$

e.g.,

$$\text{When } A = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix}, A^2 = \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix} \begin{bmatrix} 2 & -3 \\ -4 & 6 \end{bmatrix} = \begin{bmatrix} 16 & -24 \\ -32 & 48 \end{bmatrix}.$$

We will do an example that motivates the definition of the "inverse" of a matrix.

Prob 17, pg 117

If $A = \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix}$, and $AB = \begin{bmatrix} -1 & 2 & -1 \\ 6 & -9 & 3 \end{bmatrix}$, find B.

Since A is 2×2 , and AB 2×3 , B must be a 2×3 matrix.

Let $B = \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \end{bmatrix}$.

$$\begin{aligned} AB &= \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \end{bmatrix} = \begin{bmatrix} b_{11} - 2b_{21} & b_{12} - 2b_{22} & b_{13} - 2b_{23} \\ -2b_{11} + 5b_{21} & -2b_{12} + 5b_{22} & -2b_{13} + 5b_{23} \end{bmatrix} \\ &= \begin{bmatrix} -1 & 2 & -1 \\ 6 & -9 & 3 \end{bmatrix} \end{aligned}$$

\bar{c}

We can find $\begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix}$ by solving the system of linear equations given as $\begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix} = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$. Similar calculations

could give us $\bar{b}_2 = \begin{bmatrix} b_{21} \\ b_{22} \end{bmatrix}$ and $\bar{b}_3 = \begin{bmatrix} b_{31} \\ b_{32} \end{bmatrix}$. Notice that

the coefficient matrix A is the same in all three systems here!