MATH 401: Lecture 11 (09/23/2025)

Midterm exam: Oct 7
Take-home exam; sections 1.1-1.6, 2.1, 2.2

Today: * Metric spaces

Mean Value Theorem (MVT) on R

For the final theorem (4th one, after IVT, BW, EVT), we assume the function is much "nicer", i.e., it's deferentiable, to be able to present a stronger result on its structure. We reall the definition of derivative first.

Recall: Derivative of function f at x=a is $f'(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$ is $f(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$ is $f(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$ is $f(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$.

The mean value theorem says for a differentiable and continuous function of on [a,b], there exists a point inside the interval where the instantaneous slope of the function is equal to the 'mean' slope of over the interval. We need two results to be used as building blocks first.

Lemma 2.3.5 Let $f: [a_1b] \rightarrow \mathbb{R}$ have a maximum or minimum at an inner point $c \in (a_1b)$ where the function is differentiable. Then f'(c)=0.

Proof We show f'(c) > 0 or f'(c) < 0 is not possible. Assume f'(c) > 0. A similar argument works for f'(c) < 0.

 $f(c) = \lim_{x \to c} \frac{f(x) - f(c)}{x - c}$ by definition.

 $\Rightarrow \frac{f(x)-f(c)}{x-c} > 0 \text{ for all } x \text{ sufficiently close to } c.$

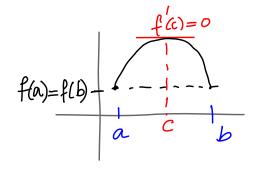
 $\Rightarrow \quad \begin{array}{l} x-c \\ \Rightarrow \\ x>c \\ \Rightarrow \\ f(x)>f(c), \text{ and} \\ & f(x)=f(c) \text{ for } \forall x. \\ & \\ x>c \\ \Rightarrow \\ x=c \text{ is neither a } \\ \underline{maximum} \text{ nor minimum: argument now.} \\ \square \end{array}$

Lemma 2.3.6 (Rolle's Theorem) Let $f:[a,b] \to \mathbb{R}$ be continuous at all $x \in [a_1b]$ and is differentiable at all inner points $x \in (a_1b)$. If f(a) = f(b), then there exists a point $c \in (a,b)$ such that f(c) = a

Proof EVT (Theorem 2.3.4) =>

f has a maximum and minimum in [a,b]. Since f(a)=f(b), at least one of these optima must be at an inner point c.

So Lemma 2.3.5 $\Rightarrow f(c)=0$.



Trivial case: f(x)=fa) YxE[a,b]

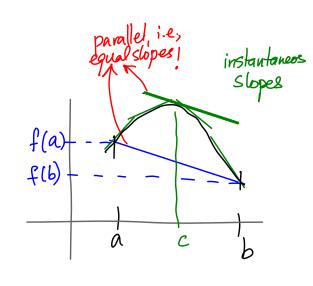
S straight line!

Theorem 2.3.7 (The Mean Value Theorem (MVT))

Let $f: [a,b] \rightarrow \mathbb{R}$ be continuous in all [a,b] and differentiable at all inner points $x \in (a,b)$. Then there exists $c \in (a,b)$ s.t.

$$f(c) = \frac{f(b) - f(a)}{b - a}$$

The mean (or average) slope of f(x) over [a,b] is f(b)-f(a)/(b-a). This theorem says there is a point $C \in (a,b)$ where the instantaneous slope, i.e., slope of tangent, is equal to the mean elope!



Proof

let
$$g(x) = f(x) - \left(\frac{f(b) - f(a)}{b - a}\right)(x - a)$$
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$$g(a) = f(a)$$
, and $b > a$ by assumption, and $g(b) = f(b) - \left(\frac{f(b) - f(a)}{b - a}\right)(b - a) = f(a)$. hence $b - a \neq 0$.

We can show that g(x) is indeed continuous in $[a_1b]$ and differentiable at all $x \in (a_1b)$. $\Longrightarrow g(x) = f(x) + m(x-a)$ for constant m_i f(x) is continuous and differentiable, and so is (x-a); their sum is so as well.

So, Rolle's theorem. (Lemma 2.3.6) \Rightarrow $\exists c \in (a_1b) \text{ s.t. } g'(c)=0.$

$$\Rightarrow g'(x) = f'(x) - \left(\frac{f(b)-f(a)}{b-a}\right) = 0 \text{ at } x=c.$$

$$\Rightarrow f'(c) = \frac{f(b)-f(a)}{b-a}.$$

Now, how did we come up with the g(x) function?!

$$f'(c) = \lim_{x \to c} \frac{f(x) - f(c)}{x - c} = \frac{f(b) - f(a)}{b - a}$$

$$f'(x) \Big|_{x = c} = \Rightarrow f'(x) - \left(\frac{f(b) - f(a)}{b - a}\right) \Big|_{x = c} = o$$

Looks like g'(x)=0 for some function g(x).

We want to find g(x) such that g(a) = g(b) = 0, and then we could use Polle's theorem!

So we take antiderivative of
$$f'(x) - \frac{f(b) - f(a)}{b - a}$$
 to get $f(x) - \left(\frac{f(b) - f(a)}{b - a}\right) \times + C \longrightarrow constant$

With
$$g(x) = f(x) - \left(\frac{f(b) - f(a)}{b - a}\right) \times + C$$
, we choose C such that $g(a) = g(b)!$ Note that

$$f(b) - \left(\frac{f(b) - f(a)}{b - a}\right)b + \left(\frac{f(b) - f(a)}{b - a}\right)a = f(a) = f(a) - \left(\frac{f(b) - f(a)}{b - a}\right)a + \left(\frac{f(b) - f(a)}{b - a}\right)a.$$

$$g(b)$$

We have showed several results on sequences and functions in R and R. But many of these results could be shown for far more general spaces which have many of the nice properties of R (or Rm). We define metric spaces with this goal in mind.

3.1 Definitions

Def A metric space (X, d) consists of a set $X \neq \emptyset$, and a function $d: X \times X \longrightarrow [0, \infty)$ such that

(i) (possitivity) d(X, X)

- (i) (positivity) $d(x,y) \equiv 0 + x, y \in X$, and $d(x_iy) = 0$ iff $x = y_i$
- (ii) (symmetry) $d(x,y) = d(y,x) + x,y \in X$; and
- (iii) (triangle inequality) $d(x,y) \leq d(x,z) + d(z,y) \forall x,y,z \in X$.

hold. A function of satisfying (i)-(iii) on X is a metric on X.

We sometimes write just X, when the metric d is evident.

At the same time, note that a space X could have multiple metrics defined on it. The first example we consider studies a metric on IR2 that is different from the usual Euclidean metric.

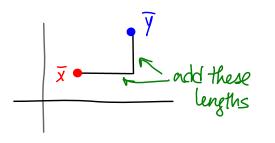
Examples

LSIRA eq.3 Manhattan or taxi cab metric (in $\mathbb{R}^{\frac{1}{2}}$). For $\overline{x}, \overline{y} \in \mathbb{R}^2$, let $\overline{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \overline{y} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

$$\overline{X} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \overline{Y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \overline{Z} = \begin{pmatrix} Z_1 \\ Z_2 \end{pmatrix}$$

 $d(\overline{x},\overline{y}) = |y_1-x_1| + |y_2-x_2|.$

Check that this is a metric space.



The intuition is that if a taxi is to go from point X to point Y in Sowntown Manhattan with perpendicular streets, it will have to go East/west (horizontal) and then North/South (vertical). We add these two straight line distances to get the taxi cab distance between X and Y.

- (i) $d(\bar{x}, \bar{y}) = 0$ holds, as $|x_1 y_1| = 0$ and $|x_2 y_2| = 0$. The only way we get $d(\bar{x},\bar{y})=0$ is when both absolute differences are zero, i.e., when $x_1=y_1$, and $x_2=y_2$, i.e., when $\bar{x}=\bar{y}$.
- (ii) $d(\bar{x}, \bar{y}) = d(\bar{y}, \bar{x})$ follows from absolute differences being symmetric, i.e., $|x_i-y_i|=|y_i-x_i|$ for i=1,2.
- (iii) Triangle inequality:

$$d(\bar{x}_{1}\bar{y}) = |y_{1}-x_{1}| + |y_{2}-x_{2}|$$

$$= |y_{1}-z_{1}+z_{1}-x_{1}| + |y_{2}-z_{2}+z_{2}-x_{2}|$$

$$= |y_{1}-z_{1}| + |z_{1}-x_{1}| + |y_{2}-z_{2}| + |z_{2}-x_{2}|$$

$$= |y_{1}-z_{1}| + |z_{1}-x_{1}| + |y_{2}-z_{2}| + |z_{2}-x_{2}|$$

$$= d(x,z) + d(z_{1}y).$$

Hence $d(\bar{x},\bar{y}) \leq d(\bar{x},\bar{z}) + d(\bar{z},\bar{y}) + \bar{x},\bar{y},\bar{z} \in \mathbb{R}^2$