

Adding Types and Theory Kinds to Drasil

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- ➊ Background: Drasil
- ➋ 4 Research Areas:
 - ➊ Structuring theories
 - ➋ Restricting mathematical expression terminology to appropriate contexts
 - ➌ Well-typedness of mathematical expressions
 - ➍ An extensible database for remembering everything

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What is Drasil? How does it work?

“Generate All The Things!”



- 1 Software generation suite for “well-understood” domains
- 2 De-duplicating and capturing knowledge across software artifacts
- 3 Uses a Software Requirements Specification (SRS) template to decompose scientific problems and generate software

Example

SRS to Code

Using SRS components:

- 1 Symbols (inputs, outputs, and everything in-between)
- 2 Problem description and goals
- 3 Assumptions
- 4 Abstract theories
- 5 Concrete theories
- 6 ...

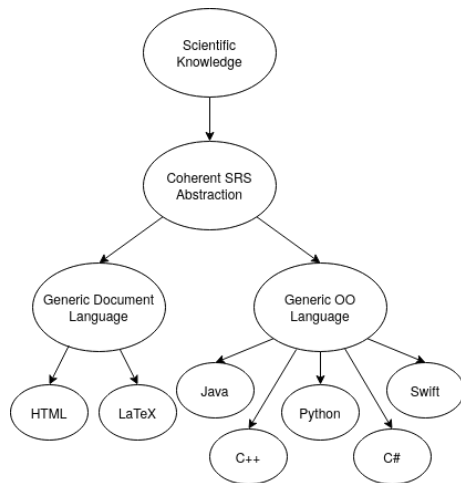


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How are theories used?

Refname	IM:calOfLandingDist
Label	Calculation of landing position
Input	$v_{\text{launch}}, \theta$
Output	p_{land}
...	...
Equation	$p_{\text{land}} = \frac{2v_{\text{launch}}^2 \sin(\theta) \cos(\theta)}{g}$
Description	p_{land} is the landing position (m) v_{launch} is the launch speed ($\frac{\text{m}}{\text{s}}$) θ is the launch angle (rad) g is the gravitational acceleration ($\frac{\text{m}}{\text{s}^2}$)

...

```
landPosExpr :: Expr
```

```
landPosExpr = sy landPos $= 2 * square (sy  
  ↳ launSpeed) * sin (sy launAngle) * cos (sy  
  ↳ launAngle) / sy gravitationalAccelConst
```

```
landPosRC :: RelationConcept
```

```
landPosRC = makeRC "landPosRC" (nounPhraseSP  
  ↳ "calculation of landing position")  
  ↳ landPosConsNote landPosExpr
```

...

How are theories used?

```
relToQD :: ExprRelat c => ChunkDB -> c -> QDefinition
relToQD sm r = convertRel sm (r ^. relat)

convertRel :: ChunkDB -> Expr -> QDefinition
convertRel d (BinaryOp Eq (C x) r) = ec (symbResolve d x) r
convertRel _ _ = error "Conversion failed"
```

```
public static double func_p_land(double v_launch, double theta, double g_vect)
↪ {
    return 2 * Math.pow(v_launch, 2) * Math.sin(theta) * Math.cos(theta) /
    ↪ g_vect;
}
```

Decompose, classify, and encode

data ModelKinds e **where**

```
NewDEModel      :: DifferentialModel -> ModelKinds e
DEModel          :: RelationConcept   -> ModelKinds e
EquationalConstraints :: ConstraintSet e -> ModelKinds e
EquationalModel   :: QDefinition e     -> ModelKinds e
EquationalRealm    :: MultiDefn e      -> ModelKinds e
OthModel          :: RelationConcept   -> ModelKinds e
```

- EquationalModel: $x := f(x, y, z, \dots)$
- EquationalConstraints: $a \wedge b \wedge c \wedge \dots$
- EquationalRealm: $x := f(x, y, z, \dots) \vee x := g(x, y, z, \dots) \vee \dots$
- DEModel & NewDEModel: $dy = f(x, y, \dots)$
- OthModel: ?

Bigger picture

- Categorization through types/constructors.
- Structured creation, interaction, and analysis.
- More opportunity for (domain-specific) interpretation.
 - Code generation!

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What are they used for?

In encoding...

Code (00)

```
def theta(...):  
    return math.asin(d * g  
    ↪ / (v ** 2)) / 2
```

Concrete theories

Refname	IM:calOfLandingDist
Label	Calculation of landing position
Input	v_{launch}, θ
Output	p_{land}
...	...
Equation	$p_{land} = \frac{2v_{launch}^2 \sin(\theta) \cos(\theta)}{g}$
Description	p_{land} is the landing position (m) v_{launch} is the launch speed ($\frac{m}{s}$) θ is the launch angle (rad) g is the gravitational acceleration ($\frac{m}{s^2}$)

Abstract theories

Refname	TM:acceleration
Label	Acceleration
Equation	$a = \frac{dv}{dt}$
Description	a is the acceleration ($\frac{m}{s^2}$) t is the time (s) v is the velocity ($\frac{m}{s}$)
Source	accelerationWiki
RefBy	GD:rectVel

Restricting terms by context

- 1 Split up the expression language by context.
- 2 “Typed-tagless” encoding to make usage seamless and interoperable.

$$\text{Expr} \Rightarrow \text{Expr} \cup \text{ModelExpr} \cup \text{CodeExpr}$$

$$\text{ModelExpr} \supseteq \text{Expr} \subseteq \text{CodeExpr}$$

Bigger picture

- 1 Restricting terms by context.
- 2 Stop users from entering in unexpected expressions.
- 3 Know when “Equational Models” are usable for (OO) code generation.

Validity of Expressions

```
data Expr where
  Lit      :: Literal -> Expr
  AssocA   :: AssocArithOper -> [Expr] -> Expr
  AssocB   :: AssocBoolOper -> [Expr] -> Expr
  C        :: UID -> Expr
  ...
```

```
illTyped :: Expr
illTyped = int 1 $+ str "Drasil"
```

```
public static double func_ex() {
    return 1 + "Drasil";
}
```

```
error: incompatible
↳ types: String
↳ cannot be
↳ converted to
↳ double
  return 1 +
    ↳ "Drasil";
      ^
```

1 Adding *bidirectional* type-checking, reporting en masse.

$$\frac{v : s \in \Gamma}{\Gamma \vdash v \Rightarrow s} \text{ SYMBOLS}$$

$$\frac{l \text{ is a literal of type } s}{\Gamma \vdash l \Rightarrow s} \text{ LITERALS}$$

$$\frac{\begin{array}{c} \oplus \in \{+, \cdot\} \quad \text{isNum}(s) \\ \Gamma \vdash e_1 \Rightarrow s \quad \Gamma \vdash e_2 \Rightarrow s \quad \dots \quad \Gamma \vdash e_n \Rightarrow s \end{array}}{\Gamma \vdash (e_1 \oplus e_2 \oplus \dots \oplus e_n) \Rightarrow s} \text{ ASSOC. ARITH. OPS}$$

$$\frac{\begin{array}{c} \oplus \in \{\wedge, \vee\} \\ \Gamma \vdash e_1 \Rightarrow \mathbb{B} \quad \Gamma \vdash e_2 \Rightarrow \mathbb{B} \quad \dots \quad \Gamma \vdash e_n \Rightarrow \mathbb{B} \end{array}}{\Gamma \vdash (e_1 \oplus e_2 \oplus \dots \oplus e_n) \Rightarrow \mathbb{B}} \text{ ASSOC. BOOL. OPS}$$

$$\frac{\begin{array}{c} f : (s_1 \times s_2 \times \dots \times s_n) \rightarrow s \in \Gamma \\ \Gamma \vdash e_1 \Rightarrow s_1 \quad \Gamma \vdash e_2 \Rightarrow s_2 \quad \dots \quad \Gamma \vdash e_n \Rightarrow s_n \end{array}}{\Gamma \vdash f(e_1, e_2, \dots, e_n) \Rightarrow s} \text{ FUN. APP.}$$

$$\frac{\Gamma \vdash e \Rightarrow s}{\Gamma \vdash e \Leftarrow s} \text{ CHECKED BY INFERENCE}$$

$$\frac{\begin{array}{c} \Gamma \vdash e_1 \Rightarrow s \quad \Gamma \vdash c_1 \Rightarrow \mathbb{B} \\ \Gamma \vdash e_2 \Rightarrow s \quad \Gamma \vdash c_2 \Rightarrow \mathbb{B} \\ \vdots \\ \Gamma \vdash e_n \Rightarrow s \quad \Gamma \vdash c_n \Rightarrow \mathbb{B} \end{array}}{\Gamma \vdash \text{Cases}(e_1, \dots, e_n, c_1, \dots, c_n) \Rightarrow s} \text{ CASES}$$

$$\frac{\begin{array}{c} \Gamma \vdash e_{11} \Rightarrow s \quad \Gamma \vdash e_{12} \Rightarrow s \quad \dots \quad \Gamma \vdash e_{1n} \Rightarrow s \\ \Gamma \vdash e_{21} \Rightarrow s \quad \Gamma \vdash e_{22} \Rightarrow s \quad \dots \quad \Gamma \vdash e_{2n} \Rightarrow s \\ \vdots \end{array}}{\Gamma \vdash e_{m1} \Rightarrow s \quad \Gamma \vdash e_{m2} \Rightarrow s \quad \dots \quad \Gamma \vdash e_{mn} \Rightarrow s} \text{ MATRIX}$$

$$\frac{\text{Matrix}(e_{11}, \dots, e_{mn}) \Rightarrow \text{Matrix}(m, n, s)}{\Gamma \vdash e_{m1} \Rightarrow s \quad \Gamma \vdash e_{m2} \Rightarrow s \quad \dots \quad \Gamma \vdash e_{mn} \Rightarrow s} \text{ MATRIX}$$

$$\frac{\text{isNum}(s) \quad s \neq \mathbb{N} \quad \Gamma \vdash e \Rightarrow s}{\Gamma \vdash |e| \Rightarrow s} \text{ ABS.}$$

$$\frac{\text{isNum}(s) \quad s \neq \mathbb{N} \quad \Gamma \vdash e \Rightarrow s}{\Gamma \vdash -e \Rightarrow s} \text{ NEG.}$$

$$\frac{s \in \{\mathbb{R}, \mathbb{Z}\} \quad \Gamma \vdash p \Rightarrow s}{\Gamma \vdash e^p \Rightarrow \mathbb{R}} \text{ EXP.}$$

Note: not all type rules shown here.

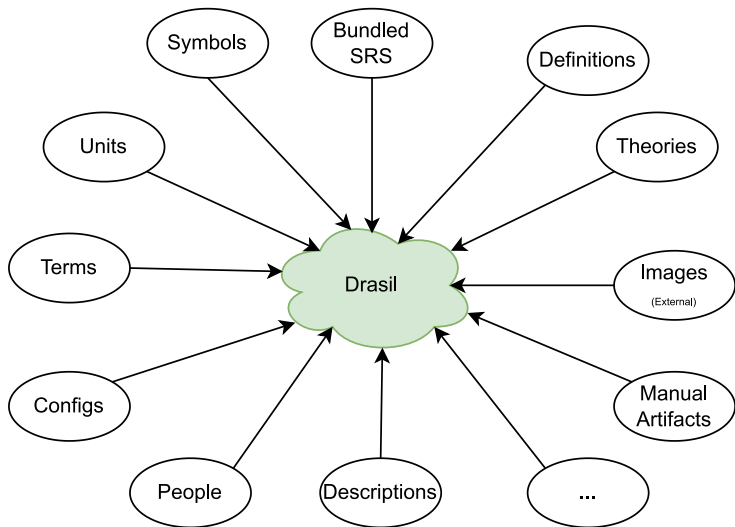
Bigger picture

- ① Found many typing issues!
- ② Realized we needed more **Expr** terms.

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How is data stored in Drasil?



How is data stored in Drasil?

```
data ChunkDB = CDB
{ symbolTable :: SymbolMap
, termTable  :: TermMap
, defTable   :: ConceptMap
, _unitTable :: UnitMap
, _traceTable :: TraceMap
, _refbyTable :: RefbyMap
, _dataDefnTable  :: DatadefnMap
, _insmodelTable   :: InsModelMap
, _gendefTable     :: GendefMap
, _theoryModelTable :: TheoryModelMap
, _conceptinsTable :: ConceptInstanceMap
, _sectionTable    :: SectionMap
, _labelledcontentTable :: LabelledContentMap
} --TODO: Expand and add more databases
```

Scaling against new *kinds* of data

Mask the type information!

```
{-# LANGUAGE ExistentialQuantification, ConstraintKinds #-}
```

```
type IsChunk a = (HasUID a, HasChunkRefs a, Typeable a)
```

```
data Chunk = forall a. IsChunk a => Chunk a
```

```
type ChunkDB = Map UID Chunk
```

```
unChunk :: Typeable a => Chunk -> Maybe a
```

```
unChunk (Chunk c) = cast c
```

Scaling against new *kinds* of data

Extra machinery

```
type ReferredBy = [UID]
```

```
type ChunkByUID = M.Map UID (Chunk, ReferredBy)
```

```
type ChunksByTypeRep = M.Map TypeRep [Chunk]
```

```
newtype ChunkDB = ChunkDB (ChunkByUID, ChunksByTypeRep)
```


Bigger picture

- ① One place!
- ② Simpler chunk analysis:
 - ① type usage analytics
 - ② build chunk dependency tree
 - ③ find cyclic knowledge
- ③ ChunkDB manipulation
- ④ Usable “base” across Drasil-like projects

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Regarding...

① Theories:

- ① Explore alternative **ModelKinds** design.
- ② Explore remaining theories (e.g., structure **OthModels**).

② Expressions:

- ① Add typing to **ModelExpr**, **CodeExpr**, and GOOL.
- ② For vectors and matrices in **Expr**, add length information, where applicable, to type-checker.

③ **ChunkDB**:

- ① Adjust existing chunk schema to merge in new **ChunkDB** implementation.
- ② Add analysis capabilities.

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Concluding Remarks & Takeaways

To sum up, we...

- ① structured theories,
- ② restricted expressions by context,
- ③ added type-checking to expressions,
- ④ and prototyped an extensible chunk database structure.