Software Requirements Specification for Glass-BR

Nikitha Krishnan and Spencer Smith

June 18, 2018

Contents

1	Ref	erence Material	2
	1.1	Table of Units	2
	1.2	Table of Symbols	
	1.3	Abbreviations and Acronyms	
2	Intr	roduction	5
	2.1	Purpose of Document	5
	2.2	Scope of Requirements	
	2.3	Characteristics of Intended Reader	
	2.4	Organization of Document	
3	Stal	keholders	6
	3.1	The Client	7
	3.2	The Customer	
4	Ger	neral System Description	7
	4.1	System Context	7
		User Characteristics	
	4.3	System Constraints	
5	Sco	pe of the Project	8
		Product Use Case Table	8
		Individual Product Use Cases	

\mathbf{Spe}	cific S	ystem Description	9
6.1	Proble	em Description	9
	6.1.1	Terminology and Definitions	9
	6.1.2	Physical System Description	11
	6.1.3	Goal Statements	11
6.2	Soluti	on Characteristics Specification	11
	6.2.1	Assumptions	12
	6.2.2	Theoretical Models	
	6.2.3		
	6.2.4	Instance Models	
	6.2.5	Data Constraints	20
Rec	nnirem	ents	21
	-		
7.2			
Like	ely Ch	anges	24
Tra	ceabili	ty Matrices and Graphs	24
Val	ues of	Auxiliary Constants	29
Ref	erence	S	30
Apı	oendix		31
	6.1 6.2 Rec 7.1 7.2 Like Tra Val Ref	6.1 Proble 6.1.1 6.1.2 6.1.3 6.2 Solution 6.2.1 6.2.2 6.2.3 6.2.4 6.2.5 Requirem 7.1 Functi 7.2 Nonfu Likely Ch Traceabili Values of	6.1.1 Terminology and Definitions 6.1.2 Physical System Description 6.1.3 Goal Statements 6.2 Solution Characteristics Specification 6.2.1 Assumptions 6.2.2 Theoretical Models 6.2.3 Data Definitions 6.2.4 Instance Models 6.2.5 Data Constraints Requirements 7.1 Functional Requirements 7.2 Nonfunctional Requirements Traceability Matrices and Graphs Values of Auxiliary Constants References

1 Reference Material

This section records information for easy reference.

1.1 Table of Units

Throughout this document SI (Système International d'Unités) is employed as the unit system. In addition to the basic units, several derived units are used as described below. For each unit, the symbol is given followed by a description of the unit and its name.

symbol	unit	SI
Pa	pressure	Pascal
N	force	Newton

1.2 Table of Symbols

The table that follows summarizes the symbols used in this document along with their units. The symbols are listed in alphabetical order.

Symbol	Unit	Description
\overline{a}	mm	Plate length (long dimension)
B	unitless	Risk function
b	mm	Plate width (short dimension)
d_{\max}	mm	Maximum value for one of the dimensions of the glass plate
d_{\min}	mm	Minimum value for one of the dimensions of the glass plate
E	kPa	Modulus of elasticity of glass
g	unitless	Glass type, $g \in \{AN, HS, FT\}$
h	mm	Actual thickness
is_safe1	unitless	True when calculated probability is less than tolerable probability
is_safe2	unitless	True when load resistance (capacity) is greater than load (demand)
J	unitless	Stress distribution factor (Function)
$J_{ m tol}$	unitless	Stress distribution factor (Function) based on $P_{b_{\text{tol}}}$
k	${ m N}^{-7}{ m m}^{12}$	Surface flaw parameter
m	${ m N}^{-7}{ m m}^{12}$	Surface flaw parameter
P_b	unitless	Probability of breakage
$P_{b_{ m tol}}$	unitless	Tolerable probability of breakage
q	kPa	Applied load (demand)
\hat{q}	unitless	Dimensionless load
$\hat{q}_{ ext{tol}}$	unitless	Tolerable load
SD	m	Stand off distance which is represented in coordinates (SD_x, SD_y, SD_z)
$\mathrm{SD}_{\mathrm{max}}$	m	Maximum stand off distance permissible for input
SD_{\min}	m	Minimum stand off distance permissible for input
t	mm	Nominal thickness $t \in \{2.5, 2.7, 3.0, 4.0, 5.0, 6.0, 8.0, 10.0, 12.0, 16.0, 19.0, 22.0\}$
t_d	second	Duration of load
w	kg	Charge weight
$w_{\rm max}$	kg	Maximum permissible input charge weight
w_{min}	kg	Minimum permissible input charge weight
w_{TNT}	kg	Explosive Mass in equivalent weight of TNT

1.3 Abbreviations and Acronyms

Abbreviation	Full Form
AN	Annealed Glass
AR	Aspect Ratio
AR_{max}	Maximum Aspect Ratio
FT	Fully Tempered Glass
GTF	Glass Type Factor
HS	Heat Strengthened
IG	Insulating Glass
LDF	Load Distribution Factor
LG	Laminated Glass
LR	Load Resistance
LSF	Load Share Factor
N/A	Not Applicable
NFL	Non-Factored load
TNT	TNT (Trinitrotoluene) equivalent factor

2 Introduction

Software is helpful to efficiently and correctly predict the blast risk involved with the glass slab. The blast under consideration is any type of man-made explosion. The software, herein called Glass-BR aims to predict the blast risk involved with the glass slab using an intuitive interface. The following section provides an overview of the Software Requirements Specification (SRS) for Glass-BR. This section explains the purpose the document is designed to fulfil, the scope of the requirements and the organization of the document: what the document is based on and intended to portray.

2.1 Purpose of Document

The main purpose of this document is to predict whether a given glass slab is likely to resist a specified blast. The goals and theoretical models used in the Glass-BR code are provided, with an emphasis on explicitly identifying assumptions and unambiguous definitions. This document is intended to be used as a reference to provide all information

necessary to understand and verify the analysis. The SRS is abstract because the contents say what problem is being solved, but not how to solve it.

This document will be used as a starting point for subsequent development phases, including writing the design specification and the software verification and validation plan. The design document will show how the requirements are to be realized, including decisions on the numerical algorithms and programming environment. The verification and validation plan will show the steps that will be used to increase confidence in the software documentation and the implementation.

2.2 Scope of Requirements

The scope of the requirements includes getting all input parameters related to the glass slab and also the parameters related to blast type. Given the input, Glass-BR is intended to use the data and predict whether the glass slab is safe to use or not.

2.3 Characteristics of Intended Reader

Reviewers of this documentation should have a strong knowledge in theory behind glass breakage and blast risk. The reviewers should also have an understanding of second year calculus, structural mechanics, and computer applications in civil engineering. In addition, reviewers should be familiar with the applicable standards for constructions using glass from [4-6] in Section. The users of GlassBR can have a lower level of expertise, as explained in Section 4.2.

2.4 Organization of Document

The organization of this document follows the template for an SRS for scientific computing software proposed by [1] and [2], with some aspects taken from Volere template 16 [3]. The presentation follows the standard pattern of presenting goals, theories, definitions, and assumptions. For readers who would like a more bottom up approach, they can start reading the data definitions in Section 6.2.3 and trace back to find any additional information they require.

The goal statements are refined to the theoretical models, and theoretical models to the instance models. The data definitions are used to support the definitions of the different models.

3 Stakeholders

This section describes the stakeholders: the people who have an interest in the product.

3.1 The Client

The client for Glass-BR is a company named Entuitive. It is developed by Dr. Manuel Campidelli. The client has the final say on acceptance of the product.

3.2 The Customer

The customers are the end users of Glass-BR.

4 General System Description

This section provides general information about the system including identifying the interfaces between the system and its environment (system context), describing the user characteristics and listing the system constraints.

4.1 System Context

Figure 1 shows the system context. A circle represents an external entity outside the software, the user in this case. A rectangle represents the software system itself (Glass-BR). Arrows are used to show the data flow between the system and its environment.



Figure 1: System Context

The interaction between the product and the user is through a user interface. The responsibilities of the user and the system are as follows:

- User Responsibilities:
 - Provide the input data related to the glass slab and the blast type, ensuring no errors in the data entry
 - Ensure that consistent units are used for input variables
 - Ensure required software assumptions (Section 6.2.1) are appropriate for any particular problem input to the software
- Glass-BR Responsibilities:

- Detect data type mismatch, such as a string of characters input instead of a floating point number
- Determine if the inputs satisfy the required physical and software constraints
- Predict whether the glass slab is safe to use or not.

4.2 User Characteristics

- The end user of Glass-BR is expected to have completed at least the equivalent of the second year of an undergraduate degree in civil or structural engineering.
- The end user is expected to have an understanding of theory behind glass breakage and blast risk.
- The end user is expected to have basic computer literacy to handle the software.

4.3 System Constraints

N/A

5 Scope of the Project

This section presents the scope of the project. It describes the expected use of Glass-BR as well as the inputs and outputs of each action. The use cases are input and output, which defines the action of getting the input and displaying the output.

5.1 Product Use Case Table

Actor	Input and Output
User	Characteristics of the glass slab and of the blast. Details in Section 5.2
GlassBR	Whether or not the glass slab is safe for the calculated load and supporting
	calculated values

Table 1: Use Case Table

5.2 Individual Product Use Cases

The user provides the inputs to GlassBR for use within the analysis. There are two main classes of inputs: glass geometry and blast type. The glass geometry based inputs include the glass type and dimensions of the glass plane. The blast type input includes parameters like weight of charge, TNT equivalent factor and stand off distance from the point of explosion. These parameters describe charge weight and stand off blast. Another input the user gives is the tolerable value of probability of breakage. GlassBR outputs if the glass slab will be safe by comparing whether capacity is greater than demand. Capacity is the the load resistance calculated and demand is the requirement which is the 3 second duration equivalent pressure. The second condition is to check whether the calculated probability (P_b) is less than the tolerable probability (P_{btol}) which is obtained from the user as an input. If both conditions return true then it's shown that the glass slab is safe to use, else if both return false then the glass slab is considered unsafe. All the supporting calculated values are also displayed as output.

6 Specific System Description

This section first presents the problem description, which gives a high-level view of the problem to be solved. This is followed by the solution characteristics specification, which presents the assumptions, theories and definitions.

6.1 Problem Description

A system is needed to efficiently and correctly predict the blast risk involved with the glass. Glass-BR is a computer program developed to interpret the inputs to give out the outputs which predicts whether the glass slab can withstand the blast under the given conditions.

6.1.1 Terminology and Definitions

This subsection provides a list of terms that are used in the subsequent sections and their meaning, with the purpose of reducing ambiguity and making it easier to correctly understand the requirements. All of the terms are extracted from [4].

1. Aspect ratio (AR) - The ratio of the long dimension of the glass to the short dimension of the glass. For glass supported on four sides, the aspect ratio is always equal to or greater than 1.0. For glass supported on three sides, the ratio of the length of one of the supported edges perpendicular to the free edge, to the length of the free edge, is equal to or greater than 0.5.

- 2. Glass breakage The fracture or breakage of any lite or ply in monolithic, laminated, or insulating glass.
- 3. Lite Pieces of glass that are cut, prepared, and used to create the window or door.
- 4. Glass Types:
 - (a) Annealed (AN) glass A flat, monolithic, glass lite which has uniform thickness where the residual surface stresses are almost zero, as defined in [5]
 - (b) Fully tempered (FT) glass A flat and monolithic, glass lite of uniform thickness that has been subjected to a special heat treatment process where the residual surface compression is not less than 69 MPa (10 000 psi) or the edge compression not less than 67 MPa (9700 psi) as defined in [6].
 - (c) Heat strengthened (HS) glass A flat, monolithic, glass lite of uniform thickness that has been subjected to a special heat treatment process where the residual surface compression is not less than 24 MPa (3500 psi) or greater than 52 MPa (7500 psi)as defined in [6].
- 5. Glass type factor (GTF) A multiplying factor for adjusting the LR of different glass types, that is, AN, HS, or FT in monolithic glass, LG (Laminated Glass), or IG (Insulating Glass) constructions
- 6. Lateral Perpendicular to the glass surface.
- 7. Load A uniformly distributed lateral pressure.
 - (a) Specified design load The magnitude in kPa (psf), type (for example, wind or snow) and duration of the load given by the specifying authority
 - (b) Load resistance (LR) The uniform lateral load that a glass construction can sustain based upon a given probability of breakage and load duration as defined in [4]
 - (c) Long duration load Any load lasting approximately 30 days.
 - (d) Non-factored load (NFL) Three second duration uniform load associated with a probability of breakage less than or equal to 8 lites per 1000 for monolithic AN glass
 - (e) Glass weight load The dead load component of the glass weight.
 - (f) Short duration load Any load lasting 3 s or less

- 8. Load share factor (LSF) A multiplying factor derived from the load sharing between the double glazing, of equal or different thickness's and types (including the layered behaviour of LG under long duration loads), in a sealed IG unit
- 9. Probability of breakage (P_b) The fraction of glass lites or plies that would break at the first occurrence of a specified load and duration, typically expressed in lites per 1000 [5].
- 10. Specifying authority The design professional responsible for interpreting applicable regulations of authorities having jurisdiction and considering appropriate site specific factors to determine the appropriate values used to calculate the specified design load, and furnishing other information required to perform this practice.
- 11. Blast resistant glazing Glazing that provides protection against air blast pressure generated by explosions.
- 12. Equivalent TNT charge mass Mass of TNT placed on the ground in a hemisphere that represents the design explosive threat.
- 13. Stand off distance (SD) The distance from the glazing surface to the centroid of a hemispherical high explosive charge.

6.1.2 Physical System Description

The physical system of Glass-BR, as shown in Figure 2 includes the following elements:

- PS1: Glass slab
- PS2: The point of explosion. Where the bomb, or any man made explosive, is located. The stand off distance is the distance between the point of explosion and the glass.

6.1.3 Goal Statements

GS1: Analyze and predict whether the glass slab under consideration will be able to withstand the explosion of a certain degree which is calculated based on user input.

6.2 Solution Characteristics Specification

This section explains all the assumptions considered and the theoretical models which are supported by the data definitions.

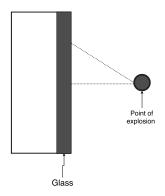


Figure 2: The physical system

6.2.1 Assumptions

This section simplifies the original problem and helps in developing the theoretical model by filling in the missing information for the physical system. The numbers given in the square brackets refer to the data definition, or the instance model, in which the respective assumption is used.

- A1: The standard E1300-09a for calculation applies only to monolithic, laminated, or insulating glass constructions of rectangular shape with continuous lateral support along one, two, three, or four edges. This practice assumes that (1) the supported glass edges for two, three, and four-sided support conditions are simply supported and free to slip in plane; (2) glass supported on two sides acts as a simply supported beam and (3) glass supported on one side acts as a cantilever.
- A2: This practice does not apply to any form of wired, patterned, etched, sandblasted, drilled, notched, or grooved glass with surface and edge treatments that alter the glass strength.
- A3: This system only considers the external explosion scenario for its calculations.
- A4: Standard values used for calculation in Glass-BR are:

(a)
$$m = 7$$

- (b) $k = 2.86 \times 10^{-53} \text{ N}^{-7} \text{m}^{12}$
- (c) $E = 7.17 \times 10^7 \text{ kPa}$
- (d) $t_d = 3 \text{ s}$

[IM1, DD3, DD5, DD7, DD9]

- A5: Glass under consideration is assumed to be a single lite. Hence the value of LSF is equal to 1 for all calculations in Glass-BR. [IM2, DD7]
- A6: Boundary conditions for the glass slab is assumed to be 4-sided support for all calculations. [IM1]
- A7: The response type considered in Glass-BR is flexural. [IM1]
- A8: With reference to A4 the value of load distribution factor (LDF) is a constant in Glass-BR. It is calculated by the equation: LDF = $(\frac{t_d}{60})^{\frac{m}{16}}$. Using this, LDF = 0.27. [DD3]

6.2.2 Theoretical Models

Number	T1
Label	Safety Requirement-1
Equation	is_safe1 = $P_b < P_{b_{\text{tol}}}$
Description	If is_safe1 = True, the glass is considered safe. is_safe1 and is_safe2 (from T2) are either both True or both False.
	P_b is the probability of breakage, as calculated in IM1
	$P_{b_{\mathrm{tol}}}$ is the tolerable probability entered by the user
Source	[4]
Ref. By	T2

Number	T2
Label	Safety Requirement-2
Equation	$is_safe2 = LR > q$
Description	If is_safe2 = True, the glass is considered to be safe. is_safe1 (from T1) and is_safe2 are either both True or both False.
	LR is the Load Resistance (also called capacity), as defined in IM2
	q (also refereed as the demand) is the 3 second equivalent pressure, as defined in IM_3
Source	[4]
Ref. By	T1

6.2.3 Data Definitions

This section collects and defines all the data needed to build the instance models.

Number	DD1
Label	Risk of Failure (B)
Equation	$B = \frac{k}{(\frac{a}{1000} \times \frac{b}{1000})^{m-1}} ((E \times 1000)(\frac{h}{1000})^2)^m \times LDF \times e^J$
Description	B is the risk of failure
	m, k are the surface flaw parameters
	a, b are dimensions of the plate, where $(a > b)$
	E is the modulus of elasticity
	h is the true thickness, which is based on the nominal thickness as shown in $\mathrm{DD2}$
	LDF is the Load Duration Factor, as defined in DD3
	J is the stress distribution factor, as defined in DD4
Source	[4]
Ref. By	IM <mark>1</mark>

Number	DD2
Label	Minimum Thickness (h) from Nominal Thickness (t)
Equation	h = h(t)
Description	h is a function that maps from the nominal thickness (t) to the minimum thickness, as follows:
	$h(t) \equiv (t = 2.5 \Rightarrow 2.16 \mid t = 2.7 \Rightarrow 2.59 \mid$
	$t = 3.0 \Rightarrow 2.92 \mid t = 4.0 \Rightarrow 3.78 \mid$
	$t = 5.0 \Rightarrow 4.57 \mid t = 6.0 \Rightarrow 5.56 \mid$
	$t = 8.0 \Rightarrow 7.42 \mid t = 10.0 \Rightarrow 9.02 \mid$
	$t = 12.0 \Rightarrow 11.91 \mid t = 16.0 \Rightarrow 15.09 \mid$
	$t = 19.0 \Rightarrow 18.26 \mid t = 22.0 \Rightarrow 21.44$)
Source	[4]
Ref. By	IM1, DD9, DD7, DD5

Number	DD3
Label Load Duration Factor (LDF)	
Equation	$LDF = \left(\frac{t_d}{60}\right)^{m/16}$
Description	t_d is the duration of the load
	m is a surface flaw parameter
Source	[4]
Ref. By	IM1, DD9

Number	DD4
Label	Stress Distribution Factor (J)
Symbols	$J = J(\hat{q}, a/b)$
Description	J is the stress distribution factor, which is obtained by interpolating from the data shown in Figure 8
	\hat{q} is the dimensionless load defined in DD7
	a, b are dimensions of the plate, where $(a > b)$
Source	[4]
Ref. By	IM <mark>1</mark>

Number	DD5	
Label	Non-Factored Load	
Equations	$NFL = rac{\hat{q}_{ m tol}Eh^4}{(ab)^2}$	
Description	E is the modulus of elasticity	
	a, b are the dimensions of the plate where $(a > b)$	
	h is the true thickness, which is based on the nominal thickness as sho in $\mathrm{DD2}$	
	\hat{q}_{tol} is the tolerable pressure defined in DD8	
Source	[4]	
Ref. By	IM2	

Number	DD6	
Label	Glass Type Factor (GTF)	
Equation	GTF = GTF(g)	
Description	GTF is a function that maps from the glass type (g) to a real number, as follows:	
	$GTF(g) \equiv (g = AN \Rightarrow 1.0 g = FT \Rightarrow 4.0 g = HS \Rightarrow 2.0)$	
	AN is annealed glass	
	FT is fully tempered glass	
	HS is heat strengthened glass	
Source		
Ref. By	DD7, IM2	

Number	DD7		
Label	Dimensionless Load (\hat{q})		
Equation	$\hat{q} = \frac{q(ab)^2}{Eh^4GTF}$		
Description	q is the 3 second equivalent pressure, as given in IM3		
	a, b are dimensions of the plate, where $(a > b)$		
	E is the modulus of elasticity		
	h is the true thickness, which is based on the nominal thickness as show in $\mathrm{DD2}$		
	GTF is the Glass Type Factor, as given by DD6		
Source	[4]		
Ref. By	DD4		

Number	DD8	
Label	Tolerable Pressure (\hat{q}_{tol})	
Equations	$\hat{q}_{\text{tol}} = \hat{q}_{\text{tol}}(J_{\text{tol}}, (a/b))$	
Description	\hat{q}_{tol} is the tolerable pressure which is obtained from Figure 8 using J_{tol} and aspect ratio (a/b) as parameters using interpolation. Calculation of J_{tol} is defined in DD9.	
Source	[4]	
Ref. By	DD5	

Number	DD9			
Label	Tolerable Stress Distribution Factor (J_{tol})			
Symbols	$J_{\text{tol}} = \ln\left[\ln\left(\frac{1}{1 - P_{b_{\text{tol}}}}\right) \frac{\left(\frac{a}{1000} \times \frac{b}{1000}\right)^{m-1}}{k((E \times 1000)\left(\frac{h}{1000})^2\right)^m \text{LDF}}\right]$			
Description	$J_{\rm tol}$ is the stress distribution factor calculated with reference to $P_{b_{ m tol}}$			
	a, b are dimensions of the plate where $(a > b)$			
	h is the true thickness, which is based on the nominal thickness as showin $\mathrm{DD2}$			
	m, k are the surface flaw parameters			
	LDF is the Load Duration Factor, as defined by DD3			
	E is the modulus of elasticity			
	$P_{b_{\text{tol}}}$ is the tolerable probability entered by the user			
Source	[4]			
Ref. By	DD8			

6.2.4 Instance Models

Number	IM1	
Label	Probability of Glass Breakage	
Equation	$P_b = 1 - e^{-B}$	
Description	P_b is the calculated probability of breakage	
	B is the risk of failure, as defined in DD1	
Source	[4]	
Ref. By	T1	

Number	IM2	
Label	Calculation of Capacity (LR)	
Equation	$LR = NFL \times GTF \times LSF$	
Description	LR is the Load Resistance, which is also called capacity	
	NFL is the Non-Factored Load, as defined in DD5	
	GTF is the Glass Type Factor, as given by DD6	
	LSF is the Load Share Factor	
Source	[4]	
Ref. By	T2	

Number	IM3	
Label	Calculation of Demand (q)	
Equation	$q = q(w_{\text{TNT}}, \text{SD})$	
Description	q , or demand, is the 3 second equivalent pressure obtained from the Figure 7 by interpolation using stand off distance (SD) and $w_{\rm TNT}$ as parameters	
	$w_{\rm TNT}$ is defined as $w_{\rm TNT} = w \times {\rm TNT}$	
	w is the charge weight	
	TNT is the TNT equivalent factor	
	SD is the stand off distance where SD = $\sqrt{\text{SD}_x^2 + \text{SD}_y^2 + \text{SD}_z^2}$	
	where (SD_x, SD_y, SD_z) are coordinates.	
Source	[4]	
Ref. By	T2, DD7	

6.2.5 Data Constraints

Table 2 shows the data constraints on the input variables. The column of physical constraints gives the physical limitations on the range of values that can be taken by the variable. The constraints are conservative, to give the user of the model the flexibility to experiment with unusual situations. The column of typical values is intended to provide a feel for a common scenario. The uncertainty column provides an estimate of the confidence with which the physical quantities can be measured. This information would be part of the input if one were performing an uncertainty quantification exercise. Table 3 gives the values of the specification parameters used in Table 2. AR_{max} refers to the maximum aspect ratio for the plate of glass.

Note: The values for d_{\min} and d_{\max} are obtained from Figure 3 and the GLASS_BR_0_40b.xslm which can be found in the Reference directory. The value for AR_{\max} is obtained from Figure 8 and the GLASS_BR_0_40b.xslm. The values for w_{\min} , w_{\max} , SD_{min} and SD_{max} are obtained from Figure 7 and the GLASS_BR_0_40b.xslm.

Table 4 shows the constraints that must be satisfied by the output.

Table 2: Input Variables

Var	Physical Cons	Software Constraints	Typical Value	Uncertainty
a	$a > 0 \land a/b > 1$	$d_{\min} \le a \le d_{\max} \land a/b < AR_{\max}$	1500 mm	10%
b	$b > 0 \land b < a$	$d_{\min} \le b \le d_{\max} \land a/b < AR_{\max}$	$1200~\mathrm{mm}$	10%
$P_{b_{ m tol}}$	$0 < P_{b_{\rm tol}} < 1$	_	0.008	0.1%
w	$w \ge 0$	$w_{\min} < w < w_{\max}$	42 kg	10%
TNT	TNT > 0	_	1	10%
SD	SD > 0	$\mathrm{SD}_{min} < \mathrm{SD} < \mathrm{SD}_{max}$	45 m	10%

Table 3: Specification Parameter Values

Var	Value	Var	Value
d_{\min}	$0.1 \mathrm{m}$	d_{\max}	5 m
$\mathrm{AR}_{\mathrm{max}}$	5	w_{\min}	$4.5~\mathrm{kg}$
$w_{\rm max}$	$910~\mathrm{kg}$	$\mathrm{SD}_{\mathrm{min}}$	6 m
$\mathrm{SD}_{\mathrm{max}}$	$130~\mathrm{m}$		

Table 4: Output Variables

Var	Physical Constraints
P_b	$0 < P_b < 1$

7 Requirements

7.1 Functional Requirements

The following section provides the functional requirements, the business tasks that the software is expected to complete.

R1: Input the following quantities, which define the glass dimensions, type of glass, tolerable probability of failure and the characteristics of the blast:

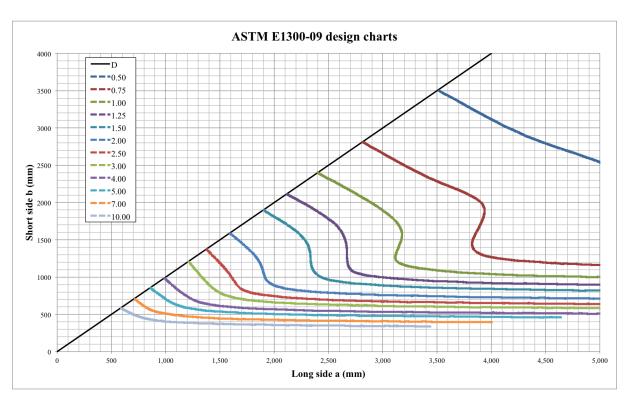


Figure 3: Long side (a) versus Short side (b)

symbol	unit	description
\overline{a}	mm	Length of the glass slab
b	mm	Breadth of the glass slab
g	unitless	Glass Type, $g \in \{AN, HS, GT\}$
$P_{b_{ m tol}}$	unitless	Tolerable probability
SD_x	m	Stand off distance $(x$ -component)
SD_y	m	Stand off distance (y-component)
SD_z	m	Stand off distance $(z$ -component)
t	mm	Nominal thickness of the glass slab, $t \in \{2.5, 2.7, 3.0, 4.0, 5.0, 6.0, 8.0, 10.0, 12.0, 16.0, 19.0, 22.0\}$
TNT	unitless	TNT equivalent factor
w	kg	Charge weight

R2: The system shall set the known values as follows:

```
-m, k, E, t_d following A4
```

- LDF following A8
- LSF following A5
- -h from DD2
- GTF from DD6
- R3: The system shall check the entered input values to ensure that they do not exceed the data constraints mentioned in 6.2.5. If any of the input parameters is out of bounds, an error message is displayed and the calculations stop.
- R4: Output the input quantities from R1 and the known quantities from R2.
- R5: If is_safe1 ∧ is_safe2 (from T1 and T2) output the message "For the given input parameters, the glass is considered safe." If the condition is false, then output the message "For the given input parameters, the glass is NOT considered safe."
- R6: Output the following quantities:
 - Probability of breakage (P_b) (IM1)
 - Load Resistance (LR) (IM2)
 - Applied load (demand) (q) (IM3)
 - Actual thickness (h) (DD2)
 - Load Duration Factor (LDF) (DD3)
 - Stress Distribution Factor (J) (DD4)
 - Non Factored Load (NFL) (DD5)
 - Glass Type Factor (GTF) (DD6)
 - Dimensionless load (\hat{q}) (DD7)
 - Tolerable load (\hat{q}_{tol}) (DD8)
 - Stress distribution factor based on P_b (J_{tol}) (DD9)
 - Aspect Ratio (AR = a/b)

7.2 Nonfunctional Requirements

Given the small size, and relative simplicity, of this problem, performance is not a priority. Any reasonable implementation will be very quick and use minimal storage. Rather than performance, the priority nonfunctional requirements are correctness, verifiability, understandability, reusability, maintainability and portability.

8 Likely Changes

- LC1: A3 The system currently only calculates for external blast risk. In the future calculations can be added for the internal blast risk.
- LC2: A4, A8 Currently the values for m, k and E are assumed to be the same for all glass. In the future these values can be changed to variable inputs.
- LC3: A5 The software may be changed to accommodate more than a single lite.
- LC4: A6 The software may be changed to accommodate more boundary conditions than 4-sided support.
- LC5: A7 The software may be changed to consider more than just flexure of the glass.

9 Traceability Matrices and Graphs

The purpose of the traceability matrices is to provide easy references on what has to be additionally modified if a certain component is changed. Every time a component is changed, the items in the column of that component that are marked with an "X" should be modified as well. Table 5 shows the dependencies of theoretical models, data definitions, and instance models with each other. Table 6 shows the dependencies of requirements on theoretical models, instance models, data definitions and data constraints. Table 7 shows the dependencies of theoretical models, data definitions, instance models, likely changes and requirements on the assumptions.

	T1	T2	IM1	IM2	IM <mark>3</mark>	DD1	DD2	DD_3	DD4	DD5	DD6	DD7	DD8	DD9
T1		X	X											
T2	X			X	X									
IM1						X	X	X	X					
IM2										X	X			
IM <mark>3</mark>														
DD1														
DD_2														
DD3														
DD4												X		
DD_5							X						X	
DD6														
DD7					X		X				X			
DD8														X
DD_9							X	X						

Table 5: Traceability Matrix Showing the Connections Between Items of Different Sections

	T1	T2	IM1	IM2	IM <mark>3</mark>	DD1	DD_2	DD_3	DD4	DD_{5}	DD_6	DD7	DD8	DD9	6.2.5	R1	R2
R1																	
R2																	
R3															X		
R4																X	X
R5	X	X															
R6			X	X	X		X	X	X	X	X	X	X	X			

 ${\it Table 6: Traceability Matrix Showing the Connections Between Requirements and Other Items.}$

	A1	A2	A3	A4	A5	A6	A7	A8
T1								
T2								
IM1				X		X	X	
IM2					X			
IM3								
DD1								
DD2								
DD3				X				X
DD4								
DD_5				X				
DD6								
DD7					X			
DD8								
DD9				X				
LC1			X					
LC2				X				X
LC3					X			
LC4						X		
LC5							X	
R1								
R2				X	X			X
R3								
R4								
R5								
R6								

Table 7: Traceability Matrix Showing the Connections Between Assumptions and Other Items

The purpose of the traceability graphs is also to provide easy references on what has to be additionally modified if a certain component is changed. The arrows in the graphs represent dependencies. The component at the tail of an arrow is depended on by the component at the head of that arrow. Therefore, if a component is changed, the components that it points to should also be changed. Figure 4 shows the dependencies of theoretical models, data definitions, instance models on each other. Figure 5 shows the dependencies of requirements on theoretical models, instance models, data definitions and data constraints. Figure 6 shows the dependencies of theoretical models, instance models, data definitions, requirements and likely changes on assumptions.

NOTE: Building a tool to automatically generate the graphical representation of the matrix by scanning the labels and reference can be future work.



Figure 4: Traceability Graph Showing the Connections Between Items of Different Sections.

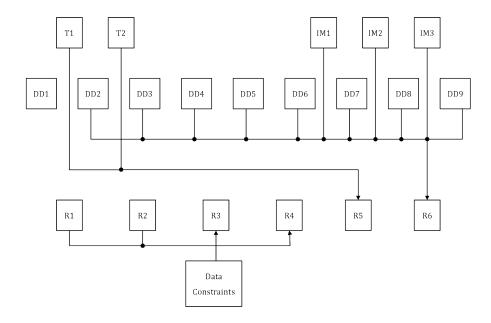


Figure 5: Traceability Graph Showing the Connections Between Requirements and Other Items.

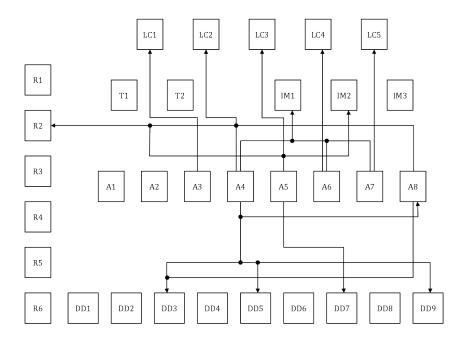


Figure 6: Traceability Graph Showing the Connections Between Assumptions and Other Items.

10 Values of Auxiliary Constants

This section contains the standard values that are used for calculations in GlassBR.

Symbol	Description	Value	Unit
\overline{m}	surface flaw parameter	7	$\frac{\frac{m^{12}}{N^7}}{\frac{m^{12}}{N^7}}$
k	surface flaw parameter	$(2.86)10^{-53}$	$\frac{\mathrm{m}^{12}}{\mathrm{N}^7}$
E	modulus of elasticity of glass	$(7.17) 10^7$	Pa
t_d	duration of load	3	S

LDF	load duration factor	$\left(\frac{t_d}{60}\right)^{\frac{m}{16}}$	Unitless
LSF	load share factor	1	Unitless
d_{max}	maximum value for one of the dimensions of the	5.0	mm
	glass plate		
d_{min}	minimum value for one of the dimensions of the	0.1	mm
	glass plate		
AR_{max}	maximum aspect ratio	5.0	Unitless
w_{max}	maximum permissible input charge weight	910.0	kg
w_{min}	minimum permissible input charge weight	4.5	kg
SD_{min}	minimum stand off distance permissible for input	6.0	m
SD_{max}	maximum stand off distance permissible for input	130.0	m

Table 8: Auxiliary Constants

11 References

- [1] N. Koothoor, "A document drive approach to certifying scientific computing software," Master's thesis, McMaster University, Hamilton, Ontario, Canada, 2013.
- [2] W. S. Smith and L. Lai, "A new requirements template for scientific computing," in Proceedings of the First International Workshop on Situational Requirements Engineering Processes Methods, Techniques and Tools to Support Situation-Specific Requirements Engineering Processes, SREP'05 (J. Ralyté, P. Agerfalk, and N. Kraiem, eds.), (Paris, France), pp. 107–121, In conjunction with 13th IEEE International Requirements Engineering Conference, 2005.
- [3] S. Robertson and J. Robertson, *Mastering the Requirements Process*, ch. Volere Requirements Specification Template, pp. 353–391. New York, NY, USA: ACM Press/Addison-Wesley Publishing Co, 1999.
- [4] ASTM Standards Committee, "Standard practice for determining load resistance of glass in buildings," Standard E1300-09a, American Society for Testing and Material (ASTM), 2009.
- [5] ASTM, developed by subcommittee C1408, Book of standards 15.02, "Standard specification for flat glass, C1036."
- [6] ASTM, developed by subcommittee C14.08, Book of standards 15.02, "Specification for heat treated flat glass-Kind HS, kind FT coated and uncoated glass, C1048."

12 Appendix

This appendix holds the graphs (Figure 7 and Figure 8) used for interpolating values needed in the models.

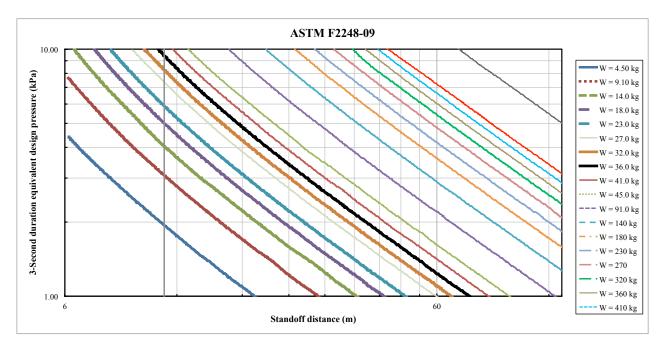


Figure 7: 3 second equivalent pressure (q) versus Stand off distance (SD) versus charge weight (w)

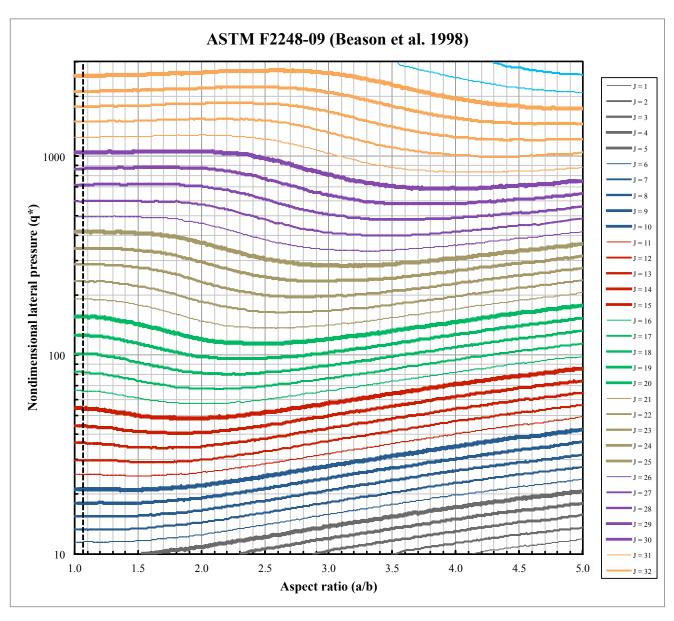


Figure 8: Non dimensional lateral load ($\hat{q})$ versus Aspect ratio versus Stress distribution factor (J)