# Sravan Balaji

Email: balajsra@umich.edu Phone: (248) 417 - 0955 LinkedIn: sravan-balaji Website: sravanbalaji.com

**EDUCATION** 

# • University of Michigan

Ann Arbor, MI

B.S.E. in Mechanical Engineering and Computer Science; GPA: 3.757

Sep. 2016 - Dec. 2020

o Autonomous Robotics Lab, Mobile Robotics, Computer Vision, Design of Digital Control Systems

# Work Experience

#### • Hughes Network Systems

San Diego, CA

Software Development Intern

May 2019 - Aug. 2019

- Created Windows GUI app in C# employing .NET framework; automated mobile terminal configuration process to reduce user involvement, prevent errors, and decrease configuration time
- Implemented location based services on terminal software written in C; leveraged MQTT-SN protocol to provide low-cost method of sending GPS data to server

• Rivian Plymouth, MI

 $Business\ Technology\ Intern$ 

May 2018 - Dec. 2018

- Introduced and designed an internal website to collect and display data from business systems utilizing Python and Django; worked with REST APIs to present reports of issues by severity
- $\circ$  Led effort to migrate IT team to a new service desk; worked with Jira Service Desk to automate triage and assignment of IT tickets; increased ticket resolution rate within SLA targets from 70% to 95%

# RESEARCH

# • Compliant Systems Design Lab

Ann Arbor, MI

Research Assistant

Jan. 2019 - Apr. 2019

- Formulated and conducted an experiment to investigate applicability of digital image correlation (DIC) for analyzing strain in fiber reinforced elastomeric enclosures (FREEs)
- Analyzed creep behavior of FREEs and generated plots with C++ program

# PROJECTS

#### • Reduce Reuse Recycle Robot

Ann Arbor, MI

EECS 467 Course Project (GitHub: EECS-467-W20-RRRobot-Project/RRRobot)

Mar. 2020 - Apr. 2020

- Simulated UR10 robot arm with ROS and Gazebo that classifies and sorts items into trash and recycling
- Employed convolutional neural network to classify images, depth camera point cloud coordinate transformations to determine grip position, and inverse kinematics to calculate joint positions

# • Autonomous Delivery of Supercritical CO<sub>2</sub>

Canton, MI

MECHENG 450 Course Project with Fusion Coolant Systems

Sep. 2019 - Dec. 2019

- Led team of 5 through entire design process for semester project: problem definition, concept generation and evaluation, final design prototyping and validation
- Performed engineering analysis, technical report writing, and CAD in SolidWorks; created engineering drawings, design review presentations, and physical prototype of final design

# SKILLS

- Programming: C++, C#, C, Python, Arduino, ROS, Java, Excel VBA, LATEX, HTML, CSS
- Computer Aided Design: SolidWorks, CATIA
- Simulation: MATLAB, Simulink
- Manufacturing: University of Michigan Wilson Center Basic I & II, Mill Training
- Languages: English (first language), French (conversational), Tamil (conversational)