



Sample JSONs ▾

- Simple
- Array
- Complex

```
27         "RShoulder"
28     ],
29     [
30         806.459,
31         559.6,
32         0.728736,
33         3,
34         "RElbow"
35     ],
36     [
37         712.354,
38         393.683,
39         0.718274,
40         4,
41         "RWrist"
42     ]
43 ]
```

Valid Json

Reformat

Minify



Clear

Generate

Json Tabular Form

⌵ Collapse All

⌵ time string	0:03:34.266667
⌵ frame number	6428
⌵ raw	{...}

⊖ angle_total number	2696.3420039853063				
⊖ keypoints Array - (25)	Index	⊖ keypoint_no	⊖ keypoint_name	⊖ delta	⊖ angle
	⊖ 0	0	Nose	825.611	-179.56060388787358
	⊖ 1	1	Neck	688.966	-179.73593664614742
	⊖ 2	2	RShoulder	536.184	-179.99514325334357
	⊖ 3	3	RElbow	246.92999999999995	-179.99373400662375
	⊖ 4	4	RWrist	308.587	179.37900228920336
	⊖ 5	5	LShoulder	844.941	-179.9979812089624
	⊖ 6	6	LElbow	708.3299999999999	-179.74116281799866
	⊖ 7	7	LWrist	737.5679999999999	-179.7556272577268
	⊖ 8	8	MidHip	162.53999999999996	-179.990385861481
	⊖ 9	9	RHip	35.70100000000002	179.96354258245879
	⊖ 10	10	RKnee	0	0
	⊖ 11	11	RAnkle	0	0
	⊖ 12	12	LHip	282.774	-178.75659264873246
	⊖ 13	13	LKnee	0	0
	⊖ 14	14	LAnkle	0	0
	⊖ 15	15	REye	799.5699999999999	-179.98869668777473
	⊖ 16	16	LEye	900.223	-179.99873171101018
	⊖ 17	17	REar	727.977	-179.4872862184939
	⊖ 18	18	LEar	942.6099999999999	-179.99757690747572
	⊖ 19	19	LBigToe	0	0
	⊖ 20	20	LSmallToe	0	0
	⊖ 21	21	LHeel	0	0
	⊖ 22	22	RBigToe	0	0

Object	number													
	⊖ wrists_angle number	-100.97304665559182												
⊖ keypoints_LWrist_nose_delta Object	⊖ keypoint_no number	7												
	⊖ keypoint_name string	LWrist												
	⊖ l_wrist_nose_delta number	384.9055386052531												
⊖ keypoints_RWrist_nose_delta Object	⊖ keypoint_no number	4												
	⊖ keypoint_name string	RWrist												
	⊖ r_wrist_nose_delta number	367.870637187857												
	⊖ r_wrist_nose_angle_degrees number	-54.35189640906004												
⊖ keypoints_direction Array - (25)	[...]													
⊖ raw_wrists_shoulders Object	⊖ raw_r_wrist Array - (5)	<table><tr><td>Index</td><td></td></tr><tr><td>⊖ 0</td><td>712.354</td></tr><tr><td>⊖ 1</td><td>393.683</td></tr><tr><td>⊖ 2</td><td>0.718274</td></tr><tr><td>⊖ 3</td><td>4</td></tr><tr><td>⊖ 4</td><td>RWrist</td></tr></table>	Index		⊖ 0	712.354	⊖ 1	393.683	⊖ 2	0.718274	⊖ 3	4	⊖ 4	RWrist
	Index													
⊖ 0	712.354													
⊖ 1	393.683													
⊖ 2	0.718274													
⊖ 3	4													
⊖ 4	RWrist													
	⊖ raw_l_wrist	<table><tr><td>Index</td><td></td></tr></table>	Index											
Index														

		<div>⊖ 4</div>	LWrist
	⊖ raw_r_shoulder Array - (5)	Index	
		⊖ 0	923.42
		⊖ 1	380.797
		⊖ 2	0.672191
		⊖ 3	2
		⊖ 4	RShoulder
	⊖ raw_l_shoulder Array - (5)	Index	
		⊖ 0	1209.39
		⊖ 1	357.983
		⊖ 2	0.740862
		⊖ 3	5
		⊖ 4	LShoulder
	⊖ delta_mavg number	8804.193800000001	