1 Introduction

This document lists the available plans for checking OpenLCB implementations.

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1. CAN Frame Level Plan

2. Message Network Plan

3. Event Transport Plan

4. Datagram Transport Plan

5. Configuration Description Information Plan

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6. Memory Configuration Protocol Plan

7. Simple Node Information Protocol Plan

8. Firmware Upgrade Plan

9. Broadcast Time Protocol Plan

10. Train Control Protocol Plan

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11. Train Search Protocol Plan

12. Function Description Information Plan