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| --- | --- |
| 1.1 | * The Jacobian, derivative of the warped point’s position with respect to the warp parameters   For pure translation:   * Looking at the values getting minimized * must be invertible |
| 1.3 | Every 100 frames: |
| 1.3  cont. | Frames 5, 25, 50, 75, and 100 |