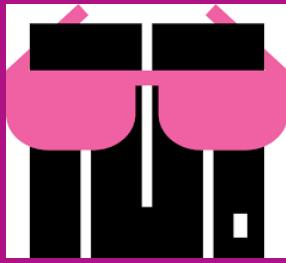
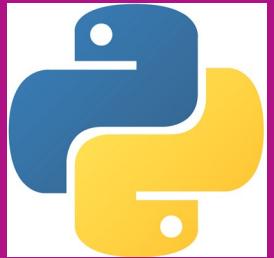
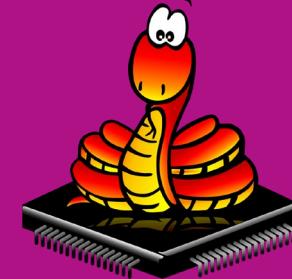


# INTERNET OF THINGS (IOT) PROJECTS USING PYTHON

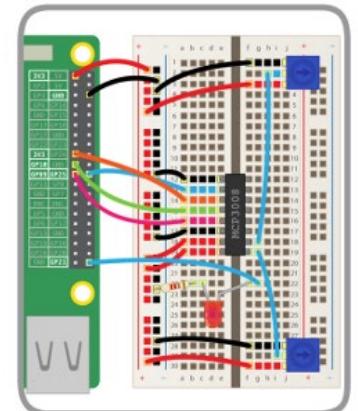
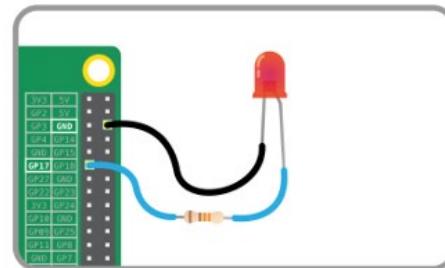
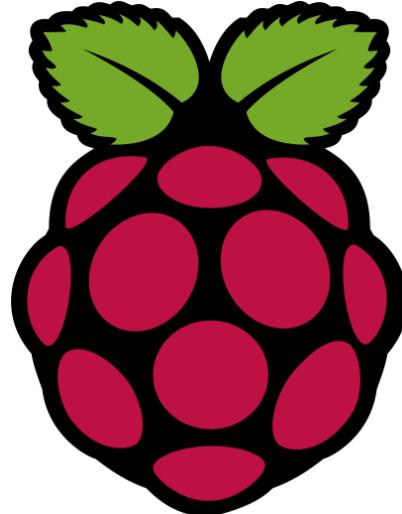


(CSE 4110)

(LECTURE – 3)

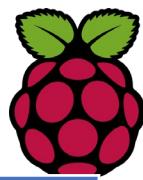


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# Course Outcomes

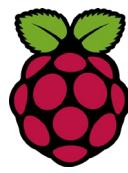


## Course Outcomes

CO1	Understand general concepts of Internet of Things (IoT), the working of Raspberry Pi and its features.
CO2	Recognize various components, sensors, actuators, devices and their applications.
CO3	Analyze various python programs to interface with sensors, actuators, LED's, cloud and camera using Raspberry pi.
CO4	Measure physical parameters using sensors.
CO5	Demonstrate the ability to transmit data wirelessly between different devices to build simple IoT systems using Raspberry Pi.
CO6	Create IoT devices and systems through a variety of interfaces, including web apps and mobile apps.



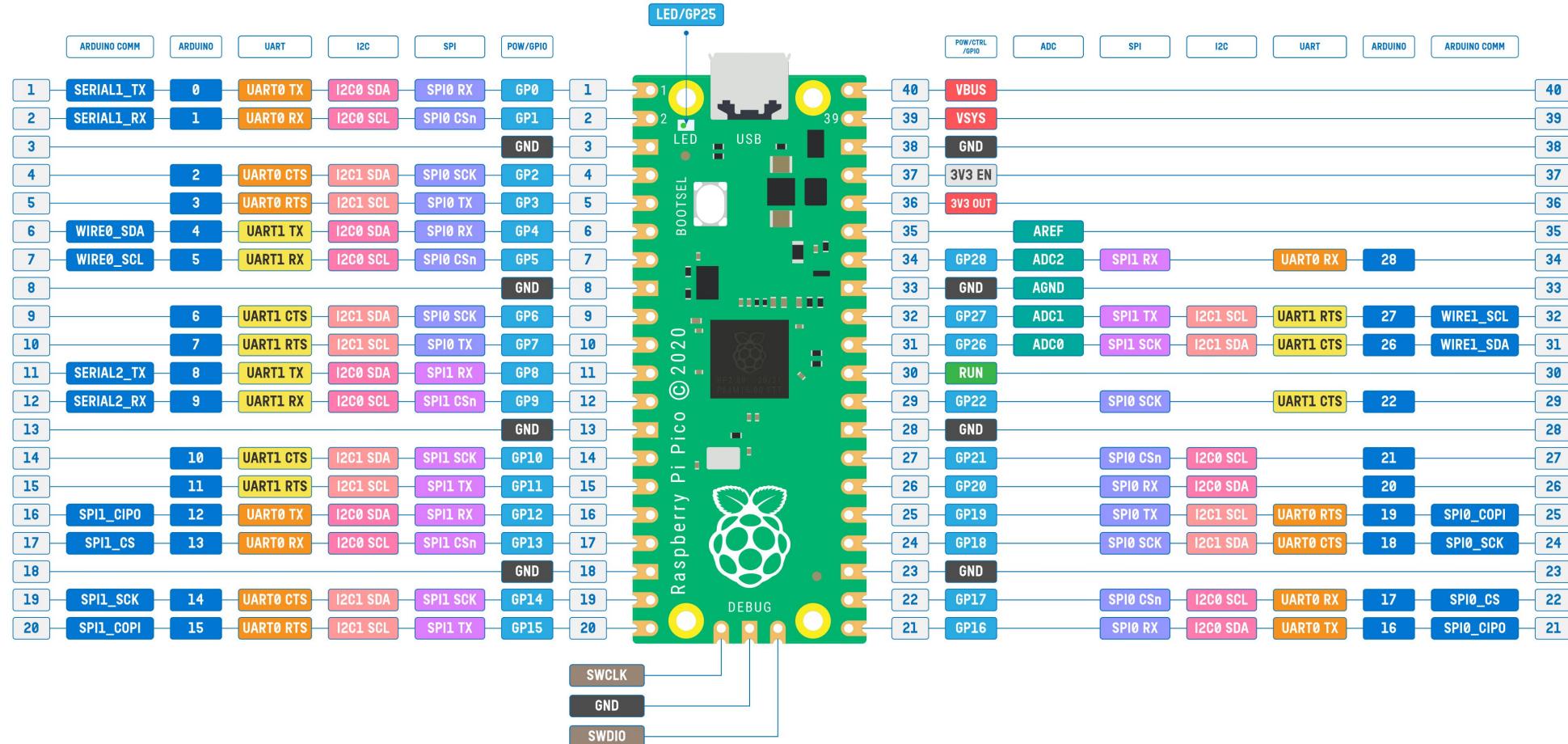
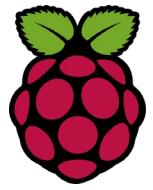
# What Students will learn?



Students will be developing simple hardware projects/experiments with the Raspberry Pi Pico, using the Thonny text editor. They also learn how a Raspberry Pi Pico can be used to control and receive input from a variety of electronic components to engage in some creative physical computing experiments/projects.

- ✓ Implementation of Flashing LED using a Timer using Raspberry Pi Pico.
- ✓ Implementation of Alternately Flashing two different colour LEDs using Raspberry Pi Pico.
- ✓ Implementation of four LEDs display a pattern of rotating left using Raspberry Pi Pico

# Raspberry Pi Pico – Full Pinout



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## ARDUINO PINS

## SWD Pins

PHYSICAL PIN	POSITIVE SUPPLY	UART1 Pins	UART0 Pins
RESET/ENABLE	GROUND SUPPLY	I2C1 Pins	I2C0 Pins
GPIO PORT/PIN	ANALOG PIN	SPI1 Pins	SPI0 Pins

- GP29/ADC3 is used to measure VSYS.
- GP25 is used for debug LED.
- GP24 is used for VBUS sense.
- GP23 is connected to SMPS Power Save pin.
- All GPIO pins support PWM. There are total 16 PWM channels.
- All GPIO pins support level and edge interrupts.
- Arduino pins are as per [Arduino-Pico core](#) by [@earlephilhower](mailto:Earle F. Philhower, III)
- Arduino's default Serial is the USB-CDC of Pico.

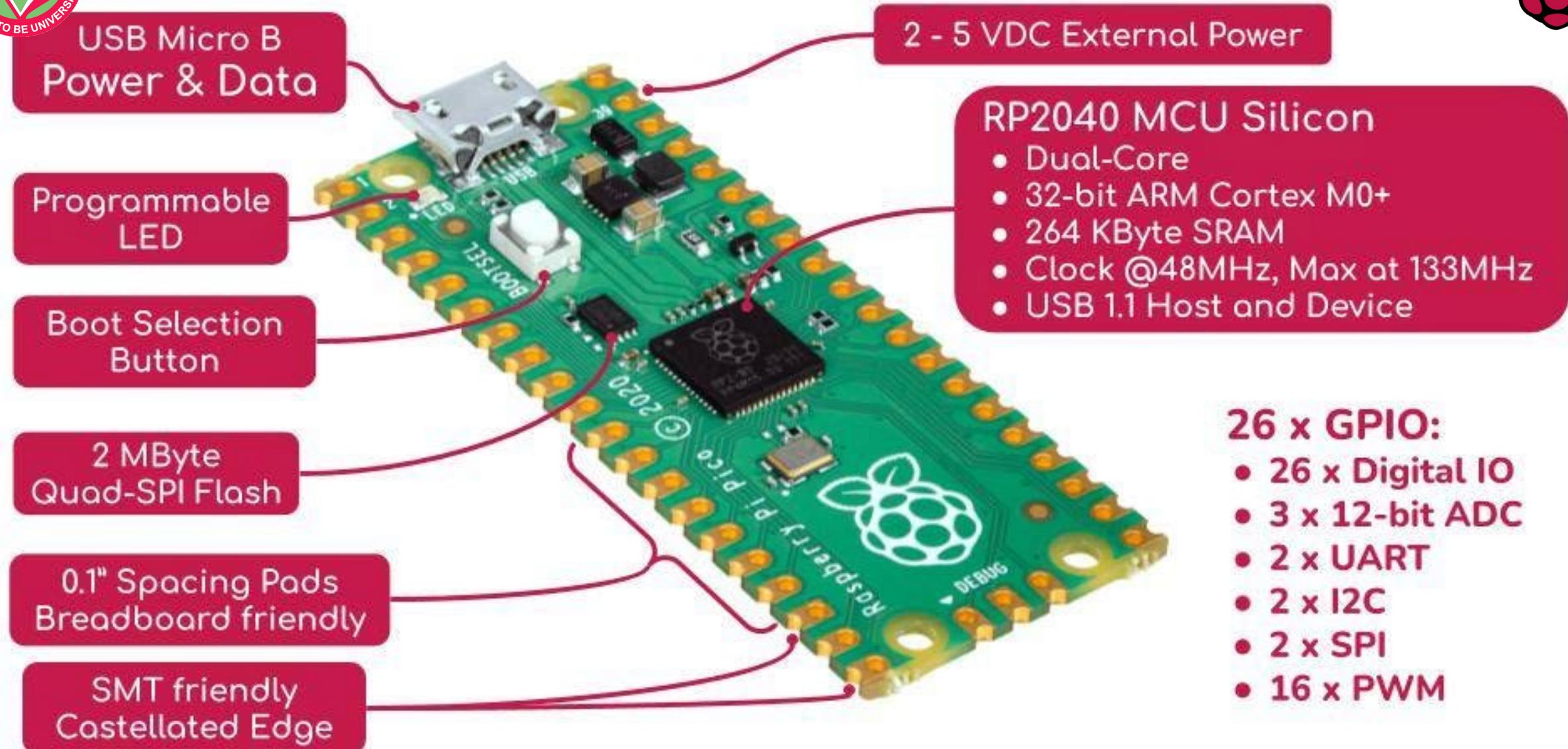
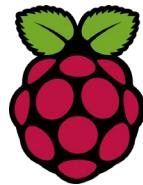


Rev. 0.2, 15-07-2022

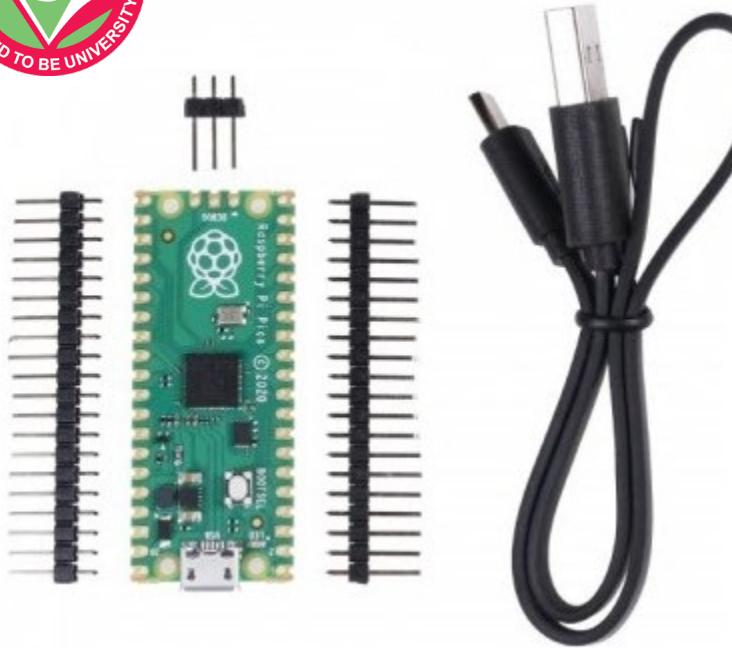
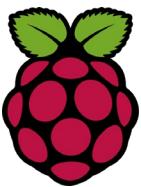
Design: Vishnu Mohanan

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# Raspberry Pi Pico – In Short

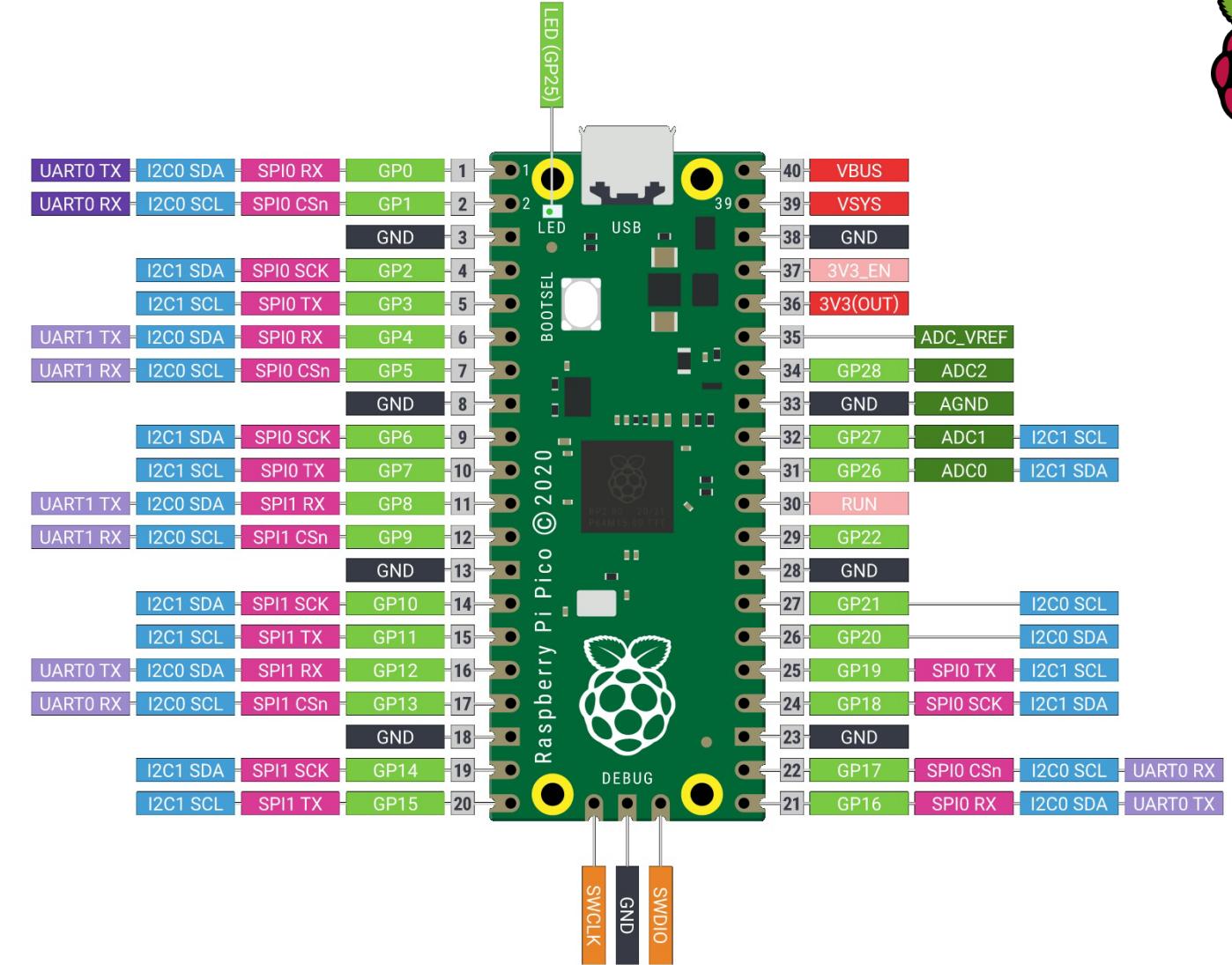


Pi Foundation has released an RP2040 Microprocessor based development board, in the same form factor as an Arduino Nano.

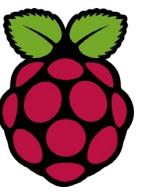


## Package Includes:

- 1 x Raspberry Pi Pico
- 1 x Micro-USB cable
- 2 x 20 Pin Header
- 1 x 3 Pin Header

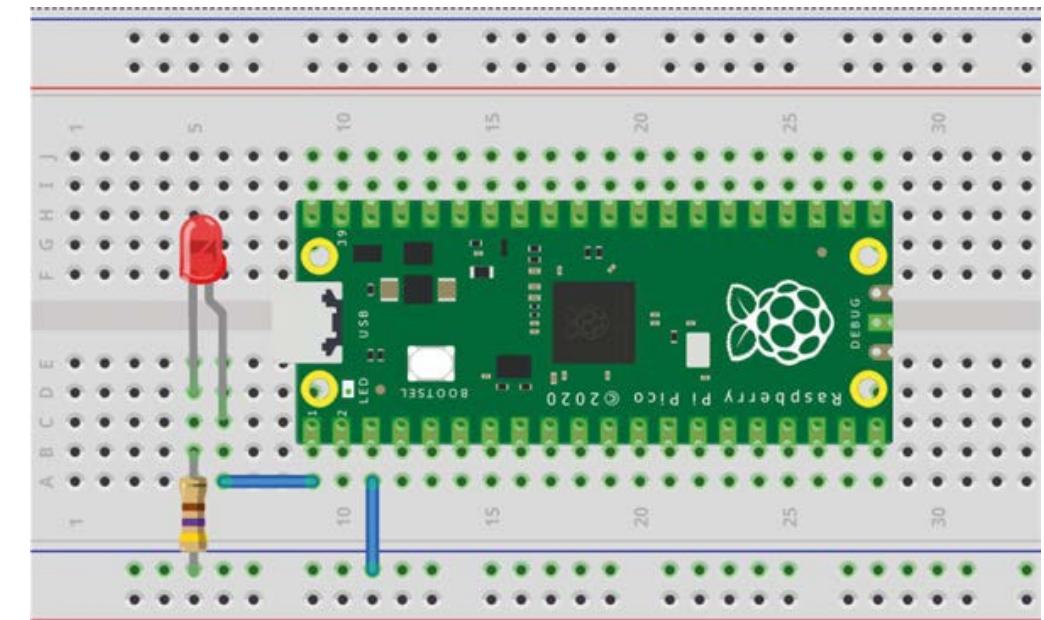
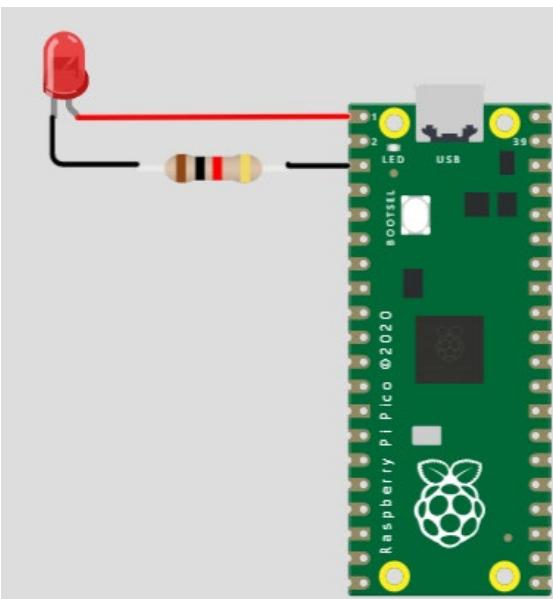


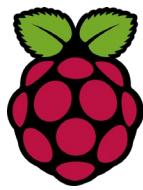
■ Power ■ Ground ■ UART / UART (default) ■ GPIO, PIO, and PWM ■ ADC ■ SPI ■ I2C ■ System Control ■ Debugging



# Flashing LED – using a timer

- ✓ An external LED is connected to port pin GP0 of the Pico. In this objective a timer is used to flash the LED every 500 ms.
- ✓ A timer is initialized which calls function **Flash\_LED** twice (**freq = 2.0**) a second in a periodic manner.
- ✓ LED is flashed using the **toggle** function.





# Flashing LED – using a timer

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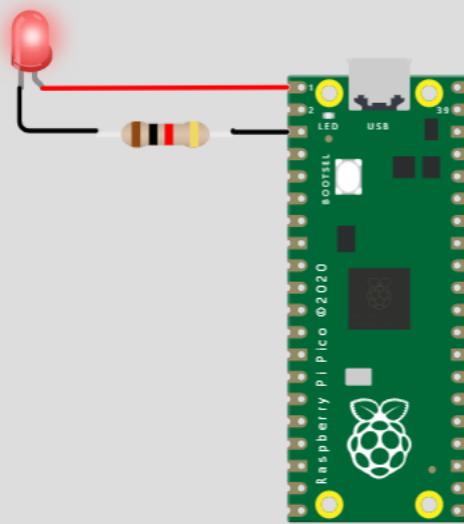
main.py • diagram.json • PIO 1

```
1 from machine import Pin, Timer
2 LED = Pin(0, Pin.OUT)
3
4 tim = Timer()
5 def Flash_LED(timer):
6     global LED
7     LED.toggle()
8 tim.init(freq = 2.0, mode = Timer.PERIODIC, callback = Flash_LED)
```

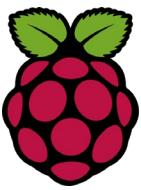
Simulation



⌚ 00:13.696 📺 90%



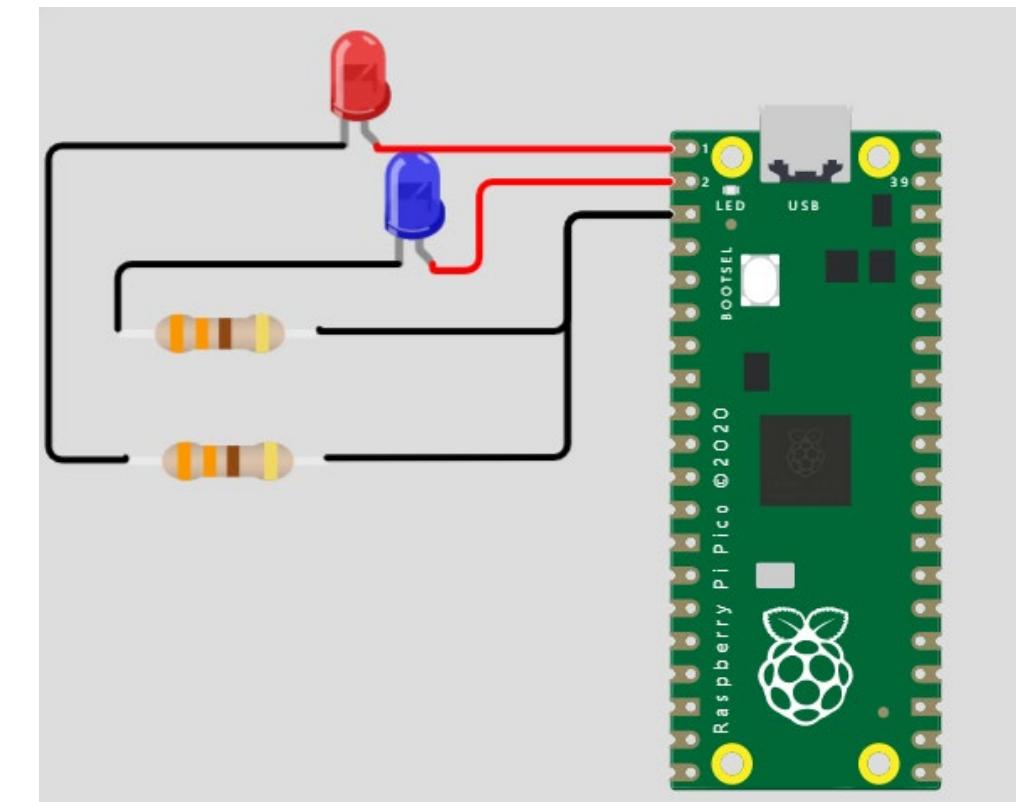
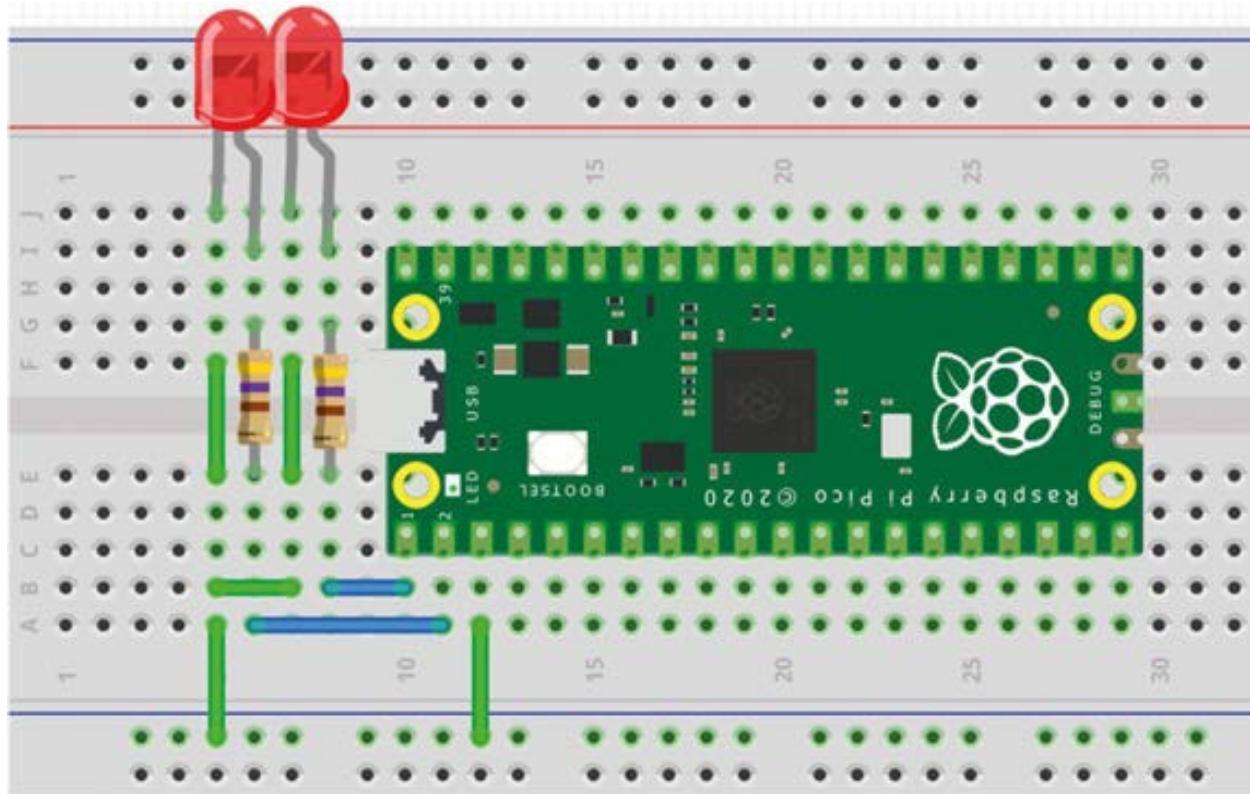
```
MPY: soft reboot
MicroPython v1.18 on 2022-01-17; Raspberry Pi Pico with RP2040
Type "help()" for more information.
>>>
```



# Alternately flashing LEDs

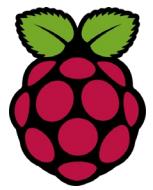
Two LEDs are connected to the Pico to pins GP0 (pin 1) and GP1 (pin 2).

The LEDs flash alternately every 500 ms.





# Alternately flashing LEDs

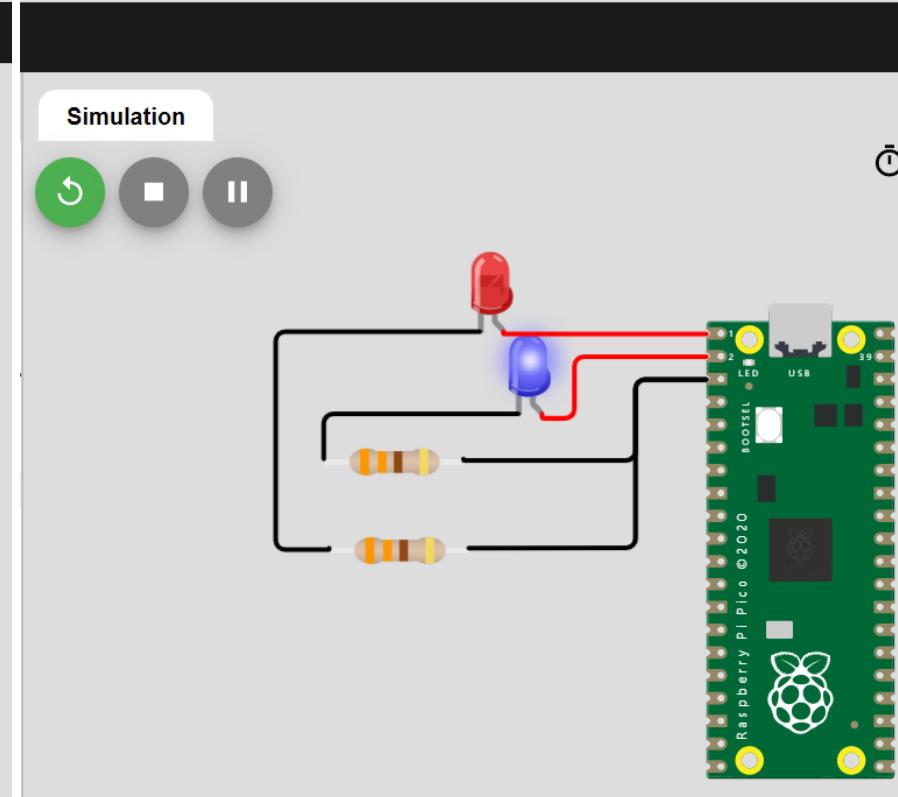
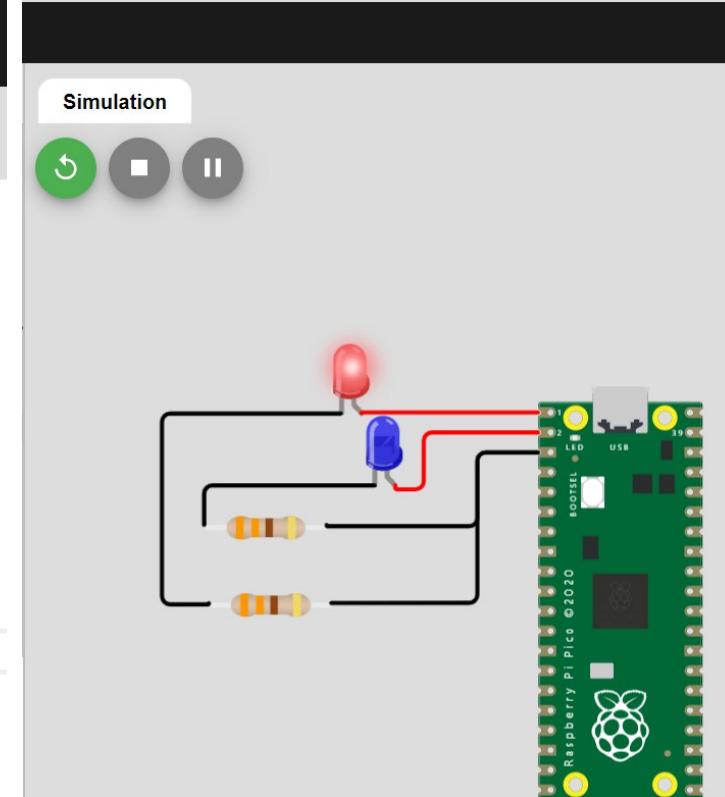


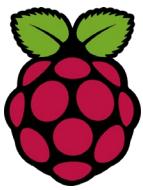
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main.py • diagram.json • PIO 🐍

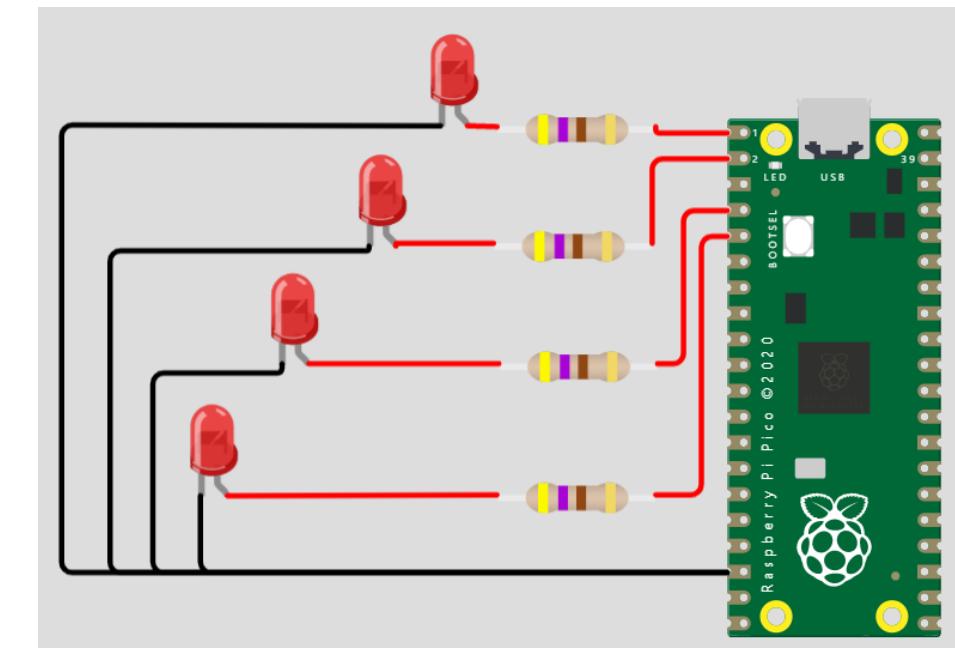
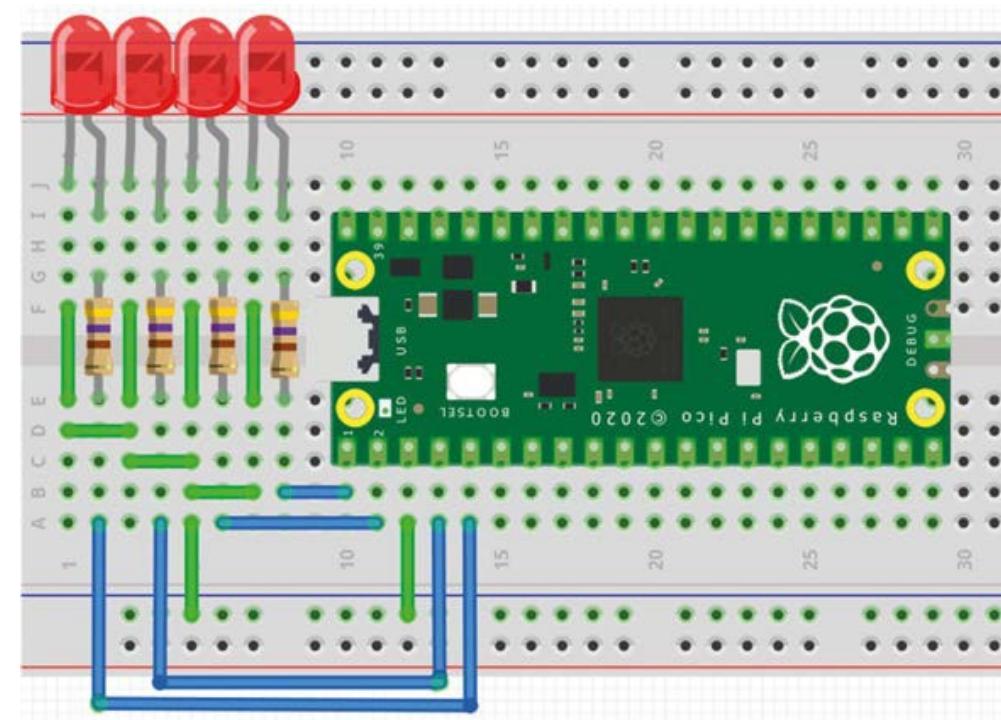
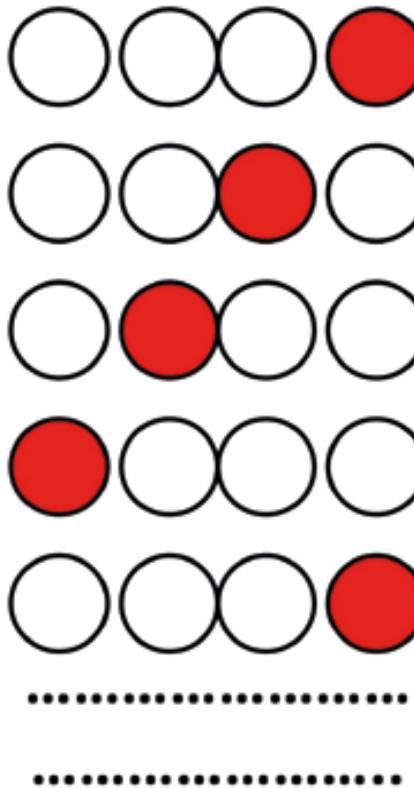
```
1 from machine import Pin
2 import utime
3 LED1 = Pin(0, Pin.OUT)
4 LED2 = Pin(1, Pin.OUT)
5 while True:
6     LED1.value(1)
7     LED2.value(0)
8     utime.sleep(0.5)
9     LED1.value(0)
10    LED2.value(1)
11    utime.sleep(0.5)
12
```

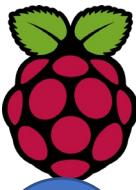




# ROTATING LEDs

4 LEDs are connected from port pin GP0 to GP3 of the Pico. The LEDs display pattern of rotating to the left





# ROTATING LEDs

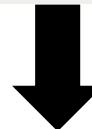
WOKwi

SAVE

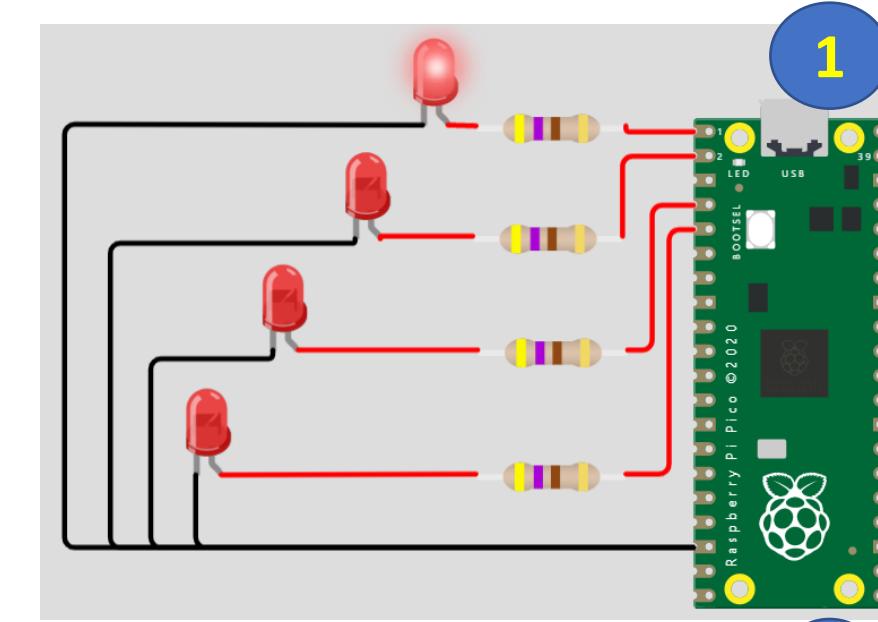
SHARE

main.py • diagram.json • PIO

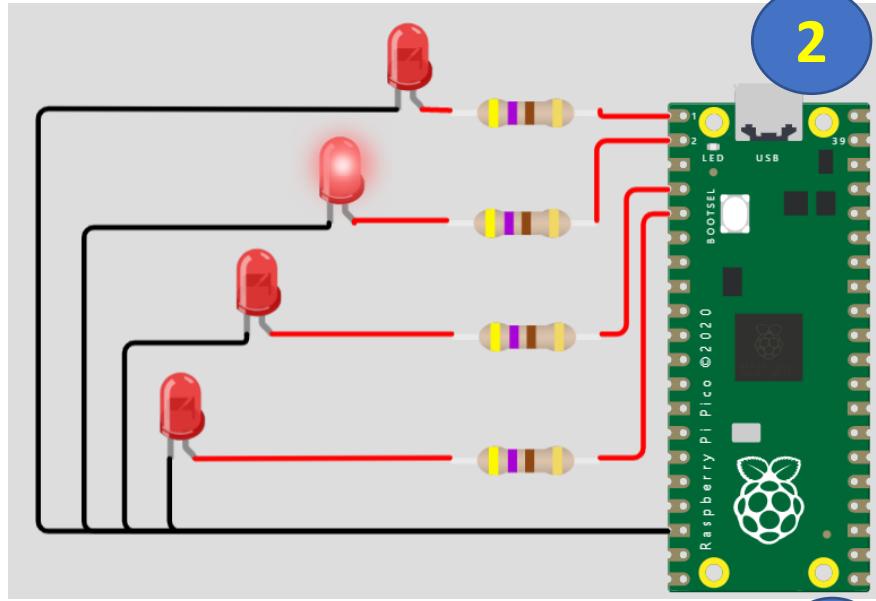
```
1  from machine import Pin
2  import utime
3  LED1 = Pin(0, Pin.OUT)
4  LED2 = Pin(1, Pin.OUT)
5  LED3 = Pin(2, Pin.OUT)
6  LED4 = Pin(3, Pin.OUT)
7
8  while True:
9      LED1.value(1)
10     utime.sleep(0.5)
11     LED1.value(0)
12     LED2.value(1)
13     utime.sleep(0.5)
14     LED2.value(0)
15     LED3.value(1)
16     utime.sleep(0.5)
17     LED3.value(0)
18     LED4.value(1)
19     utime.sleep(0.5)
20     LED4.value(0)
```



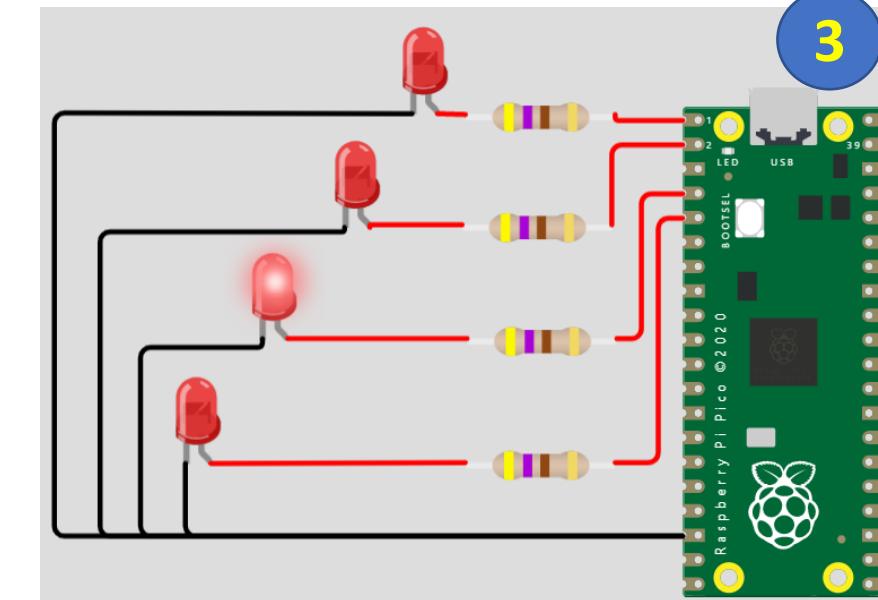
Can you write a more efficient program??



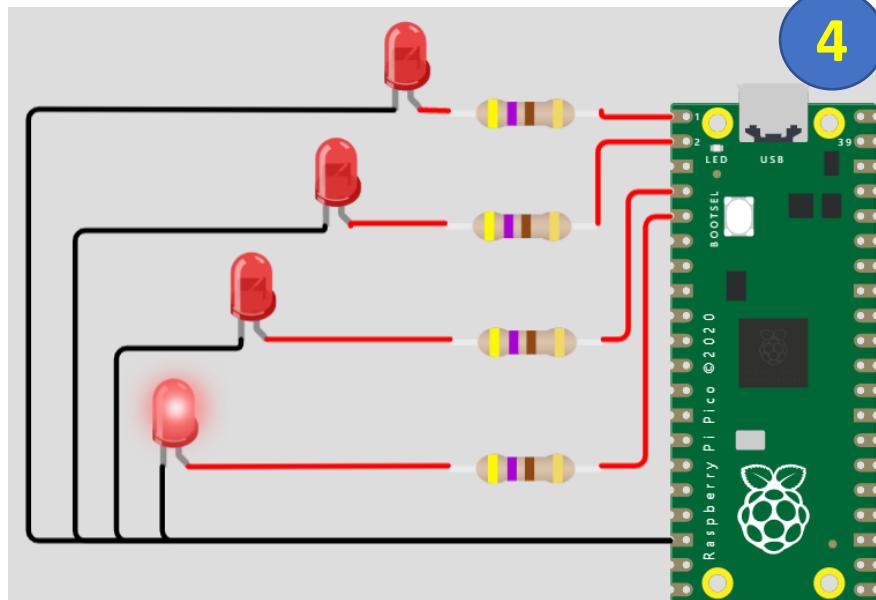
1



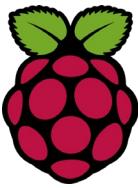
2



3



4



# EFFICIENT ROTATING LEDs

WOKWi

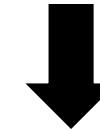
SAVE



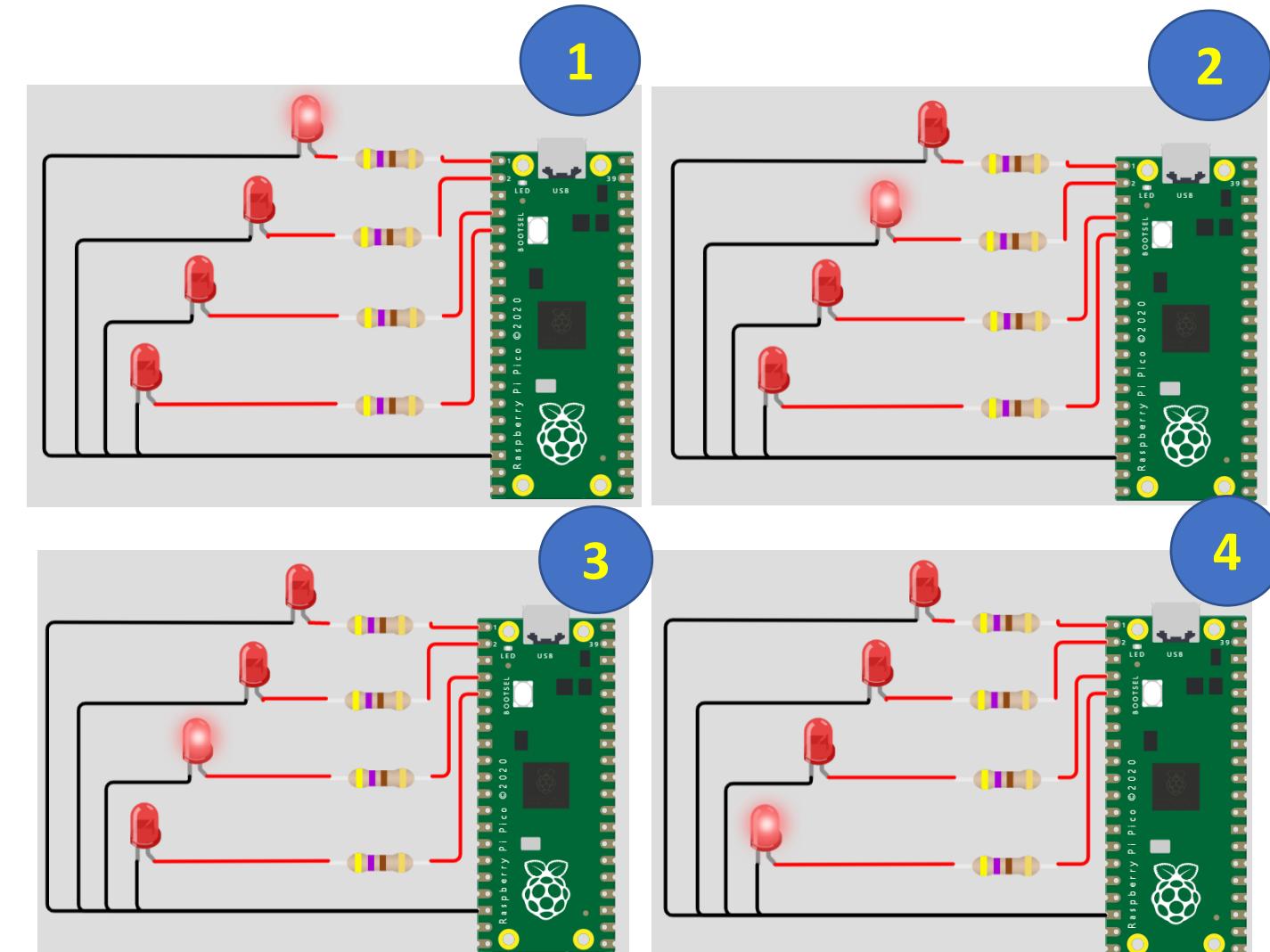
SHARE

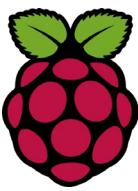
main.py • diagram.json •

```
1  from machine import Pin  
2  import utime  
3  
4  LEDS = [0, 1, 2, 3]          # LED ports  
5  L = [0, 0, 0, 0]  
6  
7  for i in range(4):           # Do for all LEDs  
8      L[i] = Pin(LEDS[i], Pin.OUT) # All are outputs  
9  
10 while True:                 # Do forever  
11     for i in range(4):         # LED ON  
12         L[i].value(1)          # Wait 0.5 second  
13         utime.sleep(0.5)        # LED OFF  
14         L[i].value(0)
```



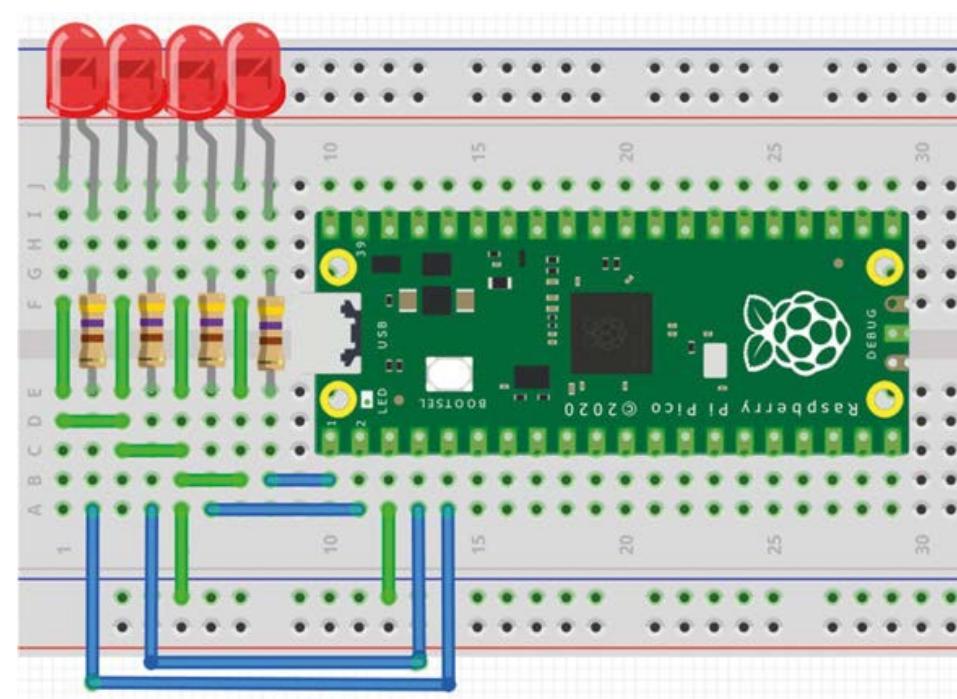
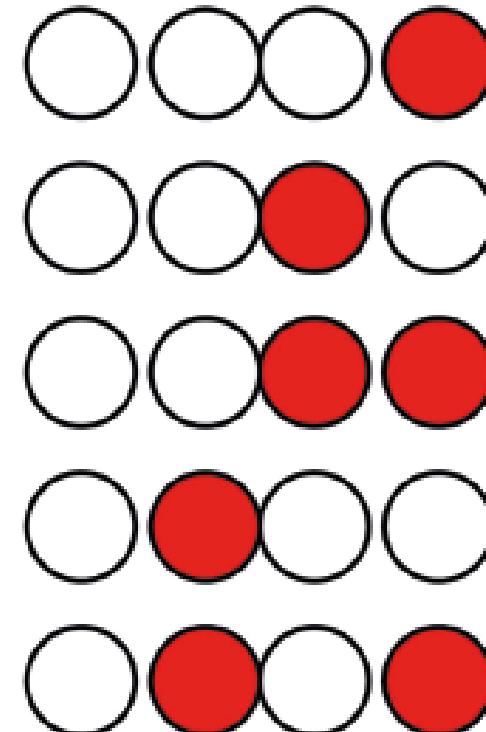
This is especially true if there are more than 4 LEDs.

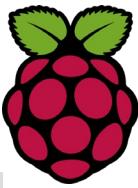




# 4-bit Binary-counting LEDs

- ✓ 4 LEDs are connected to Pico.
- ✓ The LEDs count up in binary every second from 0 to 15.



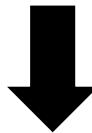


# 4-bit Binary-counting LEDs

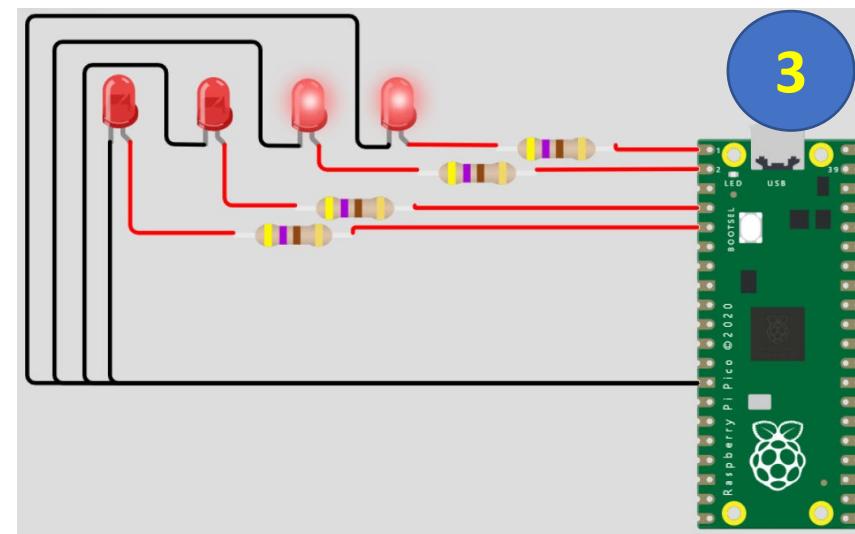
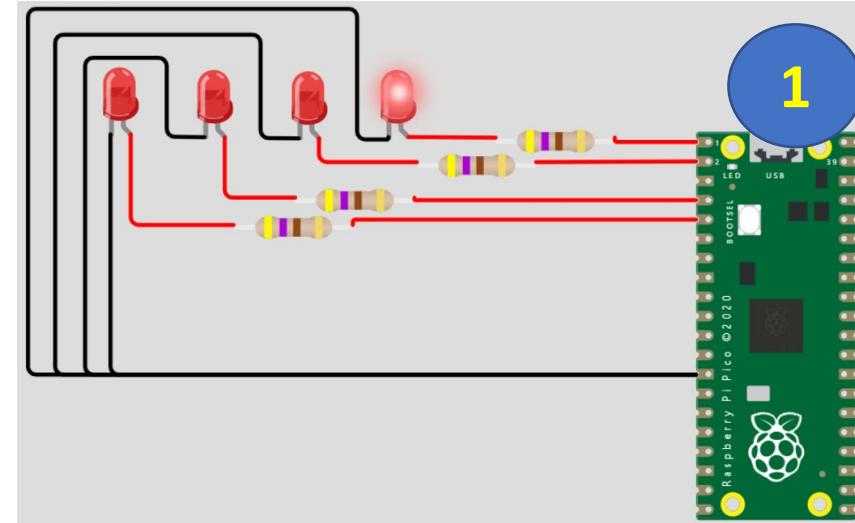
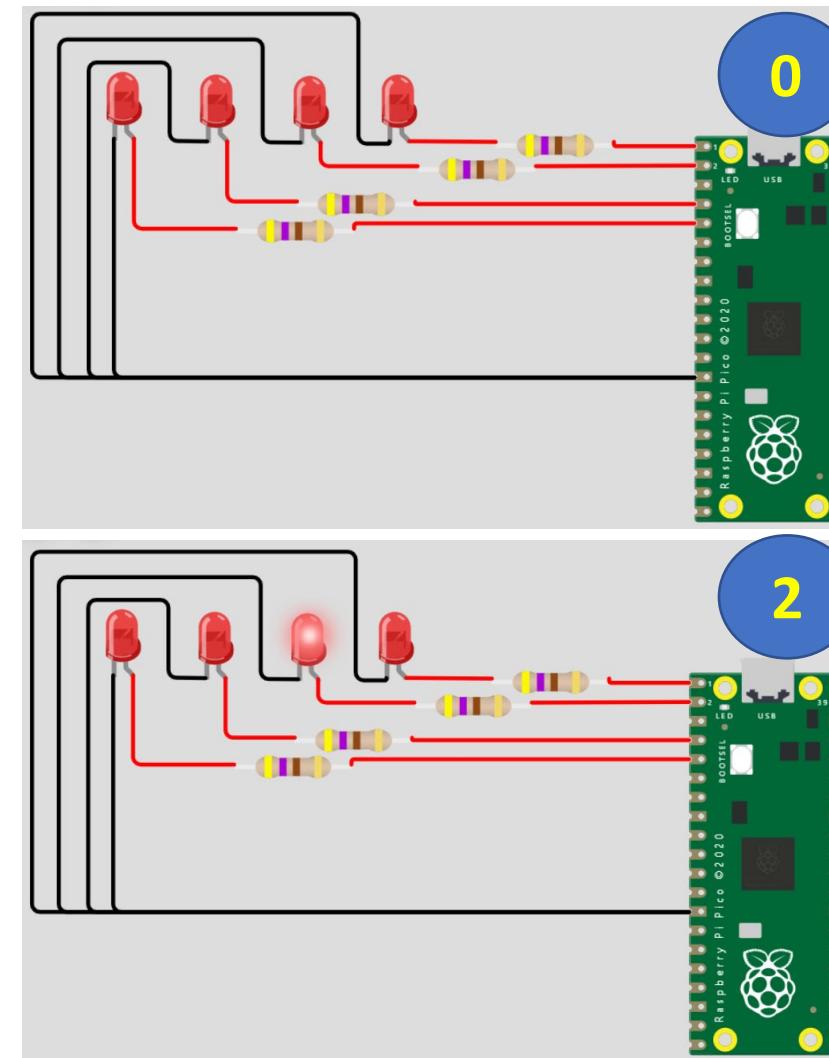
WOKWi

main.py diagram.json

```
1 from machine import Pin
2 from utime import sleep
3
4 led1 = Pin(0, Pin.OUT)
5 led2 = Pin(1, Pin.OUT)
6 led3 = Pin(2, Pin.OUT)
7 led4 = Pin(3, Pin.OUT)
8
9 while True:
10     led4.value(0)
11     led3.value(0)
12     led2.value(0)
13     led1.value(0)
14     sleep(1)
15
16     led4.value(0)
17     led3.value(0)
18     led2.value(0)
19     led1.value(1)
20     sleep(1)
21
22     led4.value(0)
23     led3.value(0)
24     led2.value(1)
25     led1.value(0)
26     sleep(1)
```



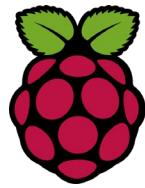
Can you write a more  
efficient program??



and so on.....



# Efficient 4-bit Binary-counting LEDs



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main.py • diagram.json

```
1 from machine import Pin
2 import utime
3
4 PORT = [3, 2, 1, 0]          # port connections
5 DIR = ["0","0","0","0"]        # port directons
6 L = [0]*4
7 #
8 # This function configures the port pins as outputs ("0") or
9 # as inputs ("I")
10 #
11 def Configure_Port():
12     for i in range(0, 4):
13         if DIR[i] == "0":
14             L[i] = Pin(PORT[i], Pin.OUT)
15         else:
16             L[i] = Pin(PORT[i], Pin.IN)
17     return
18 #
19 # This function sends 4-bit data (0 to 15) to the PORT
20 #
21 def Port_Output(x):
22     b = bin(x)                  # convert into binary
23     b = b.replace("0b", "")       # remove leading "0b"
24     diff = 4 - len(b)            # find the length
25     for i in range (0, diff):
26         b = "0" + b              # insert leading os
27
28     for i in range (0, 4):
29         if b[i] == "1":
```

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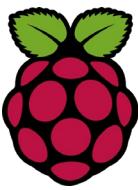
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main.py • diagram.json

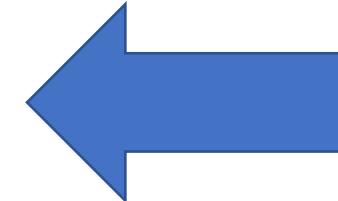
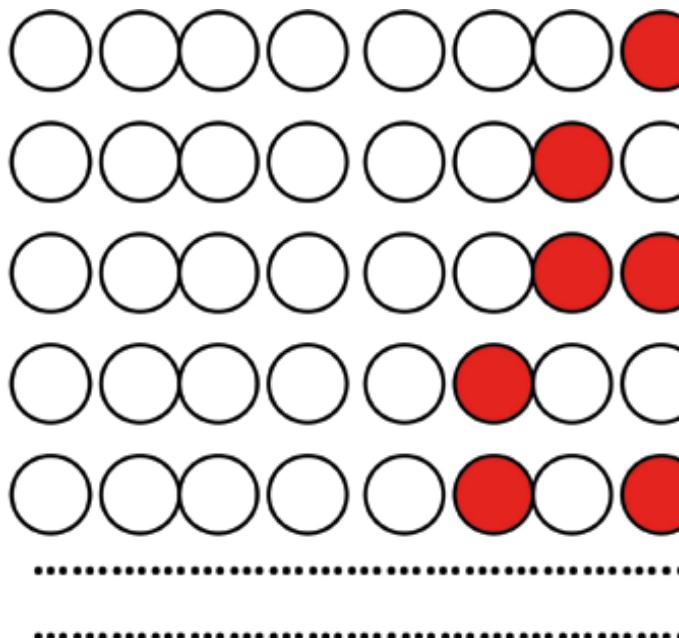
```
30     L[i].value(1)
31     else:
32         L[i].value(0)
33     return
34
35 # Configure PORT to all outputs
36 #
37 Configure_Port()
38 # Main program loop. Count up in binary every second
39 #
40 cnt = 0
41 while True:
42     Port_Output(cnt)           # send cnt to port
43     utime.sleep(1)             # wait 1 second
44     cnt = cnt + 1              # increment cnt
45     if cnt > 15:
46         cnt = 0
```

and so on.....

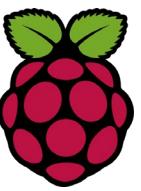


# 8-bit Binary-counting LEDs

- ✓ 8 LEDs are connected to Pico.
- ✓ The LEDs count up in binary every second from 0 to 255.



**Try to implement**



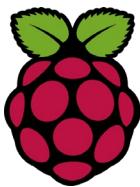
# Fancy Diwali/Christmas lights

- ✓ 8 LEDs are connected to Pico.
- ✓ The LEDs flash randomly every 250 milliseconds just like Diwali Light or fancy Christmas lights.

**Clue:**

**Generate random numbers between 1 and 255 and then shows how to use these numbers to turn the individual LEDs ON and OFF randomly.**

**Try to implement by yourself**



# Fancy Diwali/Christmas lights

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main.py • diagram.json •

```
1  from machine import Pin
2  import utime import sleep
3  import random
4
5  PORT = [7, 6, 5, 4, 3, 2, 1, 0]
6  DIR = ["0","0","0","0","0","0","0","0"]
7  L = [0]*8
8
9  def Configure_Port():
10     for i in range(0, 8):
11         if DIR[i] == "0":
12             L[i] = Pin(PORT[i], Pin.OUT)
13         else:
14             L[i] = Pin(PORT[i], Pin.IN)
15     return
16
17  def Port_Output(x):
18      b = bin(x)
19      b = b.replace("0b", "")
20      diff = 8 - len(b)
21      for i in range (0, diff):
22          b = "0" + b
23
24  for i in range (0, 8):
25      if b[i] == "1":
26          L[i].value(1)
```

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main.py • diagram.json •

```
27  else:
28      | L[i].value(0)
29  return
30
31  Configure_Port()
32
33  while True:
34      numbr = random.randint(1, 255)
35      Port_Output(numbr)
36      sleep(0.25)
```