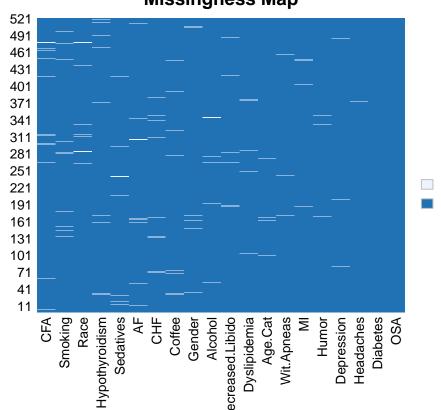
Missingness Map



Missing (1%)

Observed (99%