Missingness Map
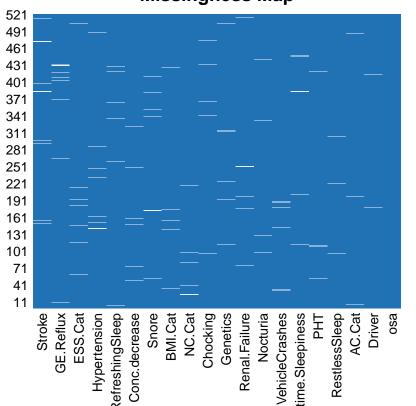
Missing (1%)
Observed (99%)