

# Astrostatistics: Tue 27 Feb 2017

<https://github.com/CambridgeAstroStat/PartIII-Astrostatistics>

- Lecture Demo Codes are online in directory lecture\_codes/
- Example Class 2: Friday, Mar 2, **2:00pm**, MR 5
- Fitting Statistical Models to Astronomical Data
  - Markov Chain Monte Carlo
  - Refs: Not much in Ivezić, Ch 5, F&B Ch 3
  - Gelman et al. Bayesian Data Analysis (Ch 11 & 12)
  - Givens & Hoeting. “Computational Statistics” (Ch 7 & 8)
  - Roberts & Casella. “Monte Carlo Statistical Methods” (theory) (Ch 6 & 7)
  - Hogg & DFM, 2017 “Data analysis recipes: Using Markov Chain Monte Carlo.”  
<https://arxiv.org/abs/1710.06068>

# Plan

- Last Time: M-H algorithm, Gibbs sampling
- Today:
  - Metropolis-within-Gibbs
  - Theoretical Justifications
- Next time? Gaussian Processes

# Remarks on Multivariate Gaussians Properties

- Last time: Conditionals and Marginals of Multivariate Gaussians
- Last time: Building Jointly Multivariate Gaussians from Conditional and Marginals
- Dimensions of Covariance Matrices

What if you can't directly sample  
the posterior:  $\theta_i \sim P(\theta | D)$ ?

$$\mathbb{E}[f(\boldsymbol{\theta}) | D] = \int f(\boldsymbol{\theta}) P(\boldsymbol{\theta} | D) d\boldsymbol{\theta} \approx \frac{1}{m} \sum_{i=1}^m f(\boldsymbol{\theta}_i)$$

- Posterior simulation - Markov Chain Monte Carlo:
- Generate a correlated sequence (chain) of random variates (Monte Carlo) that (in a long run limit) are draws from the posterior distribution. The next value in the sequence only depends on the current values (Markov).
- Many degrees of freedom for user: choose to most efficiently generate *independent* samples

## d-dim Metropolis Algorithm:

Posterior  $P(\theta | D)$ ,

Symmetric Proposal/Jump dist'n  $J(\theta^* | \theta) = J(\theta | \theta^*)$

1. Choose a random starting point  $\theta_0$
2. At step  $i = 1 \dots N$ , propose a new parameter value  $\theta^* \sim N(\theta_{i-1}, \Sigma_p)$ .  
The proposal distr'n is  $J(\theta^* | \theta_{i-1}) = N(\theta^* | \theta_{i-1}, \Sigma_p)$
3. Evaluate ratio of posteriors at proposed vs current values.  $r = P(\theta^* | \mathbf{y}) / P(\theta_{i-1} | \mathbf{y})$ .
4. Accept  $\theta^*$  with probability  $\min(r, 1)$ :  $\theta_i = \theta^*$ . If not accept, stay at same value  $\theta_i = \theta_{i-1}$  for the next step & include in chain.
5. Repeat steps 2-4 until reach some measure of convergence (G-R) and gather enough independent samples to compute your inference (reduce Monte Carlo error)

Metropolis-Hastings Algorithm:  
More General Jumping Rule:  $J(\theta^*|\theta_i)$

(Need not be symmetric -  
if symmetric you have the special case of Metropolis)

1. Choose a random starting point  $\theta_0$
2. At step  $i = 1 \dots N$ , propose a new parameter value:  $\theta^* \sim J(\theta^*|\theta_{i-1})$
3. Evaluate ratio of posteriors at proposed vs current values.  
$$r = [P(\theta^* | \mathbf{y}) / J(\theta^*|\theta_{i-1})] / [P(\theta_{i-1} | \mathbf{y}) / J(\theta_{i-1}|\theta^*)]$$
4. Accept  $\theta^*$  with probability  $\min(r, 1)$ :  $\theta_i = \theta^*$ . If not accept, stay at same value  $\theta_i = \theta_{i-1}$  & include in chain.
5. Repeat steps 2-4 until reach some measure of convergence and gather enough samples to compute your inference

# Gibbs Sampling

- Multi-dimensional sampling, when you can utilise the set of conditional posterior distributions.
- If joint posterior is  $P(\theta, \phi | \mathbf{D})$
- And you can solve for tractable conditionals:

$$P(\theta | \phi, \mathbf{D})$$

$$P(\phi | \theta, \mathbf{D})$$

- Jump along one parameter-dimension at a time

# d-dim Gibbs Sampler

$$\boldsymbol{\theta} = (\theta_1 \dots \theta_d) \quad \boldsymbol{\theta}_{-j} \equiv (\theta_1, \dots, \theta_{j-1}, \theta_{j+1} \dots \theta_d)$$

1. Choose a random starting point  $\theta_0$
2. At step  $i = 1 \dots N$ , cycle through the d-parameters:  
For each  $j = 1 \dots d$ , move  $j$ th parameter to  $\theta_j \sim P(\theta_j | \boldsymbol{\theta}_{-j}^{i-1}, \mathbf{D})$   
and always accept.

The proposal distr'n is  $J(\boldsymbol{\theta}^* | \boldsymbol{\theta}^{i-1}) = P(\theta_j | \boldsymbol{\theta}_{-j}, \mathbf{D})$

3. The Metropolis-Hastings ratio is always 1 (don't need to compute)
4. Always accept  $\theta_j^*$ .
5. Repeat steps 2-4 until reach some measure of convergence (G-R)  
and gather enough independent samples to compute your  
inference (reduce Monte Carlo error)



# Gibbs Sampling: Example

(Gelman BDA Section 11.1)

Likelihood:  $\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \sim N \left( \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right) \quad \rho \text{ known}$

Priors:  $P(\theta_1) = P(\theta_2) \propto 1$

Posterior:  $\begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \mid \mathbf{y} \sim N \left( \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$

$$P(\boldsymbol{\theta} \mid \mathbf{y}) = P(\theta_1 \mid \theta_2, \mathbf{y})P(\theta_2 \mid \mathbf{y}) = P(\theta_2 \mid \theta_1, \mathbf{y})P(\theta_1 \mid \mathbf{y})$$

Conditional Posteriors:

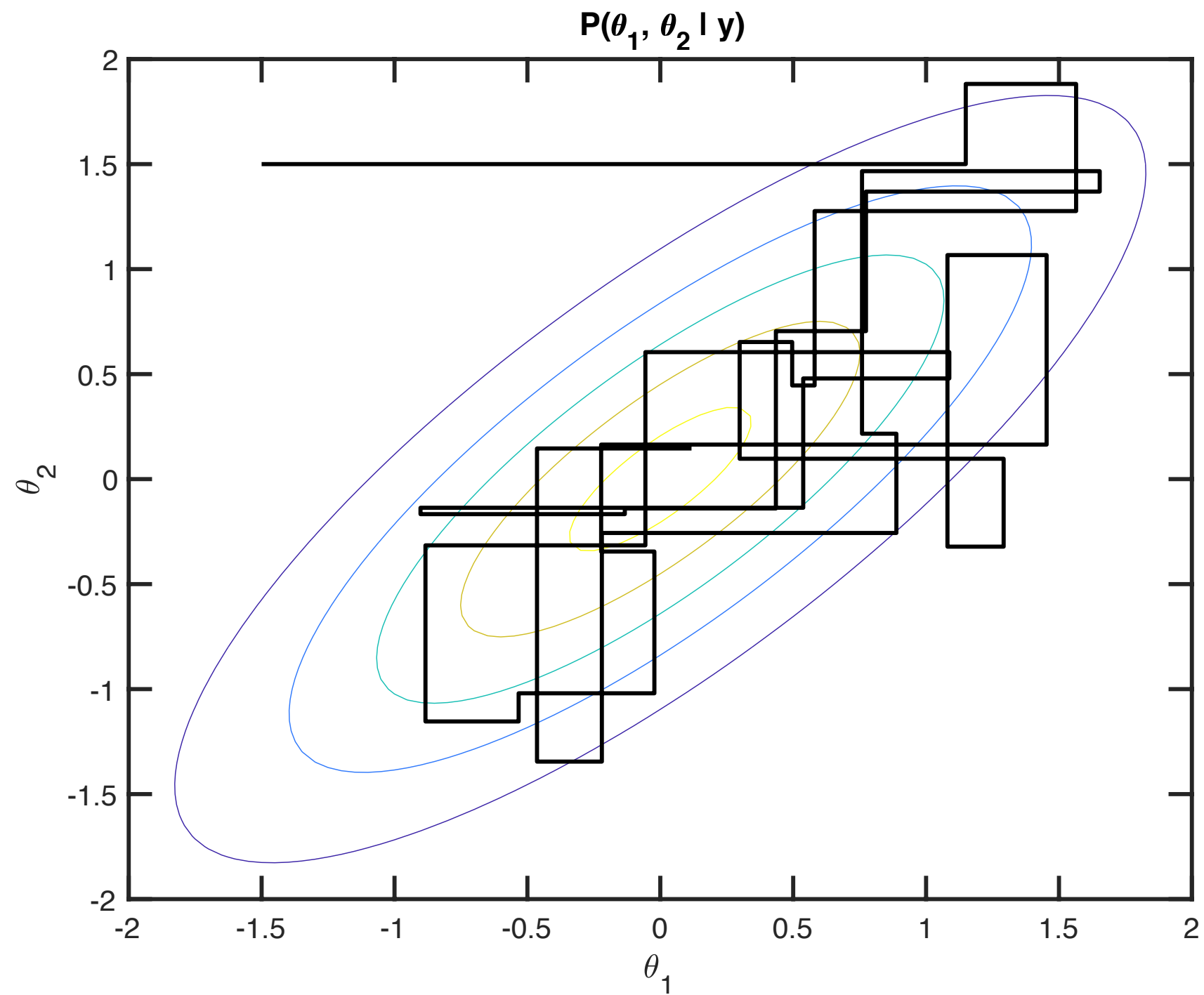
$$\theta_1 \mid \theta_2, \mathbf{y} \sim N(y_1 + \rho(\theta_2 - y_2), 1 - \rho^2)$$

$$\theta_2 \mid \theta_1, \mathbf{y} \sim N(y_2 + \rho(\theta_1 - y_1), 1 - \rho^2)$$

# Gibbs Sampling: demo

## `gibbs_example.m`

### 2D Trace Paths for 50 iterations

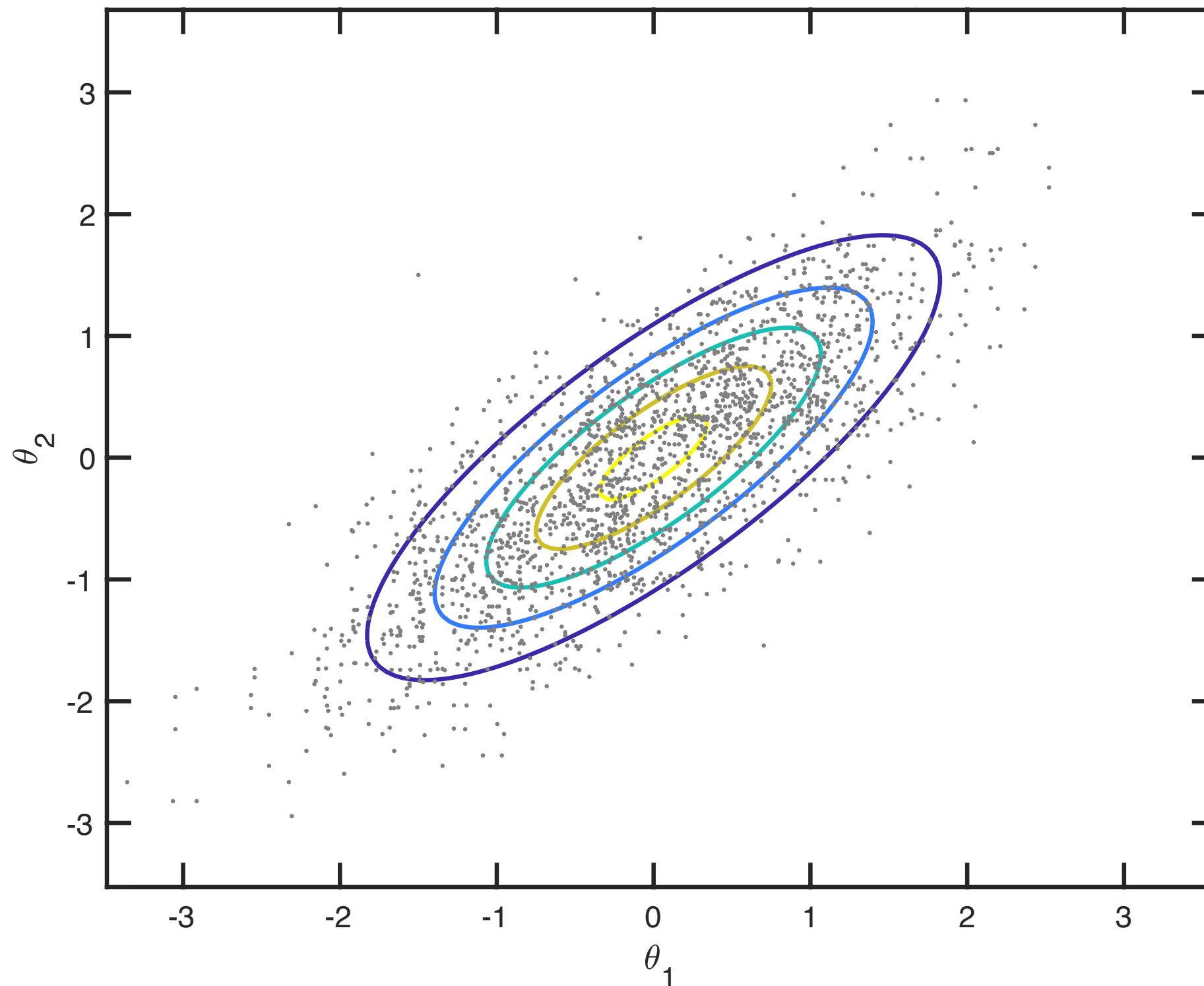


# Gibbs Sampling: demo

## `gibbs_example.m`

### Joint Posterior Densities

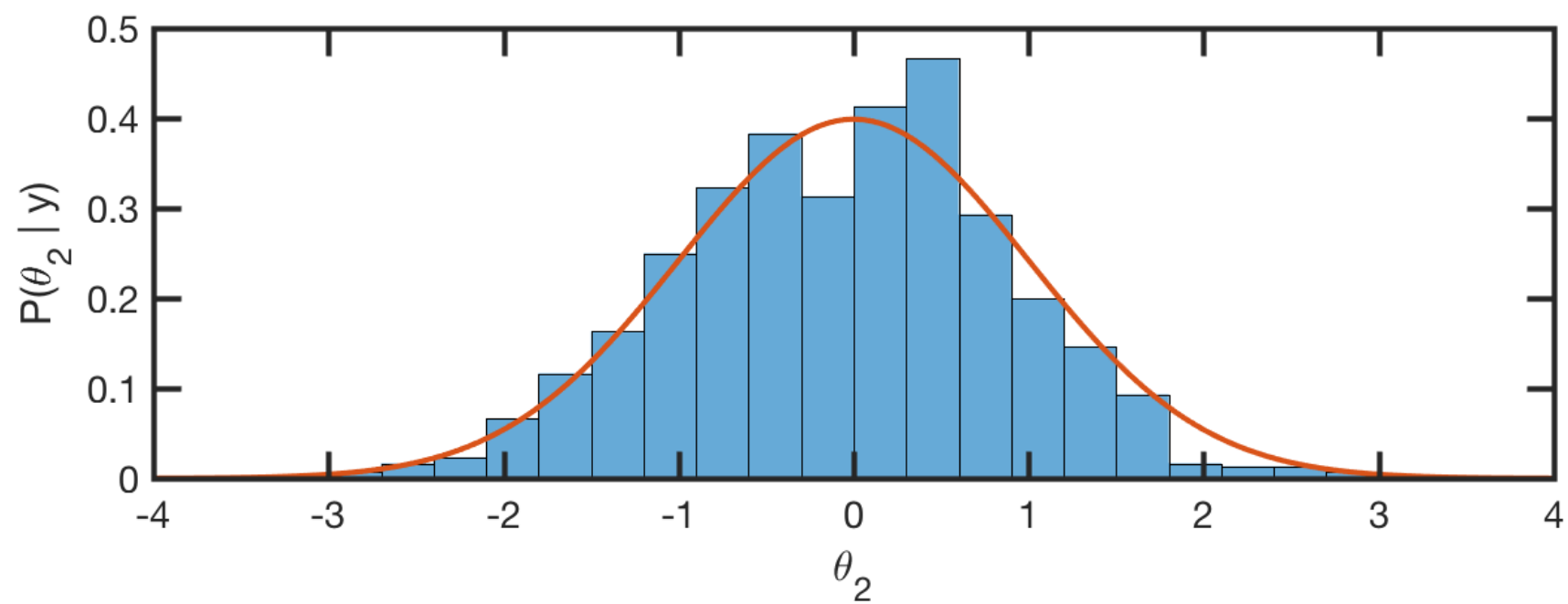
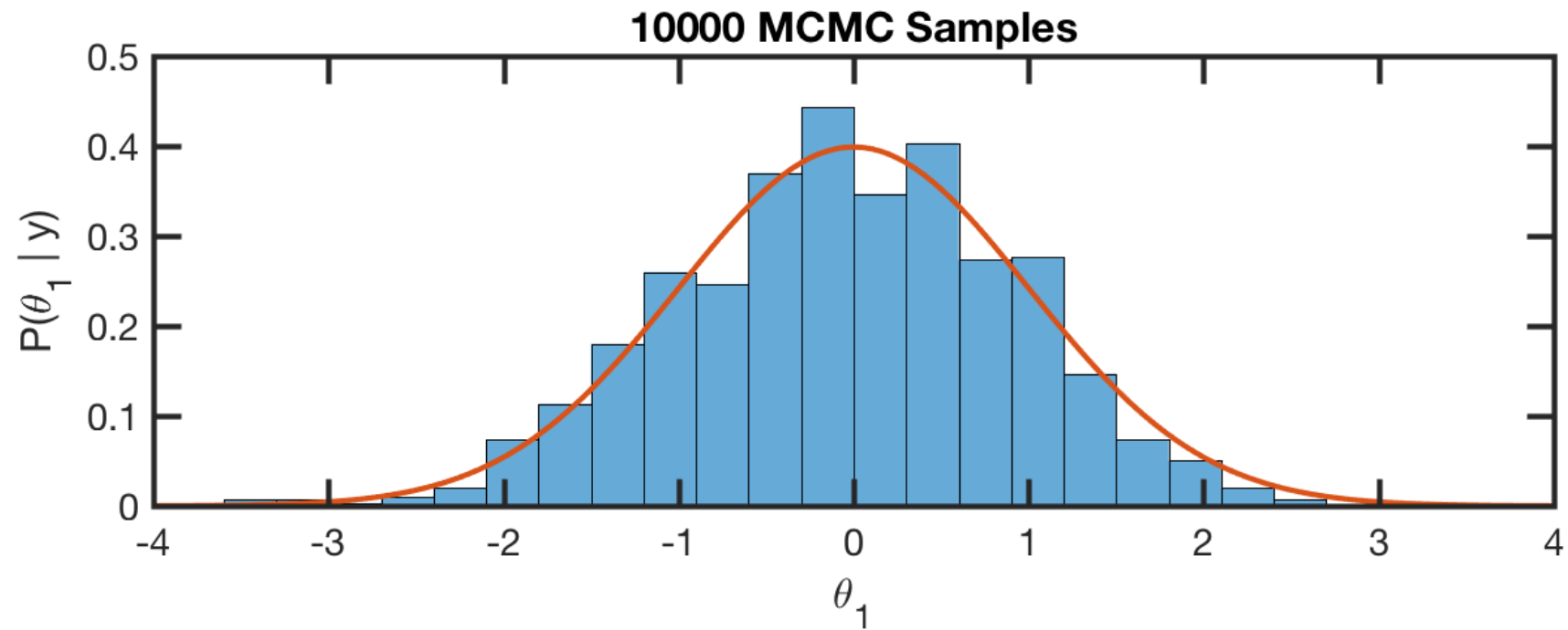
10000 MCMC Samples, target:  $P(\theta_1, \theta_2 | y)$



# Gibbs Sampling: demo

gibbs\_example.m

## Marginal Posterior Densities



# Metropolis-within-Gibbs

$$\boldsymbol{\theta} = (\theta_1 \dots \theta_d) \qquad \boldsymbol{\theta}_{-j} \equiv (\theta_1, \dots, \theta_{j-1}, \theta_{j+1} \dots \theta_d)$$

- When you can't solve for tractable conditional distributions for all  $\theta_j$ :  $P(\theta_j | \boldsymbol{\theta}_{-j}, \mathbf{D})$
- Replace each substep for updating each  $j$ th parameter  $\theta_j$  with a separate Metropolis rule, compute Metropolis ratio, and accept/reject
- Cycle through all parameters, and repeat all for  $N$  MCMC steps

# d-dim Metropolis-within-Gibbs Sampler

$$\boldsymbol{\theta} = (\theta_1 \dots \theta_d) \quad \boldsymbol{\theta}_{-j} \equiv (\theta_1, \dots, \theta_{j-1}, \theta_{j+1} \dots \theta_d)$$

1. Choose a random starting point  $\theta_0$
2. At step  $i = 1 \dots N$ , cycle through the d-parameters:
  1. For each  $j = 1 \dots d$ , propose a new jth parameter from a 1-Dimensional Gaussian:  $\theta_j^* \sim N(\theta_j^{i-1}, \tau^2)$
  2. Evaluate ratio of posteriors at proposed vs current values:

$$r = P(\theta_j^*, \boldsymbol{\theta}_{-j}^{i-1} | \mathbf{y}) / P(\boldsymbol{\theta}^{i-1} | \mathbf{y}) = P(\theta_j^* | \boldsymbol{\theta}_{-j}^{i-1}, \mathbf{y}) / P(\theta_j^{i-1} | \boldsymbol{\theta}_{-j}^{i-1}, \mathbf{y})$$

3. Accept  $\theta_j^i = \theta_j^*$  with probability  $\min(r, 1)$ , otherwise  $\theta_j^i = \theta_j^{i-1}$
3. Repeat steps 2 for all parameters until reach some measure of convergence (G-R) and gather enough independent samples to compute your inference (reduce Monte Carlo error)

# Metropolis-within-Gibbs Sampling: Example: Gelman BDA Section 11.1)

Likelihood:  $\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \sim N \left( \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right) \quad \rho \text{ known}$

Priors:  $P(\theta_1) = P(\theta_2) \propto 1$

Posterior:  $\begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \mid \mathbf{y} \sim N \left( \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$

Suppose we can't solve for the Conditional Posteriors.

# Metropolis-within-Gibbs Sampling: Code Demo `metropolisgibbs_example.m`



# A sketch of Markov Chain Theory

- See Robert & Casella “Monte Carlo Statistical Methods” Chapter 6 “Markov Chains” for the technical details
- Existence of a stationary limiting distribution (irreducible, aperiodic).
- The target distribution (posterior) is the invariant, stationary distribution under your chosen transition probabilities