

Project Name

Author

Sunday 2<sup>nd</sup> June, 2024

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# 1 Introduction

Introduction to Project. Example cite<sup>[1]</sup> and example references are in appendix A.

## **2 Design**

How this project is designed to do

### **3 Implementation**

How the project was implemented

## **4 Conclusion**

How the project turned out in the end

## References

- [1] Dr. Michael J. Robers. *Fundamentals of Signals & Systems*. McGraw-Hill, first edition, 2008.

# Appendix A   Example Elements

## A.1   Equations

Equations with numbers with label A.1:

$$y = mx + c$$

(A.1)

Multiline equation (numbered)

$$\begin{aligned} e(t) &= \omega_{setpoint} - \omega_{feedback} \\ u &= K_p e(t) + K_d \frac{e(t)}{dt} + K_i \int_0^t e(t) dt \end{aligned}$$

(A.2)

Equation without number

$$f(x) = g(\omega)$$

Inline mathematics  $u(x) = \delta(x)$

Multiline equation (non-numbered)

$$\begin{aligned} e(t) &= \omega_{setpoint} - \omega_{feedback} \\ u &= K_p e(t) + K_d \frac{e(t)}{dt} + K_i \int_0^t e(t) dt \end{aligned}$$

## A.2   Lists

- Item 1
- Item 2

To Do Box:

- Task 1
- Task 2
- Task 3

## A.3   Tables

Non captioned Tables:

Date	Time	Task
7th April 2014	2hrs	Project Introduction
1st May 2014	2hrs	Final Design Logistics

Captioned Tables:



Date	Time	Task
7th April 2014	2hrs	Project Introduction
1st May 2014	2hrs	Final Design Logistics

Table A.1: Example of a customized captioned tabularx table

## A.4 Images

Auto placed Picture

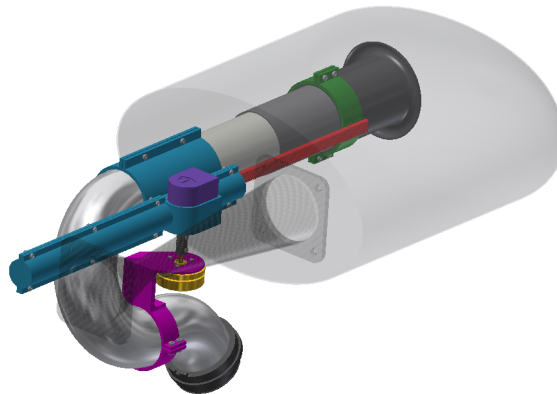


Figure A.1: Variable Length Manifold

## Appendix B Program Code

Hello World in C (from file)

```

1 #include <stdio.h>
2
3 int main(void)
4 {
5     printf("hello, world\n");
6 }

```

Hello World in python (inline)

```

1 print("Hello World")

```