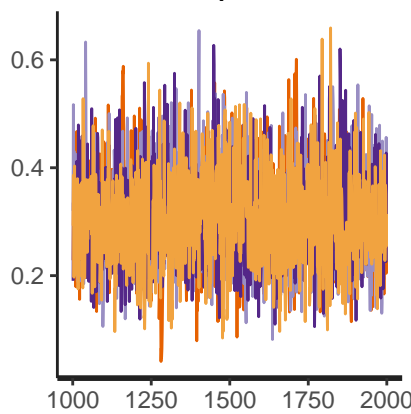
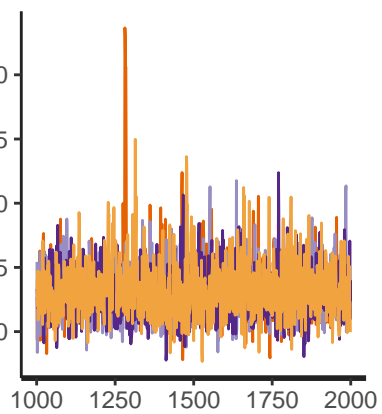


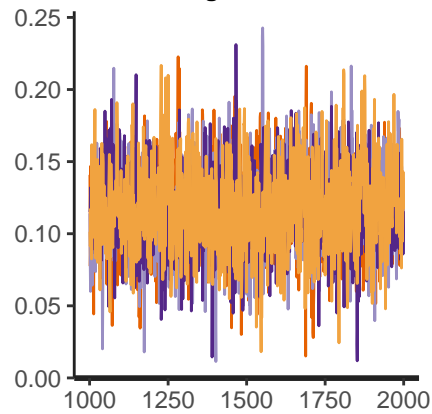
alpha



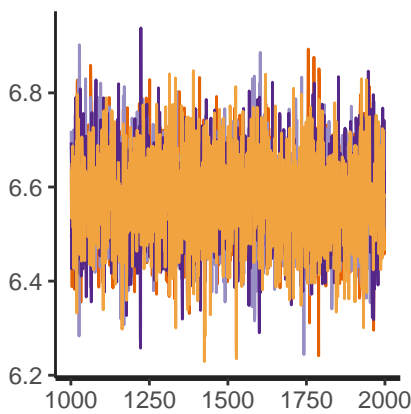
effort\_baseline



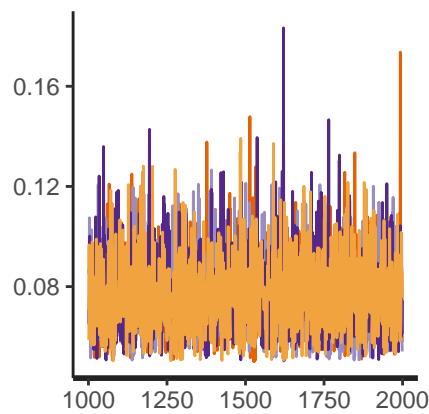
gamma



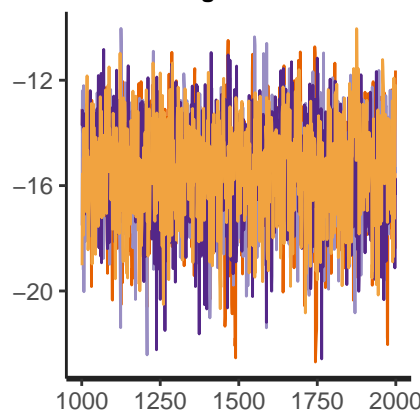
effort\_0



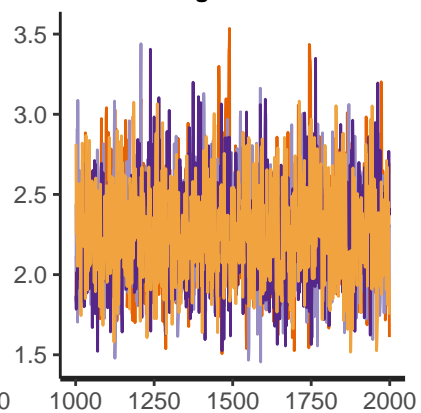
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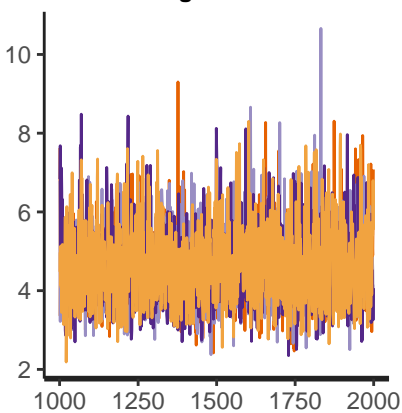
gain20



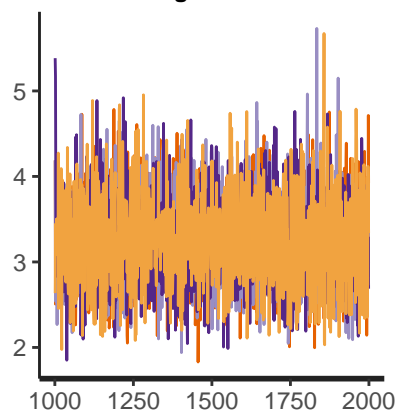
gain21



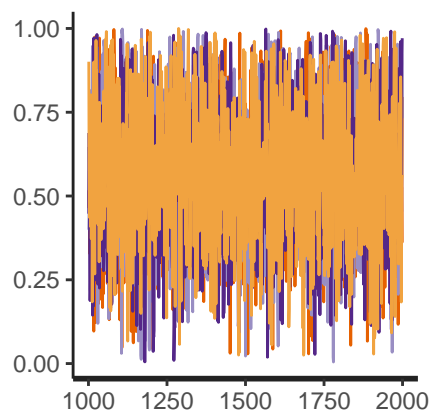
gain22



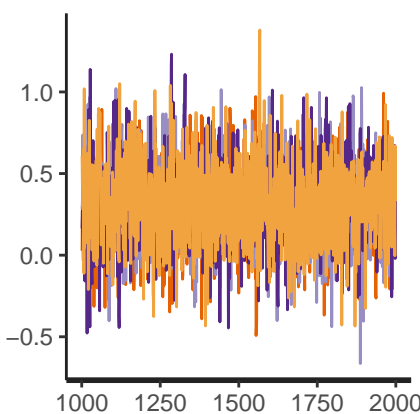
gain23



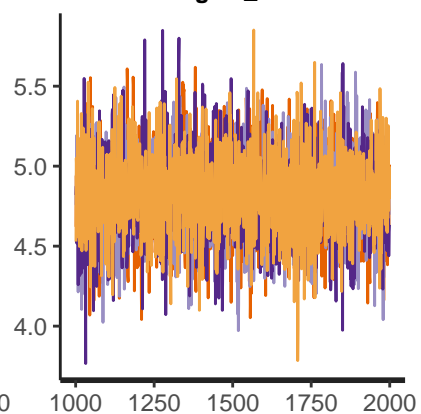
theta



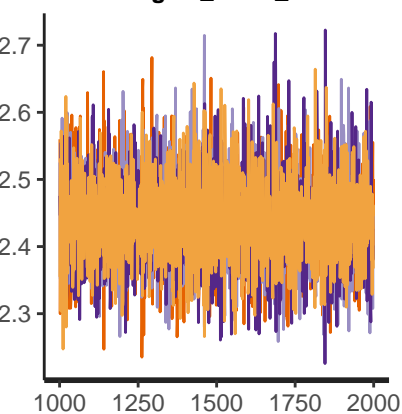
lambda



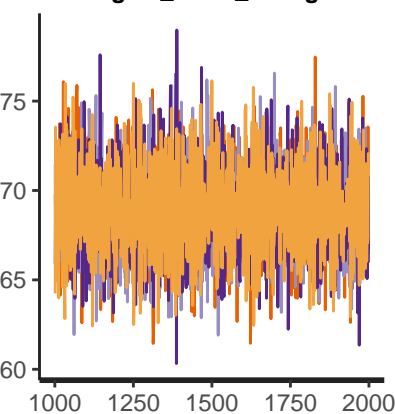
goal\_0



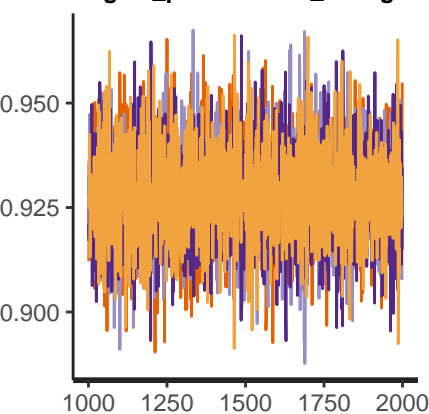
sigma\_effort\_0



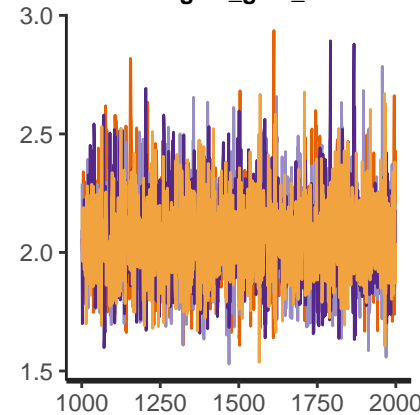
sigma\_effort\_change



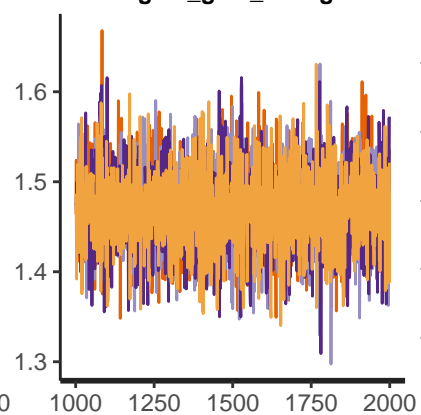
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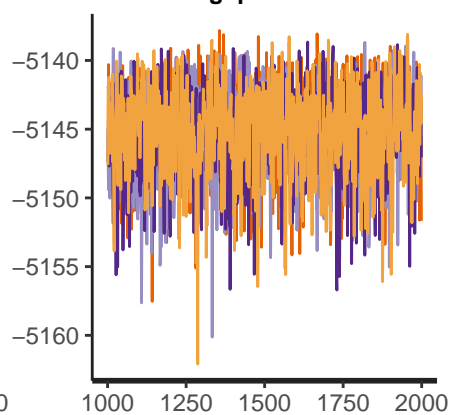
sigma\_goal\_0



sigma\_goal\_change



log-posterior



chain

- 1
- 2
- 3
- 4